# Parallel software

And how they run on parallel hardware

Introduction

Parallel programming

Two examples

Conclusion

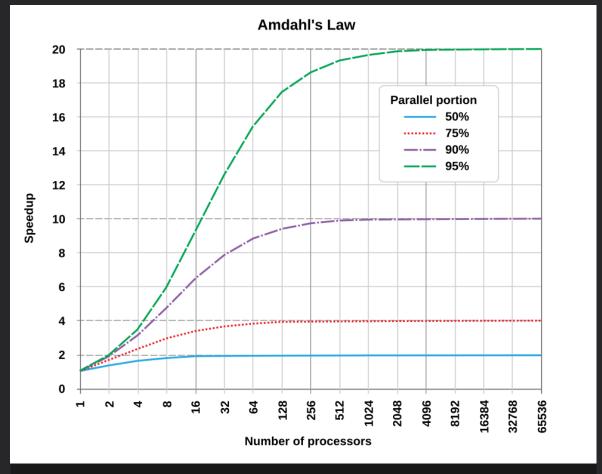
#### Amdahl's Law

- Let  $Speedup = \frac{Time_o}{Time_e}$ 
  - o is original
  - e is enhanced
- Amdahl's law: Enhance fraction of computation (f) by some speedup (S):

$$Speedup_e(f,S) = \frac{1}{(1-f) + f/S}$$

- Implications of Amdahl's law
  - Small f means enhancement has little effect
  - Even with very large S, speedup is bounded by  $\frac{1}{1-f}$

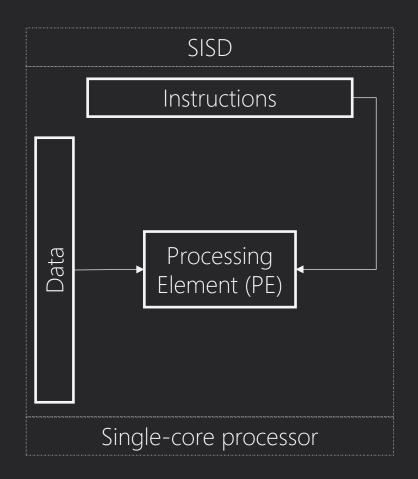
The speedup from enhancing one part of a system is limited by the fraction of time the improved part is used.

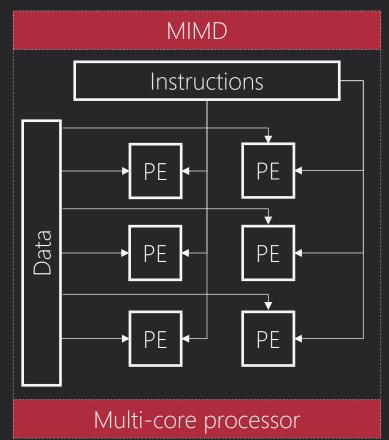


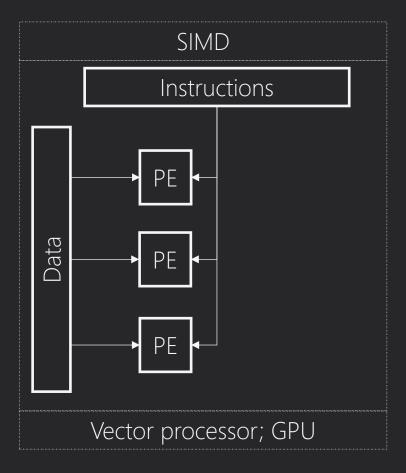
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### Flynn's Taxonomy

- Single instruction, single data (SISD)
- Multiple instruction, multiple data (MIMD)
- Single instruction, multiple data (SIMD)

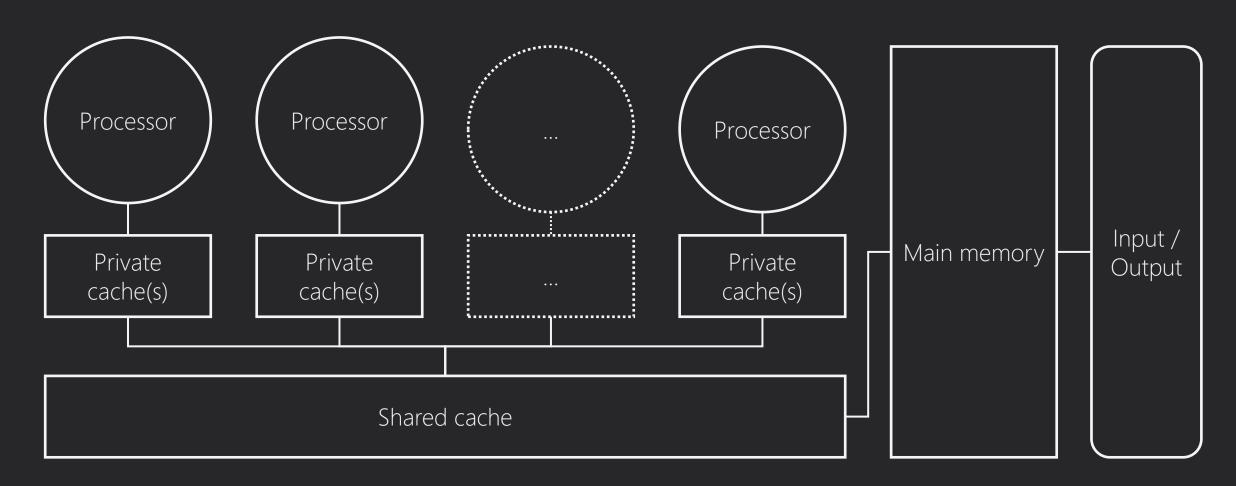






# Thread-level parallelism (TLP)

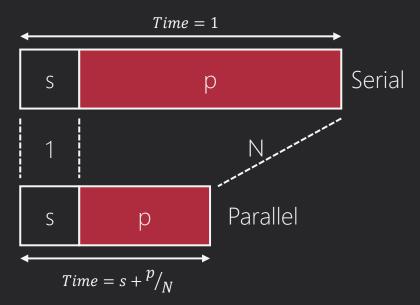
- Threads can be executed in parallel. But programmers must be explicit about what each thread does
- Weeks 6 to 9

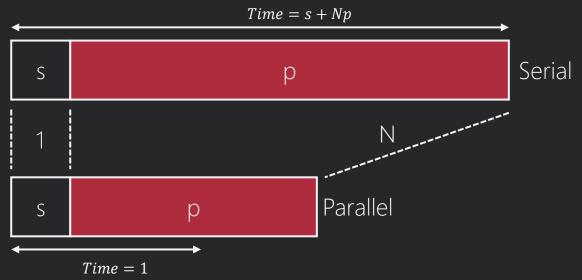


#### What is Gustafson's Law?

- s: serial fraction of time
- p: parallel fraction of time
- N: number of cores

- Amdahl's law assumes a fixed problem size
  - Speedup =  $\frac{1}{s + \frac{p}{N}}$
- Gustafson's law assumes the problem size scales with the number of processors
  - Speedup = s + Np = N + s(1 N)





### What is scaling?

#### Strong scaling

- Measuring speed up while the problem size (W) is fixed, regardless of the number of processors (P)
- i.e, the amount of work to do by each processor is:  $^{W}/_{P}$
- Useful model for applications whose working set do not grow (much) over time

#### Weak scaling

- Measuring speed up when the problem size (W) grows with the number of processors (P)
- i.e., the amount of work to do by each processor is:  $\boldsymbol{W}$
- Useful model for applications whose working sets grow commensurate with processing power (i.e., number of cores)

# Parallel programming

An overview of abstractions for parallel programming

### Why is writing parallel software challenging?

- Load balancing (or work partitioning)
  - How do you ensure that each processor gets an equal division of work?
- Communication (or coordination)
  - Many algorithms require data to be communicated across processors
- Incentive
  - The program already works for single-core and runs well enough...

### How do we go from sequential to parallel?

#### Method

- Identify which program segments can be run in parallel
- Two sequential segments, S1 and S2, can be run in parallel iff S1 and S2 are independent
  - i.e., S2 does not need data from S1

#### Common patterns

- Data-level parallelism in loops
  - No loop-carried dependencies (each iteration's computation is independent)
- Task-level parallelism
  - Functions are tasks performed in parallel
  - The ordering of tasks is based on dependencies between them
- A function pipeline
  - Useful in streaming applications

#### What is a thread?

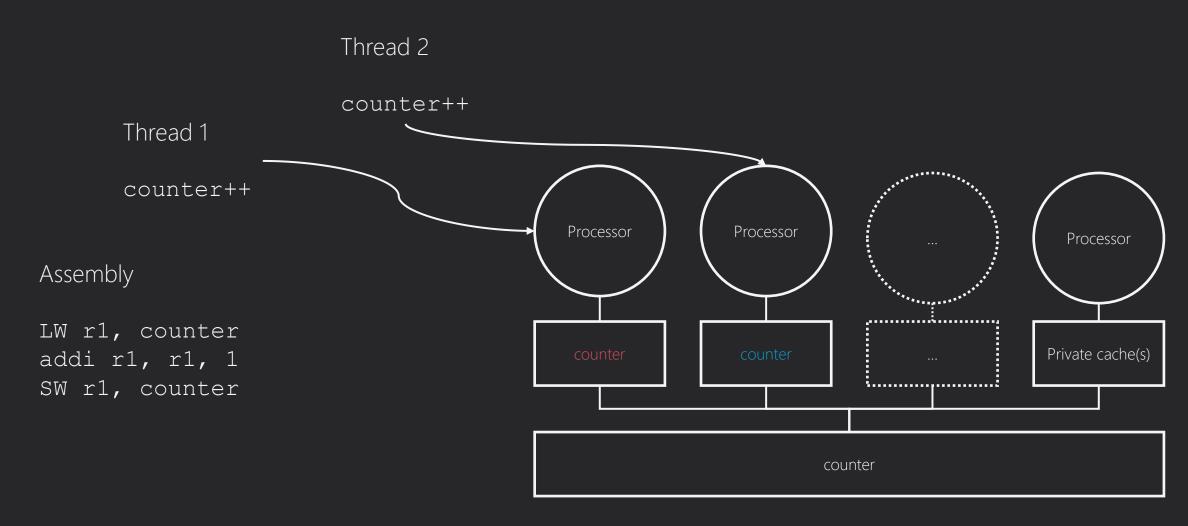
#### Definition

- A thread is a control flow through a program
- A sequential program has one control flow
- A multi-threaded program has multiple control flows

#### Effect

- Each thread has its own PC
- Threads may run in parallel
- Threads share resources with other threads
  - Hardware
  - Memory and data
- Sharing data needs to be done correctly

#### How do threads execute in parallel?



### What is synchronization?

- In a shared memory system, threads communicate implicitly
  - Load and store instructions

- Synchronization is a mechanism
  - That makes communication explicit
  - That avoids incorrect interleaving of loads and stores
- Later: how does hardware support synchronization?

# Creating parallel programs

From sequential to parallel

#### Examples of sequential algorithms

#### Sum all elements of an array

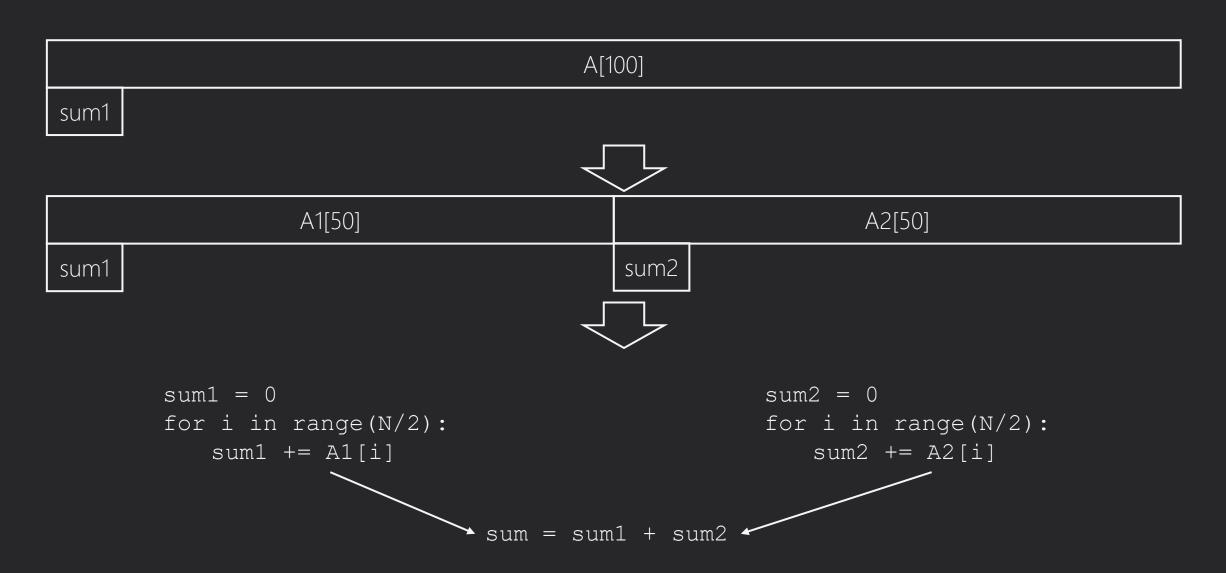
```
sum = 0
for i in range(N):
    sum += A[i]
```

#### Matrix multiplication and summation

```
sum = 0
for i in range(N):
  for j in range(N):
    C[i][j] = 0;
    for k in range(N):
      C[i][j] += A[i][k]*B[k][j]
    sum += C[i][j]
```

#### Dividing the data in half

```
for i in range(N):
    sum += A[i]
```



#### Dividing the data across T threads

- OpenMP is an API that simplifies parallel program
  - Use "decorators" to indicate parallel pattern
- OpenMP will...
  - Create a pool of threads (to re-use)
  - Assign work to threads
  - Follow the decorated patterns
- Easy to use, difficult to debug

```
#define N 100 // elements in array
#define T 4 // number of threads
#pragma omp parallel num threads(T)
for (int t = 0; t < T; t++)
  for (int i = N * t; i < N * (t + 1); i++)
   psum[t] += A[i]
for (int t = 0; t < T; t += 1)
  sum += psum[t]
```

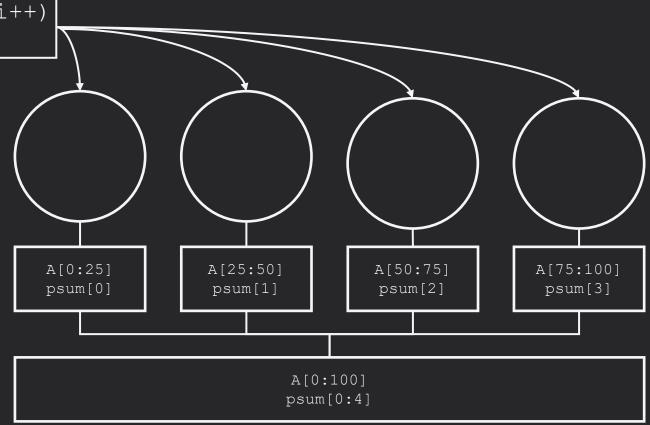
### Running the sum on a parallel processor

```
#pragma omp parallel for
for (int t = 0; t < T; t++)</pre>
```

```
for(int i = N * t; i < N * (t + 1); i++)
psum[t] += A[i]
```

Data is partitioned to avoid sharing:

- Each thread only reads the parts of A it needs
- Each thread writes to its own psum



#### Running the reduction on a parallel processor

```
#pragma omp parallel for reduction(+: sum)
for (int t = 0; t < T; t += 1)
  sum += psum[t]
 Some data is partitioned to avoid sharing.
 Needs synchronization on sum – handled by
 OpenMP
                                                  psum[0:1]
                                                                 psum[2:3]
                                                     sum
                                                                   sum
                                                                        psum[0:4]
                                                                           sum
```

#### Dividing the matrix across T threads

- Each thread
  - Executes the code on the right
  - Loops over a part of the matrix
  - Calculates a partial sum

• What about the final sum?

```
#define N 100 // elements in matrix
#define T 4 // number of threads
end = low + N / T
psum = 0
  for j in range(N):
   C[i][j] = 0;
    for k in range(N):
     C[i][j] += A[i][k]*B[k][j]
   psum += C[i][j]
```

### Running the sum on a parallel processor

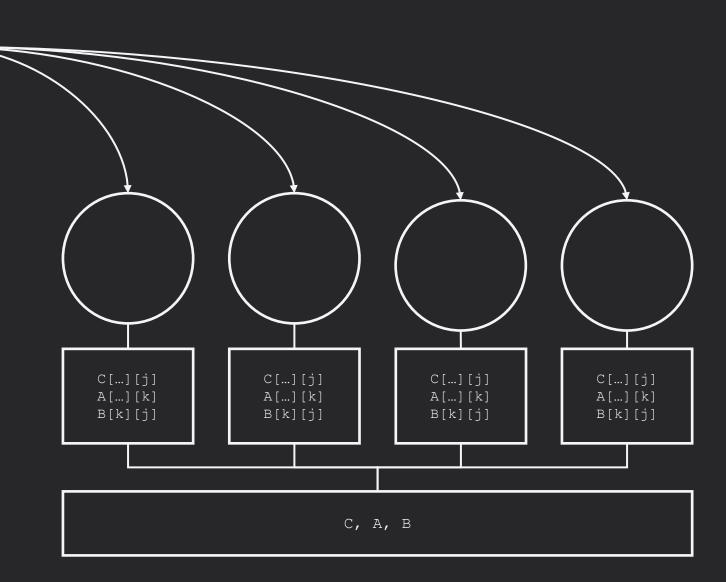
```
for k in range(N):
    C[i][j] += A[i][k]*B[k][j]
```

Data is partitioned to avoid sharing:

• Each thread only writes a part of C

Other data is shared "nicely":

- No writes to A or B
- Data brought into the shared cache by one thread may help another (e.g., B)



#### Summing up the partial sums

- Use a more flexible API: POSIX threads
- What is a barrier?
  - A meeting point
  - "Wait here until all other threads reach this point"
- What is a lock?
  - "Only I will update sum at this time"
  - Serializes updates to sum across all threads

```
// ... see earlier slide ...
psum = 0
for (i = start; i < end; i++)
  for j in range(N):
    C[i][j] = 0;
    for k in range(N):
      C[i][j] += A[i][k]*B[k][j]
    psum += C[i][j]
barrier()
lock()
```

## Conclusion

A summary and parting thoughts

### Parallel programming

- Programmers must explicitly,
  - Divide program into multiple threads
  - Define communication between threads
  - Be aware of implicit communication, so that they
  - include synchronization to shared memory where interleavings are problematic
- Different APIs are available
  - OpenMP (easy to use, difficult to debug)
  - POSIX threads (more flexible, difficult to debug)

#### What do architects need to do?

- Correctness
  - Ensure sequential programs run as expected on parallel processors
  - Ensure parallel programs run correctly (assuming correct synchronization)
- Support
  - Provide support in the hardware for synchronization
- Performance
  - Ensure communication across processors is fast