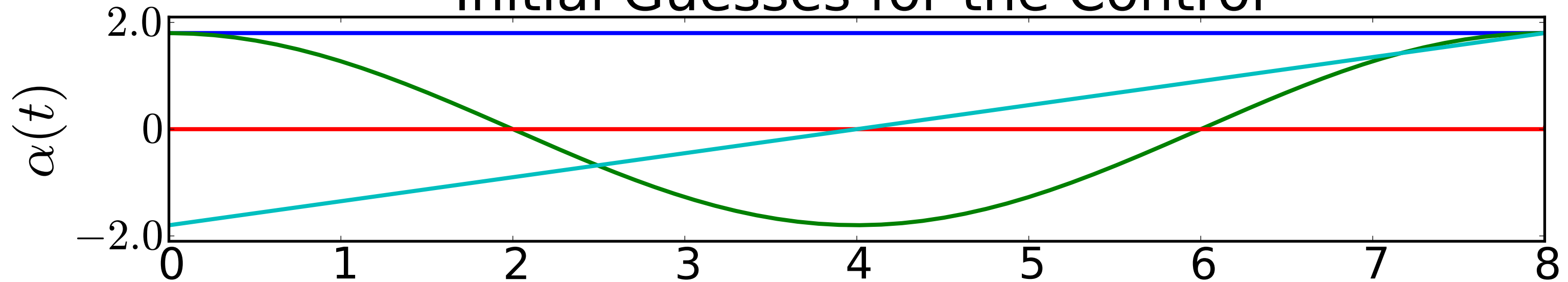
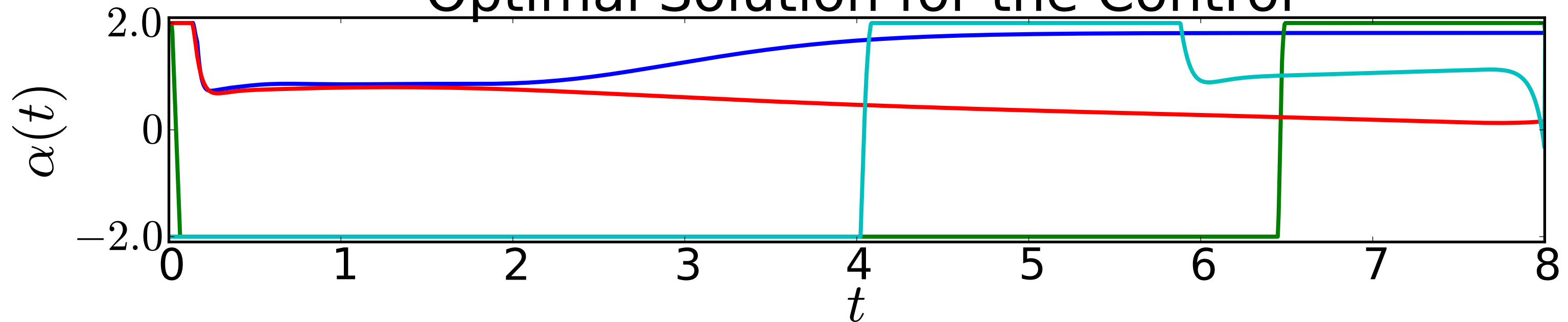


# Initial Guesses for the Control



# Optimal Solution for the Control



# Iterated values of mutual information

