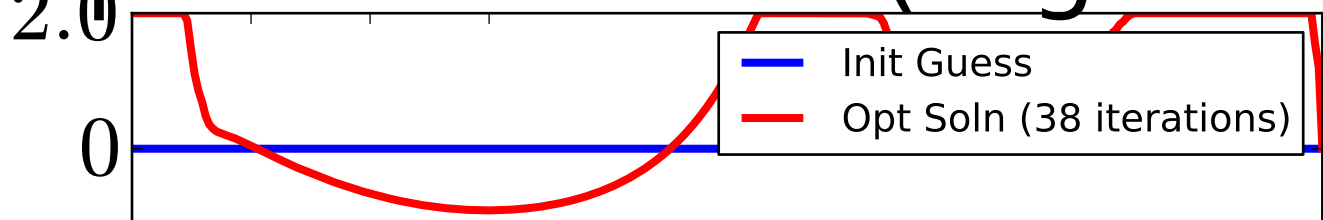


# Optimal Control ( $\operatorname{argmax} I$ )



# Gradient Ascent of the Objective

