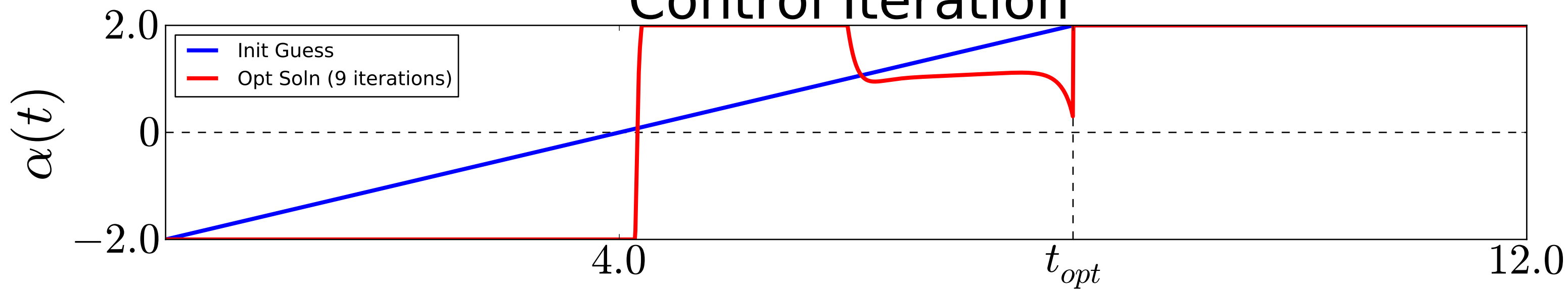
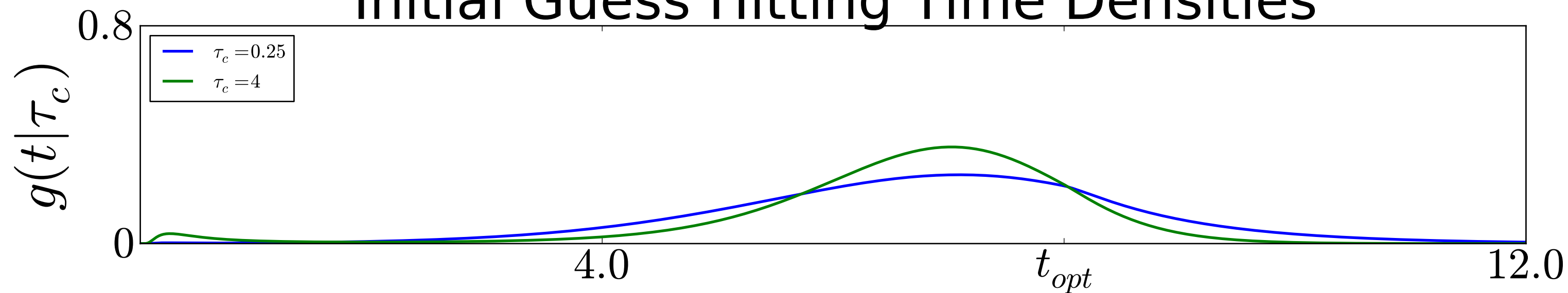


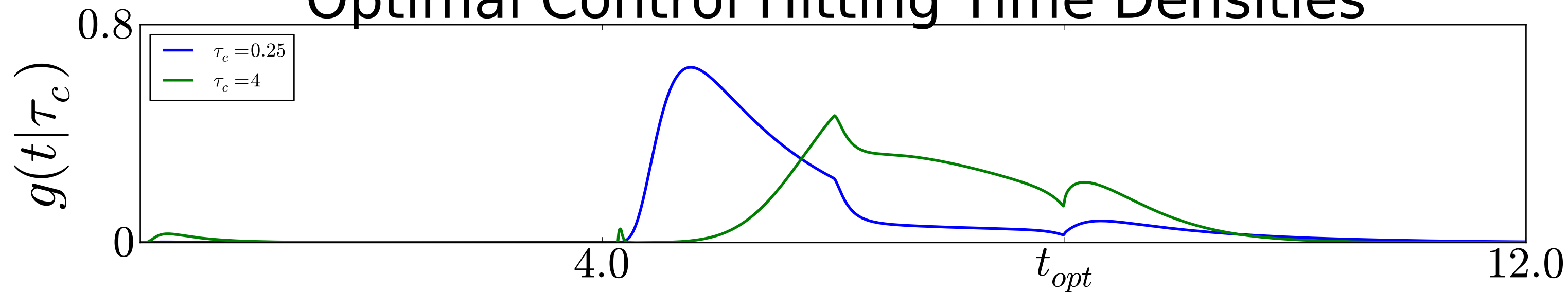
Control Iteration



Initial Guess Hitting Time Densities



Optimal Control Hitting Time Densities

Gradient Ascent of the Objective I 