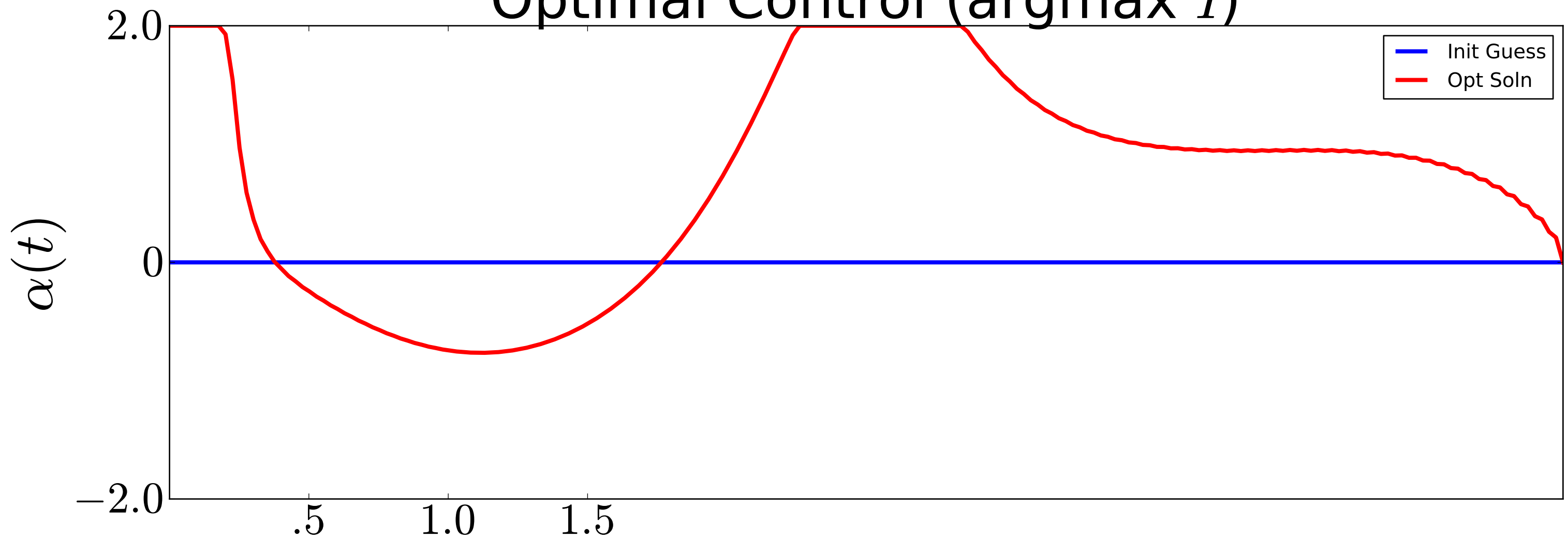


# Optimal Control (argmax $I$ )



# Gradient Ascent of the Objective $I$

