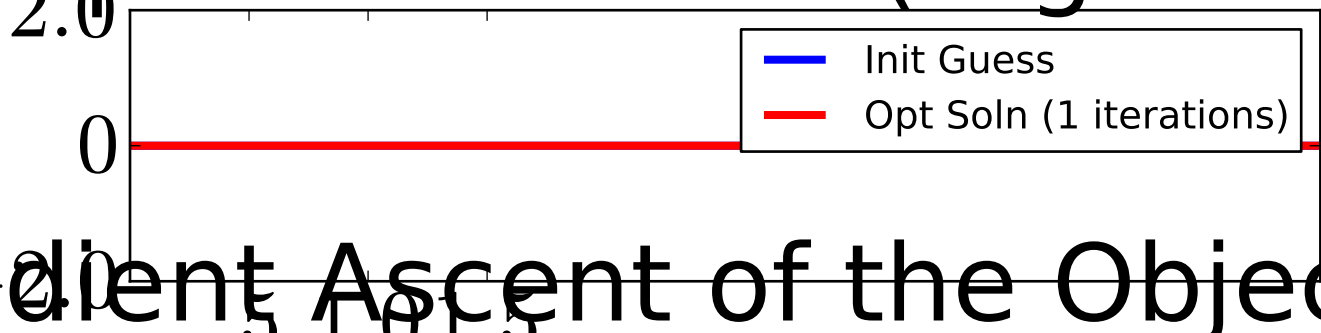


Optimal Control ($\operatorname{argmax} I$)



Gradient Ascent of the Objective

