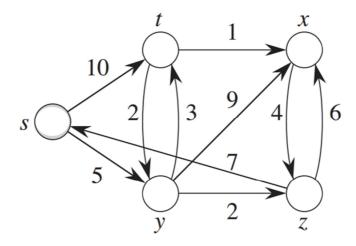
# **Class Tutorial 3**

# 1. Shortest path example

Consider the following graph:



- a. Run the Bellman-Ford algorithm on the graph.
- b. Run Dijkstra's algorithm on the graph.

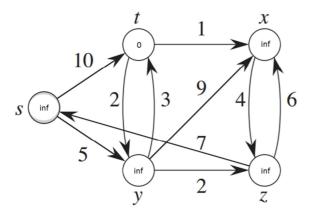
## **Solution**

a.

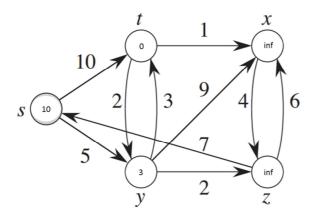
#### Bellman-Ford Algorithm.

```
\begin{array}{l} \textit{Input: A weighted directed graph } G \text{ , and destination node } t \text{ .} \\ \textit{Initialization: } d[t] = 0 \text{ , } d[v] = \infty \text{ for } v \in V \setminus \{t\}, \quad \pi[v] = \phi \text{ for } v \in V \\ \text{for } i = 1 \text{ to } |V| - 1 \\ d'[v] = d[v], \quad v \in V \setminus \{t\} \\ \text{ for each vertex } v \in V \setminus \{t\}, \\ \text{ compute } q[v] = \min_u \{w(v,u) + d'[u] \colon (v,u) \in E\} \\ \text{ if } q[v] < d[v], \\ \text{ set } d[v] = q[v], \quad \pi[v] \in \arg\min_u \{w(v,u) + d'[u] \colon (v,u) \in E\} \\ \textit{return } \{d[v], \pi[v]\} \end{array}
```

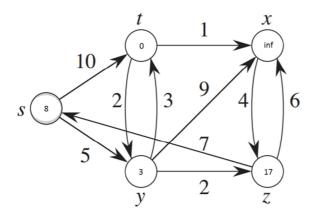
Initialization:



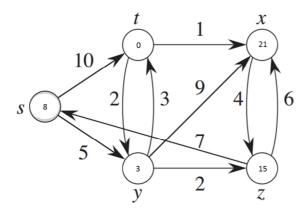
Iteration 1:



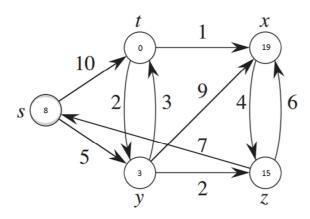
Iteration 2:



Iteration 3:



Iteration 4:



b.

# Dijkstra's Algorithm.

 $\textit{Input:}\ A$  weighted directed graph, and destination node t .

Initialization: 
$$d[t] = 0$$
,  $d[v] = \infty$  for  $v \in V \setminus \{t\}$ ,  $\pi[v] = \phi$  for  $v \in V$   
 $S = \phi$ 

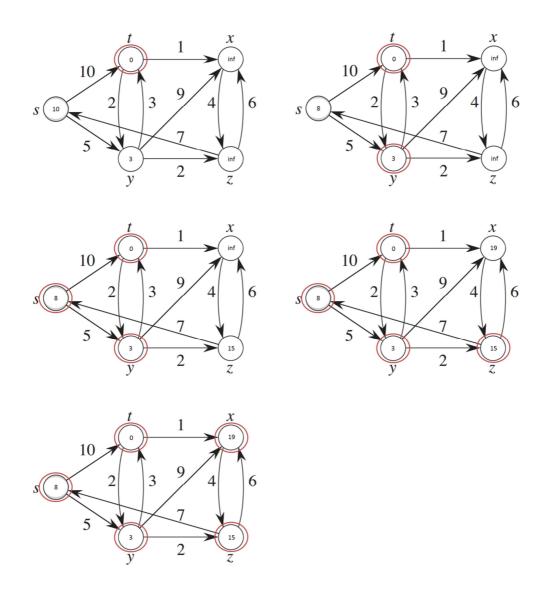
while 
$$S \neq V$$
, (\*\*\*)

choose  $u \in V \setminus S$  with minimal value d[u], add it to S

for each vertex v with  $(v,u) \in E$ ,

if 
$$d[v] > w(v,u) + d[u]$$
,  
set  $d[v] = w(v,u) + d[u]$ ,  $\pi[v] = u$ 

return  $\{d[v], \pi[v]\}$ 



# ${\bf 2.\ Dijkstra's\ Algorithm\ -\ Correctness}$

We let  $d^*(v)$  denote the (true) shortest path length from node  $v \in V$  to the destination node t, and let d(v) denote the value of node v during execution on Dijkstra's algorithm. Prove the following properties:

- a. Triangle inequality: for any edge  $(u,v) \in E$  we have  $d^*(u) \le w(u,v) + d^*(v)$ .
- b. Upper bound property: for all  $v \in V$  and at any time in the execution of the algorithm, we have  $d(v) \ge d^*(v)$ . Moreover, once equality is obtained, d(v) never changes.
- c. Correctness of Dijkstra's algorithm: for a graph with non-negative weights, Dijkstra's algorithm terminates with  $d(v) = d^*(v)$  for all  $v \in V$ .

## **Solution**

a. Suppose p is a shortest path from u to t. Then p has no more weight than any other path from u to t, specifically the path that goes from u to v and then continues optimally.

b. We prove by induction on the number of relaxation steps, i.e., number of executions of

if 
$$d[v] > w(v,u) + d[u]$$
,  
set  $d[v] = w(v,u) + d[u]$ 

For the first step this is clearly true, due to the initialization procedure.

Assume  $d(x) \le d^*(x)$  for all  $x \in V$  prior to the relaxation step, and consider a relaxation of edge (v,u). The only value that may change is d(v). If it changes we have

$$d(v) = w(v,u) + d(u)$$

$$\geq w(v,u) + d^*(u)$$

$$\geq d^*(v)$$

Where the first inequality is by the induction hypothesis, and the second by the triangle inequality. Thus, the induction invariant is maintained.

Once  $d(v) = d^*(v)$ , it cannot decrease as we have now shown, and it cannot increase since relaxations only decrease values.

c. We prove the following loop invariant:

At the start of each while loop (\*\*\*), we have  $d(v) = d^*(v)$  for all  $v \in S$ .

It suffices to show that for all  $u \in V$  we have  $d(u) = d^*(u)$  when u is added to S. By the upper-bound property, it will never change afterwards.

**Initialization**: initially  $S = \emptyset$  so the invariant is trivially true.

**Maintenance**: For the purpose of contradiction, let u be the first node added to the set S such that  $d(u) \neq d^*(u)$ .

We must have  $u \neq t$  since t is the first node added to S and  $d(t) = d^*(t) = 0$ . We also have that  $S \neq \emptyset$  just before u is added. There must be a path from u to t otherwise  $d(u) = d^*(u) = \infty$ . Thus, there is a shortest path p from u to t.

Prior to adding u to S, p connects a node in V-S to a node in S. Let x denote the last node in p such that  $x \in V-S$  and let y denote x's successor, i.e.,  $y \in S$ . We can decompose p into  $u \to x \to y \to t$ .

We claim that  $d(x) = d^*(x)$  when u is added to S. To see this, observe that  $d(y) = d^*(y)$  since  $y \in S$  and u is the first node for which this property does not hold.

Since  $x \to y \to t$  is the shortest path from x to t, when y was relaxed, we had  $d(x) = w(x, y) + d^*(y) = d^*(x)$ .

We now obtain the contradiction. Since x appears after u on the shortest path p, and since all weights are non-negative, we must have  $d^*(x) \le d^*(u)$ . Therefore

$$d(x) = d^*(x)$$

$$\leq d^*(u)$$

$$\leq d(u)$$

But because x and u were in V-S we must also have  $d(u) \le d(x)$  , therefore,  $d(x) = d^*(x) = d^*(u) = d(u)$  , which contradicts our definition of u.