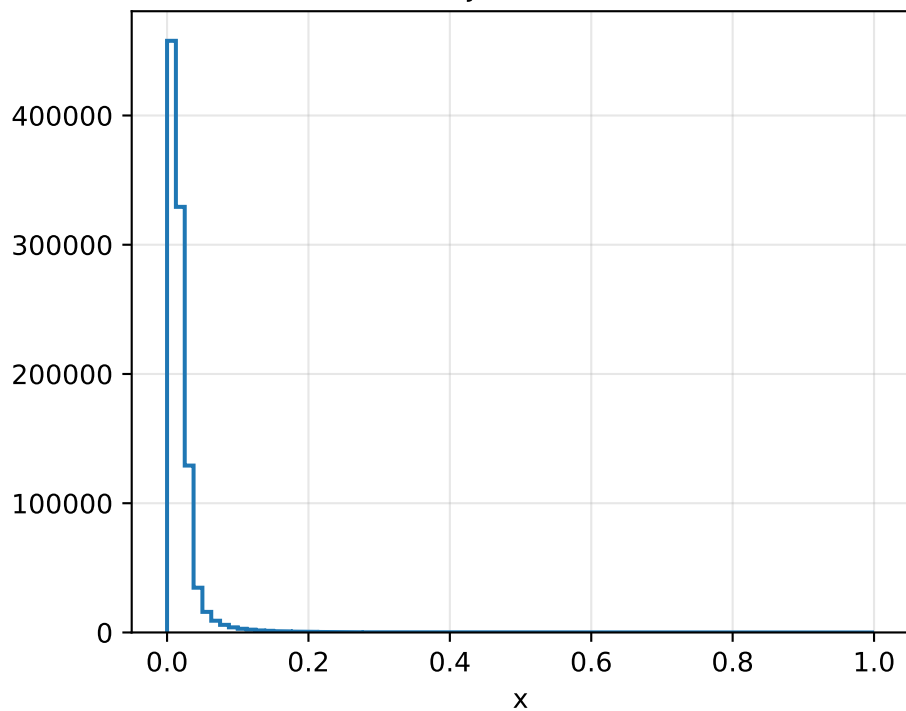
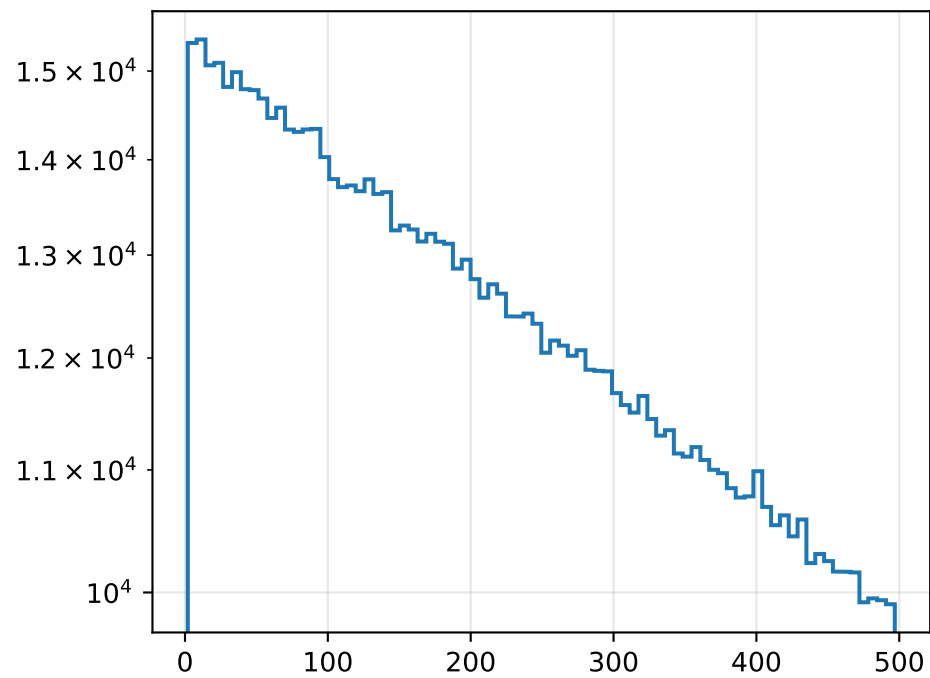
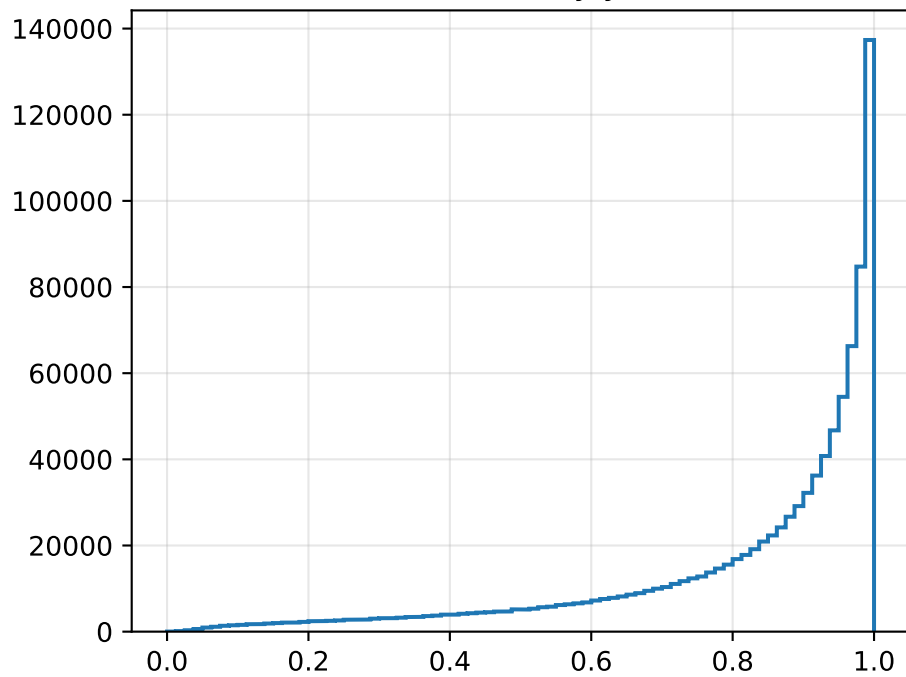
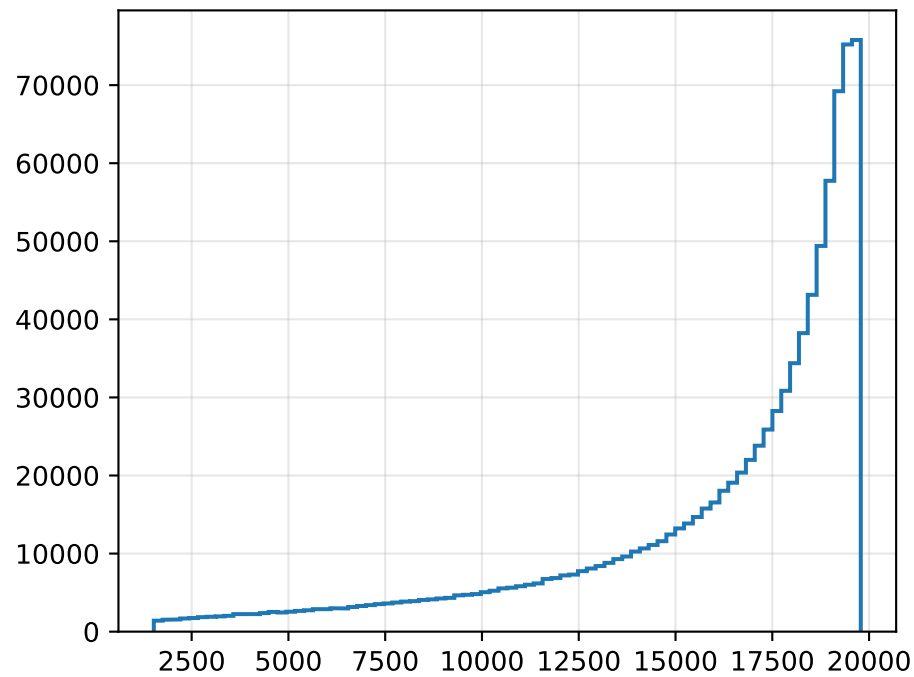
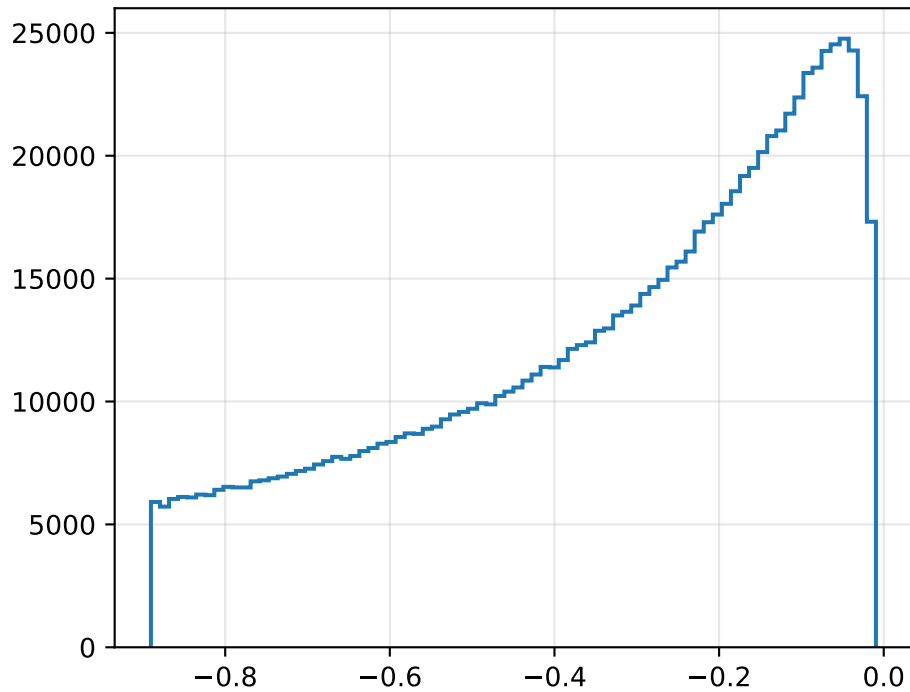


Bjorken x

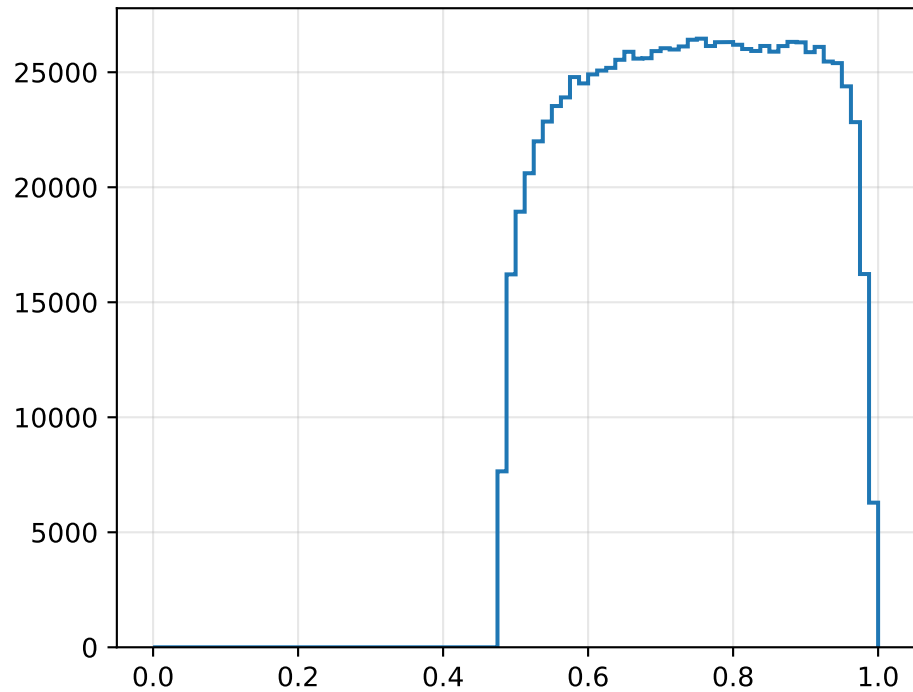
 Q^2 [GeV²]

inelasticity y

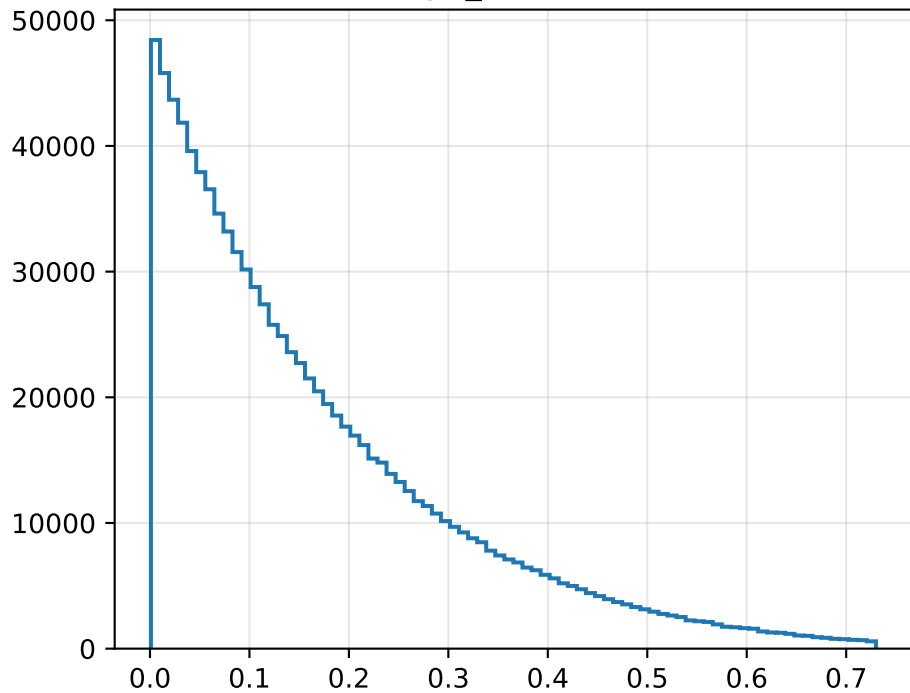
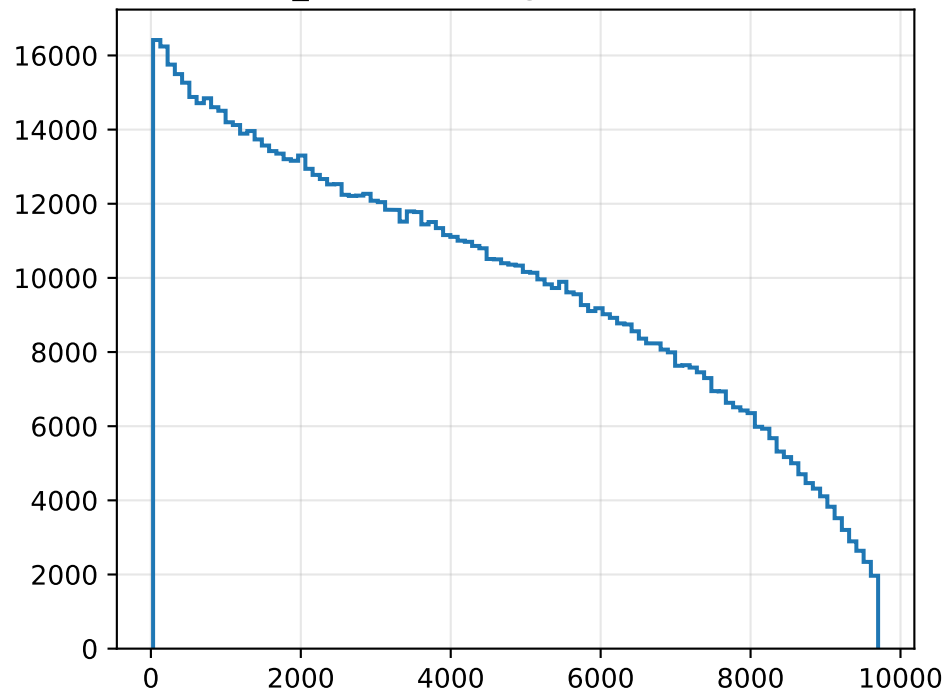
 W^2 [GeV²]

t [GeV²]

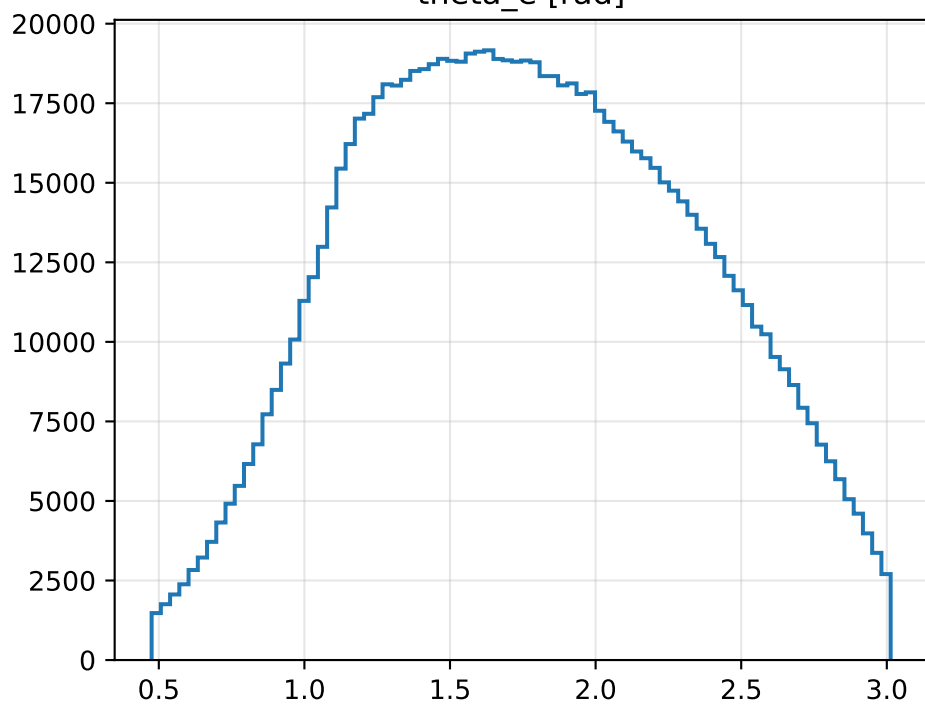
x_L



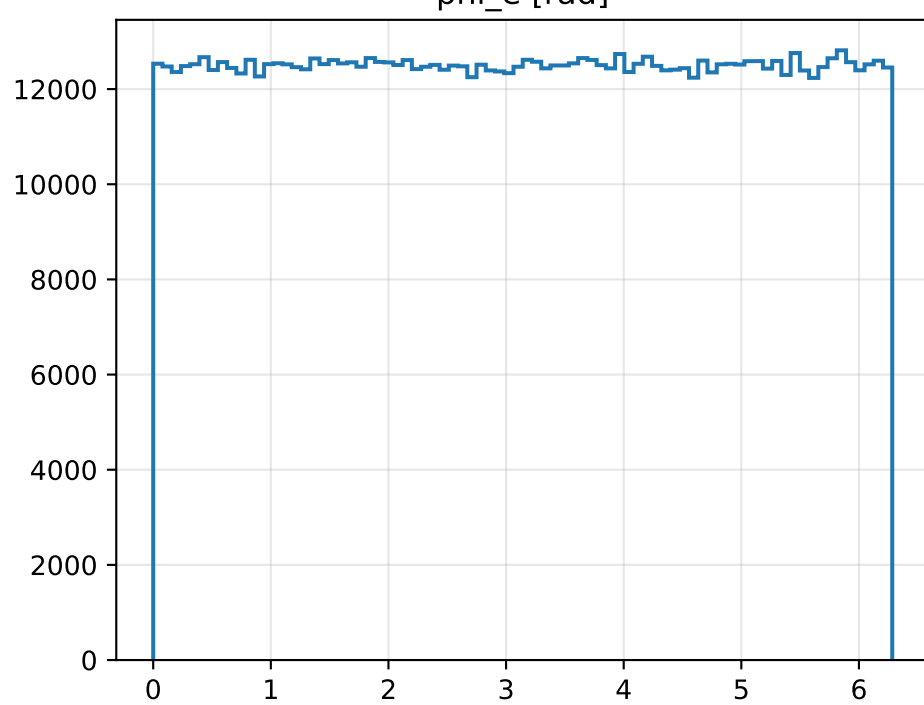
pT_L [GeV]

M_X² [GeV²] (negative allowed)

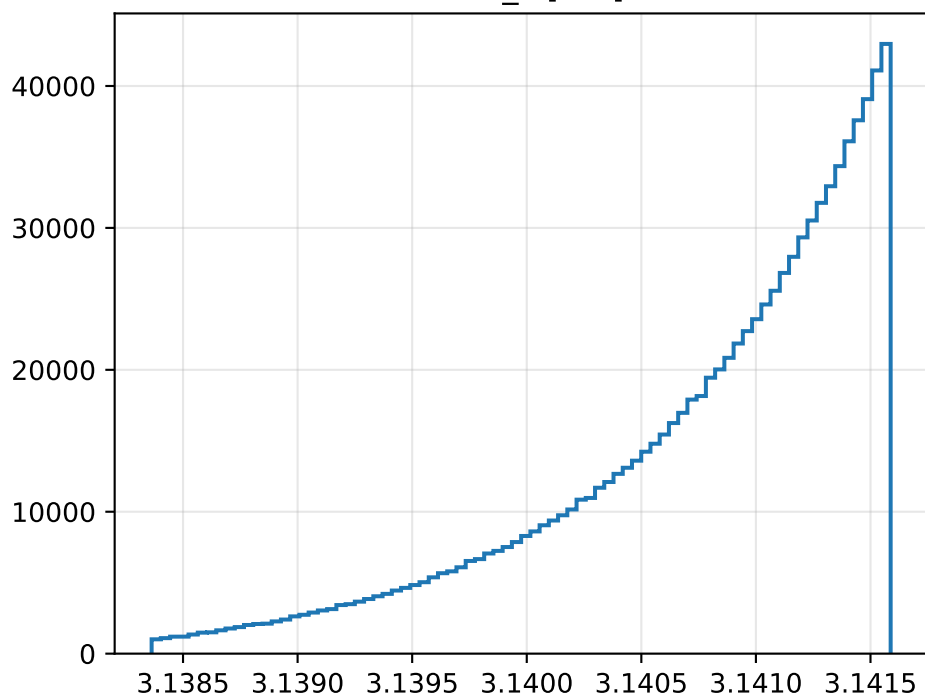
theta_e [rad]



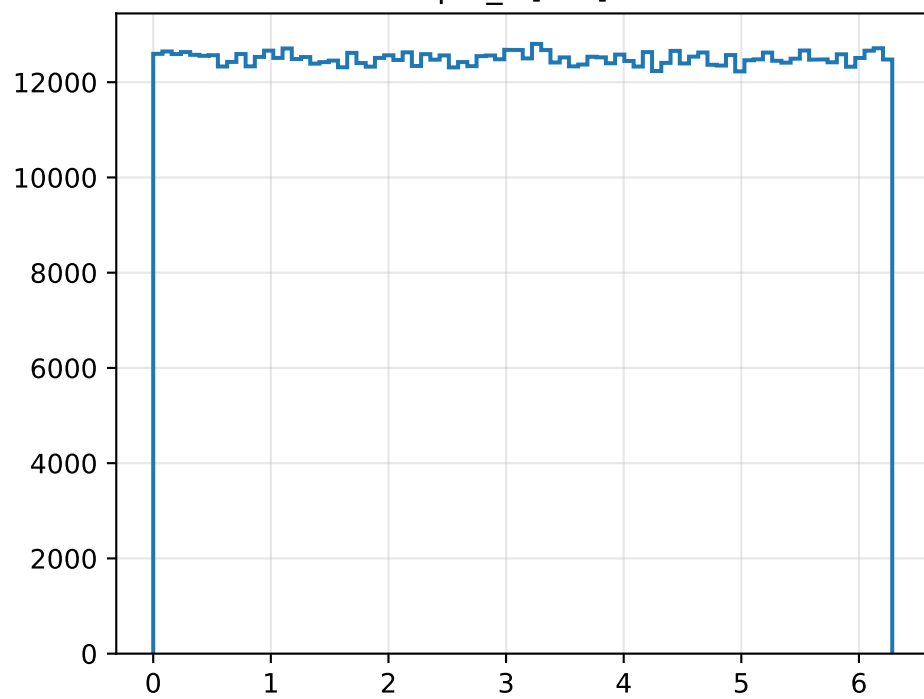
phi_e [rad]

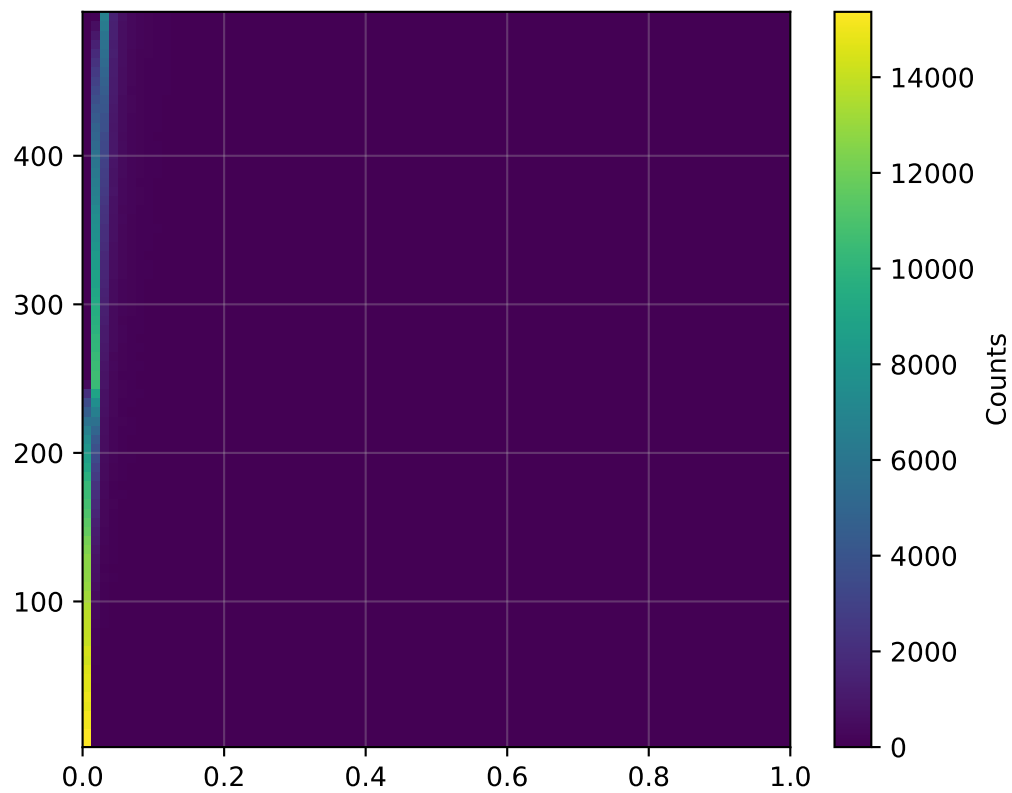
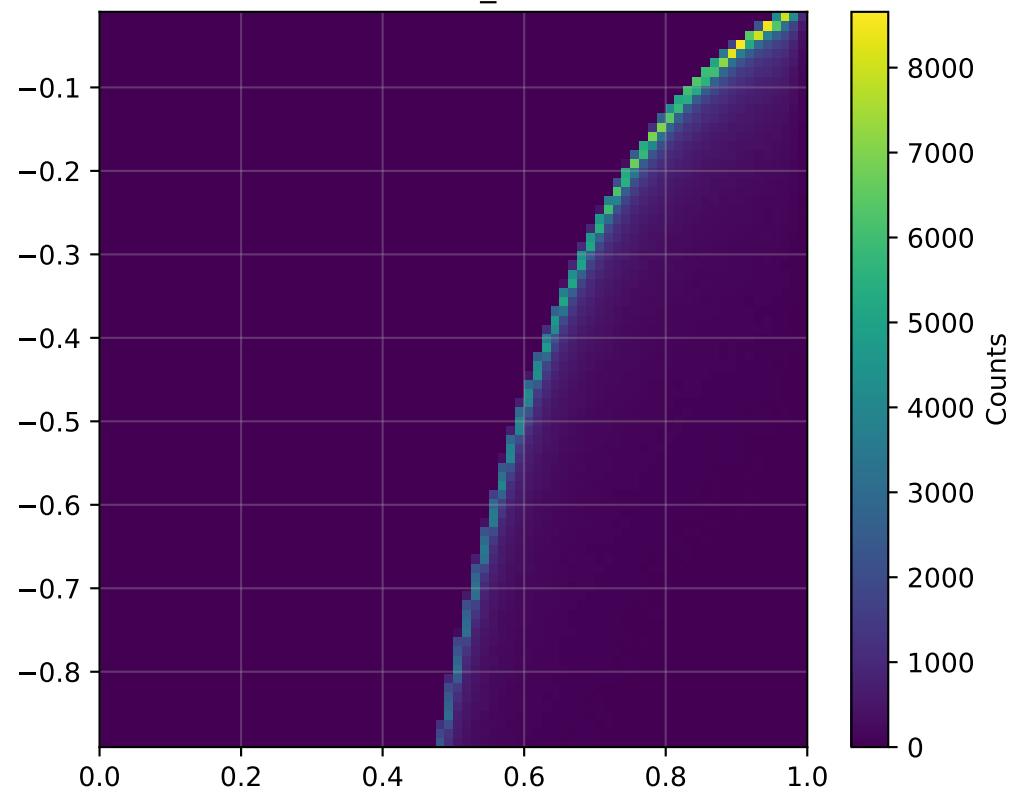
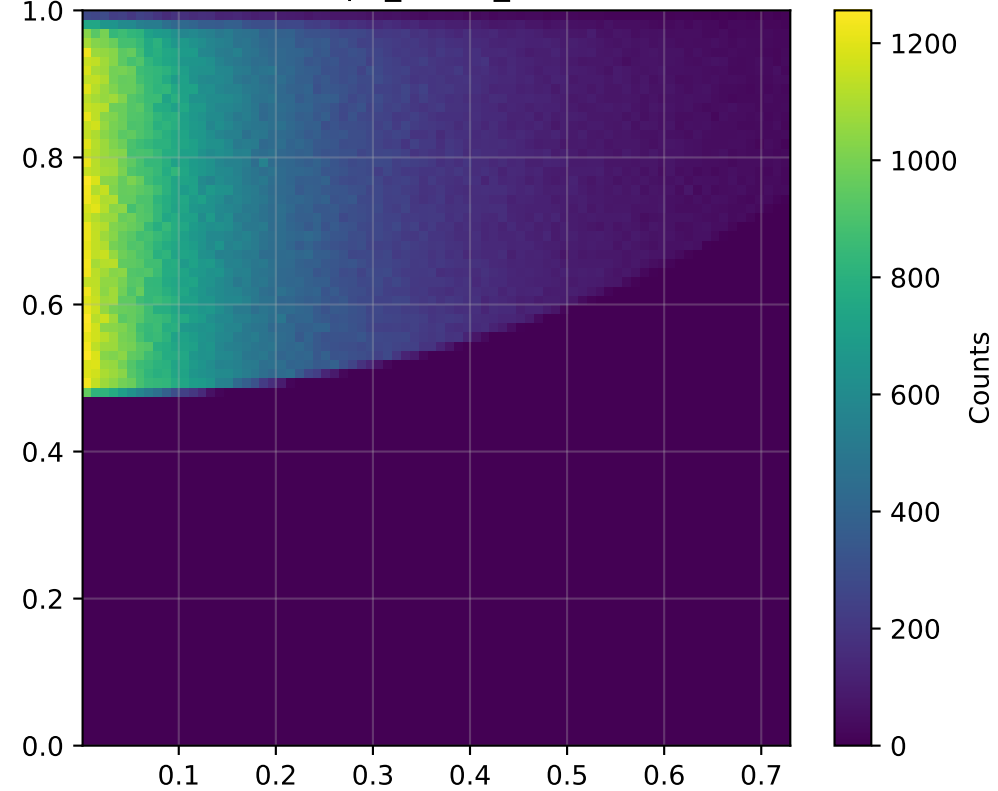
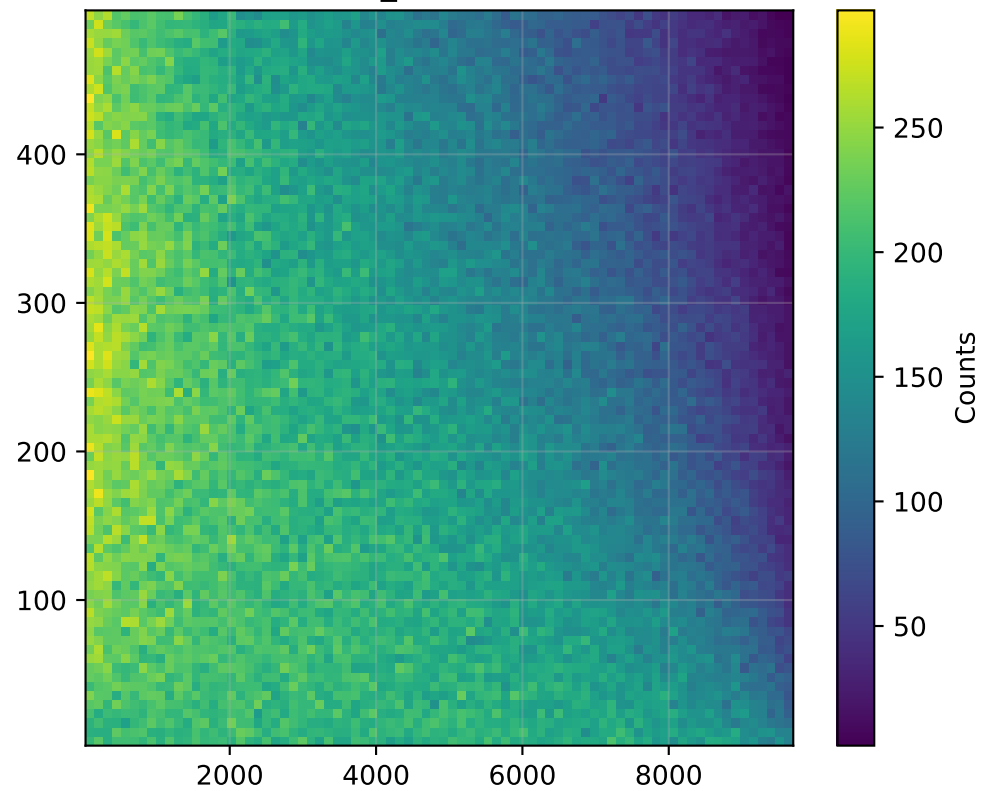


theta_L [rad]

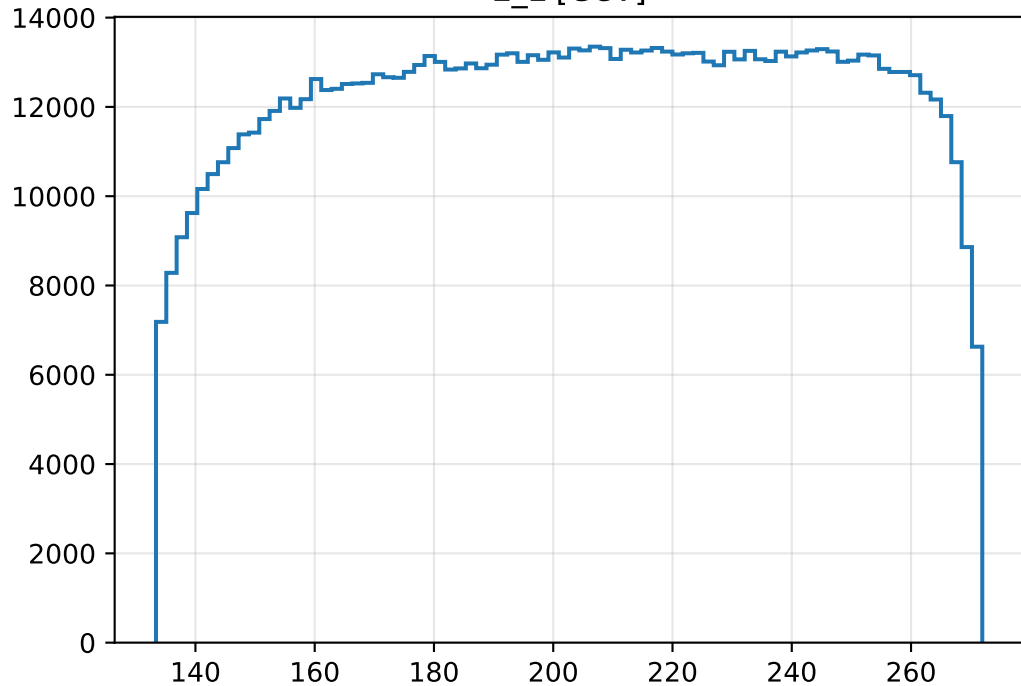
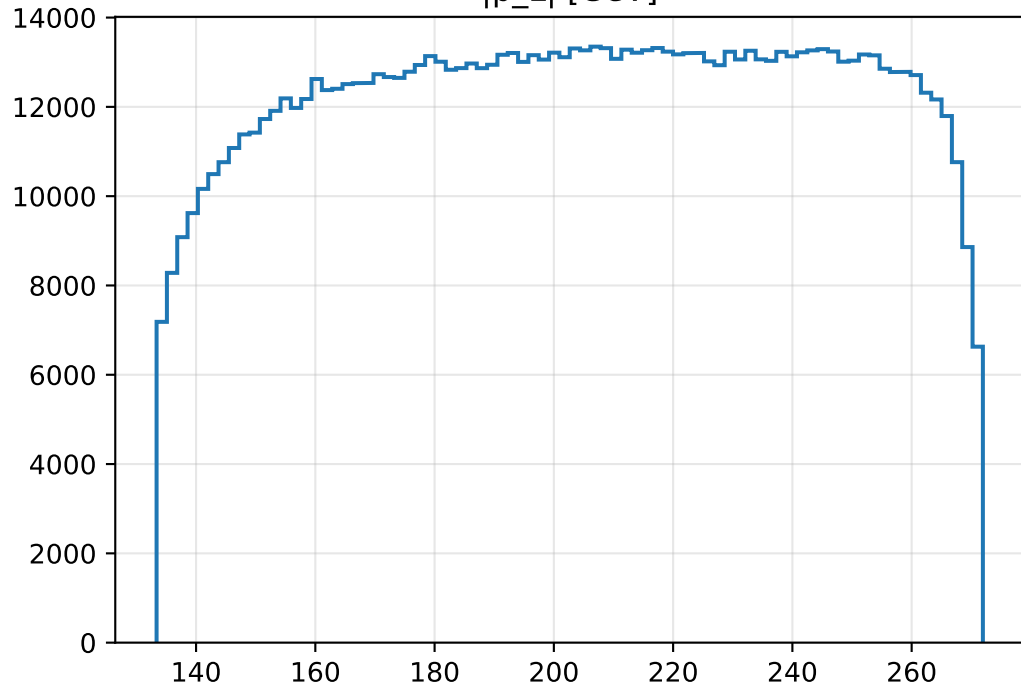


phi_L [rad]

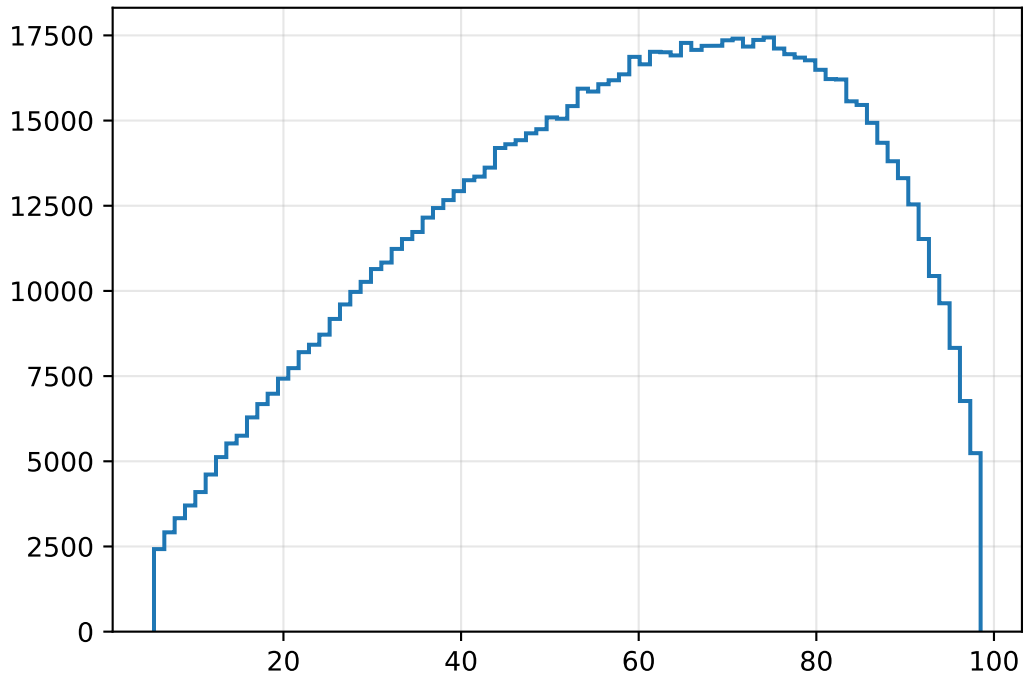


x vs Q^2 t vs x_L pT_L vs x_L  M_X^2 vs Q^2 

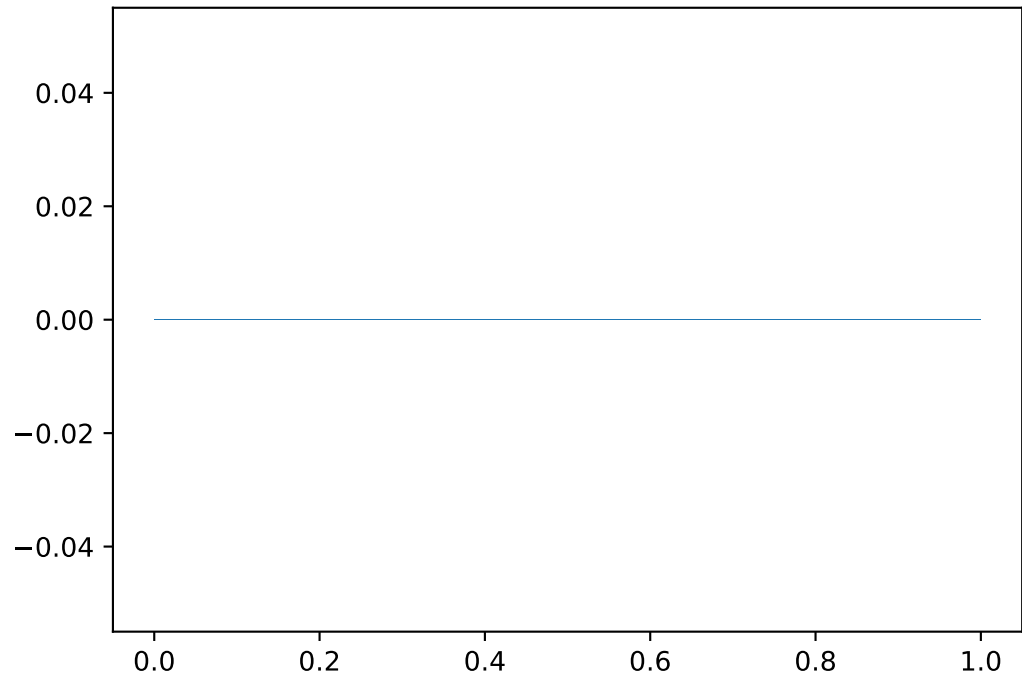
E_L [GeV]

 $|p_L|$ [GeV]

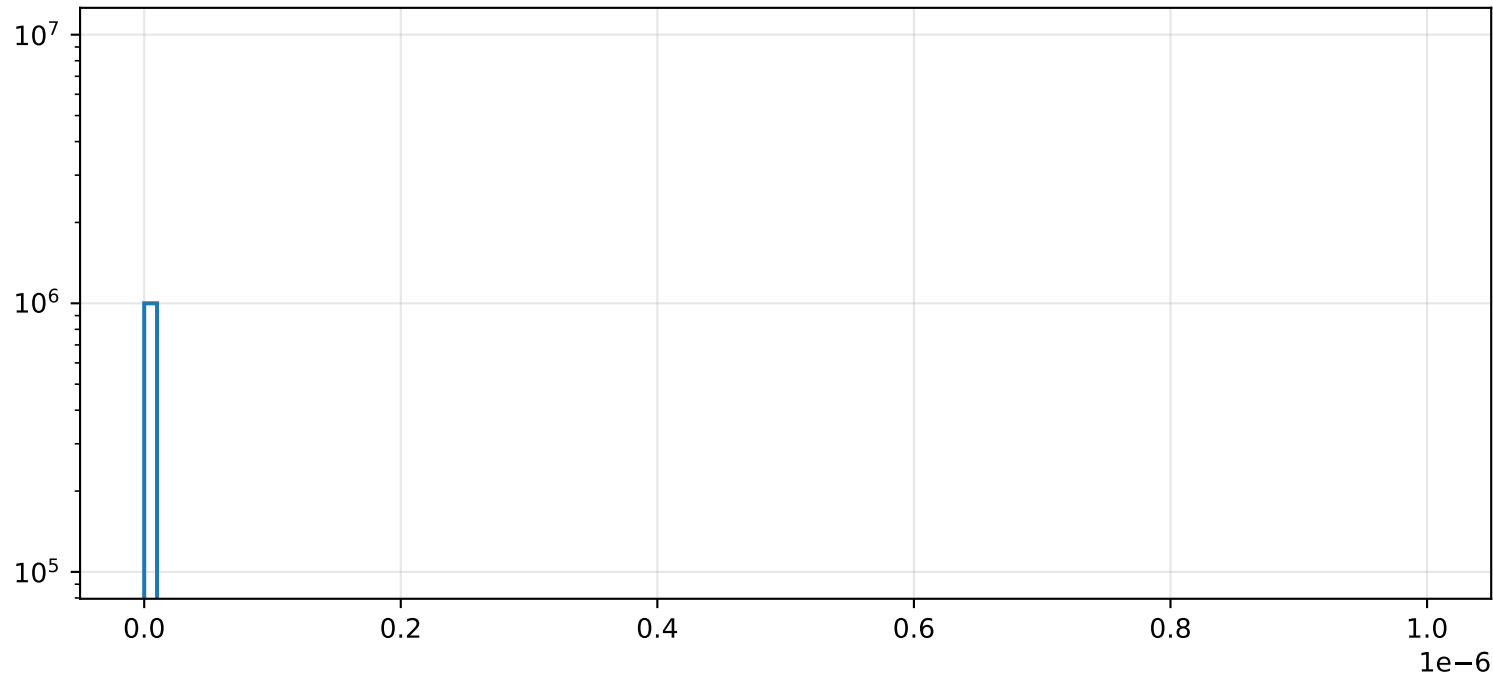
M_X (sqrt of positive M_X²)



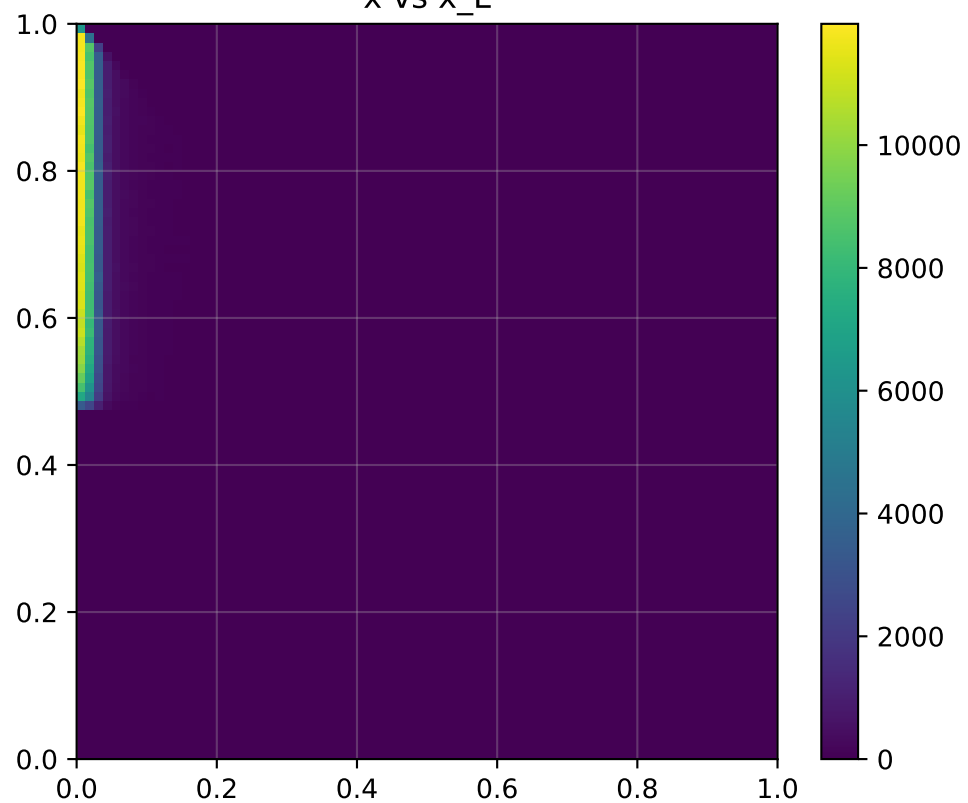
Negative M_X² (count=0)



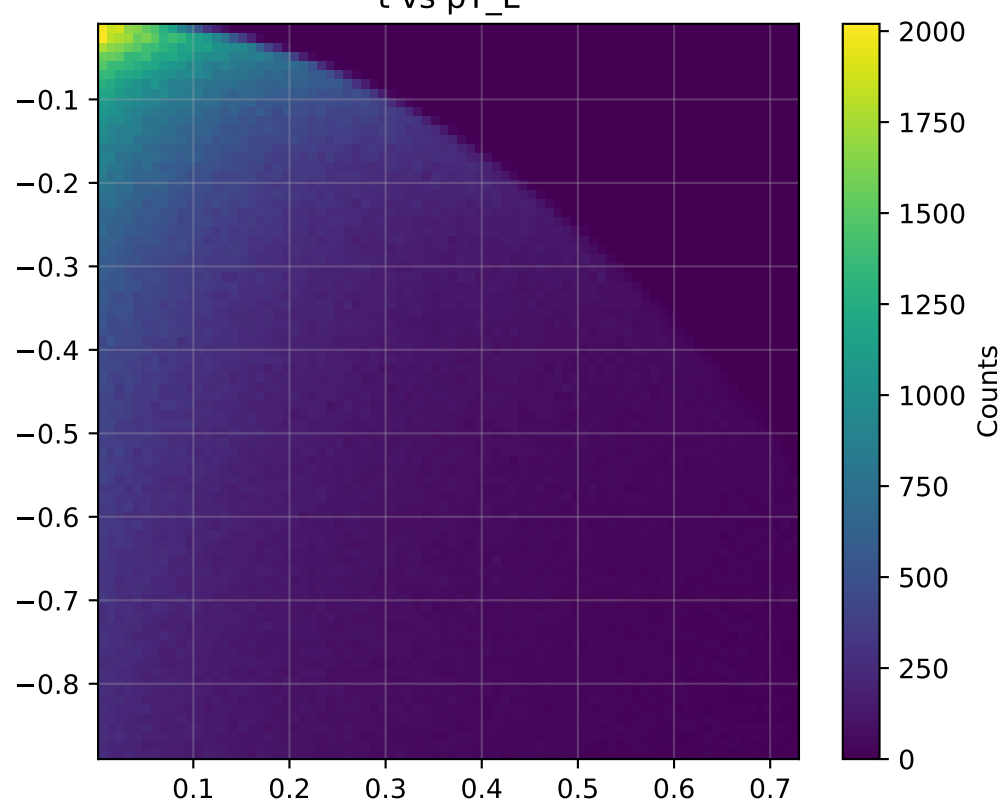
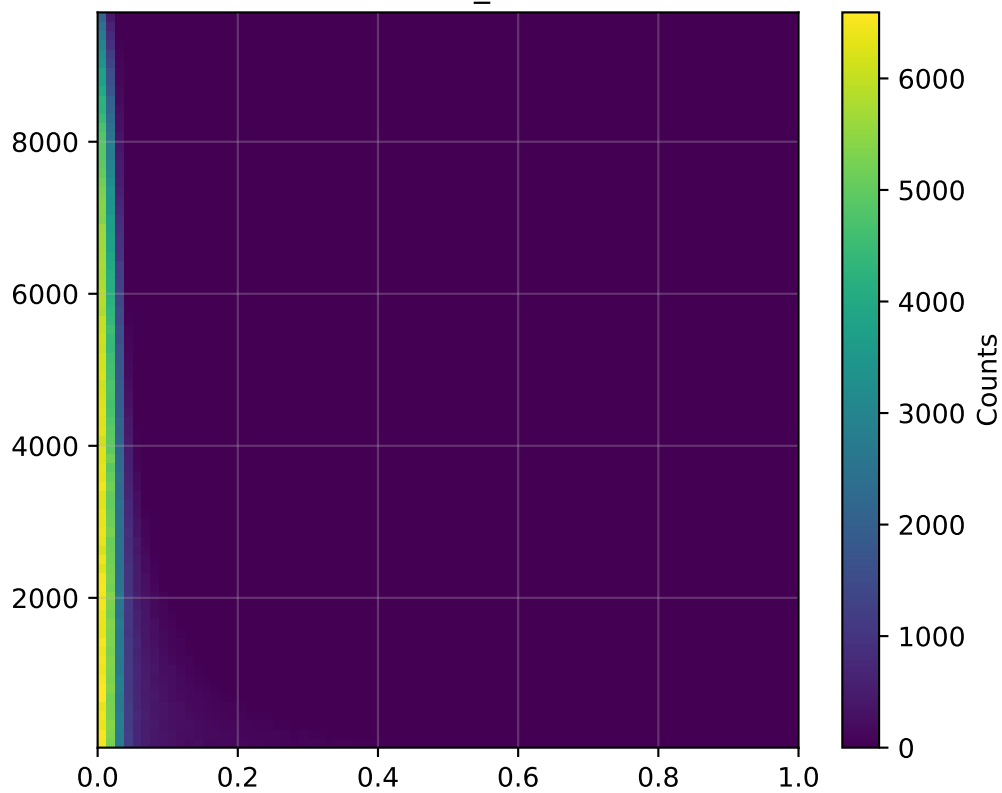
4-vector residual magnitude (Euclidean) [GeV]



x vs x_L



t vs pT_L

x vs M_X²Q² vs M_X²