



Fakultät für Informatik
Lehrstuhl für Echtzeitsysteme und Robotik

Scene-aware and Social-aware Motion Prediction for Autonomous Driving

Alfred Nguyen

Practical Course *Motion Planning for Autonomous Vehicles* WS 2023/2024

Advisor: Dr. Di Liu

Supervisor: Prof. Dr.-Ing. Matthias Althoff

Submission: 20. February 2024

Your title

First name and last name
Technische Universität München
Email: Your email

Abstract—The abstract goes here.

REFERENCES

- [1] H. Kopka and P. W. Daly, *A Guide to L^AT_EX*, 3rd ed. Harlow, England: Addison-Wesley, 1999.

I. INTRODUCTION

This demo file is intended to serve as a “starter file” for IEEE conference papers produced under L^AT_EX using IEEE-tran.cls version 1.8 and later. I wish you the best of success.

mds

December 27, 2012

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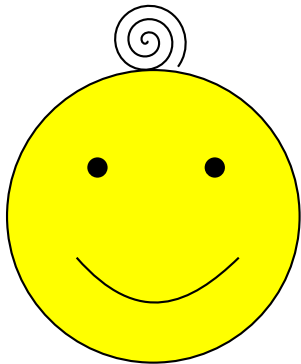


Fig. 1. A vector graphic loaded from a PDF file



Fig. 2. A bitmap graphic loaded from a PNG file

II. CONCLUSION

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