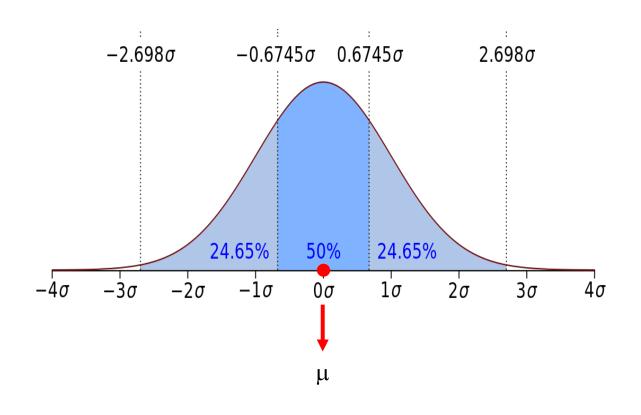




#### Gaussian distribution

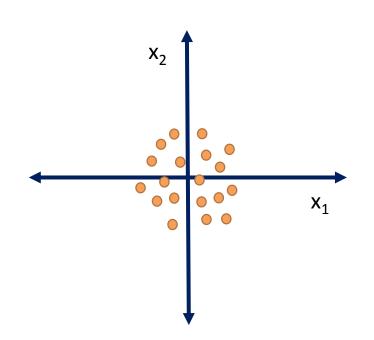


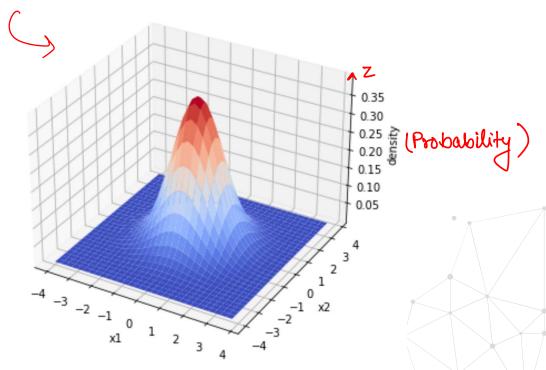
- <u>Univariate</u> Gaussian distributions are determined by  $\mu$  and  $\sigma$
- $\mu$  = Mean value
  - → centre of distribution
- $\sigma$  = standard deviation
  - → measure of dispersion

How for from the mean can the values take place.



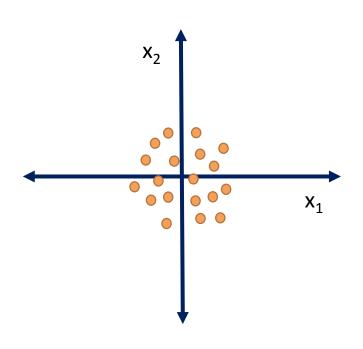
The prob. of x occurring, now x is a vector that contains values n, & x2, is given by the joint probability of (x1, x2). Now, extimating this distribution.





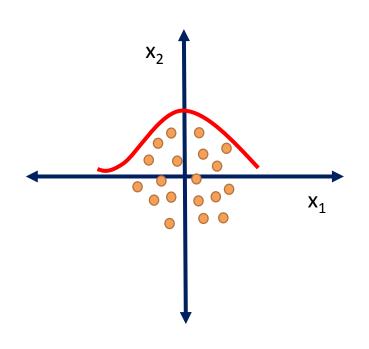
The probability of a value x occurring is given by the joint probability of x1 and x2





- μ1 and μ2.
- $\sigma^2 1$  and  $\sigma^2 2$ .

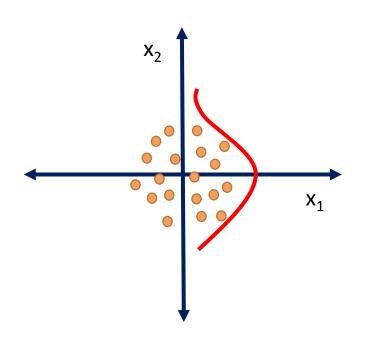




From given values of  $x_1 & x_2$  we can calculate the mean and variance.

- $\mu 1$  and  $\mu 2$ .
- $\sigma^2 1$  and  $\sigma^2 2$ .
- X1 ~N( $\mu$ 1=0,  $\sigma$ <sup>2</sup>1=1)



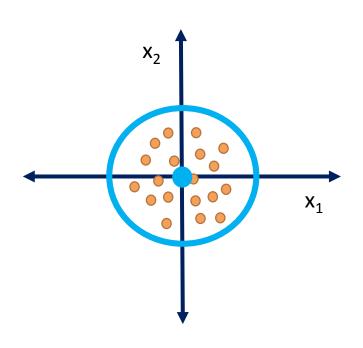


- μ1 and μ2.
- $\sigma^2$ 1 and  $\sigma^2$ 2.

• X1 ~N(
$$\mu$$
1=0,  $\sigma^2$ 1=1)

• X2 ~N( $\mu$ 2=0,  $\sigma^2$ 2=1)

But the params. of the respective variables are not enough to cleatribe the dispersion or joint occurance of each one of these values we want to find a function that allows us to estimate the prob. of each of these vectors occuring



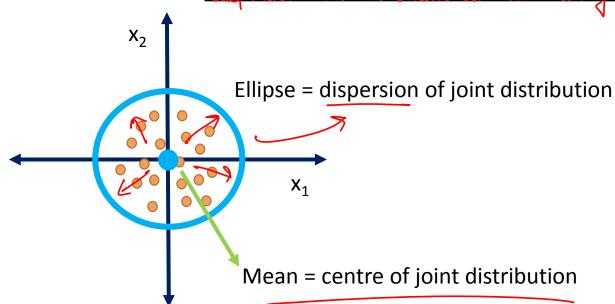
- μ1 and μ2.
- $\sigma^2 1$  and  $\sigma^2 2$ .
- X1 ~N( $\mu$ 1=0,  $\sigma^2$ 1=1)
- $X2 \sim N(\mu 2=0, \sigma^2 2=1)$



This joint distribution has a center, denoting the mean of values, in this case it's a vector.

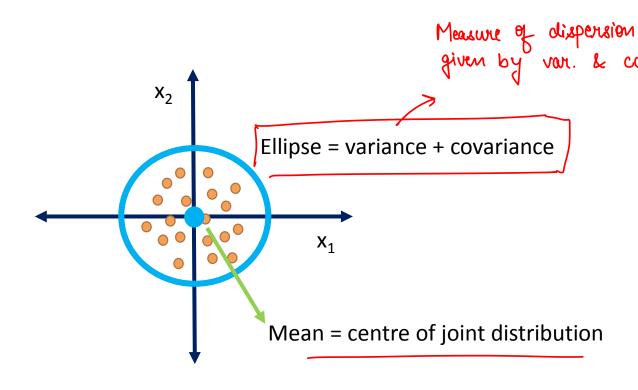
And a measure of dispersion, denoted by the Ellipse (here circle), shows the

dispersion that the values can take away from the mean in any direction.



- μ1 and μ2.
- $\sigma^2 1$  and  $\sigma^2 2$ .
- X1 ~N( $\mu$ 1=0,  $\sigma^2$ 1=1)
- X2 ~N( $\mu$ 2=0,  $\sigma^2$ 2=1)

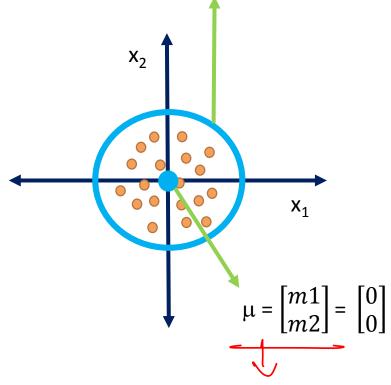




- μ1 and μ2.
- $\sigma^2 1$  and  $\sigma^2 2$ .
- X1 ~N( $\mu$ 1=0,  $\sigma^2$ 1=1)
- $X2 \sim N(\mu 2=0, \sigma^2 2=1)$



Covariance matrix = 
$$\Sigma = \begin{bmatrix} K_{X1X1} & K_{X1X2} \\ K_{X2X1} & K_{X2X2} \end{bmatrix} = \begin{bmatrix} \nabla_{\mathbf{x}_1 \mathbf{x}_1}^2 & \nabla_{\mathbf{x}_1 \mathbf{x}_2}^2 \\ \nabla_{\mathbf{x}_2 \mathbf{x}_1}^2 & \nabla_{\mathbf{x}_2 \mathbf{x}_2}^2 \end{bmatrix} \Rightarrow \text{Capturs variance}$$



• 
$$\sigma^2 1$$
 and  $\sigma^2 2$ .

• μ1 and μ2.

• X1 ~N(
$$\mu$$
1=0,  $\sigma^2$ 1=1)

• 
$$X2 \sim N(\mu 2=0, \sigma^2 2=1)$$

• 
$$X = \begin{bmatrix} x1 \\ x2 \end{bmatrix} \sim N(\mu = \begin{bmatrix} m1 \\ m2 \end{bmatrix}, \Sigma = \begin{bmatrix} K_{X1X1} & K_{X1X2} \\ K_{X2X1} & K_{X2X2} \end{bmatrix})$$



- Generalizes the univariate Gaussian distribution to higher dimensions
  - ✓ More than 1 variable
  - ✓ Instead of values, we now have <u>vectors</u>
- Multivariate Gaussian distributions need  $\mu$ ,  $\sigma^2$  and the covariance  $\Sigma$ 
  - Covariance matrix: captures  $\sigma^2$  and  $\Sigma$



Measure of joint probability of 2 random variables.

Measure of correlation:

• Cov(X1, X2) = 
$$\frac{\sum (x_{ij} - x_{jmean})(x_{ik} - x_{kmean})}{n}$$



Measure of joint probability of 2 random variables.

• Cov(X1, X2) = 
$$\frac{\sum (x_{ij} - x_{jmean})(x_{ik} - x_{kmean})}{n}$$

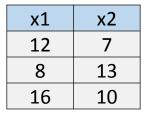
X1	X2	
12	10	
8	7	
16	13	

$$Cov(X1, X2) = \frac{(12-12)*(10-10)+(8-12)*(7-10)+(16-12)*(13-10)}{3} = 8$$



x1	x2
12	10
8	7
16	13

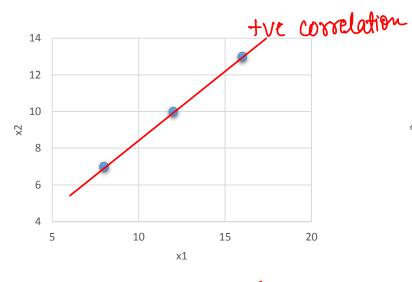
x1	x2
12	10
8	13
16	7

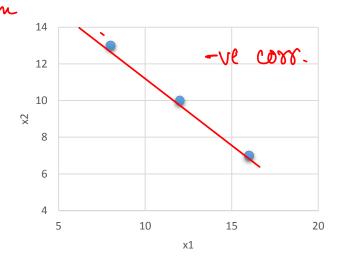


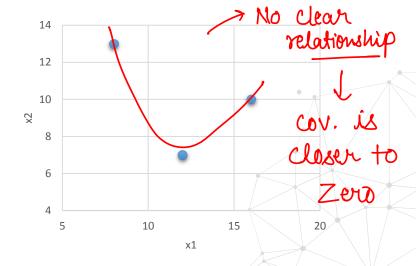
12 10











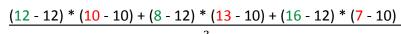
Cov(X1, X2) = ?

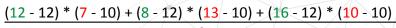
(12 - 12) \* (10 - 10) + (8 - 12) \* (7 - 10) + (16 - 12) \* (13 - 10)

= 8

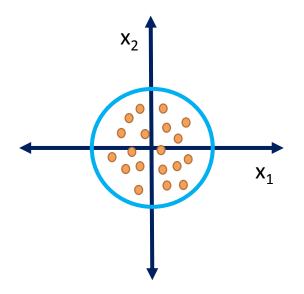
$$Cov(X1, X2) = -8$$

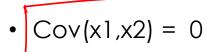
= - 8



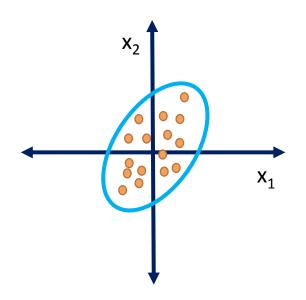


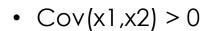
Cov(X1, X2) = -4

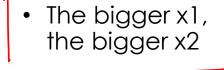




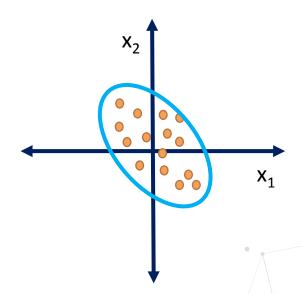
X1 and x2 are not correlated











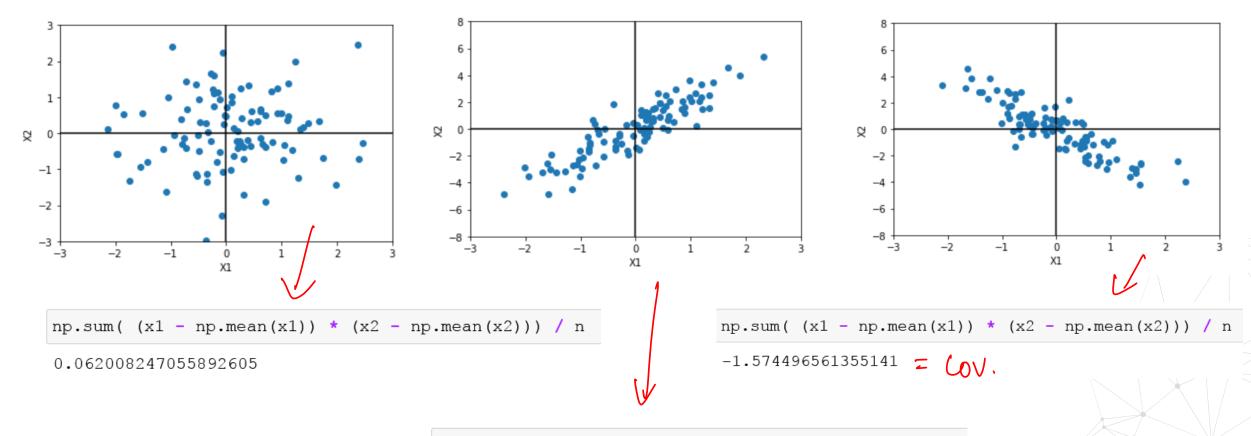
• Cov(x1,x2) < 0

 The bigger x1, the smaller x2









np.sum((x1 - np.mean(x1)) \* (x2 - np.mean(x2))) / n

1.7016981044990922



#### **Covariance Matrix**

- Square matrix with the covariance of each pair of variables.
- Symmetric
- The diagonal contains the variances, i.e., the covariance of each variable with itself

 The covariance matrix provides a succinct way to summarize the covariance of all pairs of variables

$$\sum = \begin{bmatrix} T_{x_{1}x_{1}} & T_{x_{1}x_{2}} \\ T_{x_{2}x_{1}} & T_{x_{2}x_{2}} \end{bmatrix}$$

$$\sum = \begin{bmatrix} K_{x_{1}x_{1}} & K_{x_{1}x_{2}} \\ K_{x_{2}x_{1}} & K_{x_{2}x_{2}} \end{bmatrix}$$

#### Where:

- Kx1x1 = var(x1)
- Kx2x2 = var(x2)
- $Kx1x2 = K^Tx2x1 = cov(x1, x2)$

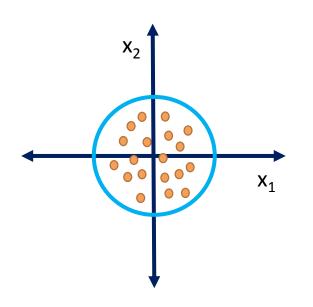


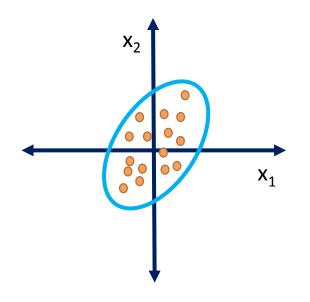
#### Covariance Matrix - General

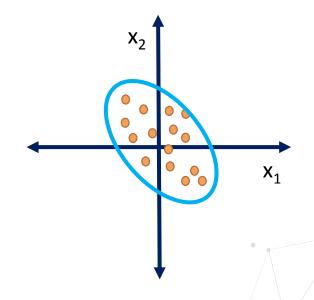
$$\Sigma = \begin{bmatrix} Kx_1x_1 & \cdots & Kx_1x_n \\ \vdots & \ddots & \vdots \\ Kx_nx_1 & \cdots & Kx_nx_n \end{bmatrix}$$



#### Covariance Matrix





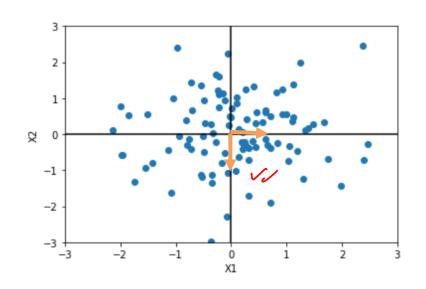


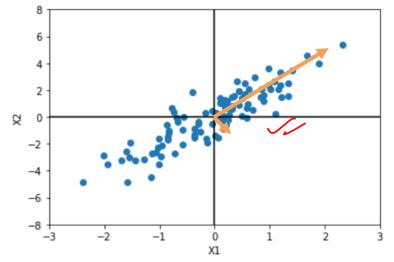
$$\Sigma = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

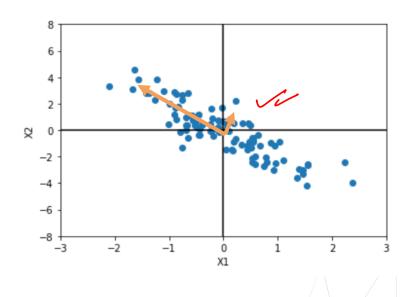
$$\Sigma = \begin{bmatrix} 1 & 0.5 \\ 0.5 & 1 \end{bmatrix}$$

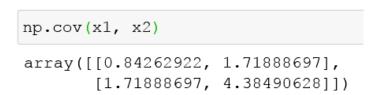
$$\Sigma = \begin{bmatrix} 1 & -0.5 \\ -0.5 & 1 \end{bmatrix}$$

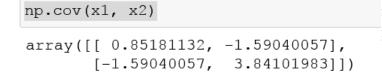
#### Covariance Matrix: simulation



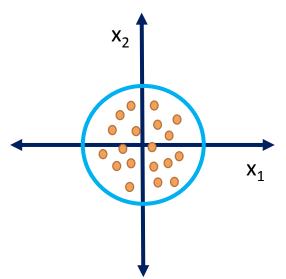






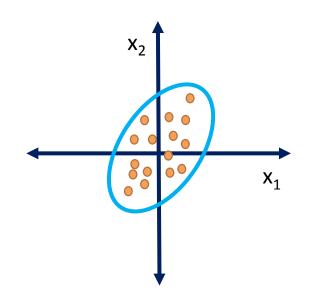


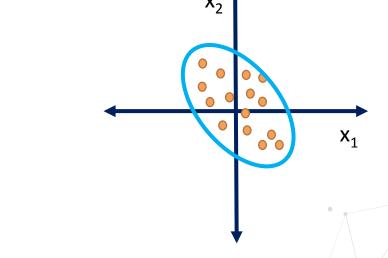




$$X = \begin{bmatrix} x1 \\ x2 \end{bmatrix} \sim N(\mu = \begin{bmatrix} 0 \\ 0 \end{bmatrix}, \Sigma = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix})$$

$$\times \sim N(\mu, \Sigma)$$



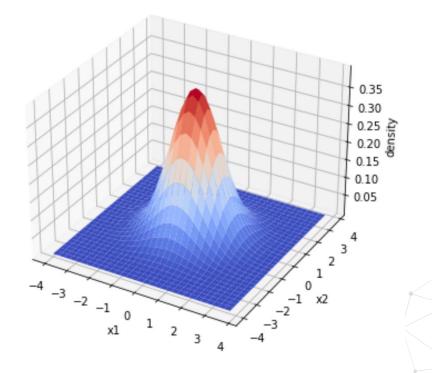


$$\begin{bmatrix} x1\\ x2 \end{bmatrix} \sim \mathsf{N}(\mu = \begin{bmatrix} 0\\ 0 \end{bmatrix}, \Sigma = \begin{bmatrix} 1 & -0.5\\ -0.5 & 1 \end{bmatrix})$$

$$\begin{bmatrix} x1\\ x2 \end{bmatrix} \sim \mathsf{N}(\mu = \begin{bmatrix} 0\\ 0 \end{bmatrix}, \, \Sigma = \begin{bmatrix} 1 & 0.5\\ 0.5 & 1 \end{bmatrix})$$



$$f_{\mathbf{X}}(x_1,\ldots,x_k) = rac{\expigl(-rac{1}{2}(\mathbf{x}-oldsymbol{\mu})^{\mathrm{T}}oldsymbol{\Sigma}^{-1}(\mathbf{x}-oldsymbol{\mu})igr)}{\sqrt{(2\pi)^k|oldsymbol{\Sigma}|}}$$



The probability of a value x occurring is given by the joint probability of x1 and x2



## THANK YOU

www.trainindata.com