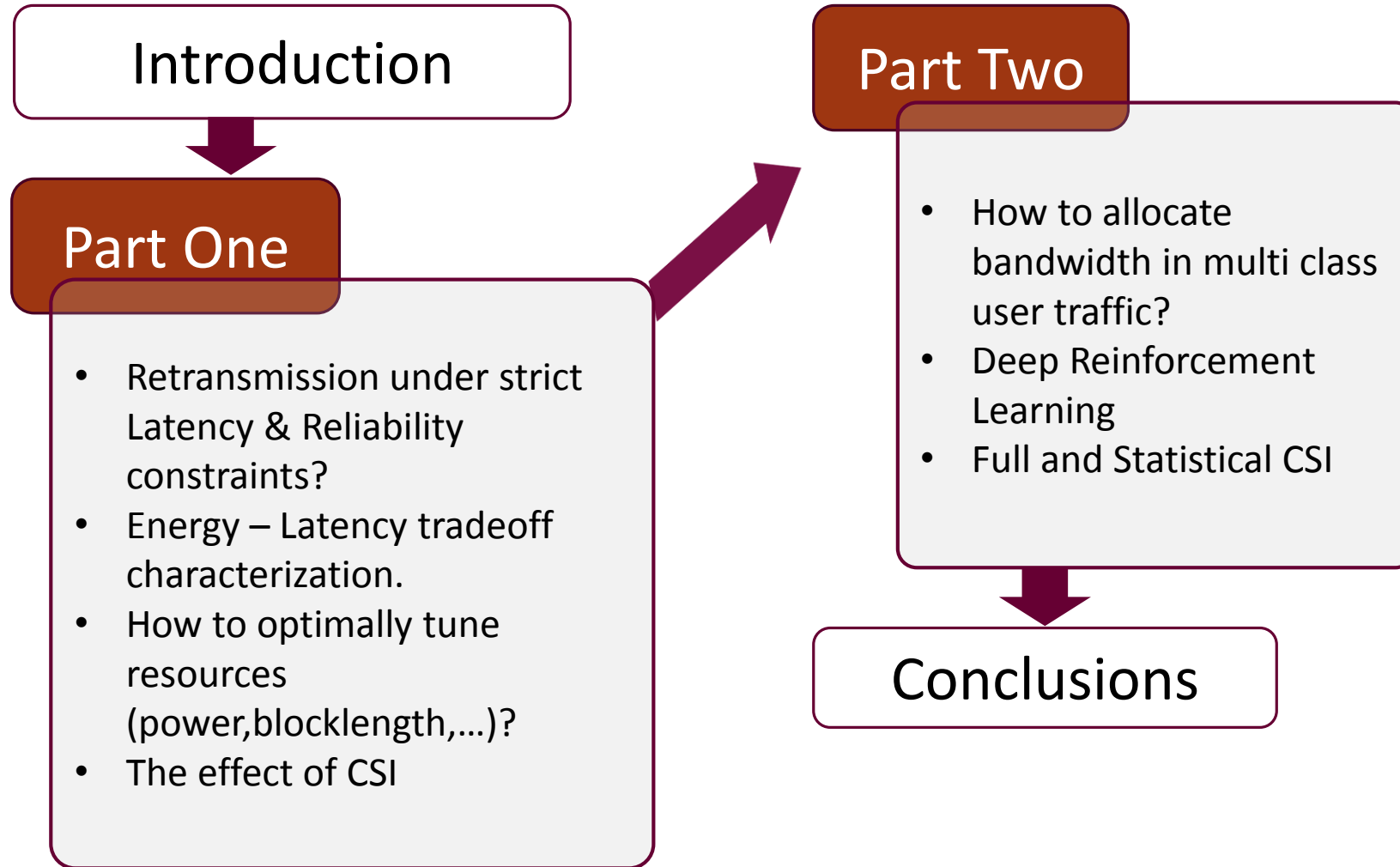


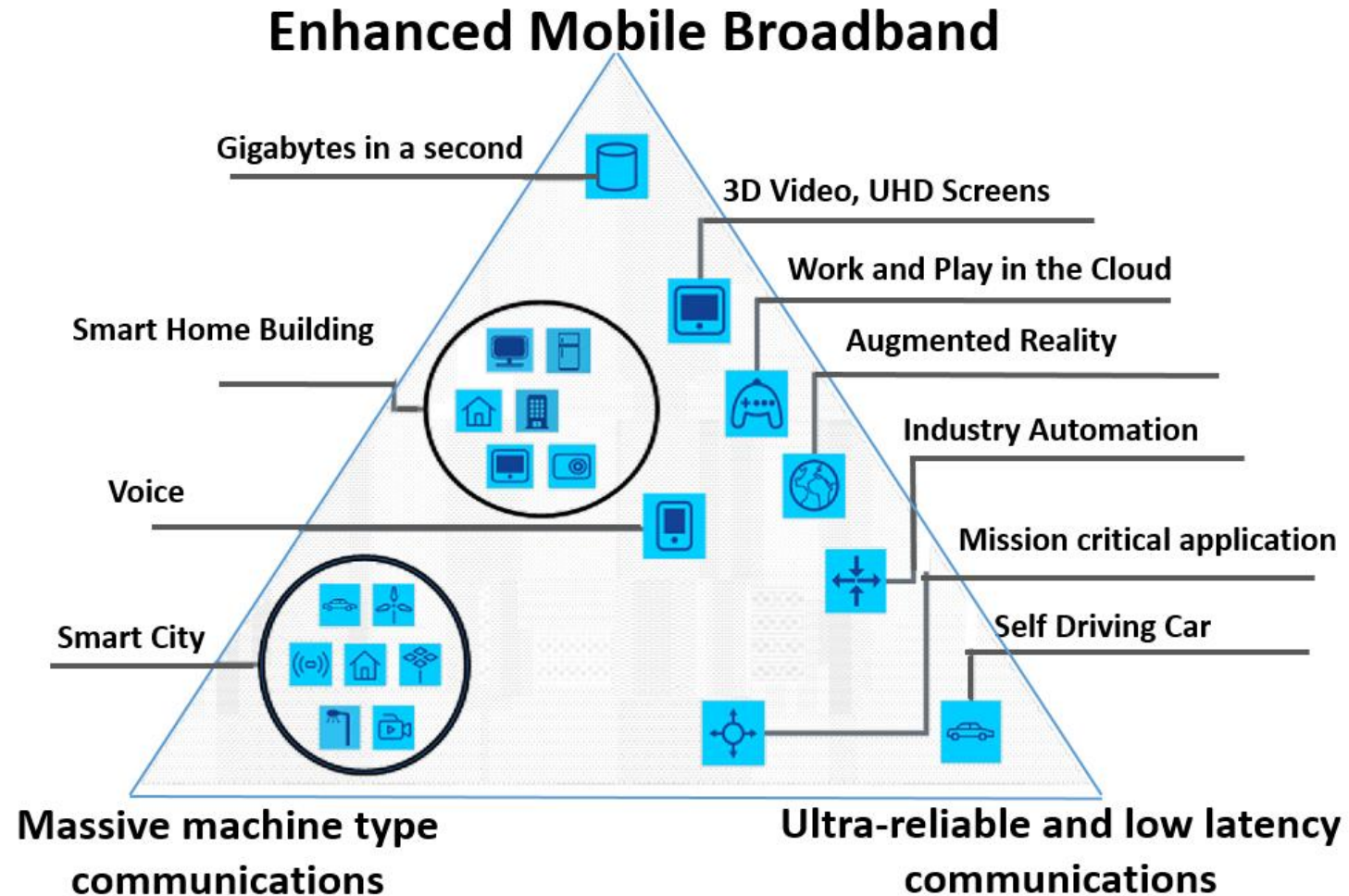
Resource Allocation for Latency sensitive Wireless Systems

Apostolos Avranas

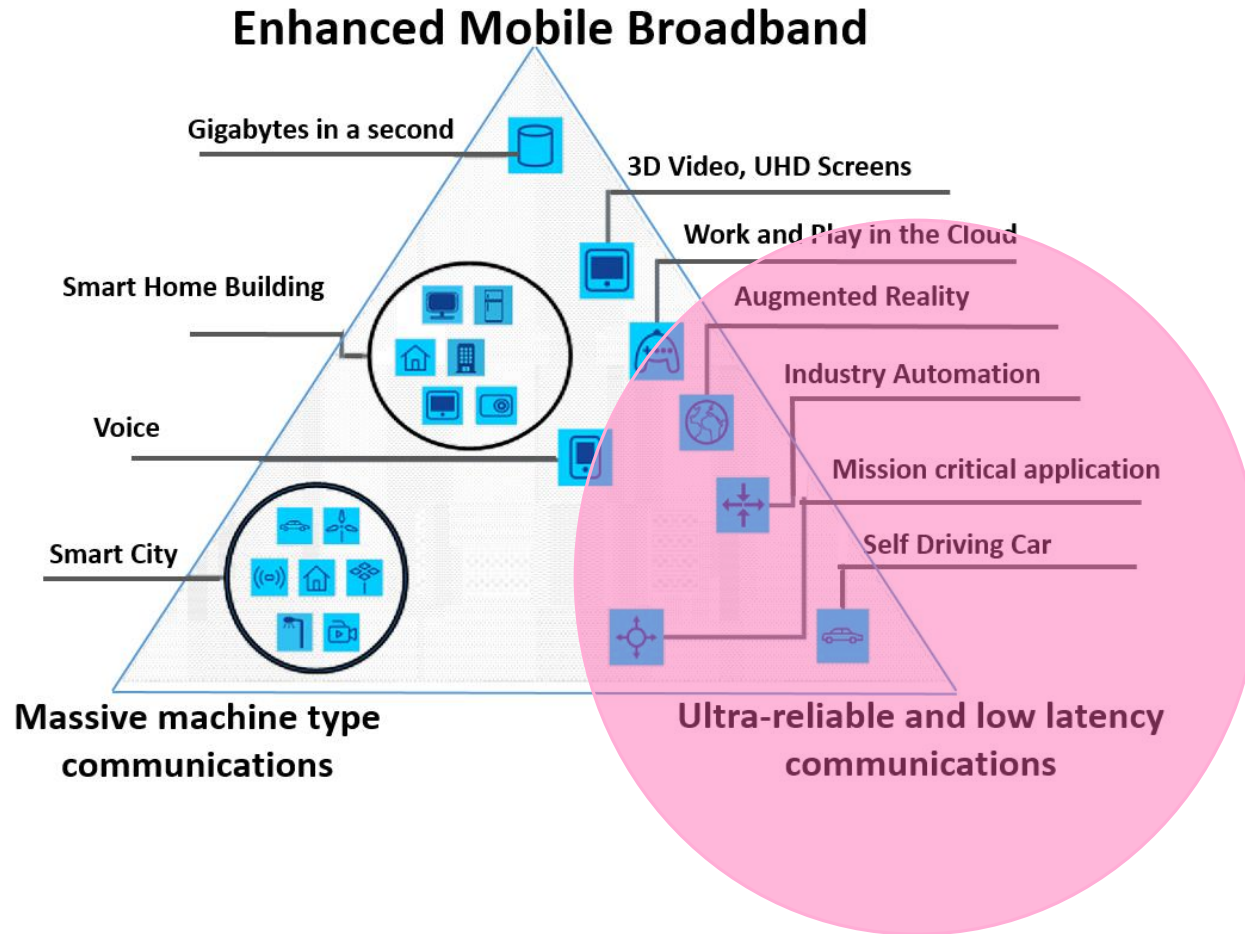
Ph.D. Thesis Defense

Outline





Our focus



Use case	Latency (ms)	Reliability (PEP)	Data size (bytes)
Industrial automation	0.25 – 10	$10^{-6} - 10^{-9}$	10 – 300
Smart grids	5 – 50	10^{-6}	80 – 1000
Intelligent transport systems	5 – 100	$10^{-3} - 10^{-5}$	500 – 1k
Telemedicine	1 – 10 (haptics) 20 – 100 (video, audio)	10^{-5}	200 – 4k

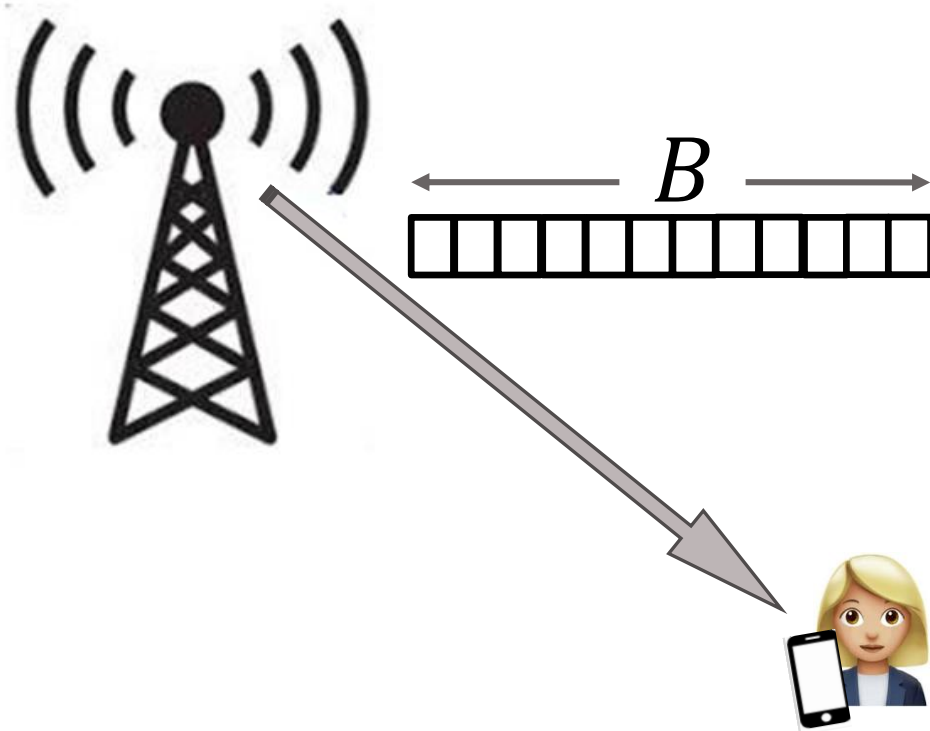
URLLC : 1 ms , 10^{-5} , 32 bytes

Part One

System Model

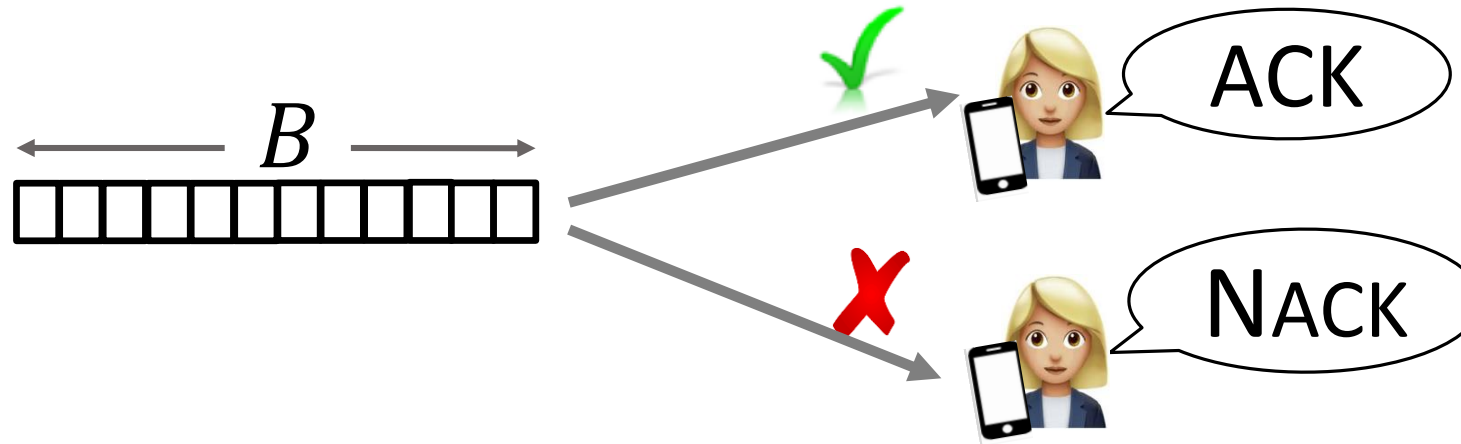
URLLC is tough!

- ❖ Diversity: Frequency, Space, Time
- ❖ *What about retransmissions?*



- Point to Point
- B Information Bits

System Model



In case of NACK it will be transmitted:

Hybrid Automatic ReQuest (HARQ)

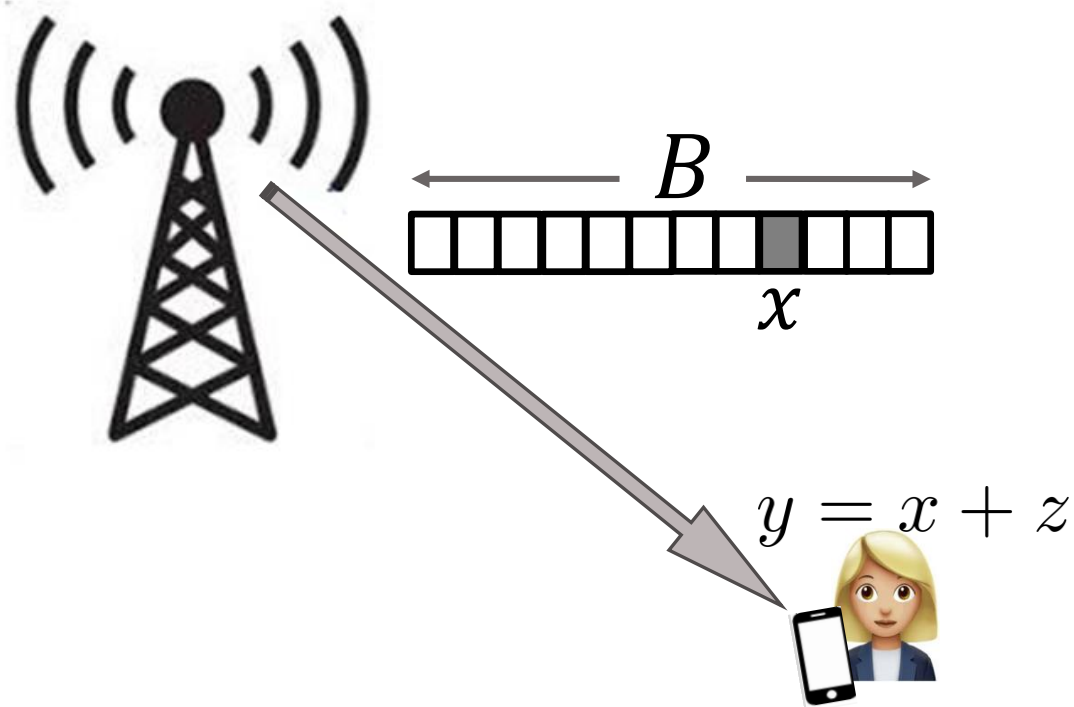
Type I HARQ



Incremental Redudancy HARQ

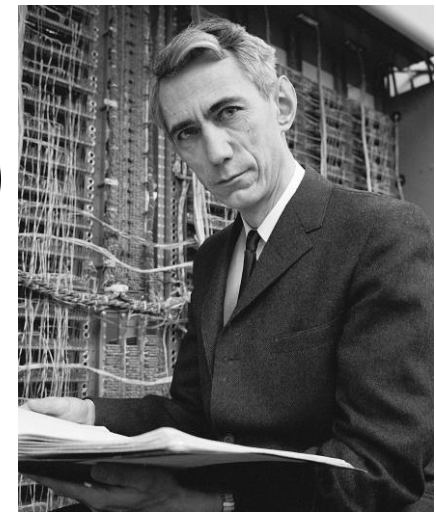


System Model



Assumption: $n \rightarrow \infty$

- AWGN: $z \sim \mathcal{CN}(0, 1)$
- Received power:
$$P = \frac{\text{EnergyPacket}}{n}, n = \#\text{symbols}$$
- Data Rate:
$$\frac{B}{n} = \log_2(1 + P)$$



Shannon (1916-2001)

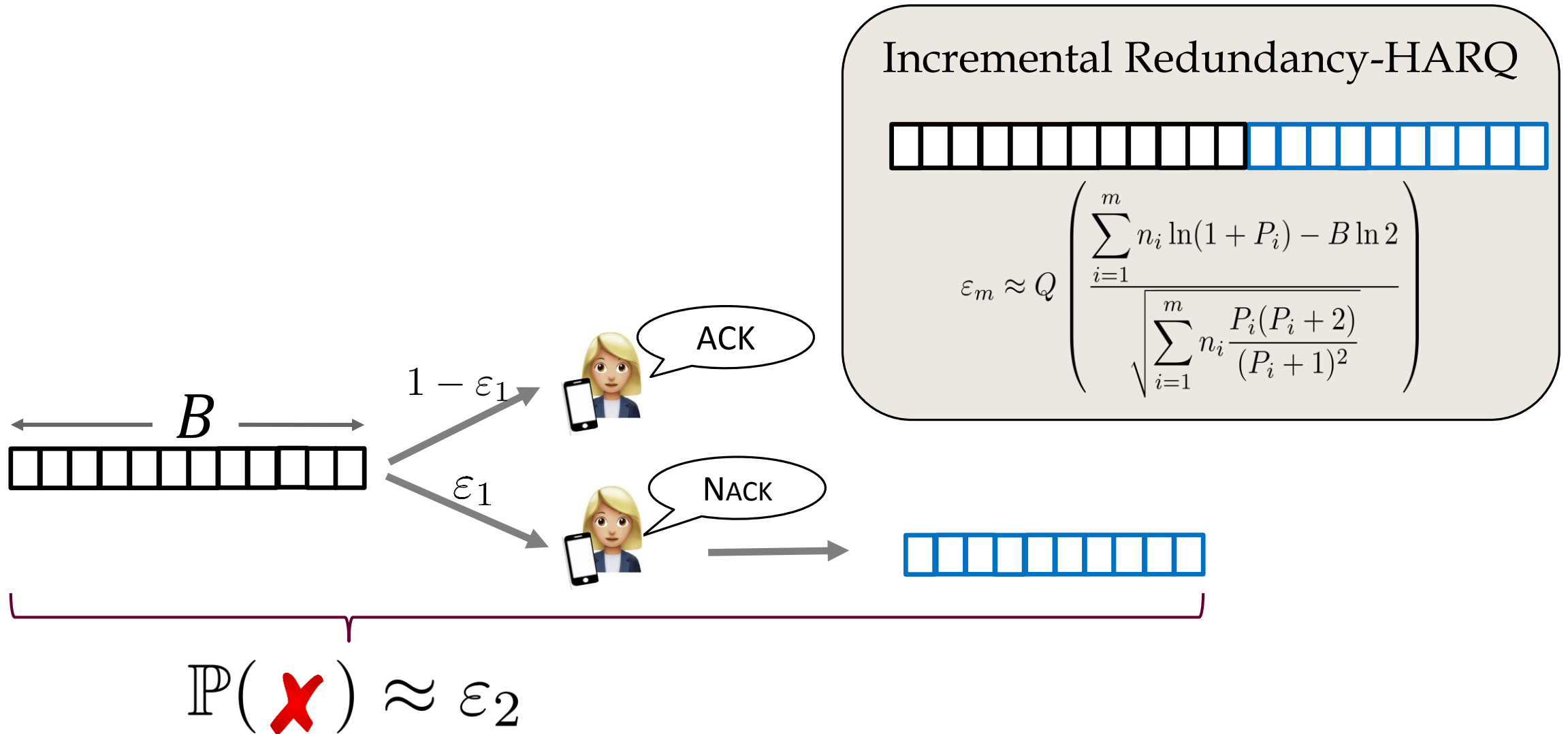
Finite Blocklength ($n < \infty$)

$$\frac{B}{n} \approx \log_2(1 + P) - \underbrace{\frac{Q^{-1}(\varepsilon)}{\sqrt{n}} \sqrt{1 - \frac{1}{(1+P)^2}}}_{\text{dispersion } V} \log_2 e + \dots$$
$$\Rightarrow \varepsilon \approx Q \left(\frac{n \ln(1+P) - B \ln 2}{\sqrt{n \frac{P(P+2)}{(P+1)^2}}} \right)$$

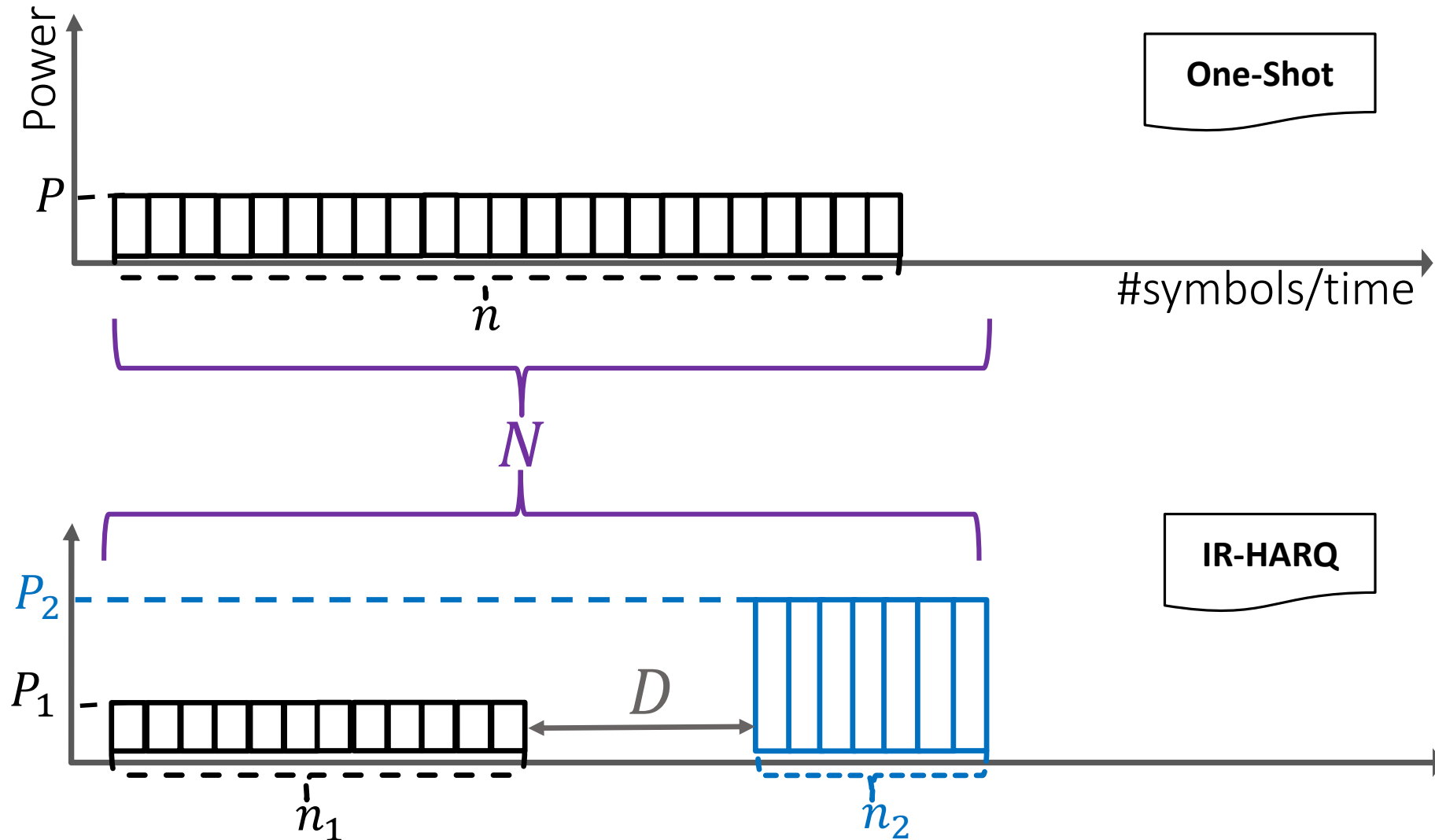
* Y. Polyanskiy, H.V. Poor, S. Verdú, "Channel coding rate in the finite blocklength regime", IEEE Trans. on Inf. Theory, vol. 56, no. 5, Apr. 2010

* M. Hayashi, "Information spectrum approach to second-order coding rate in channel coding", IEEE Trans. on Inf. Theory, vol. 55, no. 11, Nov. 2009

Sharpening System Model



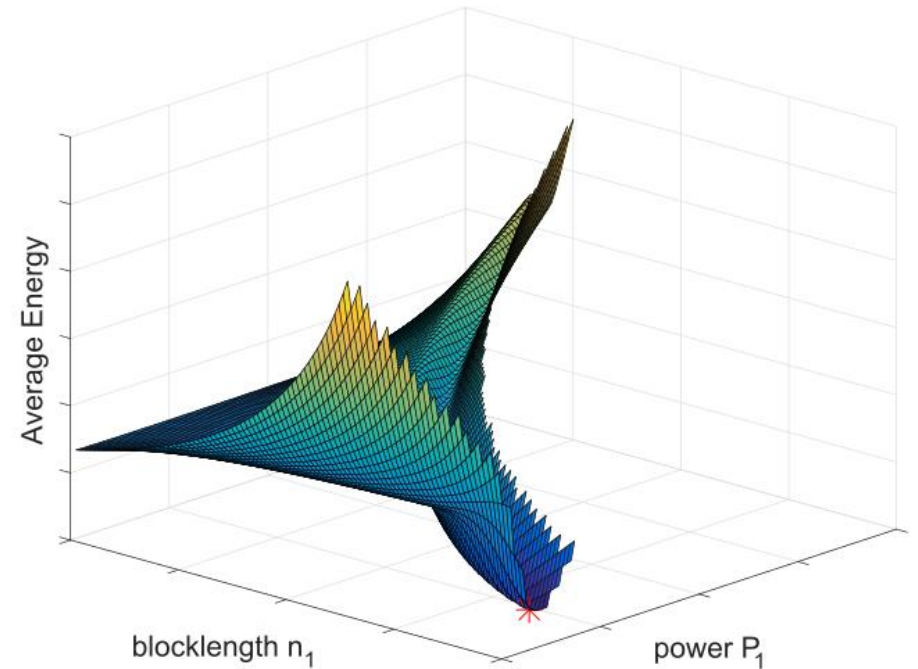
One-shot or HARQ-IR?



Minimization $\mathbb{E}[\text{Energy}]$

$$\begin{aligned} \min_{n_1, P_1, n_2, P_2} \quad & n_1 P_1 + n_2 P_2 \varepsilon_1 \quad (\mathbb{E}[\text{Energy}]) \\ \text{s.t.} \quad & n_1 + n_2 \leq N - D \quad (\text{Latency}) \\ & \varepsilon_2 \leq 1 - T_{\text{rel}} \quad (\text{Reliability}) \end{aligned}$$

Even though **Non-Convex**:
→ 2-D grid search



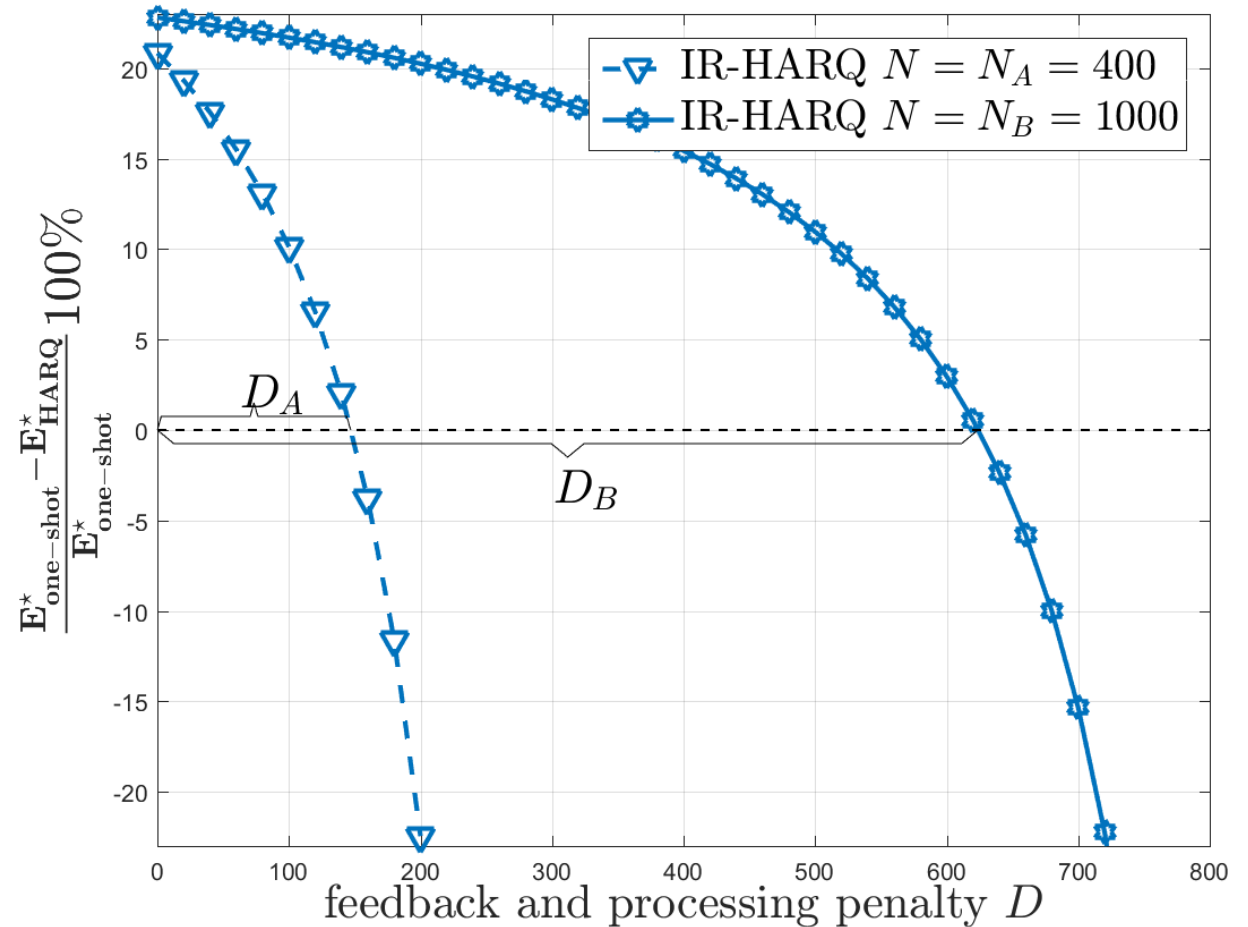
Initial Results

➤ $D = 0$:

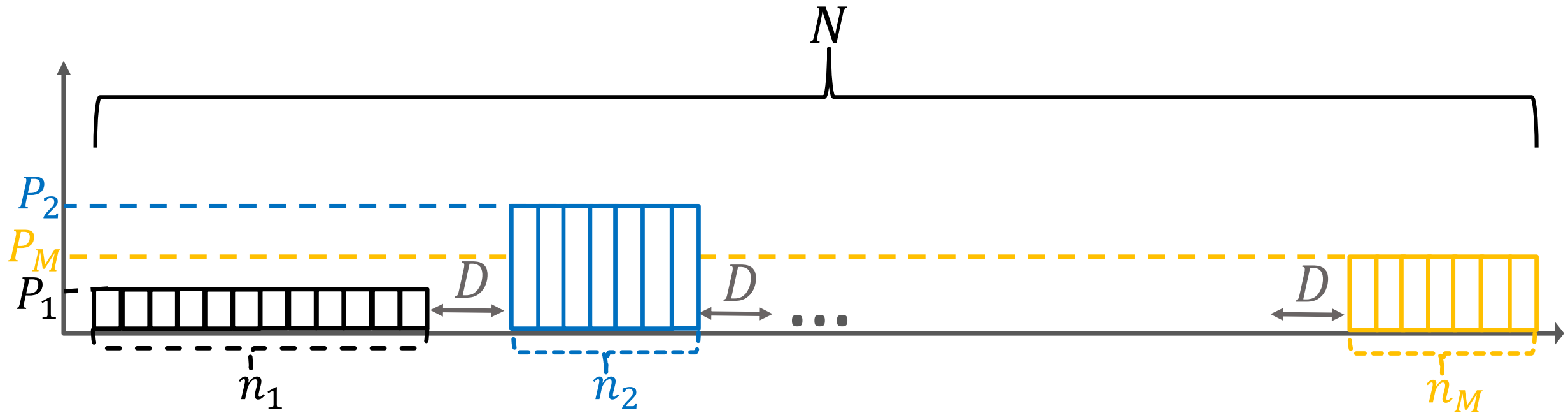
- Up to 25% Energy Economy
- Benefits due to “early termination”

➤ $D > 0$:

- Same logic but diminishing benefits.
- If increased much, one-shot better since powers are increasing exponentially to meet URLLC constraints.



General Case ($M > 2$)



- ☐ Best M ? Best Configuration?
- ☐ Convexity

“Simple” case feedback delay $D = 0$

$$\begin{aligned} \min_{M, n_1, \dots, n_M, P_1, \dots, P_M} \quad & \sum_{m=1}^M n_m P_m \varepsilon_{m-1} \quad (\mathbb{E}[\text{Energy}]) \\ \text{s.t.} \quad & \sum_{m=1}^M n_m \leq N \quad (\text{Latency}) \\ & \varepsilon_M = Q \left(\frac{\sum_{i=1}^m n_i \ln(1 + P_i) - B \ln 2}{\sqrt{\sum_{i=1}^m n_i \frac{P_i(P_i + 2)}{(P_i + 1)^2}}} \right) \leq 1 - T_{\text{rel}} \quad (\text{Reliability}) \end{aligned}$$

“Simple” case feedback delay $D = 0$

$$\begin{aligned}
 & \min_{M, n_1, \dots, n_M, P_1, \dots, P_M} \sum_{m=1}^M n_m P_m \varepsilon_{m-1} \\
 & \text{s.t.} \quad \sum_{m=1}^M n_m = N \\
 & \varepsilon_M = Q \left(\frac{\sum_{i=1}^M n_i \ln(1 + P_i) - B \ln 2}{\sqrt{\sum_{i=1}^M n_i \frac{P_i(P_i + 2)}{(P_i + 1)^2}}} \right) = 1 - T_{\text{rel}}
 \end{aligned}$$

So what if **Dynamic Programming** since: $\sum_{i=1}^m x_i = x_m + \sum_{i=1}^{m-1} x_i$

Goal: Construct state such that:

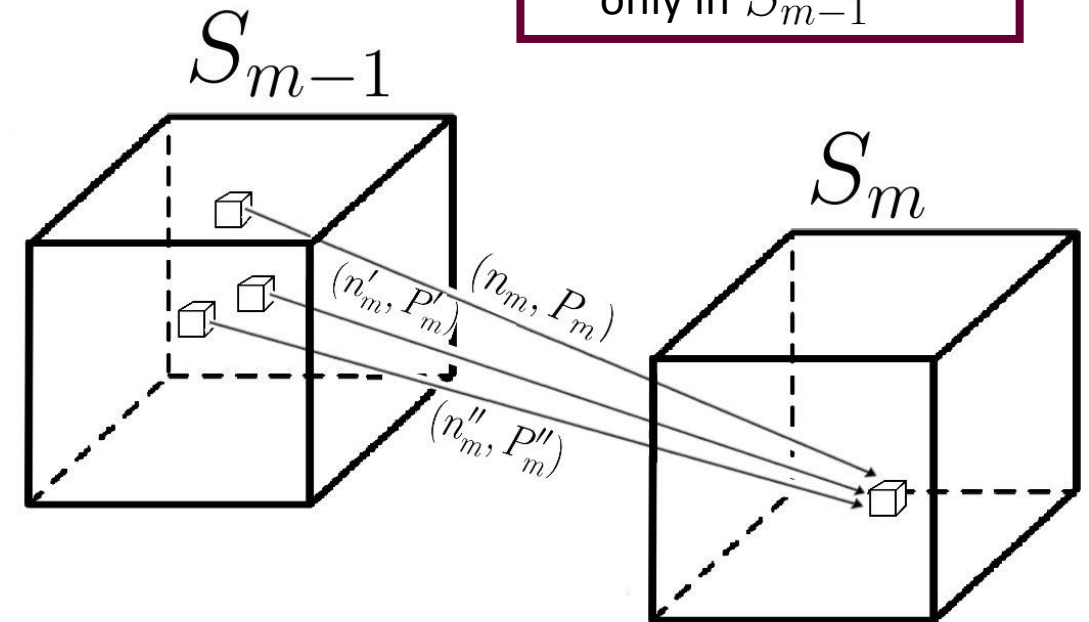
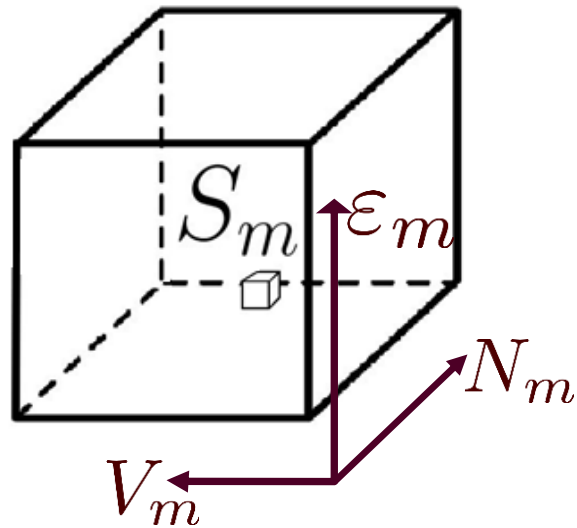
$$\text{Energy}^*(S_{m+1}) = \min_{\forall \text{ possible } S_m} \{ \text{Energy}^*(S_m) + \Delta \text{Energy}(S_{m+1}, S_m) \}$$

State at m^{th} round

$$S_m = (N_m, V_m, \epsilon_m)$$

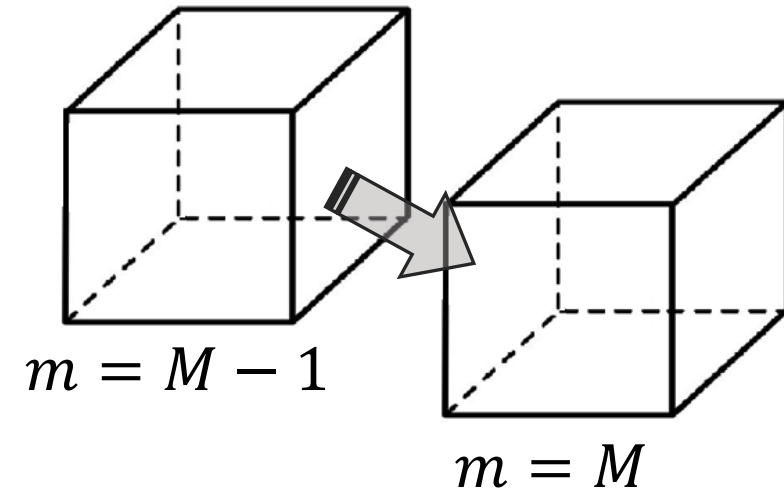
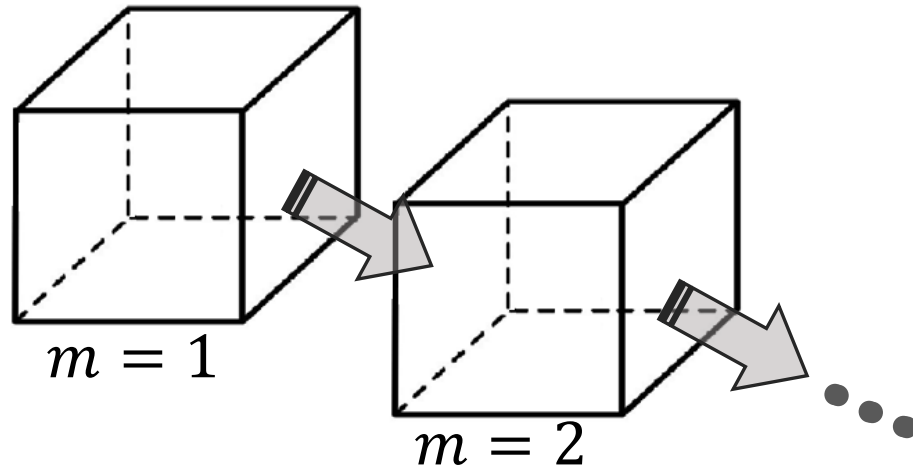
Latency
till m^{th}

Reliability
till m^{th}

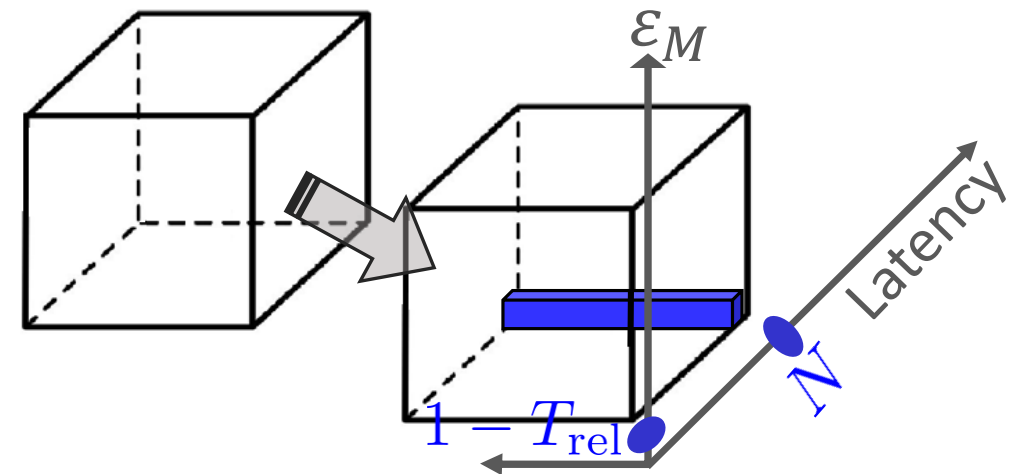
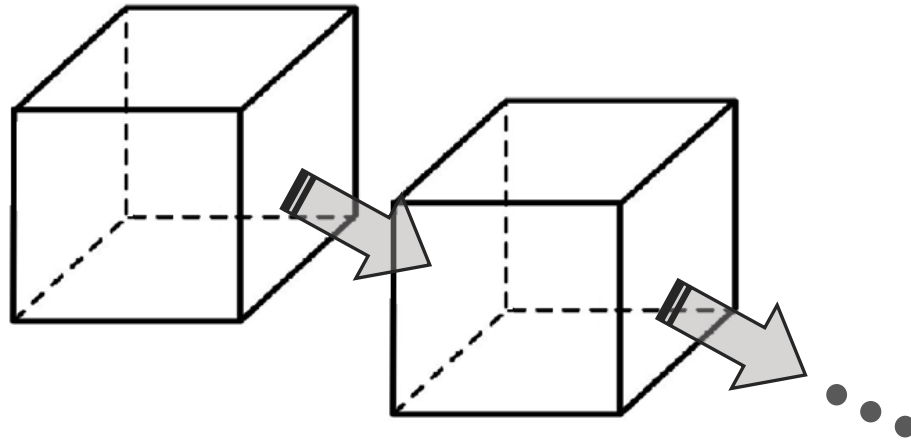


- Optimality in S_m requires optimality only in S_{m-1}

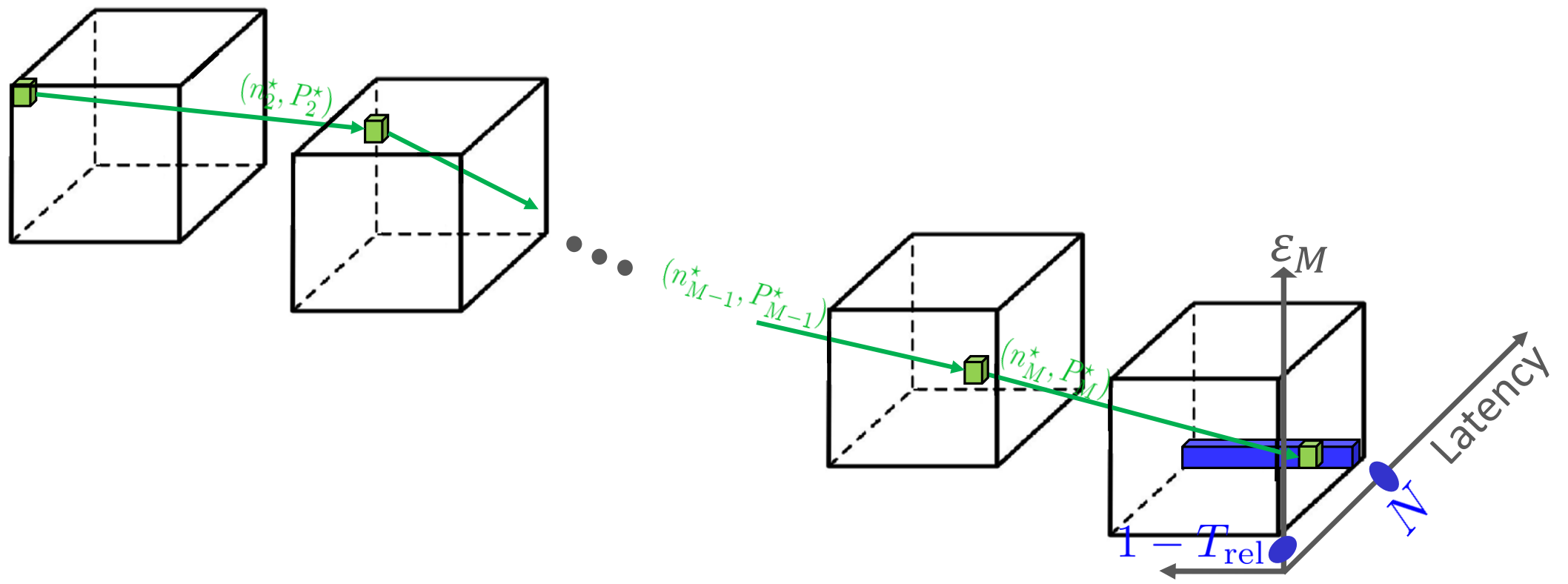
“Simple” case feedback delay $D = 0$



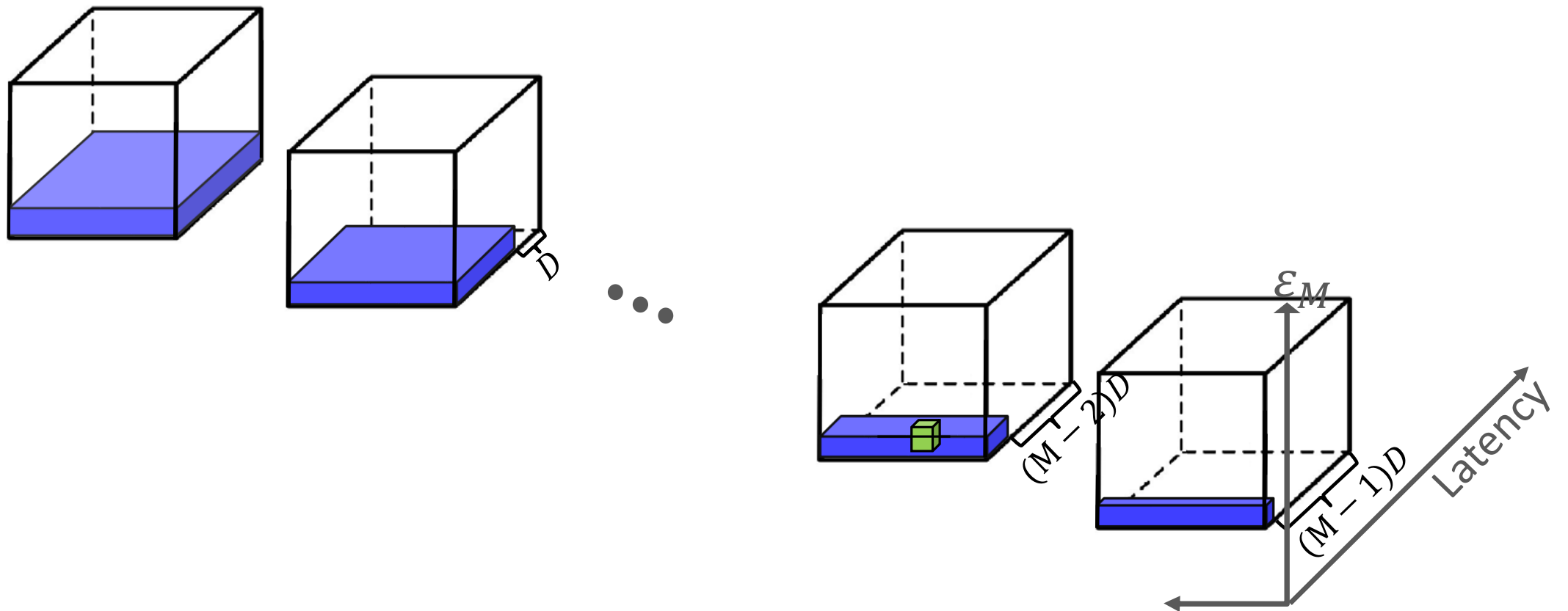
“Simple” case feedback delay $D = 0$



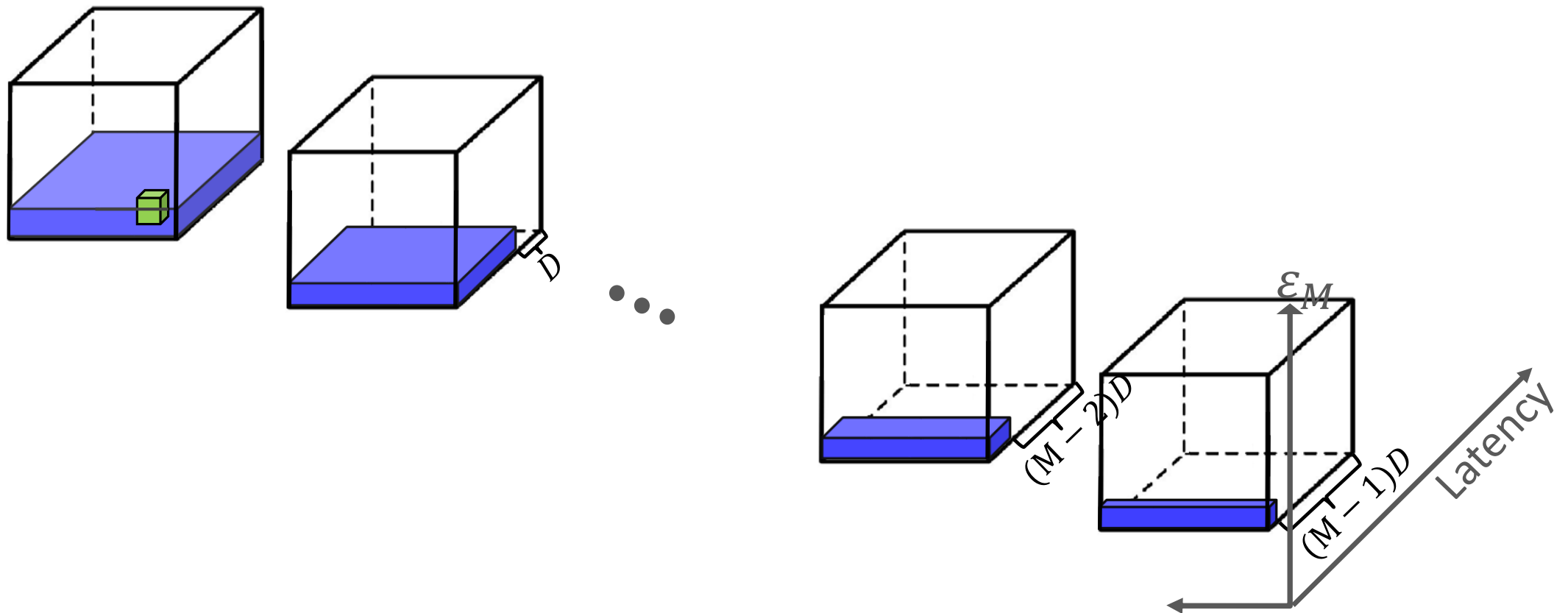
feedback delay $D = 0$, rounds $m \leq M$



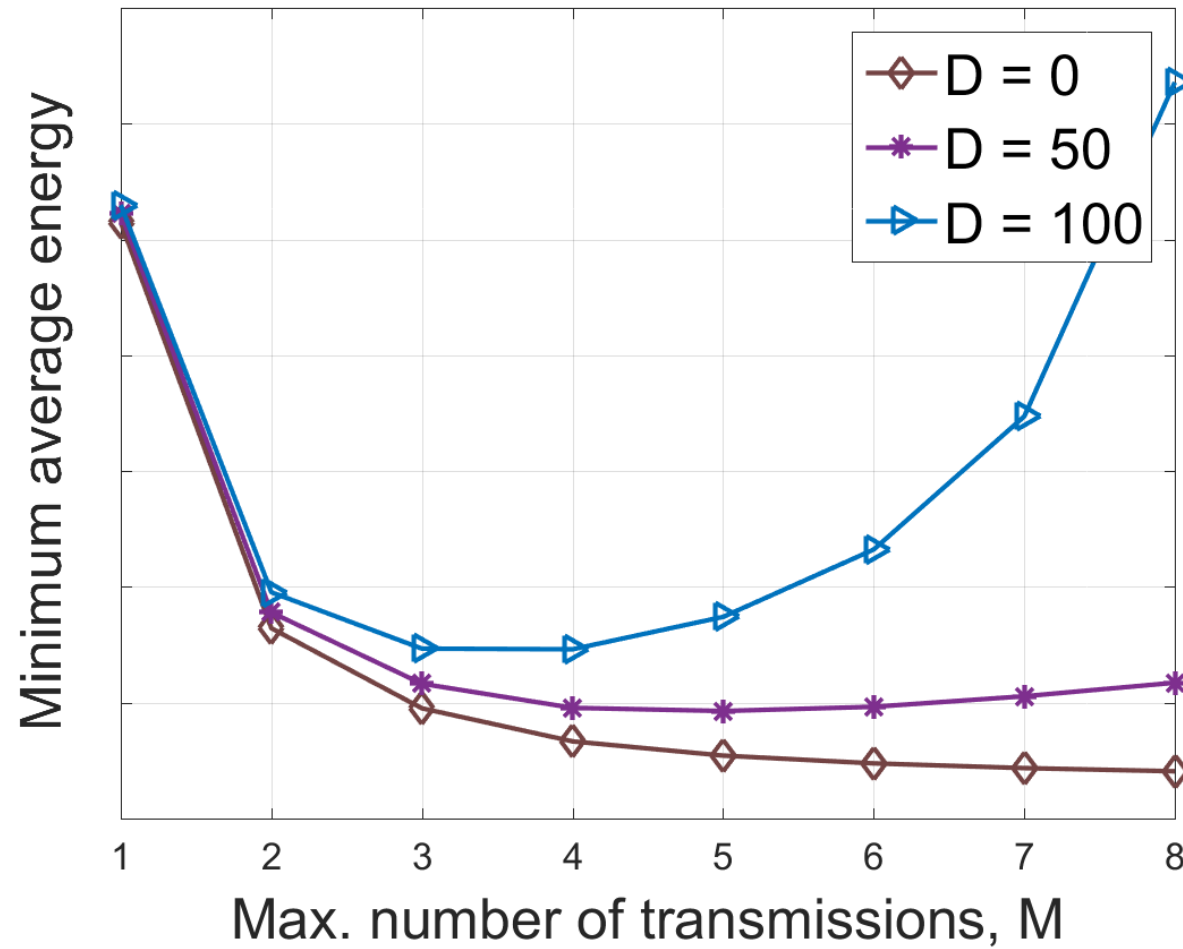
feedback delay $D > 0$



feedback delay $D > 0$



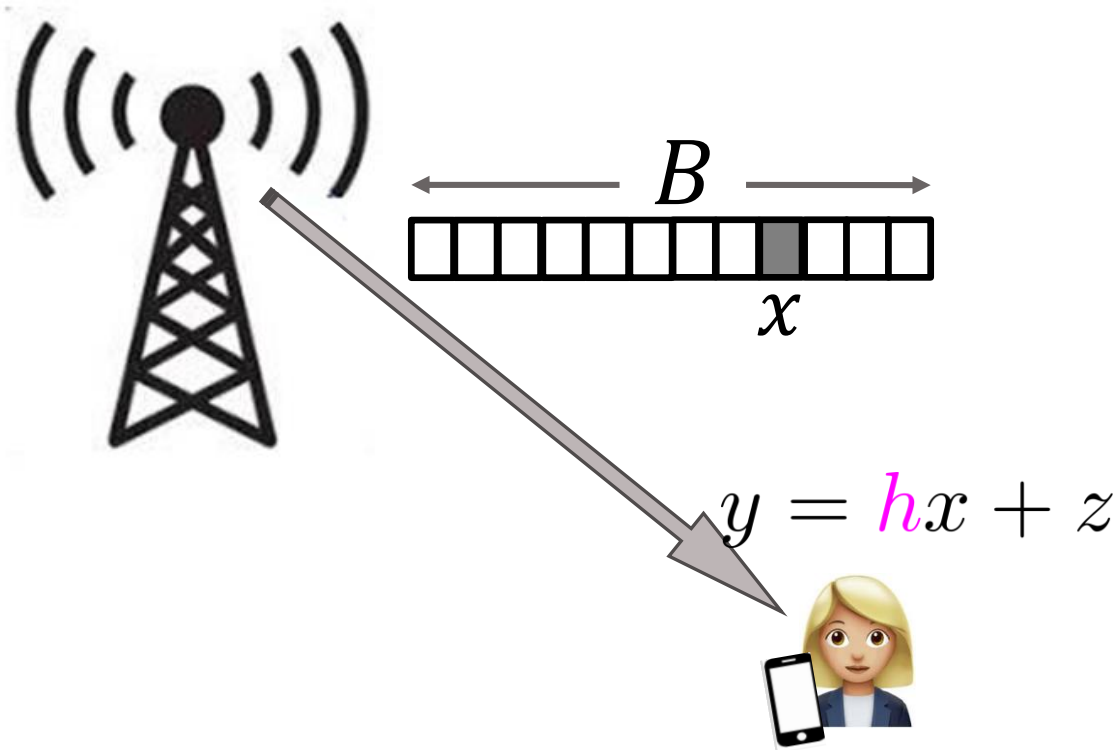
feedback delay $D > 0$



Throughput Maximization

$$\begin{array}{ll} \max_{M, B, n_1, \dots, n_M, P_1, \dots, P_M} & \textit{Throughput} \\ \text{s.t.} & \text{Reliability} \\ & \text{Latency} \\ & \text{Maximum Power} \end{array}$$

Revisit System Model



❑ Received power:

$$P = |h|^2 \frac{\text{EnergyPacket}}{n}$$

❑ $|h| \sim \text{Rice}(K, 1)$

- $K = \frac{\text{Power direct path}}{\text{Power scattered path}}$
- $K = \infty$, AWGN
- $K = 0$, Rayleigh Fading

❑ Channel State Information:

- Full CSI (h known)
- Statistical CSI (distribution of h known)

Throughput-Energy Trade-off

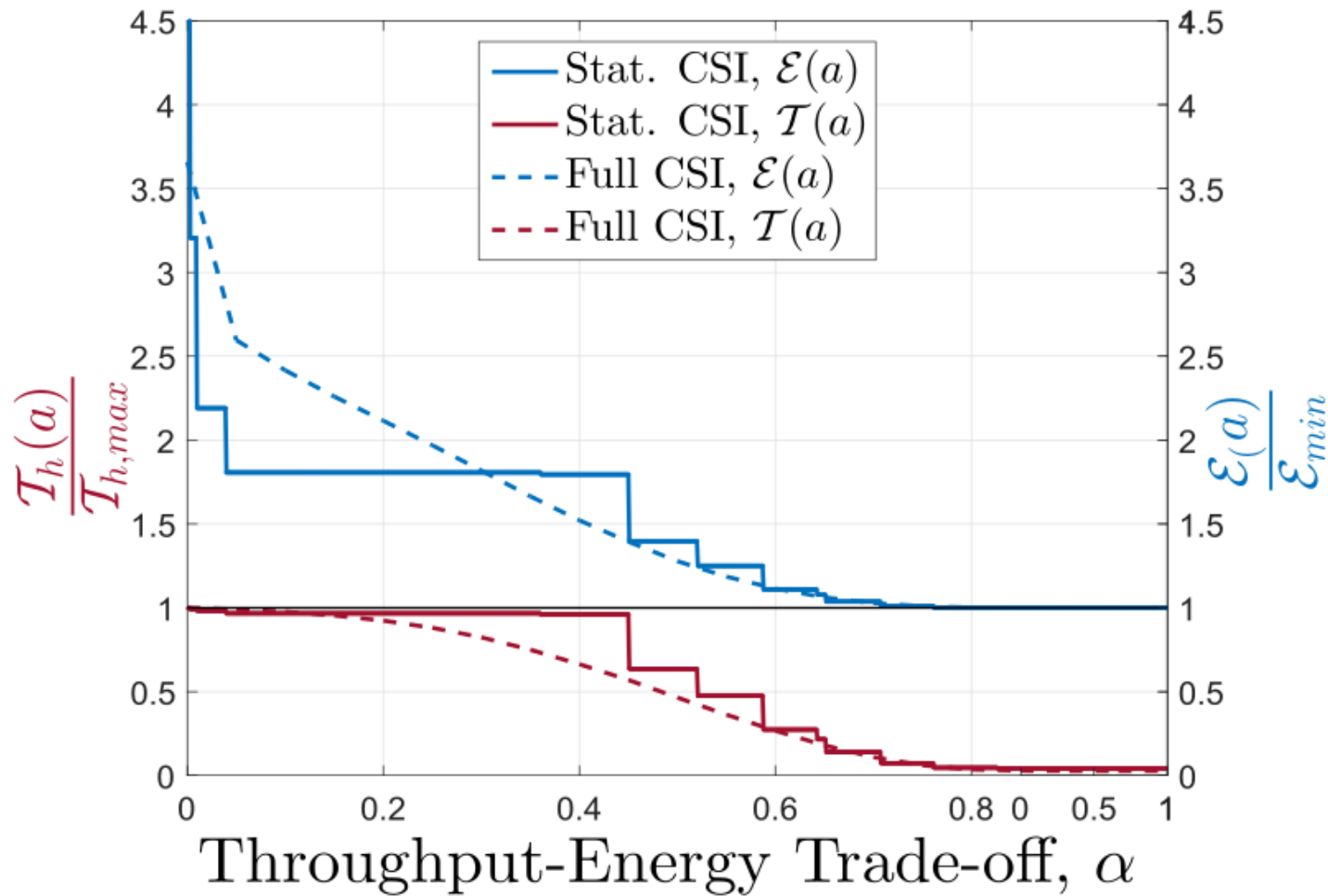
$$\max \quad \mathbb{E}_h[(1 - \alpha)\textit{Throughput} - \alpha\textit{Energy}]$$

$$\text{s.t.} \quad \mathbb{E}_h[\text{Reliability}]$$

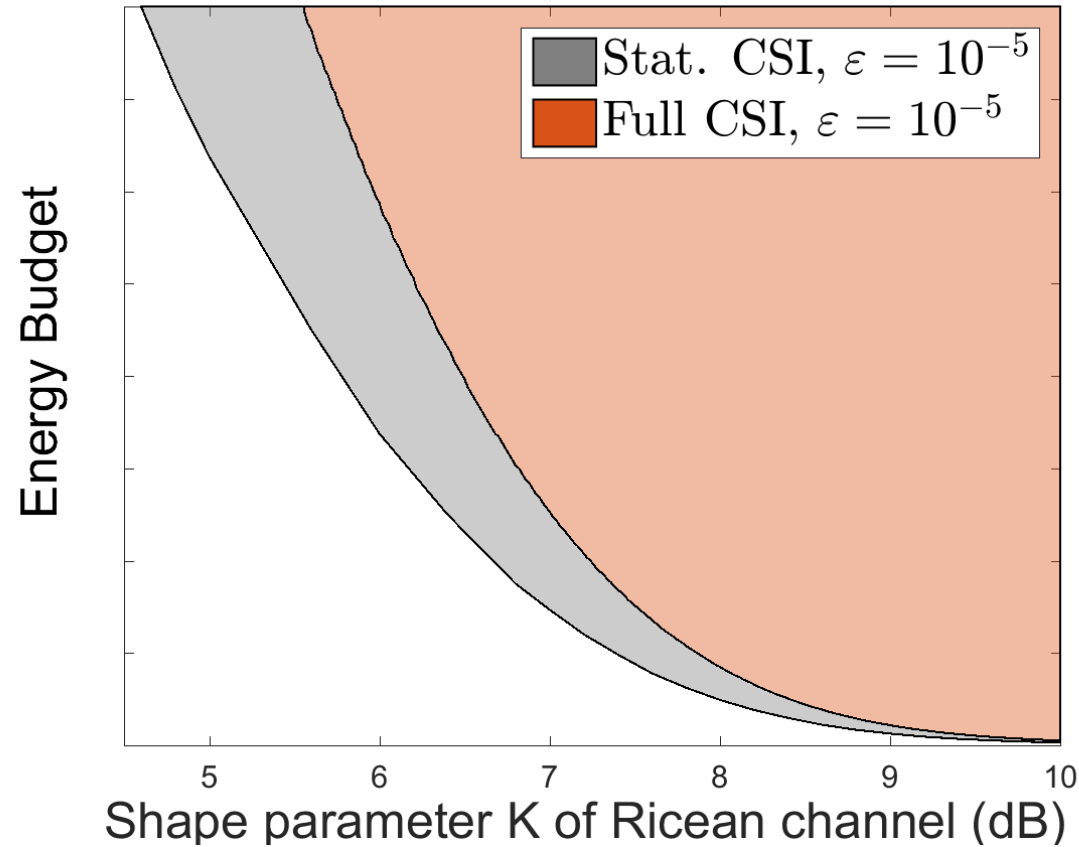
Latency

Maximum Energy/Power

Throughput-Energy Trade-off



Throughput-Energy Trade-off



Part Two

PHY → MAC

Similarities:

- Strict Latency Constraint L
- B information bits
- Retransmissions

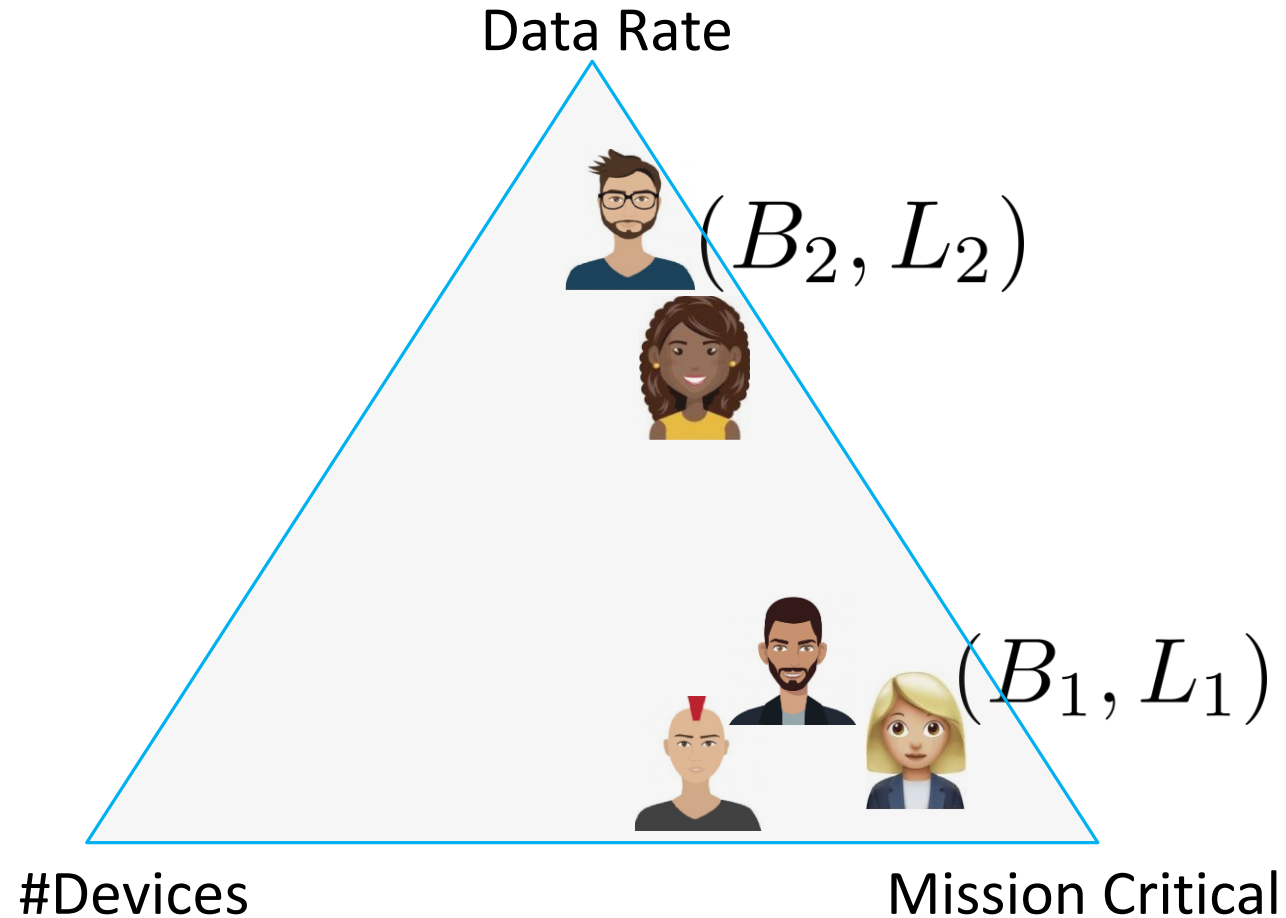
Differences:

- Back to Shannon
- h_t depends on h_{t-1}

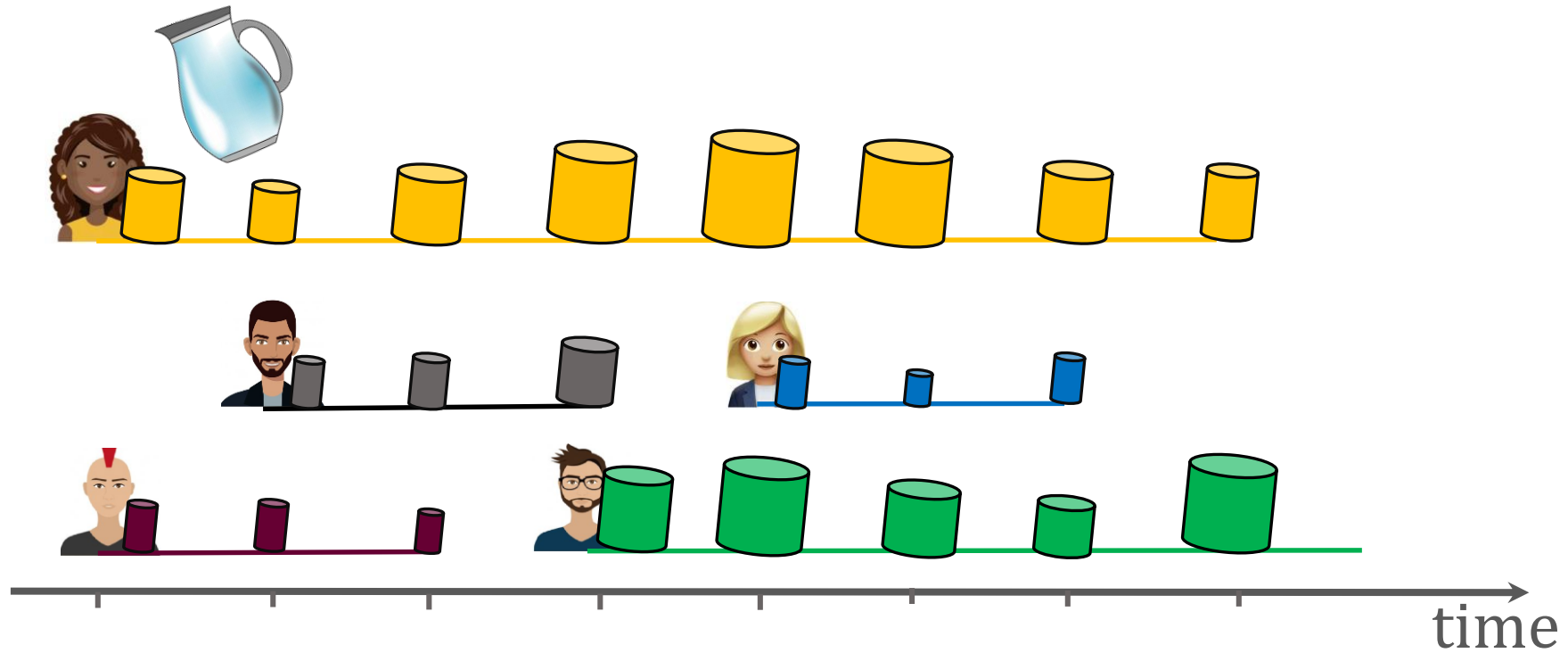
→ Type I HARQ

IR-HARQ

Multi Class Traffic

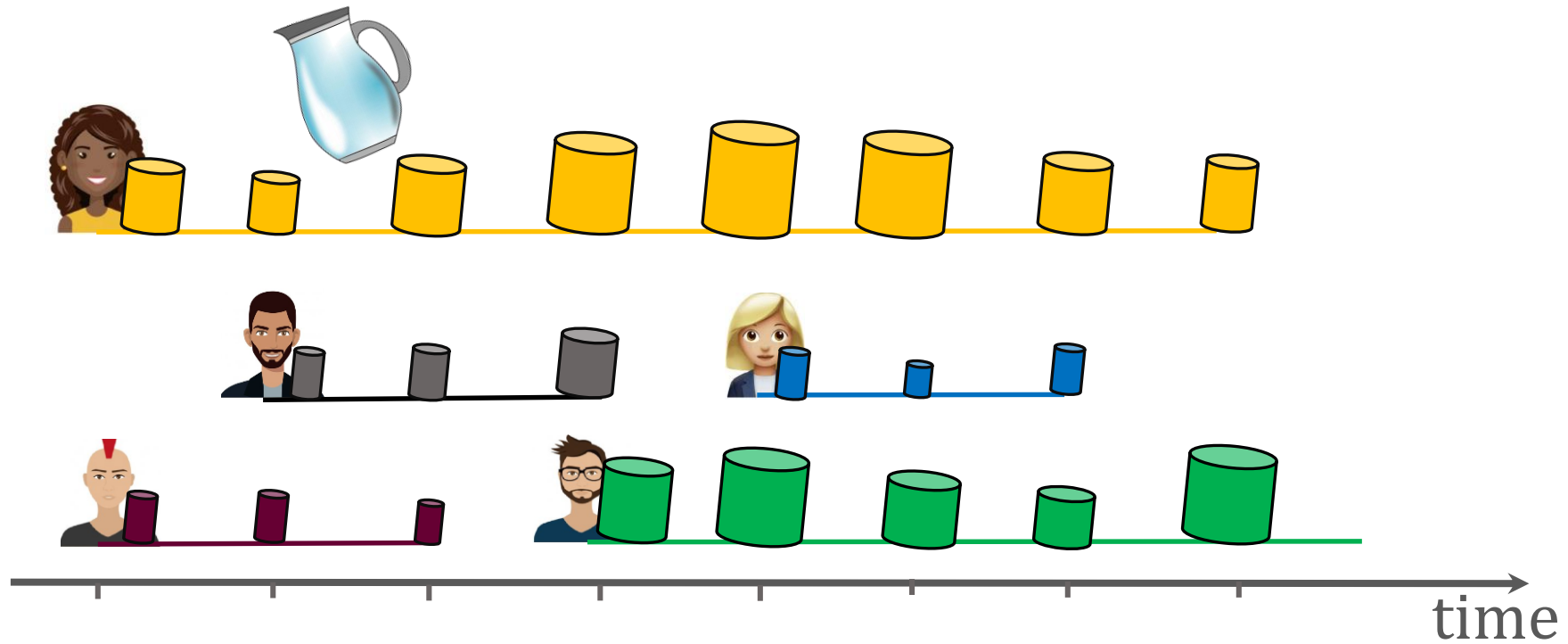


Multi Class Traffic



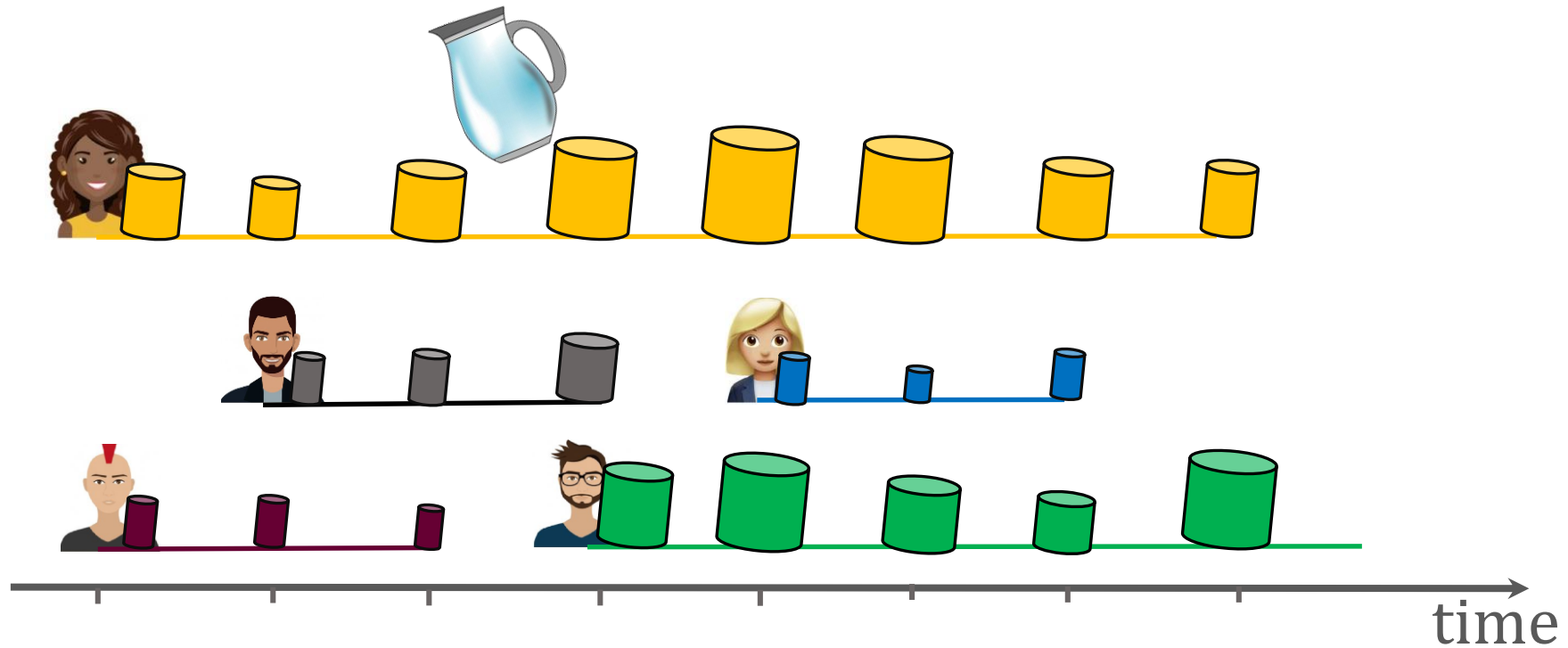
$$\text{Size Of Glass}_u = f(B_u, h_{u,t})$$

Multi Class Traffic



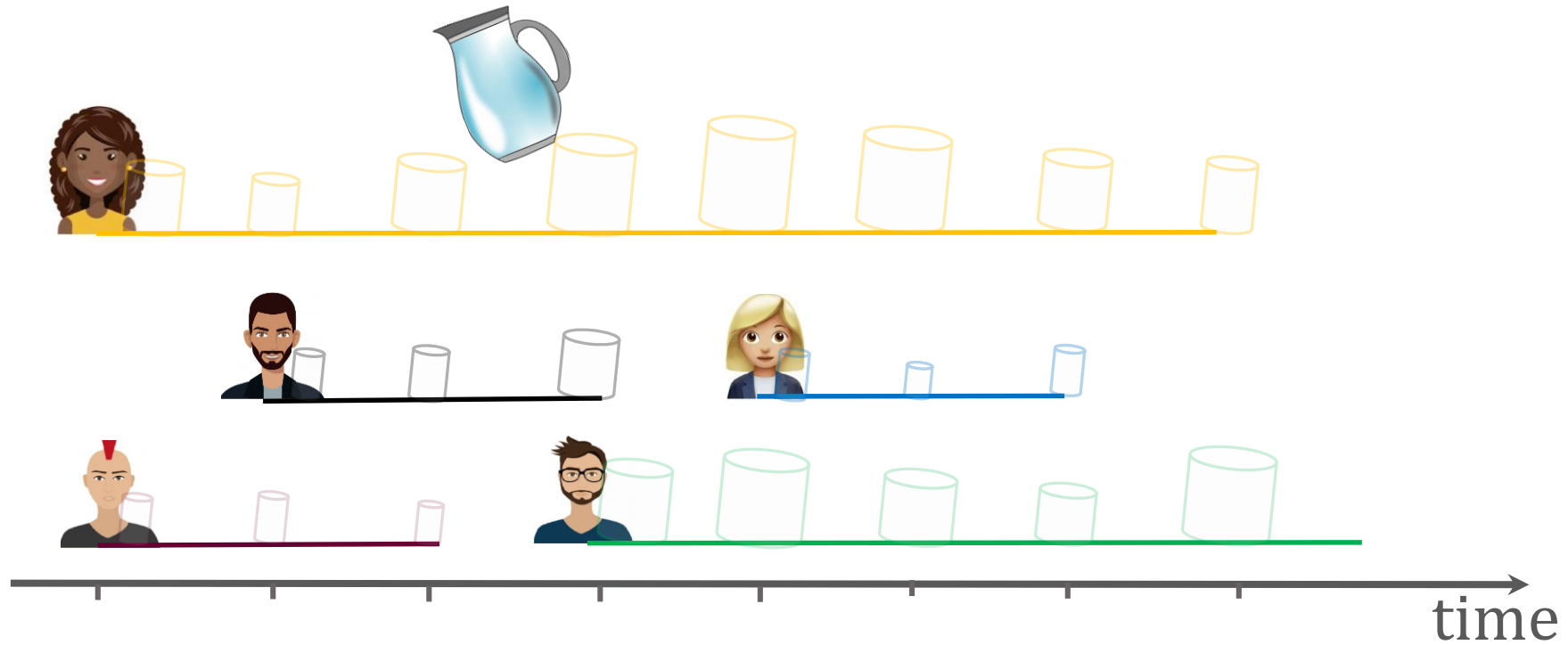
$$\text{Size Of Glass}_u = f(B_u, h_{u,t})$$

Multi Class Traffic



$$\text{Size Of Glass}_u = f(B_u, h_{u,t})$$

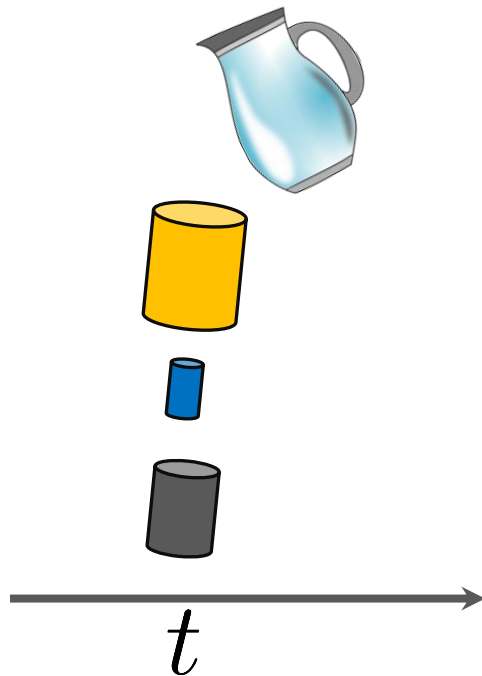
Multi Class Traffic



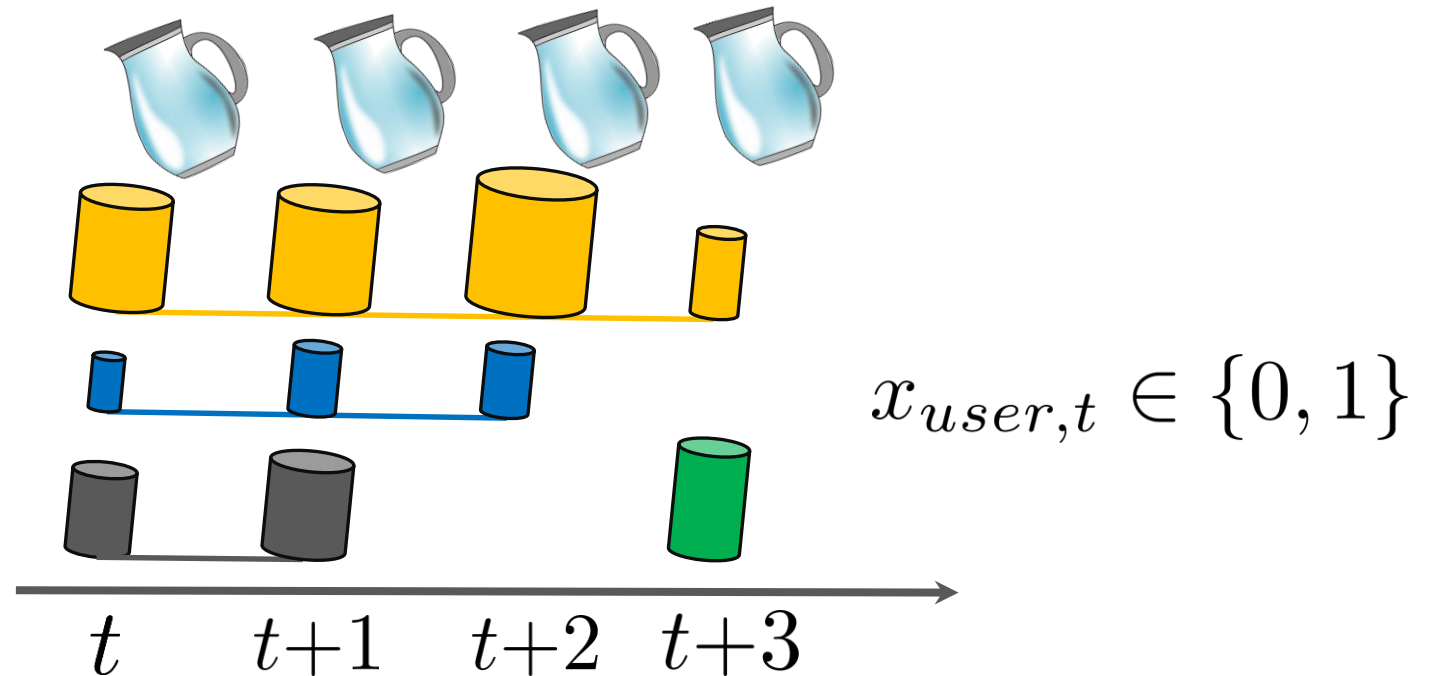
$$\text{Size Of Glass}_u = f(B_u, h_{u,t})$$

Full CSI (Benchmarks)

Greedy - Knapsack



Oracle – Integer Linear Programming(ILP)



Reinforcement Learning (full CSI)

- *Markov Decision Process (MDP):*

state: $s_t = \{\forall u \in \text{Users}_t: B_{u,t}, \text{latency}_{u,t}, h_{u,t}\}$

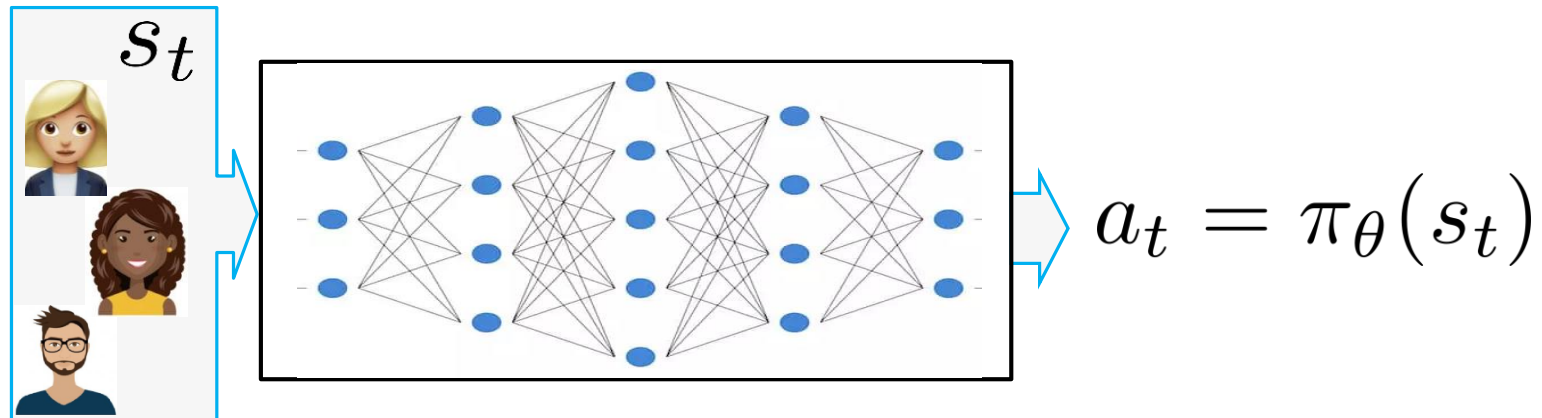
action: $a_t = \{\forall u \in \text{Users}_t: \text{serve}_u\}$

- *Q-learning (lookup table):*

Let K users, C number of classes, L_{\max} the maximum latency.

Size of Table = $K \cdot C \cdot L_{\max} \cdot \infty \cdot 2^K$

- *Deep Deterministic Policy Gradient:*



Goal of Actor

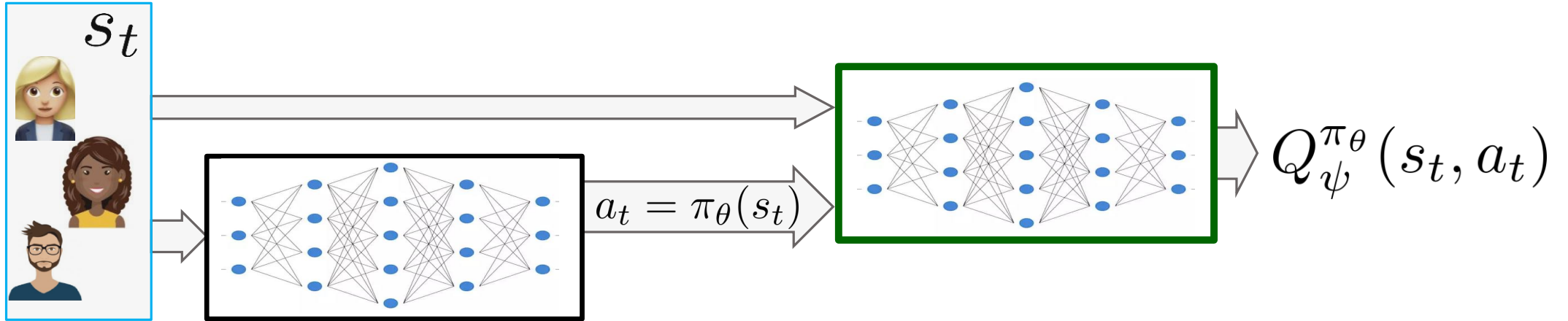
Return: $Z^{\pi_{\theta}}(s_t, a_t) = R(s_t, a_t) + \sum_{i=1}^{\infty} \gamma^i R(S_{t+i}, \pi_{\theta}(S_{t+i}))$

Value function: $Q^{\pi_{\theta}}(s_t, a_t) = \mathbb{E}[Z^{\pi_{\theta}}(s_t, a_t)]$

Goal: $J(\theta) = \mathbb{E}_{s_t}[Q^{\pi_{\theta}}(s_t, a_t) | a_t = \pi_{\theta}(s_t)]$

How to optimize θ so as to maximize the value?

Goal of Critic



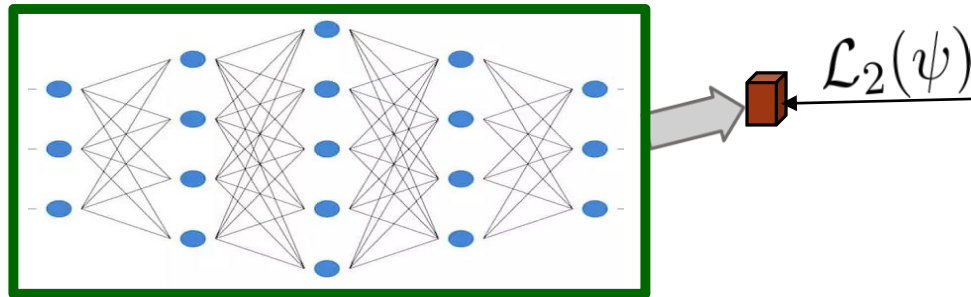
Goal: $Q_\psi^{\pi_\theta}(s_t, a_t) \approx Q^{\pi_\theta}(s_t, a_t)$

How to optimize ψ so as to improve estimation?

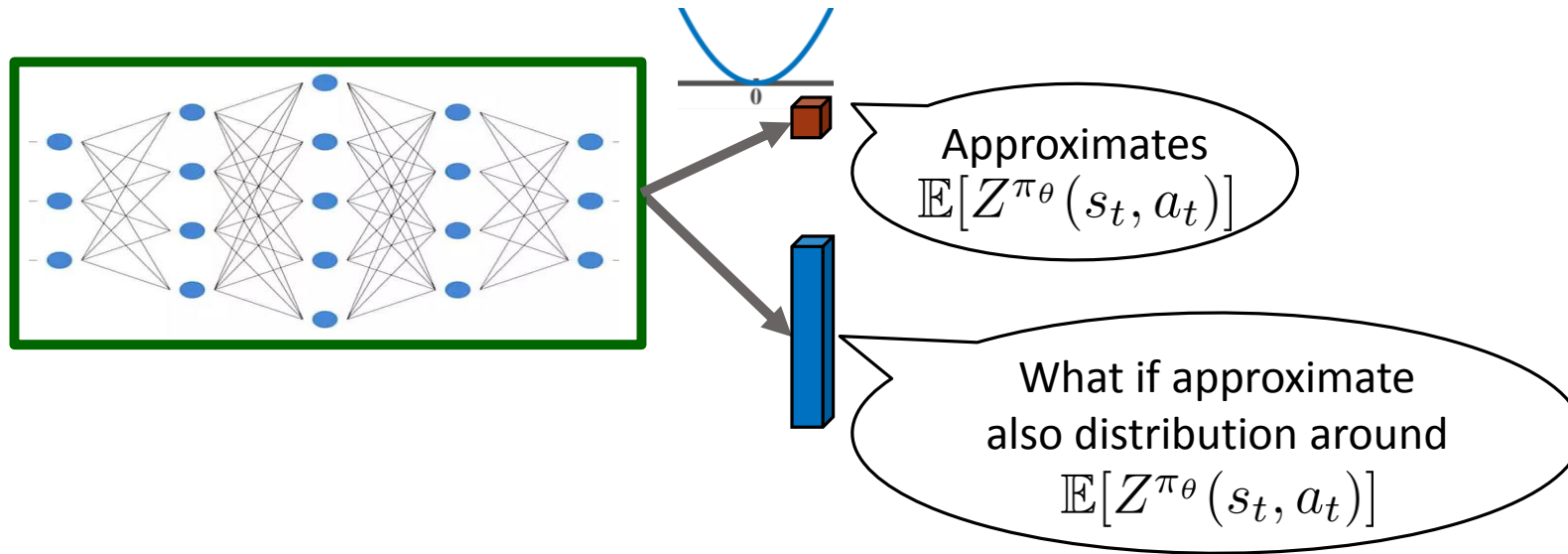
Bellman Equation

Bellman Equation: $Q^{\pi_\theta}(s_t, a_t) = R(s_t, a_t) + \gamma \mathbb{E}[Q^{\pi_\theta}(s_{t+1}, \pi_\theta(s_{t+1}))]$

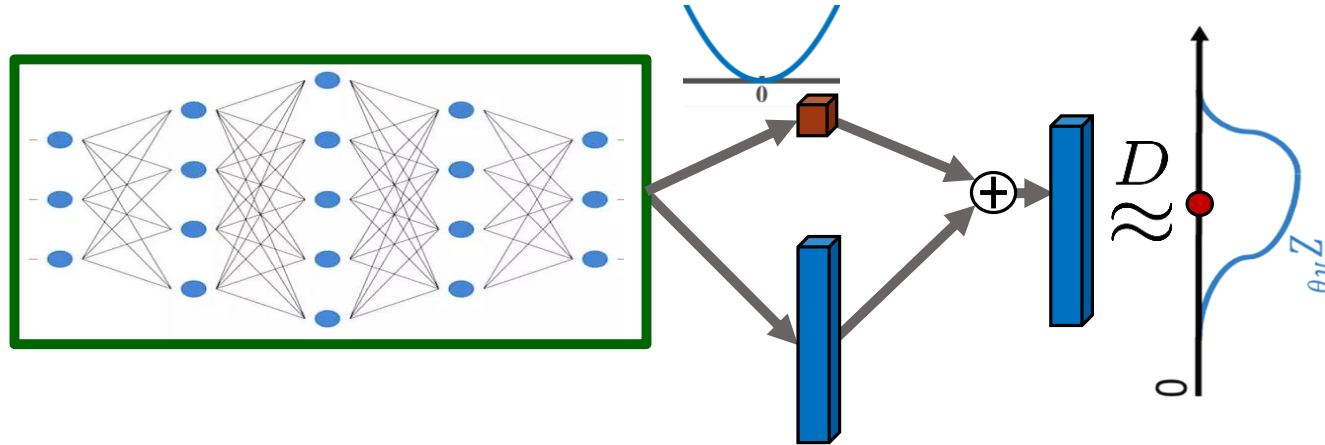
Loss Function: $\mathcal{L}_2(\psi) = \mathbb{E}[\underbrace{(Q_\psi^{\pi_\theta}(s_t, a_t))}_{\text{prediction}} - \underbrace{(R(s_t, a_t) + \gamma Q_{\psi-}^{\pi_\theta}(s_{t+1}, \pi_\theta(s_{t+1})))}_{\text{target}}]^2$



Distributional Perspective



Distributional Perspective

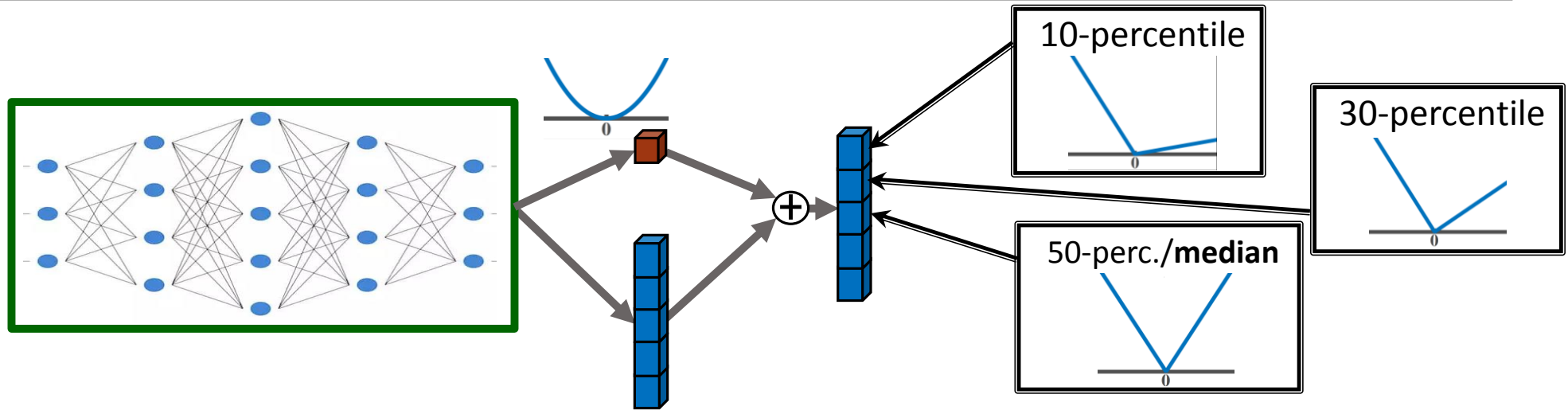


Distributional Bellman Equation:

$$Z^{\pi_\theta}(s_t, a_t) \stackrel{D}{=} R(s_t, a_t) + \gamma Z^{\pi_\theta}(S_{t+1}, \pi_\theta(S_{t+1}))$$

Representation of Distribution?

Distributional Perspective



Distributional Bellman Equation:

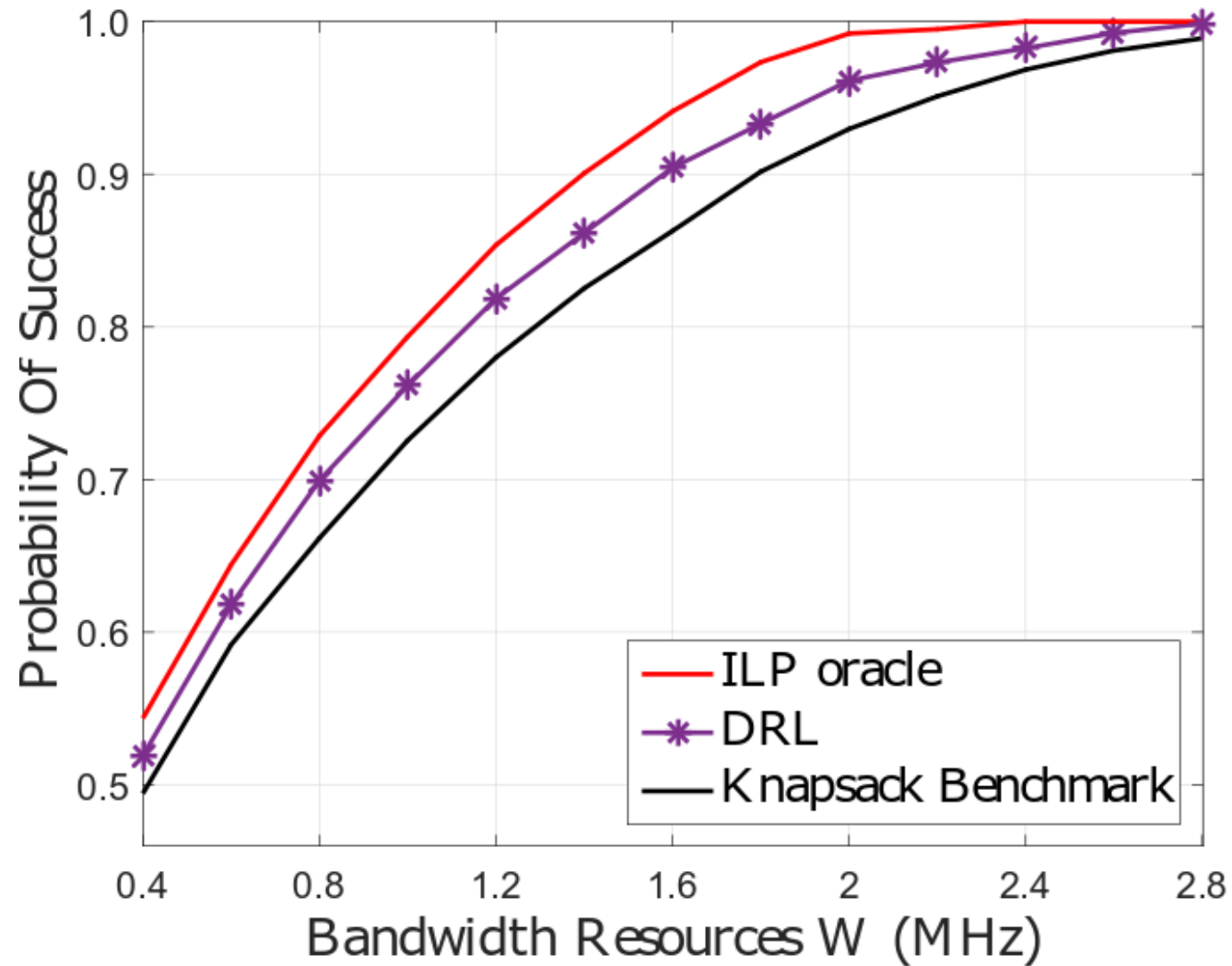
$$Z^{\pi_{\theta}}(s_t, a_t) \stackrel{D}{=} R(s_t, a_t) + \gamma Z^{\pi_{\theta}}(S_{t+1}, \pi_{\theta}(S_{t+1}))$$

Representation of Distribution?

Percentiles

Loss Function using Quantile Regression

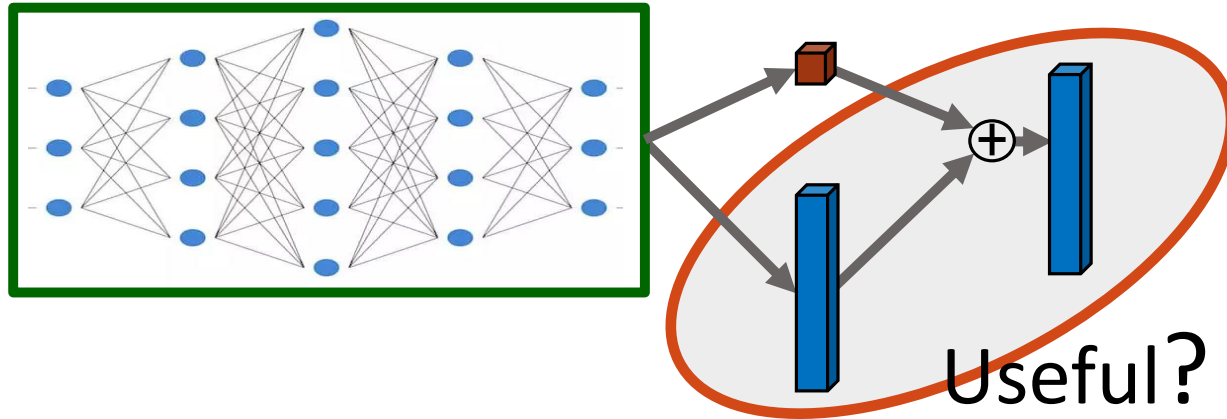
Performance



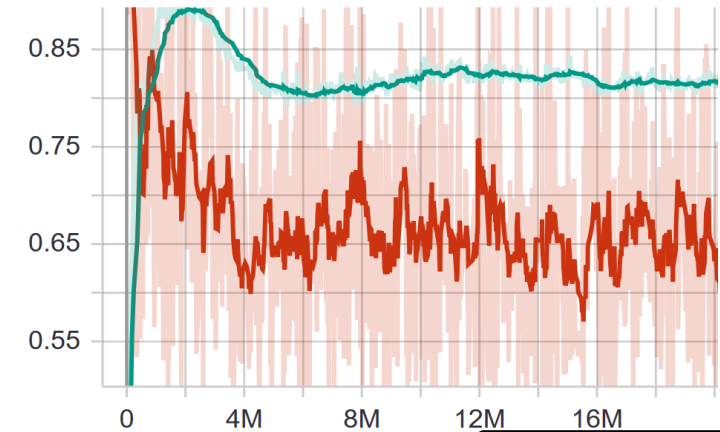
Classes Description

	B	L
class 1	256 Bytes	2
class 2	2048 Bytes	10

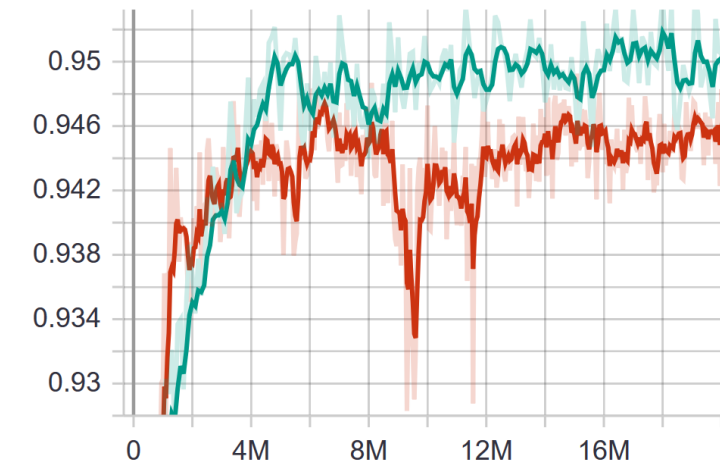
Why distributional?



LossTotal/Train
tag: Critic/LossTotal/Train



ExpRewardPerUser
tag: Test/ExpRewardPerUser



Conclusions

Part One

- Studied energy/throughput – latency tradeoffs in URLLC
- Both AWGN and Fading channels
- IR-HARQ gains if properly tuned
- Up to 25% energy saving with reasonable delays.

Part Two

- Multi user, multi class traffic scheduling
- Combined L2 and quantile regression loss through a “dueling” architecture.
- Reinforcement Learning outperforms SoTA techniques (combinatorial, integer programming and Frank-Wolfe).

Peer-reviewed Journal

- [J1] A. Avranas, M. Kountouris, and P. Ciblat, “Energy-latency tradeoff in ultra-reliable low-latency communication with retransmissions,” *IEEE Journal on Selected Areas in Communications*, vol. 36, no. 11, pp. 2475–2485, Nov. 2018.

International Conference

- [C1] M. Kountouris, N. Pappas, and A. Avranas, “QoS provisioning in large wireless networks,” in *2018 16th International Symposium on Modeling and Optimization in Mobile, Ad Hoc, and Wireless Networks (WiOpt)*, May 2018.
- [C2] M. Kountouris and A. Avranas, “Delay Performance of Multi-Antenna Multicasting in Wireless Networks,” in *2018 IEEE 19th International Workshop on Signal Processing Advances in Wireless Communications (SPAWC)*, Jun. 2018.
- [C3] A. Avranas, M. Kountouris, and P. Ciblat, “Energy-Latency Tradeoff in Ultra-Reliable Low-Latency Communication with Short Packets,” in *2018 IEEE Global Communications Conference (Globecom)*, Dec. 2018.
- [C4] —, “Throughput Maximization and IR-HARQ Optimization for URLLC Traffic in 5G Systems,” in *2019 IEEE International Conference on Communications (ICC)*, May 2019.
- [C5] —, “The Influence of CSI in Ultra-Reliable Low-Latency Communications with IR-HARQ,” in *2019 IEEE Global Communications Conference (Globecom)*, Dec. 2019.

$$\min_{n_1(g), n_2(g), P_1(g), P_2(g)} \mathbb{E}_g \left[-\frac{\mathcal{T}_h(a)}{\mathcal{T}_{h,max}} + \frac{\mathcal{E}(a)}{\mathcal{E}_{min}} \right] \quad (1)$$

$$\text{s.t. } n_1(g) + n_2(g) \leq N_\ell, \quad \forall g \quad (2)$$

$$\mathbb{E}_g[\varepsilon_2(n_1(g), n_2(g), P_1(g), P_2(g), g)] \leq \varepsilon_{\text{rel}} \quad (3)$$

$$n_1(g)P_1(g) + n_2(g)P_2(g) \leq E_b, \quad \forall g \quad (4)$$

$$P_i(g) \leq P_{\text{max}}, \quad i \in \{1, 2\} \quad \forall g \quad (5)$$

$$n_i = \begin{cases} 0 & g < g_{th} \\ n_i(g) & g \geq g_{th} \end{cases}, P_i = \begin{cases} 0 & g < g_{th} \\ P_i(g) & g \geq g_{th} \end{cases}$$

$$\varepsilon_2 = \mathbb{P}(g < g_{th}) + \mathbb{P}(g \geq g_{th})\varepsilon_{on} \leq \varepsilon_{\text{rel}}.$$

