

AVRDUDE

A program for downloading/uploading AVR microcontroller flash, EEPROM and more
for AVRDUDE, Version 7.2, 20 July 2023

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Use <https://github.com/avrdudes/avrdude/issues> to report bugs and ask questions.
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1 Introduction

AVRDUDE - AVR Downloader Uploader - is a program for downloading and uploading the on-chip memories of Atmel's AVR microcontrollers. It can program the Flash and EEPROM, and where supported by the serial programming protocol, it can program fuse and lock bits. AVRDUDE also supplies a direct instruction mode allowing one to issue any programming instruction to the AVR chip regardless of whether AVRDUDE implements that specific feature of a particular chip.

AVRDUDE can be used effectively via the command line to read or write all chip memory types (eeprom, flash, fuse bits, lock bits, signature bytes) or via an interactive (terminal) mode. Using AVRDUDE from the command line works well for programming the entire memory of the chip from the contents of a file, while interactive mode is useful for exploring memory contents, modifying individual bytes of eeprom, programming fuse/lock bits, etc.

AVRDUDE supports the following basic programmer types: Atmel's STK500, Atmel's AVRISP and AVRISP mkII devices, Atmel's STK600, Atmel's JTAG ICE (the original one, mkII, and 3, the latter two also in ISP mode), appnote avr910, appnote avr109 (including the AVR Butterfly), serial bit-bang adapters, and the PPI (parallel port interface). PPI represents a class of simple programmers where the programming lines are directly connected to the PC parallel port. Several pin configurations exist for several variations of the PPI programmers, and AVRDUDE can be configured to work with them by either specifying the appropriate programmer on the command line or by creating a new entry in its configuration file. All that's usually required for a new entry is to tell AVRDUDE which pins to use for each programming function.

A number of equally simple bit-bang programming adapters that connect to a serial port are supported as well, among them the popular Ponyprog serial adapter, and the DASA and DASA3 adapters that used to be supported by uisp(1). Note that these adapters are meant to be attached to a physical serial port. Connecting to a serial port emulated on top of USB is likely to not work at all, or to work abysmally slow.

If you happen to have a Linux system with at least 4 hardware GPIOs available (like almost all embedded Linux boards) you can do without any additional hardware - just connect them to the SDO, SDI, RESET and SCK pins of the AVR's SPI interface and use the linuxgpio programmer type. Older boards might use the labels MOSI for SDO and MISO for SDI. It bitbangs the lines using the Linux sysfs GPIO interface. Of course, care should be taken about voltage level compatibility. Also, although not strictly required, it is strongly advisable to protect the GPIO pins from overcurrent situations in some way. The simplest would be to just put some resistors in series or better yet use a 3-state buffer driver like the 74HC244. Have a look at <http://kolev.info/blog/2013/01/06/avrdude-linuxgpio/> for a more detailed tutorial about using this programmer type.

Under a Linux installation with direct access to the SPI bus and GPIO pins, such as would be found on a Raspberry Pi, the "linuxspi" programmer type can be used to directly connect to and program a chip using the built in interfaces on the computer. The requirements to use this type are that an SPI interface is exposed along with one GPIO pin. The GPIO serves as the reset output since the Linux SPI drivers do not hold chip select down when a transfer is not occurring and thus it cannot be used as the reset pin. A readily available level translator should be used between the SPI bus/reset GPIO and the chip to avoid potentially damaging the computer's SPI controller in the event that the chip

is running at 5V and the SPI runs at 3.3V. The GPIO chosen for reset can be configured in the avrdude configuration file using the `reset` entry under the `linuxspi` programmer, or directly in the port specification. An external pull-up resistor should be connected between the AVR's reset pin and Vcc. If Vcc is not the same as the SPI voltage, this should be done on the AVR side of the level translator to protect the hardware from damage.

On a Raspberry Pi, header J8 provides access to the SPI and GPIO lines.

Typically, pins 19, 21, and 23 are SPI SDO, SDI, and SCK, while pins 24 and 26 would serve as CE outputs. So, close to these pins is pin 22 as GPIO25 which can be used as /RESET, and pin 25 can be used as GND.

A typical programming cable would then look like:

J8 pin	ISP pin	Name
21	1	SDI
-	2	Vcc - leave open
23	3	SCK
19	4	SDO
22	5	/RESET
25	6	GND

(Mind the 3.3 V voltage level of the Raspberry Pi!)

The `-P portname` option defaults to `/dev/spidev0.0:/dev/gpiochip0` for this programmer.

The STK500, JTAG ICE, avr910, and avr109/butterfly use the serial port to communicate with the PC. The STK600, JTAG ICE mkII/3, AVRISP mkII, USBasp, avrftdi (and derivatives), and USBtinyISP programmers communicate through the USB, using `libusb` as a platform abstraction layer. The avrftdi adds support for the FT2232C/D, FT2232H, and FT4232H devices. These all use the MPSSE mode, which has a specific pin mapping. Bit 0 (the lsb of the byte in the config file) is SCK. Bit 1 is SDO, and Bit 2 is SDI. Bit 3 usually reset. The 2232C/D parts are only supported on interface A, but the H parts can be either A or B (specified by the `usbdev` config parameter). The STK500, STK600, JTAG ICE, and avr910 contain on-board logic to control the programming of the target device. The avr109 bootloader implements a protocol similar to avr910, but is actually implemented in the boot area of the target's flash ROM, as opposed to being an external device. The fundamental difference between the two types lies in the protocol used to control the programmer. The avr910 protocol is very simplistic and can easily be used as the basis for a simple, home made programmer since the firmware is available online. On the other hand, the STK500 protocol is more robust and complicated and the firmware is not openly available. The JTAG ICE also uses a serial communication protocol which is similar to the STK500 firmware version 2 one. However, as the JTAG ICE is intended to allow on-chip debugging as well as memory programming, the protocol is more sophisticated. (The JTAG ICE mkII protocol can also be run on top of USB.) Only the memory programming functionality of the JTAG ICE is supported by AVRDUDE. For the JTAG ICE mkII/3, JTAG, debugWire and ISP mode are supported, provided it has a firmware revision of at least 4.14 (decimal). See below for the limitations of debugWire. For ATxmega devices, the JTAG ICE mkII/3 is supported in PDI mode, provided it has a revision 1 hardware and firmware version of at least 5.37 (decimal).

The Atmel-ICE (ARM/AVR) is supported (JTAG, PDI for Xmega, debugWIRE, ISP, UPDI).

Atmel's XplainedPro boards, using EDBG protocol (CMSIS-DAP compliant), are supported by the "jtag3" programmer type.

Atmel's XplainedMini boards, using mEDBG protocol, are also supported by the "jtag3" programmer type.

The AVR Dragon is supported in all modes (ISP, JTAG, PDI, HVSP, PP, debugWire). When used in JTAG and debugWire mode, the AVR Dragon behaves similar to a JTAG ICE mkII, so all device-specific comments for that device will apply as well. When used in ISP and PDI mode, the AVR Dragon behaves similar to an AVRISP mkII (or JTAG ICE mkII in ISP mode), so all device-specific comments will apply there. In particular, the Dragon starts out with a rather fast ISP clock frequency, so the `-B bitclock` option might be required to achieve a stable ISP communication. For ATxmega devices, the AVR Dragon is supported in PDI mode, provided it has a firmware version of at least 6.11 (decimal).

Wiring boards (e.g. Arduino Mega 2560 Rev3) are supported, utilizing STK500 V2.x protocol, but a simple DTR/RTS toggle to set the boards into programming mode. The programmer type is "wiring". Note that the `-D` option will likely be required in this case, because the bootloader will rewrite the program memory, but no true chip erase can be performed.

Serial bootloaders that run a skeleton of the STK500 1.x protocol are supported via their own programmer type specification "arduino". This programmer works for the Arduino Uno Rev3 or any AVR that runs the Optiboot bootloader. The number of connection retry attempts can be specified as an extended parameter. See the section on *extended parameters* below for details.

Urprotocol is a leaner version of the STK500 1.x protocol that is designed to be backwards compatible with STK500 v1.x; it allows bootloaders to be much smaller, e.g., as implemented in the urboot project <https://github.com/stefanrueger/urboot>. The programmer type "urclock" caters for these urboot bootloaders. Owing to its backward compatibility, bootloaders that can be served by the arduino programmer can normally also be served by the urclock programmer. This may require specifying the size of (to AVRDUDE) *unknown* bootloaders in bytes using the `-x bootsize=<n>` option, which is necessary for the urclock programmer to enable it to protect the bootloader from being overwritten. If an unknown bootloader has EEPROM read/write capability then the option `-x eepromrw` informs `avrdude -c urclock` of that capability.

The BusPirate is a versatile tool that can also be used as an AVR programmer. A single BusPirate can be connected to up to 3 independent AVRs. See the section on *extended parameters* below for details.

The USBasp ISP, USBtinyISP and CH341A adapters are also supported, provided AVRDUDE has been compiled with libusb support. They former two feature simple firmware-only USB implementations, running on an ATmega8 (or ATmega88), or ATtiny2313, respectively. CH341A programmers connect directly to the AVR target. Their SPI bit clock is approximately 1.7 MHz and cannot be changed. As a consequence, the AVR target must have a CPU frequency of 6.8 MHz or more: factory-set AVR parts, which typically run on an internal oscillator between 1 MHz and 1.6 MHz, cannot be programmed using `-c ch341a`.

The Atmel DFU bootloader is supported in both, FLIP protocol version 1 (AT90USB* and ATmega*U* devices), as well as version 2 (Xmega devices). See below for some hints about FLIP version 1 protocol behaviour.

The MPLAB(R) PICKit 4 and MPLAB(R) SNAP are supported in JTAG, TPI, ISP, PDI and UPDI mode. The Curiosity Nano board is supported in UPDI mode. It is dubbed “PICKit on Board”, thus the name `pkobn_updi`.

SerialUPDI programmer implementation is based on Microchip’s *pymcuprog* (<https://github.com/microchip-pic-avr-tools/pymcuprog>) utility, but it also contains some performance improvements included in Spence Konde’s *DxCore* Arduino core (<https://github.com/SpenceKonde/DxCore>). In a nutshell, this programmer consists of simple USB->UART adapter, diode and couple of resistors. It uses serial connection to provide UPDI interface. See Section 5.3 [SerialUPDI programmer], page 63, for more details and known issues.

The `jtag2updi` programmer is supported, and can program AVRs with a UPDI interface. `Jtag2updi` is just a firmware that can be uploaded to an AVR, which enables it to interface with `avrdude` using the `jtagice mkii` protocol via a serial link (<https://github.com/ElTangas/jtag2updi>).

The Micronucleus bootloader is supported for both protocol version V1 and V2. As the bootloader does not support reading from flash memory, use the `-V` option to prevent `AVRDUDE` from verifying the flash memory. See the section on *extended parameters* below for Micronucleus specific options.

The Teensy bootloader is supported for all AVR boards. As the bootloader does not support reading from flash memory, use the `-V` option to prevent `AVRDUDE` from verifying the flash memory. See the section on *extended parameters* below for Teensy specific options.

1.1 History and Credits

`AVRDUDE` was written by Brian S. Dean under the name of `AVRPROG` to run on the FreeBSD Operating System. Brian renamed the software to be called `AVRDUDE` when interest grew in a Windows port of the software so that the name did not conflict with `AVRPROG.EXE` which is the name of Atmel’s Windows programming software.

For many years, the `AVRDUDE` source resided in public repositories on `savannah.nongnu.org`, where it continued to be enhanced and ported to other systems. In addition to FreeBSD, `AVRDUDE` now runs on Linux and Windows. The developers behind the porting effort primarily were Ted Roth, Eric Weddington, and Jörg Wunsch.

In 2022, the project moved to Github (<https://github.com/avrdudes/avrdude/>).

And in the spirit of many open source projects, this manual also draws on the work of others. The initial revision was composed of parts of the original Unix manual page written by Jörg Wunsch, the original web site documentation by Brian Dean, and from the comments describing the fields in the `AVRDUDE` configuration file by Brian Dean. The text formatting was modeled after that of the `Simulavr` documentation by Ted Roth.

2 Command Line Options

2.1 Option Descriptions

AVRDUDE is a command line tool, used as follows:

```
avrdude -p partno options ...
```

Command line options are used to control AVRDUDE's behaviour. The following options are recognized:

-p *partno* This option tells AVRDUDE what part (MCU) is connected to the programmer. The *partno* parameter is the part's id listed in the configuration file. To see a list of currently supported MCUs use ? as *partno*, which will print the part ids and official part names. In connection with -v, this will also print a list of variant part names followed by an optional colon, the package code and some absolute maximum ratings. The part id, their official part name, any of the full variant part names or their initial part up to a dash can be used to specify a part with the -p option. If a part is unknown to AVRDUDE, it means that there is no config file entry for that part, but it can be added to the configuration file if you have the Atmel datasheet so that you can enter the programming specifications. If -p ? is specified with a specific programmer, see -c below, then only those parts are output that the programmer expects to be able to handle, together with the programming interface(s) that can be used in that combination. In reality there can be deviations from this list, particularly if programming is directly via a bootloader. Currently, the following MCU types are understood:

uc3a0512	AT32UC3A0512
89S51	AT89S51
89S52	AT89S52
c128	AT90CAN128
c32	AT90CAN32
c64	AT90CAN64
pwm1	AT90PWM1
pwm161	AT90PWM161
pwm2	AT90PWM2
pwm216	AT90PWM216
pwm2b	AT90PWM2B
pwm3	AT90PWM3
pwm316	AT90PWM316
pwm3b	AT90PWM3B
pwm81	AT90PWM81
1200	AT90S1200 (****)
2313	AT90S2313
2323	AT90S2323
2333	AT90S2333
2343	AT90S2343 (*)

4414	AT90S4414
4433	AT90S4433
4434	AT90S4434
8515	AT90S8515
8535	AT90S8535
usb1286	AT90USB1286
usb1287	AT90USB1287
usb162	AT90USB162
usb646	AT90USB646
usb647	AT90USB647
usb82	AT90USB82
ata5505	ATA5505
ata6612c	ATA6612C
ata6613c	ATA6613C
ata6614q	ATA6614Q
ata6616c	ATA6616C
ata6617c	ATA6617C
ata664251	ATA664251
m103	ATmega103
m128	ATmega128
m1280	ATmega1280
m1281	ATmega1281
m1284	ATmega1284
m1284p	ATmega1284P
m1284rfr2	ATmega1284RFR2
m128a	ATmega128A
m128rfa1	ATmega128RFA1
m128rfr2	ATmega128RFR2
m16	ATmega16
m1608	ATmega1608
m1609	ATmega1609
m161	ATmega161
m162	ATmega162
m163	ATmega163
m164a	ATmega164A
m164p	ATmega164P
m164pa	ATmega164PA
m165	ATmega165
m165a	ATmega165A
m165p	ATmega165P
m165pa	ATmega165PA
m168	ATmega168
m168a	ATmega168A
m168p	ATmega168P
m168pa	ATmega168PA
m168pb	ATmega168PB
m169	ATmega169

m169a	ATmega169A
m169p	ATmega169P
m169pa	ATmega169PA
m16a	ATmega16A
m16hva	ATmega16HVA
m16hvb	ATmega16HVB
m16hvbrevb	ATmega16HVBrevB
m16m1	ATmega16M1
m16u2	ATmega16U2
m16u4	ATmega16U4
m2560	ATmega2560 (**)
m2561	ATmega2561 (**)
m2564rfr2	ATmega2564RFR2
m256rfr2	ATmega256RFR2
m32	ATmega32
m3208	ATmega3208
m3209	ATmega3209
m324a	ATmega324A
m324p	ATmega324P
m324pa	ATmega324PA
m324pb	ATmega324PB
m325	ATmega325
m3250	ATmega3250
m3250a	ATmega3250A
m3250p	ATmega3250P
m3250pa	ATmega3250PA
m325a	ATmega325A
m325p	ATmega325P
m325pa	ATmega325PA
m328	ATmega328
m328p	ATmega328P
m328pb	ATmega328PB
m329	ATmega329
m3290	ATmega3290
m3290a	ATmega3290A
m3290p	ATmega3290P
m3290pa	ATmega3290PA
m329a	ATmega329A
m329p	ATmega329P
m329pa	ATmega329PA
m32a	ATmega32A
m32c1	ATmega32C1
m32hvb	ATmega32HVB
m32hvbrevb	ATmega32HVBrevB
m32hve2	ATmega32HVE2
m32m1	ATmega32M1
m32u2	ATmega32U2

m32u4	ATmega32U4
m406	ATmega406
m48	ATmega48
m4808	ATmega4808
m4809	ATmega4809
m48a	ATmega48A
m48p	ATmega48P
m48pa	ATmega48PA
m48pb	ATmega48PB
m64	ATmega64
m640	ATmega640
m644	ATmega644
m644a	ATmega644A
m644p	ATmega644P
m644pa	ATmega644PA
m644rfr2	ATmega644RFR2
m645	ATmega645
m6450	ATmega6450
m6450a	ATmega6450A
m6450p	ATmega6450P
m645a	ATmega645A
m645p	ATmega645P
m649	ATmega649
m6490	ATmega6490
m6490a	ATmega6490A
m6490p	ATmega6490P
m649a	ATmega649A
m649p	ATmega649P
m64a	ATmega64A
m64c1	ATmega64C1
m64hve2	ATmega64HVE2
m64m1	ATmega64M1
m64rfr2	ATmega64RFR2
m8	ATmega8
m808	ATmega808
m809	ATmega809
m8515	ATmega8515
m8535	ATmega8535
m88	ATmega88
m88a	ATmega88A
m88p	ATmega88P
m88pa	ATmega88PA
m88pb	ATmega88PB
m8a	ATmega8A
m8hva	ATmega8HVA
m8u2	ATmega8U2
t10	ATtiny10

t102	ATtiny102
t104	ATtiny104
t11	ATtiny11 (***)
t12	ATtiny12
t13	ATtiny13
t13a	ATtiny13A
t15	ATtiny15
t1604	ATtiny1604
t1606	ATtiny1606
t1607	ATtiny1607
t1614	ATtiny1614
t1616	ATtiny1616
t1617	ATtiny1617
t1624	ATtiny1624
t1626	ATtiny1626
t1627	ATtiny1627
t1634	ATtiny1634
t1634r	ATtiny1634R
t167	ATtiny167
t20	ATtiny20
t202	ATtiny202
t204	ATtiny204
t212	ATtiny212
t214	ATtiny214
t22	ATtiny22
t2313	ATtiny2313
t2313a	ATtiny2313A
t24	ATtiny24
t24a	ATtiny24A
t25	ATtiny25
t26	ATtiny26
t261	ATtiny261
t261a	ATtiny261A
t28	ATtiny28
t3216	ATtiny3216
t3217	ATtiny3217
t3224	ATtiny3224
t3226	ATtiny3226
t3227	ATtiny3227
t4	ATtiny4
t40	ATtiny40
t402	ATtiny402
t404	ATtiny404
t406	ATtiny406
t412	ATtiny412
t414	ATtiny414
t416	ATtiny416

t416auto	ATtiny416auto
t417	ATtiny417
t424	ATtiny424
t426	ATtiny426
t427	ATtiny427
t4313	ATtiny4313
t43u	ATtiny43U
t44	ATtiny44
t441	ATtiny441
t44a	ATtiny44A
t45	ATtiny45
t461	ATtiny461
t461a	ATtiny461A
t48	ATtiny48
t5	ATtiny5
t804	ATtiny804
t806	ATtiny806
t807	ATtiny807
t814	ATtiny814
t816	ATtiny816
t817	ATtiny817
t824	ATtiny824
t826	ATtiny826
t827	ATtiny827
t828	ATtiny828
t828r	ATtiny828R
t84	ATtiny84
t841	ATtiny841
t84a	ATtiny84A
t85	ATtiny85
t861	ATtiny861
t861a	ATtiny861A
t87	ATtiny87
t88	ATtiny88
t9	ATtiny9
x128a1	ATxmega128A1
x128a1d	ATxmega128A1revD
x128a1u	ATxmega128A1U
x128a3	ATxmega128A3
x128a3u	ATxmega128A3U
x128a4	ATxmega128A4
x128a4u	ATxmega128A4U
x128b1	ATxmega128B1
x128b3	ATxmega128B3
x128c3	ATxmega128C3
x128d3	ATxmega128D3
x128d4	ATxmega128D4

x16a4	ATxmega16A4
x16a4u	ATxmega16A4U
x16c4	ATxmega16C4
x16d4	ATxmega16D4
x16e5	ATxmega16E5
x192a1	ATxmega192A1
x192a3	ATxmega192A3
x192a3u	ATxmega192A3U
x192c3	ATxmega192C3
x192d3	ATxmega192D3
x256a1	ATxmega256A1
x256a3	ATxmega256A3
x256a3b	ATxmega256A3B
x256a3bu	ATxmega256A3BU
x256a3u	ATxmega256A3U
x256c3	ATxmega256C3
x256d3	ATxmega256D3
x32a4	ATxmega32A4
x32a4u	ATxmega32A4U
x32c3	ATxmega32C3
x32c4	ATxmega32C4
x32d3	ATxmega32D3
x32d4	ATxmega32D4
x32e5	ATxmega32E5
x384c3	ATxmega384C3
x384d3	ATxmega384D3
x64a1	ATxmega64A1
x64a1u	ATxmega64A1U
x64a3	ATxmega64A3
x64a3u	ATxmega64A3U
x64a4	ATxmega64A4
x64a4u	ATxmega64A4U
x64b1	ATxmega64B1
x64b3	ATxmega64B3
x64c3	ATxmega64C3
x64d3	ATxmega64D3
x64d4	ATxmega64D4
x8e5	ATxmega8E5
avr128da28	AVR128DA28
avr128da32	AVR128DA32
avr128da48	AVR128DA48
avr128da64	AVR128DA64
avr128db28	AVR128DB28
avr128db32	AVR128DB32
avr128db48	AVR128DB48
avr128db64	AVR128DB64
avr16dd14	AVR16DD14

avr16dd20	AVR16DD20
avr16dd28	AVR16DD28
avr16dd32	AVR16DD32
avr16ea28	AVR16EA28
avr16ea32	AVR16EA32
avr16ea48	AVR16EA48
avr32da28	AVR32DA28
avr32da32	AVR32DA32
avr32da48	AVR32DA48
avr32db28	AVR32DB28
avr32db32	AVR32DB32
avr32db48	AVR32DB48
avr32dd14	AVR32DD14
avr32dd20	AVR32DD20
avr32dd28	AVR32DD28
avr32dd32	AVR32DD32
avr32ea28	AVR32EA28
avr32ea32	AVR32EA32
avr32ea48	AVR32EA48
avr64da28	AVR64DA28
avr64da32	AVR64DA32
avr64da48	AVR64DA48
avr64da64	AVR64DA64
avr64db28	AVR64DB28
avr64db32	AVR64DB32
avr64db48	AVR64DB48
avr64db64	AVR64DB64
avr64dd14	AVR64DD14
avr64dd20	AVR64DD20
avr64dd28	AVR64DD28
avr64dd32	AVR64DD32
avr64ea28	AVR64EA28
avr64ea32	AVR64EA32
avr64ea48	AVR64EA48
avr8ea28	AVR8EA28
avr8ea32	AVR8EA32
ucr2	deprecated,
lgt8f168p	LGT8F168P
lgt8f328p	LGT8F328P
lgt8f88p	LGT8F88P

(*) The AT90S2323 and ATtiny22 use the same algorithm.

(**) Flash addressing above 128 KB is not supported by all programming hardware. Known to work are jtag2, stk500v2, and bit-bang programmers.

(***) The ATtiny11 can only be programmed in high-voltage serial mode.

(****) The ISP programming protocol of the AT90S1200 differs in subtle ways from that of other AVRs. Thus, not all programmers support this device.

Known to work are all direct bitbang programmers, and all programmers talking the STK500v2 protocol.

-p *wildcard/flags*

Run developer options for MCUs that are matched by *wildcard*. Whilst their main use is for developers some *flags* can be of utility for users, e.g., `avrdude -p m328p/S` outputs AVRDUDE's understanding of ATmega328P MCU properties; for more information run `avrdude -p x/h`.

-b *baudrate*

Override the RS-232 connection baud rate specified in the respective programmer's entry of the configuration file.

-B *bitclock*

Specify the bit clock period for the JTAG, PDI, TPI, UPDI, or ISP interface. The value is a floating-point number in microseconds. Alternatively, the value might be suffixed with "Hz", "kHz" or "MHz" in order to specify the bit clock frequency rather than a period. Some programmers default their bit clock value to a 1 microsecond bit clock period, suitable for target MCUs running at 4 MHz clock and above. Slower MCUs need a correspondingly higher bit clock period. Some programmers reset their bit clock value to the default value when the programming software signs off, whilst others store the last used bit clock value. It is recommended to always specify the bit clock if read/write speed is important. You can use the 'default_bitclock' keyword in your `~/.config/avrdude/avrdude.rc` or `~/.avrduderc` configuration file to assign a default value to keep from having to specify this option on every invocation.

Note that some official Microchip programmers store the bitclock setting and will continue to use it until a different value is provided. This applies to "2nd gen" programmers (AVRISPmkII, AVR Dragon, JTAG ICE mkII, STK600) and "3rd gen" programmers (JTAGICE3, Atmel ICE, Power Debugger). "4th gen" programmers (PICKit 4, MPLAB SNAP) will store the last user-specified bitclock until the programmer is disconnected from the computer.

-c *programmer-id*

Specify the programmer to be used. AVRDUDE knows about several common programmers. Use this option to specify which one to use. The *programmer-id* parameter is the programmer's id listed in the configuration file. Specify `-c ?` to list all programmers in the configuration file. If you have a programmer that is unknown to AVRDUDE, and the programmer is controlled via the PC parallel port, there's a good chance that it can be easily added to the configuration file without any code changes to AVRDUDE. Simply copy an existing entry and change the pin definitions to match that of the unknown programmer. If `-c ?` is specified with a specific part, see `-p` above, then only those programmers are output that expect to be able to handle this part, together with the programming interface(s) that can be used in that combination. In reality there can be deviations from this list, particularly if programming is directly via a bootloader. Currently, the following programmer ids are understood and supported:

2232hio	2232hio based on FT2232H with buffer and LEDs
adafruit_gemma	Adafruit Trinket Gemma bootloader disguised as USBtiny
arduino	Arduino for bootloader using STK500 v1 protocol
arduino-ft232r	Arduino: FT232R connected to ISP
diecimila	Arduino: FT232R connected to ISP
arduino_as_isp	Arduino board as programmer using arduino as ISP firmware
arduino_gemma	Arduino Gemma bootloader disguised as USBtiny
arduinoisp	Arduino ISP Programmer
arduinoisporg	Arduino ISP Programmer
atmelice	Atmel-ICE (ARM/AVR) in JTAG mode
atmelice_jtag	Atmel-ICE (ARM/AVR) in JTAG mode
atmelice_dw	Atmel-ICE (ARM/AVR) in debugWIRE mode
atmelice_isp	Atmel-ICE (ARM/AVR) in ISP mode
atmelice_pdi	Atmel-ICE (ARM/AVR) in PDI mode
atmelice_tpi	Atmel-ICE (ARM/AVR) in TPI mode
atmelice_updi	Atmel-ICE (ARM/AVR) in UPDI mode
avr109	Atmel for bootloader using AppNote AVR109
avr910	Atmel Low Cost Serial Programmer
avr911	Atmel for bootloader using AppNote AVR911 AVROSP
avrisp	Atmel AVR ISP
avrisp-u	Kanda AVRISP-U
avrispmkII	Atmel AVR ISP mkII
avrisp2	Atmel AVR ISP mkII
avrispv2	Atmel AVR ISP v2
bustirate	The Bus Pirate
bustirate_bb	The Bus Pirate (bitbang interface, supports TPI)
butterfly	Atmel for bootloader (Butterfly Development Board)
butterfly_mk	Mikrokopter.de Butterfly for bootloader
mkbutterfly	Mikrokopter.de Butterfly for bootloader
bwmega	BitWizard ftdi_atmega builtin programmer
c232hm	C232HM cable from FTDI
c2n232i	serial port banging, reset=dtr sck=!rts sdo=!txd sdi=!cts
ch341a	ch341a programmer (AVR must have minimum F_CPU of 6.8 MHz)
dasa	serial port banging, reset=rts sck=dtr sdo=txd sdi=cts
dasa3	serial port banging, reset=!dtr sck=rts sdo=txd sdi=cts
digilent-hs2	Digilent JTAG HS2 (MPSSE)
dragon_dw	Atmel AVR Dragon in debugWire mode

<code>dragon_hvsp</code>	Atmel AVR Dragon in HVSP mode
<code>dragon_isp</code>	Atmel AVR Dragon in ISP mode
<code>dragon_jtag</code>	Atmel AVR Dragon in JTAG mode
<code>dragon_pdi</code>	Atmel AVR Dragon in PDI mode
<code>dragon_pp</code>	Atmel AVR Dragon in PP mode
<code>dryrun</code>	Emulates programming without a programmer
<code>ehajo-isp</code>	AVR ISP programmer from eHaJo.de
<code>flip1</code>	FLIP for bootloader using USB DFU protocol version 1 (doc7618)
<code>flip2</code>	FLIP for bootloader using USB DFU protocol version 2 (AVR4023)
<code>flyswatter2</code>	TinCan Tools Flyswatter 2
<code>ft2232h</code>	FT2232H/D based generic programmer
<code>avrftdi</code>	FT2232H/D based generic programmer
<code>2232h</code>	FT2232H/D based generic programmer
<code>ft232h</code>	FT232H based generic programmer
<code>ft232r</code>	FT232R based generic programmer
<code>ft245r</code>	FT245R based generic programmer
<code>ft4232h</code>	FT4232H based generic programmer
<code>4232h</code>	FT4232H based generic programmer
<code>iseavrprog</code>	AVR ISP programmer from iascaled.com
<code>jtag1slow</code>	Atmel JTAG ICE (mkI)
<code>jtag2dw</code>	Atmel JTAG ICE mkII in debugWire mode
<code>jtag2fast</code>	Atmel JTAG ICE mkII
<code>jtag2</code>	Atmel JTAG ICE mkII
<code>jtag2isp</code>	Atmel JTAG ICE mkII in ISP mode
<code>jtag2pdi</code>	Atmel JTAG ICE mkII in PDI mode
<code>jtag2slow</code>	Atmel JTAG ICE mkII
<code>jtag2updi</code>	JTAGv2 to UPDI bridge
<code>jtag3</code>	Atmel AVR JTAGICE3 in JTAG mode
<code>jtag3dw</code>	Atmel AVR JTAGICE3 in debugWIRE mode
<code>jtag3isp</code>	Atmel AVR JTAGICE3 in ISP mode
<code>jtag3pdi</code>	Atmel AVR JTAGICE3 in PDI mode
<code>jtag3updi</code>	Atmel AVR JTAGICE3 in UPDI mode
<code>jtagkey</code>	Amontec JTAGKey, JTAGKey-Tiny and JTAGKey2
<code>jtagmkI</code>	Atmel JTAG ICE (mkI)
<code>jtag1</code>	Atmel JTAG ICE (mkI)
<code>jtagmkII</code>	Atmel JTAG ICE mkII
<code>jtagmkII_avr32</code>	Atmel JTAG ICE mkII in AVR32 mode
<code>jtag2avr32</code>	Atmel JTAG ICE mkII in AVR32 mode
<code>ktlink</code>	KT-LINK FT2232H interface with IO switching and voltage buffers
<code>lm3s811</code>	Luminary Micro LM3S811 Eval Board (Rev. A)
<code>mib510</code>	Crossbow MIB510 programming board
<code>micronucleus</code>	Micronucleus for bootloader

nibobee	NIBObee
o-link	O-Link, OpenJTAG ARM JTAG USB
openmoko	Openmoko debug board (v3)
pavr	Jason Kyle's pAVR Serial Programmer
pickit2	MicroChip's PICKit2 Programmer
pickit4	MPLAB(R) PICKit 4 in JTAG mode
pickit4_jtag	MPLAB(R) PICKit 4 in JTAG mode
pickit4_isp	MPLAB(R) PICKit 4 in ISP mode
pickit4_pdi	MPLAB(R) PICKit 4 in PDI mode
pickit4_tpi	MPLAB(R) PICKit 4 in TPI mode
pickit4_updi	MPLAB(R) PICKit 4 in UPDI mode
pkobn_updi	Curiosity nano (nEDBG) in UPDI mode
ponyser	design ponyprog serial, reset=!txd sck=rts sdo=dtr sdi=cts
powerdebugger	Atmel PowerDebugger (ARM/AVR) in JTAG mode
powerdebugger_jtag	Atmel PowerDebugger (ARM/AVR) in JTAG mode
powerdebugger_dw	Atmel PowerDebugger (ARM/AVR) in debugWire mode
powerdebugger_isp	Atmel PowerDebugger (ARM/AVR) in ISP mode
powerdebugger_pdi	Atmel PowerDebugger (ARM/AVR) in PDI mode
powerdebugger_tpi	Atmel PowerDebugger (ARM/AVR) in TPI mode
powerdebugger_updi	Atmel PowerDebugger (ARM/AVR) in UPDI mode
serialupdi	SerialUPDI
siprogram	Lancos SI-Prog (same as ponyser)
snap	MPLAB(R) Snap in JTAG mode
snap_jtag	MPLAB(R) Snap in JTAG mode
snap_isp	MPLAB(R) SNAP in ISP mode
snap_pdi	MPLAB(R) SNAP in PDI mode
snap_tpi	MPLAB(R) SNAP in TPI mode
snap_updi	MPLAB(R) SNAP in UPDI mode
stk500	Atmel STK500
stk500hvsp	Atmel STK500 v2 in high-voltage serial program- ming mode
scratchmonkey_hvsp	Atmel STK500 v2 in high-voltage serial program- ming mode
stk500pp	Atmel STK500 v2 in parallel programming mode
scratchmonkey_pp	Atmel STK500 v2 in parallel programming mode
stk500v1	Atmel STK500 version 1.x firmware
stk500v2	Atmel STK500 version 2.x firmware
scratchmonkey	Atmel STK500 version 2.x firmware
stk600	Atmel STK600
stk600hvsp	Atmel STK600 in high-voltage serial programming mode
stk600pp	Atmel STK600 in parallel programming mode

<code>tc2030</code>	Tag-Connect TC2030
<code>teensy</code>	Teensy for bootloader
<code>tigard</code>	Tigard interface board
<code>ttl232r</code>	FTDI TTL232R-5V with ICSP adapter
<code>tumpa</code>	TIAO USB Multi-Protocol Adapter
<code>um232h</code>	UM232H module from FTDI
<code>uncompatino</code>	uncompatino with all pairs of pins shorted
<code>urclock</code>	Urclock programmer for urboot bootloaders using urprotocol
<code>usbasp</code>	USBasp ISP and TPI programmer
<code>usbasp-clone</code>	Any usbasp clone with correct VID/PID
<code>usbtiny</code>	USBTiny simple USB programmer
<code>wiring</code>	Wiring for bootloader using STK500 v2 protocol
<code>xbee</code>	XBee for Series 2 Over-The-Air (XBeeBoot) boot-loader using STK500 v1 protocol
<code>xplainedmini</code>	Atmel AVR XplainedMini in ISP mode
<code>xplainedmini_isp</code>	Atmel AVR XplainedMini in ISP mode
<code>xplainedmini_dw</code>	Atmel AVR XplainedMini in debugWIRE mode
<code>xplainedmini_tpi</code>	Atmel AVR XplainedMini in TPI mode
<code>xplainedmini_updi</code>	Atmel AVR XplainedMini in UPDI mode
<code>xplainedpro</code>	Atmel AVR XplainedPro in JTAG mode
<code>xplainedpro_pdi</code>	Atmel AVR XplainedPro in PDI mode
<code>xplainedpro_updi</code>	Atmel AVR XplainedPro in UPDI mode

`-c wildcard/flags`

Run developer options for programmers that are matched by *wildcard*. Whilst their main use is for developers some *flags* can be of utility for users, e.g., `avrdude -c usbtiny/S` shows AVRDUDE's understanding of usbtiny's properties; for more information run `avrdude -c x/h`.

`-C config-file`

Use the specified config file for configuration data. This file contains all programmer and part definitions that AVRDUDE knows about. If not specified, AVRDUDE looks for the configuration file in the following two locations:

1. `<directory from which application loaded>/../etc/avrdude.conf`
2. `<directory from which application loaded>/avrdude.conf`

If not found there, the lookup procedure becomes platform dependent. On FreeBSD and Linux, AVRDUDE looks at `/usr/local/etc/avrdude.conf`. See Appendix A for the method of searching on Windows.

If *config-file* is written as *+filename* then this file is read after the system wide and user configuration files. This can be used to add entries to the configuration without patching your system wide configuration file. It can be used several times, the files are read in same order as given on the command line.

`-A`

Disable the automatic removal of trailing-0xFF sequences in file input that is to be programmed to flash and in AVR reads from flash memory. Normally, trailing 0xFFs can be discarded, as flash programming requires the memory be

erased to 0xFF beforehand. `-A` should be used when the programmer hardware, or bootloader software for that matter, does not carry out chip erase and instead handles the memory erase on a page level. The popular Arduino bootloader exhibits this behaviour; for this reason `-A` is engaged by default when specifying `-c arduino`.

`-D` Disable auto erase for flash. When the `-U` option with flash memory is specified, avrdude will perform a chip erase before starting any of the programming operations, since it generally is a mistake to program the flash without performing an erase first. This option disables that. Auto erase is not used for ATxmega devices as these devices can use page erase before writing each page so no explicit chip erase is required. Note however that any page not affected by the current operation will retain its previous contents. Setting `-D` implies `-A`.

`-e` Causes a chip erase to be executed. This will reset the contents of the flash ROM and EEPROM to the value '0xff', and clear all lock bits. Except for ATxmega devices which can use page erase, it is basically a prerequisite command before the flash ROM can be reprogrammed again. The only exception would be if the new contents would exclusively cause bits to be programmed from the value '1' to '0'. Note that in order to reprogram EEPROM cells, no explicit prior chip erase is required since the MCU provides an auto-erase cycle in that case before programming the cell.

`-E exitspec[,...]`

By default, AVRDUDE leaves the parallel port in the same state at exit as it has been found at startup. This option modifies the state of the '/RESET' and 'Vcc' lines the parallel port is left at, according to the exitspec arguments provided, as follows:

`reset` The '/RESET' signal will be left activated at program exit, that is it will be held low, in order to keep the MCU in reset state afterwards. Note in particular that the programming algorithm for the AT90S1200 device mandates that the '/RESET' signal is active before powering up the MCU, so in case an external power supply is used for this MCU type, a previous invocation of AVRDUDE with this option specified is one of the possible ways to guarantee this condition. `reset` is supported by the `linuxspi` and `flip2` programmer options, as well as all parallel port based programmers.

`noreset` The '/RESET' line will be deactivated at program exit, thus allowing the MCU target program to run while the programming hardware remains connected. `noreset` is supported by the `linuxspi` and `flip2` programmer options, as well as all parallel port based programmers.

`vcc` This option will leave those parallel port pins active (i. e. high) that can be used to supply 'Vcc' power to the MCU.

`novcc` This option will pull the 'Vcc' pins of the parallel port down at program exit.

d_high This option will leave the 8 data pins on the parallel port active (i. e. high).

d_low This option will leave the 8 data pins on the parallel port inactive (i. e. low).

Multiple *exitspec* arguments can be separated with commas.

-F Normally, AVRDUDE tries to verify that the device signature read from the part is reasonable before continuing. Since it can happen from time to time that a device has a broken (erased or overwritten) device signature but is otherwise operating normally, this options is provided to override the check. Also, for programmers like the Atmel STK500 and STK600 which can adjust parameters local to the programming tool (independent of an actual connection to a target controller), this option can be used together with **-t** to continue in terminal mode. Moreover, the option allows to continue despite failed initialization of connection between a programmer and a target.

-i delay For bitbang-type programmers, delay for approximately *delay* microseconds between each bit state change. If the host system is very fast, or the target runs off a slow clock (like a 32 kHz crystal, or the 128 kHz internal RC oscillator), this can become necessary to satisfy the requirement that the ISP clock frequency must not be higher than 1/4 of the CPU clock frequency. This is implemented as a spin-loop delay to allow even for very short delays. On Unix-style operating systems, the spin loop is initially calibrated against a system timer, so the number of microseconds might be rather realistic, assuming a constant system load while AVRDUDE is running. On Win32 operating systems, a preconfigured number of cycles per microsecond is assumed that might be off a bit for very fast or very slow machines.

-l logfile Use *logfile* rather than *stderr* for diagnostics output. Note that initial diagnostic messages (during option parsing) are still written to *stderr* anyway.

-n No-write: disables writing data to the MCU whilst processing **-U** (useful for debugging AVRDUDE). The terminal mode continues to write to the device.

-O Perform a RC oscillator run-time calibration according to Atmel application note AVR053. This is only supported on the STK500v2, AVRISP mkII, and JTAG ICE mkII hardware. Note that the result will be stored in the EEPROM cell at address 0.

-P port Use *port* to identify the device to which the programmer is attached. Normally, the default parallel port is used, but if the programmer type normally connects to the serial port, the default serial port will be used. See Appendix A, Platform Dependent Information, to find out the default port names for your platform. If you need to use a different parallel or serial port, use this option to specify the alternate port name.

On Win32 operating systems, the parallel ports are referred to as lpt1 through lpt3, referring to the addresses 0x378, 0x278, and 0x3BC, respectively. If the parallel port can be accessed through a different address, this address can be

specified directly, using the common C language notation (i. e., hexadecimal values are prefixed by *0x*).

For the JTAG ICE mkII, if AVRDUDE has been built with libusb support, *port* may alternatively be specified as `usb[:serialno]`. In that case, the JTAG ICE mkII will be looked up on USB. If *serialno* is also specified, it will be matched against the serial number read from any JTAG ICE mkII found on USB. The match is done after stripping any existing colons from the given serial number, and right-to-left, so only the least significant bytes from the serial number need to be given. For a trick how to find out the serial numbers of all JTAG ICEs attached to USB, see Section 2.3 [Example Command Line Invocations], page 34.

As the AVRISP mkII device can only be talked to over USB, the very same method of specifying the port is required there.

For the USB programmer "AVR-Doper" running in HID mode, the port must be specified as *avrdoper*. Libhidapi support is required on Unix and Mac OS but not on Windows. For more information about AVR-Doper see <http://www.obdev.at/avrusb/avrdoper.html>.

For the USBtinyISP, which is a simplistic device not implementing serial numbers, multiple devices can be distinguished by their location in the USB hierarchy. See the respective See Appendix B [Troubleshooting], page 69, entry for examples.

For the XBee programmer the target MCU is to be programmed wirelessly over a ZigBee mesh using the XBeeBoot bootloader. The ZigBee 64-bit address for the target MCU's own XBee device must be supplied as a 16-character hexadecimal value as a port prefix, followed by the @ character, and the serial device to connect to a second directly contactable XBee device associated with the same mesh (with a default baud rate of 9600). This may look similar to: `0013a20000000001dev/tty.serial`.

For diagnostic purposes, if the target MCU with an XBeeBoot bootloader is connected directly to the serial port, the 64-bit address field can be omitted. In this mode the default baud rate will be 19200.

For programmers that attach to a serial port using some kind of higher level protocol (as opposed to bit-bang style programmers), *port* can be specified as `net:host:port`. In this case, instead of trying to open a local device, a TCP network connection to (TCP) *port* on *host* is established. Square brackets may be placed around *host* to improve readability for numeric IPv6 addresses (e.g. `net:[2001:db8::42]:1337`). The remote endpoint is assumed to be a terminal or console server that connects the network stream to a local serial port where the actual programmer has been attached to. The port is assumed to be properly configured, for example using a transparent 8-bit data connection without parity at 115200 Baud for a STK500.

Note: The ability to handle IPv6 hostnames and addresses is limited to Posix systems (by now).

-q Disable (or quell) output of the progress bar while reading or writing to the device. Specify it a second time for even quieter operation.

- `-s, -u` These options used to control the obsolete "safemode" feature which is no longer present. They are silently ignored for backwards compatibility.
- `-T cmd` Run terminal line *cmd* when it is its turn in relation to other `-t` interactive terminals, `-T` terminal commands and `-U` memory operations. Except for the simplest of terminal commands the argument *cmd* will most likely need to be set in quotes, see your OS shell manual for details. See below for a detailed description of all terminal commands.
- `-t` Tells AVRDUDE to run an interactive terminal when it is its turn in relation to other `-t` interactive terminals, `-T` terminal commands and `-U` memory operations.

`-U memory:op:filename[:format]`

Perform a memory operation when it is its turn in relation to other `-t` interactive terminals, `-T` terminal commands and `-U` memory operations. The *memory* field specifies the memory type to operate on. Use the `-T part` option on the command line or the `part` command in the interactive terminal to display all the memory types supported by a particular device.

Typically, a device's memory configuration at least contains the memory types `flash`, `eeprom`, `signature` and `lock`, which is sometimes known as `lockbits`. The `signature` memory contains the three device signature bytes, which should be, but not always are, unique for the part. The `lock` memory of one or four bytes typically details whether or not external reading/writing of the flash memory, or parts of it, is allowed. Parts will also typically have fuse bytes, which are read/write memories for configuration of the device and calibration memories that typically contain read-only factory calibration values.

Classic devices may have the following memory types in addition to `eeprom`, `flash`, `signature` and `lock`:

`calibration`

One or more bytes of RC oscillator calibration data

`efuse` Extended fuse byte

`fuse` Fuse byte in devices that have only a single fuse byte

`hfuse` High fuse byte

`lfuse` Low fuse byte

`usersig` Three extra flash pages for firmware settings; this memory is not erased during a chip erase. Only some classic parts, ATmega(64|128|256|644|1284|2564)RFR2, have a `usersig` memory. `Usersig` is different to `flash` in the sense that it can neither be accessed with ISP serial programming nor written to by bootloaders. AVRDUDE offers JTAG programming of classic-part `usersig` memories. As with all flash-type memories the `-U` option can only write 0-bits but not 1-bits. Hence, `usersig` needs to be erased before a file can be uploaded to this memory region, e.g., using `-T "erase usersig" -U usersig:w:parameters.hex:i`

ATxmega devices have the following memory types in addition to `eeeprom`, `flash`, `signature` and `lock`:

<code>application</code>	Application flash area
<code>apptable</code>	Application table flash area
<code>boot</code>	Boot flash area
<code>fuse0</code>	A.k.a. <code>jtaguid</code> : JTAG user ID for some devices
<code>fuse1</code>	Watchdog configuration
<code>fuse6</code>	Fault detection action configuration TC4/5 for ATxmega E series parts
<code>fuseN</code>	Other fuse bytes of ATxmega devices, where <i>N</i> is 2, 4 or 5, for system configuration
<code>prodsig</code>	Production signature (calibration) area
<code>usersig</code>	Additional flash memory page that can be used for firmware settings; this memory is not erased during a chip erase

Modern 8-bit AVR devices have the following memory types in addition to `eeeprom`, `flash`, `signature` and `lock`:

<code>fuse0</code>	A.k.a. <code>wdtcfg</code> : watchdog configuration
<code>fuse1</code>	A.k.a. <code>bodcfg</code> : brownout detection configuration
<code>fuse2</code>	A.k.a. <code>osccfg</code> : oscillator configuration
<code>fuse4</code>	A.k.a. <code>tcd0cfg</code> (not all devices): timer counter type D configuration
<code>fuse5</code>	A.k.a. <code>syscfg0</code> : system configuration 0
<code>fuse6</code>	A.k.a. <code>syscfg1</code> : system configuration 1
<code>fuse7</code>	A.k.a. <code>append</code> or <code>codesize</code> : either the end of the application code section or the code size in blocks of 256/512 bytes
<code>fuse8</code>	A.k.a. <code>bootend</code> or <code>bootsize</code> : end of the boot section or the boot size in blocks of 256/512 bytes
<code>fuses</code>	A "logical" memory of 9 bytes containing all <code>fuseN</code> of a part, which can be used to program all fuses at the same time
<code>osc16err</code>	Two bytes typically describing the 16 MHz oscillator frequency error at 3 V and 5 V, respectively
<code>osc20err</code>	Two bytes typically describing the 20 MHz oscillator frequency error at 3 V and 5 V, respectively
<code>osccal16</code>	Two oscillator calibration bytes for 16 MHz
<code>osccal20</code>	Two oscillator calibration bytes for 20 MHz
<code>prodsig</code>	Production signature (calibration) area

<code>sernum</code>	Serial number with a unique ID for the pary (10 bytes)
<code>tempsense</code>	Temperature sensor calibration values
<code>userrow</code>	Extra page of EEPROM memory that can be used for firmware settings; this memory is not erased during a chip erase

The *op* field specifies what operation to perform:

<code>r</code>	read the specified device memory and write to the specified file
<code>w</code>	read the specified file and write it to the specified device memory
<code>v</code>	read the specified device memory and the specified file and perform a verify operation

The *filename* field indicates the name of the file to read or write. The *format* field is optional and contains the format of the file to read or write. Possible values are:

<code>i</code>	Intel Hex
<code>I</code>	Intel Hex with comments on download and tolerance of checksum errors on upload
<code>s</code>	Motorola S-record
<code>r</code>	raw binary; little-endian byte order, in the case of the flash ROM data
<code>e</code>	ELF (Executable and Linkable Format), the final output file from the linker; currently only accepted as an input file
<code>m</code>	immediate mode; actual byte values are specified on the command line, separated by commas or spaces in place of the <i>filename</i> field of the <code>-U</code> option. This is useful for programming fuse bytes without having to create a single-byte file or enter terminal mode.
<code>a</code>	auto detect; valid for input only, and only if the input is not provided at stdin.
<code>d</code>	decimal; this and the following formats generate one line of output for the respective memory section, forming a comma-separated list of the values. This can be particularly useful for subsequent processing, like for fuse bit settings.
<code>h</code>	hexadecimal; each value will get the string <code>0x</code> prepended.
<code>o</code>	octal; each value will get a <code>0</code> prepended unless it is less than 8 in which case it gets no prefix.
<code>b</code>	binary; each value will get the string <code>0b</code> prepended.

When used as input, the `m`, `d`, `h`, `o` and `b` formats will use the same code for reading lists of numbers separated by white space and/or commas. The read routine handles decimal, hexadecimal, octal or binary numbers on a number-by-number basis, and the list of numbers can therefore be of mixed type. In

fact the syntax, is the same as for data used by the terminal write command, i.e., the file's input data can also be 2-byte short integers, 4-byte long integers or 8-byte long long integers, 4-byte floating point numbers, 8-byte double precision numbers, C-type strings with a terminating nul or C-like characters such as '\t'. Numbers are written as little endian to memory. When using 0x hexadecimal or 0b binary input leading zeros are used to determine the size of the integer, e.g., 0x002a will occupy two bytes and write a 0x2a to memory followed by 0x00, while 0x01234 will occupy 4 bytes. See the description of the terminal write command for more details.

In absence of an explicit file format, the default is to use auto detection for input files, and raw binary format for output files. Note that if *filename* contains a colon as penultimate character the *format* field is no longer optional since the last character would otherwise be misinterpreted as *format*.

When reading any kind of flash memory area (including the various sub-areas in Xmega devices), the resulting output file will be truncated to not contain trailing 0xFF bytes which indicate unprogrammed (erased) memory. Thus, if the entire memory is unprogrammed, this will result in an output file that has no contents at all. This behaviour can be overridden with the `-A` option.

As an abbreviation, the form `-U filename` is equivalent to specifying `-U flash:w:filename:a`. This will only work if *filename* does not have a pair of colons in it that sandwich a single character as otherwise the first part might be interpreted as memory, and the single character as memory operation.

`-v` Enable verbose output. More `-v` options increase verbosity level.

`-V` Disable automatic verify check when uploading data with `-U`.

`-x extended_param`

Pass *extended_param* to the chosen programmer implementation as an extended parameter. The interpretation of the extended parameter depends on the programmer itself. See below for a list of programmers accepting extended parameters or issue `avrdude -x help ...` to see the extended options of the chosen programmer.

2.2 Programmers accepting extended parameters

JTAG ICE mkII/3

Atmel-ICE

PICkit 4

MPLAB SNAP

Power Debugger

AVR Dragon

When using the JTAG ICE mkII, JTAGICE3, Atmel-ICE, PICkit 4, MPLAB SNAP, Power Debugger or AVR Dragon in JTAG mode, the following extended parameter is accepted:

`'jtagchain=UB,UA,BB,BA'`

Setup the JTAG scan chain for *UB* units before, *UA* units after, *BB* bits before, and *BA* bits after the target AVR, respectively. Each AVR unit within the chain shifts by 4 bits. Other JTAG units might require a different bit shift count.

`'hvpudi'` *Power Debugger and Pickit 4 only*

High-voltage UPDI programming is used to enable a UPDI pin that has previously been set to RESET or GPIO mode. Use `'-xhvpudi'` to enable high-voltage UPDI initialization for supported targets.

`'vtarg=VALUE, vtarg'`

Power Debugger only

The voltage generator can be enabled by setting a target voltage. The current set-voltage can be read by `'-xvtarg'` alone.

`'help'` Show help menu and exit.

Xplained Mini

The Xplained Mini/Nano programmer (ISP or UPDI, not TPI) type accepts the following extended parameters:

`'suffer=VALUE', 'suffer'`

The SUFFER register allows the user to modify the behavior of the on-board mEDBG. The current state can be read by `'-xsuffer'` alone.

Bit 7 ARDUINO:

Adds control of extra LEDs when set to 0

Bit 6..3: Reserved (must be set to 1)

Bit 2 EOF:

Agressive power-down, sleep after 5 seconds if no USB enumeration when set to 0

Bit 1 LWP:

forc running the mEDBG at 1 MHz when bit set to 0

Bit 0 FUSE:

Fuses are safe-masked when bit sent to 1. Fuses are unprotected when set to 0

`'vtarg_switch=VALUE', 'vtarg_switch'`

The on-board target voltage switch can be turned on or off by writing a 1 or a 0. The current state can be read by `'-xvtarg_switch'` alone. Note that the target power switch will always be on after a power cycle. Also note that the smaller Xplained Nano boards does not have a target power switch.

`'help'` Show help menu and exit.

Curiosity Nano

The Curiosity Nano board accepts the following extended parameter:

`'vtarg=VALUE, vtarg'`

The generated on-board target voltage can be changed by specifying a new voltage. The current set-voltage can be read by `'-xvtarg'` alone.

`'help'` Show help menu and exit.

STK500

STK600

The STK500 and STK600 boards accept the following extended parameters:

`'vtarg=VALUE, vtarg'`

The generated on-board target voltage can be changed by specifying a new voltage. The current set-voltage can be read by `'-xvtarg'` alone.

`'fosc=VALUE[MHz|M|kHz|k|Hz], fosc'`

Set the programmable oscillator frequency in MHz, kHz or Hz. The current frequency can be read by `'-xfosc'` alone.

`'varef=VALUE, varef'`

The generated on-board analog reference voltage can be changed by specifying a new reference voltage. The current reference voltage can be read by `'-xvaref'` alone.

`'varef[0,1]=VALUE, varef[0,1]'`

STK600 only

The generated on-board analog reference voltage for channel 0 or channel 1 can be changed by specifying a new reference voltage. The current reference voltage can be read by `'-xvaref0'` or `'-xvaref1'` alone.

`'attempts[=<1..99>]'`

STK500V1 only

Specify how many connection retry attempts to perform before exiting. Defaults to 10 if not specified.

`'help'` Show help menu and exit.

AVR910

The AVR910 programmer type accepts the following extended parameter:

`'devcode=VALUE'`

Override the device code selection by using *VALUE* as the device code. The programmer is not queried for the list of supported device codes, and the specified *VALUE* is not verified but used directly within the T command sent to the programmer. *VALUE* can be specified using the conventional number notation of the C programming language.

`'no_blockmode'`

Disables the default checking for block transfer capability. Use `'no_blockmode'` only if your 'AVR910' programmer creates errors during initial sequence.

`'help'` Show help menu and exit.

Arduino

The Arduino programmer type accepts the following extended parameter:

`'attempts=VALUE'`

Override the default number of connection retry attempt by using *VALUE*.

`'help'` Show help menu and exit.

Urclock

The urclock programmer type accepts the following extended parameters:

`'showall'`

Show all info for the connected part, then exit. The `-xshow...` options below can be used to assemble a bespoke response consisting of a subset (or only one item) of all available relevant information about the connected part and bootloader.

`'showid'` Show a unique Urclock ID stored in either flash or EEPROM of the MCU, then exit.

`'id=<E|F>.<addr>.<len>'`

Historically, the Urclock ID was a six-byte unique little-endian number stored in Urclock boards at EEPROM address 257. The location of this number can be set by the `-xid=<E|F>.<addr>.<len>` extended parameter. E stands for EEPROM and F stands for flash. A negative address *addr* counts from the end of EEPROM and flash, respectively. The length *len* of the Urclock ID can be between 1 and 8 bytes.

`'showdate'`

Show the last-modified date of the input file for the flash application, then exit. If the input file was stdin, the date will be that of the programming. Date and filename are part of the metadata that the urclock programmer stores by default in high flash just under the bootloader; see also `-xnometadata`.

- `'showfilename'`
Show the input filename (or title) of the last flash writing session, then exit.
- `'title=<string>'`
When set, `<string>` will be used in lieu of the input filename. The maximum string length for the title/filename field is 254 bytes including terminating nul.
- `'showapp'`
Show the size of the programmed application, then exit.
- `'showstore'`
Show the size of the unused flash between the application and metadata, then exit.
- `'showmeta'`
Show the size of the metadata just below the bootloader, then exit.
- `'showboot'`
Show the size of the bootloader, then exit.
- `'showversion'`
Show bootloader version and capabilities, then exit.
- `'showvector'`
Show the vector number and name of the interrupt table vector used by the bootloader for starting the application, then exit. For hardware-supported bootloaders this will be vector 0 (Reset), and for vector bootloaders this will be any other vector number of the interrupt vector table or the slot just behind the vector table with the name `VBL_ADDITIONAL_VECTOR`.
- `'showpart'`
Show the part for which the bootloader was compiled, then exit.
- `'bootsize=<size>'`
Manual override for bootloader size. Urboot bootloaders put the number of used bootloader pages into a table at the top of the bootloader section, i.e., typically top of flash, so the urlock programmer can look up the bootloader size itself. In backward-compatibility mode, when programming via other bootloaders, this option can be used to tell the programmer the size, and therefore the location, of the bootloader.
- `'vectornum=<arg>'`
Manual override for vector number. Urboot bootloaders put the vector number used by a vector bootloader into a table at the top of flash, so this option is normally not needed for urboot bootloaders. However, it is useful in backward-compatibility mode (or when the urboot bootloader does not offer flash read). Specifying a vector number in these circumstances implies a vector bootloader whilst the default assumption would be a hardware-supported bootloader.

- `'eepromrw'`
Manual override for asserting EEPROM read/write capability. Not normally needed for urboot bootloaders, but useful for in backward-compatibility mode if the bootloader offers EEPROM read/write.
- `'emulate_ce'`
If an urboot bootloader does not offer a chip erase command it will tell the urclock programmer so during handshake. In this case the urclock programmer emulates a chip erase, if warranted by user command line options, by filling the remainder of unused flash below the bootloader with 0xff. If this option is specified, the urclock programmer will assume that the bootloader cannot erase the chip itself. The option is useful for backwards-compatible bootloaders that do not implement chip erase.
- `'restore'`
Upload unchanged flash input files and trim below the bootloader if needed. This is most useful when one has a backup of the full flash and wants to play that back onto the device. No metadata are written in this case and no vector patching happens either if it is a vector bootloader. However, for vector bootloaders, even under the option `-xrestore` an input file will not be uploaded for which the reset vector does not point to the vector bootloader. This is to avoid writing an input file to the device that would render the vector bootloader not functional as it would not be reached after reset.
- `'initstore'`
On writing to flash fill the store space between the flash application and the metadata section with 0xff.
- `'nofilename'`
On writing to flash do not store the application input filename (nor a title).
- `'nodate'`
On writing to flash do not store the application input filename (nor a title) and no date either.
- `'nostore'`
On writing to flash do not store metadata except the metadata code byte 0xff saying there are no metadata. In particular, no data store frame is programmed.
- `'nometadata'`
Do not support any metadata. The full flash besides the bootloader is available for the application. If the application is smaller than the available space then a metadata code byte 0xff is stored nevertheless to indicate there are no further metadata available. In absence of `-xnometadata`, the default for the urclock programmer is to write as much metadata (filename, data and store information) as the size of the uploaded application and the other extended options allow.

The subtle difference between `-xnometadata` and `-xnostore` is that the latter always explicitly stores in flash that no further metadata are available, so that a such prepared flash can always be queried with `avrdude -xshowall`. In contrast to this, it cannot be guaranteed that a `-xshowall` query on flash prepared with `-xnometadata` yields useful results.

`'delay=<n>'`

Add a `<n>` ms delay after reset. This can be useful if a board takes a particularly long time to exit from external reset. `<n>` can be negative, in which case the default 120 ms delay after issuing reset will be shortened accordingly.

`'strict'` Urclock has a faster, but slightly different strategy than `-c arduino` to synchronise with the bootloader; some `stk500v1` bootloaders cannot cope with this, and they need the `-xstrict` option.

`'help'` Show help menu and exit.

BusPirate

The BusPirate programmer type accepts the following extended parameters:

`'reset=cs,aux,aux2'`

The default setup assumes the BusPirate's CS output pin connected to the RESET pin on AVR side. It is however possible to have multiple AVRs connected to the same BP with SDI, SDO and SCK lines common for all of them. In such a case one AVR should have its RESET connected to BusPirate's CS pin, second AVR's RESET connected to BusPirate's AUX pin and if your BusPirate has an AUX2 pin (only available on BusPirate version v1a with firmware 3.0 or newer) use that to activate RESET on the third AVR.

It may be a good idea to decouple the BusPirate and the AVR's SPI buses from each other using a 3-state bus buffer. For example 74HC125 or 74HC244 are some good candidates with the latches driven by the appropriate reset pin (cs, aux or aux2). Otherwise the SPI traffic in one active circuit may interfere with programming the AVR in the other design.

`'spifreq=0..7'`

0	30 kHz (default)
1	125 kHz
2	250 kHz
3	1 MHz
4	2 MHz
5	2.6 MHz
6	4 MHz
7	8 MHz

`'rawfreq=0..3'`

Sets the SPI speed and uses the Bus Pirate's binary "raw-wire" mode instead of the default binary SPI mode:

- 0 5 kHz
- 1 50 kHz
- 2 100 kHz
(Firmware v4.2+ only)
- 3 400 kHz (v4.2+)

The only advantage of the “raw-wire” mode is that different SPI frequencies are available. Paged writing is not implemented in this mode.

`'ascii'` Attempt to use ASCII mode even when the firmware supports BinMode (binary mode). BinMode is supported in firmware 2.7 and newer, older FW’s either don’t have BinMode or their BinMode is buggy. ASCII mode is slower and makes the above `'reset='`, `'spifreq='` and `'rawfreq='` parameters unavailable. Be aware that ASCII mode is not guaranteed to work with newer firmware versions, and is retained only to maintain compatibility with older firmware versions.

`'nopagedwrite'` Firmware versions 5.10 and newer support a binary mode SPI command that enables whole pages to be written to AVR flash memory at once, resulting in a significant write speed increase. If use of this mode is not desirable for some reason, this option disables it.

`'nopagedread'` Newer firmware versions support in binary mode SPI command some AVR Extended Commands. Using the “Bulk Memory Read from Flash” results in a significant read speed increase. If use of this mode is not desirable for some reason, this option disables it.

`'cpufreq=125..4000'` This sets the *AUX* pin to output a frequency of *n* kHz. Connecting the *AUX* pin to the XTAL1 pin of your MCU, you can provide it a clock, for example when it needs an external clock because of wrong fuses settings. Make sure the CPU frequency is at least four times the SPI frequency.

`'serial_recv_timeout=1...'` This sets the serial receive timeout to the given value. The timeout happens every time avrdude waits for the BusPirate prompt. Especially in `ascii` mode this happens very often, so setting a smaller value can speed up programming a lot. The default value is 100ms. Using 10ms might work in most cases.

`'help'` Show help menu and exit.

Micronucleus bootloader

The Micronucleus programmer type accepts the following extended parameter:

`'wait=timeout'`

If the device is not connected, wait for the device to be plugged in. The optional *timeout* specifies the connection time-out in seconds. If no time-out is specified, AVRDUDE will wait indefinitely until the device is plugged in.

`'help'` Show help menu and exit.

Teensy bootloader

The Teensy programmer type accepts the following extended parameter:

`'wait=timeout'`

If the device is not connected, wait for the device to be plugged in. The optional *timeout* specifies the connection time-out in seconds. If no time-out is specified, AVRDUDE will wait indefinitely until the device is plugged in.

`'help'` Show help menu and exit.

Wiring

The Wiring programmer type accepts the following extended parameter:

`'snooze=0..32767'`

After performing the port open phase, AVRDUDE will wait/snooze for *snooze* milliseconds before continuing to the protocol sync phase. No toggling of DTR/RTS is performed if *snooze* > 0.

`'help'` Show help menu and exit.

PICkit2 Connection to the PICkit2 programmer:

```
(AVR) (PICkit2)
RST  VPP/MCLR (1)
VDD  VDD Target (2)
      -- possibly
      optional if AVR
      self powered
GND  GND (3)
SDI  PGD (4)
SCLK PDC (5)
OSI  AUX (6)
```

The PICkit2 programmer type accepts the following extended parameters:

`'clockrate=rate'`

Sets the SPI clocking rate in Hz (default is 100kHz). Alternately the -B or -i options can be used to set the period.

`'timeout=usb-transaction-timeout'`

Sets the timeout for USB reads and writes in milliseconds (default is 1500 ms).

`'help'` Show help menu and exit.

USBasp

The USBasp programmer type accepts the following extended parameter:

- `'section_config'`
Programmer will erase configuration section with option '-e' (chip erase), rather than entire chip. Only applicable to TPI devices (ATtiny 4/5/9/10/20/40).
- `'help'` Show help menu and exit.

xbee

The xbee programmer type accepts the following extended parameter:

- `'xbeeresetpin=1..7'`
Select the XBee pin `DI0<1..7>` that is connected to the MCU's '/RESET' line. The programmer needs to know which DIO pin to use to reset into the bootloader. The default (3) is the `DI03` pin (XBee pin 17), but some commercial products use a different XBee pin.
The remaining two necessary XBee-to-MCU connections are not selectable - the XBee `DOUT` pin (pin 2) must be connected to the MCU's 'RXD' line, and the XBee `DIN` pin (pin 3) must be connected to the MCU's 'TXD' line.
- `'help'` Show help menu and exit.

**jtag2updi
serialupdi**

The jtag2updi and serialupdi programmer types accept the following extended parameters:

- `'rtsdtr=low,high'`
Forces RTS/DTR lines to assume low or high state during the whole programming session. Some programmers might use this signal to indicate UPDI programming state, but this is strictly hardware specific.
When not provided, driver/OS default value will be used.
- `'help'` Show help menu and exit.

linuxspi

The linuxspi programmer type accepts the following extended parameter:

- `'disable_no_cs'`
Ensures the programmer does not use the `SPI_NO_CS` bit for the SPI driver. This parameter is useful for kernels that do not support the CS line being managed outside the application.
- `'help'` Show help menu and exit.

2.3 Example Command Line Invocations

AVRDUDE error messages, warnings and progress reports are generally written to stderr which can, in bash, be turned off by `2>/dev/null` or by using increasingly more `-q` options to suppress them. Terminal output of commands or that of the `-U` command with an output file named `-` are written to stdout. In some examples empty lines are shown for clarity that are not printed by AVRDUDE or the shell.

Download the file `diag.hex` to the ATmega128 chip using the STK500 programmer connected to the default serial port:

```
$ avrdude -p m128 -c stk500 -e -U flash:w:diag.hex

avrdude: AVR device initialized and ready to accept instructions
avrdude: device signature = 0x1e9702 (probably m128)
avrdude: erasing chip
avrdude: reading input file diag.hex for flash
        with 19278 bytes in 74 section within [0, 0x4b4e]
avrdude: writing 19278 bytes flash ...
Writing | ##### | 100% 7.60 s
avrdude: 19278 bytes of flash written
avrdude: verifying flash memory against diag.hex
Reading | ##### | 100% 6.83 s
avrdude: 19278 bytes of flash verified

avrdude done. Thank you.
```

Same but in **quell-progress-reporting (silent) mode** `-qq`:

```
$ avrdude -qq -p m128 -c stk500 -e -U flash:w:diag.hex
```

Using `&&` to confirm that the silent AVRDUDE command went OK:

```
$ avrdude -qq -p m128 -c stk500 -e -U flash:w:diag.hex && echo OK
OK
```

Save flash memory in raw binary format to the file named `c:/diag flash.bin`:

```
$ avrdude -p m128 -c stk500 -U flash:r:"c:/diag flash.bin":r

avrdude: AVR device initialized and ready to accept instructions
avrdude: device signature = 0x1e9702 (probably m128)
avrdude: reading flash memory ...
Reading | ##### | 100% 46.10s
avrdude: writing output file c:/diag flash.bin

avrdude done. Thank you.
```

Using the default programmer, download the file `diag.hex` to flash, `eeeprom.hex` to EEPROM, and set the **extended, high, and low fuse bytes** to `0xff`, `0x89`, and `0x2e` respectively:

```
$ avrdude -p m128 -U flash:w:diag.hex \
          -U eeprom:w:eeeprom.hex \
          -U efuse:w:0xff:m \
          -U hfuse:w:0x89:m \
          -U lfuse:w:0x2e:m

avrdude: AVR device initialized and ready to accept instructions
avrdude: device signature = 0x1e9702 (probably m128)
avrdude: Note: flash memory has been specified, an erase cycle will be performed.
        To disable this feature, specify the -D option.
avrdude: erasing chip
avrdude: reading input file diag.hex for flash
        with 19278 bytes in 74 section within [0, 0x4b4e]
avrdude: writing 19278 bytes flash ...
Writing | ##### | 100% 7.60 s
avrdude: 19278 bytes of flash written
avrdude: verifying flash memory against diag.hex
Reading | ##### | 100% 6.83 s
avrdude: 19278 bytes of flash verified

[ ... other memory status output skipped for brevity ... ]

avrdude done. Thank you.
```

Read the fuses and print their values in different formats (hexadecimal, binary and octal):

```
$ avrdude -cusbasp -patmega128 -qq -Ulfuse:r:-:h -Uhfuse:r:-:b -Uefuse:r:-:o

0xbf
0b11000110
0377
```

Connect to the JTAG ICE mkII with a **serial number ending in 1C37** via USB, and enter **terminal mode**:

```
$ avrdude -c jtag2 -p m649 -P usb:1c:37 -t

avrdude: AVR device initialized and ready to accept instructions
avrdude: Device signature = 0x1e9603

[ ... terminal mode output skipped for brevity ... ]

avrdude done. Thank you.
```


Using the Avrdude output to print strings present in flash memory:

```
$ avrdude -pattiny13 -qq -U flash:r:-:r | strings

Main menu
Distance: %dcm
Exit
```

Factory fuse setting of a device:

```
$ avrdude -patmega328p/St | grep initval

.ptmm ATmega328P lfuse initval 0x62
.ptmm ATmega328P hfuse initval 0xd9
.ptmm ATmega328P efuse initval 0xff
.ptmm ATmega328P lock initval 0xff
```

List of all parts known to AVRDUDE:

```
$ avrdude -p*/d | grep = | cut -f2 -d"'"

ATtiny11
ATtiny12
ATtiny13
ATtiny13A
ATtiny15
AT89S51
[...]
AVR64EA48
LGT8F88P
LGT8F168P
LGT8F328P
```

List of all modern AVR parts (with UPDI interface) known to AVRDUDE:

```
$ avrdude -p*/d | grep PM_UPDI | cut -f2 -d"'"

ATtiny202
ATtiny204
ATtiny402
[...]
AVR64EA28
AVR64EA32
AVR64EA48
```

AVRDUDE in a bash script creating terminal scripts that reset a part to factory settings:

```
$ cat make-init-scripts

#!/bin/bash
mkdir /tmp/factory
for part in $(avrdude -p*/d | grep = | cut -f2 -d' '); do
  echo $part
  avrdude -p$part/St | grep initval | cut -f3,5 | grep -ve-1 \
  | sed "s/.*./write &/" >/tmp/factory/$part.ini
done
```

Run above script and use one of the created terminal scripts:

```
$ ./make-init-scripts

$ cat /tmp/factory/ATmega328P.ini
write lfuse 0x62
write hfuse 0xd9
write efuse 0xff
write lock 0xff

$ avrdude -qq -cusbsp -pATmega328P -t < /tmp/factory/ATmega328P.ini
```

Output a list of non-bootloader programmers that can be used for a part. Note that `|&` folds stderr into stdout in a bash shell:

```
$ avrdude -c? -pavr32ea32 |& grep -v bootloader

Valid programmers for part AVR32EA32 are:
  atmelice_updi      = Atmel-ICE (ARM/AVR) via UPDI
  dryrun            = Emulates programming without a programmer via UPDI
  jtag2updi         = JTAGv2 to UPDI bridge via UPDI
  jtag3updi         = Atmel AVR JTAGICE3 via UPDI
  pickit4_updi      = MPLAB(R) PICKit 4 via UPDI
  pkobn_updi        = Curiosity nano (nEDBG) via UPDI
  powerdebugger_updi = Atmel PowerDebugger (ARM/AVR) via UPDI
  serialupdi        = SerialUPDI via UPDI
  snap_updi         = MPLAB(R) SNAP via UPDI
  xplainedmini_updi = Atmel AVR XplainedMini via UPDI
  xplainedpro_updi  = Atmel AVR XplainedPro via UPDI
```

Print filename of last stored sketch with its date stamp (only with urclock programmer):

```
$avrdude -qq -curclock -P/dev/ttyUSB0 -pattiny13 -xshowdate -xshowfilename

2023-05-19 11.13 blink.hex
```

Create a bash function `avrdude-elf` that takes an elf file as input, with support for optional Avrdude flags at the end, and **writes to all memories specified in the elf file**. In this example, the elf file did not contain any EEPROM data:

```
# Show all writable memories present for the ATtiny13
$ echo $(avrdude -pattiny13/ot | grep write | cut -f3 | uniq)

eeprom flash lfuse hfuse lock

# Function that writes to all memories present in the elf file
avrdude-elf() {
  avrdude -cusbsp -pattiny13 -U{eeprom,flash,{l,h}fuse,lock}:w:"$1":e "${@:2}"
}

# Run function where -B8 and -V is appended to the Avrdude command
$ avrdude-elf program.elf -B8 -V

avrdude: set SCK frequency to 93750 Hz
avrdude: AVR device initialized and ready to accept instructions
avrdude: device signature = 0x1e9007 (probably t13)
avrdude: Note: flash memory has been specified, an erase cycle will be performed.
        To disable this feature, specify the -D option.
avrdude: erasing chip

avrdude: reading input file Blink.elf for eeprom
        with 0 bytes in 0 sections within [0, -1]
        using 0 pages and 0 pad bytes
avrdude: writing 0 bytes eeprom ...
Writing | ##### | 100% 0.00 s
avrdude: 0 bytes of eeprom written

avrdude: reading input file Blink.elf for flash
        with 78 bytes in 1 section within [0, 0x4d]
        using 3 pages and 18 pad bytes
avrdude: writing 78 bytes flash ...
Writing | ##### | 100% 0.09 s
avrdude: 78 bytes of flash written

avrdude: reading input file Blink.elf for lfuse
        with 1 byte in 1 section within [0, 0]
avrdude: writing 1 byte lfuse ...
avrdude: 1 byte of lfuse written

avrdude: reading input file Blink.elf for hfuse
        with 1 byte in 1 section within [0, 0]
avrdude: writing 1 byte hfuse ...
avrdude: 1 byte of hfuse written

avrdude: reading input file Blink.elf for lock
        with 1 byte in 1 section within [0, 0]
avrdude: writing 1 byte lock ...
avrdude: 1 byte of lock written

avrdude done. Thank you.
```

3 Terminal Mode Operation

AVRDUDE has an interactive mode called *terminal mode* that is enabled by the `-t` option. This mode allows one to enter interactive commands to display and modify the various device memories, perform a chip erase, display the device signature bytes and part parameters, and to send raw programming commands. Commands and parameters may be abbreviated to their shortest unambiguous form. Terminal mode also supports a command history so that previously entered commands can be recalled and edited.

3.1 Terminal Mode Commands

In this mode, AVRDUDE only initializes communication with the MCU, and then awaits user commands on standard input. Commands and parameters may be abbreviated to the shortest unambiguous form. Terminal mode provides a command history using `readline(3)`, so previously entered command lines can be recalled and edited.

The *addr* and *len* parameters of the `dump`, `read`, `write`, `save` and `erase` commands can be negative with the same syntax as substring computations in perl or python. The table below details their meaning with respect to an example memory of size `sz=0x800`.

addr	len	Memory interval	Comment
0/positive	positive	[addr, addr+len-1]	Note: len = end-start + 1
0/positive	negative	[addr, sz+len]	End is len bytes below memory size sz
negative	positive	[sz+addr, ...]	Start is addr bytes below memory size
negative	negative	[sz+addr, sz+len]	Combining above two cases
any	zero	empty set	No action
0x700	12	[0x700, 0x70b]	Conventional use
1024	-257	[0x400, 0x6ff]	Size of memory is 2048 or 0x800
-512	512	[0x600, 0x7ff]	Last 512 bytes
-256	-1	[0x700, 0x7ff]	Last 256 bytes
0	49	[0, 48]	First 49 bytes
0	-49	[0, 1999]	All but the last 48 = len+1 bytes
0	-1	[0, 0x7ff]	All memory without knowing its size

The following commands are implemented for all programmers:

`dump memory addr len`

Read from the specified memory interval (see above), and display in the usual hexadecimal and ASCII form.

`dump memory addr`

Read from memory `addr` as many bytes as the most recent `dump memory addr len` command with this very memory had specified (default 256 bytes), and display them.

`dump memory`

Continue dumping from the memory and location where the most recent `dump` command left off; if no previous `dump` command has addressed a memory an error message will be shown.

`dump memory addr ...`

Start reading from `addr`, all the way to the last memory address (deprecated: use `dump memory addr -1`).

`dump memory ...`

Read all bytes from the specified memory, and display them (deprecated: use `dump memory 0 -1`).

`read`

Can be used as an alias for `dump`.

`write memory addr data[,] {data[,]}`

Manually program the respective memory cells, starting at address `addr`, using the data items provided. The terminal implements reading from and writing to flash, EEPROM and usersig type memories normally through a cache and paged access functions. All other memories are directly written to without use of a cache. Some older parts without paged access, depending on the programmer, might also have flash and EEPROM directly accessed without cache.

Items `data` can have the following formats:

Type	Example	Size (bytes)
String	"Hello, world\n"	varying
File	C:/My\ projects/blink.hex	varying
File with format	blink.hex:i	varying
Character	'A'	1
Binary integer	0b101010	1, 2, 4, or 8
Octal integer	012345	1, 2, 4, or 8
Decimal integer	12345	1, 2, 4, or 8

Hexadecimal integer	0x12345	1, 2, 4, or 8
Decimal float	3.1415926	4
Hexadecimal float	0xA.8p2	4
Decimal double	3.141592653589793D	8
Hexadecimal double	0xA.8p2D	8

data can be binary, octal, decimal or hexadecimal integers, floating point numbers or C-style strings and characters. If nothing matches, **data** will be interpreted as a name of a file containing data, which will be read and inserted at this point. In order to force the interpretation of a data item as file, e.g., when the file name would be understood as a number otherwise, the file name can be given a *:f* format specifier. In absence of a format suffix, the terminal will try to auto-detect the file format.

For integers, an optional case-insensitive suffix specifies the data size as in the table below:

LL	8 bytes / 64 bits
L	4 bytes / 32 bits
H or S	2 bytes / 16 bits
HH	1 byte / 8 bits

Suffix D indicates a 64-bit double, F a 32-bit float, whilst a floating point number without suffix defaults to 32-bit float. Hexadecimal floating point notation is supported. An ambiguous trailing suffix, e.g., 0x1.8D, is read as no-suffix float where D is part of the mantissa; use a zero exponent 0x1.8p0D to clarify.

An optional U suffix makes integers unsigned. Ordinary 0x hexadecimal and 0b binary integers are always treated as unsigned. +0x, -0x, +0b and -0b numbers with an explicit sign are treated as signed unless they have a U suffix. Unsigned integers cannot be larger than $2^{64}-1$. If *n* is an unsigned integer then *-n* is also a valid unsigned integer as in C. Signed integers must fall into the $[-2^{63}, 2^{63}-1]$ range or a correspondingly smaller range when a suffix specifies a smaller type.

Ordinary 0x hexadecimal and 0b binary integers with *n* hex digits (counting leading zeros) use the smallest size of one, two, four and eight bytes that can accommodate any *n*-digit hexadecimal/binary integer. If an integer suffix specifies a size explicitly the corresponding number of least significant bytes are written, and a warning shown if the number does not fit into the desired representation. Otherwise, unsigned integers occupy the smallest of one, two, four or eight bytes needed. Signed numbers are allowed to fit into the smallest signed or smallest unsigned representation: For example, 255 is stored as one byte as 255U would fit in one byte, though as a signed number it would not fit into a

one-byte interval [-128, 127]. The number `-1` is stored in one byte whilst `-1U` needs eight bytes as it is the same as `0xFFFFFFFFFFFFFFFFU`.

One trailing comma at the end of data items is ignored to facilitate copy and paste of lists.

write memory addr data

The start address `addr` may be omitted if the size of the memory being written to is one byte.

write memory addr len data[,] {data[,]} ...

The ellipsis `...` form writes the data to the entire memory interval addressed by `addr len` and, if necessary, pads the remaining space by repeating the last data item. The fill write command does not write beyond the specified memory area even if more data than needed were given.

save memory {addr len} file[:format]

Save one or more memory segments to a file in a format specified by the `:format` letter. The default is `:r` for raw binary. Each memory segment is described by an address and length pair. In absence of any memory segments the entire memory is saved to the file. Only Motorola S-Record (`:s`) and Intel Hex (`:i` or `:I`) formats store address information with the saved data. Avrdude cannot currently save ELF file formats. All the other file formats lose the address information and concatenate the chosen memory segments into the output file. If the file name is `-` then avrdude writes to `stdout`.

erase Perform a chip erase and discard all pending writes to EEPROM and flash. Note that EEPROM will be preserved if the EESAVE fuse bit is set.

erase memory

Erase the entire specified memory.

erase memory addr len

Erase a section of the specified memory.

flush Synchronise with the device all pending writes to flash, EEPROM and usersig. With some programmer and part combinations, flash (and sometimes EEPROM, too) looks like a NOR memory, i.e., a write can only clear bits, never set them. For NOR memories a page erase or, if not available, a chip erase needs to be issued before writing arbitrary data. Usersig is generally unaffected by a chip erase. When a memory looks like a NOR memory, either page erase is deployed (e.g., with parts that have PDI/UPDI interfaces), or if that is not available, both EEPROM and flash caches are fully read in, a chip erase command is issued and both EEPROM and flash are written back to the device. Hence, it can take minutes to ensure that a single previously cleared bit is set and, therefore, this routine should be called sparingly.

abort Normally, caches are only ever actually written to the device when using `flush`, at the end of the terminal session after typing `quit`, or after EOF on input is encountered. The `abort` command resets the cache discarding all previous writes to the flash, EEPROM and usersig cache.

config [*opts*]

Show all configuration properties of the part; these are usually bitfields in fuses or lock bits bytes that can take on values, which typically have a mnemonic name. Each part has their own set of configurable items. The option `-f` groups the configuration properties by the fuses and lock bits byte they are housed in, and shows the current value of these memories as well. Config `-a` outputs an initialisation script with all properties and all possible respective assignments. The currently assigned mnemonic values are the ones that are not commented out. The option `-v` increases the verbosity of the output of the config command.

config [*opts*] *property* [*opts*]

Show the current value of the named configuration property. Wildcards or initial strings are permitted (but not both), in which case the current values of all matching properties are displayed.

config [*opts*] *property*= [*opts*]

Show all possible values of the named configuration property (notice the trailing `=`). The one that is currently set is the only one not commented out. As before, wildcards or initial strings are permitted.

config [*opts*] *property*=*value* [*opts*]

Modify the named configuration property to the given value. The corresponding fuse or lock bits will be changed immediately but the change will normally only take effect the next time the part is reset, at which point the fuses and lock bits are utilised. Value can either be a valid integer or one of the symbolic mnemonics, if known. Wildcards or initial strings are permitted for either the property or the assigned mnemonic value, but an assignment only happens if both the property and the name can be uniquely resolved.

It is quite possible, as is with direct writing to the underlying fuses and lock bits, to brick a part, i.e., make it unresponsive to further programming with the chosen programmer: here be dragons.

include [*opts*] *file*

Include contents of the named file *file* as if it was typed. This is useful for batch scripts, e.g., recurring initialisation code for fuses. The include option `-e` prints the lines of the file as comments before processing them; on a non-zero verbosity level the line numbers are printed, too.

sig Display the device signature bytes.

part Display the current part settings and parameters. Includes chip specific information including all memory types supported by the device, read/write timing, etc.

verbose [*level*]

Change (when *level* is provided), or display the verbosity level. The initial verbosity level is controlled by the number of `-v` options given on the command line.

quell [*level*]
 Change (when *level* is provided), or display the quell level. 1 is used to suppress progress reports. 2 or higher yields progressively quieter operations. The initial quell level is controlled by the number of `-q` options given on the command line.

?
 ?

help Give a short on-line summary of the available commands.

quit Leave terminal mode and thus AVRDUDE.

q Can be used as an alias for `quit`.

!line Run the shell *line* in a subshell, e.g., `!ls *.hex`. Subshell commands take the rest of the line as their command. For security reasons, they must be enabled explicitly by putting `allow_subshells = yes;` into your `${HOME}/.config/avrdude/avrdude.rc` or `${HOME}/.avrduderc` file.

comment Place comments onto the terminal line (useful for scripts).

In addition, the following commands are supported on some programmers:

pgerase *memory addr*
 Erase one page of the memory specified.

send *b1 b2 b3 b4*
 Send raw instruction codes to the AVR device. If you need access to a feature of an AVR part that is not directly supported by AVRDUDE, this command allows you to use it, even though AVRDUDE does not implement the command. When using direct SPI mode, up to 3 bytes can be omitted.

spi Enter direct SPI mode. The *pgmled* pin acts as chip select. *Only supported on parallel bitbang programmers, and partially by USBtiny.* Chip Select must be externally held low for direct SPI when using USBtinyISP, and send must be a multiple of four bytes.

pgm Return to programming mode (from direct SPI mode).

vtarg *voltage*
 Set the target's supply voltage to *voltage* Volts.

varef [*channel*] *voltage*
 Set the adjustable voltage source to *voltage* Volts. This voltage is normally used to drive the target's *Aref* input on the STK500 and STK600. The STK600 offers two reference voltages, which can be selected by the optional parameter *channel* (either 0 or 1).

fosc *freq*[*M|k*]
 Set the programming oscillator to *freq* Hz. An optional trailing letter *M* multiplies by 1E6, a trailing letter *k* by 1E3.

fosc off Turn the programming oscillator off.

sck *period*
 Set the SCK clock period to *period* microseconds. Note that some official Microchip programmers store the bitclock setting and will continue to use it until a different value is provided. See `-B bitclock` for more information.

`parms` Display programmer specific parameters.

Program the fuse bits of an ATmega328P with a fuse calculator

- Enable full-swing high speed external crystal with long startup time
- Remove default clock division by 8
- Make reset jump to boot loader
- Set the size of the bootloader to 512 bytes (256 words)
- Enable brown-out detection at 2.7 V

First display the factory defaults, then consult an external fuse calculator, select the ATmega328P part, find above settings, note the ensuing new values for the three fuses and reprogram:

```
$ avrdude -c usbasp -p atmega328p -t

avrdude: AVR device initialized and ready to accept instructions
avrdude: device signature = 0x1e950f (probably m328p)

avrdude> dump efuse
Reading | ##### | 100% 0.00 s
0000 ff |. |

avrdude> dump hfuse
Reading | ##### | 100% 0.00 s
0000 d9 |. |

avrdude> dump lfuse
Reading | ##### | 100% 0.00 s
0000 62 |b |

avrdude> #
avrdude> # Consult external fuse calculator
avrdude> #
avrdude> #

avrdude> write efuse 0xfd
Writing | ##### | 100% 0.01 s

avrdude> write hfuse 0xde
Writing | ##### | 100% 0.01 s

avrdude> write lfuse 0xf7
Writing | ##### | 100% 0.01 s

avrdude> quit

avrdude done. Thank you.
```

Program the fuse bits of an ATmega328P with the config command

```
$ avrdude -qq -c usbasp -p atmega328p -t

avrdude> # Show all configurations
avrdude> config
config sut_cksel=intrcosc_8mhz_6ck_14ck_65ms # 34
config ckout=co_disabled # 1
config ckdiv8=by_8 # 0
config bootrst=application # 1
config bootasz=bs_2048w # 0
config eesave=ee_erased # 1
config wdton=wdt_programmable # 1
config spien=isp_enabled # 0
config dwen=dw_off # 1
config rstdisbl=external_reset # 1
config bodlevel=bod_disabled # 7
config lb=no_lock # 3
config blb0=no_lock_in_app # 3
config blb1=no_lock_in_boot # 3

avrdude> # Show possible values for full-swing external crystal
avrdude> config sut_cksel=extfs
avrdude warning: (config) ambiguous; known sut_cksel extfs symbols are:
- sut_cksel=extfsxtal_258ck_14ck_4ms1 # 6
- sut_cksel=extfsxtal_1kck_14ck_65ms # 7
- sut_cksel=extfsxtal_258ck_14ck_65ms # 22
- sut_cksel=extfsxtal_16kck_14ck_0ms # 23
- sut_cksel=extfsxtal_1kck_14ck_0ms # 38
- sut_cksel=extfsxtal_16kck_14ck_4ms1 # 39
- sut_cksel=extfsxtal_1kck_14ck_4ms1 # 54
- sut_cksel=extfsxtal_16kck_14ck_65ms # 55

avrdude> # Set the one with appropriate startup times
avrdude> c su=55

avrdude> # Unprogram clock division by 8, make reset jump to boot loader
avrdude> c ckdiv8=1
avrdude> c bootrst=boot
avrdude> c bootasz=bs_256w

avrdude> # Query which bod levels exist; set brown-out at 2.7 V
avrdude> c bodlevel=
# conf bodlevel=bod_4v3 # 4
# conf bodlevel=bod_2v7 # 5
# conf bodlevel=bod_1v8 # 6
config bodlevel=bod_disabled # 7 (factory)
avrdude> c bod=*2v7

avrdude> quit
```

The following example demonstrates **negative address and length bytes**, and the **fill form of the write command using an ellipsis ...** where the last data item provided is used to fill up the indicated memory range.

```
$ avrdude -c usbasp -p atmega328p -t

avrdude: AVR device initialized and ready to accept instructions
avrdude: device signature = 0x1e950f (probably m328p)

avrdude> dump flash -64 -33
Reading | ##### | 100% 0.02 s
7fc0 ff ff ff ff ff ff ff ff ff ff ff ff ff ff ff ff |.....|
7fd0 ff ff ff ff ff ff ff ff ff ff ff ff ff ff ff ff |.....|

avrdude> dump flash -32 -1
Reading | ##### | 100% 0.00 s
7fe0 ff ff ff ff ff ff ff ff ff ff ff ff ff ff ff ff |.....|
7ff0 ff ff ff ff ff ff ff ff ff ff ff ff ff ff ff ff |.....|

avrdude> write flash -64 1234567890 'A' 'V' 'R' 2.718282 0xaa 0xbb 0xcc "Hello World!"
Caching | ##### | 100% 0.00 s

avrdude> write flash -32 -1 0x01 0b00000010 0b11 0x04 0x05 ...
Caching | ##### | 100% 0.00 s

avrdude> read flash -64 -33
Reading | ##### | 100% 0.00 s
7fc0 d2 02 96 49 41 56 52 55 f8 2d 40 aa bb cc 48 65 |...IAVRU.-@...He|
7fd0 6c 6c 6f 20 57 6f 72 6c 64 21 00 ff ff ff ff ff |llo World!.....|

avrdude> read flash -32 -1
Reading | ##### | 100% 0.00 s
7fe0 01 02 03 04 05 05 05 05 05 05 05 05 05 05 05 |.....|
7ff0 05 05 05 05 05 05 05 05 05 05 05 05 05 05 05 |.....|

avrdude> flush
avrdude: synching cache to device ...
Writing | ##### | 100% 0.05 s

avrdude> quit

avrdude done. Thank you.
```

Mixing terminal commands and -U memory operations: the example below burns a boot-loader, uses a terminal line to write application data to flash, loads the application, configures the brownout detection level to 2.7 V and, finally, stores the full flash as new hex file. Note the use of different quotation marks in bash to pass the terminal command lines as single entity to AVRDUDE.

```
$ avrdude -qc dryrun -p m328p \  
    -U urboot_m328p_1s_autobaud_uart0_pr_ee_ce.hex \  
    -T 'write flash 0x7D00 0xc0cac01a 0xcafe "secret Coca Cola recipe"' \  
    -U flash:w:cola-vending-machine.hex \  
    -T "config -v bod=*2v7" \  
    -U flash:r:app+data.hex:I  
  
avrdude: AVR device initialized and ready to accept instructions  
avrdude: device signature = 0x1e950f (probably m328p)  
avrdude: Note: flash memory has been specified, an erase cycle will be performed.  
    To disable this feature, specify the -D option.  
avrdude: erasing chip  
  
avrdude: processing -U flash:w:urboot_m328p_1s_autobaud_uart0_pr_ee_ce.hex:i  
avrdude: reading input file urboot_m328p_1s_autobaud_uart0_pr_ee_ce.hex for flash  
    with 368 bytes in 2 sections within [0x7e80, 0x7fff]  
    using 3 pages and 16 pad bytes  
avrdude: writing 368 bytes flash ...  
avrdude: 368 bytes of flash written  
avrdude: verifying flash memory against urboot_m328p_1s_autobaud_uart0_pr_ee_ce.hex  
avrdude: 368 bytes of flash verified  
  
avrdude: processing -T write flash 0x7D00 0xc0cac01a 0xcafe "secret Coca Cola recipe"  
avrdude: synching cache to device ... done  
  
avrdude: processing -U flash:w:cola-vending-machine.hex:i  
avrdude: reading input file cola-vending-machine.hex for flash  
    with 736 bytes in 1 section within [0, 0x2df]  
    using 6 pages and 32 pad bytes  
avrdude: writing 736 bytes flash ...  
avrdude: 736 bytes of flash written  
avrdude: verifying flash memory against cola-vending-machine.hex  
avrdude: 736 bytes of flash verified  
  
avrdude: processing -T config -v bod=*2v7  
config bodlevel=bod_2v7 # 5  
  
avrdude: processing -U flash:r:app+data.hex:I  
avrdude: reading flash memory ...  
avrdude: writing output file app+data.hex  
  
avrdude done. Thank you.
```

4 Configuration File

AVRDUDE reads a configuration file upon startup which describes all of the parts and programmers that it knows about. The advantage of this is that if you have a chip that is not currently supported by AVRDUDE, you can add it to the configuration file without waiting for a new release of AVRDUDE. Likewise, if you have a parallel port programmer that is not supported, chances are that you can copy an existing programmer definition and, with only a few changes, make your programmer work.

AVRDUDE first looks for a system wide configuration file in a platform dependent location. On Unix, this is usually `/usr/local/etc/avrdude.conf`, whilst on Windows it is usually in the same location as the executable file. The full name of this file can be specified using the `-C` command line option. After parsing the system wide configuration file, AVRDUDE looks for a per-user configuration file to augment or override the system wide defaults. On Unix, the per-user file is `${XDG_CONFIG_HOME}/avrdude/avrdude.rc`, whereas if `${XDG_CONFIG_HOME}` is either not set or empty, `${HOME}/.config/` is used instead. If that does not exist `.avrduderc` within the user's home directory is used. On Windows, this file is the `avrdude.rc` file located in the same directory as the executable.

4.1 AVRDUDE Defaults

```
default_parallel = "default-parallel-device";
```

Assign the default parallel port device. Can be overridden using the `-P` option.

```
default_serial = "default-serial-device";
```

Assign the default serial port device. Can be overridden using the `-P` option.

```
default_linuxgpio = "default-linuxgpio-device";
```

Assign the default gpiochip for linuxgpio's libgpiod mode, e.g. "gpiochip0". Ignored for linuxgpio's sysfs mode. Can be overridden using the `-P` option.

```
default_programmer = "default-programmer-id";
```

Assign the default programmer id. Can be overridden using the `-c` option.

```
default_bitclock = "default-bitclock";
```

Assign the default bitclock value. Can be overridden using the `-B` option.

```
allow_subshells = no;
```

Whether or not AVRDUDE's interactive terminal is allowed to use subshell `!` commands. This defaults to no for security reasons, e.g., in the rare case `avrdude -t` is set up with attached hardware to provide a web service, remote ssh or a login on a PC instead of a shell, say, for demo or training purposes. In almost all other cases this can be overridden in the personal `avrdude.rc` or `.avrduderc` configuration file with yes.

4.2 Programmer Definitions

The format of the programmer definition is as follows:

```
programmer
  parent <id>                                # optional parent
  id      = <id1> [, <id2> ... ] ;          # <idN> are quoted strings
```



```

desc      = <description> ;           # quoted string
type      = <type>;                   # programmer type, quoted string
                                           # supported types can be listed by "-c ?type"

prog_modes = PM_<i/f> { | PM_<i/f> }   # interfaces, e.g., PM_SPM|PM_PDI
connection_type = parallel | serial | usb | spi
baudrate = <num> ;                     # baudrate for avr910-programmer
vcc       = <pin1> [, <pin2> ... ] ;    # pin number(s)
buff      = <pin1> [, <pin2> ... ] ;    # pin number(s)
reset     = <pin> ;                     # pin number
sck       = <pin> ;                     # pin number
sdo       = <pin> ;                     # pin number
sdi       = <pin> ;                     # pin number
errled    = <pin> ;                     # pin number
rdyled    = <pin> ;                     # pin number
pgmled    = <pin> ;                     # pin number
vfyled    = <pin> ;                     # pin number
usbvid    = <hexnum> ;                  # USB VID (Vendor ID)
usbpid    = <hexnum> [, <hexnum> ...] ; # USB PID (Product ID)
usbdev    = <interface> ;               # USB interface or other device info
usbvendor = <vendorname> ;              # USB Vendor Name
usbproduct = <productname> ;            # USB Product Name
usbsn     = <serialno> ;                 # USB Serial Number
hvspdi_support = <num> [, <num>, ... ] ; # UPDI HV Variants Support
;

```

If a parent is specified, all settings of it (except its ids) are used for the new programmer. These values can be changed by new setting them for the new programmer.

Known programming modes are

- PM_SPM: Bootloaders, self-programming with SPM opcodes or NVM Controllers
- PM_TPI: Tiny Programming Interface (t4, t5, t9, t10, t20, t40, t102, t104)
- PM_ISP: SPI programming for In-System Programming (almost all classic parts)
- PM_PDI: Program and Debug Interface (xmega parts)
- PM_UPDI: Unified Program and Debug Interface
- PM_HVSP: High Voltage Serial Programming (some classic parts)
- PM_HVPP: High Voltage Parallel Programming (most non-HVSP classic parts)
- PM_debugWIRE: Simpler alternative to JTAG (a subset of HVPP/HVSP parts)
- PM_JTAG: Joint Test Action Group standard (some classic parts)
- PM_JTAGmkI: Subset of PM_JTAG, older parts, Atmel ICE mkI
- PM_XMEGAJTAG: JTAG, some XMEGA parts
- PM_AVR32JTAG: JTAG for 32-bit AVRs
- PM_aWire: AVR32 parts

To invert a bit in the pin definitions, use = ~ <num>. To invert a pin list (all pins get inverted) use ~ (<num1> [, <num2> ...]).

Not all programmer types can handle a list of USB PIDs.

The following programmer types are currently implemented:

arduino	Arduino programmer
avr910	Serial programmers using protocol described in application note AVR910

avrftdi	Interface to the MPSSE Engine of FTDI Chips using libftdi.
buspirate	Using the Bus Pirate's SPI interface for programming
buspirate_bb	Using the Bus Pirate's bitbang interface for programming
butterfly	Atmel Butterfly evaluation board; Atmel AppNotes AVR109, AVR911
butterfly_mk	Mikrokopter.de Butterfly
ch341a	Driver for "ch341a"-type programmers
dryrun	Dryrun programmer for testing avrdude
dragon_dw	Atmel AVR Dragon in debugWire mode
dragon_hvsp	Atmel AVR Dragon in HVSP mode
dragon_isp	Atmel AVR Dragon in ISP mode
dragon_jtag	Atmel AVR Dragon in JTAG mode
dragon_pdi	Atmel AVR Dragon in PDI mode
dragon_pp	Atmel AVR Dragon in PP mode
flip1	FLIP USB DFU protocol version 1 (doc7618)
flip2	FLIP USB DFU protocol version 2 (AVR4023)
ftdi_syncbb	FT245R/FT232R Synchronous BitBangMode Programmer
jtagmki	Atmel JTAG ICE mkI
jtagmkii	Atmel JTAG ICE mkII
jtagmkii_avr32	Atmel JTAG ICE mkII in AVR32 mode
jtagmkii_dw	Atmel JTAG ICE mkII in debugWire mode
jtagmkii_isp	Atmel JTAG ICE mkII in ISP mode
jtagmkii_pdi	Atmel JTAG ICE mkII in PDI mode
jtagmkii_updi	Atmel JTAG ICE mkII in UPDI mode
jtagice3	Atmel JTAGICE3
jtagice3_pdi	Atmel JTAGICE3 in PDI mode
jtagice3_updi	Atmel JTAGICE3 in UPDI mode
jtagice3_dw	Atmel JTAGICE3 in debugWire mode
jtagice3_isp	Atmel JTAGICE3 in ISP mode
jtagice3_tpi	Atmel JTAGICE3 in TPI mode
linuxgpio	GPIO bitbanging using the Linux libgpiod or sysfs interface (not available)
linuxspi	SPI using Linux spidev driver (not available)
micronucleus	Micronucleus Bootloader
par	Parallel port bitbanging
pickit2	Microchip's PICKit2 Programmer
serbb	Serial port bitbanging
serialupdi	Driver for SerialUPDI programmers
stk500	Atmel STK500 Version 1.x firmware
stk500generic	Atmel STK500, autodetect firmware version
stk500v2	Atmel STK500 Version 2.x firmware

stk500hvsp	Atmel STK500 V2 in high-voltage serial programming mode
stk500pp	Atmel STK500 V2 in parallel programming mode
stk600	Atmel STK600
stk600hvsp	Atmel STK600 in high-voltage serial programming mode
stk600pp	Atmel STK600 in parallel programming mode
teensy	Teensy Bootloader
urclock	Urclock programmer for urboot bootloaders (arduino compatible)
usbasp	USBasp programmer, see http://www.fischl.de/usbasp/
usbtiny	Driver for "usbtiny"-type programmers
wiring	http://wiring.org.co/ , Basically STK500v2 protocol, with some glue to trigger the bootloader.
xbee	XBee Series 2 Over-The-Air (XBeeBoot)

4.3 Part Definitions

```

part
    desc                = <description> ;                # quoted string, the long part name, eg, "ATmega328p"
    id                  = <id> ;                          # quoted string, normally an abbreviated part name
    variants            = <str1> [, <str2> ...];          # quoted strings, each starts so "<alt-name>: ..."
    family_id           = <id> ;                          # quoted string, e.g., "megaAVR" or "tinyAVR"
    prog_modes           = PM_<i/f> { | PM_<i/f>}          # interfaces, e.g., PM_SPM|PM_ISP|PM_HVPP|PM_debugWIRE
    mcuid                = <num>;                        # unique id in 0..2039 for 8-bit AVR
    n_interrupts        = <num>;                        # number of interrupts, used for vector bootloaders
    n_page_erase        = <num>;                        # if set, number of pages erased during SPM erase
    n_boot_sections     = <num>;                        # Number of boot sections
    boot_section_size   = <num>;                        # Size of (smallest) boot section, if any
    hvupdi_variant      = <num> ;                       # numeric -1 (n/a) or 0..2
    devicecode           = <num> ;                       # deprecated, use stk500_devcode
    stk500_devcode       = <num> ;                       # numeric
    avr910_devcode      = <num> ;                       # numeric
    has_jtag             = <yes/no> ;                    # part has JTAG i/f (deprecated, use prog_modes)
    has_debugwire        = <yes/no> ;                    # part has debugWire i/f (deprecated, use prog_modes)
    has_pdi              = <yes/no> ;                    # part has PDI i/f (deprecated, use prog_modes)
    has_updi             = <yes/no> ;                    # part has UPDI i/f (deprecated, use prog_modes)
    has_tpi              = <yes/no> ;                    # part has TPI i/f (deprecated, use prog_modes)
    is_avr32             = <yes/no> ;                    # AVR32 part (deprecated, use prog_modes)
    is_at90s1200         = <yes/no> ;                    # AT90S1200 part
    signature            = <num> <num> <num> ;          # signature bytes
    usbpid               = <num> ;                       # DFU USB PID
    chip_erase_delay     = <num> ;                       # microseconds
    reset                = dedicated | io ;
    retry_pulse         = reset | sck ;
    # STK500 parameters (parallel programming IO lines)
    pagel                = <num> ;                       # page load pin name in hex, e.g., 0xD7
    bs2                  = <num> ;                       # byte select 2 pin name in hex, e.g., 0xA0
    serial               = <yes/no> ;                    # can use serial downloading
    parallel             = <yes/no/pseudo> ;             # can use parallel programming
    # STK500v2 parameters, to be taken from Atmel's ATDF files
    timeout              = <num> ;
    stabdelay            = <num> ;

```

```

cmdexedelay      = <num> ;
synchloops       = <num> ;
bytedelay        = <num> ;
pollvalue        = <num> ;
pollindex        = <num> ;
predelay         = <num> ;
postdelay        = <num> ;
pollmethod       = <num> ;
hvspcmdexedelay = <num> ;
# STK500v2 HV programming parameters, from ATDFs
pp_controlstack = <num>, <num>, ... ; # PP only
hvsp_controlstack = <num>, <num>, ... ; # HVSP only
flash_instr     = <num>, <num>, <num> ;
eeprom_instr    = <num>, <num>, ... ;
hventerstabeldelay = <num> ;
progmodedelay   = <num> ; # PP only
latchcycles     = <num> ;
togglevtg       = <num> ;
poweroffdelay   = <num> ;
resetdelayms    = <num> ;
resetdelayus    = <num> ;
hvleavestabeldelay = <num> ;
resetdelay      = <num> ;
synchcycles     = <num> ; # HVSP only
chiperasepulsewidth = <num> ; # PP only
chiperasepolltimeout = <num> ;
chiperasetime   = <num> ; # HVSP only
programfusepulsewidth = <num> ; # PP only
programfusepolltimeout = <num> ;
programlockpulsewidth = <num> ; # PP only
programlockpolltimeout = <num> ;
# debugWIRE and/or JTAG ICE mkII parameters, also from ATDF files
allowfullpagebitstream = <yes/no> ;
enablepageprogramming = <yes/no> ;
idr              = <num> ; # IO addr of IDR (OCD) reg
rampz            = <num> ; # IO addr of RAMPZ reg
spmcr           = <num> ; # mem addr of SPMC[S]R reg
eecr            = <num> ; # mem addr of EECR reg
eind            = <num> ; # mem addr of EIND reg
mcu_base        = <num> ; # MCU control block in ATxmega devices
nvm_base        = <num> ; # NVM controller in ATxmega devices
ocd_base        = <num> ; # OCD module in AVR8X/UPDI devices
ocdrev          = <num> ; # JTAGICE3 parameter from ATDF files
pgm_enable      = <instruction format> ;
chip_erase      = <instruction format> ;
# parameters for bootloaders
autobaud_sync   = <num> ; # autobaud detection byte, default 0x30

memory <memory>
  paged          = <yes/no> ; # yes/no (flash only, do not use for EEPROM)
  offset         = <num> ; # memory offset
  size           = <num> ; # bytes
  page_size      = <num> ; # bytes
  num_pages      = <num> ; # numeric
  initval        = <num> ; # factory setting of fuses and lockbits
  bitmask        = <num> ; # bits used (only in fuses and lockbits)
  n_word_writes  = <num> ; # TPI only: if set, number of words to write
  min_write_delay = <num> ; # micro-seconds

```

```

max_write_delay = <num> ;           # micro-seconds
readback        = <num> <num> ;     # pair of byte values
readback_p1     = <num> ;           # byte value (first component)
readback_p2     = <num> ;           # byte value (second component)
pwoff_after_write = <yes/no> ;      # yes/no
mode            = <num> ;           # STK500 v2 file parameter from ATDF files
delay          = <num> ;           # "
blocksize      = <num> ;           # "
readsize       = <num> ;           # "
read           = <instruction format> ;
write          = <instruction format> ;
read_lo       = <instruction format> ;
read_hi       = <instruction format> ;
write_lo      = <instruction format> ;
write_hi      = <instruction format> ;
loadpage_lo   = <instruction format> ;
loadpage_hi   = <instruction format> ;
writepage     = <instruction format> ;
;
;

```

If any of the above parameters are not specified, the default value of 0 is used for numerics (except for `mcuid`, `hvupdi_variant`, `ocdrev`, `initval` and `bitmask`, all of which default to -1, and for `autobaud_sync` which defaults to 0x30) or the empty string "" for string values. If a required parameter is left empty, AVRDUDE will complain. Almost all occurrences of numbers (with the exception of pin numbers and where they are separated by space, e.g., in signature and `readback`) can also be given as simple expressions involving arithmetic and bitwise operators.

4.3.1 Parent Part

Parts can also inherit parameters from previously defined parts using the following syntax. In this case specified integer and string values override parameter values from the parent part. New memory definitions are added to the definitions inherited from the parent. If, however, a new memory definition refers to an existing one of the same name for that part then, from v7.1, the existing memory definition is extended, and components overwritten with new values. Assigning NULL removes an inherited SPI instruction format, memory definition, control stack, eeprom or flash instruction, e.g., as in `memory "efuse" = NULL;`. The `variants` parameter is never inherited as it almost always would be a mistake to do so: `variants` defines a string list detailing variant names of the part followed by an optional colon, the package code and some absolute maximum ratings.

Example format for part inheritance:

```

part parent <id>                    # String identifying parent
  id                                = <id> ;                          # Id string for new part
  <any set of other parameters from the list above>
;

```

4.3.2 Instruction Format

Instruction formats are specified as a comma separated list of string values containing information (bit specifiers) about each of the 32 bits of the instruction. Bit specifiers may be one of the following formats:

- 1 The bit is always set on input as well as output

0	The bit is always clear on input as well as output
x	The bit is ignored on input and output
a	The bit is an address bit, the bit-number matches this bit specifier's position within the current instruction byte
aN	The bit is the Nth address bit, bit-number = N, i.e., a12 is address bit 12 on input, a0 is address bit 0.
i	The bit is an input data bit; as with a bits an input data bit can optionally be followed by a bit number, here between 0 and 7, if the bit needs to be moved to a different position in the SPI write command byte than it appears in memory.
o	The bit is an output data bit; as with i bits an output data bit can optionally be followed by a bit number; this is useful in case the part's SPI read command places a particular bit into a different position than the write command put it, e.g., ATtiny22L or AT90S8535 lock bits.

Each instruction must be composed of 32 bit specifiers. The instruction specification closely follows the instruction data provided in Atmel's data sheets for their parts. For example, the EEPROM read and write instruction for an AT90S2313 AVR part could be encoded as:

```
read = "1 0 1 0 0 0 0 0 x x x x x x x x",
      "x a6 a5 a4 a3 a2 a1 a0 o o o o o o o o";

write = "1 1 0 0 0 0 0 0 x x x x x x x x",
       "x a6 a5 a4 a3 a2 a1 a0 i i i i i i i i";
```

As the address bit numbers in the SPI opcodes are highly systematic, they don't really need to be specified. A compact version of the format specification neither uses bit-numbers for address lines nor spaces. If such a string is longer than 7 characters, then the characters 0, 1, x, a, i and o will be recognised as the corresponding bit, whilst any of the characters ., -, _ or / can act as arbitrary visual separators, which are ignored. Examples:

```
loadpage_lo = "0100.0000--000x.xxxx--xxaa.aaaa--iiii.iiii";

loadpage_lo = "0100.0000", "000x.xxxx", "xxaa.aaaa", "iiii.iiii";
```

4.4 Other Notes

- The `devicecode` parameter is the device code used by the STK500 and is obtained from the software section (`avr061.zip`) of Atmel's AVR061 application note available from http://www.atmel.com/dyn/resources/prod_documents/doc2525.pdf.
- Not all memory types will implement all instructions.
- AVR Fuse bits and Lock bits are implemented as a type of memory.
- Example memory types are: `flash`, `eeprom`, `fuse`, `lfuse` (low fuse), `hfuse` (high fuse), `efuse` (extended fuse), `signature`, `calibration`, `lock`.
- The memory type specified on the AVRDUDE command line must match one of the memory types defined for the specified chip.

- The `pwroff_after_write` flag causes AVRDUDE to attempt to power the device off and back on after an unsuccessful write to the affected memory area if VCC programmer pins are defined. If VCC pins are not defined for the programmer, a message indicating that the device needs a power-cycle is printed out. This flag was added to work around a problem with the at90s4433/2333's; see the at90s4433 errata at:

<https://www.microchip.com/content/dam/mchp/documents/OTH/ProductDocuments/DataSheets/doc1042.pdf>

- The boot loader from application note AVR109 (and thus also the AVR Butterfly) does not support writing of fuse bits. Writing lock bits is supported, but is restricted to the boot lock bits (BLBxx). These are restrictions imposed by the underlying SPM instruction that is used to program the device from inside the boot loader. Note that programming the boot lock bits can result in a “shoot-into-your-foot” scenario as the only way to unprogram these bits is a chip erase, which will also erase the boot loader code.

The boot loader implements the “chip erase” function by erasing the flash pages of the application section.

Reading fuse and lock bits is fully supported.

5 Programmer Specific Information

5.1 Atmel STK600

The following devices are supported by the respective STK600 routing and socket card:

Routing card	Socket card	Devices
STK600-RC008T-2	STK600-ATTINY10 STK600-DIP	ATtiny4 ATtiny5 ATtiny9 ATtiny10 ATtiny11 ATtiny12 ATtiny13 ATtiny13A ATtiny25 ATtiny45 ATtiny85
STK600-RC008T-7	STK600-DIP	ATtiny15
STK600-RC014T-42	STK600-SOIC	ATtiny20
STK600-RC020T-1	STK600-DIP STK600-TinyX3U	ATtiny2313 ATtiny2313A ATtiny4313 ATtiny43U
STK600-RC014T-12	STK600-DIP	ATtiny24 ATtiny44 ATtiny84 ATtiny24A ATtiny44A
STK600-RC020T-8	STK600-DIP	ATtiny26 ATtiny261 ATtiny261A AT- tiny461 ATtiny861 ATtiny861A
STK600-RC020T-43	STK600-SOIC	ATtiny261 ATtiny261A ATtiny461 AT- tiny461A ATtiny861 ATtiny861A
STK600-RC020T-23	STK600-SOIC	ATtiny87 ATtiny167
STK600-RC028T-3	STK600-DIP	ATtiny28
STK600-RC028M-6	STK600-DIP	ATtiny48 ATtiny88 ATmega8 ATmega8A ATmega48 ATmega88 ATmega168 AT- mega48P ATmega48PA ATmega88P AT- mega88PA ATmega168P ATmega168PA ATmega328P
	QT600-ATTINY88- QT8	ATtiny88
STK600-RC040M-4	STK600-DIP	ATmega8515 ATmega162
STK600-RC044M-30	STK600-TQFP44	ATmega8515 ATmega162
STK600-RC040M-5	STK600-DIP	ATmega8535 ATmega16 ATmega16A AT- mega32 ATmega32A ATmega164P AT- mega164PA ATmega324P ATmega324PA ATmega644 ATmega644P ATmega644PA ATmega1284P
STK600-RC044M-31	STK600-TQFP44	ATmega8535 ATmega16 ATmega16A AT- mega32 ATmega32A ATmega164P AT- mega164PA ATmega324P ATmega324PA ATmega644 ATmega644P ATmega644PA ATmega1284P
	QT600-ATMEGA324- QM64	ATmega324PA

STK600-RC032M-29	STK600-TQFP32	ATmega8 ATmega8A ATmega48 ATmega88 ATmega168 ATmega48P ATmega48PA ATmega88P ATmega88PA ATmega168P ATmega168PA ATmega328P
STK600-RC064M-9	STK600-TQFP64	ATmega64 ATmega64A ATmega128 ATmega128A ATmega1281 ATmega2561 AT90CAN32 AT90CAN64 AT90CAN128
STK600-RC064M-10	STK600-TQFP64	ATmega165 ATmega165P ATmega169 AT- mega169P ATmega169PA ATmega325 AT- mega325P ATmega329 ATmega329P AT- mega645 ATmega649 ATmega649P
STK600-RC100M-11	STK600-TQFP100	ATmega640 ATmega1280 ATmega2560
	STK600-ATMEGA2560	ATmega2560
STK600-RC100M-18	STK600-TQFP100	ATmega3250 ATmega3250P ATmega3290 ATmega3290P ATmega6450 ATmega6490
STK600-RC032U-20	STK600-TQFP32	AT90USB82 AT90USB162 ATmega8U2 ATmega16U2 ATmega32U2
STK600-RC044U-25	STK600-TQFP44	ATmega16U4 ATmega32U4
STK600-RC064U-17	STK600-TQFP64	ATmega32U6 AT90USB646 AT90USB1286 AT90USB647 AT90USB1287
STK600-RCPWM-22	STK600-TQFP32	ATmega32C1 ATmega64C1 ATmega16M1 ATmega32M1 ATmega64M1
STK600-RCPWM-19	STK600-SOIC	AT90PWM2 AT90PWM3 AT90PWM2B AT90PWM3B AT90PWM216 AT90PWM316
STK600-RCPWM-26	STK600-SOIC	AT90PWM81
STK600-RC044M-24	STK600-TSSOP44	ATmega16HVB ATmega32HVB
	STK600-HVE2	ATmega64HVE
	STK600-ATMEGA128RFA1	ATmega128RFA1
STK600-RC100X-13	STK600-TQFP100	ATxmega64A1 ATxmega128A1 ATxmega128A1_revD ATxmega128A1U
	STK600-ATXMEGA1281A1	ATxmega128A1
	QT600-ATXMEGA128A1-ATxmega128A1	ATxmega128A1
	QT16	ATxmega128A1
STK600-RC064X-14	STK600-TQFP64	ATxmega64A3 ATxmega128A3 ATxmega256A3 ATxmega64D3 ATxmega128D3 ATxmega192D3 ATxmega256D3
STK600-RC064X-14	STK600-MLF64	ATxmega256A3B
STK600-RC044X-15	STK600-TQFP44	ATxmega32A4 ATxmega16A4 ATxmega16D4 ATxmega32D4
	STK600-ATXMEGAT0	ATxmega32T0
	STK600-uC3-144	AT32UC3A0512 AT32UC3A0256 AT32UC3A0128

STK600-RCUC3A144-33	STK600-TQFP144	AT32UC3A0512 AT32UC3A0128	AT32UC3A0256
STK600-RCuC3A100-28	STK600-TQFP100	AT32UC3A1512 AT32UC3A1128	AT32UC3A1256
STK600-RCuC3B0-21	STK600-TQFP64-2	AT32UC3B0256 AT32UC3B0512 AT32UC3B064	AT32UC3B0512RevC AT32UC3B0128 AT32UC3D1128
STK600-RCuC3B48-27	STK600-TQFP48	AT32UC3B1256	AT32UC3B164
STK600-RCUC3A144-32	STK600-TQFP144	AT32UC3A3512 AT32UC3A3128 AT32UC3A3256S AT32UC3A364S	AT32UC3A3256 AT32UC3A364 AT32UC3A3128S
STK600-RCUC3C0-36	STK600-TQFP144	AT32UC3C0512 AT32UC3C0128	AT32UC3C0256 AT32UC3C064
STK600-RCUC3C1-38	STK600-TQFP100	AT32UC3C1512 AT32UC3C1128	AT32UC3C1256 AT32UC3C164
STK600-RCUC3C2-40	STK600-TQFP64-2	AT32UC3C2512 AT32UC3C2128	AT32UC3C2256 AT32UC3C264
STK600-RCUC3C0-37	STK600-TQFP144	AT32UC3C0512 AT32UC3C0128	AT32UC3C0256 AT32UC3C064
STK600-RCUC3C1-39	STK600-TQFP100	AT32UC3C1512 AT32UC3C1128	AT32UC3C1256 AT32UC3C164
STK600-RCUC3C2-41	STK600-TQFP64-2	AT32UC3C2512 AT32UC3C2128	AT32UC3C2256 AT32UC3C264
STK600-RCUC3L0-34	STK600-TQFP48	AT32UC3L064 AT32UC3L016	AT32UC3L032
	QT600-AT32UC3L-QM64	AT32UC3L064	

Ensure the correct socket and routing card are mounted *before* powering on the STK600. While the STK600 firmware ensures the socket and routing card mounted match each other (using a table stored internally in nonvolatile memory), it cannot handle the case where a wrong routing card is used, e. g. the routing card STK600-RC040M-5 (which is meant for 40-pin DIP AVR's that have an ADC, with the power supply pins in the center of the package) was used but an ATmega8515 inserted (which uses the “industry standard” pinout with Vcc and GND at opposite corners).

Note that for devices that use the routing card STK600-RC008T-2, in order to use ISP mode, the jumper for AREF0 must be removed as it would otherwise block one of the ISP signals. High-voltage serial programming can be used even with that jumper installed.

The ISP system of the STK600 contains a detection against shortcuts and other wiring errors. AVRDUDE initiates a connection check before trying to enter ISP programming mode, and display the result if the target is not found ready to be ISP programmed.

High-voltage programming requires the target voltage to be set to at least 4.5 V in order to work. This can be done using *Terminal Mode*, see Chapter 3 [Terminal Mode Operation], page 40.

5.2 Atmel DFU bootloader using FLIP version 1

Bootloaders using the FLIP protocol version 1 experience some very specific behaviour.

These bootloaders have no option to access memory areas other than Flash and EEPROM.

When the bootloader is started, it enters a *security mode* where the only acceptable access is to query the device configuration parameters (which are used for the signature on AVR devices). The only way to leave this mode is a *chip erase*. As a chip erase is normally implied by the `-U` option when reprogramming the flash, this peculiarity might not be very obvious immediately.

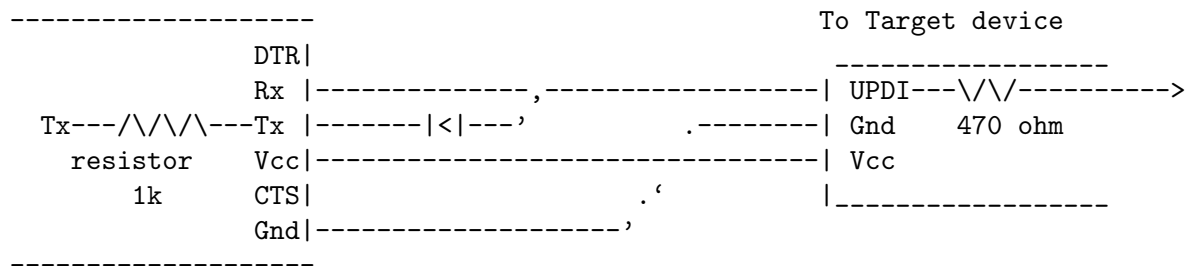
Sometimes, a bootloader with security mode already disabled seems to no longer respond with sensible configuration data, but only `0xFF` for all queries. As these queries are used to obtain the equivalent of a signature, AVRDUDE can only continue in that situation by forcing the signature check to be overridden with the `-F` option.

A *chip erase* might leave the EEPROM unerased, at least on some versions of the bootloader.

5.3 SerialUPDI programmer

SerialUPDI programmer can be used for programming UPDI-only devices using very simple serial connection. You can read more about the details here <https://github.com/SpenceKonde/AVR-Guidance/blob/master/UPDI/jtag2updi.md>

SerialUPDI programmer has been tested using FT232RL USB->UART interface with the following connection layout (copied from Spence Kohde's page linked above):



There are several limitations in current SerialUPDI/AVRDUDE integration, listed below.

At the end of each run there are fuse values being presented to the user. For most of the UPDI-enabled devices these definitions (low fuse, high fuse, extended fuse) have no meaning whatsoever, as they have been simply replaced by array of fuses: `fuse0..9`. Therefore you can simply ignore this particular line of AVRDUDE output.

Currently available devices support only UPDI NVM programming model 0 and 2, but there is also experimental implementation of model 3 - not yet tested.

One of the core AVRDUDE features is verification of the connection by reading device signature prior to any operation, but this operation is not possible on UPDI locked devices. Therefore, to be able to connect to such a device, you have to provide `-F` to override this check.

Please note: using `-F` during write operation to locked device will force chip erase. Use carefully.

Another issue you might notice is slow performance of EEPROM writing using SerialUPDI for AVR Dx devices. This can be addressed by changing *avrdude.conf* section for this device - changing EEPROM page size to 0x20 (instead of default 1), like so:

```
#-----
# AVR128DB28
#-----

part parent      ".avrdx"
  id             = "avr128db28";
  desc           = "AVR128DB28";
  signature      = 0x1E 0x97 0x0E;

  memory "flash"
    size         = 0x20000;
    offset       = 0x800000;
    page_size    = 0x200;
    readsize     = 0x100;
  ;

  memory "eeprom"
    size         = 0x200;
    offset       = 0x1400;
    page_size    = 0x1;
    readsize     = 0x100;
  ;
;
```

USERROW memory has not been defined for new devices except for experimental addition for AVR128DB28. The point of USERROW is to provide ability to write configuration details to already locked device and currently SerialUPDI interface supports this feature, but it hasn't been tested on wide variety of chips. Treat this as something experimental at this point. Please note: on locked devices it's not possible to read back USERROW contents when written, so the automatic verification will most likely fail and to prevent error messages, use `-V`.

Please note that SerialUPDI interface is pretty new and some issues are to be expected. In case you run into them, please make sure to run the intended command with debug output enabled (`-v -v -v`) and provide this verbose output with your bug report. You can also try to perform the same action using *pymcuprog* (<https://github.com/microchip-pic-avr-tools/pymcuprog>) utility with `-v debug` and provide its output too. You will notice that both outputs are pretty similar, and this was implemented like that on purpose - it was supposed to make analysis of UPDI protocol quirks easier.

Appendix A Platform Dependent Information

A.1 Unix

A.1.1 Unix Installation

To build and install from the source tarball on Unix like systems:

```
$ gunzip -c avrdude-7.2.tar.gz | tar xf -
$ cd avrdude-7.2
$ ./configure
$ make
$ su root -c 'make install'
```

The default location of the install is into `/usr/local` so you will need to be sure that `/usr/local/bin` is in your `PATH` environment variable.

If you do not have root access to your system, you can do the following instead:

```
$ gunzip -c avrdude-7.2.tar.gz | tar xf -
$ cd avrdude-7.2
$ ./configure --prefix=$HOME/local
$ make
$ make install
```

A.1.1.1 FreeBSD Installation

AVRDUDE is installed via the FreeBSD Ports Tree as follows:

```
$ su - root
# cd /usr/ports/devel/avrdude
# make install
```

If you wish to install from a pre-built package instead of the source, you can use the following instead:

```
$ su - root
# pkg_add -r avrdude
```

Of course, you must be connected to the Internet for these methods to work, since that is where the source as well as the pre-built package is obtained.

A.1.1.2 Linux Installation

On rpm based Linux systems (such as RedHat, SUSE, Mandrake, etc.), you can build and install the rpm binaries directly from the tarball:

```
$ su - root
# rpmbuild -tb avrdude-7.2.tar.gz
# rpm -Uvh /usr/src/redhat/RPMS/i386/avrdude-7.2-1.i386.rpm
```

Note that the path to the resulting rpm package, differs from system to system. The above example is specific to RedHat.

A.1.2 Unix Configuration Files

When AVRDUDE is build using the default `--prefix` configure option, the default configuration file for a Unix system is located at `/usr/local/etc/avrdude.conf`. This can be overridden by using the `-C` command line option. Additionally, the user's home directory is searched for a file named `.avrduderc`, and if found, is used to augment the system default configuration file.

A.1.2.1 FreeBSD Configuration Files

When AVRDUDE is installed using the FreeBSD ports system, the system configuration file is always `/usr/local/etc/avrdude.conf`.

A.1.2.2 Linux Configuration Files

When AVRDUDE is installed using from an rpm package, the system configuration file will be always be `/etc/avrdude.conf`.

A.1.3 Unix Port Names

The parallel and serial port device file names are system specific. MacOS has no default serial or parallel port names, but available ports can be found under `/dev/cu.*`. The following table lists the default names for a given system.

System	Default Parallel Port	Default Serial Port
FreeBSD	<code>/dev/ppi0</code>	<code>/dev/cuad0</code>
Linux	<code>/dev/parport0</code>	<code>/dev/ttyS0</code>
Solaris	<code>/dev/printers/0</code>	<code>/dev/term/a</code>

On FreeBSD systems, AVRDUDE uses the `ppi(4)` interface for accessing the parallel port and the `sio(4)` driver for serial port access.

On Linux systems, AVRDUDE uses the `ppdev` interface for accessing the parallel port and the `tty` driver for serial port access.

On Solaris systems, AVRDUDE uses the `ecpp(7D)` driver for accessing the parallel port and the `asy(7D)` driver for serial port access.

A.1.4 Unix Documentation

AVRDUDE installs a manual page as well as info, HTML and PDF documentation. The manual page is installed in `/usr/local/man/man1` area, while the HTML and PDF documentation is installed in `/usr/local/share/doc/avrdude` directory. The info manual is installed in `/usr/local/info/avrdude.info`.

Note that these locations can be altered by various configure options such as `--prefix`.

A.2 Windows

A.2.1 Installation

A Windows executable of `avrdude` is included in WinAVR which can be found at <http://sourceforge.net/projects/winavr>. WinAVR is a suite of executable, open source software development tools for the AVR for the Windows platform.

There are two options to build `avrdude` from source under Windows. The first one is to use Cygwin (<http://www.cygwin.com/>).

To build and install from the source tarball for Windows (using Cygwin):

```
$ set PREFIX=<your install directory path>
$ export PREFIX
$ gunzip -c avrdude-7.2.tar.gz | tar xf -
$ cd avrdude-7.2
$ ./configure LDFLAGS="-static" --prefix=$PREFIX --datadir=$PREFIX
--sysconfdir=$PREFIX/bin --enable-versioned-doc=no
$ make
$ make install
```

Note that recent versions of Cygwin (starting with 1.7) removed the MinGW support from the compiler that is needed in order to build a native Win32 API binary that does not require to install the Cygwin library `cygwin1.dll` at run-time. Either try using an older compiler version that still supports MinGW builds, or use MinGW (<http://www.mingw.org/>) directly.

A.2.2 Configuration Files

A.2.2.1 Configuration file names

AVRDUDE on Windows looks for a system configuration file name of `avrdude.conf` and looks for a user override configuration file of `avrdude.rc` in the same directory where `avrdude.exe` is located.

A.2.2.2 How AVRDUDE finds the configuration files.

AVRDUDE on Windows has a different way of searching for the system and user configuration files. Below is the search method for locating the configuration files:

1. Only for the system configuration file: `<directory from which application loaded>/../etc/avrdude.conf`
2. The directory from which the application loaded.
3. The current directory.
4. The Windows system directory. On Windows NT, the name of this directory is `SYSTEM32`.
5. Windows NT: The 16-bit Windows system directory. The name of this directory is `SYSTEM`.
6. The Windows directory.
7. The directories that are listed in the `PATH` environment variable.

A.2.3 Port Names

A.2.3.1 Serial Ports

When you select a serial port (i.e. when using an STK500) use the Windows serial port device names such as: `com1`, `com2`, etc.

A.2.3.2 Parallel Ports

AVRDUDE will accept 3 Windows parallel port names: `lpt1`, `lpt2`, or `lpt3`. Each of these names corresponds to a fixed parallel port base address:

<code>lpt1</code>	<code>0x378</code>
<code>lpt2</code>	<code>0x278</code>
<code>lpt3</code>	<code>0x3BC</code>

On your desktop PC, `lpt1` will be the most common choice. If you are using a laptop, you might have to use `lpt3` instead of `lpt1`. Select the name of the port the corresponds to the base address of the parallel port that you want.

If the parallel port can be accessed through a different address, this address can be specified directly, using the common C language notation (i. e., hexadecimal values are prefixed by `0x`).

A.2.4 Documentation

AVRDUDE installs a manual page as well as info, HTML and PDF documentation. The manual page is installed in `/usr/local/man/man1` area, while the HTML and PDF documentation is installed in `/usr/local/share/doc/avrdude` directory. The info manual is installed in `/usr/local/info/avrdude.info`.

Note that these locations can be altered by various configure options such as `--prefix` and `--datadir`.

Appendix B Troubleshooting

In general, please report any bugs encountered via <https://github.com/avrdudes/avrdude/issues>.

- Problem: I'm using a serial programmer under Windows and get the following error:
`avrdude: serial_open(): can't set attributes for device "com1",`
 Solution: This problem seems to appear with certain versions of Cygwin. Specifying `"/dev/com1"` instead of `"com1"` should help.
- Problem: I'm using Linux and my AVR910 programmer is really slow.
 Solution (short): `setserial port low_latency`
 Solution (long): There are two problems here. First, the system may wait some time before it passes data from the serial port to the program. Under Linux the following command works around this (you may need root privileges for this).
`setserial port low_latency`
 Secondly, the serial interface chip may delay the interrupt for some time. This behaviour can be changed by setting the FIFO-threshold to one. Under Linux this can only be done by changing the kernel source in `drivers/char/serial.c`. Search the file for `UART_FCR_TRIGGER_8` and replace it with `UART_FCR_TRIGGER_1`. Note that overall performance might suffer if there is high throughput on serial lines. Also note that you are modifying the kernel at your own risk.
- Problem: I'm not using Linux and my AVR910 programmer is really slow.
 Solutions: The reasons for this are the same as above. If you know how to work around this on your OS, please let us know.
- Problem: Updating the flash ROM from terminal mode does not work with the JTAG ICES.
 Solution: None at this time. Currently, the JTAG ICE code cannot write to the flash ROM one byte at a time.
- Problem: Page-mode programming the EEPROM (using the `-U` option) does not erase EEPROM cells before writing, and thus cannot overwrite any previous value `!= 0xff`.
 Solution: None. This is an inherent feature of the way JTAG EEPROM programming works, and is documented that way in the Atmel AVR datasheets. In order to successfully program the EEPROM that way, a prior chip erase (with the `EESAVE` fuse unprogrammed) is required. This also applies to the STK500 and STK600 in high-voltage programming mode.
- Problem: How do I turn off the *DWEN* fuse?
 Solution: If the *DWEN* (debugWire enable) fuse is activated, the */RESET* pin is not functional anymore, so normal ISP communication cannot be established. There are two options to deactivate that fuse again: high-voltage programming, or getting the JTAG ICE mkII talk debugWire, and prepare the target AVR to accept normal ISP communication again.

The first option requires a programmer that is capable of high-voltage programming (either serial or parallel, depending on the AVR device), for example the STK500. In high-voltage programming mode, the */RESET* pin is activated initially using a

12 V pulse (thus the name *high voltage*), so the target AVR can subsequently be reprogrammed, and the *DWEN* fuse can be cleared. Typically, this operation cannot be performed while the AVR is located in the target circuit though.

The second option requires a JTAG ICE mkII that can talk the debugWire protocol. The ICE needs to be connected to the target using the JTAG-to-ISP adapter, so the JTAG ICE mkII can be used as a debugWire initiator as well as an ISP programmer. AVRDUDE will then be activated using the *jtag2isp* programmer type. The initial ISP communication attempt will fail, but AVRDUDE then tries to initiate a debugWire reset. When successful, this will leave the target AVR in a state where it can accept standard ISP communication. The ICE is then signed off (which will make it signing off from the USB as well), so AVRDUDE has to be called again afterwards. This time, standard ISP communication can work, so the *DWEN* fuse can be cleared.

The pin mapping for the JTAG-to-ISP adapter is:

JTAG pin	ISP pin
1	3
2	6
3	1
4	2
6	5
9	4

- Problem: Multiple USBasp or USBtinyISP programmers connected simultaneously are not found.

Solution: The USBtinyISP code supports distinguishing multiple programmers based on their bus:device connection tuple that describes their place in the USB hierarchy on a specific host. This tuple can be added to the *-P usb* option, similar to adding a serial number on other USB-based programmers.

The actual naming convention for the bus and device names is operating-system dependent; AVRDUDE will print out what it found on the bus when running it with (at least) one *-v* option. By specifying a string that cannot match any existing device (for example, *-P usb:xxx*), the scan will list all possible candidate devices found on the bus.

Examples:

```
avrdude -c usbtiny -p atmega8 -P usb:003:025 (Linux)
avrdude -c usbtiny -p atmega8 -P usb:/dev/usb:/dev/ugen1.3 (FreeBSD 8+)
avrdude -c usbtiny -p atmega8 \
-P usb:bus-0:\\.\libusb0-0001--0x1781-0x0c9f (Windows)
```

- Problem: I cannot do . . . when the target is in debugWire mode.

Solution: debugWire mode imposes several limitations.

The debugWire protocol is Atmel's proprietary one-wire (plus ground) protocol to allow an in-circuit emulation of the smaller AVR devices, using the */RESET* line. DebugWire mode is initiated by activating the *DWEN* fuse, and then power-cycling the target. While this mode is mainly intended for debugging/emulation, it also offers limited programming capabilities. Effectively, the only memory areas that can be read or programmed in this mode are flash ROM and EEPROM. It is also possible to read out the signature. All other memory areas cannot be accessed. There is no *chip erase* functionality in debugWire mode; instead, while reprogramming the flash ROM, each

flash ROM page is erased right before updating it. This is done transparently by the JTAG ICE mkII (or AVR Dragon). The only way back from debugWire mode is to initiate a special sequence of commands to the JTAG ICE mkII (or AVR Dragon), so the debugWire mode will be temporarily disabled, and the target can be accessed using normal ISP programming. This sequence is automatically initiated by using the JTAG ICE mkII or AVR Dragon in ISP mode, when they detect that ISP mode cannot be entered.

- Problem: I want to use my JTAG ICE mkII to program an Xmega device through PDI. The documentation tells me to use the *XMEGA PDI adapter for JTAGICE mkII* that is supposed to ship with the kit, yet I don't have it.

Solution: Use the following pin mapping:

JTAGICE mkII probe	Target pins	Squid cab- le colors	PDI header
1 (TCK)		Black	
2 (GND)	GND	White	6
3 (TDO)		Grey	
4 (VTref)	VTref	Purple	2
5 (TMS)		Blue	
6 (nSRST)	PDI_CLK	Green	5
7 (N.C.)		Yellow	
8 (nTRST)		Orange	
9 (TDI)	PDI_DATA	Red	1
10 (GND)		Brown	

- Problem: I want to use my AVR Dragon to program an Xmega device through PDI.

Solution: Use the 6 pin ISP header on the Dragon and the following pin mapping:

Dragon ISP Header	Target pins
1 (SDI)	PDI_DATA
2 (VCC)	VCC
3 (SCK)	
4 (SDO)	
5 (RESET)	PDI_CLK / RST
6 (GND)	GND

- Problem: I want to use my AVRISP mkII to program an ATtiny4/5/9/10 device through TPI. How to connect the pins?

Solution: Use the following pin mapping:

AVRISP connector	Target pins	ATtiny pin #
1 (SDI)	TPIDATA	1
2 (VTref)	Vcc	5
3 (SCK)	TPICLK	3
4 (SDO)		
5 (RESET)	/RESET	6
6 (GND)	GND	2

- Problem: I want to program an ATtiny4/5/9/10 device using a serial/parallel bitbang programmer. How to connect the pins?

Solution: Since TPI has only 1 pin for bi-directional data transfer, both *SDI* and *SDO* pins should be connected to the *TPIDATA* pin on the ATtiny device. However, a 1K resistor should be placed between the *SDO* and *TPIDATA*. The *SDI* pin connects to *TPIDATA* directly. The *SCK* pin is connected to *TPICLK*.

In addition, the *Vcc*, */RESET* and *GND* pins should be connected to their respective ports on the ATtiny device.

- Problem: How can I use a FTDI FT232R USB-to-Serial device for bitbang programming?

Solution: When connecting the FT232 directly to the pins of the target Atmel device, the polarity of the pins defined in the `programmer` definition should be inverted by prefixing a tilde. For example, the *dasa* programmer would look like this when connected via a FT232R device (notice the tildes in front of pins 7, 4, 3 and 8):

```
programmer
  id    = "dasa_ftdi";
  desc  = "serial port banging, reset=rts sck=dtr sdo=txd sdi=cts";
  type  = serbb;
  reset = ~7;
  sck   = ~4;
  sdo   = ~3;
  sdi   = ~8;
;
```

Note that this uses the FT232 device as a normal serial port, not using the FTDI drivers in the special bitbang mode.

- Problem: My ATtiny4/5/9/10 reads out fine, but any attempt to program it (through TPI) fails. Instead, the memory retains the old contents.

Solution: Mind the limited programming supply voltage range of these devices.

In-circuit programming through TPI is only guaranteed by the datasheet at $V_{cc} = 5$ V.

- Problem: My ATxmega...A1/A2/A3 cannot be programmed through PDI with my AVR Dragon. Programming through a JTAG ICE mkII works though, as does programming through JTAG.

Solution: None by this time (2010 Q1).

It is said that the AVR Dragon can only program devices from the A4 Xmega sub-family.

- Problem: when programming with an AVRISPMkII or STK600, AVRDUDE hangs when programming files of a certain size (e.g. 246 bytes). Other (larger or smaller) sizes work though.

Solution: This is a bug caused by an incorrect handling of zero-length packets (ZLPs) in some versions of the libusb 0.1 API wrapper that ships with libusb 1.x in certain Linux distributions. All Linux systems with kernel versions $< 2.6.31$ and libusb $\geq 1.0.0 < 1.0.3$ are reported to be affected by this.

See also: <http://www.libusb.org/ticket/6>

- Problem: after flashing a firmware that reduces the target's clock speed (e.g. through the CLKPR register), further ISP connection attempts fail. Or a programmer cannot initialize communication with a brand new chip.

Solution: Even though ISP starts with pulling */RESET* low, the target continues to run at the internal clock speed either as defined by the firmware running before or as set by the factory. Therefore, the ISP clock speed must be reduced appropriately (to less than 1/4 of the internal clock speed) using the *-B* option before the ISP initialization sequence will succeed.

As that slows down the entire subsequent ISP session, it might make sense to just issue a *chip erase* using the slow ISP clock (option *-e*), and then start a new session at higher speed. Option *-D* might be used there, to prevent another unneeded erase cycle.

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