Digital Image Processing - CS 663

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Mean Shift Segmentation

Mean shift is a procedure for locating the maxima—the modes—of a density function given discrete data sampled from that function. [1] This is an iterative method, and we start with an initial estimate x. A function determines the weight of nearby points for re-estimation of the mean.

Formula used in segmentation is-

 $\vec{r_i}$ is symbolic for all 3-D vector that of RGB space. \vec{r} represents the 3-D RGB vector for which mean shift is being calculated.

 $\vec{z_i}$ is symbolic for all 2-D vector that of the pair(x,y) of img. \vec{Z} represents the 3-D RGB vector for which mean shift is being calculated.

$$\begin{split} f(x) &= \alpha \sum_i K\left(\frac{||\vec{z_i} - \vec{z}||^2}{2h_s^2}\right) K\left(\frac{||\vec{r_i} - \vec{r}||^2}{2h_r^2}\right) \\ K(x^2) &= \beta exp(-x^2/2) \\ f(x) &= \alpha \beta^2 \sum_i exp\left(\frac{||\vec{z_i} - \vec{z}||^2}{2h_s^2}\right) exp\left(\frac{||\vec{r_i} - \vec{r}||^2}{2h_r^2}\right) \end{split}$$

differentiating wrt to \vec{r} and \vec{z}

$$\begin{split} \Delta f &= \frac{\alpha \beta^2}{h_r^2} \sum_{i} (\vec{r_i} - \vec{r}) \exp\left(\frac{||\vec{z_i} - \vec{z}||^2}{2h_s^2} + \frac{||\vec{r_i} - \vec{r}||^2}{2h_r^2}\right) \\ \Delta log(f) &= \frac{\Delta f}{f} = \frac{1}{h_r^2} \frac{\sum_{i} (\vec{r_i} - \vec{r}) exp\left(\frac{||\vec{r_i} - \vec{r}||^2}{2h_r^2} + \frac{||\vec{z_i} - \vec{z}||^2}{2h_s^2}\right)}{\sum_{i} exp\left(\frac{||\vec{r_i} - \vec{r}||^2}{2h_r^2} + \frac{||\vec{z_i} - \vec{z}||^2}{2h_s^2}\right)} \\ \Delta f &= \frac{\alpha \beta^2}{h_s^2} \sum_{i} (\vec{z_i} - \vec{z}) exp\left(\frac{||\vec{z_i} - \vec{z}||^2}{2h_s^2} + \frac{||\vec{r_i} - \vec{r}||^2}{2h_r^2}\right) \\ \Delta log(f) &= \frac{\Delta f}{f} = \frac{1}{h_r^2} \frac{\sum_{i} (\vec{z_i} - \vec{z}) exp\left(\frac{||\vec{r_i} - \vec{r}||^2}{2h_r^2} + \frac{||\vec{z_i} - \vec{z}||^2}{2h_s^2}\right)}{\sum_{i} exp\left(\frac{||\vec{r_i} - \vec{r}||^2}{2h_r^2} + \frac{||\vec{z_i} - \vec{z}||^2}{2h_s^2}\right)} \end{split}$$

hence the mean is shift to

$$\begin{split} \vec{m_r} &= \frac{\sum_{i} \vec{r_i} exp\left(\frac{||\vec{r_i} - \vec{r}||^2}{2h_r^2}\right) exp\left(\frac{||\vec{z_i} - \vec{z}||^2}{2h_s^2}\right)}{\sum_{i} exp\left(\frac{||\vec{r_i} - \vec{r}||^2}{2h_r^2}\right) exp\left(\frac{||\vec{z_i} - \vec{z}||^2}{2h_s^2}\right)} - \vec{r} \\ \vec{m_s} &= \frac{\sum_{i} \vec{z_i} exp\left(\frac{||\vec{r_i} - \vec{r}||^2}{2h_r^2}\right) exp\left(\frac{||\vec{z_i} - \vec{z}||^2}{2h_s^2}\right)}{\sum_{i} exp\left(\frac{||\vec{r_i} - \vec{r}||^2}{2h_r^2}\right) exp\left(\frac{||\vec{z_i} - \vec{z}||^2}{2h_s^2}\right)} - \vec{z} \\ \vec{z} &= \vec{z} + k_r m_r(\vec{x}) \\ \vec{r} &= \vec{r} + k_s m_r(\vec{r}) \end{split}$$

Where k_s and k_r are scaling factor, Main code-snippet is given below (when only spatial part is updated):-

```
for k=x_min_range : x_max_range
2
      for l=y_min_range : y_max_range
           %rgb space difference norm
           X = double((output_img(k,l,1) - output_img(i,j,1)) ^ 2 + (
4
     \operatorname{output\_img}(k,1,2) - \operatorname{output\_img}(i,j,2)) ^ 2 + (\operatorname{output\_img}(k,1,3) -
     output_img(i,j,3)) ^ 2);
           %spatial gaussian
5
           a = exp(-((k-i)^2 + (1-j)^2) / (2 * (h_s)^2));
6
            %colour space gaussian
           b = \exp(-(X/(2 * h_r^2)));
           %sum of weighted average in all color space
9
           for m=1:cha
               weighted_factor(m) = weighted_factor(m) + a * b * double((
     output_img(k,1,m)));
13
             %sum (G_s * G_c)
14
           factor = factor + a * b;
      end
```

Steps Taken

- 1. Down sample the input image and apply Gaussian blurring
- 2. For each pixel \vec{z} in the image we make a region of $4h_s$ around it (as any point greater than this window will have negligible weight)
- 3. Apply the above formula for each $\vec{z_i} \& \vec{r_i}$ in the window and calculate mean shift \vec{m}
- 4. Shift \vec{r} by $\vec{m_r}$ & \vec{z} by $\vec{m_s}$
- 5. Repeat last three steps for few iterations

Without spatial update

Flower

- 1. Bandwidth for the color feature = 10
- 2. Bandwidth for the spatial feature = 6
- 3. number of iterations = 15

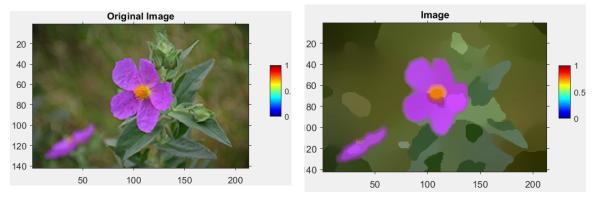


Figure 1: original image

Figure 2: segmented image

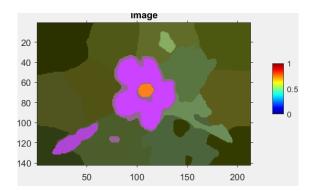


Figure 3: clustered image

Bird

- 1. Bandwidth for the color feature = 30
- 2. Bandwidth for the spatial feature =20
- 3. number of iterations = 15

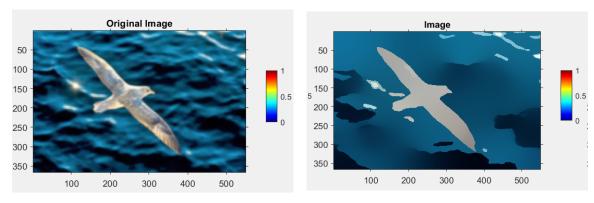


Figure 4: original image

Figure 5: segmented image

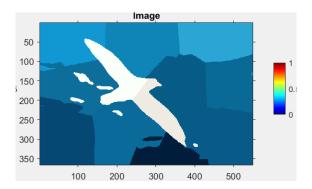


Figure 6: clustered image

Baboon

- 1. Bandwidth for the color feature = 16
- 2. Bandwidth for the spatial feature = 8
- 3. number of iterations = 15

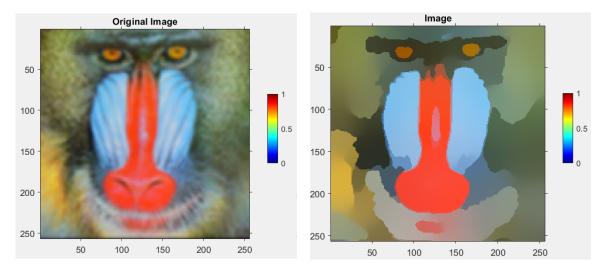


Figure 7: original image

Figure 8: segmented image

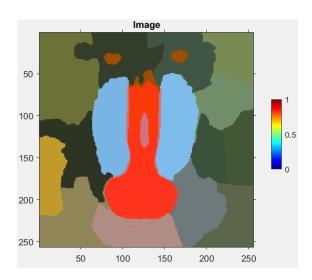


Figure 9: clustered image

With spatial update

Flower

- 1. Bandwidth for the color feature = 10
- 2. Bandwidth for the spatial feature = 6
- 3. number of iterations = 15

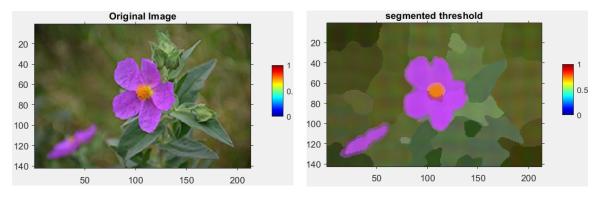


Figure 10: original image

Figure 11: segmented image

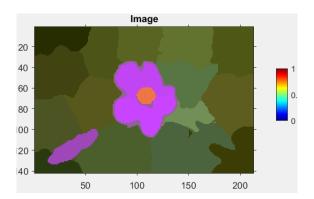


Figure 12: clustered image

Bird

- 1. Bandwidth for the color feature = 30
- 2. Bandwidth for the spatial feature =20
- 3. number of iterations = 15

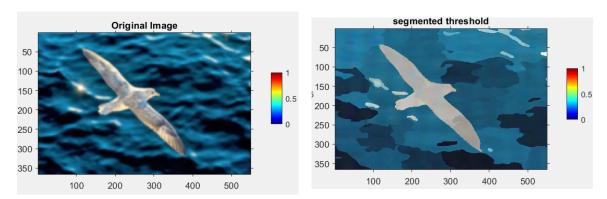


Figure 13: original image

Figure 14: segmented image

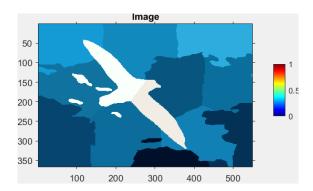


Figure 15: clustered image

Baboon

- 1. Bandwidth for the color feature = 15
- 2. Bandwidth for the spatial feature = 15
- 3. number of iterations = 15

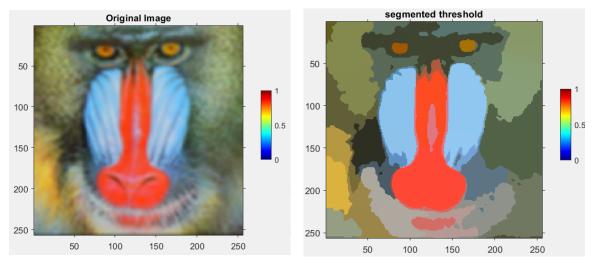


Figure 16: original image

Figure 17: segmented image

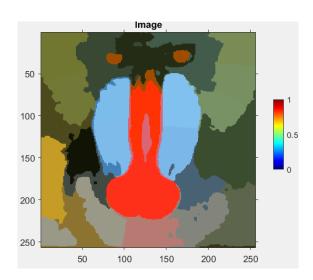


Figure 18: Clustered Image

Remarks

- 1. The results are better in case of 'without spatial coordinates update'
- 2. Spatial coordinates update introduces isometric patches.
- 3. Clustering is done by using kmeans and the colour of patch is the colour of centroid.
- 4. Introducing learning rate (scaling factor) help us to achieve convergence faster.