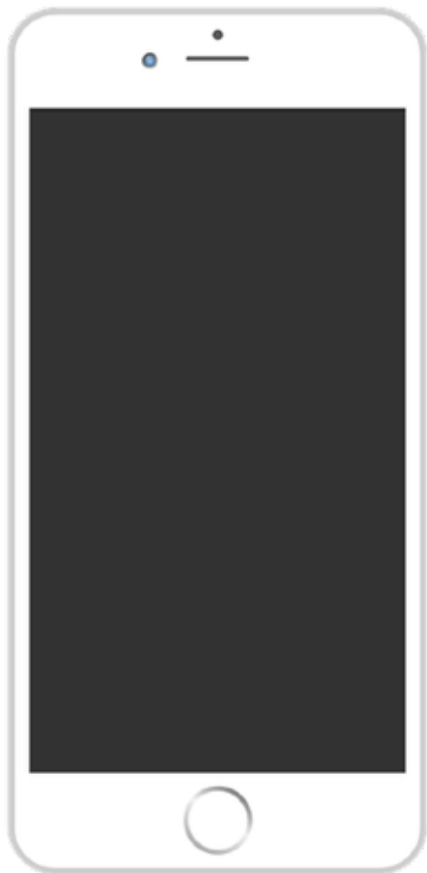


Protype

The real time feedback was given as shown in the screen in the middle. The patient was required to follow the grey square, whereas the green square was mimicking the motion of their foot. If rotational movement was detected, the green square turned red.

The exercise being demoed here is Dynamic Quadriceps, to strengthen the hamstrings. This data was then recorded and shown to the patients through a webpage.



4

3

2

1

0



4

3

2

1

0



Readline feed back



Welcome, Kaushik!

Dates

14/11/19

15/11/19

16/11/19

17/11/19

18/11/19

19/11/19

20/11/19

This is your dashboard! Records of all the exercises you do will be kept here.

Dynamic Quadriceps

Straight Leg Raising

Session 1

Number of repetitions: 8

Highest Range of Motion achieved: 111.47°

Dynamic Quadriceps Set 1

— Initial Movement
— Initial Position
— Max Range of Motion



Pulse Levels

Number of Sessions: 1

Max Pulse Level

Average Pulse Level

Resting Pulse Level



Sample link: <https://aykashya.github.io/GSTH/EGD2L1DQ.html>





4

3

2

1

0



4

3

2

1

0

4

3

2

1

0



4

3

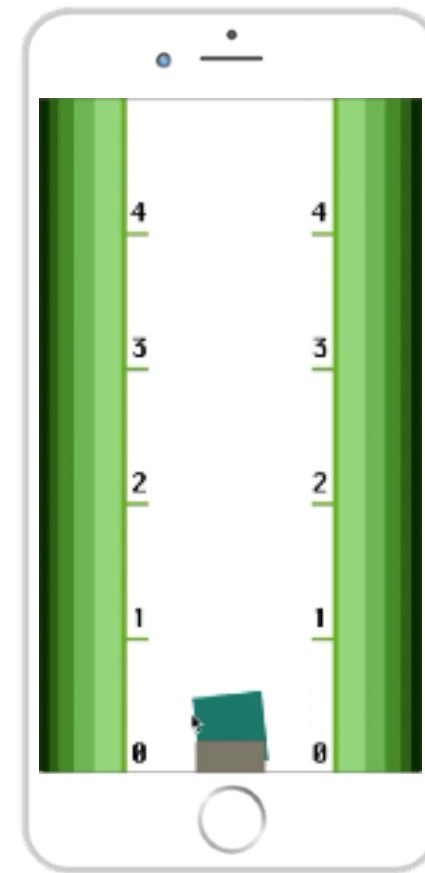
2

1

0

Sample link: https://avyayrkashyap.github.io/GSTH/EG02L_1_DQ.html

Realttime feedback



The real time feedback was given as shown in the screen in the middle. The patient was required to follow the grey square, whereas the green square was mimicking the motion of their foot. If rotational movement was detected, the green square turned red.

The exercise being demoed here is Dynamic Quadriceps, to strengthen the hamstrings. This data was then recorded and shown to the patients through a webpage.

Prototype



Prototype

