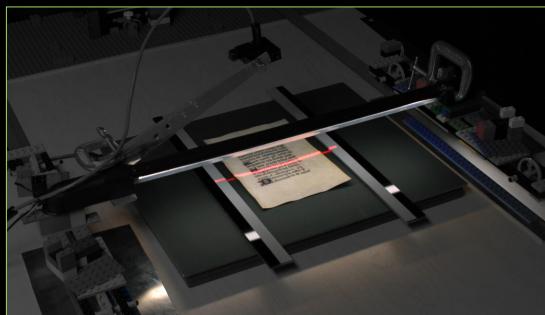


Spatially Varying Reflectance Modeling



70001 – Advanced Computer Graphics: Photographic Image Synthesis

Abhijeet Ghosh

Lecture 13, Feb. 16th 2024

1

SVBRDF (Spatially Varying BRDFs)



SVBRDF

- 6D function (Surface position, incident, exitant)
- Planar surfaces
- Many independent surface points with different BRDFs
- Not a simple texture!



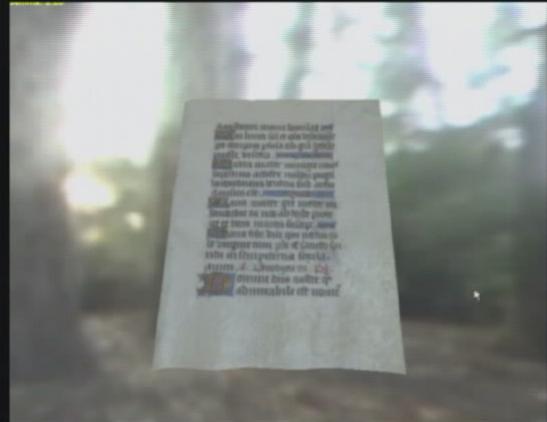
Question

- How to efficiently capture and model?
 - Analytic
 - Data-driven
 - Statistical modeling

2

1

SVBRDF (Spatially Varying BRDFs) [Gardner et al. 03]

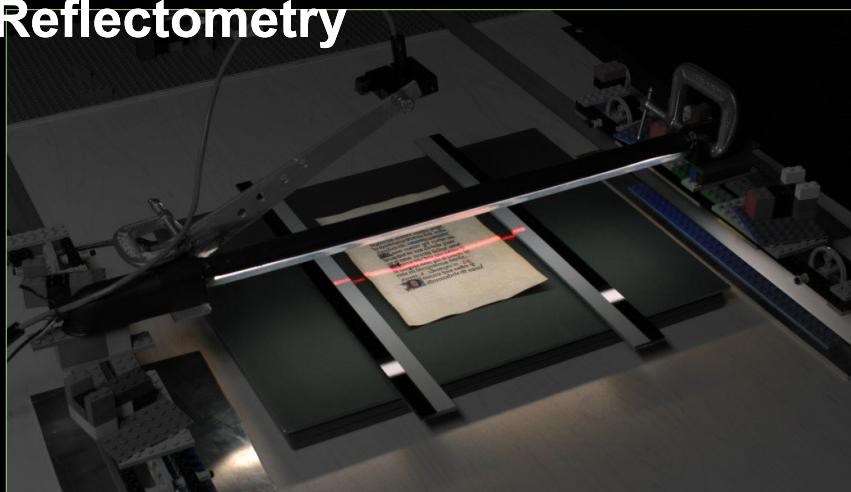


Spatially varying properties:

- Diffuse Color
- Specular Color
- Specular Roughness

3

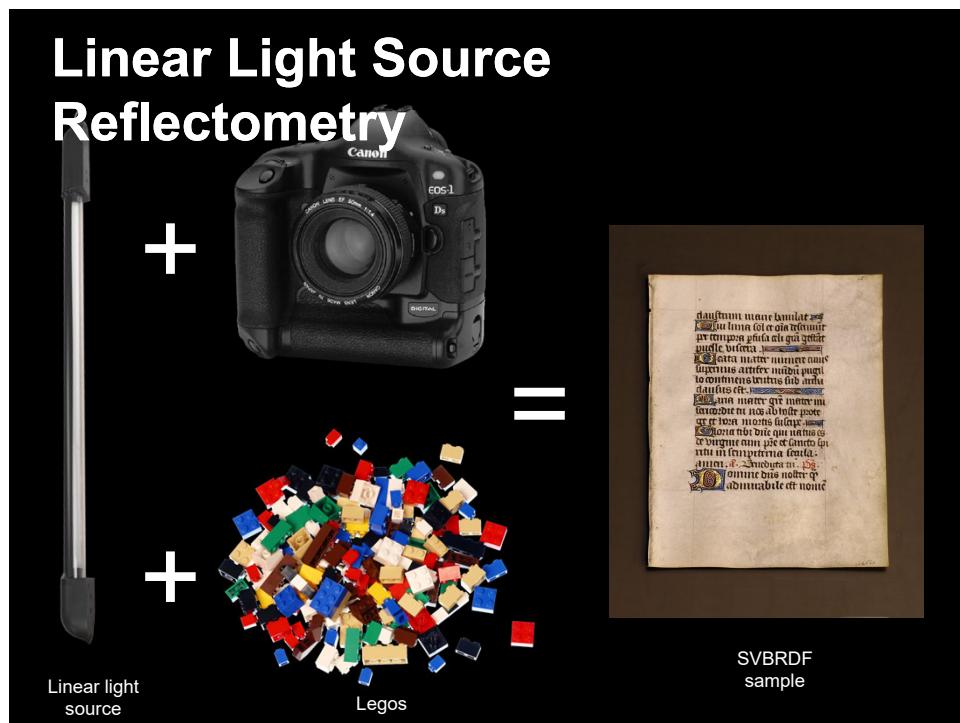
Linear Light Source Reflectometry



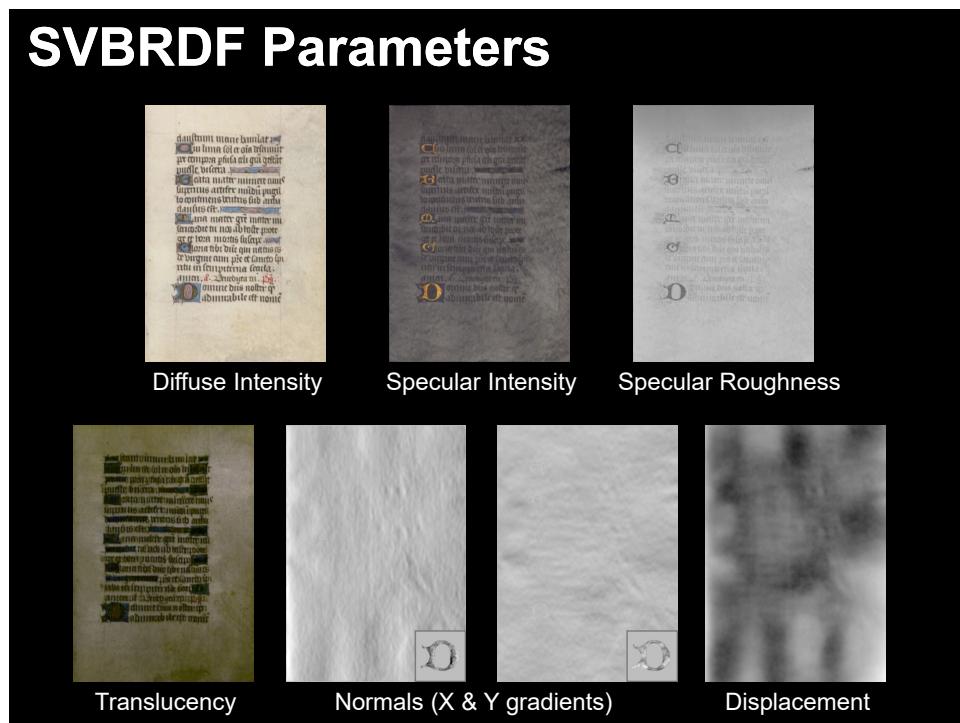
Andrew Gardner, Chris Tchou, Tim Hawkins,
and Paul Debevec, SIGGRAPH 2003

4

2

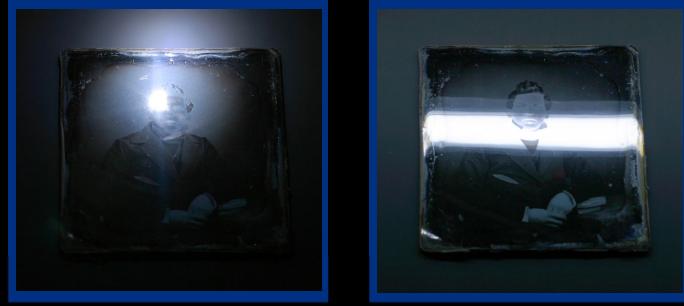


5



6

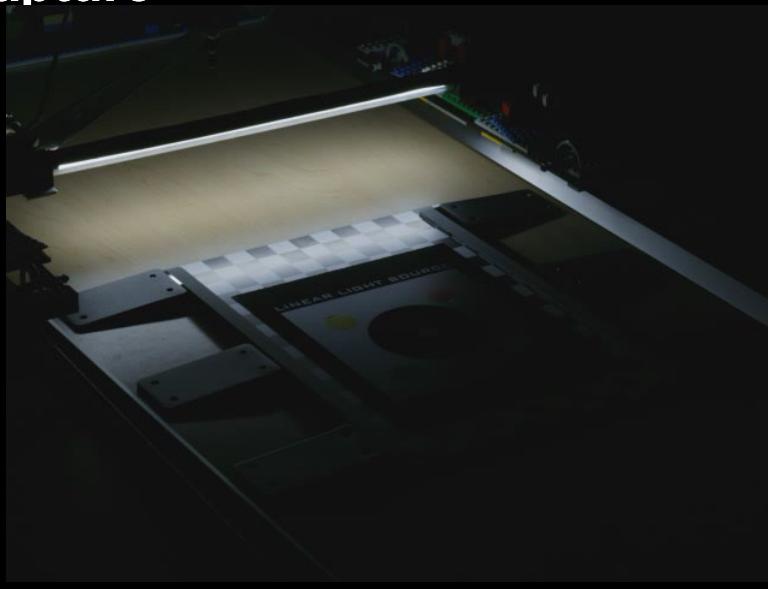
Motivation: Linear Light Source



- Fewer images needed to cover planar samples with linear light source
- Dynamic range compression compared to point light source
 - can be photographed with single exposure instead of HDR
- Simple machinery of linear 1D translation to cover entire sample

7

Capture



8

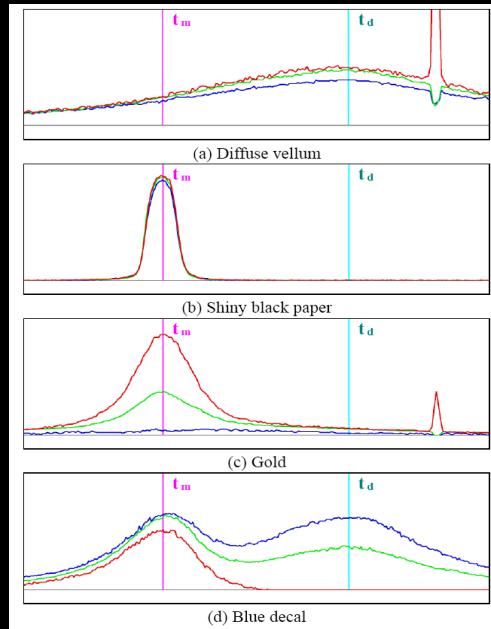
Reflectance trace for each pixel

X-axis: time (light motion)

Y-axis: reflectance

Diffuse peak t_d coincides with light aligned with surface normal

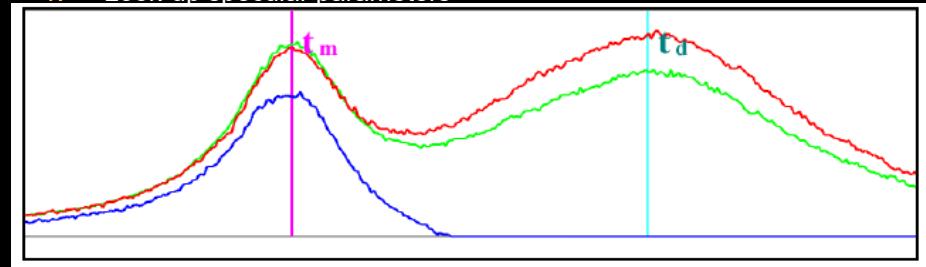
Specular peak t_m coincides with light aligned with mirror reflection



9

BRDF Fitting

1. Fit diffuse
2. Subtract diffuse
3. Estimate mean and variance of specular
4. Look-up specular parameters

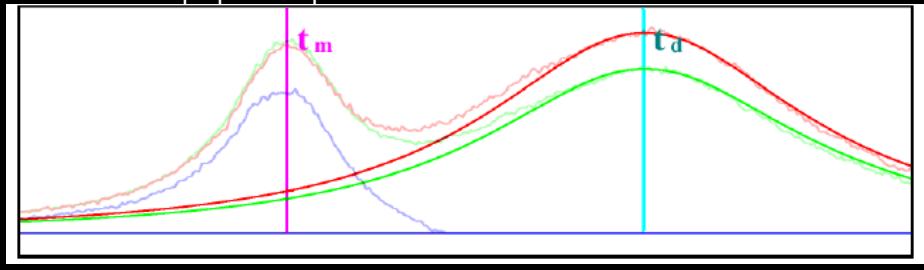


10

5

BRDF Fitting

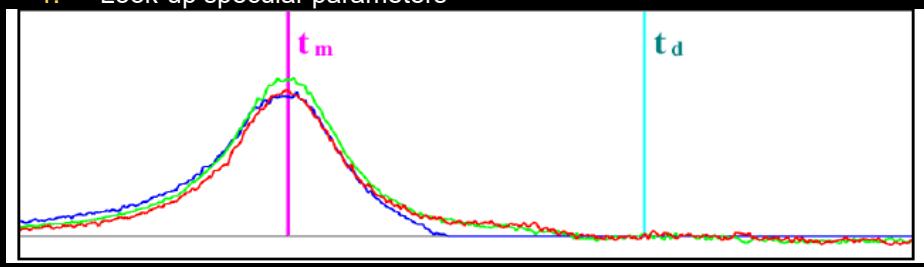
1. Fit diffuse
2. Subtract diffuse
3. Estimate mean and variance of specular
4. Look-up specular parameters



11

BRDF Fitting

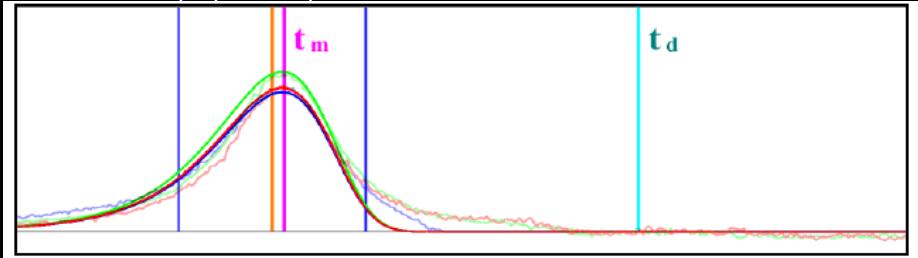
1. Fit diffuse
2. Subtract diffuse
3. Estimate mean and variance of specular
4. Look-up specular parameters



12

BRDF Fitting

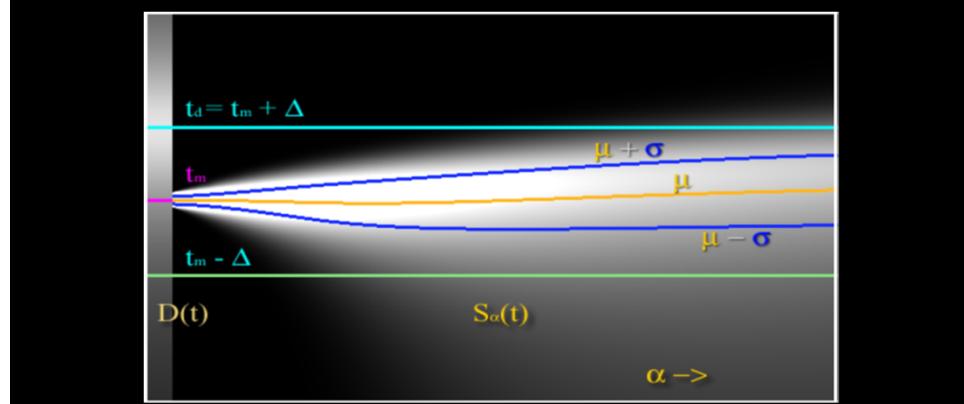
1. Fit diffuse
2. Subtract diffuse
3. Estimate mean and variance of specular
4. Look-up specular parameters



13

BRDF Fitting

1. Fit diffuse
2. Subtract diffuse
3. Estimate mean and variance using precomputed lookup table



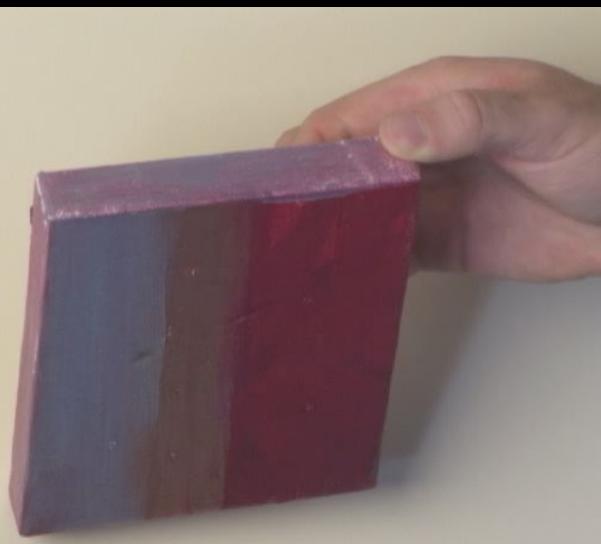
14

Results



15

Results



16

Pocket Reflectometry

Ren et al. SIGGRAPH 2011

17

Pocket Reflectometry



+



BRDF Chart

+



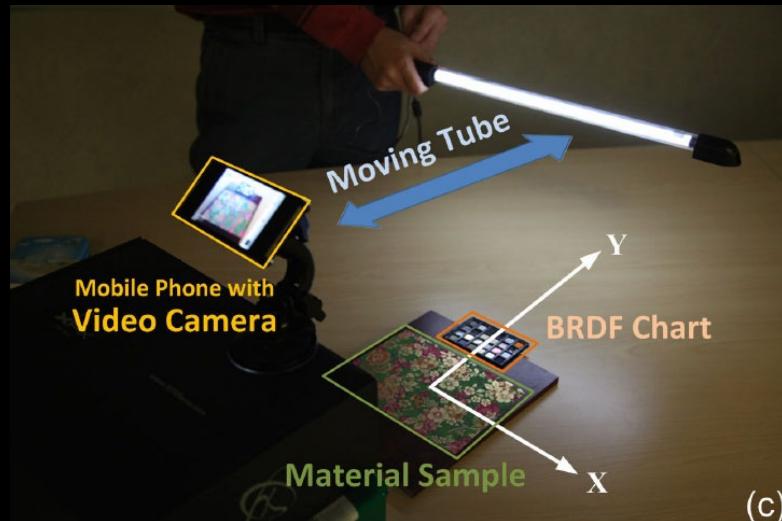
Mobile Phone Camera



18

9

Pocket Reflectometry



19

BRDF chart

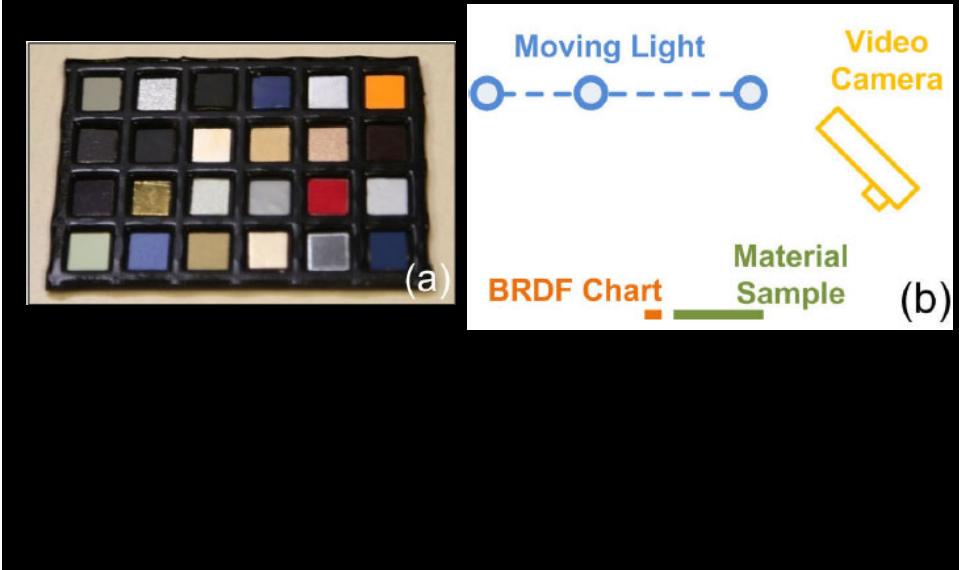


| | | | | | |
|----------------|--------------|-----------------------|------------------|-----------------------|-------------------|
| plaster | sliver paint | rubber | polished acrylic | aluminium | fluorescent paint |
| matte tape | black paper | polished resin | bronze | bronze metallic paint | acrylic |
| plastic | brass | coated metallic paint | polyethylene | red metallic paint | alumina |
| 80% Spectralon | leather | matte golden paint | alum-bronze | tinfoil | lactoprene |

- Exemplar materials inspired by the MERL BRDF database!
- Data-driven BRDF modelling

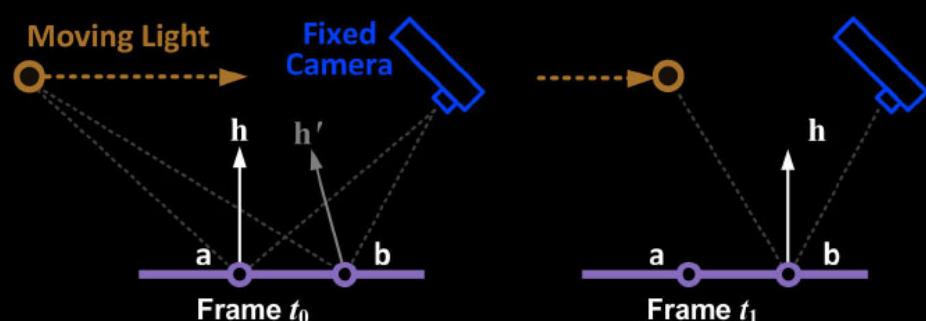
20

Pocket Reflectometry



21

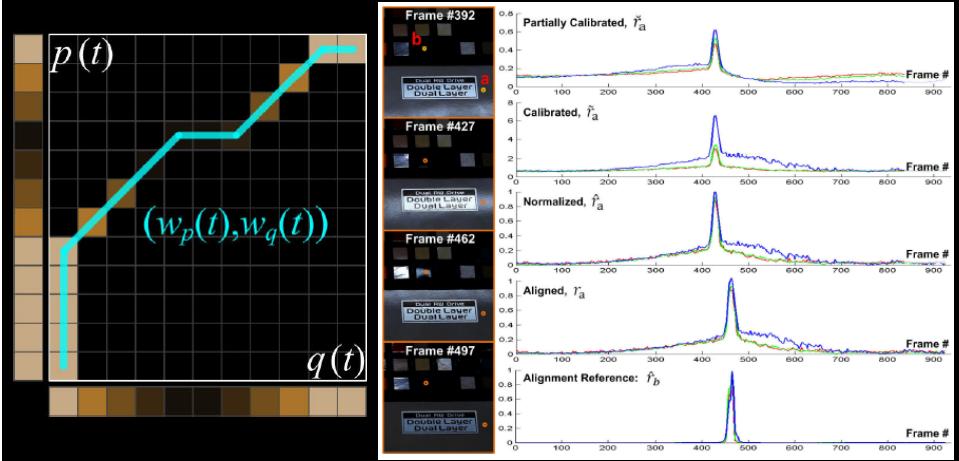
Time-shift compensation



- Different surface points will have their peaks at different time (frame)
- Reflectance trace of BRDF chart cannot be directly compared with sample

22

Dynamic time warping



- Alignment of reflectance traces of BRDF chart with sample

23

Reflectance estimation from chart

$$\mathbf{r} = d \mathbf{a} + s \mathbf{b},$$

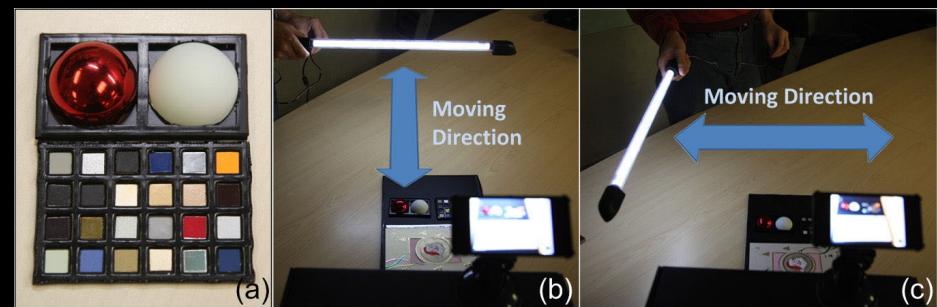
$$a(t) = \int_{\Omega^+} L_t(\mathbf{i}) \alpha(\mathbf{i}, \mathbf{o}) (\mathbf{n} \cdot \mathbf{i}) d\mathbf{i}, \quad b(t) = \int_{\Omega^+} L_t(\mathbf{i}) \beta(\mathbf{i}, \mathbf{o}) (\mathbf{n} \cdot \mathbf{i}) d\mathbf{i},$$

$$\min_{u_0, u_1, \dots, u_k} \left\| \mathbf{r} - u_0 \mathbf{a} - \sum_{j=1}^k u_j \mathbf{b}_j \right\|, \quad u_j \geq 0, \quad \mathbf{b}_j \in \Phi(\mathbf{r})$$

- a diffuse BRDF with albedo d
- \mathbf{b} specular BRDF with parameters s
- Instead of direct estimation of s , estimate a linear combination of k exemplar BRDFs in BRDF chart that fits the observed data per-pixel

24

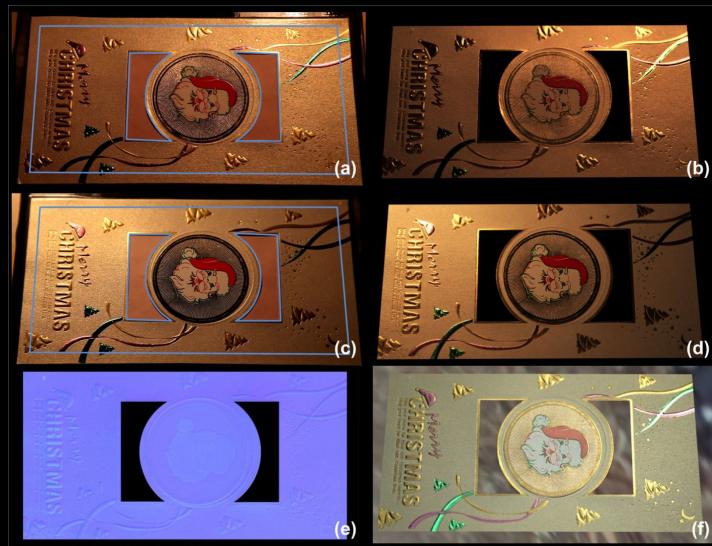
Bumpy surface estimation



- Compute surface normal as intersection of two orthogonal passes of light source to estimate X & Y components of surface normals
- Assumption mostly flat surface, so no need to estimate z component

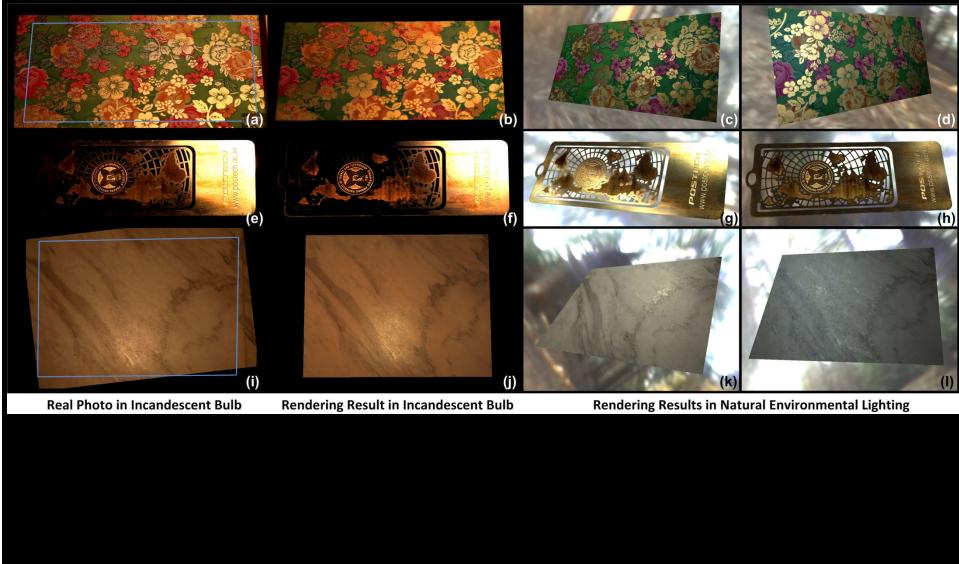
25

Bumpy surface results



26

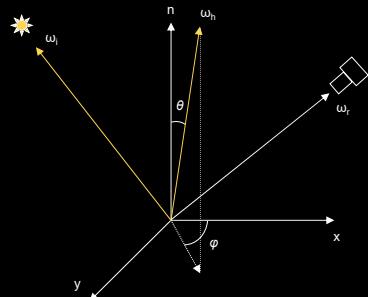
Flat surface results



27

Measure and fit

- Analytic BRDF models
 - albedo
 - specular roughness
 - normal and tangent directions
- Is DIRECT estimate possible?



28

14

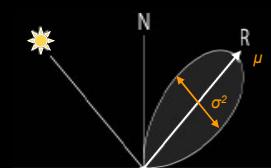
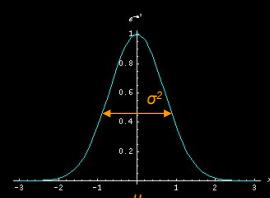
Second order statistics of reflectance

Ghosh et al. EGSR 2009

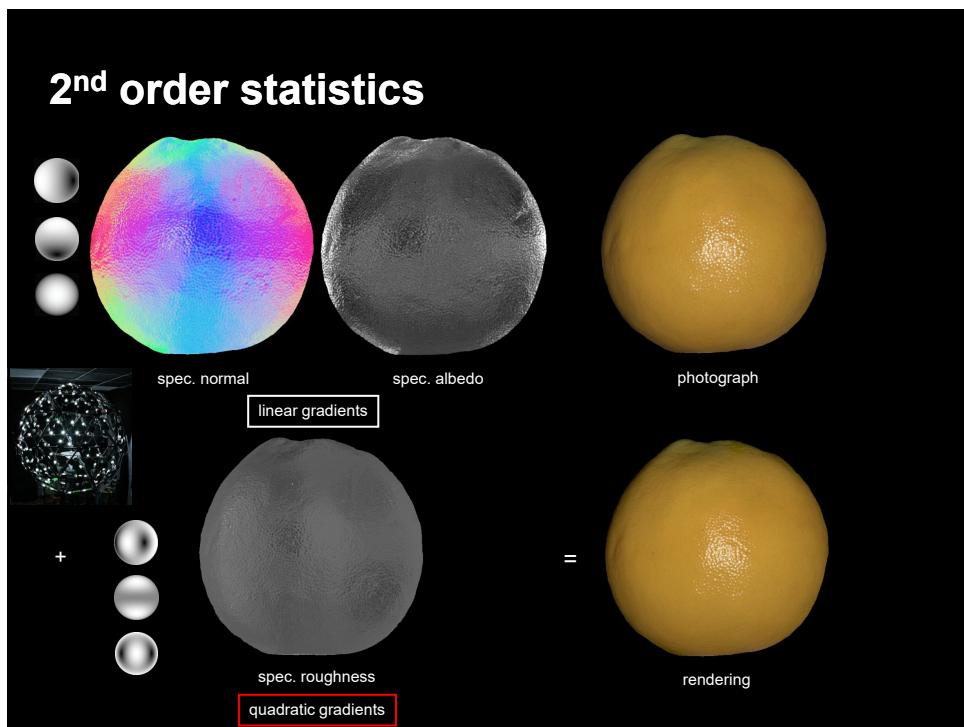
29

2nd order statistics of reflectance

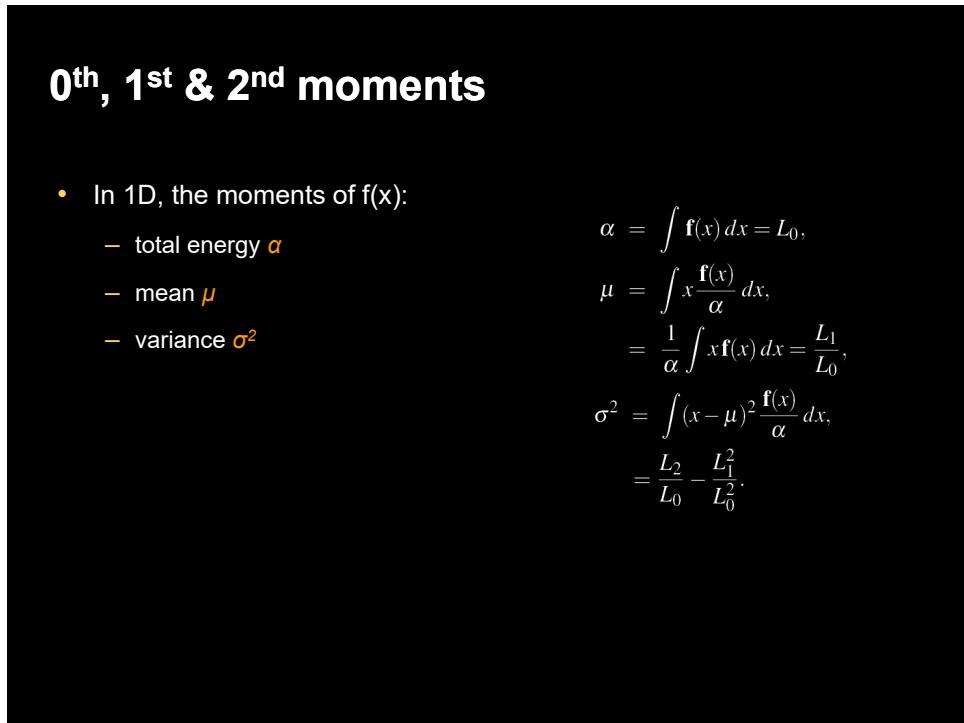
- Specular reflection
 - measure of variance σ^2 about mean μ
 - reflection vector and specular roughness
 - computational illumination for optical measurement of reflectance statistics!



30



31



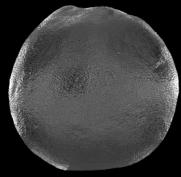
32

0th spherical moment

parallel



cross



$$L_0 = \int_{\Omega} \mathbf{f}(\vec{\omega}) d\vec{\omega},$$

α

33

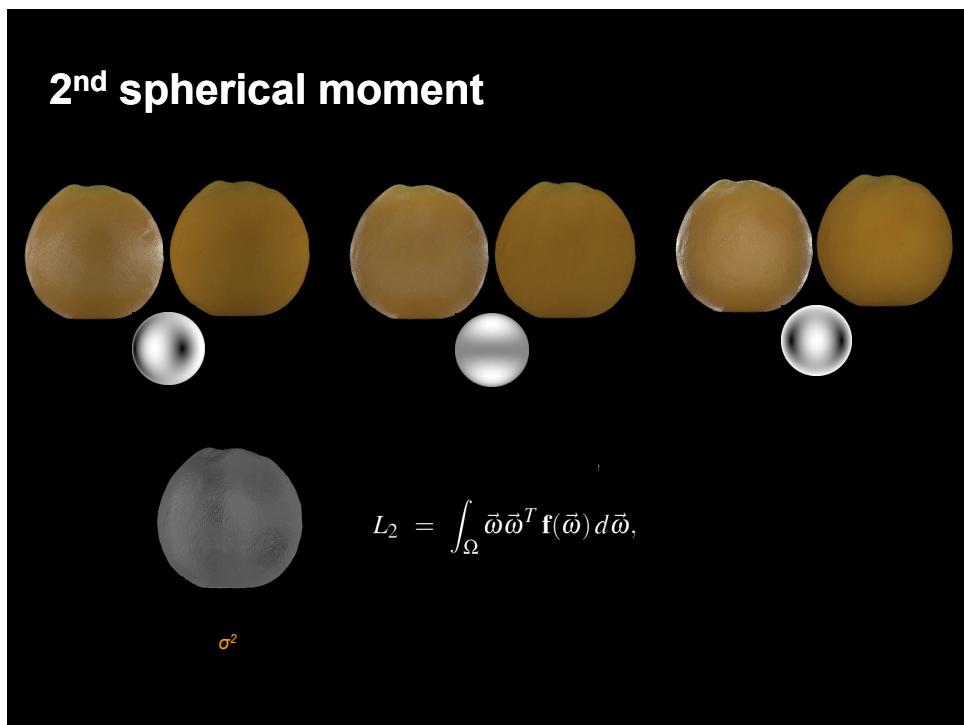
1st spherical moment

μ

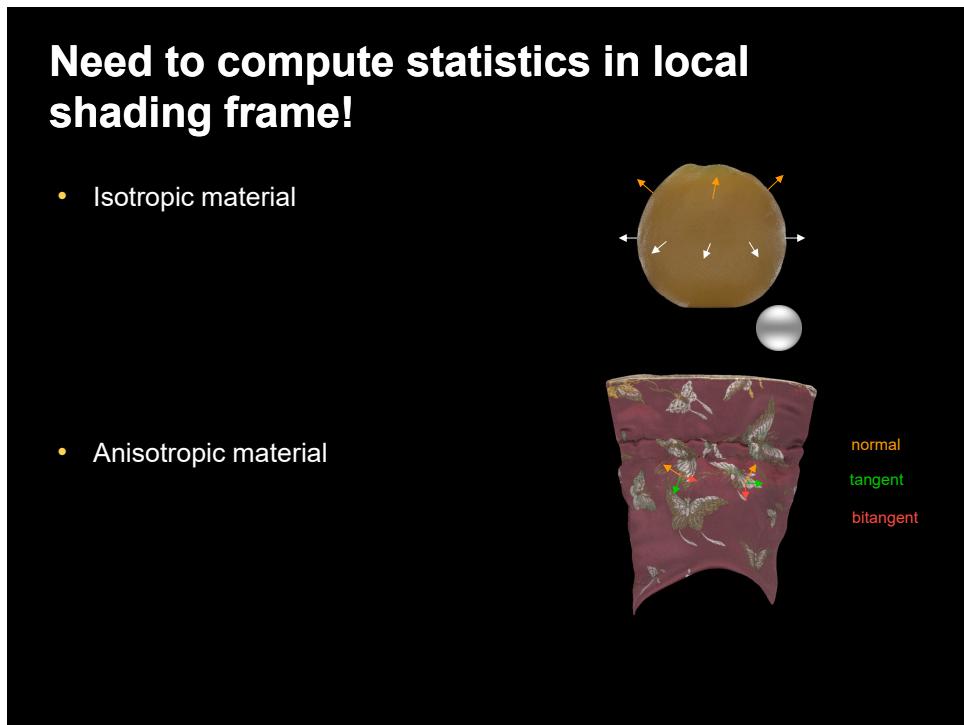
$$L_1 = \int_{\Omega} \vec{\omega} \mathbf{f}(\vec{\omega}) d\vec{\omega},$$

34

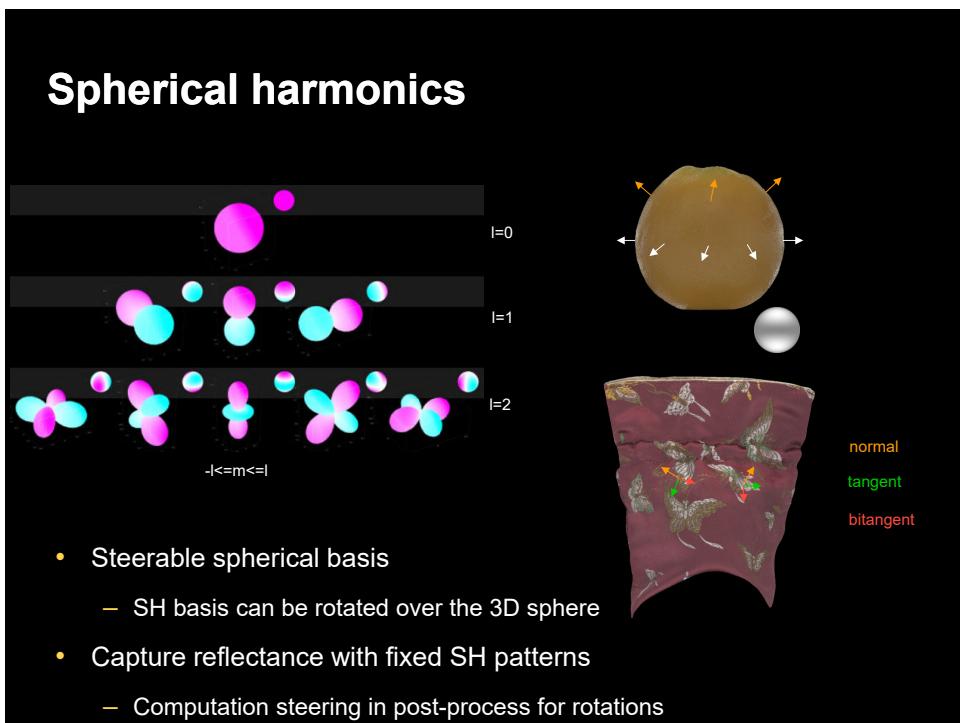
17



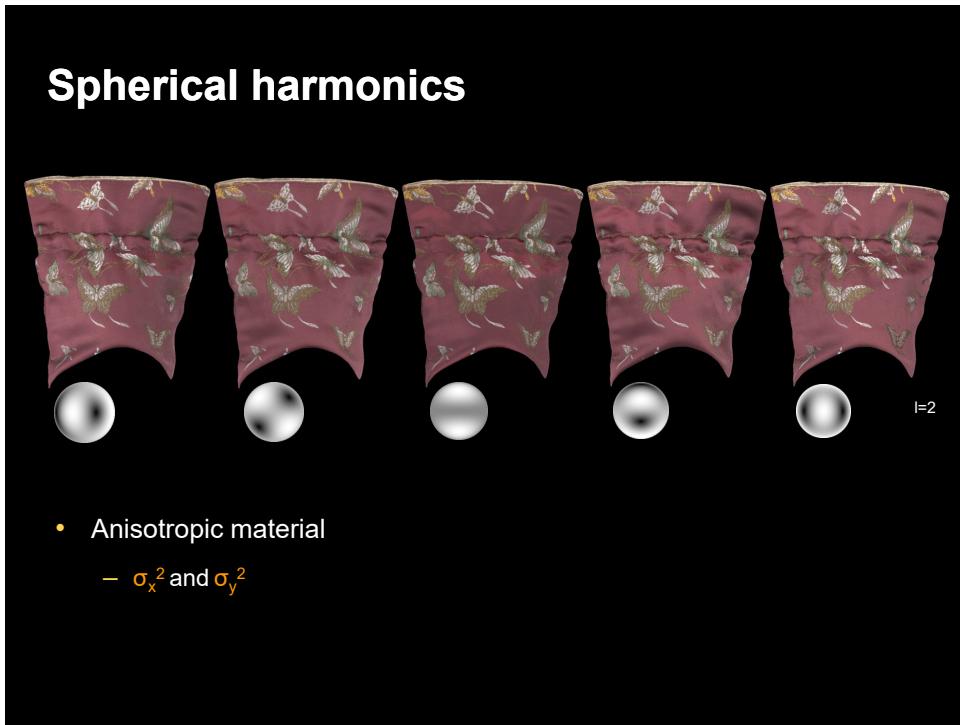
35



36



37



38

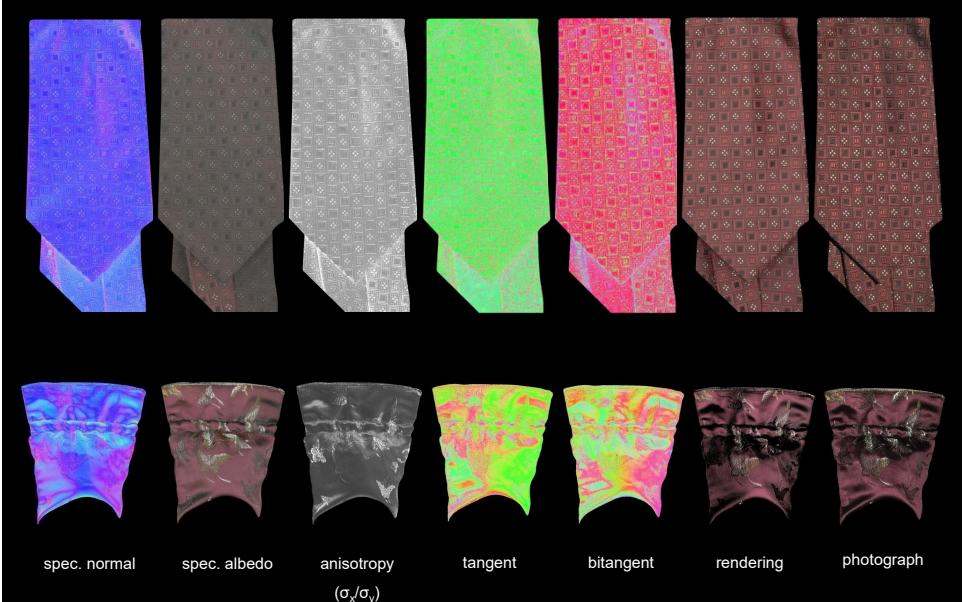
19

Isotropic reflectance

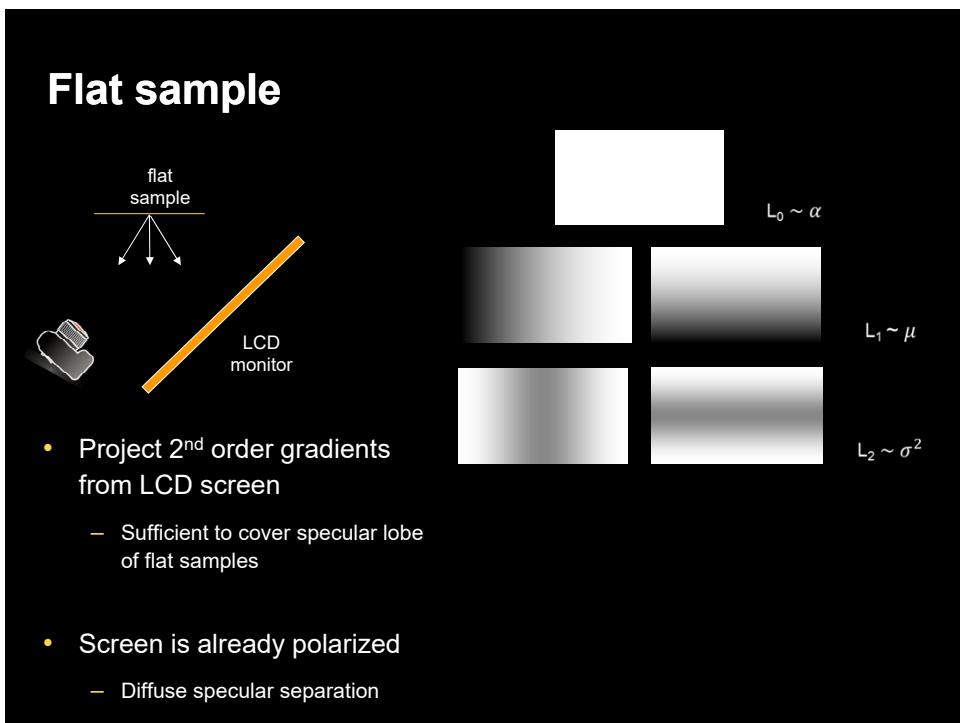


39

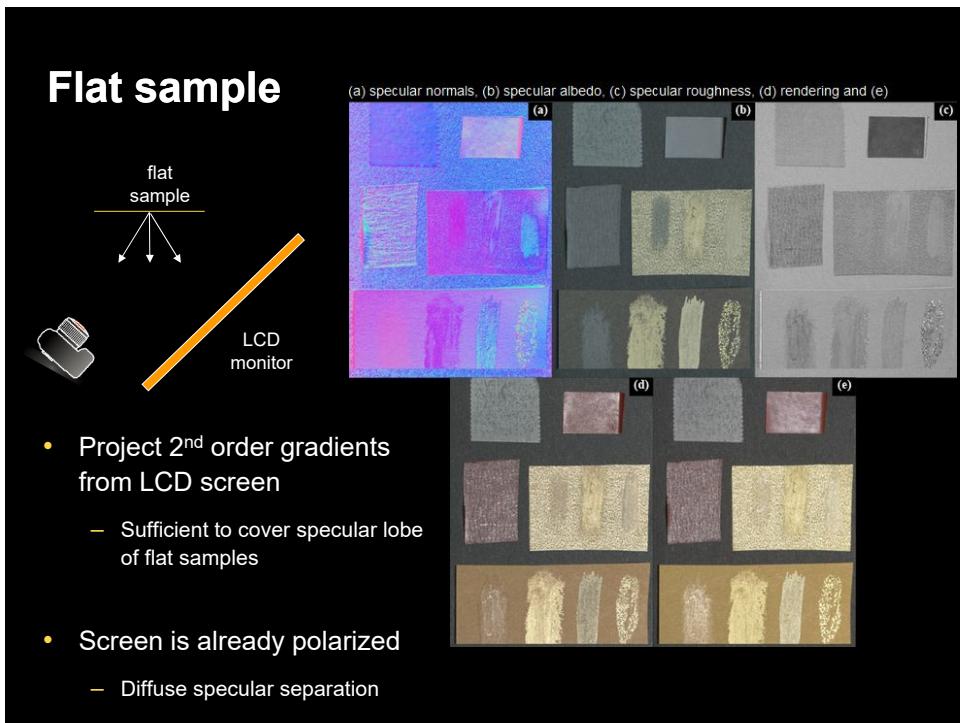
Anisotropic reflectance



40



41



42

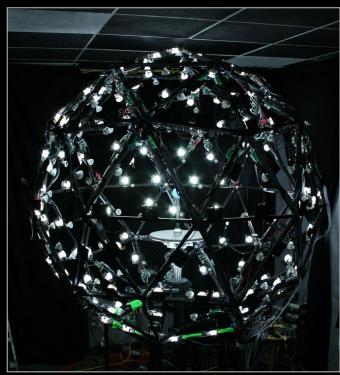
Specular materials!



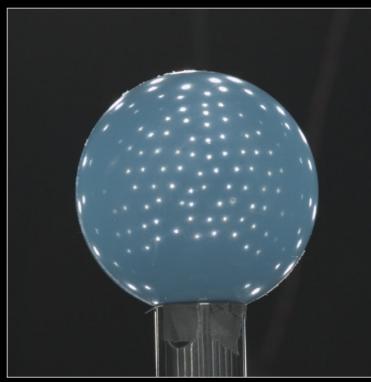
- Highly specular objects difficult to acquire ☺
 - especially if not planar

43

Specular materials!



LED sphere

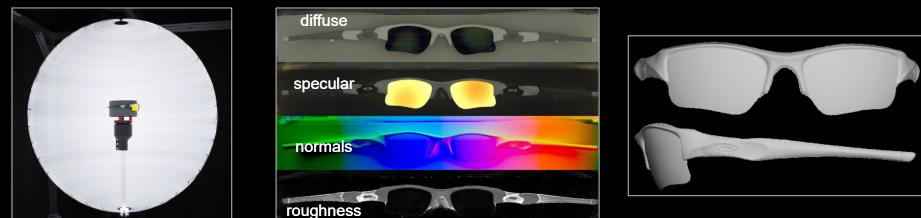


- Discrete light stage results in hot spots of specular reflection
 - Niquist sampling problem!

44

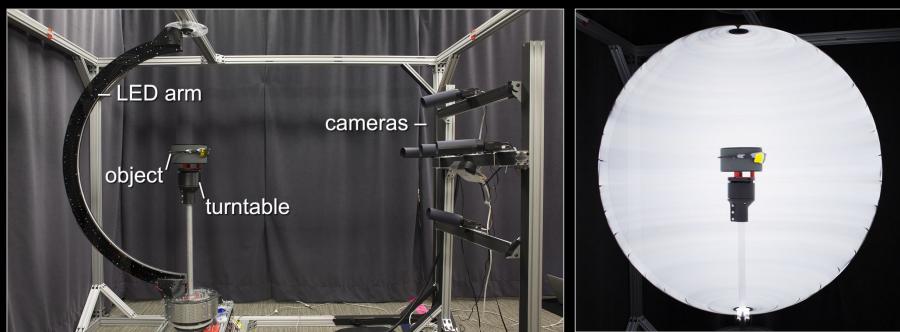
Continuous spherical harmonic illumination

[Tunwattanpong et al. 2013]



45

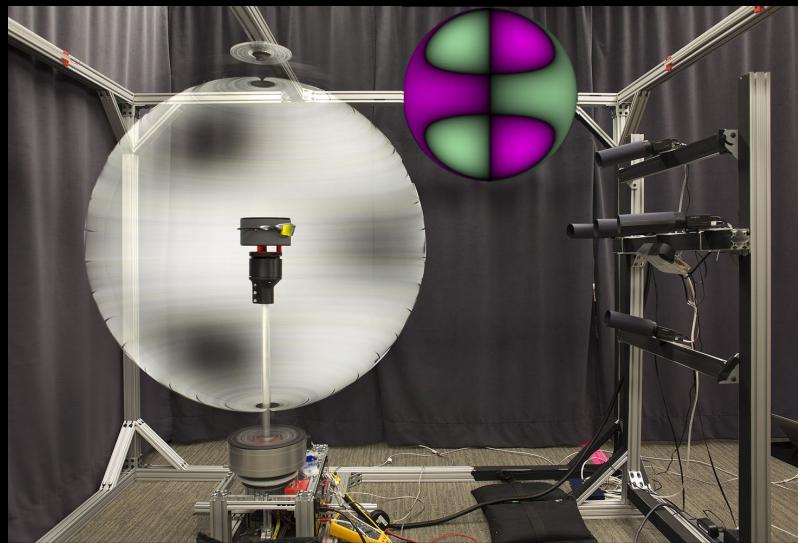
Hardware setup



- LED arc creates a full continuous sphere of light through rotation
 - Long exposure photography required to integrate over the entire sphere!

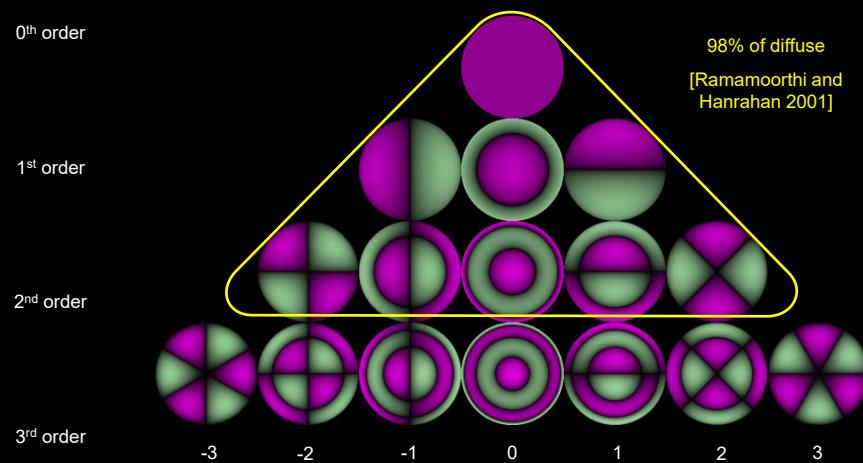
46

SH illumination



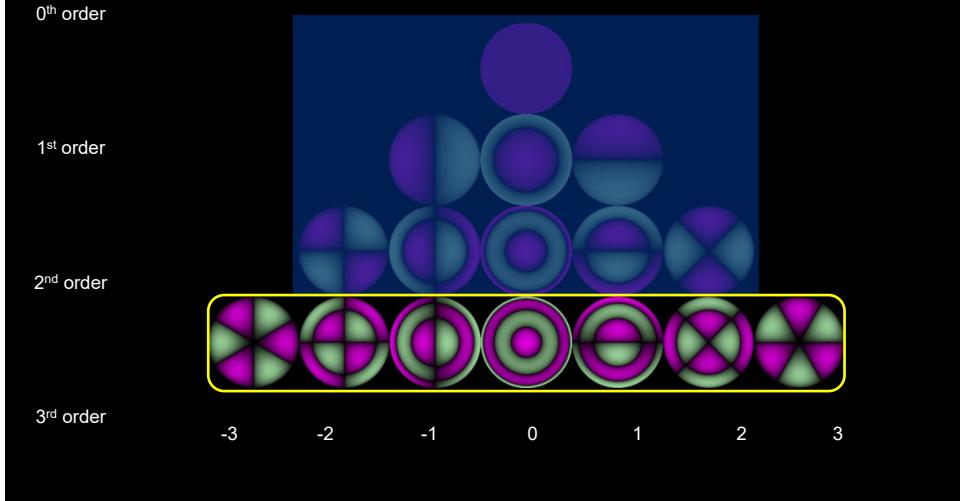
47

Diffuse-specular separation



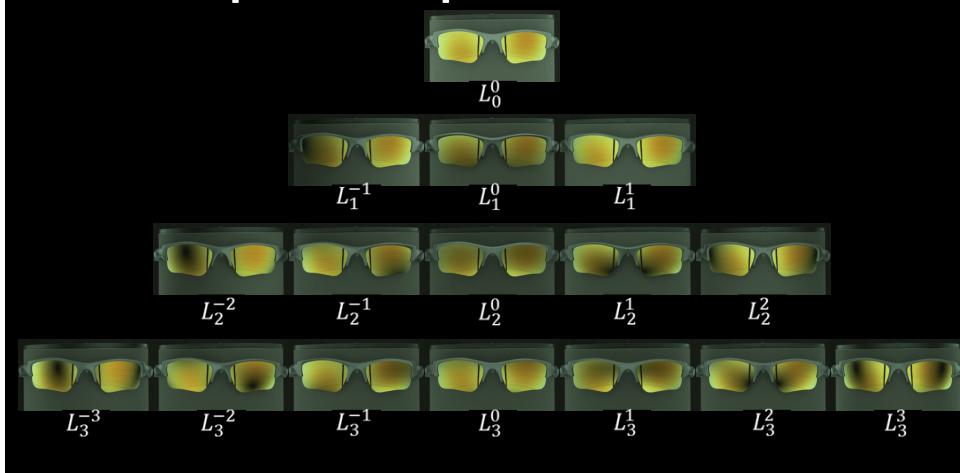
48

Specular response only!



49

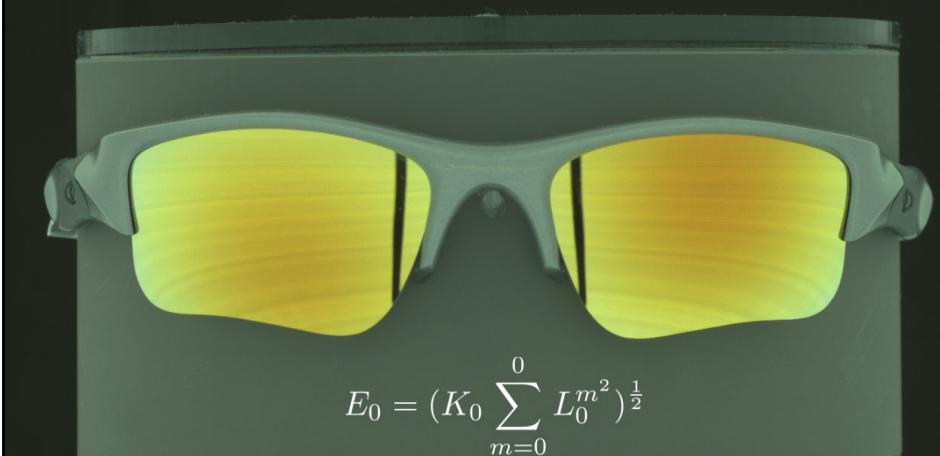
Diffuse-specular separation



50

25

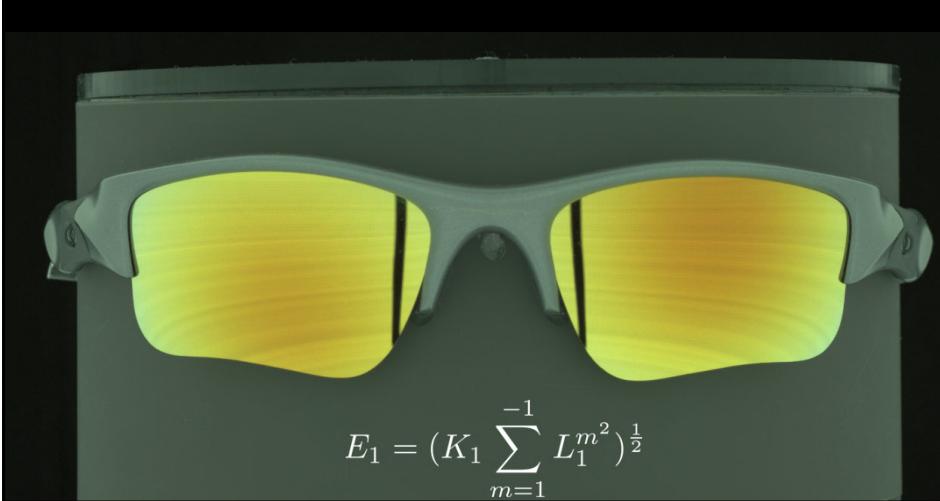
0th order energy



$$E_0 = (K_0 \sum_{m=0}^0 L_0^{m^2})^{\frac{1}{2}}$$

51

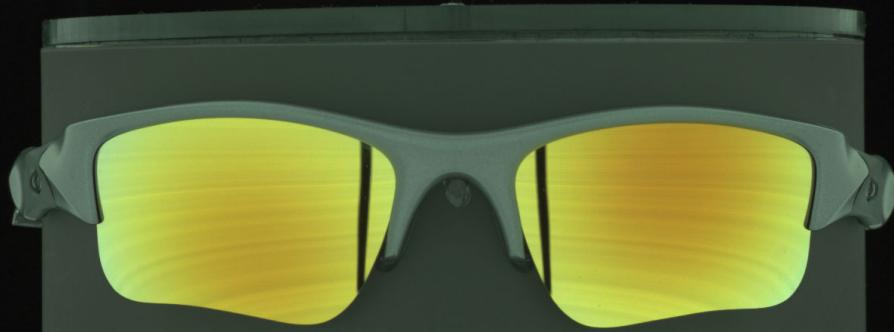
1st order energy



$$E_1 = (K_1 \sum_{m=1}^{-1} L_1^{m^2})^{\frac{1}{2}}$$

52

2nd order energy



$$E_2 = (K_2 \sum_{m=2}^{-2} L_2^{m^2})^{\frac{1}{2}}$$

53

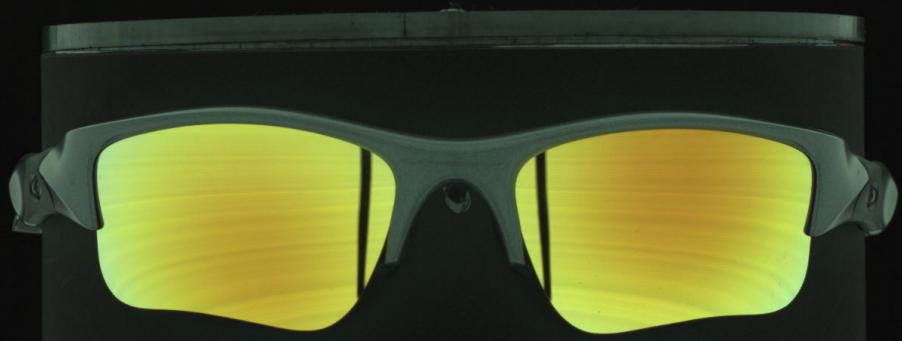
3rd order energy!



$$E_3 = (K_3 \sum_{m=3}^{-3} L_3^{m^2})^{\frac{1}{2}}$$

54

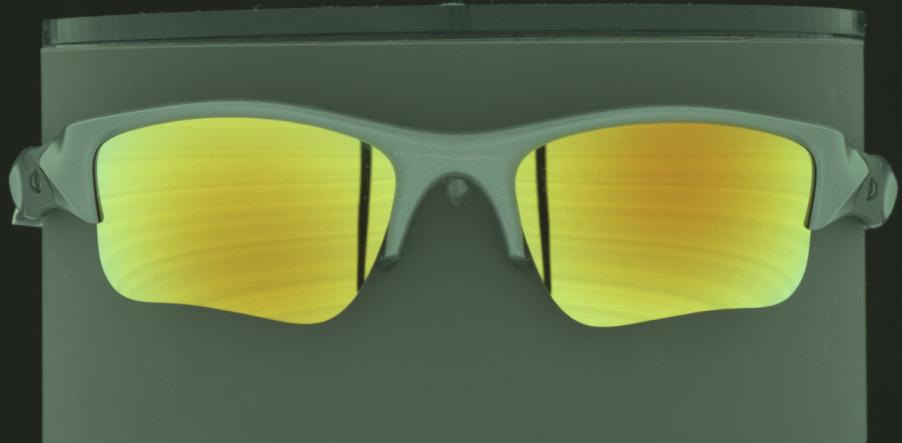
5th order energy!



$$E_5 = (K_5 \sum_{m=5}^{-5} L_5^{m^2})^{\frac{1}{2}}$$

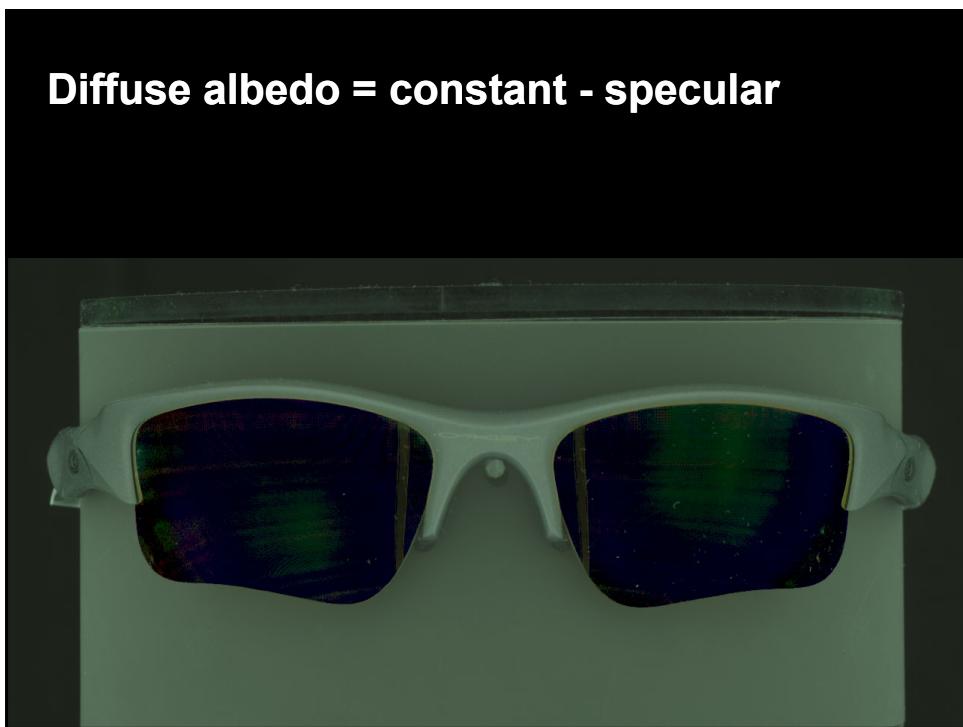
55

Constant illumination



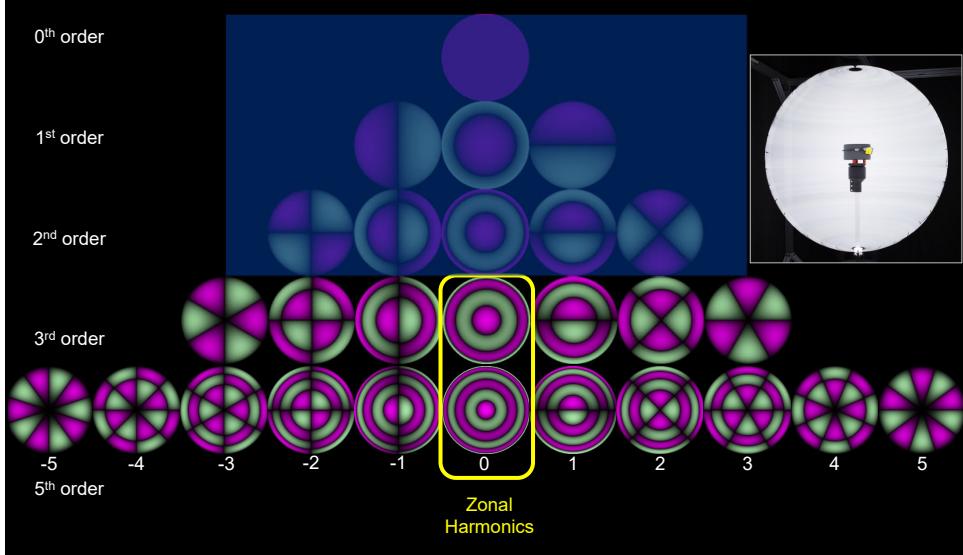
56

Diffuse albedo = constant - specular



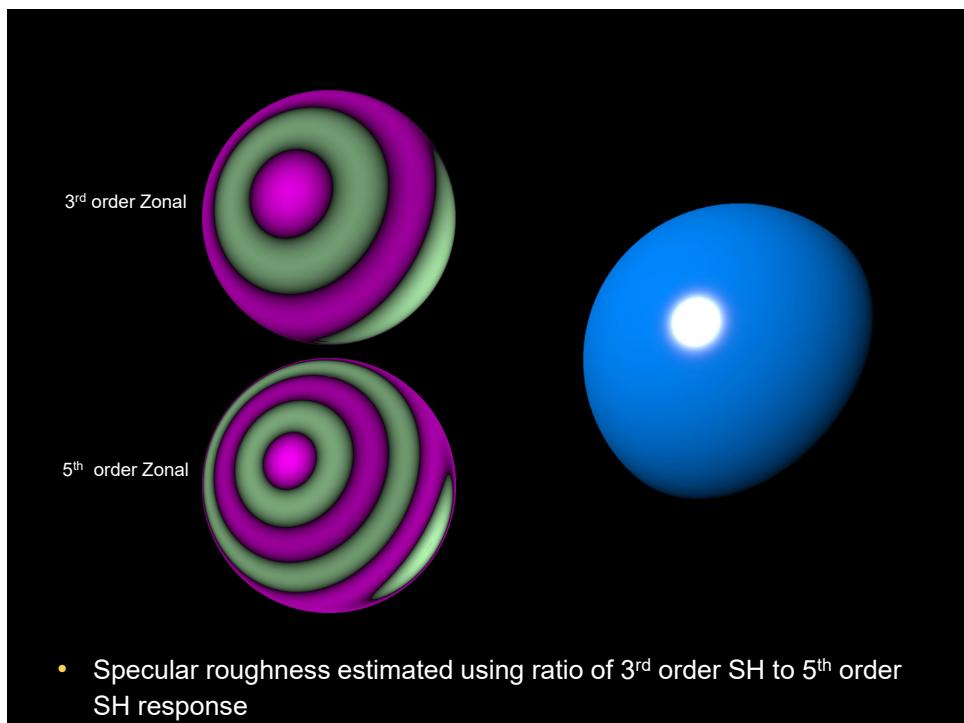
57

Reflectometry from SH

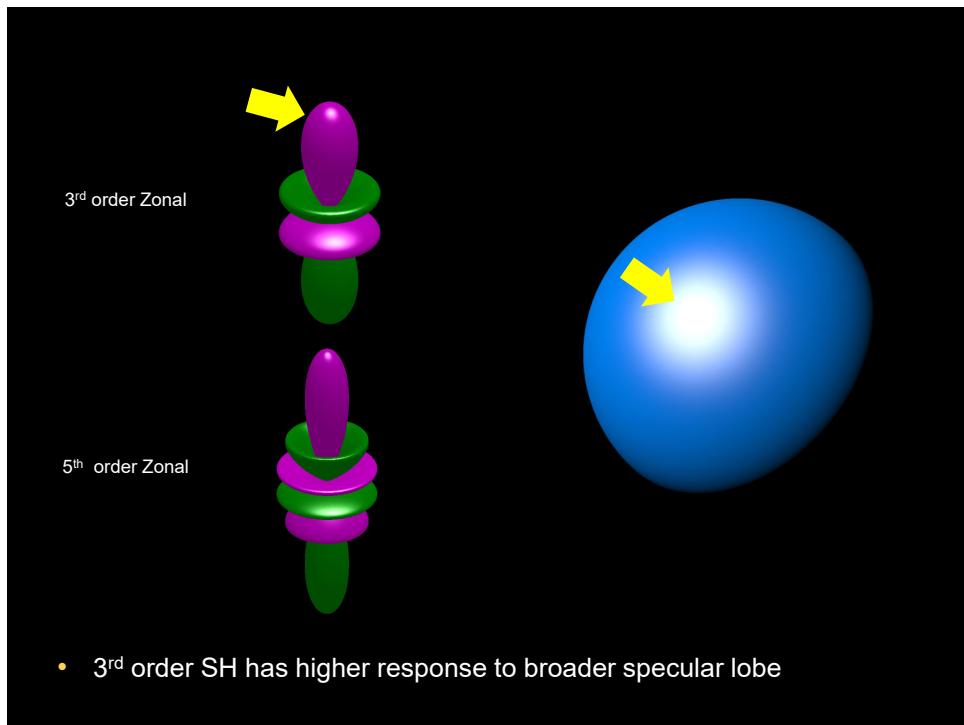


58

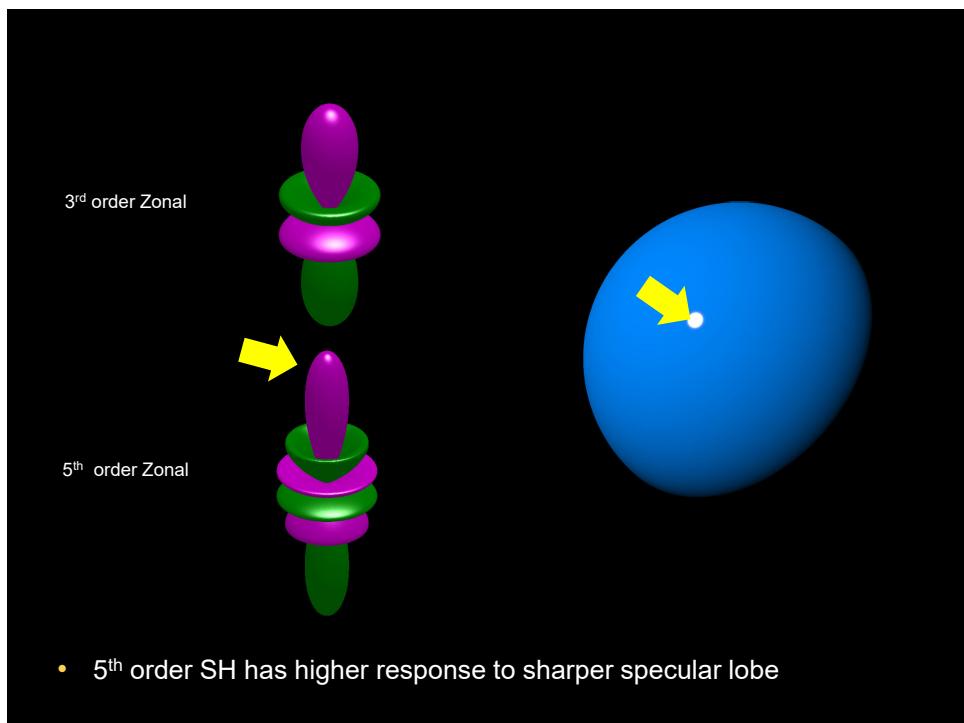
29



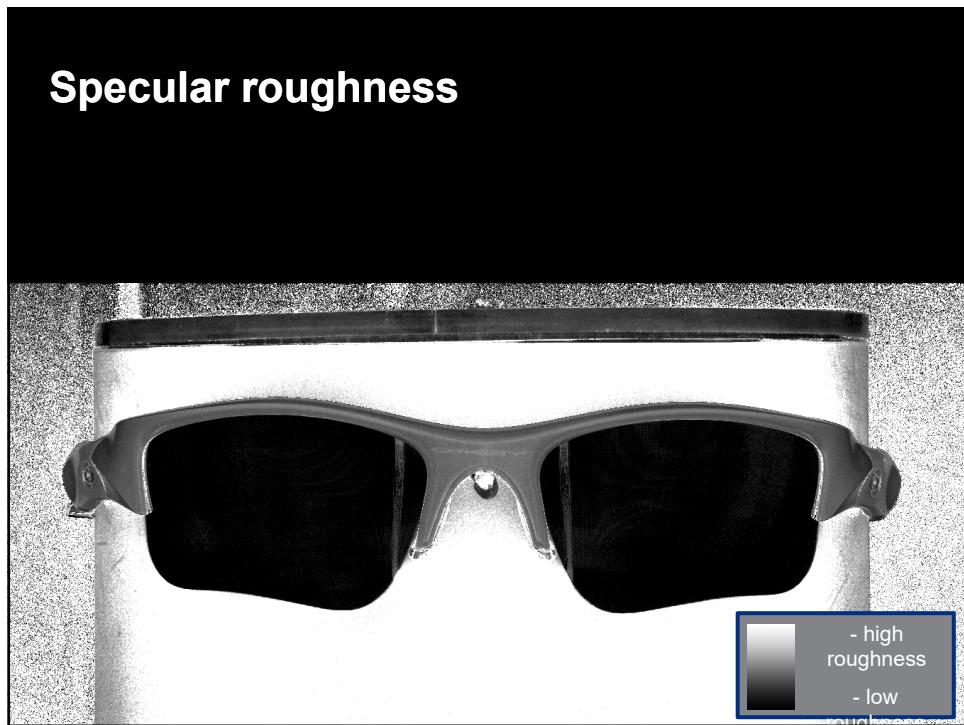
59



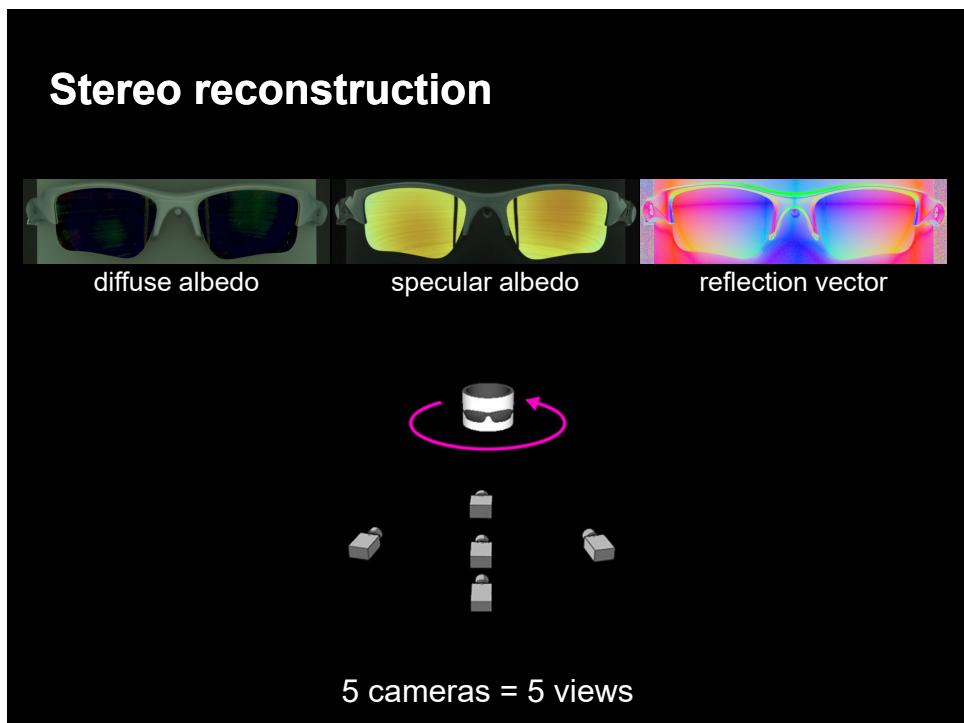
60



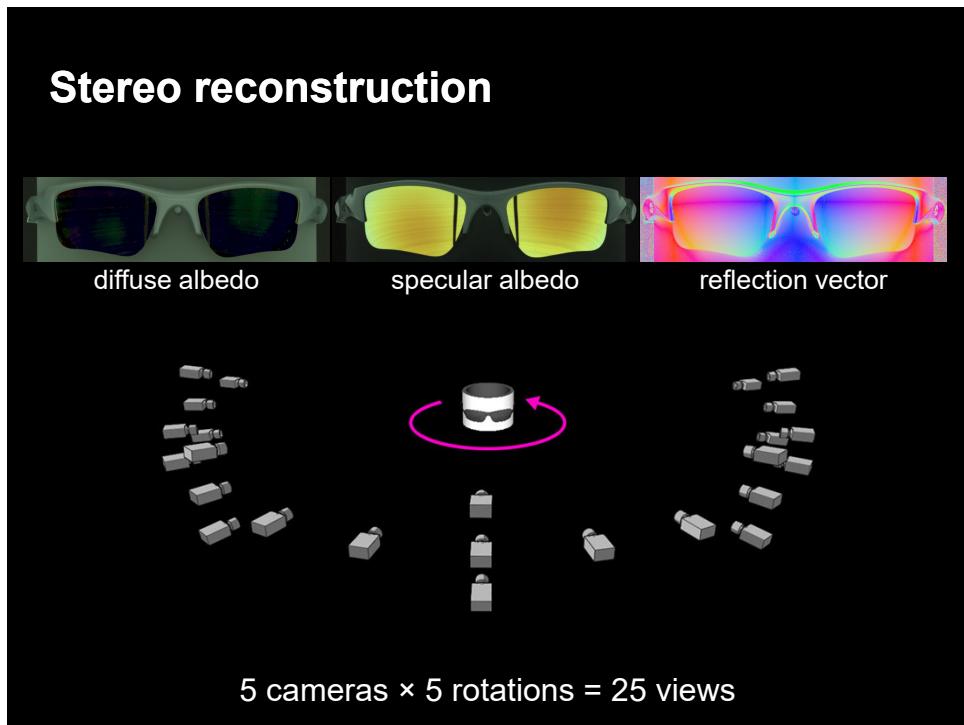
61



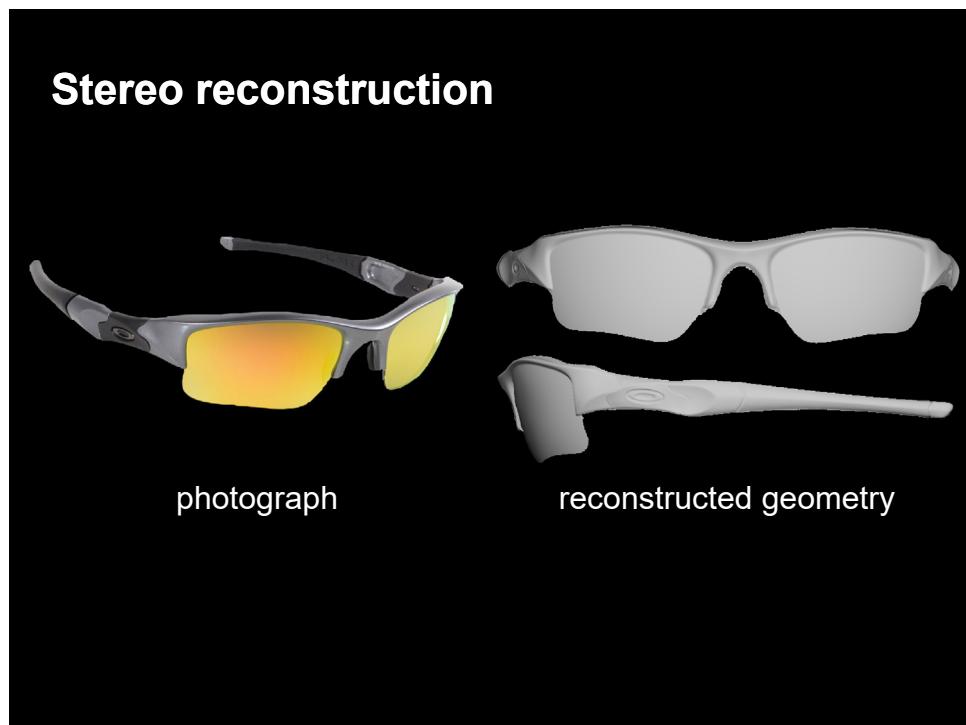
62



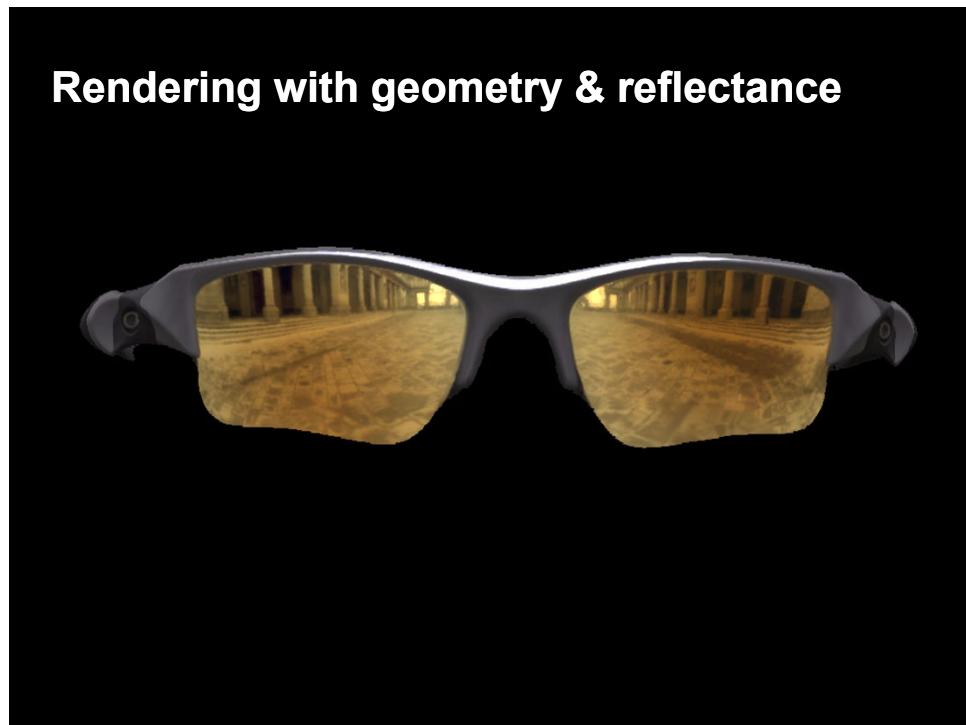
63



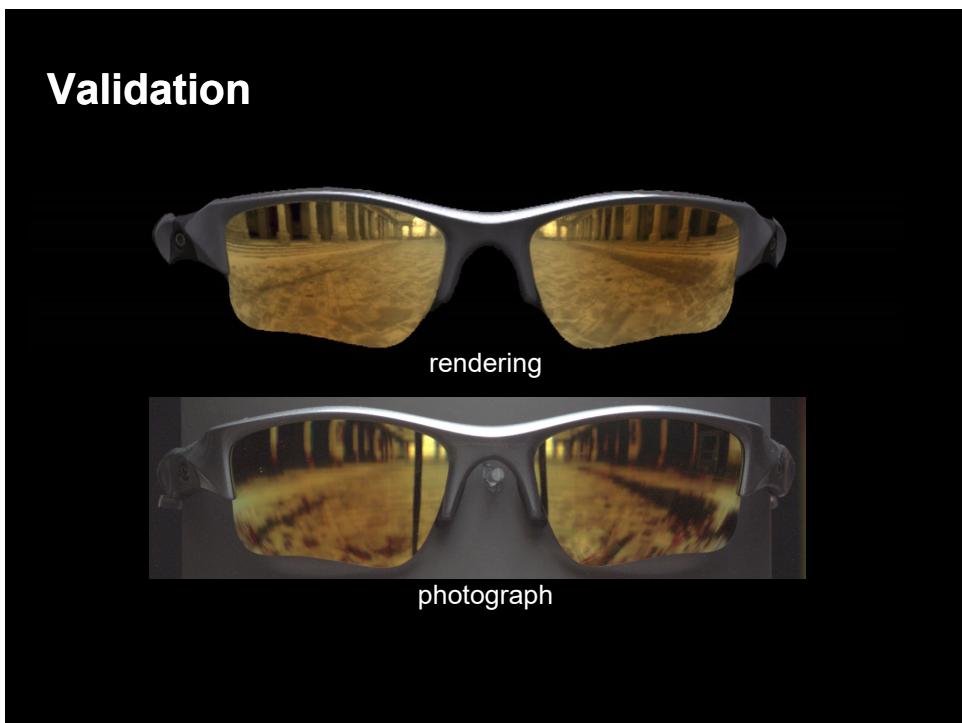
64



65



66



67

Mobile surface reflectometry

- Camera-flash pair
 - backscatter measurements
 - rough specular BRDFs

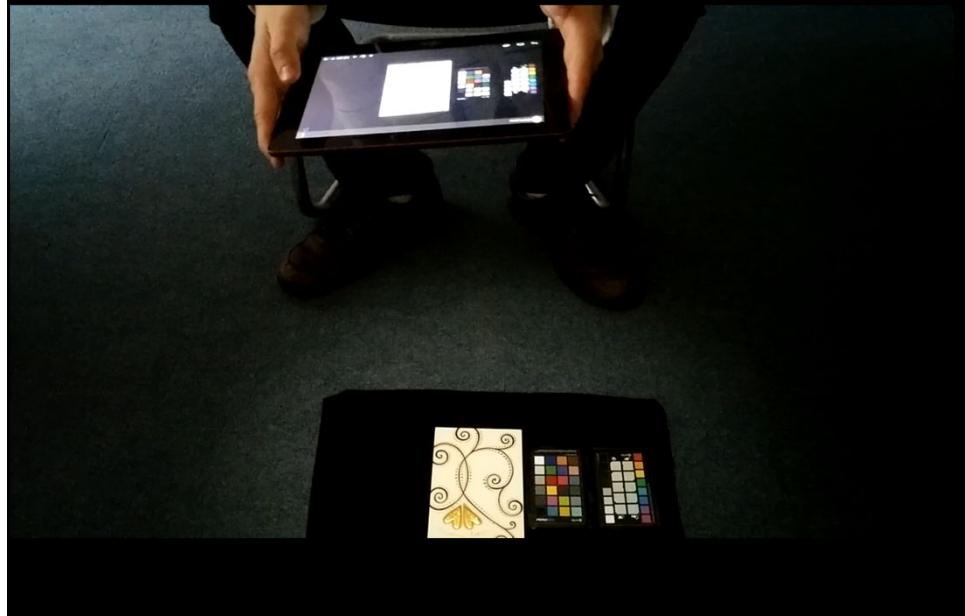
Hand-held acquisition Rendering

J. Riviere, P. Peers, A. Ghosh
Computer Graphics Forum 2016

68

Mobile surface reflectometry

[Riviere et al. 16]

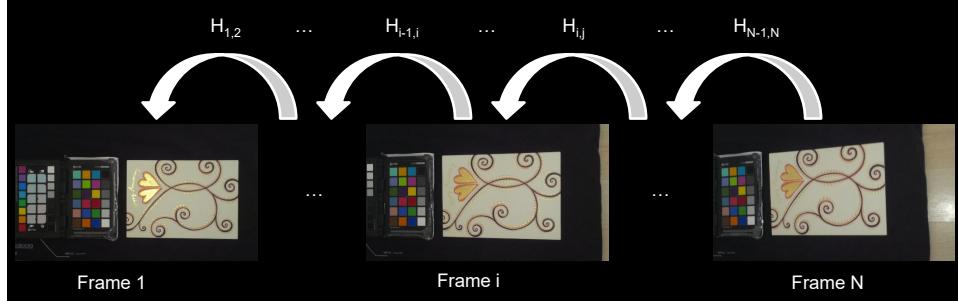


69

Data registration

[Riviere et al. 16]

- Feature extraction (Harris corners)
 - Matched with optical flow
- Homography-based warping

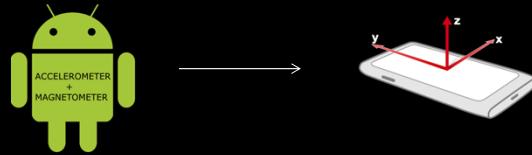


70

[Riviere et al. 16]

Light/view direction estimation

- $\omega_i = \omega_r$ (back scattering direction)
- Android standard API (getRotationMatrix)



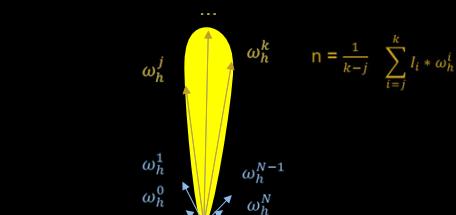
- 3D tracking
 - Simultaneous Localisation And Mapping (PTAM [G. Klein and D. Murray 2007])
 - Limited to feature rich scenes
 - SfM alternate solution

71

[Riviere et al. 16]

Mobile surface reflectometry

- Normal map: Weighted average

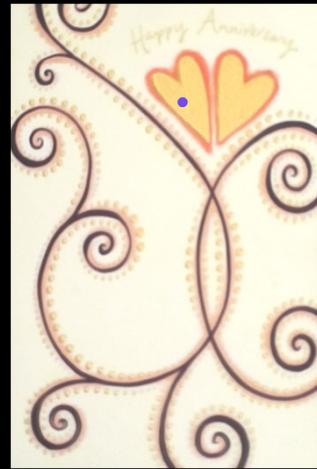
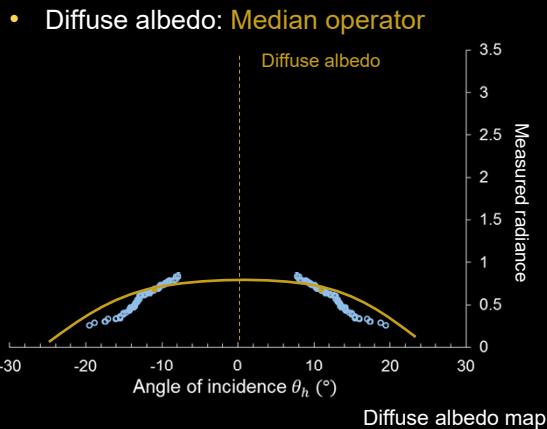


Normal map

72

Mobile surface reflectometry

[Riviere et al. 16]



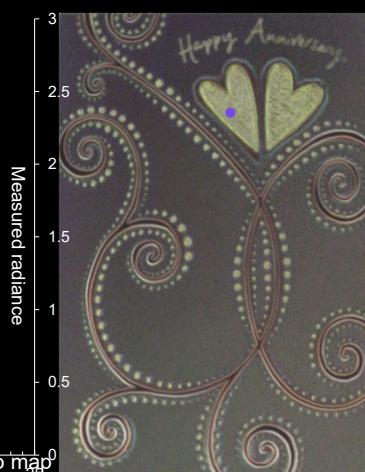
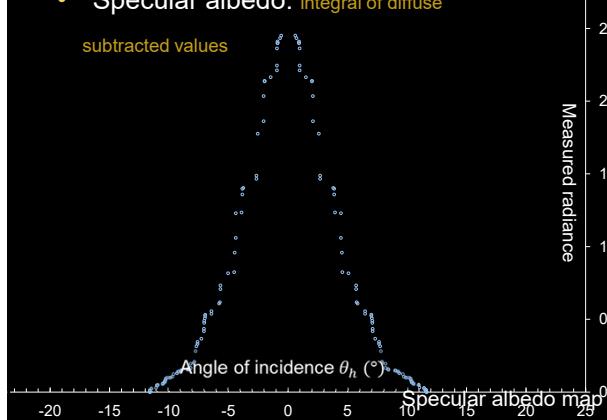
73

Mobile surface reflectometry

[Riviere et al. 16]

- Specular albedo: integral of diffuse

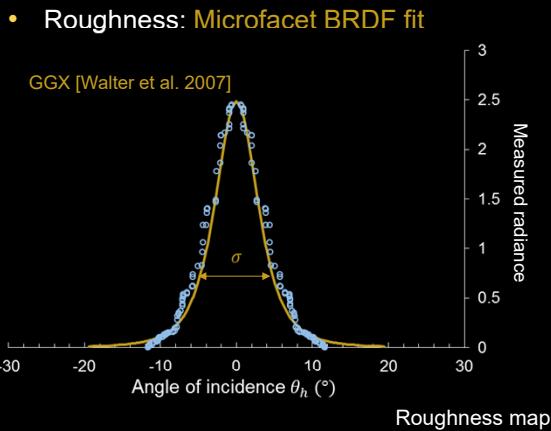
subtracted values



74

Mobile surface reflectometry

[Riviere et al. 16]



75

Mobile surface reflectometry

[Riviere et al. 16]

Rendering – frontal view

$$\omega_i = \omega_r \uparrow n$$



76

Mobile surface reflectometry

[Riviere et al. 16]

Rendering – novel view



77

Mobile surface reflectometry

[Riviere et al. 16]

Rendering – novel view



78

39

Summary for SVBRDF measurement

- Linear light sources
 - Hand held acquisition
 - Measure and fit – analytic or data-driven
- Frequency domain analysis
 - Second order statistics (with polarization)
 - Higher order spherical harmonics (without polarization)
- Hardware setups
 - LED sphere/arc, LCD panels
 - Mobile devices!

79

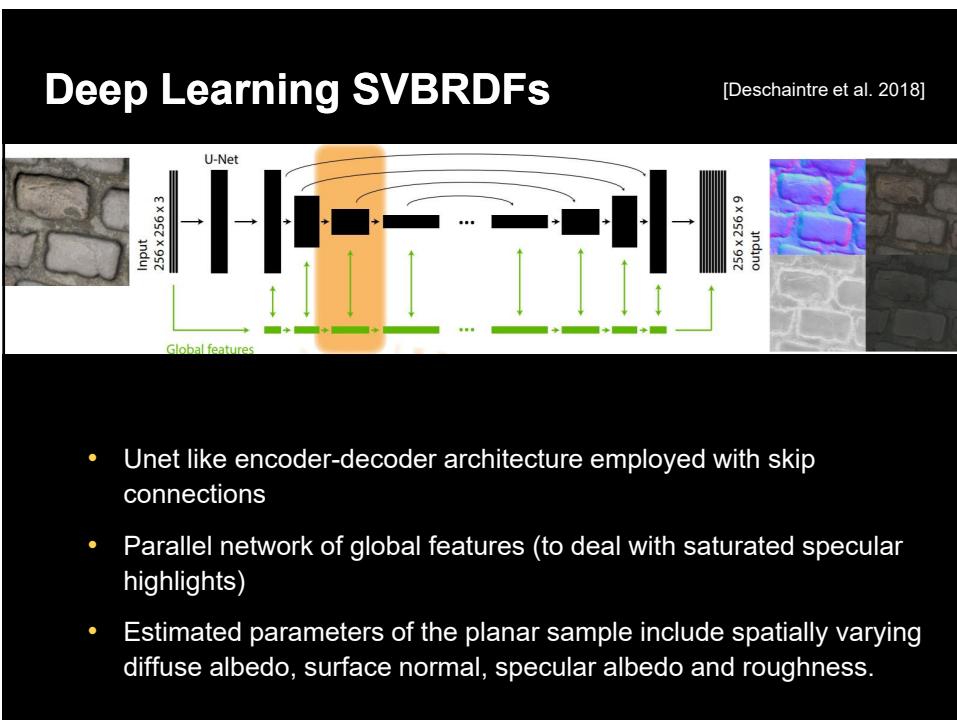
Deep Learning SVBRDFs

[Deschaintre et al. 2018]

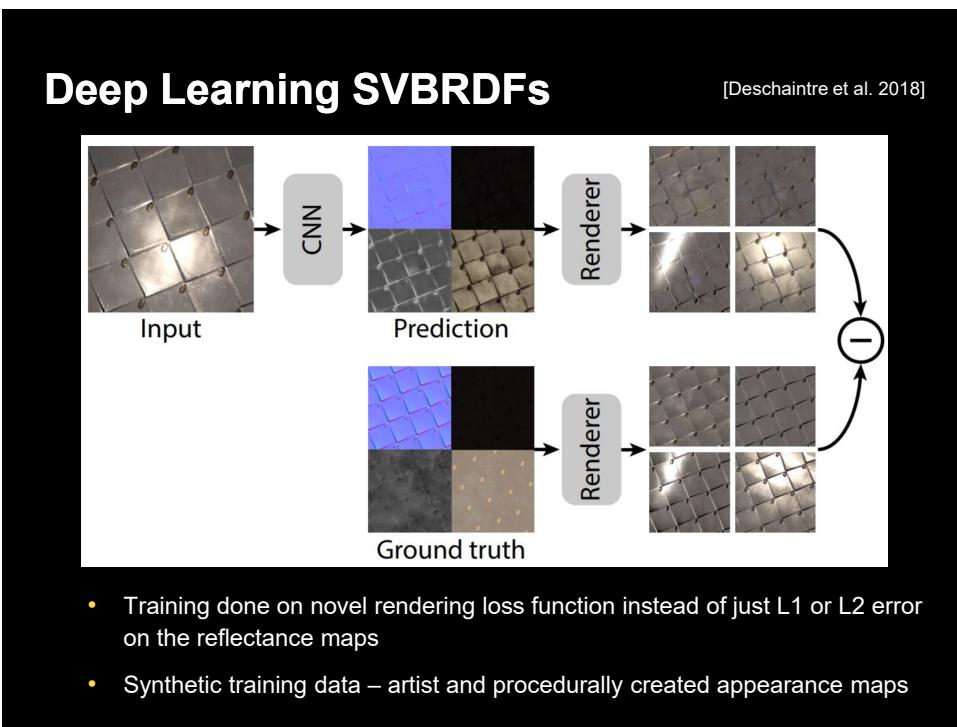


- U-net applied to predict the spatially varying appearance parameters of a planar sample seen under flash illumination.
- Estimated parameters of the planar sample include spatially varying diffuse albedo, surface normal, specular albedo and roughness.

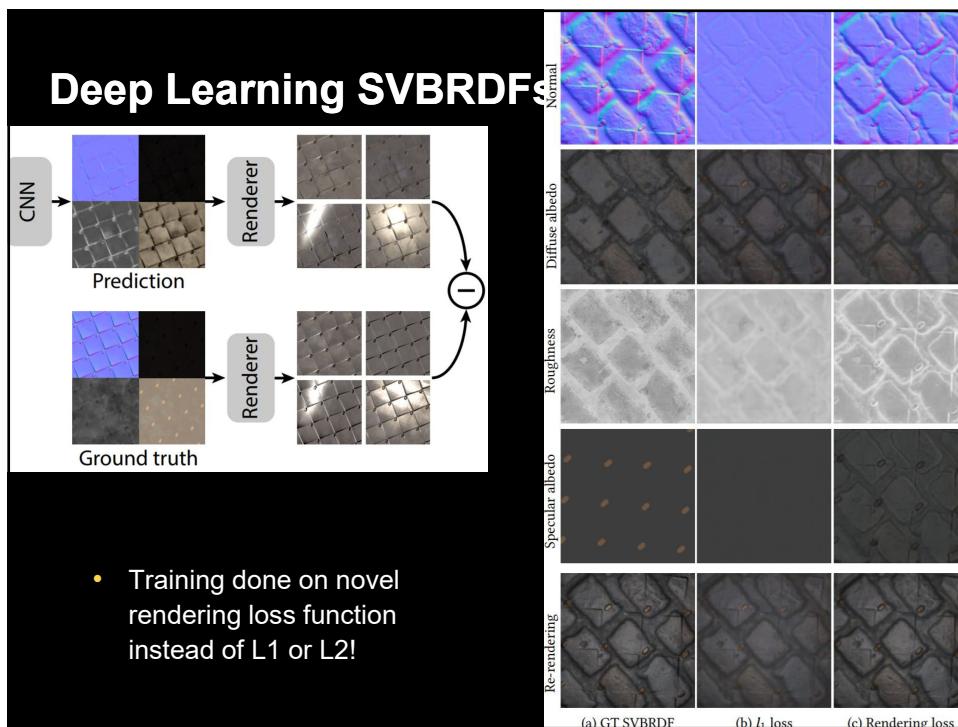
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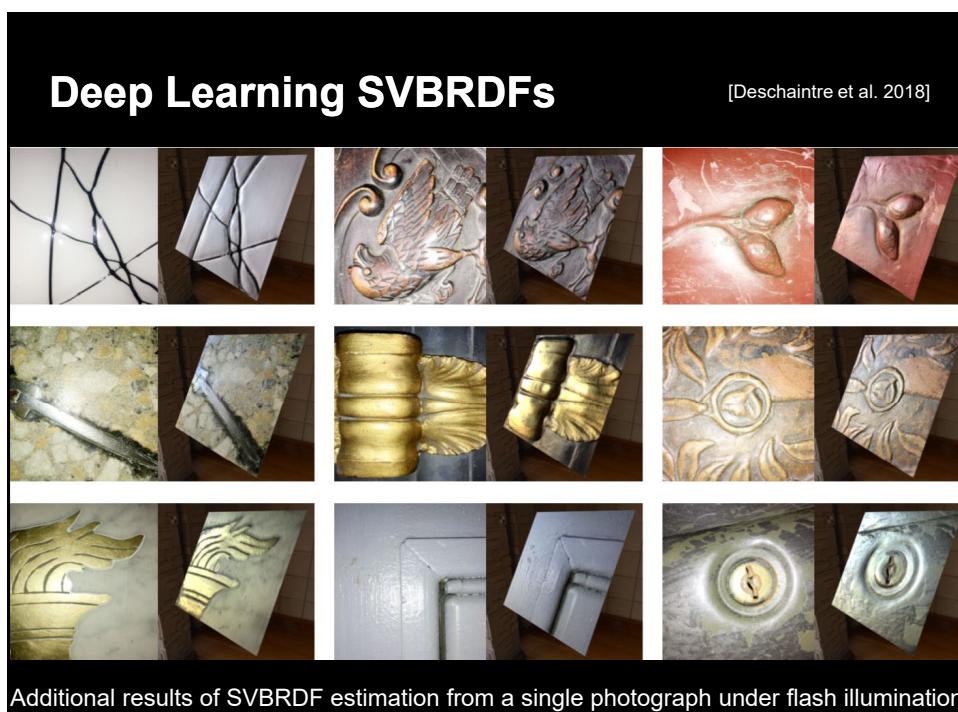
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