# **B-Trees**

# **Balanced Binary Search Tree**

- H = O(Log(N)). Insert, remove, and search all have complexity of  $O(log(n)) = O(Log_2(N))$
- Each Node has a maximum of 2 children

## **C-ary Tree in Tree**

- $N = C^0 + C^1 + \ldots + C^H$
- $ullet N = rac{C^{H+1}-1}{C-1} pprox C^H$
- So  $Hpprox log_{\in}(H)=rac{Log_2(N)}{Log_2(C)}$
- If we increase the max number of children from 2 to C and maintain a balanced tree, the height is reduced by  $(Log_2(C))$

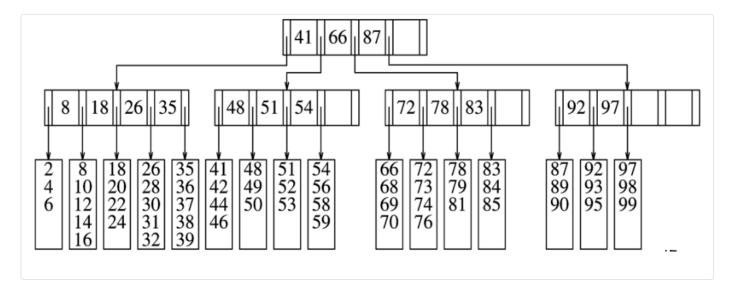
## **M-ary Trees**

- Allow up to M children for each node
  - Instead of 2 max for binary trees
- ullet A complete M-ary tree of N nodes has a depth of  $log_M N$
- Each node has (M-1) keys to decide which branch follows
- Larger M, smaller tree depth
- Balancing M-ary
  - 1. Restrict the tree shape like in AVL
  - 2. Restrict the number of children each node can have
- B-Tree takes the second approach, easier to implement

### **Balanced Trees (B-Tree)**

- B-Tree is an M-ary search tree with restrictions
  - 1. Data items stored at the leafs
  - 2. Non-lead nodes store up to M-1 Keys to guide search
  - 3. The root can be a leaf or have between 2 to M children
  - 4. Non lead Nodes except the root have between ceil M/2 and M children
  - 5. All leaves are at the same depth, have between ceil(L/2) and L data items

 Keys in each node are sorted. The i'th key in a node is the smallest data in the i+1 subtree



#### **Deletion**

- Do a search to find the leaf node to delete
- If the lead still has at least L/2 data entries, done
- Else, merge the data with neighboring leaf to ensure L/2 data entries

