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RAPL in Action: Experiences in Using RAPL for Power Measurements

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To improve energy efficiency and comply with the power budgets, it is important to be able to measure the power consumption of cloud computing servers. Intel's Running Average Power Limit (RAPL) interface is a powerful tool for this purpose. RAPL provides power limiting features and accurate energy readings for CPUs and DRAM, which are easily accessible through different interfaces on large distributed computing systems. Since its introduction, RAPL has been used extensively in power measurement and modeling. However, the advantages and disadvantages of RAPL have not been well investigated yet. To fill this gap, we conduct a series of experiments to disclose the underlying strengths and weaknesses of the RAPL interface by using both customized microbenchmarks and three well-known application level benchmarks: *Stream*, *Stress-ng*, and *ParFullCMS*. Moreover, to make the analysis as realistic as possible, we leverage two production-level power measurement datasets from the *Taito*, a supercomputing cluster of the Finnish Center of Scientific Computing and also replicate our experiments on Amazon EC2. Our results illustrate different aspects of RAPL and document the findings through comprehensive analysis. Our observations reveal that RAPL readings are highly correlated with plug power, promisingly accurate enough, and have negligible performance overhead. Experimental results suggest RAPL can be a very useful tool to measure and monitor the energy consumption of servers without deploying any complex power meters. We also show that there are still some open issues, such as driver support, non-atomicity of register updates, and unpredictable timings that might weaken the usability of RAPL in certain scenarios. For such scenarios, we pinpoint solutions and workarounds.

CCS Concepts: • **Hardware** → **Energy metering**; **Enterprise level and data centers power issues**; **Emerging architectures**; • **Computer systems organization** → *Cloud computing*;

Additional Key Words and Phrases: RAPL, power modeling, RAPL accuracy, RAPL validation, DRAM power

ACM Reference format:

Kashif Nizam Khan, Mikael Hirki, Tapio Niemi, Jukka K. Nurminen, and Zhonghong Ou. 2018. RAPL in Action: Experiences in Using RAPL for Power Measurements. *ACM Trans. Model. Perform. Eval. Comput. Syst.* 3, 2, Article 9 (March 2018), 26 pages.

<https://doi.org/10.1145/3177754>

Author Kashif Nizam Khan would like to thank Nokia Foundation for a grant which helped to carry out this work. Author Zhonghong Ou would like to thank the Fundamental Research Funds for the Central Universities and National Natural Science Foundation of China (Grant No. 61702046) for the support. The authors would also like to thank CSC, IT Center for Science, Finland for the datasets.

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<https://doi.org/10.1145/3177754>

1 INTRODUCTION

Energy efficiency in data centers has become one of the major concerns in the past decade, not only because of the monetary cost but also for environmental sustainability. The electricity consumption of data centers is constantly increasing and there is an urge to apply optimizations in hardware and software to achieve the best performance per watt.

As such, a number of studies have been directed toward predicting and/or modeling energy consumption in large-scale data centers [24, 31, 43]. Many such models or prediction techniques require an accurate measure of the energy consumption of the data center on the go. Until recently, measuring the power consumption of a computer system required separate metering hardware [3]. Besides the difficulties of purchasing, deploying, and using external power meters, their measuring accuracy and granularity are usually inadequate for detailed analysis. Moreover, dividing the power to different parts of the computing system inside the chip is not possible. There are also tools like the Intelligent Platform Management Interface (IPMI), which reports the power measurement readings through sensors mounted with the system. Existing studies [21] find that the accuracy of such sensors is not promising and therefore these sensors cannot be practically used as a substitute for more accurate watt meters on a per-machine basis.

The other option is model-based power estimation, which uses a set of performance counters and a computational model to turn the performance readings into estimates of electricity consumption. The accuracy of this approach strongly depends on the quality of the model and typically is not able to give good results, especially with highly fluctuating workloads [30]. McCullough et al. [30] performed a comprehensive evaluation of the power modeling of computing systems and concluded that power modeling techniques pose several limitations caused by the increased complexity and variability of software and hardware. Their results motivate more toward low cost, direct, and instantaneous energy measurement tools.

Intel's Running Average Power Limit (RAPL) [40] is one such hardware feature that allows us to monitor energy consumption across different domains of the CPU chip, attached DRAM, and on-chip GPU with promising accuracy. This feature was introduced in Intel's Sandy Bridge architecture and has evolved in the later versions of Intel's processing architecture. With RAPL, it is possible to programmatically get real-time data on the power consumption of the CPU package and its components, as well as of the DRAM memory that the CPU is managing. RAPL is thus a good tool to measure, monitor, and react to the power consumption of computing. It has potential for new and innovative ideas to better deal with the electricity consumption of computing [24, 38, 43]. Skrenes et al. [36] use RAPL as an "always on" energy-metering tool in their proposed speed-scaling simulator, *Profilo*. *Profilo* measures the energy consumption of the CPU with a goal to quantify the differences between different speed-scaling strategies and uses RAPL as an effective measurement tool in their automated simulation process. Kelley et al. [22] use RAPL as a power-tracing tool to profile peak power under core scaling, which reduces the profiling time significantly. Their approach shows that RAPL measurements are reliable enough to be used as a power-measurement tool as they use RAPL to collect the power trace for a sampling period and then this trace is used to predict peak power under different settings and across different architectures.

Despite the merits and potentials of RAPL, it is not clear whether RAPL also has weaknesses in measuring and monitoring the energy consumption of various CPU components. Thus, an in-depth study of the RAPL interface itself is still needed to reveal its underlying principles. In this article, we conduct a thorough study of RAPL by utilizing a series of customized benchmarks, and two well-known application-level benchmarks, that is *Stream* and *ParFullCMS*. To make the analysis as realistic as possible, we leverage a production-level power measurement dataset from the

Taito supercluster of the Finnish Center of Scientific Computing (CSC) and also use five different instance types from Amazon EC2 as testbeds.

This article substantially enhances the work presented in References [17, 23, 24]. In addition to the prior works, in this article, we analyze RAPL's capability to predict the full-system power consumption with different modeling techniques using the large CSC dataset. The in-depth analysis of RAPL as an energy measurement tool in terms of different aspects like performance overhead or high sampling rate is also a significant addition. Last, the RAPL measurement experiences with Amazon EC2 is a considerable enhancement. In summary, we make the following major contributions in this work:

- (1) With detailed measurements, we investigate the accuracy, granularity, and performance of the RAPL measurements. Accuracy of RAPL measurements is measured by determining how closely the RAPL measurements predict the overall power consumption of the system. The "closeness" or "predictability" of RAPL's measurement is obtained through modeling and fitting the RAPL measurements with full-system power consumption obtained from high-accuracy external power meters.
- (2) We also highlight a few aspects that need to be considered for the proper use of RAPL, as well as issues that would require further development.
- (3) We pinpoint a few major differences in the performance, granularity, and accuracy of RAPL in different Intel architectures: Sandy Bridge, Haswell, and Skylake.
- (4) We present a study of RAPL's performance in virtualized cloud computing environment using Amazon EC2.

Key findings from our study are listed below:

- (1) The promising accuracy of RAPL measurements to predict full-system power consumption is established by modeling the full-system power consumption from RAPL readings using a large production dataset from CSC.
- (2) The performance overhead of RAPL measurements is considerably low and negligible.
- (3) There is a measurable correlation between RAPL's package power and temperature, at least in the Haswell architecture.
- (4) In the case of Skylake, RAPL updates the PP0 domain in the order of μs ($\approx 50\text{--}70\mu s$).
- (5) RAPL's support in Amazon EC2 can be useful but it needs more careful considerations.

The rest of the article is organized as follows: Section 2 presents detailed information about RAPL in general. Section 3 highlights the related literature. Section 4 discusses the experimental setup and benchmark specifications. In Section 5, we discuss the good aspects of RAPL such as its accuracy, granularity, and so on. Section 6 discusses the weak aspects of RAPL. We also discuss possible solutions to overcome a few of the weak aspects of RAPL in Section 6. In Section 7, we present RAPL measurement results and experiences with Amazon EC2 instances. Section 8 summarizes our findings, and Section 9 presents the conclusion with possible future directions.

2 RUNNING AVERAGE POWER LIMIT

The RAPL interface is a feature introduced in the Intel Sandy Bridge architecture. Generally speaking, RAPL provides two different functionalities. First, it allows energy consumption to be measured at very fine granularity and a high sampling rate. Second, it allows limiting (or capping) the average power consumption of different components inside the processor, which also limits the thermal output of the processor [40]. We will focus on the energy-measuring functionality in this article.

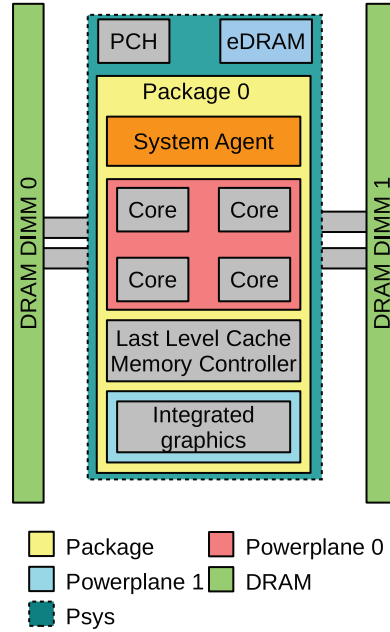


Fig. 1. Power domains supported by RAPL.

RAPL supports multiple power domains. The RAPL power domain is a physically meaningful domain (e.g., Processor Package, DRAM, etc.) for power management. Each power domain informs the energy consumption of the domain, allows us to limit the power consumption of that domain over a specified time window, monitors the performance impact of the power limit, and provides other useful information, that is, energy measurement units, minimum or maximum power supported by the domain [20].

Figure 1 shows the hierarchy of the power domains graphically. RAPL provides the following power domains for both measuring and limiting energy consumption:

- **Package:** Package (PKG) domain measures the energy consumption of the entire socket. It includes the consumption of all the cores, integrated graphics and also the uncore components (last level caches, memory controller).
- **Power Plane 0:** Power Plane 0 (PP0) domain measures the energy consumption of all processor cores on the socket.
- **Power Plane 1:** Power Plane 1 (PP1) domain measures the energy consumption of processor graphics (GPU) on the socket (desktop models only).
- **DRAM:** DRAM domain measures the energy consumption of random access memory (RAM) attached to the integrated memory controller.
- **PSys:** Intel Skylake has introduced a new RAPL Domain named PSys. It monitors and controls the thermal and power specifications of the entire SoC and it is useful especially when the source of the power consumption is neither the CPU nor the GPU. As Figure 1 suggests, PSys includes the power consumption of the package domain, System Agent, PCH, eDRAM, and a few more domains on a single-socket SoC.

For multi-socket server systems, each socket reports its own RAPL values (for example, a two-socket computing system has two separate PKG readings for both the packages, two separate PP0 readings, etc.).

Table 1. Comparison of RAPL Power Domains Supported by Different Intel Processor Models

Model	Power domain supported?				
	PKG	PP0	PP1	DRAM	PSys
Sandy Bridge	yes	yes	yes	No	No
Sandy Bridge-EP	yes	yes	No	yes	No
Haswell	yes	yes	yes	yes	No
Haswell-EP [12]	yes	No	No	yes	No
Skylake	yes	yes	yes	yes	yes*

The -EP models are server-grade processors.

*Not All Skylake versions support PSys.

```

uint64_t msr_value;
/* Haswell: units of 61 microjoules */
/* MSR_PKG_ENERGY_STATUS is at address 0x611 */

double energy_units = pow(0.5, 14);
int fd = open("/dev/cpu/0/msr", O_RDONLY);
if (fd < 0) {
    perror("open");
    return -1;
}
if (pread(fd, &msr_value, 8, 0x611) < 0) {
    perror("pread");
    return -1;
}
double energy = msr_value * energy_units;
printf("%f\n", energy);

```

Listing 1. Reading RAPL package energy using the MSR method on Haswell.

The support for different power domains varies according to the processor model. Table 1 presents a comparison of RAPL domains supported by different models. Power Plane 1 is present only in desktop models. In Haswell, Intel added support for the DRAM domain to desktop models. Both Power Planes 0 and 1 are absent in the Haswell server models. Thus, the only universally supported power domain is the Package domain. In the case of Skylake, unlike PKG, PSys requires an additional system-level implementation, and so it is not supported in all Skylake versions.

The RAPL energy counters can be accessed through model-specific registers (MSRs). The counters are 32-bit registers that indicate the energy consumed since the processor was booted up. The counters are updated approximately once every 1ms. The energy is counted in multiples of model-specific energy units. Sandy Bridge uses energy units of $15.3\mu\text{J}$, whereas Haswell and Skylake uses units of $61\mu\text{J}$. In some CPU architectures such as Haswell-EP, DRAM units differ from CPU energy units. The units can be read from specific MSRs before doing energy calculations. There is no specific implication of different energy units in different architectures.

The MSRs can be accessed directly on Linux using the *msr* driver in the kernel. Listing 1 shows an example of this. For direct MSR access the MSR driver must be enabled and the read access permission must be set for the driver [40]. Reading RAPL domain values directly from MSRs requires detecting the CPU model and reading the RAPL energy units before reading the RAPL domain (i.e., PKG, PP0, PP1, etc.) consumption values.

Once the CPU model is detected, the RAPL domains can be read per package of the CPU by reading the corresponding “MSR status” register. For example, *MSR_PKG_ENERGY_STATUS* holds the

energy readings for package domain (PKG). There are basically two types of events that RAPL events report: static and dynamic events. Static events reported by RAPL events are thermal specifications, maximum and minimum power caps, and time windows. The RAPL domain energy readings from the chip such as PKG, PP0, PP1, or DRAM are the dynamic events reported by RAPL.

Apart from directly reading MSRs, RAPL readings can also be read from *sysfs* interface, *perf* events, or through the PAPI library. RAPL support for the *sysfs powercap* interface is enabled from Linux Kernel version 3.13 and the *perf_event_open* support requires Linux Kernel version 3.14. PAPI library is used for gathering performance-related data. It is platform independent, and it has a RAPL interface that uses the MSR driver to report RAPL values.

3 RELATED WORKS

Hähnel et al. [14] evaluated whether RAPL can be used to measure short code paths. They showed that RAPL updates do not occur precisely every 1ms but instead they have some jitter. They also compared the RAPL measurements (Sandy Bridge) with external measurements with a manually instrumented board and showed that RAPL measurements do correlate nicely with external measurement with a fixed offset.

Hackenberg et al. [11] provided a comparison of power measurement techniques. They pointed out that the RAPL updates have no timestamps, which can lead to significant inaccuracy when sampling the RAPL counters. They also showed that the Sandy Bridge-EP implementation of RAPL suffers from systematic errors.

In 2015, Hackenberg et al. [13] studied RAPL on the Intel Haswell-EP platform. They compared the accuracy of RAPL between Sandy Bridge-EP and Haswell-EP and showed that Haswell has improved RAPL measurements. They also showed that RAPL measurements correlate very well with external power measurements.

Ilse et al. [19] compared different power measurement techniques, including RAPL and showed that the key advantages of RAPL are: low cost and the ability to isolate the power consumption of the processor package from the rest of the system.

Huang et al. [18] evaluated RAPL for Haswell-EP processors and compared RAPL with traditional power monitoring tools. They showed that monitoring with RAPL using the Performance Application Programming Interface (PAPI) can consume 28.6% more power than an idle system. This is, however, when RAPL is monitored with all its 28 attributes and not all of these attributes are related to power or energy monitoring. They also claimed that if RAPL is monitored with selected attributes (PKG, PP1, PP0, etc.), this power overhead can be reduced by 90%. These measurements, however, do not account for the PAPI library's power consumption and different granularities of RAPL measurements will also affect the energy overhead.

Spencer et al. [6] validated the RAPL DRAM values. We discuss their findings and contributions in Section 6.4 in more detail. Zhang et al. [44] validate RAPL's power limiting features based on stability, accuracy, settling time, overshoot, and efficiency. They show that RAPL power limiting performs well in terms of accuracy, settling time, overshoot and stability. They, however, argue that RAPL power limiting can underperform at low-power limits and with high-power limits it can achieve performance that is within 90% of optimal.

Apart from these studies, there is a significant body of literature [7, 8] that independently verifies the accuracy of RAPL readings with different workloads, architectures, systems, and settings. RAPL has also been quite extensively used in energy profiling [23, 28, 41], full-system power modeling [24, 26], application-level power modeling [43], and power limiting under different scenarios [33, 37, 45].

Table 2. System Specifications

Processor (Intel)	Architecture	Type	Sockets	Cores	L3 Cache	Memory
Core i7-4770 @ 3.40GHz	Haswell	Workstation	1	4	8MB	16GB
i5-6500 @ 3.20GHz	Skylake	Desktop	1	4	6MB	8GB

Some of the above-mentioned studies have performed the analysis of RAPL energy measurements in specific scenarios. In this work, we present a detailed analysis and technical know-how of RAPL with respect to accuracy, granularity, and performance overhead, and we identify the essential issues regarding the usage of RAPL (we term them as “bad” in this article). Our contributions in this work are twofold. First, there are unique discoveries regarding RAPL such as the relation between RAPL power readings and temperature, the non-atomic nature of RAPL updates and the detailed study of RAPL with the CSC data. Second, we also complement and confirm previous observations, such as RAPL performance overhead and RAPL DRAM energy accuracy. We also include our first-hand experience of RAPL in Skylake, which adds to the analysis of previous literature.

4 EXPERIMENTAL SETUP

We used both Haswell- and Skylake-based systems in our experiments. The latest Skylake microarchitecture also supports RAPL [20]. Skylake features higher performance than Haswell and added energy-efficiency features. These factors make Skylake an attractive platform for energy measurement.

Table 2 shows more details of the systems. Haswell was a workstation-grade system, while Skylake was a desktop-grade system. For Haswell, we performed experiments with two software configurations. We first disabled turbo boost, huge-pages, and some background processes to create a simple configuration. Then, we compared this with the default configuration, which had those optimizations enabled. No major differences were found in the RAPL analysis for these two cases. With optimizations (especially turbo boost) enabled, the software ran slightly faster: 2–3% speed difference with the experiments in Table 4. For Skylake experiments, we used the default configuration without disabling any such configurations.

For the analysis of RAPL behavior, we used multiple sources:

Microbenchmarks. We wrote a set of microbenchmarks in our previous article [17]. These benchmarks¹ are designed to exercise specific parts inside the CPU (execution units, caches, and the instruction decoders). Our benchmarks perform simple mathematical operations like *Stream* [29]; however, unlike *Stream* our microbenchmarks do not write anything to memory essentially. The motivation behind writing such microbenchmarks is to examine the power expenditure of a system when different components inside the CPU are exercised with different types of loads and operations. While we previously were specifically interested in the instruction decoder, this time we are using the code as a more generic benchmark. Our benchmark code is published in a Git repository [16].

Application level benchmarks. We also used a few well-known benchmarks namely: *Stream* and *ParFullCMS*. **Stream** [29] is a well-known benchmark designed to measure sustainable memory bandwidth. Using *Stream* helps us understand the characteristics of different systems in terms of power consumption when running a memory intensive task.

Stress-ng is originally designed to stress different subsystems of a computer. In our work,

¹<https://github.com/mhirkirapl-tools>.

we use Stress-ng to stress the CPU cores at 100% load. **ParFullCMS** is a Geant4 [10] benchmark, which is a multi-threaded high energy physics workload. This benchmark employs complex geometry for simulation and essentially exhibits similar properties like Compact Muon Solenoid (CMS) experiments in CERN. Using *ParFullCMS* helps us to understand whether RAPL is able to measure the power consumption of complex scientific applications with acceptable accuracy and granularity.

Traces from data center. We used two data sets from the Finnish Center of Scientific Computing. The datasets are from the production site of CSC data center *Taito* [4]. The first data set contains 0.5Hz sample rate data over a period of 48h and the other one 0.2Hz sample rate data over 10 days. The datasets include the output of the Linux *vmstat* (Virtual memory statistics) tool, RAPL readings, and the plug power consumption for almost 1,000 machines from the *Taito* super cluster (around 460 Haswell computing nodes, around 400 Sandy Bridge computing nodes, and a few other special purpose nodes). *vmstat* vms [1] is a Linux tool, which reports the usage summary of memory, interrupts, processes, CPU usage, and block I/O. We used this dataset to validate the accuracy of RAPL readings.

Measurement Methodology. The RAPL power readings are collected using our *trace-energy* tool. This tool captures the power consumption of RAPL package, PP0, PP1, and DRAM domain by reading the corresponding *msr* registers. The frequency of energy tracing is supplied as a command line argument to the tool. The benchmark program/application program for which we want to measure the power consumption is attached to the *trace-energy* tool as a command line argument. For our in-house experiments, we used the *Plugwise* [34] power meter to capture the plug power consumption of the system from the wall socket. This device has the highest frequency of 0.1Hz, and we used the same frequency to capture the power-consumption data. The CSC datasets captured the *vmstat*, RAPL, and plug power from the IMPI tool at a frequency of approximately 0.5Hz and 0.2Hz. The metrics collection for these datasets was done manually. For the continuous collection and analysis of such data, we need high-resolution automatic energy measurement tools, which should ideally work on a cross-platform basis across different hardware and batch job schedulers.

5 GOOD FEATURES OF RAPL

In this section, we discuss desirable features of RAPL such as high accuracy and small performance overhead.

5.1 Accuracy of RAPL Energy Readings

The accuracy of RAPL energy readings is high even though it is based on activity counters [11, 14] and the accuracy varies across different processing architectures.

We performed experiments with the *Stream* benchmark on a Haswell machine that show a strong correlation between RAPL package power and full-system power consumption from the wall socket. The results are presented in Figure 2. The results show that RAPL power values are promisingly accurate, and these values can be used to predict or model full-system power consumption. From Figure 2, we can see that when we run the *Stream* benchmark at different processor frequencies on a Haswell machine, the full-system power consumption from the wall strongly correlates with RAPL package power. The correlation coefficient between the two values is 0.99.

We also compared the accuracy of RAPL using two large datasets collected from a supercomputing cluster containing almost 1,000 computing nodes. The RAPL and IPMI power (plug) readings were collected in the first dataset every 2s for a period of 2 days and in the second data set

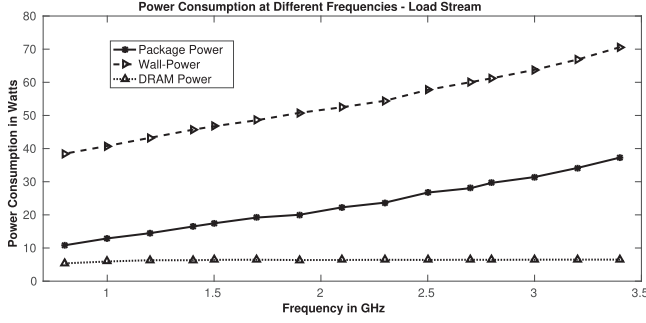


Fig. 2. Wall and RAPL package power consumption with time—*Stream*.

every 5s for a period of 10 days. We tested cross correlation among RAPL values and plug power measurements and noticed that there is a significant time difference between these. Therefore, we computed several lagged plug variables. Since the measurements are strongly autocorrelated, we took a random sample of 30,000 measurements for both SandyBridge and Haswell nodes and divided the sample into 80% training and 20% testing sets. The distribution of plug measurements does not follow any standard distribution very well but the normal distribution gives the best results in the prediction models.

We fitted both linear regression and Generalized Additive Models (GAM) with the data to estimate the plug measurements using the RAPL values. Generalized additive models (GAMs) [42] are regression models in which the expected value of the response variable Y depends on unknown smooth functions of some predictors $x_{1,2,\dots,m}$ as follows:

$$E(Y) = \beta_0 + f_1(x_1) + f_2(x_2) + \dots + f_m(x_m),$$

where β_0 denotes the intercept, and $f_{1,2,\dots,m}$ are smooth functions of covariates.

The benefit of GAM over linear regression is that it can also model non-linear relationships. For the Haswell architecture nodes, we used the following linear regression model:

```
Call: lm(formula = plug.l10 ~ CPU1 + CPU2 + DRAM1 + DRAM2, data = training)
```

Residuals:

Min	1Q	Median	3Q	Max
-215.384	-4.177	-0.155	3.822	214.368

Coefficients:

	Estimate	Std. Error	t value	Pr(> t)
(Intercept)	54.366131	0.530629	102.46	<2e-16 ***
CPU1	1.044694	0.005318	196.46	<2e-16 ***
CPU2	1.078358	0.004627	233.04	<2e-16 ***
DRAM1	0.837673	0.040788	20.54	<2e-16 ***
DRAM2	1.088337	0.040950	26.58	<2e-16 ***

Signif. codes: 0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1

Residual standard error: 11.2 on 22483 degrees of freedom

(1512 observations deleted due to missingness)

Multiple R-squared: 0.9281, Adjusted R-squared: 0.928

F-statistic: 7.25e+04 on 4 and 22483 DF, p-value: < 2.2e-16

And the following GAM model:

```
Family: gaussian
Link function: identity
Formula: plug.l10 ~ s(CPU1) + s(CPU2) + s(DRAM1) + s(DRAM2)
Parametric coefficients:
      Estimate Std. Error t value Pr(>|t|)
(Intercept) 322.95820    0.07159   4511  <2e-16 ***
---
Signif. codes:  0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1
Approximate significance of smooth terms:
      edf Ref.df    F p-value
s(CPU1)  8.755  8.981 2995.61  <2e-16 ***
s(CPU2)  8.905  8.997 5929.64  <2e-16 ***
s(DRAM1)  8.269  8.860   60.09  <2e-16 ***
s(DRAM2)  8.625  8.959   90.40  <2e-16 ***
---
Signif. codes:  0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1
R-sq.(adj) =  0.934   Deviance explained = 93.4%
GCV = 115.43   Scale est. = 115.25    n = 22488
```

For SandyBridge, the models omitted DRAM parameters, since the RAPL does not support them in that architecture.

The best results gave a lag of 10s in the case of Haswell and 24s in SandyBridge. However, we cannot be sure whether this difference is caused by different versions of the IPMI plug power measurement or RAPL itself. The results for the 0.5Hz data set are shown in Table 3. The linear model performs well but GAM still gives slightly better results. This may indicate that the relationship (RAPL and plug) has a small non-linear effect. The large ten day data set gave similar but slightly better results (e.g., MAE 1.0 and RMSE 5.7 for Haswell). However, these are not directly comparable with the 48 hours data set because of different sampling rates.

The regression models for Haswell include DRAM values of RAPL but this feature is not supported in SandyBridge. Therefore, we also tested whether the better accuracy in Haswell is due to the DRAM measurements. Results indicate that DRAM does improve the accuracy but even without DRAM the RAPL seems to perform better in Haswell (mean absolute percentage error 3.1%) than SandyBridge (mean absolute percentage error 4.0%).

When trying to estimate power consumption using only OS counters (vmstat outputs), the results are clearly worse than using RAPL. For SandyBridge, the Mean Absolute Percentage Error (MAPE) using the linear model was 11% and 6% when using a GAM model. The same errors for Haswell were 15% and 5%. These results confirm that RAPL readings are accurate enough to predict full-system power consumption and can provide better estimation models when compared to the models that are based on OS counters.

Studies have also shown that RAPL power readings show promising accuracy. Hackenberg et al. [12] compared the RAPL implementation in Sandy Bridge-EP and Haswell-EP platforms. They compared power consumption predicted by RAPL with calibrated external readings. The results show that RAPL in Sandy Bridge-EP suffers from systematic errors while the Haswell-EP has a nearly perfect correlation with external measurements across all workloads. Therefore, Haswell-EP is clearly a better choice for accurate power estimates. This applies to the entire family of models based on the Haswell microarchitecture, as we have shown here. Similar to our approach, Khan et al. [24] used RAPL package power reading to propose an empirical power model to predict the full-system power.

Table 3. Regression Models for the Plug Power (Mean Absolute Error, Root Mean Square Error, and Mean Absolute Percentage Error)

Model	Architecture	MAE	RMSE	MAPE
Linear	Haswell	5.6	9.8	1.8%
GAM	Haswell	5.2	9.8	1.7%
Linear	Sandy Bridge	10.5	17.2	4.3%
GAM	Sandy Bridge	9.8	16.3	4.0%

Table 4. RAPL Performance Overhead

Application	100Hz	200Hz	500Hz	1,000Hz	1,100Hz
Idq-bench-float-array-l1-schoenauer	0.07%	0.15%	0.35%	0.70%	0.75%
Idq-bench-float-array-l2-schoenauer	0.15%	0.23%	0.42%	0.78%	0.86%
Idq-bench-float-array-l3-schoenauer	0.15%	0.17%	0.40%	0.75%	0.84%
STREAM-NTIMES-2000	0.46%	0.35%	0.89%	1.20%	0.70%
Idq-bench-int-algo-prng	0.07%	0.14%	0.34%	0.66%	0.70%
Idq-bench-int-algo-prng-multi4	0.07%	0.14%	0.34%	0.67%	0.72%

5.2 Performance Overhead

The RAPL energy calculations are implemented in the hardware. There is no need to do any complex calculations, such as numerical integration in the software. Energy consumption can be measured on the same machine without significant overhead. No additional equipment is needed, which makes RAPL a very-low-cost option for energy measurements. We performed experiments to measure the performance overhead caused by RAPL measurements with different applications and measurement frequencies. The results are presented in Table 4.

To measure the RAPL measurement overhead on performance, we used our instruction decoder benchmarks for different caches and data types. In addition, we also used the well-known *Stream* [29] benchmark. For the overhead measurement, we pinned the application and the RAPL measurement program on the same CPU core. In such a manner, the application program will be slowed down depending on the sampling rate of the measurement program. Our *schoenauer* benchmarks are based around the following loop:

$D += A[j] + B[j] * C[j].$

By changing the sizes of these arrays, we can make them fit in the L1, L2, or L3 cache. The *Idq-bench-int-algo-prng* is simply a linear congruential generator used to generate pseudo-random numbers. This code has no dependency on any cache. The *multi4* version has four generators in a single loop, creating a bigger loop. Since switching to another process involves flushing the L1 cache, we expect that the benchmarks with a heavier cache dependency will suffer from a bigger overhead.

Table 4 depicts the percentage performance overhead (wall clock time) for RAPL measurements on frequencies 100, 200, 500, 1,000, and 1,100Hz. As we can see, for *Idq-bench-float-array-l1-schoenauer* the highest performance overhead is 0.75% at 1,100Hz over a normal run when no RAPL measurement is performed. The results follow the same trend for other applications: for *Idq-bench-float-array-l2-schoenauer*, the highest overhead is 0.86% at 1,100Hz, for *Idq-bench-float-array-l3-schoenauer*, the same value is 0.84% and so on. Interestingly, for *Stream*, the highest performance overhead is 1.20%, which occurs at 1,000Hz and for 1,100Hz the overhead is smaller: 0.70%.

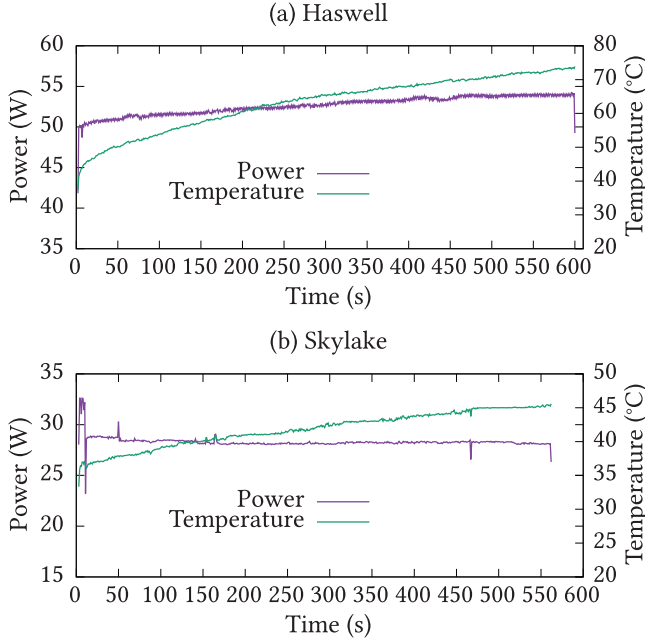


Fig. 3. Package Temperature and Package Power over time with a constant load on CPU.

We tested this 10 times and for every run the result had no significant difference. This might be due to the nature of *Stream*; however, we cannot verify this in the scope of this article. Nevertheless, from Table 4 it is clear that even for a sampling rate of 1,100Hz, the performance overhead will be less than 2% in most cases. Since the overhead is small, it is possible to take advantage of high sampling rates without disturbing the system too much.²

5.3 Correlation with Temperature

We performed experiments to analyze how CPU package temperature relates to package power for both Haswell and Skylake architectures. To do this, we used our own microbenchmark named *idq-bench-float-array-l3-schoenauer*. This benchmark was originally written to stress specific parts inside the CPU such as execution units, caches and the instruction decoders. This benchmark is used here as it exhibits stable and steady power consumption profiles and it also consumes quite a lot of power, which makes the CPU heat up. The results are presented in Figure 3. The temperature and package power data are collected using 250Hz sampling rate. For the sake of simplicity in visualizing data, we take the average of every 50 data points in time so that the trend in data can be visible in the figure.

As Figure 3 indicates, it is important to control the temperature of the CPU to obtain accurate power readings through RAPL. The initial data for Haswell suggests that the package power grows by approximately 10–12% between 37°C and 74°C. In the case of Skylake the package power grows by approximately 8–10% between 23°C and 32°C. We can see that the package power drifts 5–10W for Haswell; however, the Skylake package power readings are quite stable. The correlation

²Note that for calculating the overhead we used “real” time taken for a program to complete (as measured by the *time* command). The RAPL MSR registers are read from user space and the average latency of reading the MSR (*RDMSR* instruction execution + a system call) file is 393ns. So, if RAPL is read from kernel space, the system call time would be eliminated.

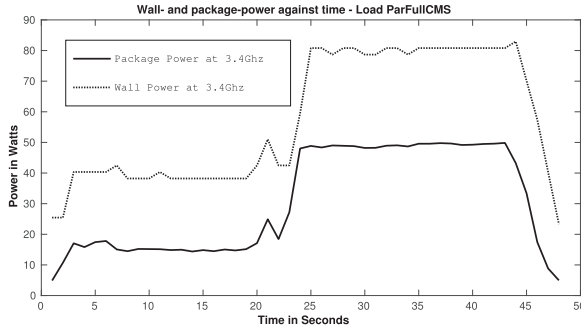


Fig. 4. Wall and RAPL package power consumption with time.

coefficient between Haswell's package reading and temperature is 0.93 and the same for Skylake is 0.34 . The high correlation coefficient for Haswell suggests that in case of Haswell temperature can have a measurable impact on the package power consumption and thus it is important to take the temperature of the system into account while measuring power using RAPL. Skylake have improved this phenomenon and there is a smaller correlation between the package power and temperature. The standard deviation for the Haswell package power reading is 1.29 and for Skylake it is 0.28 . This also confirms that Skylake power draw is fairly stable while the temperature of a system grows. One possible reason for this might be the optimized use of the fan in case of Skylake.

The Linux *coretemp* driver only provides a time resolution of 1Hz. However, the MSR registers for the temperature sensors are actually updated every 1ms. This coincides with the RAPL update interval. There is a good correlation with the RAPL package power and temperature. Nevertheless, Figure 3 shows that CPU temperature can influence the CPU package power draw. To obtain accurate RAPL power readings it would be good to warm up the CPU before obtaining any RAPL measurements. A 2min warm-up period should be enough for any suitable program that keeps the CPU package busy.

5.4 High Sampling Rate

RAPL updates the energy counters approximately once every 1ms, that is, 1,000Hz. This frequency is much higher compared to external power meters that typically measure power only once a second. Servat et al. [35] demonstrated that many HPC benchmarks have phases with different package and DRAM power consumption characteristics. We found that the RAPL sample rate is sufficient to distinguish different execution phases in applications.

We tested this phenomenon with a scientific computing application ParFullCMS benchmark on a Haswell based system. Figure 4 demonstrates that the multi-threaded ParFullCMS has two broad distinct phases: the first phase is the initialization phase, which sets up the events to be processed and consumes relatively less power; the second phase is the compute-intensive phase, which performs the bulk of simulation tasks and consumes relatively more power. It is evident from the figure that RAPL package power sampling is able to capture distinct phases in ParFullCMS like High Energy Physics (HEP) benchmarks. We performed another experiment with *Stress-ng* to compare RAPL's sampling rate with a plug power capturing device. *Stress-ng* was invoked as CPU intensive workload with fluctuating loads. The RAPL PKG consumption value was captured every 5ms and the plug value was captured every 100ms (10Hz is the highest frequency of sampling supported by the Plugwise device we used). The results are presented in Figure 5. The plug power

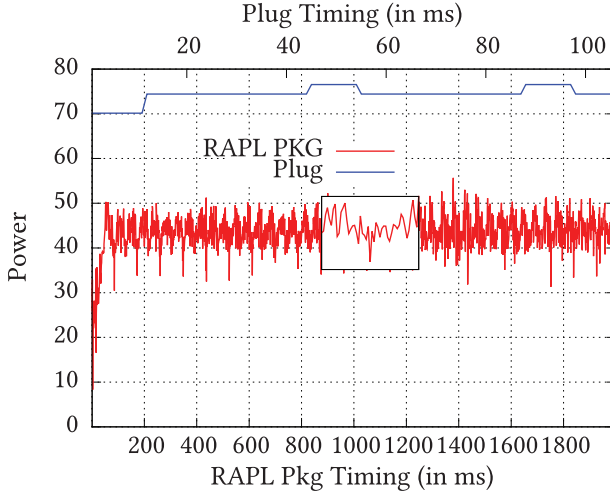


Fig. 5. RAPL Sampling Rate Experiment with Stress-ng.

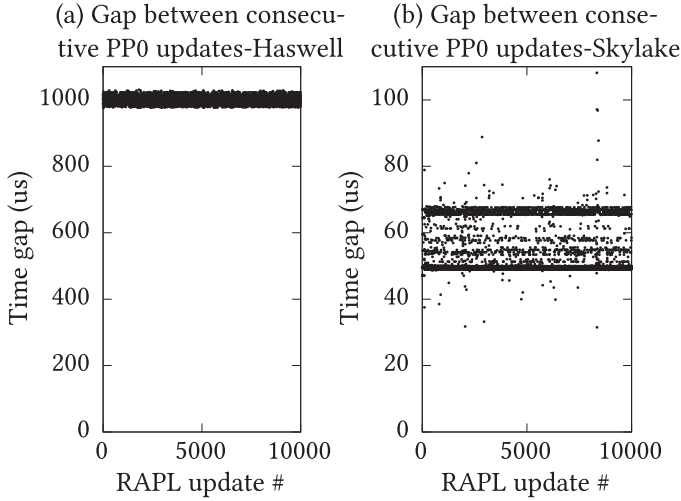


Fig. 6. PP0 sampled every 5ms with a constant load on one CPU core.

metering device was unable to capture the distinct phases as the phases changed faster than the metering device's frequency. RAPL could actually capture the phase changes at a 5ms sampling frequency (RAPL can be sampled in 1ms frequency). The zoomed area of RAPL package power in Figure 5 shows the distinct phase changes in computation (and thus in power consumption) in finer detail.

Our Skylake experiments also reveal that Intel has improved the temporal resolution of PP0 updates in Skylake in comparison to Haswell and previous architectures. PP0 in Skylake updates 20 times on an average in between a single update for other domains (PKG, PP1 and DRAM). Figure 6 shows the time gap between two consecutive PP0 updates in case of Haswell and Skylake for about 10,000 updates. This figure shows that for Haswell most of the PP0 update happen at a time gap of nearly 1ms or $1,000\mu s$, whereas for Skylake the bulk of the updates happen between 50 and

70 μ s with a few outliers. This new improvement for Skylake allows a more granular temporal resolution and as a result it improves the possibility to determine the energy consumption of short code paths.

5.5 Always Running

RAPL starts running as soon as the processor boots up. There is no need to configure it if one wants to measure energy consumption, which makes it very easy to use. Since RAPL is always running, there is very little additional overhead introduced by reading the energy counters.

6 RAPL LIMITATIONS

This section discusses the weaker aspects of RAPL, which should be properly addressed in specific scenarios. We also discuss solutions to overcome these issues in this section.

6.1 Poor Driver Support

Sandy Bridge processors supporting RAPL were released in 2011. Full RAPL driver support was introduced as late as 2013 to the Linux kernel. Currently, there are three ways to read the energy counters on Linux.

As mentioned in Section 2, the *msr* driver supports raw access to any MSR including the RAPL energy counters. It is nearly universally supported regardless of the kernel version. The main drawback is that root access is required to use the *msr* driver. The earlier Listing 1 shows how to access the counters using the *msr* driver. Popular libraries, such as PAPI, rely on the *msr* driver interface. Thus, root access is also required when using these libraries.

The *powercap* driver allows reading the energy counters and configuring the power consumption limits. The counters can be found under `/sys/devices/power/events/`. They can be read without root access. The *powercap* driver was introduced in the kernel version 3.13.

The performance events (also called `perf_events`) subsystem in the Linux kernel supports RAPL energy counters since the kernel version 3.14. This allows the Perf tool to read the counters. Weaver [39] provided an example of how to programmatically read the counters using the `perf_events` API.

6.2 Register Overflows

The energy counters are limited to 32bits even though the MSRs are 64bit wide. Therefore, they will eventually overflow. Fortunately, these overflows are quite rare. We can calculate the time to overflow t_{overflow} using the following equation:

$$t_{\text{overflow}} = \frac{2^{32} \times E_u}{P}. \quad (1)$$

Here, E_u is the energy units used (61 μ J for Haswell) and P is the power consumption. For example, a Haswell processor consuming 84W would cause an overflow every 52min:

$$\frac{2^{32} \times 61\mu\text{J}}{84\text{W}} = 3120\text{s}.$$

The overflows can be mitigated easily by sampling the energy counters more frequently than t_{overflow} . Frequent-enough sampling allows detecting every overflow that occurs. As a general rule, sampling the counters every 5min should be sufficient for any CPU model.

6.3 Non-atomic Register Updates

Our measurements show a time delay between updates to different energy counters, which means that the RAPL updates are not atomic. The non-atomicity introduces errors when sampling multiple counters at high sampling rates. It is possible to read both fresh and stale values of different

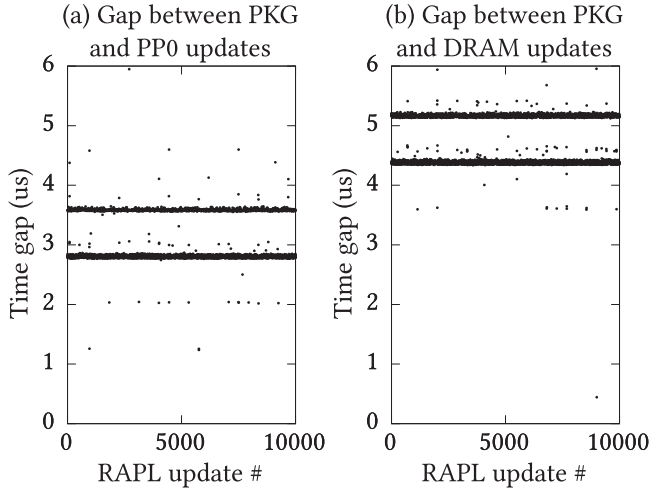


Fig. 7. The time gap between updates to different RAPL registers (Haswell). The timing is measured in microseconds.

counters. Figure 7 shows the timing difference between updates to different RAPL registers for our Haswell machine. In this experiment, we perform busy polling to two RAPL registers alternately. For example, Figure 7(a) shows the timing gap between the RAPL Package (PKG) and PP0 registers. We record the timestamp of every update for both the registers and calculate the difference between the two timestamps. In the case of Haswell, we observe that RAPL registers are always updated in a specific order. The PP0 register is updated either 2.8ms or 3.6ms after the PKG register. The DRAM register is updated either 4.4ms or 5.2ms after the PKG register. The 0.8ms difference between these numbers is due to our limited polling frequency. The average latency of reading the MSR (*RDMSR* instruction execution + a system call) file is 393ns [15]. Therefore, polling two registers takes approximately 0.8ms.

There is a measurable delay between updates of different RAPL registers. We observe similar behavior in case of Skylake. Nevertheless, Figure 6 has already shown us that there are measurable gaps between two Skylake RAPL register updates. It is quite obvious that RAPL registers are not updated atomically. This means that it is possible to accidentally read both fresh and stale energy values when sampling multiple RAPL registers. Specific precautions should be taken to avoid this. For example, we can first identify the correct sequence of RAPL register updates for a specific processor architecture and then if busy polling is used to detect RAPL updates, one should poll the last register updated (in our Haswell experiment DRAM register appears to be the last updated).

6.4 DRAM Energy Accuracy

A few articles [5, 25, 32] have focused on validating the RAPL values specifically for the RAPL DRAM domain. The initial findings suggest that RAPL DRAM values were unstable and unreliable for earlier versions of processors that included RAPL. DRAM values were only available to server-grade systems prior to Haswell. Prior to Haswell, the RAPL DRAM values followed different trends depending on the benchmark, and the values also differed substantially at times with reference values. Since the introduction of Haswell, RAPL DRAM values are now more reliable and follow a strong correlation with AC reference measurements [13, 24].

In our own analysis, DRAM measurements clearly improve accuracy. Modeling the plug power using only CPU measurements gives 3.1% error, including DRAM measurements reduces this error

to 1.7%. However, using only DRAM measurements alone for estimating the plug power yields quite a large error, 7.7%.

A more recent work on the validation of RAPL DRAM power measurements [6] also confirms these results. According to Spencer et al. [6] RAPL DRAM values now closely match the overall energy power and energy trends by a constant power offset for Haswell processors. They also show that there are differences in RAPL DRAM energy measurements across different architectures although the results with newer architectures are more accurate. Thus it is important to pay attention to the underlying architecture before relying on RAPL DRAM energy measurements.

6.5 Unpredictable Timings

The update interval of the RAPL energy counters is approximately 1ms. Intel documentation states that the time unit used by RAPL is 0.976ms. Our experiments show that the actual interval is much closer to 1ms. Unfortunately, the updates do not have any timestamps associated with them [11]. In addition, there seems to be no way to predict the exact timing of future RAPL updates. Nevertheless, there are several solutions for coping with this problem.

First solution: busy polling. It is possible to determine the exact timing of the RAPL updates by busy polling the counters for updates. This technique allows for exact synchronization with the RAPL updates. Hähnel et al. [14] demonstrated that this method can be used to measure the energy consumption of short functions. They use busy polling to detect the start of a RAPL measurement period. They then execute a function they want to measure. Subsequently, they use busy polling to wait until the end of the RAPL period. They obtain the energy used by the function itself by deducting the energy used for busy polling. The downside of this method is the overhead in terms of time and energy.

Second solution: supersampling. Every update can be observed without the timing by sampling more often than every 1ms, for example, every 0.9ms. We call this method supersampling. The method will occasionally produce duplicate values, but they can be filtered out easily. The main advantage is the reduced overhead compared to busy polling. However, the relative overhead is still quite large.

Third solution: High frequency sampling. Sampling frequencies in the range 50–1,000Hz fall into this category. The advantage is lower overhead due to lower sampling rate. A 50Hz sampling rate is still sufficient to distinguish different execution phases, as Servat et al. [35] demonstrated. A drawback of this solution is that the number of updates in one sampling period is not predictable. For example, when sampling at 200Hz, most samples correspond to five RAPL updates. However, occasionally one sample contains four or six updates. This will create spikes in the data. The spikes can be filtered out but this leads to a small loss of data.

Figure 8 shows an example of the spikes when sampling at 200Hz. In this case, the spikes come in two flavors: (1) a spike that is 20% below the mean, and (2) a spike 20% above the mean combined with a second spike 20% below the mean. The first flavor is caused by the fact that the mean time between RAPL updates is 1.00229ms. Thus, in a 10s time period, there will be only $10,000 \div 1.00229 = 9,977$ updates. The second flavor is caused by the random spread in the timings, which allows six updates to be observed inside a 5ms period. We have drawn circles around the points that are 20% above the mean.

Fourth solution: Low frequency sampling. At sampling rates slower than 50Hz, the relative error due to the spikes is less than 0.5%, which is small enough to be ignored. The energy values should remain accurate even with long sampling periods, since they are calculated by the hardware. Thus, the only drawback with slow sampling is the loss of temporal precision.

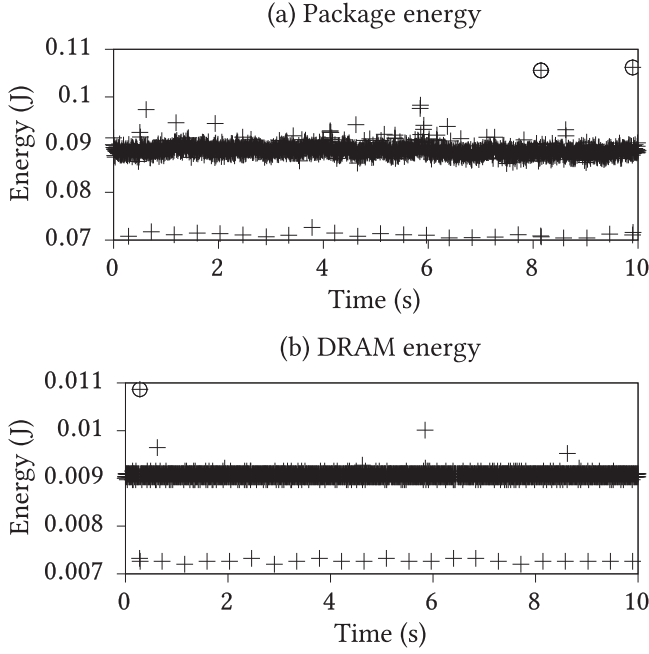


Fig. 8. Package and DRAM energy sampled every 5ms with a constant load on one CPU core.

6.6 Individual Core Measurement Not Supported

RAPL does not support measuring the power consumption of individual CPU cores. The Power Plane 0 domain only gives the total energy consumed by all cores in a single package. Each core has its own MSRs, but we found that all cores show the same values for the RAPL counters. This prevents us from separating the power consumption of different processes or threads running concurrently on the same processor.

There are still alternatives that allow examining the power consumption of individual threads. The first alternative is to run an application in single-threaded mode. We measured the Power Plane 0 power consumption, which is nearly zero when all the cores are sleeping. Thus, Power Plane 0 is equivalent to the power consumption of a single CPU core when only one core is active.

The second alternative is to use multiple cores and divide the power consumption by the number of active cores. This method works best if all threads are performing the same task. For example, microbenchmarks can execute identical workloads across multiple threads.

Individual core measurement is further complicated by hyperthreading. Hyperthreading allows one core to simultaneously execute instructions from two threads. There is no way to separate the power consumption of one thread from the other. However, there are techniques that use hardware counters to model and attribute the power consumption to individual threads such as HaPPy [43]. Such models tend to have large errors ($\approx 10\%$) and therefore, it is advisable to either explicitly enable or disable hyperthreading depending on what needs to be measured.

6.7 Fixed Sampling Rate and Energy Units

It is not possible to increase the sampling rate from the default of 1,000 samples per second, which limits our ability to measure the energy consumption of individual functions using for example, IgProf [23]. One solution is to force the application to sleep before and after the execution of a

Table 5. Amazon EC2 Instance Specifications

Instance Type	Processor	Architecture	Cores	Memory
t2.micro	Intel(R) Xeon(R) CPU E5-2676 v3 @ 2.40GHz	Haswell-EP	1	1GB
t2.xlarge	Intel(R) Xeon(R) CPU E5-2676 v3 @ 2.40GHz	Haswell-EP	4	16GB
t2.2xlarge	Intel(R) Xeon(R) CPU E5-2676 v3 @ 2.40GHz	Haswell-EP	8	32GB
c3.xlarge	Intel(R) Xeon(R) CPU E5-2680 v2 @ 2.80GHz	IvyBridge-EP	4	7.5GB
c4.xlarge	Intel(R) Xeon(R) CPU E5-2666 v3 @ 2.90GHz	Haswell-EP	4	7.5GB

single function. In this manner only a single function is executed during one RAPL update period. Hähnel et al. [14] have shown that this method works. The size of the RAPL energy units limits how accurately a single function can be measured. There are differences in the energy units between different models, which means that some models are better for measuring small variations in energy consumption. For example, Haswell models use units of $61\mu\text{J}$, while Sandy Bridge models use units of $15.3\mu\text{J}$.

7 RAPL MEASUREMENTS IN AMAZON EC2

To further quantify and qualify RAPL measurements, we performed several experiments with Amazon Elastic Compute Cloud (Amazon EC2). The motivation behind choosing a cloud environment is to examine how RAPL performs in popular cloud based services like Amazon EC2. Energy consumption in such a cloud environment is very crucial and tools like RAPL can simplify the energy consumption monitoring of individual users and instances and trigger new energy based pricing mechanisms such as $\$/\text{joule}$ instead of $\$/\text{core}/\text{hour}$. In this section, we present our experiences while using RAPL in Amazon EC2. With respect to RAPL, we performed the following experiments: performance overhead, correlation with temperature, and sampling rates. The methodologies used in these experiments are the same as those mentioned in Sections 4 and 5.

Amazon EC2 allows to read RAPL's MSR registers. Currently, with all of the processor family available in Amazon EC2, it is possible to read the package and DRAM power consumptions. We experimented with five different Amazon EC2 instances: t2.micro, t2.xlarge, t2.2xlarge, c3.xlarge, and c4.xlarge [9]. The specifications of these instances are presented in Table 5. t2 instances are general purpose computing instances with mostly Intel's *Haswell-EP* architecture, whereas c3 and c4 instances are compute optimized instances with a mix of Intel's *Haswell-EP*, *Broadwell-EP*, *IvyBridge-EP*, and *Sandybridge-EP* architectures. We could not obtain the plug power consumption in EC2 instances from sources like IPMI and as a result we could not establish or verify the accuracy of the RAPL readings in virtualized cloud computing platforms like EC2. Our first-hand experience of using RAPL in Amazon is discussed in the following.

Performance overhead. We used the same benchmarks and same frequency settings as mentioned in Table 4 for measuring performance overhead in Amazon EC2. The impact of RAPL measurement on performance overhead in a cloud environment is particularly interesting to examine, because the same physical resources are shared between different users in a virtualized cloud environment and there is an expected measurable impact of other co-running user instances on the overall power consumption and load of the system. In our experiments, we mainly focused on t2 instances for examining performance overhead. The results are presented in Table 6. The performance overheads of RAPL measurements in the case of Amazon t2 instances are quite similar to our observations with *Haswell*-based standalone systems as presented in Table 4. In t2.micro the maximum overhead was observed in *Idq-bench-int-algo-prng-multi4*, while reading the RAPL MSRs at a frequency of 1,100Hz and the overhead was 2.30%. In t2.micro, we observed a lot of

Table 6. Amazon EC2- RAPL Performance Overhead

t2.micro					
Application	100Hz	200Hz	500Hz	1,000Hz	1,100Hz
Idq-bench-float-array-l1-schoenauer	0.38%	0.60%	1.00%	1.63%	1.75%
Idq-bench-float-array-l2-schoenauer	0.04%	0.05%	0.64%	1.50%	1.64%
Idq-bench-float-array-l3-schoenauer	0.09%	0.63%	0.77%	1.84%	2.05%
STREAM-NTIMES-2000	0.08%	0.54%	0.98%	1.36%	1.28%
Idq-bench-int-algo-prng	0.19%	0.26%	0.69%	1.40%	1.64%
Idq-bench-int-algo-prng-multi4	0.91%	1.10%	1.39%	1.97%	2.30%
t2.xlarge					
Application	100Hz	200Hz	500Hz	1,000Hz	1,100Hz
Idq-bench-float-array-l1-schoenauer	0.18%	0.53%	1.08%	1.61%	2.24%
Idq-bench-float-array-l2-schoenauer	0.09%	0.24%	0.43%	1.23%	1.42%
Idq-bench-float-array-l3-schoenauer	0.25%	0.48%	0.73%	1.33%	1.25%
STREAM-NTIMES-2000	0.08%	0.54%	0.98%	1.36%	1.28%
Idq-bench-int-algo-prng	0.27%	0.43%	0.84%	1.49%	1.59%
Idq-bench-int-algo-prng-multi4	0.10%	0.31%	0.79%	1.37%	1.56%
t2.2xlarge					
Application	100Hz	200Hz	500Hz	1,000Hz	1,100Hz
Idq-bench-float-array-l1-schoenauer	0.41%	0.65%	1.45%	1.59%	1.79%
Idq-bench-float-array-l2-schoenauer	0.14%	0.10%	0.61%	1.70%	1.70%
Idq-bench-float-array-l3-schoenauer	0.19%	0.43%	0.92%	1.95%	1.81%
STREAM-NTIMES-2000	0.11%	0.41%	0.46%	1.48%	1.52%
Idq-bench-int-algo-prng	0.17%	0.27%	0.64%	1.43%	1.48%
Idq-bench-int-algo-prng-multi4	0.47%	0.62%	1.02%	1.51%	1.59%

performance variations due to variable load on the system. In such cases, the benchmark itself took unusually longer time to completion compared to cases where sampling frequency was even higher. We carefully discarded the unstable results. We present an example of such a scenario in a later discussion. For the t2.xlarge instance, the maximum overhead was 2.24%, which was reported in *Idq-bench-float-array-l1-schoenauer* at 1,100Hz and in t2.2xlarge the maximum overhead was 1.95%, which was measured at 1,000Hz for the *Idq-bench-float-array-l3-schoenauer* benchmark. For t2.2xlarge, the overhead measurements were less than 2.0%, which was also the case for the standalone *Haswell* based workstation. Since t2.2xlarge was an 8 core *Haswell-EP*-based system, the possibility of load variation due to CPU or resource sharing was quite low, since the number of virtual CPUs in the instances and number of physical CPUs of the architecture are the same and the observations were more stable. In brief, the performance overhead observed in Amazon EC2 was less than 2.5%.

Correlation with temperature. The correlation between the RAPL package power and the core temperature could not be verified in the case of Amazon EC2. Although, it was possible to read the MSRs like *IA32_THERM_STATUS* and *IA32_PACKAGE_THERM_STATUS*, we obtained a constant value of 25°C as the PKG temperature. We verified this with different benchmarks like *Stress-ng*, *Stream*, and our *Instruction decoder* benchmark (presented in Table 4) and the package temperature remained static at 25°C. We assume that Amazon EC2 filters out the temperature sensor value and presents a dummy constant value for package temperature. Apparently, Liu et al. reported in Reference [27] that it was possible to read the CPU temperature readings but things have changed since then.

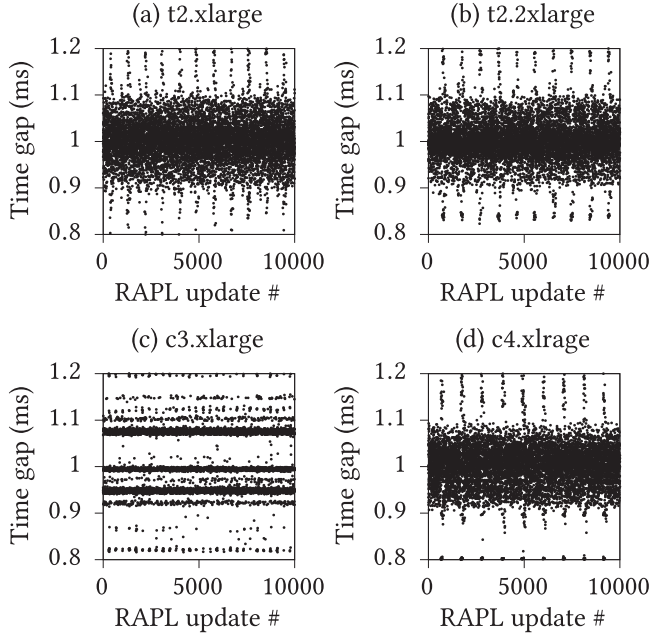


Fig. 9. PKG power timing gap between consecutive updates.

Timing gap in consecutive RAPL updates. We performed experiments to identify the timing gaps in consecutive RAPL updates and to verify the high resolution of RAPL updates similar to experiments presented in Figure 6. The experiments were performed using t2.xlarge, t2.2xlarge, c3.xlarge, and c4.xlarge instances. The timing gaps (in ms) for 10,000 consecutive RAPL PKG power updates is plotted in Figure 9. As indicated in this figure, the timing gaps are very sporadic for t2.xlarge, t2.2xlarge, and c4.xlarge ((a), (b), and (d), respectively, in Figure 9). The timing gaps in c3.xlarge ((c) in Figure 9) show a certain pattern but it is still inconclusive and does not show a uniform update interval (which should be ideally 1ms for Haswell) if we compare it with Figure 6. Interestingly, among the four types of instances examined here, only c3.xlarge has the Ivybridge-EP processor architecture and the remaining three have Haswell-EP processor architecture. The results show that there is a difference in RAPL implementation between the two architectures. We found a measurable difference in polling delay between standalone workstations and Amazon EC2 instances. The hypervisor in EC2 instances traps the MSR reads, which can add to the polling delay. The CPU in EC2 also runs at a lower clock rate, which might also add to the delay. Nevertheless, it is hard to pinpoint whether the timing gaps are produced by the hardware or interference from the hypervisor. Further investigation is required to make such claims.

Reading RAPL values with Amazon EC2 is challenging, since the current implementation of RAPL does not give the per-core energy consumption measurements. Additionally, it is not necessary for a virtual CPU to be mapped to a physical CPU in a cloud environment. The RAPL readings in such a scenario are also affected by other virtual instances running on the physical server. We profiled the c4.xlarge instance for 500s, where we simply captured the RAPL readings at a 250Hz sampling rate without doing anything. Figure 10 shows the power consumption during that 500s, when we executed no workload but just listened to the RAPL updates. This figure shows that during the experiment period the PKG power consumption of the instance highly fluctuated between the mid 30W to close to 100W. Therefore, it is very hard to do the energy accounting in such a

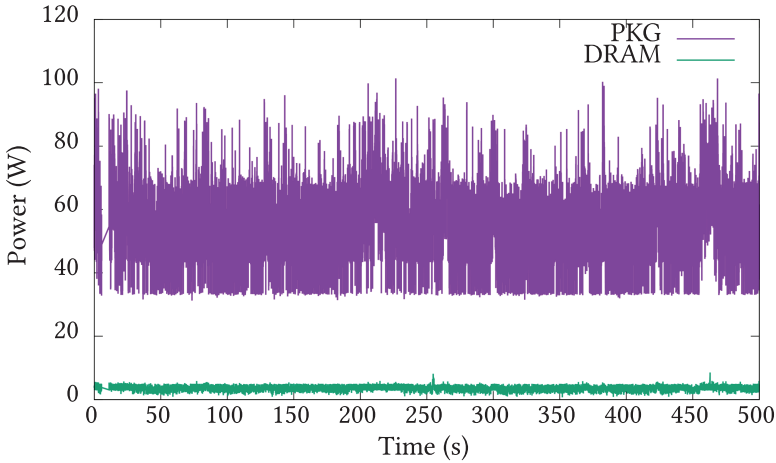


Fig. 10. Amazon EC2 Power profiling.

Table 7. Summary

Aspects	Findings
Accuracy	Correlation ≈ 0.99 with AC power
Plug Power Estimation	MAPE 1.7%
Correlation with temperature	High Correlation with package power in Haswell: 0.93 Less correlation with package power in Skylake: 0.34
Sampling rate	High sampling rate ≈ 1 ms Skylake PP0 sampling rate $\approx 50 \mu s$
Performance overhead	Negligible: $< 1\%$ overhead for standalone systems $< 2.5\%$ for Amazon EC2
DRAM energy	$\leq 20\%$ deviation from actual measurements [6]

virtualized environment and RAPL needs to address this issue to make it more usable in cloud environments like EC2. A few straightforward enhancements that could make RAPL more usable in virtual environment are listed below:

- Reducing the delay of reading RAPL MSRs through hypervisors.
- Adding per core energy accounting instead of per package. This would also make the RAPL implementation more secure, since it would not be possible to see the activities of other instances sharing the same package through power consumption patterns.
- Adding timestamps to RAPL updates to allow per job or per process energy profiling.

8 DISCUSSION

Table 7 summarizes the important aspects of RAPL that we have discussed in detail in the previous sections. We have pinpointed our findings about Intel RAPL’s accuracy, plug power estimation capability, relation with temperature, sampling rate, performance overhead, and some other important aspects that we need to quantify about RAPL through our own experiments and a thorough review of the literature. Our study shows that Intel RAPL can provide accurate enough results for the power consumption of a CPU or attached DRAMs without manually instrumenting the system.

The sampling rate is high enough and the performance overhead for reading RAPL counters at a higher rate is low enough for most of the general cases.

On the contrary, there are some aspects of RAPL that might not make it a suitable tool for cases where we need to determine the power consumption of short code paths [14] or cases where we need to know the exact timestamps attached with each RAPL update. We have discussed all of these aspects to highlight the advantages as well as weaker aspects of RAPL. For future references, we pinpoint a few of our proposed workarounds in brief:

- Register overflow problem can be mitigated by sampling more frequently than the time to overflow.
- Non-atomicity of register updates can be dealt with correctly by identifying the sequence of RAPL register updates and then busy polling the last register in the sequence.
- In case of DRAM energy measurements, Haswell and later processor architectures should be used.
- To mitigate the lack of timestamps in RAPL updates, one can use busy polling, supersampling, high frequency sampling or low frequency sampling depending on the requirements. (Please refer to Section 6.5 for more details)
- Individual core measurements can be obtained either by running a single threaded mode of a workload or by dividing the power consumption by the number of active cores given that all the threads perform the same task.

RAPL measurements in Amazon EC2 instances suggest that although it is possible to obtain power consumption readings in Amazon EC2, the power consumption of such a virtualized cloud computing environment itself varies depending on the load on the actual systems, and therefore the current implementation of RAPL may not be so useful in such scenarios compared to standalone systems. RAPL implementation should properly address this in the future architectures to make it useful and efficient in cloud computing systems.

The promising aspect of RAPL is that it has evolved through generations of architecture. Sandybridge RAPL energy consumption values are based on modeling approaches. On the contrary, Haswell is able to achieve higher levels of accuracy because of the introduction of on-chip voltage regulators and more fine grained control of frequencies [13]. We have also shown that Skylake has improved from Haswell in granularity for measuring the PP0 domain and it introduces a new, PSys domain to monitor and control the power consumption of the platform domain. Our limited experiments with Skylake already show improvements in RAPL implementation and in the future we plan to perform a detailed study on Skylake's RAPL validation.

We do not particularly focus on GPU workloads in this article, since our focus here is traditional CPU or memory intensive workloads. In the future, we plan to extend our work with such enhancements. There are alternatives for RAPL in case of AMD, ARM processors and NVIDIA GPUs. Prior works suggest AMD processor can report "Current Power In Watts" using MSRs like RAPL [14], ARM has cross-platform chip monitor integrated with recent versions of processors [2], and recent NVIDIA GPUs can also report power usage via the NVIDIA Management Library (NVML) [14].

Despite a few differences in RAPL and reference measurements, Intel's RAPL can be a useful tool to track a program's power consumption behavior in large-scale data centers and it can be a good alternative to metering devices specifically as it does not require a complex manual instrumentation of every system of interest. It will be more useful to use RAPL if it addresses some of the concerns that we discuss in this article: adding timestamps to individual updates, atomic register updates, individual core measurement features, handling register overflows more gracefully, and

perhaps adding more features such as handling even the power consumption of the other system components rather than only the CPU chip.

9 CONCLUSION

The study of energy-efficiency in computing has been a hot topic for a long time. The introduction of RAPL has enabled a number of experiment scenarios that were not possible before. Nevertheless, there are also weaknesses that are associated with such an approach. In this article, we conducted a comprehensive study to demonstrate how Intel RAPL performs in terms of accuracy, performance, granularity, usability, and other important aspects of user experiences. We also pinpointed several directions toward the improved handling of some of the issues that might arise in certain scenarios. Our overall study suggests that RAPL has evolved toward a better energy measurement tool since its introduction in Sandybridge, and it has appeared to be a useful and efficient alternative for manually instrumented complex power monitors. With the Haswell architecture, RAPL has improved considerably, its power readings now closely match plug power readings and it has now introduced the new measurement domain PSys and improved the power performance in Skylake. In the future, we plan to continue our work with a comparative analysis of RAPL performance in Haswell and Skylake.

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Received June 2017; revised October 2017; accepted January 2018