

Cricket Bat & Ball Detection + Speed Estimation System

This project detects **cricket ball and bat**, tracks the **ball trajectory**, and estimates the **ball speed when it reaches the batter** using **YOLOv8** and **OpenCV**.

The system combines two trained models:

1. **Ball Detection Model**
2. **Bat Detection Model**

Both models are used together to accurately detect, track, and estimate the ball's speed in real-time from a video.

Paths to the models

The YOLOv8 models for ball and bat detection are saved at:

- **Ball model:** D:\Projects\ball_detection\runs\cric_detect_train_bat_ball_sample2\weights\best.pt
 - **Bat model:** D:\Projects\ball_detection\runs\cric_detect_train_bat_ball_finetune3\weights\best.pt
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Project Structure

```
ball_detection/
|
├── ball_dataset/                                # Dataset for training ball detection
model
├── bat_dataset/                                # Dataset for training bat detection
model
|
└── notebooks/
    ├── Ball_model_training.ipynb            # Notebook used to train YOLO model for
    |   ball detection
    └── Bat_model_training.ipynb            # Notebook used to train YOLO model for
    |   bat detection
|
└── runs/
    ├── detect/
    |   ├── cric_detect_train_bat_ball_sample2/  # Folder containing the trained
    |   |   ball detection model
    |   |   └── cric_detect_train_bat_ball_finetune3/ # Folder containing the fine-
    |   |   |   tuned bat detection model
    |
    └── utils/
        ├── tracker.py                         # Custom object tracking class (centroid
        |   + IoU based)
        |   └── speed_estimation.py          # Functions for speed calculation and
        |       smoothing
```

```
└── vedios/
    ├── input/                                # Input video(s)
    │   └── example_clip.mp4
    └── output/                               # Processed videos (saved here after
running detection)
        └── processed_clip.mp4

└── videos/
    └── detection_and_tracking.ipynb      # Main notebook to run detection,
tracking, and speed estimation
```

Environment Setup

1. **Clone or download** the project folder [ball_detection/](#) to your local system.
2. Open a terminal or Anaconda prompt inside the folder.
3. Create and activate a virtual environment (recommended):

```
conda create -n cricket_env python=3.10 -y
conda activate cricket_env
```

4. **Install dependencies:**

```
pip install ultralytics opencv-python numpy
```

Model Training

1. Ball Detection Model

- **File:** [ball_detection/notebooks/Ball_model_training.ipynb](#)
- **Description:** Trains a YOLOv8 model using the dataset inside [ball_dataset/](#).
- **Result:** The trained weights are saved inside:

```
ball_detection/runs/detect/cric_detect_train_bat_ball_sample2/weights/best.pt
```

2. Bat Detection Model

- **File:** [ball_detection/notebooks/Bat_model_training.ipynb](#)

- **Description:** Fine-tunes YOLOv8 for bat detection using `bat_dataset/`.
- **Result:** The fine-tuned model is saved inside:

```
ball_detection/runs/detect/cric_detect_train_bat_ball_finetune3/weights/best.pt
```

Components Explanation

1. `utils/tracker.py`

Implements **object tracking** based on:

- Centroid distance
- Intersection over Union (IoU)
- Unique IDs for consistent tracking across frames

2. `utils/speed_estimation.py`

Contains:

- `calculate_speed()` → Converts pixel movement to real-world speed (km/h)
- `SpeedAggregator` → Smooths speed over frames and freezes at the hit
- Utility functions for overlay and UI display

3. `videos/detection_and_tracking.ipynb`

Main notebook that:

- Loads both **bat and ball models**
- Detects objects frame-by-frame
- Tracks the ball trajectory
- Calculates and displays **instantaneous** and **maximum speed**
- Detects “**hit**” event (when bat and ball overlap)
- Saves processed output video to:

```
ball_detection/vedios/output/processed_clip.mp4
```

How to Run the System

1. Place your cricket video inside:

```
ball_detection/vedios/input/
```

Example: `ball_detection/vedios/input/example_clip.mp4`

2. Open the notebook:

```
ball_detection/videos/detection_and_tracking.ipynb
```

3. Run all cells in order. It will:

- Load the two trained YOLO models
- Detect & track the ball and bat
- Calculate ball speed frame-by-frame
- Display results with overlays
- Save processed output at:

```
ball_detection/vedios/output/processed_clip.mp4
```

Speed Estimation Notes

The **ball speed** is estimated using:

- Distance covered between consecutive frames
- Frame rate (FPS) of the video
- Pixel-to-meter conversion factor

Formula: $\text{Speed (m/s)} = \frac{\text{Distance in pixels}}{\text{pixels per meter}} \times \frac{1}{\text{Time per frame}}$

Converted to **km/h** for display.

Limitations

- Works best on **high-quality videos** (720p or above).
- If the video is **blurry** or **too dark**, detections may be inaccurate.
- Models are trained for **specific cricket angles** — performance may vary with different camera perspectives.
- Ensure FPS and camera distance are consistent for accurate speed estimation.

Output Example

Once the system runs successfully, you'll find:

- **Detected and tracked video:** [ball_detection/vedios/output/processed_clip.mp4](#)
- **Speed displayed on video overlay** (in km/h)
- **Hit event** highlighted when bat and ball make contact