

# Continuous Logic and Learning Bounds

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# Model Theory to Learnability

- Let  $\mathcal{C} = \{c_y : y \in Y\}$  be a class of subsets of  $X$  indexed by  $Y$ .
- $\mathcal{C}$  is NIP/stable when there is an NIP/stable formula  $\phi(x; y)$  such that  $x \in c_y \iff \phi(x; y)$ .
- The properties in each row are equivalent:

Model Theory	Combinatorics	Learning Theory
NIP	finite VC dimension	PAC learnable
stable	finite Littlestone dimension	online learnable

# Continuous Logic to Learnability

- Let  $\mathcal{H} = \{h_y : y \in Y\}$  be a class of functions  $X \rightarrow [0, 1]$  indexed by  $Y$ .
- $\mathcal{H}$  is NIP/stable when there is an NIP/stable formula  $\phi(x; y)$  of continuous logic such that  $h_y(x) = \phi(x; y)$ .
- The properties in the table have been generalized to  $\mathcal{H}$ , but the connections are understudied.

# New Learnable Function Classes

## Theorem (A., Benedikt)

*A class  $\mathcal{H}$  of functions  $X \rightarrow [0, 1]$  is stable iff it is online learnable.*

## Theorem (A., Benedikt)

*The randomization of a PAC/online learnable function class  $\mathcal{H}$  is also PAC/online learnable.*

# Generalizing VC Dimension to Continuous Logic

## Theorem (Ben Yaacov)

*A formula  $\phi$  of continuous logic is NIP iff the class of functions it defines has finite  $\gamma$ -fat-shattering dimension for all  $\gamma > 0$ .*

## Definition

Let  $\mathcal{H}$  be a class of functions  $X \rightarrow [0, 1]$  and let  $\gamma > 0$ . We say  $\mathcal{H}$  has  $\gamma$ -fat-shattering dimension at least  $n$  when there are

- $x_1, \dots, x_n \in X$
- $s_1, \dots, s_n \in [0, 1]$
- For every  $E \subseteq \{1, \dots, n\}$ , a function  $h_E \in \mathcal{H}$  satisfying
  - if  $i \in E$ ,  $h_E(x_i) \geq s_i + \gamma$
  - if  $i \notin E$ ,  $h_E(x_i) \leq s_i - \gamma$ .

# Probably Approximately Correct Learning

A class  $\mathcal{H}$  of functions  $X \rightarrow [0, 1]$  is PAC learnable when for every  $\varepsilon, \delta > 0$ , there is  $n$  such that when...

- $(x_1, y_1), \dots, (x_n, y_n) \in X \times [0, 1]$  are i.i.d. random,
- we can choose  $h \in \mathcal{H}$  (hoping that  $h(x_{n+1}) \approx y_{n+1}$ ) such that
- with probability at least  $1 - \delta$ ,
- $\mathbb{E}[|y_{n+1} - h(x_{n+1})|]$  is within  $\varepsilon$  of the best case for all  $h \in \mathcal{H}$ .

We call  $n = n(\varepsilon, \delta)$  the *sample complexity*.

# PAC Learning Bound

## Theorem (Bartlett, Long)

*The sample complexity  $n(\epsilon, \delta)$  of PAC-learning  $\mathcal{H}$  is bounded by*

$$O\left(\frac{1}{\epsilon^2} \cdot \left(\text{FatSHDim}_{\frac{\epsilon}{9}}(\mathcal{H}) \cdot \log^2\left(\frac{1}{\epsilon}\right) + \log\left(\frac{1}{\delta}\right)\right)\right)$$

*In fact,  $\mathcal{H}$  is PAC-learnable if and only if the  $\gamma$ -fat-shattering dimension is finite for all  $\gamma > 0$ .*

Hu et al. extended this to learning a class of measures on  $\mathcal{H}$ , at the cost of a much worse bound.

We'll use continuous logic to find examples of learnable classes and improve the Hu et al. bound.

# The Expectation Class

Suppose  $(\Omega, \Sigma, \mu)$  is a probability space and  $\mathcal{F} = (\mathcal{H}_\omega : \omega \in \Omega)$  is a family of function classes  $\mathcal{H}_\omega = (h_{\omega,y} : y \in Y)$ .

## Definition

Assuming measurability, define  $\mathbb{E}\mathcal{F}_y : X \rightarrow [0, 1]$  by

$$\mathbb{E}\mathcal{F}_y(x) = \mathbb{E}[h_{\omega,y}(x)].$$

We call the class  $\mathbb{E}\mathcal{F} = \{\mathbb{E}\mathcal{F}_y : y \in Y\}$  the *expectation class* of  $\mathcal{F}$ .

Think of  $\mathbb{E}\mathcal{F}$  and every  $\mathcal{H}_\omega$  as a class of functions  $h : X \rightarrow [0, 1]$  indexed by  $Y$ .



# The Randomization

If the classes  $\mathcal{H} \in \mathcal{F}$  are uniformly definable in some structure  $M$ , then  $\mathbb{E}\mathcal{F}$  is definable in a structure  $M^R$  (of continuous logic) called the *randomization* of  $M$ , whose elements are  $M$ -valued random variables.

## Theorem (Ben Yaacov, Keisler)

- If  $\mathcal{F}$  is uniformly NIP/stable, then  $\mathbb{E}\mathcal{F}$  is NIP/stable.
- If a structure  $M$  is NIP/stable, then  $M^R$  is NIP/stable.

# PAC Learning Expectations

## Theorem (A., Benedikt)

If each  $\mathcal{H} \in \mathcal{F}$  has  $\text{FatSHDim}_{\frac{\epsilon}{50}}(\mathcal{H}) \leq d$ , one can PAC learn the expectation class  $\mathbb{E}\mathcal{F}$  with sample complexity

$$O\left(\frac{d}{\epsilon^4} \cdot \log^2 \frac{d}{\epsilon} + \frac{1}{\epsilon^2} \cdot \log \frac{1}{\delta}\right).$$

- FatSHDim can be used to bound *Rademacher mean width*
- Rademacher mean width can be used to bound sample complexity
- Adapt Ben Yaacov's proof that *Gaussian* mean width is preserved under randomization

# Online Learning

- At step  $i$ , an adversary chooses  $(x_i, y_i) \in X \times [0, 1]$
- Given  $x_i$ , you guess  $y'_i \approx y_i$  (you can use randomness)
- The adversary tells you  $y_i$ , penalizes you  $|y_i - y'_i|$
- After  $n$  steps, compare to the best strategy  $y'_i = h(x_i)$  for  $h \in \mathcal{H}$ .
- Call the difference in penalty the *regret*.
- $\mathcal{H}$  is online learnable if whatever the adversary does, regret is sublinear in  $n$ .

# Online Learning Bounds

To bound regret in online learning, replace our existing notions with *sequential* versions, replacing subsets  $E \subseteq \{1, \dots, n\}$  with branches of a binary tree of depth  $n$ :

## Theorem (Rakhlin, Sridharan, Tewari)

*Finite  $\gamma$ -sequential-fat-shattering dimension is equivalent to online learnability, with bounds given.*

Their proof goes through sequential Rademacher mean width.

# Our Online Learning Results

## Theorem (A., Benedikt)

- *Stability in continuous logic is equivalent to finite  $\gamma$ -sequential-fat-shattering dimension for all  $\gamma > 0$ .*
- *Sequential Rademacher mean width, and thus online learnability, is preserved under randomization.*

## Theorem (A., Benedikt)

*The minimax regret of online learning for the randomization class of  $\mathcal{H}$  with  $\gamma$ -sequential-fat-shattering dimension at most  $d$  on a run of length  $n$  is at most*

$$4 \cdot \gamma \cdot n + 12 \cdot (1 - \gamma) \cdot \sqrt{d \cdot n \cdot \log \left( \frac{2 \cdot e \cdot n}{\gamma} \right)}.$$

# Thank you!

For downloadable slides, see

`https://awainverse.github.io/talks/learningrandom/`

For valued fields enthusiasts: Talk to me about RCMVF.