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## TUTORIAL

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### 1 Wiedemann's algorithm

Let  $K$  be a finite field (e.g.  $\mathbb{Z}/p\mathbb{Z}$  with  $p$  prime) and  $M \in M_n(K)$  be an invertible matrix, with  $\omega(M)$  non zero coefficients.

1. Recall the main steps of Wiedemann's algorithm to compute a solution of  $Mx = b$  for some vector  $b$ . What is its complexity ?
2. Assume now that  $M$  is non invertible and that its minimal polynomial is known. Can you describe some non-zero vectors in its kernel?
3. Deduce a probabilistic algorithm that finds a non zero element in  $\ker M$ . What complexity do you obtain ? Compare it with the approach using Gaussian elimination.
4. Propose a modification to Wiedemann's algorithm for a non-square  $M \in K^{n \times r}$  for  $r < n$ .

### 2 Lanczos algorithm

In this exercise we are going to consider a linear equation

$$Ax = b$$

over the real numbers and we assume we can compute with sufficient precision (i.e., values close to 0 are *not* treated as 0).

1. Show that we can further assume that  $A$  is symmetric and positive definite.
2. We thus assume  $A$  is symmetric and positive definite. Then, it induces scalar product as

$$\langle x, y \rangle_A := \langle x, Ay \rangle = \langle Ax, y \rangle$$

Consider the following orthogonalization process:

- set  $v_0 = b$ ;
- for  $i \geq 0$ , set  $w_i = Av_i$  and

$$v_{i+1} = w_i - \sum_{j=0}^i \frac{\langle w_j, v_i \rangle_A}{\langle v_j, v_j \rangle_A} \cdot v_j$$

Show that this creates indeed an orthogonal family in  $\mathbb{R}^n$  w.r.t.  $A$ . How many scalar products you need to compute this basis?

3. Show how to compute the solution  $x$  in time  $O(n^2)$ .
4. What might get wrong in the above process?

### 3 Iterative methods for solving linear systems

In this exercise, we let that  $K = \mathbb{R}$  or  $K = \mathbb{C}$ . We will consider iterative methods to compute an approximation of the solution of a system

$$Ax = b \quad (1)$$

with  $A$  an invertible matrix of size  $n$ .

1. Let  $A = M - N$  with  $M, N \in M_n(K)$  and  $M$  invertible. Show that solving (1) is equivalent to find a fixed point of the function  $f : K^n \rightarrow K^n$  defined by  $f(x) = M^{-1}Nx + M^{-1}b$ .

We first design an algorithm to compute an approximation of  $x$  under some assumptions:

- we assume that  $x$  is the unique fixed point of  $f$ ;
- for some known  $x_0 \in K$ , the sequence defined by  $x_{n+1} = f(x_n)$  converges to  $x$ .

In a second part, we will give a sufficient condition for these assumptions.

2. **Jacobi's method:** assume that  $A$  has no zero on its diagonal. Show that the next term in the sequence can be computed in  $O(n^2)$  operations for a good choice of  $M, N$ .

Further assume that there exists  $0 \leq k < 1$  such that, for all  $x_1, x_2 \in K^n$ , we have  $\|f(x_1) - f(x_2)\| \leq k\|x_1 - x_2\|$ . Such a map is called a *contraction*.

3. Give an algorithm to compute an approximation of  $x$  such that  $Ax = b$  with at least  $r$  bits of precision for each coordinate. What is its complexity in terms of operations in  $K$  (assume we already know a ball of radius 10 containing  $x$ )?

We now give general examples of contractions. Let  $M \in M_n(K)$  be a matrix. We define the matrix norm of  $M$  associated to  $\|\cdot\|$  by

$$|||M||| = \sup_{x \in K^n \setminus \{0\}} \left( \frac{\|Mx\|}{\|x\|} \right).$$

4. Prove that  $|||M||| = \max_{x \in K^n, \|x\|=1} (\|Mx\|)$  (beware, there is now a max and not a sup). (Hint: use the fact that the unit ball is compact in  $K^n$ ).
5. Let  $f$  be as in question 1, and give a condition on  $M$  and  $N$  such that  $f$  is a contraction.
6. Let  $A$  be a strictly row diagonally dominant matrix, that is  $|a_{i,i}| > \sum_{j \neq i} |a_{i,j}|$  for all  $1 \leq i \leq n$ . Prove that the Jacobi's method converges for  $A$  (Hint : use the  $\|\cdot\|_\infty$  norm to prove that the condition of question 5 is satisfied).

**Banach-Picard's fixed point theorem** : we now show that the “contraction” assumption implies the two others.

7. Let  $g : K^n \rightarrow K^n$  be a contraction. Prove that  $g$  has at most one fixed point  $\ell$  in  $K^n$ .
8. Let  $x_0 \in K^n$  be any vector and define  $x_{n+1} = g(x_n)$ . Prove that this sequence converges. What is its limit ? What is the speed of convergence of this sequence ?