1.3: 12,14,16,18,19,26,28,30 14: 3,8,10,12,22,32

Consider the following meatrices: 
$$A = \begin{bmatrix} 1 & 2 & 3 \\ 2 & 1 & 4 \end{bmatrix}$$
,  $B = \begin{bmatrix} 1 & 0 \\ 3 & 2 \end{bmatrix}$ ,  $C = \begin{bmatrix} 3 & -1 & 3 \\ 4 & 1 & 5 \\ 2 & 1 & 3 \end{bmatrix}$ ,  $D = \begin{bmatrix} 3 & -2 \\ 2 & 5 \end{bmatrix}$ ,  $E = \begin{bmatrix} 2 & -4 & 5 \\ 0 & 1 & 4 \\ 3 & 2 & 1 \end{bmatrix}$ , and  $F = \begin{bmatrix} -1 & 2 \\ 0 & 4 \\ 3 & 5 \end{bmatrix}$ 

1.3.121 If possible, compute the following:

which you cannot add are to differing matrix sizes.

(6)  $E C = \begin{bmatrix} 2-45 \\ 0 & 14 \\ 3 & 2 \end{bmatrix} \begin{bmatrix} 3-13 \\ 4 & 15 \\ 2 & 13 \end{bmatrix} = \begin{bmatrix} 0-1 & 1 \\ 125 & 17 \\ 210 & 27 \end{bmatrix}$ 

(c)  $CE = \begin{bmatrix} 3 & -1 & 3 \\ 4 & 1 & 5 \\ 2 & 1 & 3 \end{bmatrix} \begin{bmatrix} 2 & -4 & 5 \\ 0 & 1 & 4 \\ 3 & 2 & 1 \end{bmatrix} = \begin{bmatrix} 15 & -7 & 14 \\ 23 & -5 & 29 \\ 13 & -1 & 17 \end{bmatrix}$ 

Council multiply F Cas F is a 3x2 matrix and Cis 93x3 (e) FC+D Matrix "

Hw K 2 p. 2 1.3.14 If possible, compute the following: (a) A(BD) (B) (4B) D (c) A(c+E) (d) Ac+AE (e)  $(2AB)^T$  and  $2(AB)^T$  (f) A(C-3E). (a)  $A(BD) = A(\begin{bmatrix} 1 & 0 \\ 2 & 2 \end{bmatrix} \begin{bmatrix} 3 & -2 \\ 2 & 5 \end{bmatrix}) = A\begin{bmatrix} 3 & -2 \\ 8 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 2 & 3 \\ 2 & 1 & 4 \end{bmatrix} \begin{bmatrix} 3 & -2 \\ 8 & 1 \end{bmatrix} = \begin{bmatrix} 58 & 12 \\ 66 & 13 \end{bmatrix}$ 16)  $(AB)D = (\begin{bmatrix} 1 & 2 & 3 \\ 2 & 1 & 4 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 2 & 1 \end{bmatrix} D = \begin{bmatrix} 114 & 8 \\ 16 & 9 \end{bmatrix} \begin{bmatrix} 3 & -2 \\ 2 & 5 \end{bmatrix} = \begin{bmatrix} 58 & 10 \\ 66 & 13 \end{bmatrix}$ (c)  $A(C+F) = A(\begin{bmatrix} 3 & -1 & 3 \\ 4 & 1 & 5 \\ 2 & 1 & 3 \end{bmatrix} + \begin{bmatrix} 2 & -4 & 5 \\ 0 & 1 & 4 \end{bmatrix}) = \begin{bmatrix} 1 & 2 & 3 \\ 2 & 1 & 4 \end{bmatrix} \begin{bmatrix} 5 & -5 & 8 \\ 4 & 2 & 9 \\ 5 & 3 & 4 \end{bmatrix} = \begin{bmatrix} 28 & 8 & 38 \\ 34 & 4 & 41 \end{bmatrix}$ (3)  $AC+AE = \begin{bmatrix} 1 & 3 & 3 \end{bmatrix} \begin{bmatrix} 3 & -1 & 3 \\ 2 & 1 & 4 \end{bmatrix} \begin{bmatrix} 3 & -1 & 3 \\ 2 & 1 & 4 \end{bmatrix} \begin{bmatrix} 2 & -4 & 5 \\ 3 & 1 & 4 \end{bmatrix} = \begin{bmatrix} 17 & 4 & 22 \\ 18 & 3 & 23 \end{bmatrix} + \begin{bmatrix} 1 & 4 & 16 \\ 16 & 1 & 18 \end{bmatrix} = \begin{bmatrix} 28 & 838 \\ 34 & 441 \end{bmatrix}$ (e)  $(2 + B)^T = \left(2 \begin{bmatrix} 12 & 3 \\ 2 & 14 \end{bmatrix} \begin{bmatrix} 10 \\ 21 \end{bmatrix}\right)^T = \left(2 \begin{bmatrix} 14 & 8 \\ 16 & 9 \end{bmatrix}\right)^T = \begin{bmatrix} 28 & 16 \\ 32 & 18 \end{bmatrix}^T = \begin{bmatrix} 28 & 32 \\ 16 & 18 \end{bmatrix}$  $2(4B)^{T} = 2[148]^{T} = 2[1416] = [2832]$ If)  $A(C-3E) = A(\begin{bmatrix} 3 & -1 & 3 \\ 4 & 1 & 5 \end{bmatrix} - 3\begin{bmatrix} 2 & -4 & 5 \\ 0 & 1 & 4 \end{bmatrix} = \begin{bmatrix} -3 & 11 & -12 \\ 4 & 1 & 5 \end{bmatrix} = \begin{bmatrix} -16 & -8 & -26 \\ 4 & 1 & 5 \end{bmatrix} = \begin{bmatrix} -3 & 0 & -31 \end{bmatrix}$ 1.3.16 Let 4 = [1 2-3], B = [-1 42], and C = [-3 01]. If possible, compute to blowing:

(9) ABT (B) CAT (C) (BAT) C (J) ATB (e) CCT (P) CTC (G) BT CAAT (a)  $AB^{\dagger} = \begin{bmatrix} 1 & 2 - 3 \end{bmatrix} \begin{bmatrix} -1 \\ 2 \end{bmatrix} = 1$  (a)  $CA^{\dagger} = \begin{bmatrix} -3 & 0 \\ 1 \end{bmatrix} \begin{bmatrix} 2 \\ -3 \end{bmatrix} = -6$ (c) (BAT) C = ([-142] [2]) C=1C=[-301] (d)  $A^TB = \begin{bmatrix} 1 \\ 2 \\ -3 \end{bmatrix} \begin{bmatrix} -1 & 4 & 2 \\ -2 & 8 & 4 \\ 3-12 & -6 \end{bmatrix}$  (e)  $CC^T = \begin{bmatrix} -3 & 01 \end{bmatrix} \begin{bmatrix} -3 \\ 0 \\ 1 \end{bmatrix} = 10$ (F)  $C^{T}C = \begin{bmatrix} -3 \\ 0 \end{bmatrix} \begin{bmatrix} -3 \\ 0 \end{bmatrix} = \begin{bmatrix} 9 & 0 & -3 \\ 0 & 0 & 0 \\ -3 & 0 & 1 \end{bmatrix}$ (9)  $B^{T}CAA^{T} = B^{T}C\begin{bmatrix} 12 - 3 \end{bmatrix}\begin{bmatrix} \frac{1}{2} \\ -3 \end{bmatrix} = B^{T}C\begin{bmatrix} 14 = 14 \\ \frac{1}{2} \end{bmatrix}\begin{bmatrix} -3 & 1 \end{bmatrix} = 14\begin{bmatrix} 3 & 0 & -14 \\ -12 & 0 & 4 \\ -6 & 0 & 2 \end{bmatrix} = \begin{bmatrix} 422 & 0 & -14 \\ -168 & 0 & 56 \\ -84 & 0 & 28 \end{bmatrix}$ 

1.3.18 If 
$$I_2 = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$
 and  $D = \begin{bmatrix} 2 & 3 \\ -1 & -2 \end{bmatrix}$ , compute  $DI_2$  and  $I_2D$ .

$$D\Gamma_{2} = \begin{bmatrix} 2 & 3 \\ -1 & -2 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} = \begin{bmatrix} 2 & 3 \\ -1 & -2 \end{bmatrix} \text{ and } \Gamma_{2}D = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 2 & 3 \\ -1 & -2 \end{bmatrix} = \begin{bmatrix} 2 & 3 \\ -1 & -2 \end{bmatrix}.$$

$$AB = \begin{bmatrix} 1 & 2 \\ 3 & 2 \end{bmatrix} \begin{bmatrix} 2 & -1 \\ -3 & 4 \end{bmatrix} = \begin{bmatrix} -4 & 7 \\ 0 & 5 \end{bmatrix}, BA = \begin{bmatrix} 2 & -1 \\ -3 & 4 \end{bmatrix} \begin{bmatrix} 1 & 2 \\ 3 & 2 \end{bmatrix} = \begin{bmatrix} -1 & 2 \\ 9 & 2 \end{bmatrix}$$
 so  $AB \neq BA$ .

1.3.26 (a) Find a value of r so that 
$$AB^{\dagger} = 0$$
, where  $A = [r \mid -2]$  and  $B = [l \mid 3 - i]$ .

(B) Give an alternative way to write this product.

(a) 
$$AB^{T} = [r_{1}-2]\begin{bmatrix} 1\\ 3 \end{bmatrix} = r+3+2 = r+5=0$$
 So  $r=-5$ .

- 1.3.281 (a) Let A be an man matrix with a vow consisting entirely of zeroes. Show that if B is an nxp matrix, then AB has a row of zeroes.
  - (B) Let A be an mxn matrix with a column consisting entirely of zeroes and let B be pxm. Show that BA has a column of Zeroes.
  - (a) Let row i of A Be Zero so row; (A) = 0. Then for any column j of B the element Cij of AB is (row; (A)) Col; (B) = 0. Col; (B) = 0 showing that row i of AB is also Zero.
  - (B) Let column j of A Be zero so colj(A) = 0. Then for any row i of B the clenent Cij of BA is (rowilb) T. Colj(A) = (rowilb) T. O = O showing that column j of BA is also zero.

1.3.30 Consider the following linear System:  

$$2x_1 + 3x_2 - 3x_3 + x_4 + x_5 = 7$$
  
 $3x_1 + 2x_3 + 3x_5 = -2$   
 $2x_1 + 3x_2 - 4x_4 = 3$ 

(a) Find the coofficient matrix. 
$$A = \begin{bmatrix} 2 & 3 - 3 & 1 & 1 \\ 3 & 0 & 2 & 0 & 3 \\ 2 & 3 & 0 - 4 & 0 \\ 0 & 0 & 1 & 1 & 1 \end{bmatrix}$$

1.4.3] Verify Theorem 1.2(a) for the following matrices:
$$A = \begin{bmatrix} 1 & 3 \\ 2 & 1 \end{bmatrix}, B = \begin{bmatrix} -1 & 3 & 2 \\ 1 & -3 & 4 \end{bmatrix}, \text{ and } C = \begin{bmatrix} 1 & 0 \\ 3 & -1 \end{bmatrix}.$$

We need to verify 
$$A(BC) = [AB)C$$
 (which is true since the proof is provided).  
 $A(BC) = A\left(\begin{bmatrix} -1 & 3 & 2 \\ 1 & -3 & 4 \end{bmatrix}\begin{bmatrix} 1 & 0 \\ 3 & -1 \end{bmatrix}\right) = \begin{bmatrix} 1 & 3 \\ 2 & -1 \end{bmatrix}\begin{bmatrix} 1 & 1 \\ -4 & 11 \end{bmatrix} = \begin{bmatrix} -2 & 34 \\ 24 & -9 \end{bmatrix}$ 
(AB)  $C = \left(\begin{bmatrix} 1 & 3 \\ 2 & -1 \end{bmatrix}\begin{bmatrix} -1 & 3 & 2 \\ 1 & -3 & 4 \end{bmatrix}\right)C = \begin{bmatrix} 2 & -6 & 14 \\ -3 & 9 & 0 \end{bmatrix}\begin{bmatrix} 3 & -1 \\ 3 & 2 \end{bmatrix} = \begin{bmatrix} -2 & 34 \\ 24 & -9 \end{bmatrix}$  5.  $A(BC) = (AB)C$ 
holds for these matrices.

(a) Determine a simple expression for A?

$$A^{2} = \begin{bmatrix} \cos(\theta) & \sin(\theta) \\ -\sin(\theta) & \cos(\theta) \end{bmatrix} \begin{bmatrix} \cos(\theta) & \sin(\theta) \\ -\sin(\theta) & \cos(\theta) \end{bmatrix} = \begin{bmatrix} \cos^{2}(\theta) - \sin^{2}(\theta) & 2\cos(\theta) \sin(\theta) \\ -2\cos(\theta) \sin(\theta) & \cos^{2}(\theta) - \sin^{2}(\theta) \end{bmatrix}$$

$$= \begin{bmatrix} \cos(2\theta) & \sin(2\theta) \\ -\sin(2\theta) & \cos(2\theta) \end{bmatrix} = 2\sin(\theta)\cos(\theta) \text{ and } \cos(2\theta) = \cos^{2}(\theta) - \sin^{2}(\theta).$$

(b) Determine a Simple expression for 
$$A^3$$

$$A^3 = A^2 A = \begin{bmatrix} \cos(2\theta) & \sin(2\theta) \\ -\sin(2\theta) & \cos(2\theta) \end{bmatrix} \begin{bmatrix} \cos(\theta) & \sin(\theta) \\ -\sin(\theta) & \cos(\theta) \end{bmatrix} = \begin{bmatrix} \cos(2\theta) & \cos(\theta) & -\sin(\theta) \\ -\sin(\theta) & \cos(\theta) \end{bmatrix} \begin{bmatrix} \cos(\theta) & \sin(\theta) \\ -\sin(\theta) & \cos(\theta) \end{bmatrix} \begin{bmatrix} \cos(\theta) & \sin(\theta) \\ -\sin(\theta) & \cos(\theta) \end{bmatrix} = \begin{bmatrix} \cos(\theta) & \sin(\theta) \\ -\sin(\theta) & \cos(\theta) \end{bmatrix} \begin{bmatrix} \cos(\theta) & \sin(\theta) \\ -\sin(\theta) & \cos(\theta) \end{bmatrix} \begin{bmatrix} \cos(\theta) & \sin(\theta) \\ -\sin(\theta) & \cos(\theta) \end{bmatrix} \begin{bmatrix} \cos(\theta) & \sin(\theta) \\ -\sin(\theta) & \cos(\theta) \end{bmatrix} \begin{bmatrix} \cos(\theta) & \sin(\theta) \\ -\sin(\theta) & \cos(\theta) \end{bmatrix} \begin{bmatrix} \cos(\theta) & \sin(\theta) \\ -\sin(\theta) & \cos(\theta) \end{bmatrix} \begin{bmatrix} \cos(\theta) & \sin(\theta) \\ -\sin(\theta) & \cos(\theta) \end{bmatrix} \begin{bmatrix} \cos(\theta) & \sin(\theta) \\ -\sin(\theta) & \cos(\theta) \end{bmatrix} \begin{bmatrix} \cos(\theta) & \sin(\theta) \\ -\sin(\theta) & \cos(\theta) \end{bmatrix} \begin{bmatrix} \cos(\theta) & \sin(\theta) \\ -\sin(\theta) & \cos(\theta) \end{bmatrix} \begin{bmatrix} \cos(\theta) & \sin(\theta) \\ -\sin(\theta) & \cos(\theta) \end{bmatrix} \begin{bmatrix} \cos(\theta) & \sin(\theta) \\ -\sin(\theta) & \cos(\theta) \end{bmatrix} \begin{bmatrix} \cos(\theta) & \sin(\theta) \\ -\sin(\theta) & \cos(\theta) \end{bmatrix} \begin{bmatrix} \cos(\theta) & \sin(\theta) \\ -\sin(\theta) & \cos(\theta) \end{bmatrix} \begin{bmatrix} \cos(\theta) & \sin(\theta) \\ -\sin(\theta) & \cos(\theta) \end{bmatrix} \begin{bmatrix} \cos(\theta) & \sin(\theta) \\ -\sin(\theta) & \cos(\theta) \end{bmatrix} \begin{bmatrix} \cos(\theta) & \sin(\theta) \\ -\sin(\theta) & \cos(\theta) \end{bmatrix} \begin{bmatrix} \cos(\theta) & \sin(\theta) \\ -\sin(\theta) & \cos(\theta) \end{bmatrix} \begin{bmatrix} \cos(\theta) & \sin(\theta) \\ -\sin(\theta) & \cos(\theta) \end{bmatrix} \begin{bmatrix} \cos(\theta) & \sin(\theta) \\ -\sin(\theta) & \cos(\theta) \end{bmatrix} \begin{bmatrix} \cos(\theta) & \cos(\theta) \\ -\sin(\theta) & \cos(\theta) \end{bmatrix} \begin{bmatrix} \cos(\theta) & \cos(\theta) \\ -\sin(\theta) & \cos(\theta) \end{bmatrix} \begin{bmatrix} \cos(\theta) & \cos(\theta) \\ -\sin(\theta) & \cos(\theta) \end{bmatrix} \begin{bmatrix} \cos(\theta) & \cos(\theta) \\ -\sin(\theta) & \cos(\theta) \end{bmatrix} \begin{bmatrix} \cos(\theta) & \cos(\theta) \\ -\sin(\theta) & \cos(\theta) \end{bmatrix} \begin{bmatrix} \cos(\theta) & \cos(\theta) \\ -\sin(\theta) & \cos(\theta) \end{bmatrix} \begin{bmatrix} \cos(\theta) & \cos(\theta) \\ -\sin(\theta) & \cos(\theta) \end{bmatrix} \begin{bmatrix} \cos(\theta) & \cos(\theta) \\ -\sin(\theta) & \cos(\theta) \end{bmatrix} \begin{bmatrix} \cos(\theta) & \cos(\theta) \\ -\sin(\theta) & \cos(\theta) \end{bmatrix} \begin{bmatrix} \cos(\theta) & \cos(\theta) \\ -\sin(\theta) & \cos(\theta) \end{bmatrix} \begin{bmatrix} \cos(\theta) & \cos(\theta) \\ -\sin(\theta) & \cos(\theta) \end{bmatrix} \begin{bmatrix} \cos(\theta) & \cos(\theta) \\ -\sin(\theta) & \cos(\theta) \end{bmatrix} \begin{bmatrix} \cos(\theta) & \cos(\theta) \\ -\sin(\theta) & \cos(\theta) \end{bmatrix} \begin{bmatrix} \cos(\theta) & \cos(\theta) \\ -\sin(\theta) & \cos(\theta) \end{bmatrix} \begin{bmatrix} \cos(\theta) & \cos(\theta) \\ -\sin(\theta) & \cos(\theta) \end{bmatrix} \begin{bmatrix} \cos(\theta) & \cos(\theta) \\ -\sin(\theta) & \cos(\theta) \end{bmatrix} \begin{bmatrix} \cos(\theta) & \cos(\theta) \\ -\sin(\theta) & \cos(\theta) \end{bmatrix} \begin{bmatrix} \cos(\theta) & \cos(\theta) \\ -\sin(\theta) & \cos(\theta) \end{bmatrix} \begin{bmatrix} \cos(\theta) & \cos(\theta) \\ -\sin(\theta) & \cos(\theta) \end{bmatrix} \begin{bmatrix} \cos(\theta) & \cos(\theta) \\ -\sin(\theta) & \cos(\theta) \end{bmatrix} \begin{bmatrix} \cos(\theta) & \cos(\theta) \\ -\sin(\theta) & \cos(\theta) \end{bmatrix} \begin{bmatrix} \cos(\theta) & \cos(\theta) \\ -\sin(\theta) & \cos(\theta) \end{bmatrix} \begin{bmatrix} \cos(\theta) & \cos(\theta) \\ -\sin(\theta) & \cos(\theta) \end{bmatrix} \begin{bmatrix} \cos(\theta) & \cos(\theta) \\ -\sin(\theta) & \cos(\theta) \end{bmatrix} \begin{bmatrix} \cos(\theta) & \cos(\theta) \\ -\sin(\theta) & \cos(\theta) \end{bmatrix} \begin{bmatrix} \cos(\theta) & \cos(\theta) \\ -\sin(\theta) & \cos(\theta) \end{bmatrix} \begin{bmatrix} \cos(\theta) & \cos(\theta) \\ -\sin(\theta) & \cos(\theta) \end{bmatrix} \begin{bmatrix} \cos(\theta) & \cos(\theta) \\ -\sin(\theta) & \cos(\theta) \end{bmatrix} \begin{bmatrix} \cos(\theta) & \cos(\theta) \\ -\sin(\theta) & \cos(\theta) \end{bmatrix} \begin{bmatrix} \cos(\theta) & \cos(\theta) \\ -\sin(\theta) & \cos(\theta) \end{bmatrix} \begin{bmatrix} \cos(\theta) & \cos(\theta) \\ -\sin(\theta) & \cos(\theta) \end{bmatrix} \begin{bmatrix} \cos(\theta) & \cos(\theta) \\ -\cos(\theta) & \cos(\theta) \end{bmatrix} \begin{bmatrix} \cos(\theta) & \cos(\theta) \\ -\cos(\theta) & \cos(\theta) \end{bmatrix} \begin{bmatrix} \cos(\theta) & \cos(\theta) \\ -\cos(\theta) & \cos(\theta) \end{bmatrix} \begin{bmatrix} \cos(\theta) & \cos(\theta) \\ -\cos(\theta) & \cos(\theta) \end{bmatrix} \begin{bmatrix} \cos(\theta) & \cos(\theta) \\ -\cos(\theta) & \cos(\theta) \end{bmatrix} \begin{bmatrix} \cos(\theta) & \cos(\theta) \\ -\cos(\theta) & \cos(\theta) \end{bmatrix} \begin{bmatrix} \cos(\theta) & \cos(\theta) \\ -\cos(\theta) & \cos(\theta) \end{bmatrix} \begin{bmatrix} \cos(\theta) & \cos(\theta) \\$$

(c) Conjecture the form of a simple expression for AK, K a positive integer. AK = [Gs (KO) Sin (KO)]

(d) Prove or disprove your conjecture in part (c).

Proof by induction on K (see hundout). Base cases K= Z, 3 almody done above.

Suppose Ah = [Cos (KO) Sin (KO)]. Need behow Ahr! = [Cos (Kri)O) Sin (Kri)O) .

Suppose Ah = [-Sin (KO) cos (KO)]. Need behow Ahr! = [-Sin (Kri)O) cos (Kri)O).

$$A^{H+1} = A^{H}A = \begin{bmatrix} \cos(k\theta) & \sin(k\theta) \\ -\sin(k\theta) & \cos(k\theta) \end{bmatrix} \begin{bmatrix} \cos(\theta) & \sin(\theta) \\ -\sin(\theta) & \cos(\theta) \end{bmatrix}$$

$$=\begin{bmatrix} G_{S}(k\theta)G_{S}(\theta) - Sin(k\theta)Sin(\theta) & G_{S}(k\theta)Sin(\theta) + Sin(k\theta)G_{S}(\theta) \\ -Sin(k\theta)G_{S}(\theta) - G_{S}(k\theta)Sin(\theta) & G_{S}(k\theta)G_{S}(\theta) - Sin(k\theta)Sin(\theta) \end{bmatrix}$$

as needed by the same trig. identities in (B).

## Hwk 2-p.5

1.4.10] Find two different zxz matrices A such that  $A^2 = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$ .

There are many.  $A = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$ ,  $A = \begin{bmatrix} -1 & 0 \\ 0 & -1 \end{bmatrix}$ ,  $A = \begin{bmatrix} -1 & 0 \\ 0 & -1 \end{bmatrix}$ ,  $A = \begin{bmatrix} -1 & 0 \\ 0 & -1 \end{bmatrix}$ ,  $A = \begin{bmatrix} -1 & 0 \\ 0 & -1 \end{bmatrix}$ .

1.4.12) Find two different 2x2 matrices A such that A2=0.

Again, there are many. A = [00] is the trivial one. Note for A = [96].

 $A^2 = \begin{bmatrix} \alpha^2 + \beta c & \beta(\alpha + \beta) \\ C(\alpha + \beta) & d^2 + \beta c \end{bmatrix}$  So  $\alpha = -\beta$  and  $\alpha^2 = -\beta c$ . Then we can see

 $A = \begin{bmatrix} 1 - 2 \\ 1/2 - 1 \end{bmatrix} , \begin{bmatrix} -1 & 1/3 \\ -3 & 1 \end{bmatrix} , \begin{bmatrix} 2 - 2 \\ 2 - 2 \end{bmatrix}$ 

1.4.221 Determine a Scalar r such that  $A\vec{x} = r\vec{x}$  when  $A = \begin{bmatrix} 2 & 1 \\ 1 & 2 \end{bmatrix}$  and  $\vec{x} = \begin{bmatrix} 1 \\ 1 \end{bmatrix} = \begin{bmatrix} 3 \\ 3 \end{bmatrix} = \begin{bmatrix} r \\ r \end{bmatrix} = r\vec{x}$  so r = 3.

1.4.32 Find three ZxZ matrices A, B, and C such that AB = AC with B = C and A = O.

Note this is A(B-c) = 0 by Thm 1.2 and 1.1.

Note that [10][00] = 0 so Set A = [00] and B - C = [00].

. Then Take B = [02] and C = [0].