

**Math 535 - General Topology**  
**Fall 2012**  
**Homework 10 Solutions**

**Problem 1.** Let **Top** denote the category of topological spaces and continuous maps, and let **CHaus** denote the category of compact Hausdorff topological spaces and continuous maps. Show that the Stone-Ćech construction

$$\beta: \mathbf{Top} \rightarrow \mathbf{CHaus}$$

is a functor.

Note: So far we know that  $\beta$  sends objects of **Top** to objects of **CHaus**. There remain three things to check.

**Solution.** 1)  $\beta$  sends morphisms to morphisms. Let  $f: X \rightarrow Y$  be a continuous map between topological spaces. Consider the diagram

$$\begin{array}{ccc} X & \xrightarrow{e_X} & \beta X \\ f \downarrow & & \downarrow \\ Y & \xrightarrow{e_Y} & \beta Y \end{array}$$

where the horizontal maps are the canonical evaluation maps. Note that  $\beta Y$  is compact Hausdorff, and the composite  $e_Y \circ f: X \rightarrow \beta Y$  is continuous. By the universal property of  $\beta X$ , there is a unique continuous map  $h: \beta X \rightarrow \beta Y$  making the diagram commute, i.e. satisfying

$$h \circ e_X = e_Y \circ f.$$

Define  $\beta f$  to be this map  $h$ .

2)  $\beta$  preserves composition. Consider a composite  $X \xrightarrow{f} Y \xrightarrow{g} Z$  and consider the diagram

$$\begin{array}{ccccc} & X & \xrightarrow{e_X} & \beta X & \\ & \downarrow f & & \downarrow \beta f & \\ g \circ f & \swarrow & Y & \xrightarrow{e_Y} & \beta Y & \searrow \beta g \circ \beta f \\ & \downarrow g & & \downarrow \beta g & \\ & Z & \xrightarrow{e_Z} & \beta Z & \end{array}$$

Note that the outer rectangle commutes because the two inner squares commute:

$$\begin{aligned} (\beta g \circ \beta f) \circ e_X &= \beta g \circ (\beta f \circ e_X) \\ &= \beta g \circ (e_Y \circ f) \\ &= (\beta g \circ e_Y) \circ f \\ &= (e_Z \circ g) \circ f \\ &= e_Z \circ (g \circ f). \end{aligned}$$

But  $\beta(g \circ f): \beta X \rightarrow \beta Z$  is the *unique* continuous map making the outer rectangle commute, which proves

$$\beta(g \circ f) = \beta g \circ \beta f.$$

**3)  $\beta$  preserves identities.** The diagram

$$\begin{array}{ccc} X & \xrightarrow{e_X} & \beta X \\ \text{id}_X \downarrow & & \downarrow \text{id}_{\beta X} \\ X & \xrightarrow{e_X} & \beta X \end{array}$$

commutes:

$$\text{id}_{\beta X} \circ e_X = e_X = e_X \circ \text{id}_X.$$

But  $\beta(\text{id}_X): \beta X \rightarrow \beta X$  is the *unique* continuous map making this diagram commute, which proves

$$\beta(\text{id}_X) = \text{id}_{\beta X}.$$

□

**Problem 2.** Let  $\mathbf{Top}_*$  denote the category of pointed topological spaces and pointed continuous maps. To a space  $X$ , one can associate the pointed space

$$X_+ := X \amalg \{*\}$$

(with the coproduct topology) called “ $X$  with a disjoint basepoint”, where  $*$   $\in X_+$  is the basepoint. To a continuous map  $f: X \rightarrow Y$ , one can assign the pointed continuous map

$$f_+ : (X_+, *) \rightarrow (Y_+, *)$$

defined by

$$\begin{cases} f_+(x) = f(x) & \text{if } x \in X \\ f_+(*) = *. \end{cases}$$

One readily checks that this assignment makes the disjoint basepoint construction

$$(-)_+ : \mathbf{Top} \rightarrow \mathbf{Top}_*$$

into a functor.

**a.** Show that for any space  $X$  and pointed space  $(Y, y_0)$ , there is a bijection

$$\mathrm{Hom}_{\mathbf{Top}_*}((X_+, *), (Y, y_0)) \cong \mathrm{Hom}_{\mathbf{Top}}(X, Y).$$

**Solution.** Let  $\varphi: \mathrm{Hom}_{\mathbf{Top}_*}((X_+, *), (Y, y_0)) \rightarrow \mathrm{Hom}_{\mathbf{Top}}(X, Y)$  be the restriction map defined by

$$\varphi(f) = f|_X.$$

In the other direction, consider the function  $\psi: \mathrm{Hom}_{\mathbf{Top}}(X, Y) \rightarrow \mathrm{Hom}_{\mathbf{Top}_*}((X_+, *), (Y, y_0))$  that sends a continuous map  $g: X \rightarrow Y$  to the map  $\psi(g): X_+ \rightarrow Y$  defined by

$$\psi(g)(x) = \begin{cases} g(x) & \text{if } x \in X \\ y_0 & \text{if } x = *. \end{cases}$$

By construction, the map  $\psi(g): (X_+, *) \rightarrow (Y, y_0)$  is pointed.

To prove moreover that  $\psi(g)$  is continuous, note that its restrictions  $\psi(g)|_X = g$  and  $\psi(g)|_{\{*\}} = y_0$  are both continuous. Thus  $\psi(g)$  is continuous, since  $X_+ = X \amalg \{*\}$  has the coproduct topology.

$\psi \circ \varphi = \mathrm{id}$ . Let  $f: (X_+, *) \rightarrow (Y, y_0)$  be a continuous pointed map. Then the map  $\psi\varphi(f) = \psi(f|_X): (X_+, *) \rightarrow (Y, y_0)$  is given by

$$\psi(f|_X)(x) = \begin{cases} f|_X(x) = f(x) & \text{if } x \in X \\ y_0 & \text{if } x = *. \end{cases}$$

Recall that  $f$  is pointed, i.e. it satisfies  $f(*) = y_0$ , so that  $\psi(f|_X)$  agrees with  $f$  everywhere. This proves  $\psi(f|_X) = f$ .

$\varphi \circ \psi = \mathrm{id}$ . Let  $g: X \rightarrow Y$  be a continuous map. Then we have  $\varphi\psi(f) = (\psi f)|_X = f$  by construction.  $\square$

**b.** Show that the bijection in part (a) induces a bijection

$$[(X_+, *), (Y, y_0)]_* \cong [X, Y]$$

where  $[(A, a_0), (B, b_0)]_* := \text{Hom}_{h\mathbf{Top}_*}((A, a_0), (B, b_0))$  denotes the set of pointed homotopy classes of pointed continuous maps from  $(A, a_0)$  to  $(B, b_0)$ .

As usual,  $[X, Y] := \text{Hom}_{h\mathbf{Top}}(X, Y)$  denotes the set of homotopy classes of continuous maps from  $X$  to  $Y$ .

**Solution.** Let  $f, f': (X_+, *) \rightarrow (Y, y_0)$  be pointed maps. The statement is that  $f$  and  $f'$  are pointed homotopic if and only if their restrictions  $\varphi(f) = f|_X$  and  $\varphi(f') = f'|_X$  are homotopic.

( $\Rightarrow$ ) Let  $F: X_+ \times [0, 1] \rightarrow Y$  be a pointed homotopy from  $f$  to  $f'$ . Then the restriction

$$F_{X \times [0, 1]}: X \times [0, 1] \rightarrow Y$$

is a homotopy from  $f|_X$  to  $f'|_X$ .

( $\Leftarrow$ ) Let  $G: X \times [0, 1] \rightarrow Y$  be a homotopy from  $f|_X$  to  $f'|_X$ . Consider the map

$$\tilde{G}: X_+ \times [0, 1] \cong (X \times [0, 1]) \amalg (\{*\} \times [0, 1]) \rightarrow Y$$

defined by

$$\begin{cases} \tilde{G}|_{X \times [0, 1]} = G \\ \tilde{G}(*, t) = y_0 \quad \text{for all } t \in [0, 1]. \end{cases}$$

In other words,  $\tilde{G}$  is obtained from  $G$  by applying  $\psi$  at each time:  $\tilde{g}_t = \psi(g_t)$ .

Then  $\tilde{G}$  is continuous since its restriction to each summand  $X \times [0, 1]$  and  $\{*\} \times [0, 1]$  is continuous. By construction  $\tilde{G}$  is a pointed homotopy, i.e. it satisfies  $\tilde{G}(*, t) = y_0$  for all  $t \in [0, 1]$ . In fact, it is a pointed homotopy between the pointed maps

$$\begin{aligned} \tilde{g}_0 &= \psi(g_0) = \psi(f|_X) = f \\ \tilde{g}_1 &= \psi(g_1) = \psi(f'|_X) = f' \end{aligned}$$

which are therefore pointed homotopic. □

**Problem 3.** Let  $X$  be a topological space.

**a.** Let  $w, x, y, z \in X$ ,  $\alpha: [0, 1] \rightarrow X$  a path from  $w$  to  $x$ ,  $\beta: [0, 1] \rightarrow X$  a path from  $x$  to  $y$ , and  $\gamma: [0, 1] \rightarrow X$  a path from  $y$  to  $z$ . Show that concatenation of paths is associative up to homotopy, in the following sense:

$$(\alpha * \beta) * \gamma \simeq \alpha * (\beta * \gamma) \text{ rel } \{0, 1\}.$$

**Solution.** Note that both sides are paths that go along  $\alpha$ ,  $\beta$ , and  $\gamma$  but at varying speeds. Given  $0 < \sigma_1 < \sigma_2 < 1$ , consider the path

$$\delta(\sigma_1, \sigma_2): [0, 1] \rightarrow X$$

from  $w$  to  $z$  defined by

$$\delta(\sigma_1, \sigma_2)(s) = \begin{cases} \alpha\left(\frac{s-0}{\sigma_1-0}\right) & \text{if } 0 \leq s \leq \sigma_1 \\ \beta\left(\frac{s-\sigma_1}{\sigma_2-\sigma_1}\right) & \text{if } \sigma_1 \leq s \leq \sigma_2 \\ \gamma\left(\frac{s-\sigma_2}{1-\sigma_2}\right) & \text{if } \sigma_2 \leq s \leq 1. \end{cases}$$

In this notation, we have:

$$(\alpha * \beta) * \gamma = \delta\left(\frac{1}{4}, \frac{1}{2}\right)$$

$$\alpha * (\beta * \gamma) = \delta\left(\frac{1}{2}, \frac{3}{4}\right).$$

Now if  $\sigma_1(t)$  and  $\sigma_2(t)$  are continuous functions of  $t$  satisfying  $0 < \sigma_1(t) < \sigma_2(t) < 1$  for all  $t \in [0, 1]$ , then the map  $H: [0, 1] \times [0, 1] \rightarrow X$  defined by

$$H(-, t) = h_t = \delta(\sigma_1(t), \sigma_2(t))$$

is continuous and satisfies

$$H(0, t) = \delta(\sigma_1(t), \sigma_2(t))(0) = w$$

$$H(1, t) = \delta(\sigma_1(t), \sigma_2(t))(1) = z$$

for all  $t \in [0, 1]$ , so that  $H$  is a path homotopy from  $h_0$  to  $h_1$ .

In the case at hand, take  $\sigma_1(t) = \frac{1}{4} + \frac{1}{4}t$  and  $\sigma_2(t) = \frac{1}{2} + \frac{1}{4}t$  to obtain a path homotopy  $H$  between

$$h_0 = \delta(\sigma_1(0), \sigma_2(0)) = \delta\left(\frac{1}{4}, \frac{1}{2}\right) = (\alpha * \beta) * \gamma$$

$$h_1 = \delta(\sigma_1(1), \sigma_2(1)) = \delta\left(\frac{1}{2}, \frac{3}{4}\right) = \alpha * (\beta * \gamma).$$

□

**b.** Let  $\alpha: [0, 1] \rightarrow X$  be a path in  $X$  from  $x$  to  $y$ . Denote by  $\bar{\alpha}: [0, 1] \rightarrow X$  the **reverse** path of  $\alpha$ , defined by

$$\bar{\alpha}(s) = \alpha(1 - s).$$

Show that  $\bar{\alpha}$  is inverse to  $\alpha$  up to homotopy, in the following sense:

$$\alpha * \bar{\alpha} \simeq 1_x \text{ rel } \{0, 1\}$$

where  $1_x: [0, 1] \rightarrow X$  denotes the constant path at  $x$ .

**Solution.** The left-hand side is the path given by

$$(\alpha * \bar{\alpha})(s) = \begin{cases} \alpha(2s) & \text{if } 0 \leq s \leq \frac{1}{2} \\ \bar{\alpha}(2s - 1) = \alpha(2 - 2s) & \text{if } \frac{1}{2} \leq s \leq 1 \end{cases}$$

which can be rewritten as  $\alpha * \bar{\alpha} = \alpha \circ p$  where  $p: [0, 1] \rightarrow [0, 1]$  is the “spike-shaped” function

$$p(s) = \begin{cases} 2s & \text{if } 0 \leq s \leq \frac{1}{2} \\ 2 - 2s & \text{if } \frac{1}{2} \leq s \leq 1. \end{cases}$$

It suffices to show that  $p$  is homotopic rel  $\{0, 1\}$  to the constant function 0 in order to conclude

$$\begin{aligned} \alpha * \bar{\alpha} &= \alpha \circ p \\ &\simeq \alpha \circ 0 \text{ rel } \{0, 1\} \\ &= \text{constant path at } \alpha(0) \\ &= 1_x \end{aligned}$$

as desired.

The map  $H: [0, 1] \times [0, 1] \rightarrow [0, 1]$  defined by

$$H(s, t) = tp(s)$$

is continuous and satisfies

$$H(0, t) = tp(0) = 0$$

$$H(1, t) = tp(1) = 0$$

for all  $t \in [0, 1]$ . Therefore  $H$  is a homotopy rel  $\{0, 1\}$  between  $h_0 = H(-, 0) \equiv 0$  and  $h_1 = H(-, 1) = p$  as desired.  $\square$

*Remark.* No need to check the condition  $\bar{\alpha} * \alpha \simeq 1_y \text{ rel } \{0, 1\}$ , which follows from part (b) applied to the path  $\bar{\alpha}$  and observing  $\overline{\bar{\alpha}} = \alpha$ .

*Remark.* We have earned the right to adopt the notation  $\bar{\alpha} = \alpha^{-1}$ .

**Definition.** Let  $A \subseteq X$  be a subspace of  $X$ , and denote by  $i: A \rightarrow X$  the inclusion. Then  $A$  is called...

- a **retract** of  $X$  if there is a continuous map  $r: X \rightarrow A$  satisfying  $r \circ i = \text{id}_A$ , in other words  $r(a) = a$  for all  $a \in A$ . Such a map  $r$  is called a **retraction** from  $X$  to  $A$ .
- a **deformation retract** of  $X$  if there is a retraction  $r: X \rightarrow A$  which is moreover a homotopy equivalence, i.e. satisfying  $i \circ r \simeq \text{id}_X$ .

Explicitly: There is a homotopy  $H: X \times [0, 1] \rightarrow X$  satisfying  $H(x, 0) = x$  for all  $x \in X$ ,  $H(x, 1) \in A$  for all  $x \in X$ , and  $H(a, 1) = a$  for all  $a \in A$ .

- a **strong deformation retract** of  $X$  if there is a retraction  $r: X \rightarrow A$  which moreover satisfies

$$i \circ r \simeq \text{id}_X \text{ rel } A.$$

Explicitly: There is a homotopy  $H: X \times [0, 1] \rightarrow X$  satisfying  $H(x, 0) = x$  for all  $x \in X$ ,  $H(x, 1) \in A$  for all  $x \in X$ , and  $H(a, t) = a$  for all  $a \in A$  and all  $t \in [0, 1]$ .

**Problem 4.** Consider the 2-simplex

$$\Delta^2 := \{(x, y) \in \mathbb{R}^2 \mid x + y \leq 1, x \geq 0, y \geq 0\}$$

and consider the subspace of  $\Delta^2$  consisting of points on the coordinate axes

$$A = \{(x, y) \in \Delta^2 \mid x = 0 \text{ or } y = 0\} = (\{0\} \times [0, 1]) \cup ([0, 1] \times \{0\}).$$

Show that  $A$  is a strong deformation retract of  $\Delta^2$ .

**Solution.** Write  $\Delta^2$  as the union  $\Delta^2 = C \cup D$  of two simplices with (ordered) vertices  $(0, 0), (0, 1), (\frac{1}{2}, \frac{1}{2})$  and  $(0, 0), (1, 0), (\frac{1}{2}, \frac{1}{2})$  respectively. In other words,  $C$  is the “top left” half of  $\Delta^2$  where  $y \geq x$ , while  $D$  is the “bottom right” half where  $y \leq x$ . Note that  $C$  and  $D$  are both closed (in  $\mathbb{R}^2$  and therefore in  $\Delta^2$ ).

For  $t \in [0, 1]$ , let  $C_t$  and  $D_t$  be the simplices with (ordered) vertices  $(0, 0), (0, 1), t(\frac{1}{2}, \frac{1}{2})$  and  $(0, 0), (1, 0), t(\frac{1}{2}, \frac{1}{2})$  respectively. Let  $H: \Delta^2 \times [0, 1] \rightarrow \Delta^2$  be the map defined as follows.

$H|_{C \times [0, 1]}(-, t)$  is the unique affine transformation sending  $C$  to  $C_t$ .

$H|_{D \times [0, 1]}(-, t)$  is the unique affine transformation sending  $D$  to  $D_t$ .

Note that both maps are continuous, since the vertices of  $C_t$  and  $D_t$  vary continuously as a function of  $t$ .

Also note that  $C \cap D$  is the segment joining  $(0, 0)$  and  $(\frac{1}{2}, \frac{1}{2})$ , and those two vertices are sent to  $(0, 0)$  and  $t(\frac{1}{2}, \frac{1}{2})$  by  $H|_{C \times [0, 1]}(-, t)$  and by  $H|_{D \times [0, 1]}(-, t)$ . Therefore the two maps agree on the intersection

$$(C \times [0, 1]) \cap (D \times [0, 1]) = (C \cap D) \times [0, 1]$$

and thus define a map  $H$  on  $(C \times [0, 1]) \cup (D \times [0, 1]) = \Delta^2 \times [0, 1]$ . Moreover  $H$  is continuous since the restrictions  $H|_{C \times [0, 1]}$  and  $H|_{D \times [0, 1]}$  are continuous, and both subsets  $C \times [0, 1]$  and  $D \times [0, 1]$  are closed in  $\Delta^2 \times [0, 1]$ .

For all  $t \in [0, 1]$ , the map  $H|_{C \times [0, 1]}(-, t)$  sends  $(0, 0)$  to  $(0, 0)$  and  $(0, 1)$  to  $(0, 1)$  and therefore (since it is affine) leaves every point on the vertical segment between  $(0, 0)$  to  $(0, 1)$  fixed.

Likewise, the map  $H|_{D \times [0, 1]}(-, t)$  leaves every point on the horizontal segment between  $(0, 0)$  to  $(1, 0)$  fixed. This proves  $H(a, t) = a$  for all  $a \in A$  and  $t \in [0, 1]$ .

The equalities  $C_1 = C$  and  $D_1 = D$  prove  $H(-, 1) = \text{id}_{\Delta^2}$ .

The equality  $C_0 \cup D_0 = A$  proves  $H(x, 0) \in A$  for all  $x \in \Delta^2$ .

Therefore  $H$  is a homotopy rel  $A$  between  $\text{id}_{\Delta^2}$  and a retraction  $\Delta^2 \rightarrow A$ . □

*Remark.* A straightforward calculation yields the explicit formula of  $H$ :

$$h_t(x, y) = \begin{cases} (tx, y - x + tx) & \text{if } y \geq x \\ (x - y + ty, ty) & \text{if } y \leq x. \end{cases}$$



**Problem 5.** Two objects  $X$  and  $Y$  of a category  $\mathcal{C}$  are **connected by morphisms** if there is a zigzag of morphisms between them. More precisely, there is a finite sequence of objects

$$X = X_0, X_1, \dots, X_{n-1}, X_n = Y$$

and for every  $0 \leq i < n$ , there is a morphism  $f_i: X_i \rightarrow X_{i+1}$  or  $f_i: X_{i+1} \rightarrow X_i$ .

**a.** Show that two objects  $X$  and  $Y$  of a groupoid  $\mathcal{G}$  are connected by morphisms if and only if there is a morphism  $f: X \rightarrow Y$ .

**Solution.** ( $\Leftarrow$ ) The morphism  $f: X \rightarrow Y$  exhibits  $X$  and  $Y$  as being connected by morphisms, i.e.  $X_0 = X$ ,  $X_1 = Y$ ,  $f_0 = f$ .

( $\Rightarrow$ ) Assume there is a zigzag of morphisms  $f_i$  from  $X = X_0$  to  $Y = X_n$ . Since  $\mathcal{G}$  is a groupoid, every morphism has an inverse, and we can define morphisms  $g_i: X_i \rightarrow X_{i+1}$  by

$$g_i = \begin{cases} f_i & \text{if } f_i: X_i \rightarrow X_{i+1} \\ f_i^{-1} & \text{if } f_i: X_{i+1} \rightarrow X_i. \end{cases}$$

Then the composite

$$\begin{array}{ccccccc} X = X_0 & \xrightarrow{g_0} & X_1 & \xrightarrow{g_1} & \dots & \longrightarrow & X_{n-1} & \xrightarrow{g_{n-1}} & X_n = Y \\ & & & & & & \searrow & \nearrow & \\ & & & & & & f := g_{n-1} \circ \dots \circ g_1 \circ g_0 & & \end{array}$$

is a morphism from  $X$  to  $Y$ . □

*Remark.* In particular, two points  $x$  and  $y$  in a space  $X$  are connected by morphisms in the fundamental groupoid  $\Pi_1(X)$  if and only if they lie in the same path component of  $X$ .

**b.** Find an example of category  $\mathcal{C}$  and objects  $X$  and  $Y$  of  $\mathcal{C}$  that are connected by morphisms, but such that there are no morphisms from  $X$  to  $Y$  and no morphisms from  $Y$  to  $X$ :

$$\mathrm{Hom}_{\mathcal{C}}(X, Y) = \emptyset \text{ and } \mathrm{Hom}_{\mathcal{C}}(Y, X) = \emptyset.$$

**Solution.** Let  $\mathcal{C}$  be the category described by the graph

$$\begin{array}{ccc} Z & \xrightarrow{g} & Y \\ f \downarrow & & \\ X. & & \end{array}$$

More precisely,  $\mathcal{C}$  has three objects  $\mathrm{Ob}(\mathcal{C}) = \{X, Y, Z\}$  and only two non-identity morphisms  $f: Z \rightarrow X$  and  $g: Z \rightarrow Y$ . This automatically forms a category, since no non-identity morphisms are composable.

The objects  $X$  and  $Y$  are connected by the zigzag of morphisms

$$X \xleftarrow{f} Z \xrightarrow{g} Y$$

but by definition, there are no morphisms  $X \rightarrow Y$  or  $Y \rightarrow X$ . □

**c.** Let  $X$  and  $Y$  be objects of a groupoid  $\mathcal{G}$  that are connected by morphisms. Show that the vertex groups at  $X$  and  $Y$  are isomorphic (as groups):

$$\mathrm{Aut}_{\mathcal{G}}(X) \simeq \mathrm{Aut}_{\mathcal{G}}(Y).$$

**Solution.** By part (a), let  $f: X \rightarrow Y$  be a morphism. Consider the map  $\varphi^f: \mathrm{Aut}_{\mathcal{G}}(Y) \rightarrow \mathrm{Aut}_{\mathcal{G}}(X)$  defined by

$$\varphi^f(g) = f^{-1} \circ g \circ f.$$

**$\varphi^f$  is a group homomorphism.**

$$\begin{aligned} \varphi^f(g_1 \circ g_2) &= f^{-1} \circ g_1 \circ g_2 \circ f \\ &= f^{-1} \circ g_1 \circ f \circ f^{-1} \circ g_2 \circ f \\ &= \varphi^f(g_1) \circ \varphi^f(g_2). \end{aligned}$$

**$\varphi^f$  is invertible.** In fact its inverse is  $\varphi^{f^{-1}}: \mathrm{Aut}_{\mathcal{G}}(X) \rightarrow \mathrm{Aut}_{\mathcal{G}}(Y)$ .

For any  $g \in \mathrm{Aut}_{\mathcal{G}}(Y)$  we have:

$$\begin{aligned} \varphi^{f^{-1}} \varphi^f(g) &= \varphi^{f^{-1}}(f^{-1} \circ g \circ f) \\ &= (f^{-1})^{-1} \circ f^{-1} \circ g \circ f \circ f^{-1} \\ &= f \circ f^{-1} \circ g \circ f \circ f^{-1} \\ &= \mathrm{id}_Y \circ g \circ \mathrm{id}_Y \\ &= g. \end{aligned}$$

Likewise, we have  $\varphi^f \varphi^{f^{-1}}(g) = g$  for all  $g \in \mathrm{Aut}_{\mathcal{G}}(X)$ . □

*Remark.* This proves in particular that if  $x$  and  $y$  are two points in the same path component of a space  $X$ , then the fundamental groups  $\pi_1(X, x)$  and  $\pi_1(X, y)$  are isomorphic.

**Problem 6.** Let  $f: X \xrightarrow{\sim} Y$  be a homotopy equivalence between topological spaces. Show that for any choice of basepoint  $x_0 \in X$ , the induced group homomorphism

$$\pi_1(f): \pi_1(X, x_0) \rightarrow \pi_1(Y, f(x_0))$$

is an isomorphism.

**Solution.** Note: We omit “homotopy classes” of paths to ease the notation, i.e. write  $\gamma$  instead of  $[\gamma]$ .

**Lemma.** Let  $f, f': X \rightarrow Y$  be two continuous maps, and let  $H: X \times [0, 1] \rightarrow Y$  be a homotopy (unpointed) from  $f$  to  $f'$ . Then for any basepoint  $x_0 \in X$ , the induced maps  $\pi_1(f)$  and  $\pi_1(f')$  differ by a “change of basepoint” isomorphism

$$\begin{array}{ccc} \pi_1(X, x_0) & \xrightarrow{\pi_1(f)} & \pi_1(Y, f(x_0)) \\ & \searrow \pi_1(f') & \uparrow \varphi^\alpha \\ & & \pi_1(Y, f'(x_0)) \end{array}$$

where  $\varphi^\alpha: \pi_1(Y, f'(x_0)) \xrightarrow{\sim} \pi_1(Y, f(x_0))$  is the group isomorphism (c.f. Problem 5c)

$$\varphi^\alpha(\gamma) = \alpha * \gamma * \alpha^{-1}$$

induced by the path  $\alpha$  in  $Y$  from  $f(x_0)$  to  $f'(x_0)$  given by  $\alpha(t) = H(x_0, t)$ .

In particular,  $\pi_1(f)$  is an isomorphism if and only if  $\pi_1(f')$  is.

*Proof.* Let  $\gamma: [0, 1] \rightarrow X$  be a loop based at  $x_0$ . Then the two loops in  $Y$  being compared are

$$\pi_1(f)(\gamma) = f(\gamma) = h_0(\gamma)$$

and

$$\pi_1(f')(\gamma) = f'(\gamma) = h_1(\gamma)$$

and they are based at different points:  $f(x_0)$  and  $f'(x_0)$  respectively. In fact, for any  $t \in [0, 1]$ ,  $h_t(\gamma)$  is a loop in  $Y$  based at  $h_t(x_0) \in Y$ .

Consider the loop in  $Y$  based at  $f(x_0)$  that first runs along  $\alpha$  up to  $\alpha(t)$ , then goes through the loop  $h_t(\gamma)$ , then comes back to  $f(x_0)$  along  $\alpha^{-1}$ :

$$a_t: [0, 1 + 2t] \rightarrow Y$$

$$a_t(s) = \begin{cases} \alpha(s) & \text{if } 0 \leq s \leq t \\ h_t(s - t) & \text{if } t \leq s \leq 1 + t \\ \alpha(t - (s - 1 - t)) = \alpha(1 + 2t - s) & \text{if } 1 + t \leq s \leq 1 + 2t. \end{cases}$$

Then  $a_t$  is continuous because  $\alpha$  and  $H$  are. Reparametrizing to the interval  $[0, 1]$  yields the loop  $b_t: [0, 1] \rightarrow Y$  defined by

$$b_t(s) = a_t(s(1 + 2t)).$$

Now the map  $B: [0, 1] \times [0, 1] \rightarrow Y$  defined by  $B(s, t) = b_t(s)$  is continuous and satisfies the endpoint conditions

$$B(0, t) = b_t(0) = a_t(0) = f(x_0)$$

$$B(1, t) = b_t(1) = a_t(1 + 2t) = f(x_0)$$

for all  $t \in [0, 1]$ . Therefore  $B$  is a pointed homotopy from the loop

$$b_0 = a_0 = h_0(\gamma) = f(\gamma)$$

to the loop

$$b_1 \simeq \alpha * h_1(\gamma) * \alpha^{-1} = \varphi^\alpha(h_1(\gamma)) = \varphi^\alpha(f'(\gamma))$$

which proves  $\pi_1(f) = \varphi^\alpha \circ \pi_1(f')$ . □

Let  $g: Y \rightarrow X$  be a homotopy inverse of  $f: X \rightarrow Y$ . Consider the composite

$$\begin{array}{ccccc} \pi_1(X, x_0) & \xrightarrow{\pi_1(f)} & \pi_1(Y, f(x_0)) & \xrightarrow{\pi_1(g)} & \pi_1(X, g(f(x_0))) \\ & & \searrow \quad \quad \quad \nearrow & & \\ & & \simeq & & \\ & & \pi_1(g \circ f) & & \end{array}$$

where  $\pi_1(g) \circ \pi_1(f) = \pi_1(g \circ f)$  is an isomorphism by the lemma. Indeed,  $g \circ f$  is (unpointed) homotopic to  $\text{id}_X$ , and  $\pi_1(\text{id}_X)$  is an isomorphism. Therefore  $\pi_1(f)$  is injective and  $\pi_1(g)$  is surjective.

Since the basepoint was arbitrary, the argument also applies to the homotopy equivalence  $g: Y \xrightarrow{\simeq} X$  and basepoint  $f(x_0) \in Y$ , so that

$$\pi_1(g): \pi_1(Y, f(x_0)) \rightarrow \pi_1(X, g(f(x_0)))$$

is also injective, and thus an isomorphism.

Therefore  $\pi_1(f) = \pi_1(g)^{-1} \circ \pi_1(g \circ f)$  is an isomorphism. □

**Alternate proof that  $\pi_1(f)$  is surjective.** Consider the diagram

$$\begin{array}{ccccc}
 & & \pi_1(f \circ g) & & \\
 & \nearrow & \simeq & \searrow & \\
 \pi_1(Y, f(x_0)) & \xrightarrow{\pi_1(g)} & \pi_1(X, g(f(x_0))) & \xrightarrow{\pi_1(f)} & \pi_1(Y, f(g(f(x_0)))) \\
 & \downarrow \varphi^\alpha \simeq & & & \downarrow \varphi^{f(\alpha)} \simeq \\
 & \pi_1(X, x_0) & \xrightarrow{\pi_1(f)} & \pi_1(Y, f(x_0)) & 
 \end{array}$$

where the top composite is an isomorphism, again by the lemma. Here  $\alpha$  denotes the path in  $X$  from  $x_0$  to  $g(f(x_0))$  given by  $\alpha(t) = H(x_0, t)$  where  $H$  is a homotopy from  $\text{id}_X$  to  $g \circ f$ .

The square on the right commutes. For any  $\gamma \in \pi_1(X, g(f(x_0)))$  we have

$$\begin{aligned}
 \pi_1(f) \circ \varphi^\alpha(\gamma) &= \pi_1(f)(\alpha * \gamma * \alpha^{-1}) \\
 &= f(\alpha * \gamma * \alpha^{-1}) \\
 &= f(\alpha) * f(\gamma) * f(\alpha^{-1}) \\
 &= f(\alpha) * f(\gamma) * f(\alpha)^{-1} \\
 &= \varphi^{f(\alpha)}(f(\gamma)) \\
 &= \varphi^{f(\alpha)} \circ \pi_1(f)(\gamma).
 \end{aligned}$$

It follows that the composite

$$\varphi^{f(\alpha)} \circ \pi_1(f) \circ \pi_1(g) = \pi_1(f) \circ \varphi^\alpha \circ \pi_1(g)$$

is an isomorphism. Therefore the last step  $\pi_1(f): \pi_1(X, x_0) \rightarrow \pi_1(Y, f(x_0))$  is surjective.  $\square$