INTRO TO DATA SCIENCE LECTURE 13: DIMENSIONALITY REDUCTION

YUCHEN ZHAO / DAT-14

LAST TIME:

- SVM'S
- HARD/SOFT MARGIN CLASSIFIERS
- KERNEL METHODS FOR NONLINEAR CLASSIFICATION

I. DIMENSIONALITY REDUCTION
II. PRINCIPAL COMPONENTS ANALYSIS
III. SINGULAR VALUE DECOMPOSITION

EXERCISE:

IV. DIMENSIONALITY REDUCTION IN SCIKIT-LEARN

I. DIMENSIONALITY REDUCTION

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In general, the idea is to regard the dataset is a matrix and to decompose the matrix into simpler, meaningful pieces.

Dimensionality reduction is frequently performed as a pre-processing step before another learning algorithm is applied.

DIMENSIONALITY REDUCTION

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The number of features in our dataset can be difficult to manage, or even misleading (eg, if the relationships are actually simpler than they appear).

For example, suppose we have a dataset with some features that are related to each other.

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If these relationships are linear, then we can use well-established techniques like PCA/SVD.

EXAMPLE: 1D HARMONIC OSCILLATOR

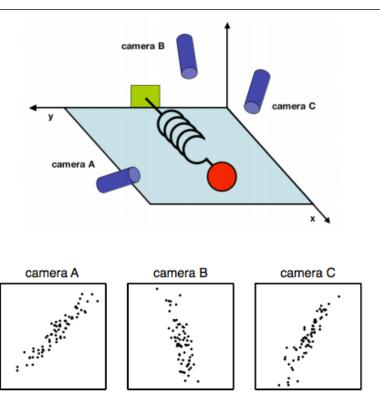


FIG. 1 A toy example. The position of a ball attached to an oscillating spring is recorded using three cameras A, B and C. The position of the ball tracked by each camera is depicted in each panel below.

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Namely, the sample size needed to accurately estimate a random variable taking values in a d-dimensional feature space grows exponentially with d (almost).

Another way of characterizing this is to say that high-dimensional spaces are inherently sparse.

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This illustrates the fact that local methods will break down in these circumstances (eg, in order to collect enough neighbors for a given point, you need to expand the radius of the neighborhood so far that locality is not preserved).

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The bottom line is that high-dimensional spaces can be problematic.

We'd like to analyze the data using the most meaningful basis (or coordinates) possible.

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More precisely: given an $n \times d$ matrix A (encoding n observations of a d-dimensional random variable), we want to find a k-dimensional representation of A (k < d) that captures the information in the original data, according to some criterion.

- reduce computational expense
- reduce susceptibility to overfitting
- reduce noise in the dataset
- enhance our intuition

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NOTE

We've already seen one example of feature selection for regression: backward elimination.

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feature extraction — mapping the features to a lower dimensional space

Feature selection is important, but typically when people say dimensionality reduction, they are referring to feature extraction.

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The goal of feature extraction is to create a new set of coordinates that simplify the representation of the data.

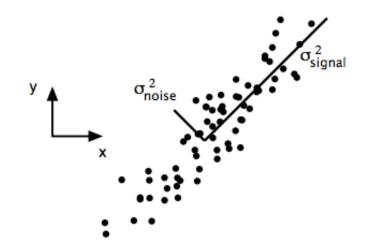
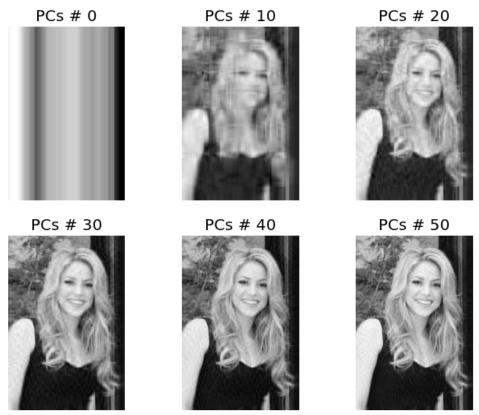


FIG. 2 Simulated data of (x,y) for camera A. The signal and noise variances σ_{signal}^2 and σ_{noise}^2 are graphically represented by the two lines subtending the cloud of data. Note that the largest direction of variance does not lie along the basis of the recording (x_A, y_A) but rather along the best-fit line.

Q: What are some applications of dimensionality reduction?

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- topic models (document clustering)
- image recognition/computer vision
- bioinformatics (microarray analysis)
- speech recognition
- astronomy (spectral data analysis)
- recommender systems



source: http://glowingpython.blogspot.it/2011/07/pca-and-image-compression-with-numpy.html

II. PRINCIPAL COMPONENT ANALYSIS

Principal Component Analysis is a dimension reduction technique that can be used on a matrix of any dimensions.

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The PCA of a matrix A boils down to the eigenvalue decomposition of the covariance matrix of A.

what is variance?

$$s^{2} = \frac{\sum_{i=1}^{n} (X_{i} - \bar{X})^{2}}{(n-1)}$$

Variance is the average distance from the mean of a data set to a point in that data set.

In other words, it is a measure of the *spread* of the data. Recall that standard deviation is the square root of variance.

what is covariance?

covariance is a measure of how much two random variables change together

Variance:

$$s^{2} = \frac{\sum_{i=1}^{n} (X_{i} - \bar{X})^{2}}{(n-1)} \qquad var(X) = \frac{\sum_{i=1}^{n} (X_{i} - \bar{X})(X_{i} - \bar{X})}{(n-1)}$$

Covariance: $cov(X,Y) = \frac{\sum_{i=1}^{n} (X_i - \bar{X})(Y_i - \bar{Y})}{(n-1)}$

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The covariance matrix C of a matrix A is always square:

$$C = \begin{bmatrix} E[(X_1 - \mu_1)(X_1 - \mu_1)] & E[(X_1 - \mu_1)(X_2 - \mu_2)] & \cdots & E[(X_1 - \mu_1)(X_n - \mu_n)] \\ E[(X_2 - \mu_2)(X_1 - \mu_1)] & E[(X_2 - \mu_2)(X_2 - \mu_2)] & \cdots & E[(X_2 - \mu_2)(X_n - \mu_n)] \\ \vdots & \vdots & \ddots & \vdots \\ E[(X_n - \mu_n)(X_1 - \mu_1)] & E[(X_n - \mu_n)(X_2 - \mu_2)] & \cdots & E[(X_n - \mu_n)(X_n - \mu_n)] \end{bmatrix}.$$

- off-diagonal elements C_{ij} give the covariance between $X_i, X_i \ (i \neq j)$
- diagonal elements C_{ii} give the variance of X_i

$$A = Q \Lambda Q^{-1}$$

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The columns of Q are the eigenvectors of A, and the values in Λ are the associated eigenvalues of A.

$$A = \begin{bmatrix} -1/2 & 3/2 \\ 3/2 & -1/2 \end{bmatrix}$$
$$= \left(\frac{1}{\sqrt{2}} \begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix}\right) \begin{bmatrix} 1 & 0 \\ 0 & -2 \end{bmatrix} \left(\frac{1}{\sqrt{2}} \begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix}\right)^{T}$$

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For an eigenvector v of A and its eigenvalue λ , we have the important relation:

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NOTE

This relationship defines what it means to be an eigenvector of

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$$Av = \lambda v$$

The eigenvectors form a basis of the vector space on which A acts (eg, they are orthogonal).

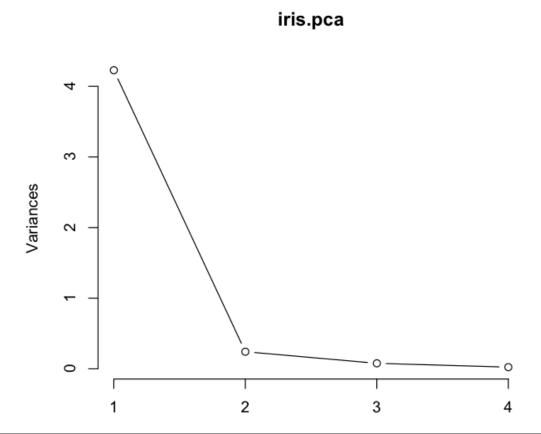
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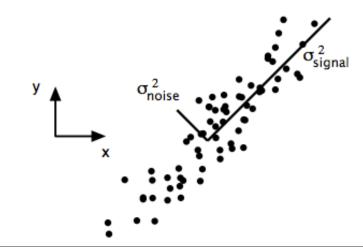
This can be visualized in a scree plot, which shows the amount of variance explained by each basis vector.



1. Linearity — The change in basis is a linear projection

2. Large variances have important structure

we assume that principal components with larger associated variances are signal, while those with lower variances represent noise.



3. The principal components are **orthogonal**

III. SINGULAR VALUE DECOMPOSITION

The singular value decomposition of A is given by:

 $\mathbf{M} = \mathbf{U} \; \mathbf{\Sigma} \; \mathbf{V}^{\mathrm{T}}$

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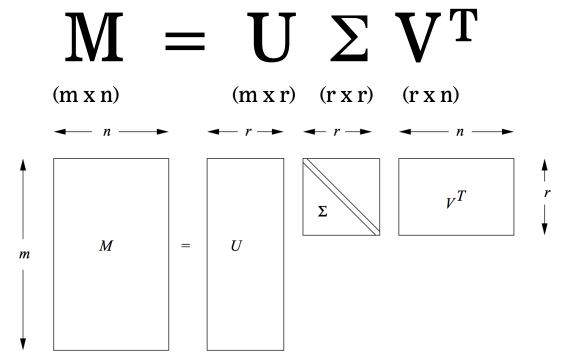
$$\mathbf{M} = \mathbf{U} \sum_{(\mathbf{m} \times \mathbf{r})} \mathbf{V}^{\mathbf{T}}$$

The singular value decomposition of A is given by:

$$\mathbf{M} = \mathbf{U} \sum_{(\mathbf{m} \times \mathbf{n})} \mathbf{V}^{\mathbf{T}}$$

st. U, V are orthogonal matrices and Σ is a diagonal matrix.

The singular value decomposition of M is given by:



Ratings of movies by users:

Matrix	Alien	Star Wars	Casablanca	Titanic
1	1	1	0	0
3	3	3	0	0
4	4	4	0	0
5	5	5	0	0
0	0	0	4	4
0	0	0	5	5
0	0	0	2	2
	1 3 4 5 0	1 1 3 3 4 4 5 5 0 0 0 0	1 1 1 3 3 3 4 4 4 5 5 5 0 0 0 0 0	1 1 1 0 3 3 3 0 4 4 4 0 5 5 5 0 0 0 0 4 0 0 0 5

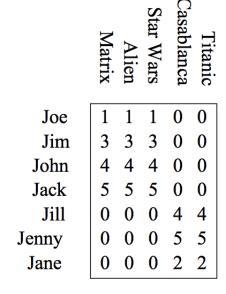
Ratings of movies by users:

```
Casablanca
                       Star Wars
              Matrix
                               Titanic
    Joe
    Jim
  John
  Jack
    Jill
Jenny
 Jane
```

there are two "concepts" underlying the movies:

science-fiction and romance

Ratings of movies by users:



All the boys rate only science-fiction All the girls rate only romance

SINGULAR VALUE DECOMPOSITION - EXAMPLE

Ratings of movies by users:

$$\begin{bmatrix} 1 & 1 & 1 & 0 & 0 \\ 3 & 3 & 3 & 0 & 0 \\ 4 & 4 & 4 & 0 & 0 \\ 5 & 5 & 5 & 0 & 0 \\ 0 & 0 & 0 & 4 & 4 \end{bmatrix} = \begin{bmatrix} .14 & 0 \\ .42 & 0 \\ .56 & 0 \\ .70 & 0 \\ 0 & .60 \end{bmatrix}$$

0

.75

.30

 Σ

12.4

0

Joe Jim 3 3 3 0 0

John 4 4 4 0 0

Jack 5 5 5 0 0

Jill 0 0 0 4 4

Jenny Jane 0 0 0 2 2

.58

Matrix

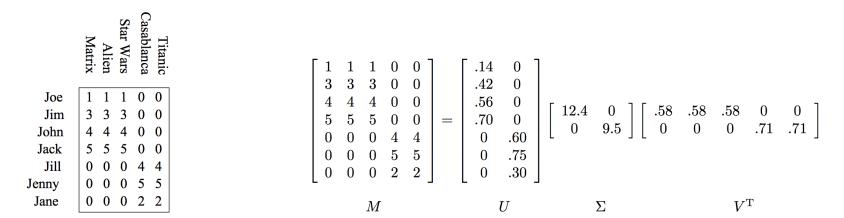
Alien

Casablanca Star Wars

Titanic

 $V^{
m T}$

M



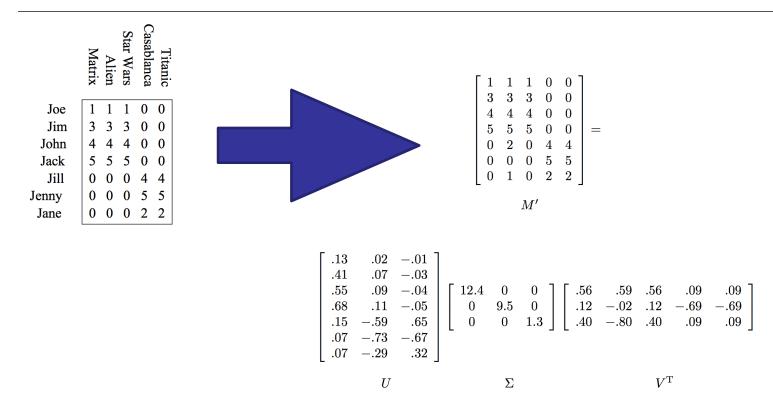
M: people -> movies

U: people -> concepts

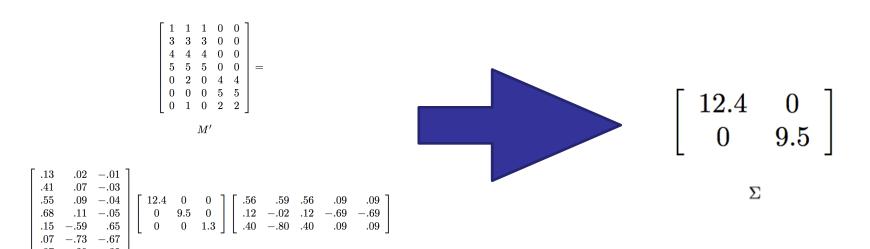
V: concepts -> movies

Σ: the strength of each of the concepts

SINGULAR VALUE DECOMPOSITION - A MORE REALISTIC EXAMPLE



How to reduce dimensions? <u>Drop Low Singular Values</u> -> eliminate corresponding rows of U and V

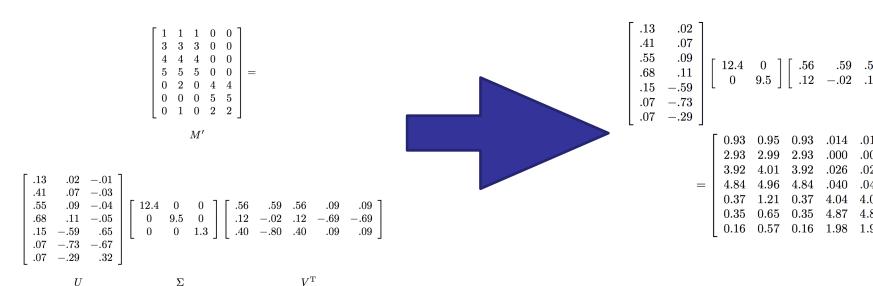


 Σ

U

SINGULAR VALUE DECOMPOSITION - EXAMPLE

How to reduce dimensions? <u>Drop Low Singular Values</u>



source: http://infolab.stanford.edu/~ullman/mmds/ch11.pdf

INTRO TO DATA SCIENCE

IV. LAB