deep-rnn

April 16, 2019

1 Deep Recurrent Neural Networks

Hidden state update

$$\mathbf{H}_{t}^{(1)} = f_{1}\left(\mathbf{X}_{t}, \mathbf{H}_{t-1}^{(1)}\right)$$

$$\mathbf{H}_{t}^{(l)} = f_{l}\left(\mathbf{H}_{t}^{(l-1)}, \mathbf{H}_{t-1}^{(l)}\right)$$

Output update

$$\mathbf{O}_t = g\left(\mathbf{H}_t^{(L)}\right)$$

Same parameters as before for training.

1.0.1 Training

epoch 500, perplexity 1.028183, time 0.06 sec

- traveller. 'but now you begin to see the object of my inves
- time traveller. 'but now you begin to see the object of my inves epoch 1000, perplexity 1.020994, time $0.05~{\rm sec}$
- traveller. 'but now you begin to see the object of my inves
- time traveller. 'but now you begin to see the object of my inves epoch 1500, perplexity 1.015552, time 0.05 sec
- traveller. 'but now you begin to see the object of my inves
- time traveller. 'but now you begin to see the object of my inves epoch 2000, perplexity 1.014056, time 0.05 sec
- traveller. 'but now you begin to see the object of my inves
- time traveller. 'but now you begin to see the object of my inves epoch 2500, perplexity 1.014954, time 0.06 sec
- traveller. 'but now you begin to see the object of my inves
- time traveller. 'but now you begin to see the object of my inves epoch 3000, perplexity 1.017568, time $0.05~{\rm sec}$
- traveller. 'but now you begin to see the object of my inves
- time traveller. 'but now you begin to see the object of my inves