Introduction to Deep Learning

6. Multilayer Perceptron

STAT 157, Spring 2019, UC Berkeley

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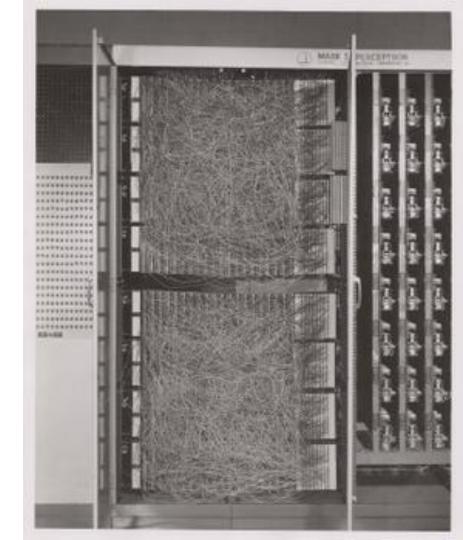
Outline

- Single Layer Perceptron
 - Decision Boundary
 - XOR is hard
- Multilayer Perceptron
 - Layers
 - Nonlinearities
 - Computational Cost



Perceptron

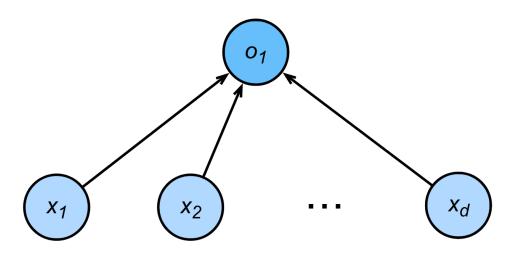
Mark I Perceptron, 1960 (wikipedia.org)



Perceptron

• Given input x, weight w and bias b, perceptron outputs:

$$o = \sigma(\langle \mathbf{w}, \mathbf{x} \rangle + b)$$
 $\sigma(x) = \begin{cases} 1 & \text{if } x > 0 \\ 0 & \text{otherwise} \end{cases}$





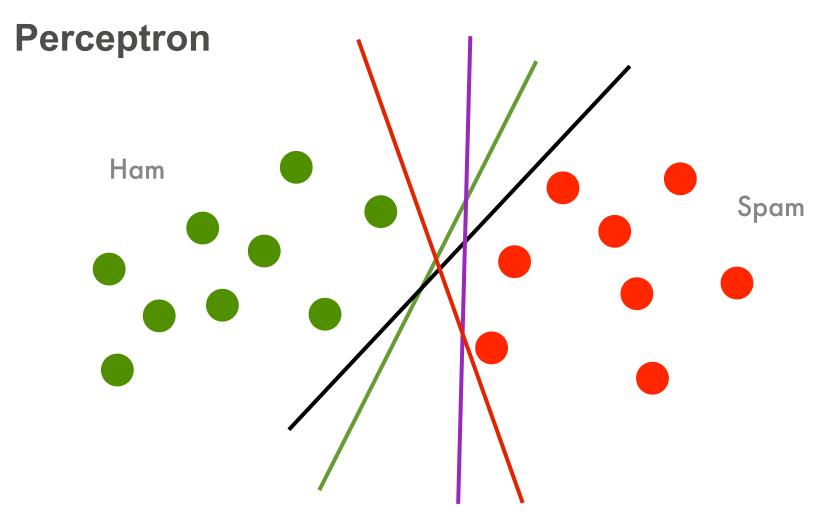
Perceptron

Given input x, weight w and bias b, perceptron outputs:

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- Binary classification (0 or 1)
 - Vs. scalar real value for regression
 - Vs. probabilities for logistic regression







Training the Perceptron

initialize w = 0 and b = 0repeat if $y_i [\langle w, x_i \rangle + b] < 0$ the

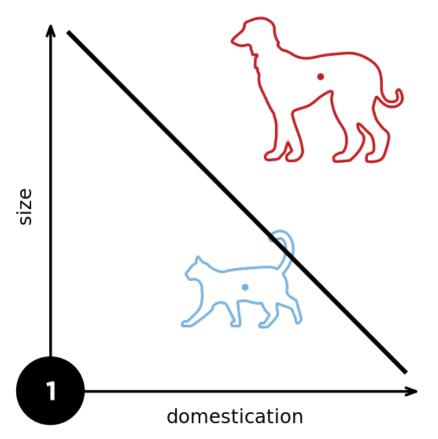
if $y_i [\langle w, x_i \rangle + b] \leq 0$ then $w \leftarrow w + y_i x_i$ and $b \leftarrow b + y_i$

end if

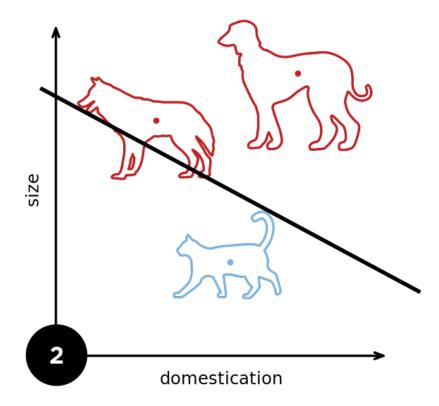
until all classified correctly

Equals to SGD (batch size is 1) with the following loss $\ell(y,\mathbf{x},\mathbf{w}) = \max(0,-y\langle\mathbf{w},\mathbf{x}\rangle)$

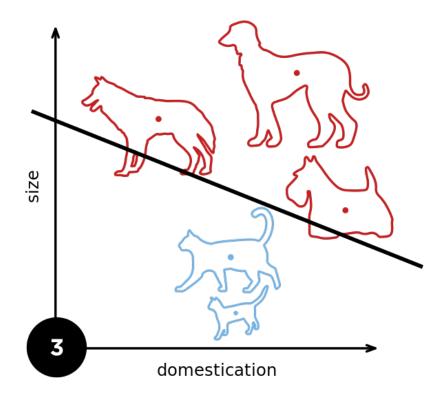




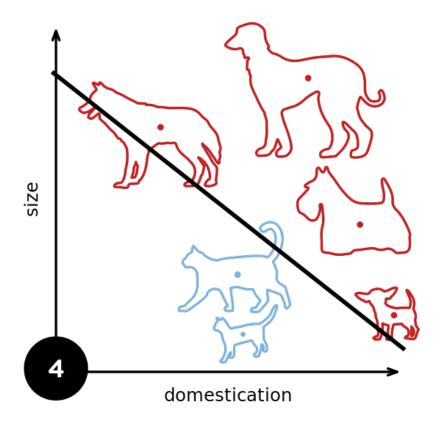














Convergence Theorem

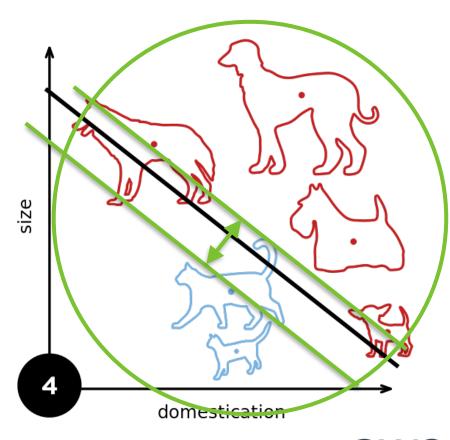
- Radius r enclosing the data
- Margin \(\rho \) separating the classes

$$y(\mathbf{x}^{\mathsf{T}}\mathbf{w} + b) \ge \rho$$

for
$$\|\mathbf{w}\|^2 + b^2 \le 1$$

Guaranteed that perceptron will converge after

$$\frac{r^2+1}{\rho^2}$$
 steps





Consequences

- Only need to store errors.
 This gives a compression bound for perceptron.
- Fails with noisy data

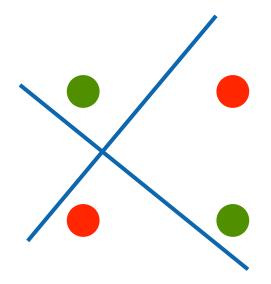
do NOT train your avatar with perceptrons





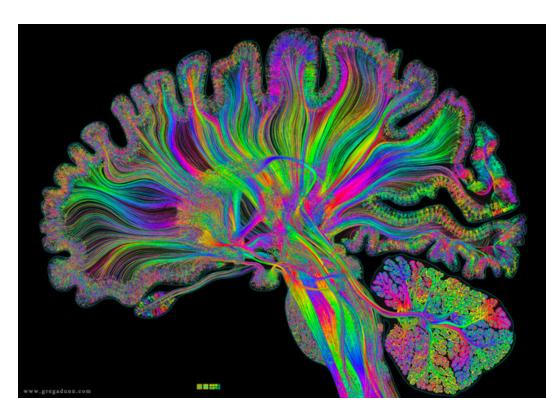
XOR Problem (Minsky & Papert, 1969)

The perceptron cannot learn an XOR function (neurons can only generate linear separators)



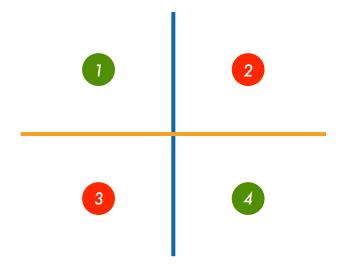


Multilayer Perceptron



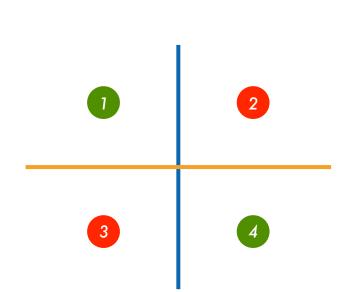


Learning XOR





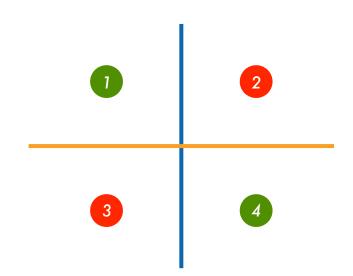
Learning XOR



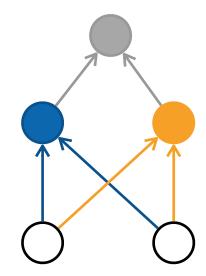
	1	2	3	4
	+	-	+	-
	+	+	-	-
product	+	-	-	+



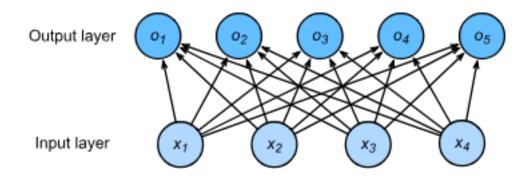
Learning XOR



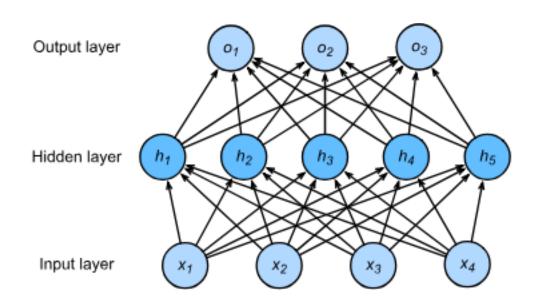
	1	2	3	4
	+	-	+	-
	+	+	-	-
product	+	-	-	+











Hyperparameter - size m of hidden layer



- Input $\mathbf{x} \in \mathbb{R}^n$
- Hidden $\mathbf{W}_1 \in \mathbb{R}^{m \times n}, \mathbf{b}_1 \in \mathbb{R}^m$
- Output $\mathbf{w}_2 \in \mathbb{R}^m, b_2 \in \mathbb{R}$

$$\mathbf{h} = \sigma(\mathbf{W}_1 \mathbf{x} + \mathbf{b}_1)$$

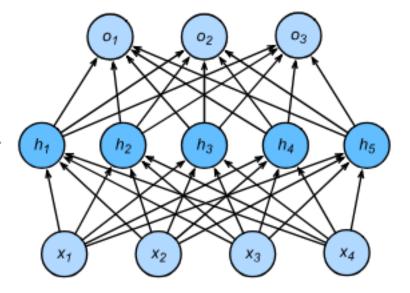
$$\mathbf{o} = \mathbf{w}_2^T \mathbf{h} + b_2$$

 σ is an element-wise activation function

Output layer

Hidden layer

Input layer





Why do we need an a nonlinear activation?

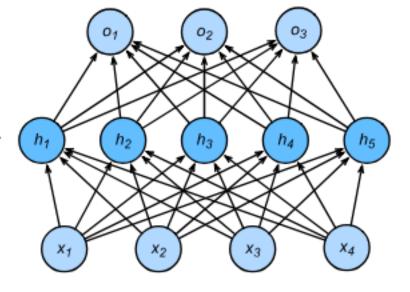
$$\mathbf{h} = \sigma(\mathbf{W}_1 \mathbf{x} + \mathbf{b}_1)$$

$$\mathbf{o} = \mathbf{w}_2^T \mathbf{h} + b_2$$

 σ is an element-wise activation function

Hidden layer

Input layer





Why do we need an a nonlinear activation?

Output layer

 $\mathbf{h} = \mathbf{W}_1 \mathbf{x} + \mathbf{b}_1$

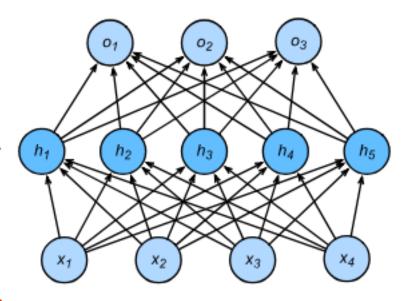
 $\mathbf{o} = \mathbf{w}_2^T \mathbf{h} + b_2$

hence $o = \mathbf{w}_2^\mathsf{T} \mathbf{W}_1 \mathbf{x} + b'$

Hidden layer

Input layer

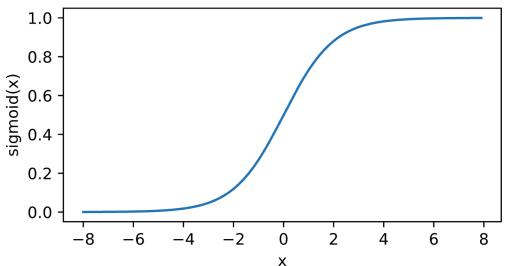
Linear ...





Sigmoid Activation

Map input into (0, 1), a soft version of $\sigma(x) = \begin{cases} 1 & \text{if } x > 0 \\ 0 & \text{otherwise} \end{cases}$ sigmoid(x) = $\frac{1}{1 + \exp(-x)}$

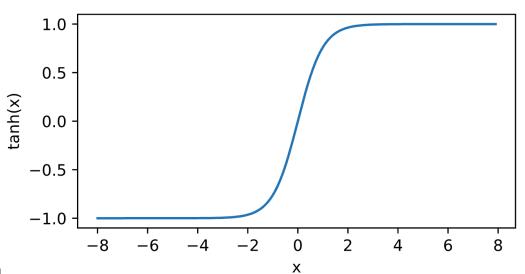




Tanh Activation

Map inputs into (-1, 1)

$$tanh(x) = \frac{1 - \exp(-2x)}{1 + \exp(-2x)}$$

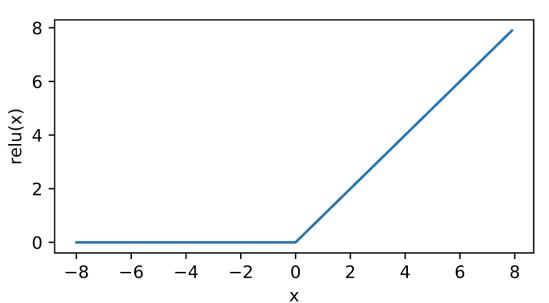




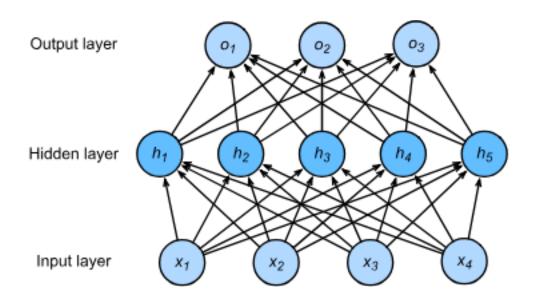
ReLU Activation

ReLU: rectified linear unit

$$ReLU(x) = max(x,0)$$

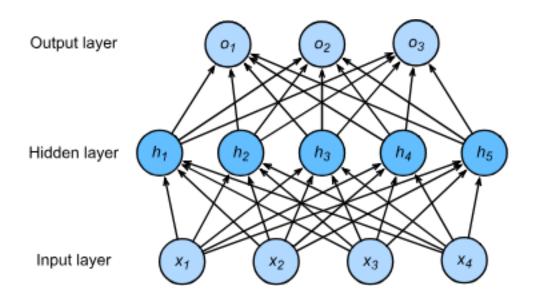








$$y_1, y_2, ..., y_k = \text{softmax}(o_1, o_2, ..., o_k)$$





• Input $\mathbf{x} \in \mathbb{R}^n$

- Output layer
- Hidden $\mathbf{W}_1 \in \mathbb{R}^{m \times n}$ and $\mathbf{b}_1 \in \mathbb{R}^m$
- Output $\mathbf{W}_2 \in \mathbb{R}^{m \times d}$ and $\mathbf{b}_2 \in \mathbb{R}^d$

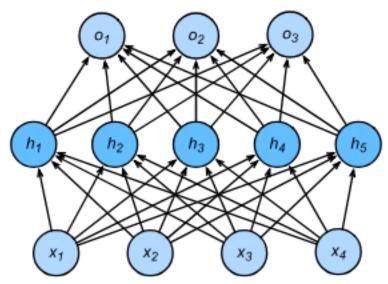
Hidden layer

$$\mathbf{h} = \sigma(\mathbf{W}_1 \mathbf{x} + \mathbf{b}_1)$$

$$\mathbf{o} = \mathbf{w}_2^T \mathbf{h} + \mathbf{b}_2$$

$$y = softmax(o)$$







• Input $\mathbf{x} \in \mathbb{R}^n$

- Output layer
- Hidden $\mathbf{W}_1 \in \mathbb{R}^{m \times n}$ and $\mathbf{b}_1 \in \mathbb{R}^m$
- Output $\mathbf{W}_2 \in \mathbb{R}^{m \times d}$ and $\mathbf{b}_2 \in \mathbb{R}^d$

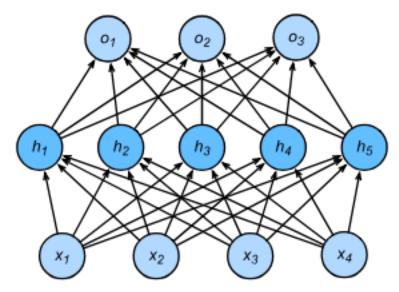
Hidden layer

$$\mathbf{h} = \sigma(\mathbf{W}_1 \mathbf{x} + \mathbf{b}_1)$$

$$\mathbf{o} = \mathbf{w}_2^T \mathbf{h} + \mathbf{b}_2$$

$$y = softmax(o)$$

Input layer





Multiple Hidden Layers

$$\mathbf{h}_1 = \sigma(\mathbf{W}_1 \mathbf{x} + \mathbf{b}_1)$$

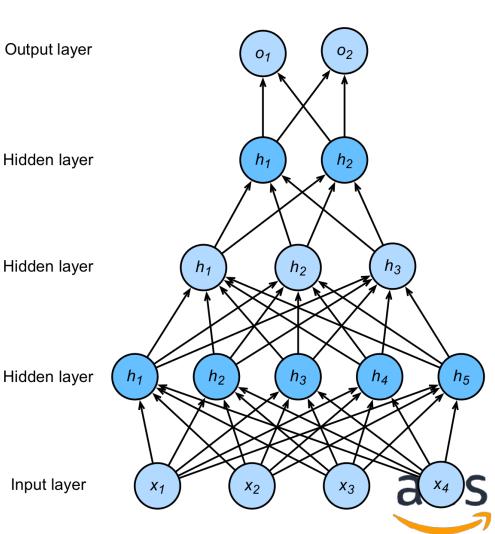
$$\mathbf{h}_2 = \sigma(\mathbf{W}_2 \mathbf{h}_1 + \mathbf{b}_2)$$

$$\mathbf{h}_3 = \sigma(\mathbf{W}_3 \mathbf{h}_2 + \mathbf{b}_3)$$

$$\mathbf{o} = \mathbf{W}_4 \mathbf{h}_3 + \mathbf{b}_4$$

Hyper-parameters

- # of hidden layers
- Hidden size for each layer



Summary

- Perceptron
 - Simple updates
 - Limited function complexity
- Multilayer Perceptron
 - Multiple layers add more complexity
 - Nonlinearity is needed
 - Simple composition (but architecture search needed)

