

A Tutorial on Gradient Descent

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1 Implicit bias of gradient descent

This section explains [1]. The big picture here is to show the gradient $\nabla_{\mathbf{w}} \mathcal{L}(\mathbf{w}) \neq \mathbf{0}$ (section of 1.3.2), the loss function $\mathcal{L}(\mathbf{w})$ will continue to decrease using gradient descent. This makes $\|\mathbf{w}(t)\| \rightarrow \infty$ as $t \rightarrow \infty$. As a result, the weights of the few dominant linear combination terms correspond to the weights associated with the support vectors.

1.1 classifier without max-margin

looking at support vector machine term below:

$$\begin{aligned} \min \left(\frac{1}{2} \|\mathbf{w}\|^2 \right) \\ \text{subject to: } 1 - y_i(\mathbf{w}^\top \mathbf{x}_i + w_0) \leq 0 \quad \forall i \end{aligned} \tag{1}$$

If we were not trying to solve a max-margin problem: if we were just trying to express the problem as a linear classifier. Then, the objective (for a single \mathbf{x}_i, y_i pair can be written as):

$$y_i(\mathbf{w}^\top \mathbf{x}_i + w_0) > 0 \tag{2}$$

to make things even simpler, drop the w_0 :

$$y_i(\mathbf{w}^\top \mathbf{x}_i) > 0 \tag{3}$$

1.1.1 smooth loss

smooth loss function used to penalize incorrect classification, for example:

$$\begin{aligned} \ell(u) &= \exp^{-u} \\ \implies \ell(\mathbf{w}^\top \mathbf{x}_i y_i) &= \exp(-\mathbf{w}^\top \mathbf{x}_i y_i) \end{aligned} \tag{4}$$

in words, we must “push” value of $\mathbf{w}^\top \mathbf{x}_i y_i$ to be large +ve value (for correctly classified data/label pairs) when smooth loss function is assigned to

1.2 use gradient descend

when gradient descend is used to minimize the objective below (note analytical solution available for svm):

$$\begin{aligned}
& \min \mathcal{L}(\mathbf{w}) \\
& = \min \sum_{i=1}^n \ell(\mathbf{w}^\top \mathbf{x}_i y_i) \\
& = \min \sum_{i=1}^n \ell(\mathbf{w}^\top \tilde{\mathbf{x}}_i) \quad \text{let } \tilde{\mathbf{x}}_i = \mathbf{x}_i y_i
\end{aligned} \tag{5}$$

1.2.1 gradient for generic loss \mathcal{L}

$$\begin{aligned}
\nabla_{\mathbf{w}} \mathcal{L}(\mathbf{w}) &= \nabla_{\mathbf{w}} \sum_{i=1}^n \ell(\mathbf{w}^\top \tilde{\mathbf{x}}_i) \\
&= \sum_{i=1}^n \ell'(\mathbf{w}^\top \tilde{\mathbf{x}}_i) \tilde{\mathbf{x}}_i
\end{aligned} \tag{6}$$

substitute into gradient descend:

$$\begin{aligned}
\mathbf{w}(t+1) &= \mathbf{w}(t) - \eta \nabla_{\mathbf{w}(t)} \mathcal{L}(\mathbf{w}(t)) \\
&= \mathbf{w}(t) - \eta \sum_{i=1}^n \ell'(\mathbf{w}(t)^\top \tilde{\mathbf{x}}_i) \tilde{\mathbf{x}}_i
\end{aligned} \tag{7}$$

we are interested in the behavior of $\mathbf{w}(t) \rightarrow \infty$

1.3 magnitude: $\|\mathbf{w}(t)\| \rightarrow \infty$

1.3.1 no finite critical points $\nabla_{\mathbf{w}(t)} \mathcal{L}(\mathbf{w}(t)) = 0$

It's difficult to show from the gradient directly why the expression $\sum_{i=1}^n \ell'(\mathbf{w}(t)^\top \tilde{\mathbf{x}}_i) \tilde{\mathbf{x}}_i$ never reach 0, i.e.,

$$\text{to show why } \lim_{t \rightarrow \infty} \sum_{i=1}^n \ell'(\mathbf{w}(t)^\top \tilde{\mathbf{x}}_i) \tilde{\mathbf{x}}_i \neq 0 \tag{8}$$

Note that people may be confused to think if we let $\ell(u) = \exp^{-u}$, then $\ell'(u) \neq 0$ anyway. right? However, since we have a sum and not just a term. Making the gradient zero may still seems "possible". To illustrate, when we let $n = 2$, we may obtain a situation where:

$$\ell'(\mathbf{w}^\top \tilde{\mathbf{x}}_1) \tilde{\mathbf{x}}_1 = -\ell'(\mathbf{w}^\top \tilde{\mathbf{x}}_2) \tilde{\mathbf{x}}_2 \quad \text{for some } \mathbf{w} \tag{9}$$

1.3.2 show $\nabla_{\mathbf{w}} \mathcal{L}(\mathbf{w}(t))$ won't be a zero vector

Let's assume $\exists \mathbf{w}^* \neq \mathbf{0}$ making data separable (if data is separable). looking at the following expression:

$$\begin{aligned} \mathbf{w}^{*\top} \eta \nabla_{\mathbf{w}(t)} \mathcal{L}(\mathbf{w}(t)) &= \mathbf{w}^{*\top} \sum_{i=1}^n \ell'(\mathbf{w}(t)^\top \tilde{\mathbf{x}}_i) \tilde{\mathbf{x}}_i \\ &= \sum_{i=1}^n \underbrace{\ell'(\mathbf{w}(t)^\top \tilde{\mathbf{x}}_i)}_{<0} \underbrace{\tilde{\mathbf{x}}_i^\top \mathbf{w}^*}_{>0} \end{aligned} \quad (10)$$

Obviously, since:

$$\begin{aligned} \ell'(\mathbf{w}(t)^\top \tilde{\mathbf{x}}_i) \tilde{\mathbf{x}}_i^\top \mathbf{w}^* &< 0 \text{ and } \mathbf{w}^* \neq \mathbf{0} \\ \implies \ell'(\mathbf{w}(t)^\top \tilde{\mathbf{x}}_i) \tilde{\mathbf{x}}_i &\neq \mathbf{0} \quad \forall i \\ \implies \nabla_{\mathbf{w}} \mathcal{L}(\mathbf{w}(t)) &\neq \mathbf{0} \end{aligned} \quad (11)$$

Explain each two terms:

1. $\mathbf{w}^{*\top} \tilde{\mathbf{x}}_i > 0 \quad \forall i$ if all data are all correctly classified/linearly separable:

$$y_i(\mathbf{w}^{*\top} \mathbf{x}_i) > 0 \quad (12)$$

note that up to here, we made **no** reference with max-margin

2. $\ell'(\cdot) < 0$ as long as we choose a monotonically decreasing ℓ which means its gradient < 0
3. also note that in here, we merely assumed $\exists \mathbf{w}^*$. Don't get confused, it is not where $\mathbf{w}(t)$ converges to!
4. also note if it's possible for $\nabla_{\mathbf{w}} \mathcal{L}(\mathbf{w}(t)) = \mathbf{0}$, it means the gradient descend will not run indefinitely.

1.3.3 why $\|\mathbf{w}(t)\| \rightarrow \infty$?

We know gradient descend on a smooth loss will converge to a minimum. This will be illustrated in the β -smooth section. Since ℓ is a smooth function, so is $\mathcal{L}(\mathbf{w}(t)) = \sum_{i=1}^n \ell(\mathbf{w}(t)^\top \tilde{\mathbf{x}}_i)$:

$$\begin{aligned}
\|\nabla \mathcal{L}(x) - \nabla \mathcal{L}(y)\| &= \left\| \frac{1}{n} \sum_i \nabla \ell_i(x) - \frac{1}{n} \sum_i \nabla \ell_i(y) \right\| \\
&= \frac{1}{n} \left\| \sum_i (\nabla \ell_i(x) - \nabla \ell_i(y)) \right\| \\
&\leq \frac{1}{n} \sum_i \|\nabla \ell_i(x) - \nabla \ell_i(y)\| \quad \text{triangle inequality} \quad (13) \\
&\leq \frac{1}{n} \sum_i (\beta_i \|x - y\|) \\
&= \left(\frac{1}{n} \sum_i \beta_i \right) \|x - y\|
\end{aligned}$$

However, the above says there is no critical points. Putting above two arguments together, and look at the objective $\sum_{i=1}^n \ell(\mathbf{w}^\top \tilde{\mathbf{x}}_i)$, we can see that, since the gradient descend algorithm continues to run (and the loss will continuously becoming smaller):

$$\left(\mathcal{L}(\mathbf{w}(t)) = \sum_{i=1}^n \ell(\mathbf{w}(t)^\top \tilde{\mathbf{x}}_i) \right) \rightarrow 0 \implies \mathbf{w}(t)^\top \tilde{\mathbf{x}}_i \rightarrow \infty \quad \text{think } \exp(-u) \quad (14)$$

Since $\tilde{\mathbf{x}}_i$ is fixed, then $\|\mathbf{w}(t)\| \rightarrow \infty$. Note that this is why we need to show there is **no** critical points first.

The norm is needed as $y_i \in \{1, -1\}$, it means:

$$\begin{aligned}
&\lim_{t \rightarrow \infty} \|\mathbf{w}(t)\| = \infty \\
&\text{or equivalently } \|\mathbf{w}(t)\| \rightarrow \infty \quad (15)
\end{aligned}$$

1.4 what about direction of $\mathbf{w}(t)$?

To characterize direction, we look at normalized $\lim_{t \rightarrow \infty} \frac{\mathbf{w}(t)}{\|\mathbf{w}(t)\|}$

Theorem 1 *under assumption as $t \rightarrow \infty$, Gradient descend behaves as:*

$$\mathbf{w}(t) \approx \frac{\mathbf{w}_{\text{svm}}}{\|\mathbf{w}_{\text{svm}}\|} \quad (16)$$

1.4.1 explanation

when $\mathbf{w}(t) \rightarrow \infty$, it has the same direction of the SVM solution, i.e., its normalized version $\frac{\mathbf{w}(t)}{\|\mathbf{w}(t)\|}$ becomes that of the \mathbf{w}_{svm}

\mathbf{w}_{svm} gives max-margin classifier which has better generalization!

1.5 proof of theorem

consider exponential loss $\mathcal{L}(u) = \exp(-u)$, gradient descend in asymptotic regime in shown in Eq.(14):

$$\mathbf{w}(t)^\top \tilde{\mathbf{x}}_i \rightarrow \infty \quad \forall i \quad (17)$$

1.5.1 what is asymptotic “simplification” convergence?

The definition of the notation $a_n \rightarrow b_n$ is designed to mean that $a_n \approx b_n$ for large n , where the fit gets better and better as n gets larger, for example:

$$\lim_{x \rightarrow \infty} x^2 + x + 1 = x^2 \quad (18)$$

and,

$$\begin{aligned} u(x+h) &= u(x) + u'(x)h + \frac{u''(x)}{2}h^2 + \dots \\ u(x+h) - u(x) + u'(x)h &= \frac{u''(x)}{2}h^2 + \dots \\ \left| \frac{u(x+h) - u(x)}{h} - u'(x) \right| &= \left| \frac{u''(x)}{2}h + \frac{u'''(x)}{3!}h^2 \dots \right| \quad \text{divided by } h \\ \Rightarrow \lim_{h \rightarrow 0} \left| \frac{u(x+h) - u(x)}{h} - u'(x) \right| &= \left| \frac{u''(x)}{2}h \right| \end{aligned} \quad (19)$$

1.5.2 asymptotic convergence of $\frac{\mathbf{w}(t)}{\|\mathbf{w}(t)\|}$

we express $\mathbf{w}(t)$ as a linear function in terms of \mathbf{w}_∞ (the remaining work is to find what \mathbf{w}_∞ is):

$$\mathbf{w}(t) = \underbrace{m(t)}_{\text{magnitude}} \mathbf{w}_\infty + \underbrace{\mathbf{b}(t)}_{\text{residual}} \quad (20)$$

assume $\exists \mathbf{w}_\infty$ (which is a unit vector), the limit of the normalization $\frac{\mathbf{w}(t)}{\|\mathbf{w}(t)\|} \rightarrow \mathbf{w}_\infty$, under assumptions of both already stated, and new ones:

1. $\lim_{t \rightarrow \infty} \frac{\mathbf{b}(t)}{m(t)} = 0$ as $\|\mathbf{b}(t)\|$ is relatively smaller compare with $\|\mathbf{w}(t)\|$, as $t \rightarrow \infty$
2. $m(t) \rightarrow \infty$ makes sense as $\|\mathbf{w}(t)\| \rightarrow \infty$

since $m(t)$ is the magnitude, then $m(t) \geq 0$. Looking at the gradient again:

$$\begin{aligned}
\nabla_{\mathbf{w}(t)} \mathcal{L}(\mathbf{w}(t)) &= \sum_{i=1}^n \ell'(\mathbf{w}(t)^\top \tilde{\mathbf{x}}_i) \tilde{\mathbf{x}}_i \\
&= - \sum_{i=1}^n \exp(-\mathbf{w}(t)^\top \tilde{\mathbf{x}}_i) \tilde{\mathbf{x}}_i \quad \text{substitute } \ell'(u) = -\exp(-u) \\
\Rightarrow -\nabla_{\mathbf{w}(t)} \mathcal{L}(\mathbf{w}(t)) &= \sum_{i=1}^n \exp(-\mathbf{w}(t)^\top \tilde{\mathbf{x}}_i) \tilde{\mathbf{x}}_i \\
&= \sum_{i=1}^n \exp\left(-\left(m(t)\mathbf{w}_\infty + \mathbf{b}(t)\right)^\top \tilde{\mathbf{x}}_i\right) \tilde{\mathbf{x}}_i \quad \text{substitute } \mathbf{w}(t) = m(t)\mathbf{w}_\infty + \mathbf{b}(t) \\
&= \sum_{i=1}^n \exp^{-m(t)\mathbf{w}_\infty^\top \tilde{\mathbf{x}}_i} \tilde{\mathbf{x}}_i \times \exp^{-\mathbf{b}(t)^\top \tilde{\mathbf{x}}_i} \tilde{\mathbf{x}}_i \\
&\approx \sum_{i=1}^n \exp^{-m(t)\mathbf{w}_\infty^\top \tilde{\mathbf{x}}_i} \tilde{\mathbf{x}}_i \quad \because \lim_{t \rightarrow \infty} \frac{\mathbf{b}(t)}{m(t)} = 0 \\
&= \sum_{i=1}^n \underbrace{\exp\left(-m(t)\mathbf{w}_\infty^\top \tilde{\mathbf{x}}_i\right)}_{\alpha_i} \tilde{\mathbf{x}}_i
\end{aligned} \tag{21}$$

so gradient step would be some non-negative linear combination of $\tilde{\mathbf{x}}_i$, i.e.,:

$$-\nabla_{\mathbf{w}(t)} \mathcal{L}(\mathbf{w}(t)) = \sum_{i=1}^n \alpha_i \tilde{\mathbf{x}}_i \tag{22}$$

1.5.3 dominate terms

assumes \mathbf{w}_∞ classifies the linearly separable data correctly, then:

$$\mathbf{w}_\infty^\top \tilde{\mathbf{x}}_i > 0 \tag{23}$$

since $m(t) \rightarrow \infty$, we have only a few dominate terms in $\{\tilde{\mathbf{x}}_i\}$ (multiply by ∞ makes them dominate!). since these $\tilde{\mathbf{x}}_i$ are closest to (and on the) decision boundary, then they are precisely support vectors! So the set is support vector set s.v.!

Note that if multiple $\tilde{\mathbf{x}}_i$ and $\tilde{\mathbf{x}}_j$ are the closest, i.e., $\mathbf{w}_\infty^\top \tilde{\mathbf{x}}_i = \mathbf{w}_\infty^\top \tilde{\mathbf{x}}_j$, then, they both are part of the support vector set!

$$\begin{aligned}
-\nabla_{\mathbf{w}(t)} \mathcal{L}(\mathbf{w}(t)) &\approx \sum_{\tilde{\mathbf{x}}_i \in \text{s. v.}} \alpha_i \tilde{\mathbf{x}}_i \\
&= \sum_{\mathbf{x}_i \in \text{s. v.}} \alpha_i \mathbf{x}_i y_i
\end{aligned} \tag{24}$$

As each of the gradient step is a linear combination of $x_i \in \text{s.v.}$, then, so is \mathbf{w}_∞ , i.e.,

$$\mathbf{w}_\infty = \sum_{\mathbf{x}_i \in \text{s.v.}} \alpha'_i \tilde{\mathbf{x}}_i \quad \text{for some } \alpha'_i \neq \alpha_i \tag{25}$$

since $\|\mathbf{w}(t)\| \rightarrow \infty$, then the initial $\mathbf{w}(0)$ value won't matter any more. There is one remaining issue though: $\mathbf{w}_\infty^\top \tilde{\mathbf{x}}_i \neq 1 \quad \forall \mathbf{x}_i \in \text{s.v.}$ so look at the next section:

1.5.4 from \mathbf{w}_∞ to obtain \mathbf{w}_{svm}

lastly, we need to scale \mathbf{w}_∞ to become \mathbf{w}_{svm} . let's see what if we perform $\frac{\mathbf{w}_\infty}{\text{some constant}}$. Now let's have $\tilde{\mathbf{x}}_{\text{s.v.}}$ such that:

$$\mathbf{w}_\infty^\top \tilde{\mathbf{x}}_{\text{s.v.}} = \min_i \{\mathbf{w}_\infty^\top \tilde{\mathbf{x}}_i\} \quad (26)$$

although the picking of the “some constant” is arbitrary, but we pick $\min_i \{\mathbf{w}_\infty^\top \tilde{\mathbf{x}}_i\}$ to reflect the SVM solution:

$$\begin{aligned} \hat{\mathbf{w}} &= \frac{\mathbf{w}_\infty}{\text{some constant}} \\ &= \frac{\mathbf{w}_\infty}{\mathbf{w}_\infty^\top \tilde{\mathbf{x}}_{\text{s.v.}}} \end{aligned} \quad (27)$$

note that $\|\mathbf{w}_\infty\| = 1$, but $\|\hat{\mathbf{w}}\| \neq 1$! By this process, it scales $\hat{\mathbf{w}}$ such that when applying to $\tilde{\mathbf{x}}_{\text{s.v.}}$:

$$\begin{aligned} \hat{\mathbf{w}}^\top \tilde{\mathbf{x}}_{\text{s.v.}} &= \frac{\mathbf{w}_\infty^\top}{\mathbf{w}_\infty^\top \tilde{\mathbf{x}}_{\text{s.v.}}} \tilde{\mathbf{x}}_{\text{s.v.}} \\ &= 1 \end{aligned} \quad (28)$$

and when it applies to other $\tilde{\mathbf{x}} \notin \{\tilde{\mathbf{x}}_{\text{s.v.}}\}$:

$$\begin{aligned} \hat{\mathbf{w}}^\top \tilde{\mathbf{x}} &= \frac{\mathbf{w}_\infty^\top}{\mathbf{w}_\infty^\top \tilde{\mathbf{x}}_{\text{s.v.}}} \tilde{\mathbf{x}} \\ &> 1 \end{aligned} \quad (29)$$

Does $\hat{\mathbf{w}}$ look familiar? Remember KKT condition is:

$$\hat{\mathbf{w}} = \sum_{i=1}^N \lambda_i \tilde{\mathbf{x}}_i \quad (30)$$

with complementary duality:

$$\begin{cases} \lambda_i > 0 & \hat{\mathbf{w}}^\top \tilde{\mathbf{x}}_i = 1 & \text{support vectors} \\ \lambda_i = 0 & \hat{\mathbf{w}}^\top \tilde{\mathbf{x}}_i > 1 & \text{non support vector} \end{cases} \quad (31)$$

compare with equation in SVM section, $\hat{\mathbf{w}} = \mathbf{w}_{\text{svm}}$

Since we already prove $\hat{\mathbf{w}}$ is proportional to \mathbf{w}_∞ . Therefore, \mathbf{w}_∞ is the SVM solution up to some constant!

References

- [1] Daniel Soudry, Elad Hoffer, Mor Shpigel Nacson, Suriya Gunasekar, and Nathan Srebro, “The implicit bias of gradient descent on separable data,” *The Journal of Machine Learning Research*, vol. 19, no. 1, pp. 2822–2878, 2018.