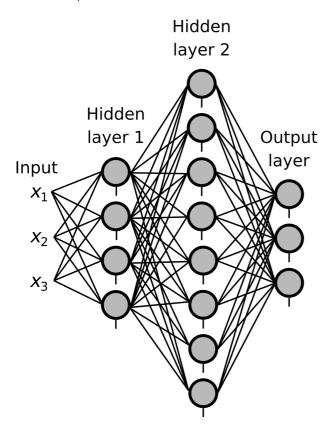
# MMAI 5500 -- Assignment 1

Your task is to code and train a neural network in Python using only NumPy. That is, the only library that you are allowed to import is NumPy. It should be imported with <code>import numpy as np</code>. Luckily some parts of the code are provided (see the *Code* section below).

## The network architecture

The network should have three fully connected weight layers, three inputs and three-class softmax output. The first hidden layer should have four neurons and the second eight neurons. All neurons should have a single bias. See the diagram below for a visual description.



## **Data**

The networks should be trained and validated on the data provided in assing1\_data.csv.

Load the data using NumPy as follows:

```
fname = 'assign1_data.csv'
data = np.genfromtxt(fname, dtype='float', delimiter=',', skip_header=1)
X, y = data[:, :-1], data[:, -1].astype(int)
X_train, y_train = X[:400], y[:400]
X_test, y_test = X[400:], y[400:]
```

#### **Task**

Use the code provided below to complete and train the network. Test it with probs, loss = forward\_pass( $X_{test}$ ,  $y_{test}$ , np.eye( $n_{class}$ )[ $y_{test}$ ]). You should get an accuracy above 90% in less than 10 epochs of training.

## **Submission**

Submit this assignment as a single PY file that loads the data, builds and trains the network and prints the accuracy on the test set. For full marks, the code has to be bug-free, PEP8 formatted (use a PEP8 plugin for your text editor) and result in a test set accuracy above 90%. The submission due date is 8:30 am on May 25, 2021.

#### Code

Use the code snippets below. Some snippets are incomplete and need you to add a few lines of code. The places where you need to add code are indicated by ... YOUR CODE HERE .....

## Layer

#### A dense (aka fully connected) layer

```
class DenseLayer:
    def __init__(self, n_inputs, n_neurons):
        Initialize weights & biases.
        Weights should be initialized with values drawn from a normal
       distribution scaled by 0.01.
        Biases are initialized to 0.0.
        self.weights = 0.01 * np.random.randn(n_inputs, n_neurons)
        self.biases = "... YOUR CODE HERE ..."
    def forward(self, inputs):
        A forward pass through the layer to give z.
        Compute it using \mathsf{np.dot}(\ldots) and then add the biases.
        self.inputs = inputs
        self.z = "... YOUR CODE HERE ..."
    def backward(self, dz):
        Backward pass
       # Gradients of weights
       self.dweights = np.dot(self.inputs.T, dz)
       # Gradients of biases
       self.dbiases = np.sum(dz, axis=0, keepdims=True)
        # Gradients of inputs
        self.dinputs = np.dot(dz, self.weights.T)
```

#### **Activations**

#### ReLu

```
class ReLu:
    """
    ReLu activation
    """

def forward(self, z):
    """
    Forward pass
    """
    self.z = z
    self.activity = "... YOUR CODE HERE ..."
```

```
def backward(self, dactivity):
    """

Backward pass
"""

self.dz = dactivity.copy()
self.dz[self.z <= 0] = 0.0</pre>
```

#### **Softmax**

```
class Softmax:
   def forward(self, z):
       0.00
       e_z = np.exp(z - np.max(z, axis=1, keepdims=True))
       self.probs = e_z / e_z.sum(axis=1, keepdims=True)
       return self.probs
   def backward(self, dprobs):
       0.00
       # Empty array
       self.dz = np.empty_like(dprobs)
       for i, (prob, dprob) in enumerate(zip(self.probs, dprobs)):
           # flatten to a column vector
           prob = prob.reshape(-1, 1)
           # Jacobian matrix
           jacobian = np.diagflat(prob) - np.dot(prob, prob.T)
           self.dz[i] = np.dot(jacobian, dprob)
```

#### Loss function

#### **Crossentropy loss**

```
class CrossEntropyLoss:
   def forward(self, probs, oh_y_true):
        Use one-hot encoded y_true.
       # clip to prevent division by 0
       # clip both sides to not bias up.
        probs_clipped = np.clip(probs, 1e-7, 1 - 1e-7)
        # negative log likelihoods
       loss = -np.sum(oh_y_true * np.log(probs_clipped), axis=1)
       return loss.mean(axis=0)
    \textbf{def backward}(\texttt{self, probs, oh\_y\_true}):
        Use one-hot encoded y_true.
       # Number of examples in batch and number of classes
       batch_sz, n_class = probs.shape
       # get the gradient
       self.dprobs = -oh_y_true / probs
       # normalize the gradient
        self.dprobs = self.dprobs / batch_sz
```

## **Optimizer**

#### **Stochastic Gradient Descent**

Note that this optimizer only updates a single layer, and have thus, to be called for each layer.

```
class SGD:
    """
    def __init__(self, learning_rate=1.0):
        # Initialize the optimizer with a learning rate
        self.learning_rate = learning_rate

def update_params(self, layer):
        layer.weights = "... YOUR CODE HERE ..."
        layer.biases = "... YOUR CODE HERE ..."
```

## **Helper functions**

# Convert probabilities to predictions

```
def predictions(probs):
    """
    y_preds = np.argmax(probs, axis=1)
    return y_preds
```

### **Accuracy**

```
def accuracy(y_preds, y_true):
    """
    return np.mean(y_preds == y_true)
```

#### **One-hot encoding**

```
oh_y_true = np.eye(n_class)[y_true]
```

# **Training**

A single forward pass through the entire network.

```
def forward_pass(X, y_true, oh_y_true):
    """
    dense1.forward(X)
    activation1.forward(dense1.z)
    "... YOUR CODE HERE ..."
    probs = "... YOUR CODE HERE ..."
    loss = "... YOUR CODE HERE ..."
```

A single backward pass through the entire network.

```
def backward_pass(probs, y_true, oh_y_true):
```

```
"""
"... YOUR CODE HERE ..."
```

## Initialize the network and set hyperparameters

For example, number of epochs to train, batch size, number of neurons, etc.

```
"... YOUR CODE HERE ..."
dense1 = "... YOUR CODE HERE ..."
activation1 = ReLu()
"... YOUR CODE HERE ..."
output_activation = "... YOUR CODE HERE ..."
crossentropy = CrossEntropyLoss()
optimizer = SGD()
```

## **Training loop**

```
for epoch in range(epochs):
    print('epoch:', epoch)

for batch_i in range(n_batch):
    # Get a mini-batch of data from X_train and y_train. It should have batch_sz examples.
    "... YOUR CODE HERE ..."
    # One-hot encode y_true
    "... YOUR CODE HERE ..."

# Forward pass
    "... YOUR CODE HERE ..."

# Print accuracy and loss
    "... YOUR CODE HERE ..."

# Backward pass
    "... YOUR CODE HERE ..."

# Update the weights
    "... YOUR CODE HERE ..."
```