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RESEARCH ARTICLE

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Kev Points:

- Sheltering coefficient is not constant as was previously assumed
- Sheltering coefficient is highly variable and depends on both the wind speed and the wave state
- The location of the steepest wind waves on the long-wave phase illustrates the aerodynamic sheltering

Supporting Information:

Supporting Information may be found in the online version of this article.

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Laboratory Wave and Stress Measurements Quantify the Aerodynamic Sheltering in Extreme Winds

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Abstract In strong winds, air flow detaches from the ocean surface in the lee of wave crests and creates a low-pressure zone on the wave's leeward face. The pressure difference between the wave's rear and front face modulates the momentum input from wind to waves. Numerical wave models parameterize this effect using a so-called sheltering coefficient. However, its value and dependence on wind speed are not well understood, particularly with background swell waves. To bridge this gap, we conducted laboratory experiments with winds up to Category 4 hurricane force blown over various mechanically generated wave conditions (pure wind sea, mixed waves with directional spreading, and monochromatic unidirectional waves) and measured the wind, waves, and stress at a sufficient frequency to resolve wind-wave variability over the long-wave phase. We analyze the results in the context of Jeffreys's sheltering theory and find two regimes: (a) from low-to-moderate wind forcing (10 m s⁻¹ < U_{10} < 33 m s⁻¹), the aerodynamic sheltering increases with wind speed, consistent with previous studies; (b) in hurricane conditions ($U_{10} > 33 \text{ m s}^{-1}$), the aerodynamic sheltering decreases with wind at a rate depending on wave state. Further, we isolate the short wind waves from the longer paddle waves and find that the aerodynamic sheltering by longer waves leads to a phase-dependent variability of the short wind-waves' local steepness, which is evidenced by the sheltering coefficient's value derived from wind and wave measurements. Our results emphasize the need for further measurements of aerodynamic sheltering and improving its representation in models.

Plain Language Summary When the wind blows over the water surface, the leeward side of the wave is sheltered by the windward side. The sheltering has historically been quantified using an empirical parameter. Our research shows that this empirical parameter is not constant as previous studies have often assumed. Instead, its value depends on the wind speed and wave form. We also show that the sheltering is evidenced by the location of the steepest wind waves on the long wave, which we also see in the camera images of the wave surface.

1. Introduction

Wave growth is governed to first-order by momentum flux from the wind, which in turn feeds back to affect the exchange of momentum from wind to the ocean surface and subsurface (Grare et al., 2013). Under wind forcing, smaller waves on the leeward side of larger waves are sheltered from the wind. Better understanding and quantifying the role of sheltering on wave growth under wind forcing remains elusive. The sensitivity of sheltering to different background waves, especially under extreme wind forcing, is also not well understood. This is important because tropical cyclones are known to have complex wind-wave states in different quadrants of the storm (Wright et al., 2001).

One of the most popular theories that incorporate sheltering is the Jeffreys's sheltering (JS) hypothesis (Jeffreys, 1924, 1925). The JS hypothesis is based on the geometric form of the wavy surface: when wind blows over the water surface, the waves induce a flow separation on the leeward side of the wave and the air flow detaches from the wave surface and creates a low-pressure area. Thus, the lee of wave is sheltered by the windward side of the wave.

Two wave growth theories alternative to JS were proposed by Phillips (1957) and Miles (1959). Phillips (1957) argued that the initial wave growth relies on a resonance between surface waves and the pressure fluctuations in the wind. The wind has a turbulent component—composed of an ensemble of eddies—as it blows over the water surface. The pressure disturbances associated with those eddies generate ripples on the water surface. As waves grow higher, the resonance plays a lesser role in wave growth. Thus, Philips theory is relevant only for

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initial wave growth on a calm water surface (Li & Shen, 2022). Miles theory, on the other hand, assumed that the transfer of energy occurs at the critical height where the wind speed equals the phase speed (C_p) of the waves. The transfer of energy from wind to waves is proportional to the curvature of the mean velocity profile at the critical height. Miles theory is thus more applicable for more developed waves than Philips theory. Further, similar to the JS hypothesis, Miles theory also considers the wind-wave coupling and the momentum flux in the context of a structural change of waves. However, the supporting physical mechanisms behind Miles theory and the JS hypothesis are different.

Both the Miles and the JS theories have been studied in laboratory and numerical studies to test their validity. Donelan et al. (2006) found experimentally that the air-flow separation occurs when the acceleration needed to keep the air flow attached to the surface downstream of the crest (referred to as centripetal acceleration) exceeds the downward vertical acceleration of the wave-induced flow at the crest, thus leading to sheltering. Savelyev et al. (2011) suggested that the sheltering mechanism from air-flow separation over the water surface supported by JS hypothesis becomes dominant compared to the nonseparated mechanism and enhances the wind-wave momentum flux for wave steepness ak (defined as wave amplitude a times wavenumber k) greater than 0.19. Using Particle Image Velocimetry (PIV) in a large wind-wave-current tank, Buckley and Veron (2016) found that the air flow over young waves (wave age $C_p/u_* < 3.7$, where u_* is the friction velocity) separates from the water surface downwind of the wave crest and a large sheltering effect was observed past the wave crest. Further, Buckley and Veron (2019) confirmed the drastic modification of wind stress by waves due to sheltering. In their research, for the wind forcing U_{10} (the wind speed at 10 m height above the water surface) of 9.41 and 16.63 m s⁻¹, the wave-induced stress was positive above both windward and leeward faces of the waves and negative elsewhere.

The wave growth theories have also been extensively studied from a numerical point of view. Touboul et al. (2008) found that the JS theory is more accurate than the Miles theory by simulating freak wave growth under wind forcing, based on the Nonlinear Schrödinger Equation (NSE). Montalvo et al. (2013) extended the Miles theory to finite depth and derived a wind-forced finite-depth NSE. They showed analytically that the sheltering mechanism in JS hypothesis is dominant compared to the Miles theory during the process of wave growth in young waves ($C_p/u_* < 7$) when they are steep enough to induce sheltering. Using Large Eddy Simulations (LES), Yang et al. (2013) demonstrated that the sheltering in the troughs due to the flow separation at the crests agrees with the calculated growth rates from many experiments. Husain et al. (2022) used LES and phase-averaged turbulent kinetic energy (TKE), vorticity, wave dissipation, and wind stress on young waves ($C_p/u_* < 1.4$). Their results show a clear air-flow separation on the leeward face of the long waves, forming a pressure "dead zone" and the TKE gradually increasing from near-zero to a maximum on the windward face of the wave in front. Further, due to the positive-definite (U_*/C_p)² in the wave growth parameterization based on the Miles theory, it cannot resolve negative flux that occurs in calm wind over swell. Miles theory can thus only be applied to young wind sea where waves are slower than and aligned with the wind (Riley et al., 1982). In contrast, the JS hypothesis is applicable in swell and wind sea alike because it permits the momentum flux to be of either sign.

To quantify sheltering in a numerical wave model, Donelan et al. (2012) used an empirical sheltering coefficient A in the parameterization of JS. In their model, the coefficient A is defined in the range [0, 1] and corresponds to the unit area of the water surface that is exposed to the wind forcing. A = 1 implies no sheltering (wind follows the wavy surface) and A = 0 implies complete sheltering (wind is completely detached from the wavy surface). Smaller A thus imply smaller wind input to the waves. Being a key parameter, the choice of the value of A can greatly affect the resulting wave growth rates and thus the accuracy of the model altogether. By validating the model against in situ wind and wave measurements in both tropical and extratropical storms, Donelan et al. (2012) iteratively determined the value of A to be 0.11, 0.10, and 0.01 in the cases of wind following waves, wind opposing waves, and waves outrunning wind (swell) conditions, respectively. While some previous studies (Donelan, 1999; Donelan & Pierson, 1987; Donelan et al., 2012) assumed A a constant, several experimental studies (Grare, 2009; Grare et al., 2013; Mastenbroek et al., 1996; Peirson & Garcia, 2008) found A in the range [0.1, 0.5], and its value decreasing with increasing wave steepness. There is thus mounting evidence that steeper waves lead to more pronounced aerodynamic sheltering.

Although sheltering has been studied under different wind-sea conditions (Buckley & Veron, 2019; Grare et al., 2013; Savelyev et al., 2011), the exact value of the sheltering coefficient A remains unknown in strong winds ($U_{10} > 30 \text{ m s}^{-1}$). Further, the dependence of A on the geometric form of background waves remains

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Figure 1. Diagram of the experimental setup in the SUSTAIN Laboratory. The vertical and horizontal dimensions are not to scale. The wind-wave tank consists a single-pass air system from the fan on the left where the wind is generated to the beach at the end of the tank on the right where the air exits the tank. A cross-tank offset of 1 m exists between the wave wire and the IRGASON sonic anemometer.

unknown. Due to the lack of systematic research on the value of *A* in the JS theory, researchers have argued that the JS hypothesis does not accurately depict the wave growth due to wind (Hristov, 2018; Stewart, 1967). Therefore, a thorough study of the sheltering coefficient—particularly in extreme wind conditions—is vital for better understanding aerodynamic sheltering and the improvement of numerical wave models as an essential component of coupled atmosphere—wave—ocean models for hurricane research and prediction.

To fill this gap, we subjected multiple mechanically generated initial waves to strong winds (from 10.9 to 65.9 m s⁻¹, up to Category 4 hurricane intensity) in a series of laboratory experiments. From in situ and high-frequency measurements of water elevation and air turbulence, we computed the sheltering coefficient to quantify the sheltering in such wind-wave conditions. We characterized sheltering in terms of wave statistical properties with support from visible-camera imagery of the wavy surface. Our study shows the behavior of the sheltering coefficient in strong winds under different wave forms and guides the future development of wind input parameterizations in the next generation wave models.

2. Methods

2.1. Jeffreys's Sheltering Hypothesis

Donelan et al. (2012) parameterized the wave energy input from wind S_{in} using the directional wave spectrum in Equation 1 of their paper. We assume conditions with no background current, waves aligned with wind direction, and omni-directionality of the wave field. Integrating their equation over directional space and casting it in the frequency domain:

$$S_{in}(f) = A \frac{\rho_a}{\rho_w} \left(\frac{U_{\lambda/2}}{C_p} - 1 \right) \left| \frac{U_{\lambda/2}}{C_p} - 1 \right| \omega E(f)$$
 (1)

where ρ_a and ρ_w are air and water density, f is wave frequency, E(f) is the spectral wave energy density in frequency space, ω is the wave angular frequency, C_p is the wave phase speed, and A is the sheltering coefficient. Equation 1 states that the wind input (the rate of wave variance spectrum change due to wind forcing) is proportional to the sheltering coefficient, the air to water density ratio, the sign-preserving wave-relative wind speed, and the wave spectrum. In this paper, we conduct a systematic research on the variability of A under different wind forcing and wave conditions. The experimental setup is described in the following subsection.

2.2. Laboratory Measurements

Our research was conducted at the SUrge Structure Atmosphere INteraction (SUSTAIN) Facility at the University of Miami's Rosenstiel School of Marine, Atmospheric and Earth Science. A schematic of the facility is shown in Figure 1. The laboratory contains a wind tunnel built over a wave tank with a 23-m long, 6-m wide, and 2-m tall working section. The wave tank is equipped with a programmable, oscillating, mechanical wave-maker

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M7.5

Table 1 Experimental	Table 1 Experimental Parameters Used in the Research							
Experiment	Fan frequency (Hz)	Paddle waves						
WO	10–50	None						
J10	10-50	JONSWAP, $H_{\text{min}} = 10 \text{ cm}$, $f_{\text{m}} = 1 \text{ Hz}$						

Monochromatic, a = 7.5 cm, $f_n = 1$ Hz

10 - 50

consisting of 12 paddles. The wave-maker can generate monochromatic or broad-banded waves with or without directional spreading. A porous parabolic beach dissipates incoming wave energy with minimum reflection. The wind tunnel is capable of generating free-stream velocities exceeding Category 5 hurricane intensity ($U_{10} > 70 \text{ m s}^{-1}$).

Wind velocity was measured using a Campbell Scientific 3-day sonic anemometer and infrared gas analyzer (IRGASON). The anemometer was placed at 9 m down-fetch from the wind inlet at 0.65 m height above the water surface. Its sampling frequency is 20 Hz. IRGASON's precision for

horizontal and vertical velocities is 1 and 0.5 mm s⁻¹, respectively. The instantaneous water surface elevation was obtained by a capacitance wave wire gauge at a sampling frequency of 20 Hz. The wave wire was placed at the same fetch as the IRGASON but 2 m away from it in the negative cross-tank direction (to the right when facing the beach). At the same fetch and outside of the tank, a camera was mounted and pointed in the cross-tank direction. The camera was set to capture 20 frames per second and adjusted to focus on the air–water interface nearest to the lens. The image size is $1,000 \times 1,000$ pixels covering an area of $82.8 \text{ cm} \times 82.8 \text{ cm}$. One pixel thus corresponds to 0.828 mm. This provides a visualization of the air–water interface that coincides with the wave and wind measurements and allows for further analysis and verification of the results.

The wind generator operated at frequencies ranging from 10 to 50 Hz with 5 Hz intervals. Each fan frequency, and thus each wind speed, was maintained for 10 min before transitioning to the next wind condition. The ramping up of wind from one steady-state condition to another takes approximately 30 s, and we excluded it from the analysis.

Three wind-wave conditions were tested: (a) pure wind-sea conditions without paddle waves, referred to as WO (Wind Only) in this paper; (b) initially short-crested JONSWAP (Hasselmann et al., 1973) spectrum of waves at peak frequency f_p of 1 Hz, significant wave height (H_{sig}) of 10 cm, and directional spreading with a \cos^2 shape (referred to as J10 in this paper); and (c) monochromatic waves with 1-Hz frequency (wave length of $\lambda \approx 0.5$ m) and amplitude a=7.5 cm (referred as M7.5 in this paper). The purpose of the WO experiment is to provide pure wind-sea conditions that are not sheltered by any long waves. Thus, WO serves as a control experiment against which J10 and M7.5 will be evaluated. The J10 experiment introduces broad-banded background waves that aim to mimic the realistic wave state that can be found in the field. J10 allows us to relate our sheltering results to the real ocean. Finally, the M7.5 experiment introduces steep, monochromatic, background waves that enable phase-dependent analysis, which is necessary for better understanding of the sheltering process. The experimental parameters are shown in Table 1.

The expression for the JONSWAP wave spectrum (Hasselmann et al., 1973) with directional spreading is

$$S(f) = \frac{\alpha g^2}{(2\pi)^4 f^5} \exp\left[-\frac{5}{4} \left(\frac{f}{f_p}\right)^{-4}\right] \Gamma^r \cos^N(\theta)$$
 (2)

wherein

$$r = \exp\left[-\frac{(f - f_p)^2}{2\sigma^2 f_p^2}\right] \tag{3}$$

and α is the Philips constant determined by the magnitude of the total wave energy. Γ is the peak enhancement factor and is equal to 3.3 in JONSWAP spectrum waves. σ has the value of 0.07 and 0.09 for waves longer and shorter than the peak, respectively. θ is the wave spreading angle and N is the spreading factor with the value of 2 in this study.

The stationary water level h was set to 0.8 m to allow all waves in the J10 and M7.5 experiments to be deepwater waves ($h/\lambda > 1/2$). However, the characteristics of J10 and M7.5 waves are different. The JONSWAP waves are broad banded and mimic a realistic, random wave field that is similar to that in the open ocean. On the other side, M7.5 waves are monochromatic, unidirectional, sine-like waves. Though such waves are not comparable to those found in the open ocean, they are useful for studying aerodynamic sheltering because they allow clean separation of wind sea and swell and phase-resolved spectral analysis of shortwaves.

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After imposing the wind forcing, the water surface features a combination of wind-sea and mechanical waves. We calculated the mean wave steepness parameter ak following Grare et al. (2013) to characterize the waves consistently across the three experiments. First, we calculate the mean wave frequency \overline{f} using:

$$\overline{f} = \frac{m_1}{m_0} \tag{4}$$

where m_0 and m_1 are the zeroth and first moments of the wave energy spectrum F(f), respectively. The general expression for the nth spectral moment is

$$m_n = \int_{f_{min}}^{f_{max}} f^n F(f) \, df \tag{5}$$

Given the sampling frequency of the wave wire we use, $f_{\min} = 0$ Hz and $f_{\max} = 10$ Hz (Nyquist frequency). Then, we calculate the mean wave height \overline{H} as

$$\overline{H} = 0.886 H_{rms} = 0.886 \sqrt{m_0} \tag{6}$$

where H_{rms} is the root mean square wave height. Then, we derive the mean wave number \overline{k} from \overline{f} using linear dispersion relation. The mean wave steepness, ak, is then defined as

$$ak = \frac{\overline{H}}{2}\overline{k} \tag{7}$$

These parameters will be used in the analysis of the results later in the paper.

2.3. Wind Stress

We derive the eddy-covariance wind stress following for example, Tennekes and Lumley (1972) and Edson et al. (1998):

$$\tau = \rho_a \sqrt{\left(-\overline{u'w'}\right)^2 + \left(-\overline{v'w'}\right)^2} \tag{8}$$

where u', v', and w' are downwind, cross-wind, and upward perturbation velocities, respectively. As the stress is not constant but linearly decreases with height inside of the tank, the measured values must be extrapolated to the mean water level (z = 0) before they can be compared with measurements from the field. This approach is common to laboratory measurements of stress in an enclosed tank (Curcic & Haus, 2020; Donelan & Plant, 2009; Donelan et al., 2004; Uz et al., 2002). To extrapolate the measured stress to the surface, we relate the vertical stress gradient with the horizontal pressure gradient. The stress was measured at heights from 0.1 to 0.6 m using a TSI IFA-300 constant temperature hot-film anemometer and related to the horizontal gradient of air pressure in a wide range of wind speeds, providing a robust linear fit. We provide the details of this procedure in Supporting Information S1. Hereon, all our wind stress estimates are in reference to the mean water surface.

Then, we obtained the friction velocity u^* at the surface using:

$$u_* = \sqrt{\frac{\tau_s}{\rho_a}} \tag{9}$$

where τ_s is the wind stress extrapolated to the surface.

The mean wind speed U_z for each fan setting was scaled from the measurement height to the standard meteorological 10-m height assuming the logarithmic profile and neutral thermodynamic conditions:

$$U_{10} = U_z + \frac{u_*}{\kappa} \ln\left(\frac{10}{z}\right) \tag{10}$$

where κ is the Von Kármán constant (0.41) and z is the measurement height (0.65 m). Measured and scaled wind speeds for each experiment and fan setting are shown in Table 2.

The total wind stress consists of two components: the form stress τ_f caused by pressure difference between the windward and leeward sides of the wave and the viscous (skin) stress τ_g caused by the drag in the viscous sublayer

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Table 2Fan Frequency and Measured and Scaled Mean Wind Speeds From All Experiments

	WO	WO	J10	J10	M7.5	M7.5
Fan frequency (Hz)	$\frac{U_z}{(\text{m s}^{-1})}$	U_{10} (m s ⁻¹)	$\frac{U_z}{(\text{m s}^{-1})}$	U_{10} (m s ⁻¹)	$\frac{U_z}{(\text{m s}^{-1})}$	U_{10} (m s ⁻¹)
10	7.5	10.9	7.4	10.9	8.0	11.4
15	11.5	16.8	11.7	16.9	11.9	16.9
20	15.4	23.1	15.8	23.3	15.7	23.0
25	19.5	30.0	19.9	30.1	19.7	29.5
30	23.5	37.2	24.3	37.6	23.4	36.1
35	27.2	44.3	28.1	44.8	28.2	44.2
40	31.2	51.5	31.6	51.6	32.8	51.8
45	35.2	58.8	35.5	59.0	37.0	59.9
50	39.1	65.9	38.6	66.1	39.7	66.4

(Donelan et al., 2012; Jones & Toba, 2001; Makin et al., 1995; Monin & Yaglom, 1971). As the aerodynamic sheltering is specifically a consequence of the wave form, τ_{ν} must be subtracted from the measured stress such that

$$\tau_f = \tau - \tau_v = \rho_a \sqrt{\left(-\overline{u'w'}\right)^2 + \left(-\overline{v'w'}\right)^2} - \tau_v \tag{11}$$

To obtain τ_{ν} , we assume the smooth law of wall with a pure laminar flow immediately adjacent to the water surface where (Donelan et al., 2012; Jones & Toba, 2001)

$$U(z) = \frac{u_{*v}}{\kappa} \ln \frac{z}{z_{0v}} \tag{12}$$

where $u_{*_{\nu}}$ and $z_{0\nu}$ are the viscous friction velocity and roughness lengths, respectively, and are related through the viscous Reynolds number and the kinematic viscosity ν :

$$Re = \frac{z_{0v} u_{*v}}{v}$$
 (13)

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Jones and Toba (2001) and Donelan et al. (2012) assumed Re=0.11 for the near-surface laminar air flow. Combining Equations 11–13 yields $u_{*_{\nu}}$, τ_{ν} , and finally τ_{f}

2.4. Sheltering Coefficient

After obtaining τ_{ρ} the wind input source function S_{in} can be linked with τ_{f} following Donelan et al. (2012):

$$\tau_f = \rho_w g \int_{f_{\min}}^{f_{\max}} \frac{S_{in}(f)}{C_p} df \tag{14}$$

By combining Equations 1 and 14 and assuming the sheltering coefficient is a constant across all wave frequencies, it can be calculated as

$$A = \frac{\tau_f}{\rho_{ag} \int_{f_{\min}}^{f_{\max}} \left(\frac{U_{\lambda/2}}{C_p} - 1\right) \left|\frac{U_{\lambda/2}}{C_p} - 1\right| kF(f) df} = \frac{\tau_f}{D}$$
(15)

Equation 15 states that the sheltering coefficient can be expressed as the ratio of the form stress and the unscaled integral of the wind input into each spectral wave component, defined as D hereafter (the denominator in Equation 15). D is largely determined by the squared wave-relative wind speed at the spectral peak. Larger form stress thus leads to larger A (less sheltering), and larger wave-relative wind speed over high-energy waves leads to smaller A (more sheltering).

The integration in the denominator makes the expression of A in Equation 15 frequency independent, so this approach may be inappropriate because aerodynamic sheltering is likely to vary at different wave scales. Thus, in this study, we extend the sheltering coefficient from a uniform parameter A across wave-frequency spectrum into a frequency-dependent parameter. To achieve this, we compute the velocity cospectrum $S_{uw}(f)$ and the frequency-dependent wind stress $\tau(f)$ (Drennan et al., 1999):

$$\tau(f) = -\rho_a S_{uw}(f) \tag{16}$$

An integration of $\tau(f)$ over f will yield to τ from Equation 8 theoretically. Due to the geometrical nature of sheltering, we assume that the sheltering effect on a particular wave comes from all the waves longer than itself (lower in frequency). Thus, for every specific frequency f, we integrate the denominator D(f) over the frequencies that are lower than f. The frequency-dependent sheltering coefficient A(f) is then:

$$A(f) = -\frac{\rho_a S_{uw}(f)}{\int_{f_{min}}^f D(f') df'}$$

$$\tag{17}$$

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In this form, the sheltering coefficient is frequency dependent. More energy in the longer waves leads to a smaller A(f) and larger sheltering for that frequency. Conversely, if the frequency-dependent stress $-\rho_a S_{uw}(f)$ is larger at a specific frequency, more energy is transferred from wind to waves in that frequency, thus leading to larger A(f) and smaller sheltering.

2.5. Local Steepness

Flow separation, which leads to sheltering, is closely related to wave steepness (Husain et al., 2019). As wave breaking plays a crucial role in the wave steepness variability under wind forcing, studying wave properties that are related to wave breaking will help us understand the variability of sheltering as well. Liu and Babanin (2004) introduced a method to calculate a wave's local steepness based on wavelet transforms. Their method was shown to be accurate in predicting wave growth and breaking by the verification of visual observation of wave breaking events on Lake George and in the Black Sea.

Following Liu and Babanin (2004), we perform a Hilbert Transform on water surface elevation η_i to obtain the local amplitude a_i :

$$a_i = \mathcal{H}(\eta_i) \tag{18}$$

Subscript i represents data at a local time point t_i . Then, a continuous wavelet transform based on the Morlet function was performed on the water surface elevation η_i to obtain the wavelet spectrum $W(\omega, t)$. The local phase p is then obtained from $W(\omega, t)$:

$$\phi(\omega, t_i) = \arctan\left(\frac{\Im[W(\omega, t_i)]}{\Re[W(\omega, t_i)]}\right)$$
(19)

 $\mathfrak{F}[W(\omega,t)]$ and $\mathfrak{R}[W(\omega,t)]$ are the imaginary and real parts of $W(\omega,t)$, respectively. The local characteristic amplitude A, is defined as

$$A_i = a_i \cos(\phi_i) \tag{20}$$

and finally the local steepness γ is defined as

$$\gamma_i = A_i \omega_p^2 / g \tag{21}$$

 ω_p is the angular frequency where the energy peak from wavelet spectrum is observed. In this study, we use these properties to investigate the local steepness γ 's variability with wind speed and to relate it to aerodynamic sheltering.

2.6. Conditional Phase Average

When shortwaves are sheltered by longer waves, the longer waves modulate the shortwave growth by reducing the wind input. Due to the shape of the wave form, shortwaves may "experience" sheltering differently depending on the phase of the long waves (Donelan et al., 2010; Laxague et al., 2017). The windward face of the long wave receives more wind input than the leeward face. To discuss the modulation of shorter waves by longer waves at different wave phases, Donelan et al. (2006) applied a Hilbert Transform to the mechanically generated long-wave elevation. Based on the phase record from the Hilbert Transform on the long waves, they conditionally sampled and averaged the shortwave properties in select long-wave phase bins. Later, Donelan et al. (2010) discussed the long-wave modulation on the growth of shortwaves generated by winds blown over the surface using conditional phase-averaging on the local wind-sea spectrum based on a wavelet transform. This method successfully revealed the sheltering from different phases of the long wave. Donelan et al. (2010) focused on low-to-moderate winds ($U_{10} < 15 \text{ m s}^{-1}$) due to the limitation of their laboratory. Therefore, the modulation of shortwaves by longer waves in strong winds remains unknown.

Although ocean waves do not exhibit monochromatic behavior but rather are composed of a broadband spectrum, the harmonic form and idealized smoothness of the former aid our ability to isolate and study sheltering. Thus, in our study and following Donelan et al. (2010), we first apply the band-pass filter in the 0.8–1.2 Hz band on the elevation signal of M7.5 to extract the long-wave signal. Then, we use a high-pass filter in the 2.1–2.9 Hz band

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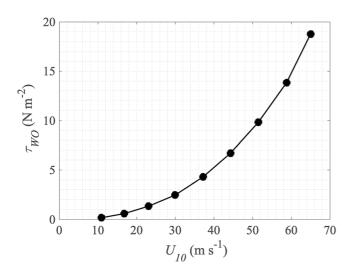


Figure 2. Eddy-covariance wind stress from IRGASON in the wind-only experiment, as function of 10-m wind speed.

to extract the short wind waves. Finally, we perform the method by Liu and Babanin (2004) to get the local wavelet spectrum W_s and local steepness γ_s of short wind-wave signal. Finally, we used 10° bins and phase average W_s and γ_s over the long-wave phases to quantify the variability of shortwave properties depending on the long-wave phase.

3. Results

3.1. Wind Stress

First, we plot the total wind stress τ from the WO experiment derived using the eddy-covariance method (Figure 2). The standard error of wind stress for each condition was found to be $\mathcal{O}(10^{-2})$ and therefore not shown in Figure 2 τ_{WO} follows an approximately quadratic relationship with wind speed and ranges from 0.16 N m⁻² at $U_{10} = 10.9$ m s⁻¹ to 18.7 N m⁻² at $U_{10} = 65.9$ m s⁻¹. Then, we normalize τ_{J10} and $\tau_{MT.5}$ with τ_{WO} for each wind condition to quantify the change of stress relative in these experiments relative to WO (Figure 3).

The measured stresses from the J10 (τ_{J10}) and M7.5 ($\tau_{M7.5}$) experiments are marginally lower than that of the WO experiment in 10-m winds less than 18

and 31 m s⁻¹, respectively. τ_{J10} becomes marginally higher than τ_{WO} in the U_{10} range from 31 to 59 m s⁻¹, by up to 2%. However, $\tau_{M7.5}$ is higher than τ_{WO} In both experiments, the relative stress difference peaks at $U_{10} = 37$ m s⁻¹. In summary, mechanically generated background waves overall cause a wind stress increase in stress except in low-to-moderate winds. This increase is more pronounced in steep monochromatic waves (11% maximum increase) than in broad-banded JONSWAP waves (2% maximum increase). This relative difference is important to establish before we proceed to evaluate the sheltering coefficient for each wind and wave condition in Section 3.4.

3.2. Separating the Form and Viscous Stresses

After obtaining τ via eddy covariance, the separation of τ_f and τ_v described in Section 2.3 was performed and the ratio of the form stress τ_f fraction of the total stress τ is plotted against U_{10} for all three experiments (Figure 4). We also compare our measurements with the numerical results from Donelan et al. (2012) for reference. Overall, τ_f constitutes approximately 60% of total stress at $U_{10} \approx 10$ m s⁻¹ and increases with wind speed to approximately

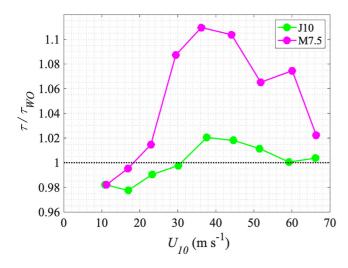


Figure 3. Eddy-covariance wind stress from IRGASON, normalized by τ_{WO} , from the J10 (green) and M7.5 experiments, as a function of 10-m wind speed from the Wind Only (WO) experiment.

90% of the total stress at $U_{10} \approx 65 \text{ m s}^{-1}$. While τ/τ in J10 is quite similar to that of WO, τ/τ in M7.5 is higher than that of WO for U_{10} in the range between 17 and 44 m s⁻¹. Higher fraction of the form stress in the M7.5 experiment compared to the WO and J10 experiments is consistent with the form of the background waves in these experiments. Being monochromatic, the waves in M7.5 are locally steeper than the broad-banded waves of WO and J10, and thus expected to induce an overall higher form drag on the air flow.

3.3. Wave Spectra

Water surface elevation measured by the capacitance wave wires allows us to compute the wave variance spectra for each wind regime and for each experiment (Figure 5). In the WO experiment, we find a sharp increase and frequency downshift of the wave spectral peak when increasing U_{10} from 10.9 to 37.2 m s⁻¹ (Figure 5). However, for stronger winds, the spectral peak exhibits a further downshift of frequency, with no increase in power. One possible mechanism that may explain this regime change is the tearing of wave crests due to direct impact from wind and intensified wave dissipation. This phenomenon has been observed previously in both the field (Holthuijsen

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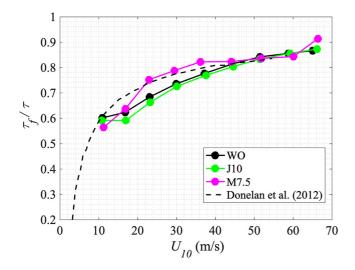


Figure 4. Ratio of form stress τ_f to total stress τ against 10-m wind speed in Wind Only (WO; black), J10 (green), and M7.5 (magenta). Numerical results from Donelan et al. (2012) are plotted in dashed black line.

et al., 2012) and the laboratory (Curcic & Haus, 2020) and is known to occur in hurricane-force winds.

In contrast to the WO experiment, the spectra in J10 maintain their peak at the frequency of 1 Hz, which is the input frequency of the JONSWAP spectrum produced by the wave generator (Figure 5b). This finding supports the results by Lee and Monty (2020) who studied wave growth under wind forcing over background waves with the JONSWAP spectrum and found that the spectral peak of the input waves persists despite the hurricane-force winds. Unlike the WO experiment where the wind-sea peak is evident even in lower wind settings, in the J10 experiment a wind-sea peak does not appear until the wind speeds reach hurricane force. Thus, even the broad-banded mechanically generated waves such as the JONSWAP spectrum are effective at suppressing a significant development of a wind-sea peak. This spectral characteristic is commonly attributed to aerodynamic sheltering of wind sea by longer waves (Chen & Belcher, 2000).

The spectra from the M7.5 experiment are characterized by multiple harmonic peaks at integer multiples of the peak period (Figure 5c). These so-called bound harmonics are an artifact of waves that are not exactly sine-like in form but more peaked being processed with a Fourier transform during the calculation of the spectral density (Donelan et al., 1985). Thus, a Fourier spectrum

of a peaked monochromatic wave results in multiple spectral peaks at integer multiples of the peak period, in our case at 1, 2, 3 s, etc. The bound harmonics are most pronounced in lower wind regimes and become more attenuated with the increase in wind forcing. Unlike the J10 experiment, a secondary wind-sea spectral peak is not evident in the M7.5 experiment in any wind condition. Nevertheless, the high-frequency part of the spectrum increases in energy with the increase in wind speed.

Although the behavior of the wave spectra shown in Figure 5 provides an insight into aerodynamic sheltering in different wind and wave regimes, we will proceed to quantify it more precisely by combining simultaneous and colocated eddy-covariance stress and wave spectrum measurements in the following section.

3.4. Quantifying Aerodynamic Sheltering

We first quantify sheltering using following the integrated, frequency-independent sheltering coefficient in Equation 14. Then, we quantify the sheltering as function of wave frequency, following Equation 15. The results of these two approaches are described in the following subsections.

3.4.1. Frequency-Independent Sheltering

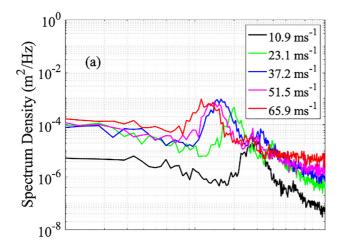
Having quantified the total and form stress and wave spectra for all wind and wave regimes, we now proceed to quantify the aerodynamic sheltering following Section 2.4. Figure 6 shows the sheltering coefficient A as function of 10-m wind speed for all three experiments. All three experiments exhibit an approximately parabolic shape of the sheltering coefficient A as function of U_{10} where A initially decreases and then increases with wind speed. The local minimum of A is located approximately between U_{10} of 30 and 35 m s⁻¹, which corresponds to the transition from tropical storm to Category 1 hurricane-force winds. However, each experiment exhibits a different range of variability of the sheltering coefficient. Specifically, A falls in the range of 0.07–0.34, 0.05–0.14, and 0.03–0.1 in the case of WO, J10, and M7.5, respectively. Recall that low sheltering coefficient A indicates higher sheltered area by the long waves. The amount of sheltering thus increases from pure wind sea to broad-banded JONSWAP to steep monochromatic waves.

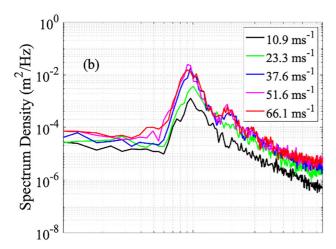
So far, we have assumed a viscous sublayer where the air flow is laminar and governed by a small Reynolds number (Donelan et al., 2012). By combining Equations 11–13, we computed τ_{ν} and thus obtained τ_{f} by subtracting τ_{ν} from the measured eddy-covariance stress τ . Recall that τ_{f} gradually assumes a dominant role in τ in all three experiments (Figure 4). However, this separation of τ_{ν} and τ_{f} does not account for the flow separation on the leeward side where the wind streamlines detach from the wave surface and the viscous sublayer is no longer clearly defined. Thus, inaccuracies may arise in our estimation of τ_{ν} . To quantify the effect of this

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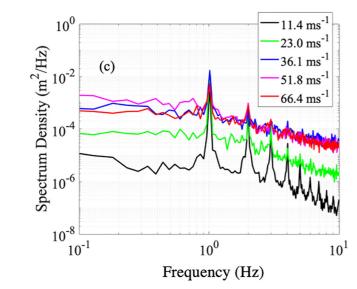


Figure 5. Wave variance spectra from experiments (a) Wind Only (WO), (b) J10, and (c) M7.5 under five different wind regimes.

uncertainty on the sheltering coefficient A, we calculated A by assuming a $\pm 25\%$ uncertainty range in the value of τ_{ν} . These uncertainties in A are shown with error bars in Figure 6. The size of these error bars confirms that the sheltering coefficient is not sensitive to the value of τ_{ν} , especially in experiments J10 and M7.5. This suggests that the denominator D in Equation 14 is the dominant contributor to the value of A. A more accurate estimation of τ_f will involve wave-following pressure measurement or a PIV technique (Banner & Peirson, 1998) in the tank, which will be one of the goals of our future research.

To place our sheltering coefficient results in the context of previous studies, we compare them with values obtained from a number of field and laboratory measurements (Donelan & Pierson, 1987; Donelan et al., 2006; Grare, 2009; Mastenbroek et al., 1996; Peirson & Garcia, 2008; Peirson et al., 2014). We plot our estimates of the sheltering coefficient, as well as those from previous studies, against mean wave steepness ak (Figure 7). A few of these studies considered A a constant (Donelan, 1999; Donelan & Pierson, 1987; Donelan et al., 2006, 2012). Others (Grare, 2009; Mastenbroek et al., 1996; Peirson & Garcia, 2008; Peirson et al., 2014) obtained A that varied with ak. Previous results were derived from pure wind-sea conditions, similar to our WO experiment. However, their wind forcing remained limited to low-to-moderate conditions. Compared to previous work, our results extend the range of ak beyond the previously measured 0.32 by Peirson et al. (2014), up to the critical steepness of 0.42 in the M7.5 experiment. Our estimates of the sheltering coefficient in pure wind-sea WO are consistent with and in support of the previous work (Grare, 2009; Grare et al., 2013; Mastenbroek et al., 1996). Overall, A decreases with increasing ak and asymptotes at values below 0.08 for very steep waves, which is indicative of strong sheltering and possibly flow separation in the lee of these waves.

In summary, the sheltering coefficient A exhibits significant variability at moderate ($U_{10} < 20 \text{ m s}^{-1}$) and extreme ($U_{10} > 40 \text{ m s}^{-1}$) wind speeds depending on the wave state. Similarly, A is also highly variable (in the range from 0.05 to 0.35) in wave states of moderate steepness (0.12 < ak < 0.25). It is important to better understand the nature and the cause of this variability to allow formulating more accurate wind input source functions for numerical wave models. We explore possible causes of sheltering variability in more depth later in this paper.

3.4.2. Frequency-Dependent Sheltering

As the typical wave states in the field are broad banded and often bimodal, a frequency-integrated sheltering coefficient may not be used to characterize the aerodynamic sheltering at different wave scales. Using Equation 17, we evaluate A as a function of frequency in all three experiments and evaluate it over the shortwave-frequency band of 1–10 Hz (Figure 8). The dominant pattern is that A(f) decreases with increasing wind forcing across the entire shortwave-frequency band. This implies that higher wind forcing induces more sheltering on shortwaves. Further, A(f) gradually decreases with frequency. This means that shorter waves are more sheltered than the longer ones. A steep decrease in A(f) occurs at 1–3 Hz in WO for $U_{10}=10.9~{\rm m~s^{-1}}$ and at 1–2 Hz for higher wind speeds (Figure 8a). Beyond 3 Hz and $U_{10}=23.1~{\rm m~s^{-1}}$ (tropical storm-force winds), A(f) appears to saturate and not decrease any further with increasing winds. This can be explained by the downshifting of the spectral speak in WO that we observed in Figure 5a—as the wind-sea peak shifts to lower frequencies with increasing wind speed,

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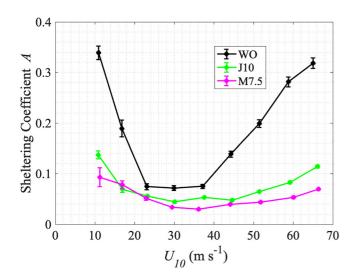


Figure 6. Sheltering coefficient *A* as function of 10-m wind speed from all three experiments. The error bars show the range of uncertainty in *A* resulting if errors in the calculation of τ_{ν} are in the range $\pm 25\%$.

so does the frequency band of well-sheltered waves shifts down. This serves as evidence that even a broad-banded wind-sea peak can effectively shelter shorter waves from wind input.

In the J10 experiment, the sharp decrease of A(f) with frequency occurs in the 1–2 Hz in all wind regimes because the sheltering is mainly governed by the strong JONSWAP peak at 1 Hz (Figure 8b). As we observed in Figure 5b, the wind-sea peak that develops in the JONSWAP spectrum is significantly attenuated and exhibits a weaker downshift, if any. As a consequence, the shape of A(f) in this wave regime is largely independent of the wind speed. However, like in the WO experiment, the increasing wind forcing decreases A(f) across most of the 1–10 Hz band. This is simply by virtue of the increasing wind speed over peak waves with more or less constant phase speed lead to a quadratically increasing denominator D in Equation 17, so the A(f) must decrease overall.

Finally, in the M7.5 experiment, A(f) is the most regularly behaved of the three experiments—it decreases mostly monotonically with frequency (Figure 8c). This is expected because the waves is M7.5 are extremely narrow banded with the peak frequency at 1 Hz. All waves shorter than that are almost equally well sheltered. However in the strongest wind forcing ($U_{10} = 66.4 \, {\rm m \, s^{-1}}$), A(f) is considerably less regular, possibly due to intense wave dissipation by direct

impact from wind that we observed visually. The absence of A(f) in this wind regime for waves longer than 2.5 Hz and higher than 9 Hz is due to the negative velocity cospectrum $\tau(f)$ (i.e., negative or upward momentum flux) in these frequency bands.

3.5. Spectral Density and Local Steepness

To better understand the physical mechanism behind the increase of A with increasing wind speed, we conditionally average the shortwave properties over the phase of a monochromatic long wave. Recall that the sheltering hypothesis proposes that the shortwaves are aerodynamically sheltered by specific geometric features (i.e., crests) of the long wave. Phase-dependent conditional averaging thus allows us to quantify the shortwave properties in relation to the long-wave crests and troughs. First, we obtained the shortwaves' elevation η_s by applying a band-pass filter of 2.1–2.9 Hz over water elevation collected by wave wire. Then, we performed the continuous

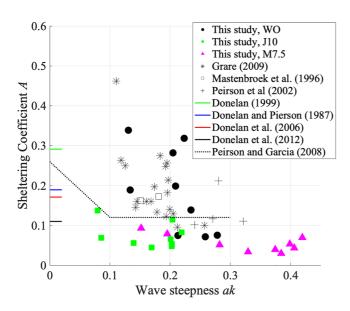


Figure 7. Sheltering coefficient *A* as a function of mean wave steepness *ak*, based on the three experiments in this study, and several previous studies.

wavelet transform to obtain the shortwaves' omni-directional wavelet spectrum density $W_s(\omega,t)$ and calculated shortwaves' local steepness γ_s from η_s mentioned in Section 2.5. An integration of $W_s(\omega,t)$ on angular frequency ω will yield a time series $W_s(t)$, in the same dimension as γ_s as well as the water elevation. We then phase-averaged γ_s and $W_s(t)$ of short-wave over the long-wave phase, using the conditional phase-averaged method mentioned in Section 2.6. To demonstrate how shortwave energy is distributed over the long-wave phase, we normalized omni-directional spectral density W_s of the shortwave by dividing its mean value over each run time (e.g., Shabani et al., 2022). Thus, the phase-averaged normalized omni-directional spectra represent the shortwave energy distribution over long waves and the local steepness of shortwave represents the geometrical form and breaking intensity of these waves in the M7.5 experiment (Figure 9), with error bars of one standard error.

The normalized spectral density and the local steepness of shortwaves overall have strong dependence on the phase of the long wave (Figure 9). In the lowest wind setting ($U_{10}=11.4~{\rm m~s^{-1}}$), the normalized spectrum of the shortwaves is upwave relative to the long-wave crest and its minimum in its trough (Figure 9a). This is mostly consistent with the traditional hydrodynamic modulation theory based on the dispersion relationship and the conservation of wave crests (Longuet-Higgins & Stewart, 1960) whose

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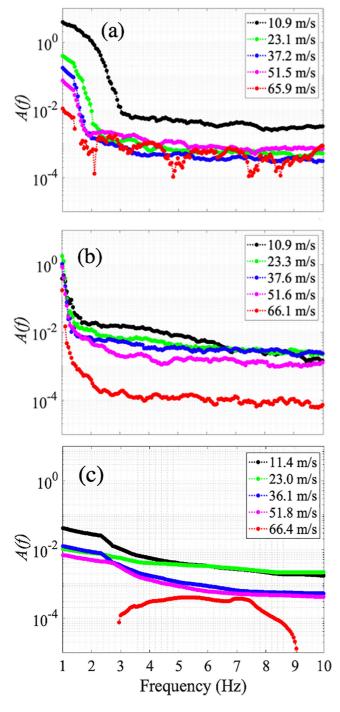


Figure 8. Frequency-dependent sheltering coefficient *A*(*f*) from experiments (a) Wind Only (WO), (b) J10, and (c) M7.5 under five different wind regimes.

solution finds the highest modulation at the crest. However, as the wind speed increases, the phase of the shortwave spectral peak shifts initially downwave at $U_{10} = 23.0 \,\mathrm{m\ s^{-1}}$ and then upwave again for higher wind speeds, consistent with the findings by Donelan et al. (2010). The downwave location of the peak at $U_{10} = 23.0 \,\mathrm{m\ s^{-1}}$ may be associated with the whitecapping of the long wave on its front face, which transfers some of the long-wave energy to higher frequencies. This result can be attributed to two distinct processes: First, the wind forcing on the rear face of the long wave generates shortwaves and results in the increase of their spectral density; second, the front face of the steep long wave amplifies the breaking of the shortwave by increasing their steepness (Donelan et al., 2012). The range of error bars for W_s has the nondimensional scale of 0.04 and is not phase dependent. Thus, we consider the distribution of W_s along long-wave's phase as statistically representative.

In contrast to the normalized spectral density, the local steepness γ_s of the shortwaves exhibits two local maxima and minima each over the phase of the long wave (Figure 9b). The range of error bars for γ_s is relatively small compared to those of W_s and is barely visible until wind forcing reaches 66.4 m s⁻¹ on the windward side. Thus, we also consider γ_s distribution along long-wave's phase as statistically representative. The first peak occurs on the windward side (0°-180°) and the second peak on the leeward side (180°-360°). The peak on the windward side is larger than that at leeward side in all wind regimes. Like the spectral density, the local steepness peak on the windward face of the long wave also shifts upwind with increasing wind speed. Once U_{10} exceeds 36.1 m s⁻¹, the peak of γ_s exceeds the breaking threshold 0.6 (Liu & Babanin, 2004). In such circumstance, shortwaves have a high probability of breaking. γ_s peaks also do not occur in the same longwave phase as W_s peak in (a). Such discrepancy is particularly observable after wind once exceeds in the same m s⁻¹ where windward γ_s peak exceeds the breaking threshold. Thus, in hurricane-force winds, although γ_s reach a maximum, the strongest energy occurred at a different long-wave phase due to the intense breaking at the γ_s peak. A similar phenomenon was observed by Donelan et al. (2010) who found that as the wavenumber moves above the spectral peak, the long waves modulate the shortwave spectral density and drive it into a breaking-limited saturation state. Thus, we interpret this disparity between γ_s and W_s to be the result of shortwave breaking due to both hydrodynamic and aerodynamic modulation (the sheltering effect, which is observed from the value of sheltering coefficient and the phase variability of γ_s 's peak on the long wave). Meanwhile, the leeward γ_s peak remains under the breaking threshold without a significant phase shift. We suspect that this may be due to a combination of increasing hydrodynamic modulation and decreasing aerodynamic modulation on the forward face of the long wave. However, further research (ideally using PIV techniques) is needed to verify such assumption.

4. Discussion

4.1. Wind Stress Variability

Vincent et al. (2019) found based on field measurements that swell modulates the wind stress. In their study, U_{10} did not exceed 20 m s⁻¹ and they found an

upward (negative) momentum flux in the swell. While in our laboratory experiments we do not produce swell waves (i.e., waves that out-run the wind), waves that do propagate faster, for example, in experiments J10 and M7.5, are expected to incur lower wind stress overall due to the relative wind terms in Equation 1. However, as U_{10} increases, wave-induced stress in J10 and M7.5 gradually increases as well and outgrows that of WO. Our

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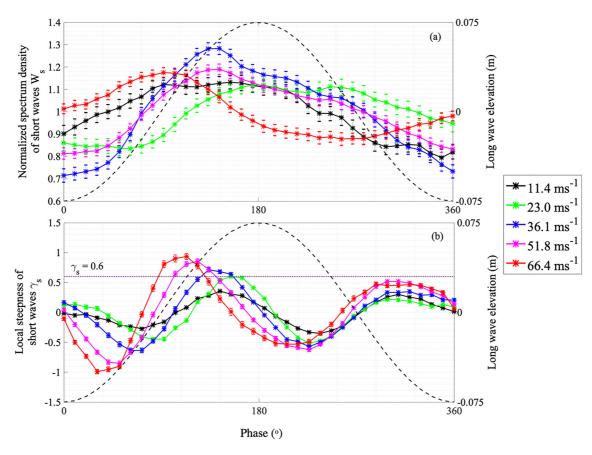


Figure 9. Conditional phase average of (a) normalized omni-directional short wind-wave spectral density and (b) short wind-wave local steepness γ_s over long-wave phase under different wind speed from M7.5. *Y*-axis on the right represents the long-wave's elevation, where the long wave is shown by black dashed line. The black dotted line (*γ* = 0.6) is the threshold used to identify breaking by Liu and Babanin (2004). The error bar is defined as the range of one standard error within each phase bin.

visual observation of whitecapping and frequent breaking at wave crests confirms frequent breaking of peak waves in the same forcing range ($U_{10} > 30 \text{ m s}^{-1}$). Further, Babanin et al. (2007) discussed the variability of τ with breaking events. Their results showed that following wave breaking there is an increase in wind input,

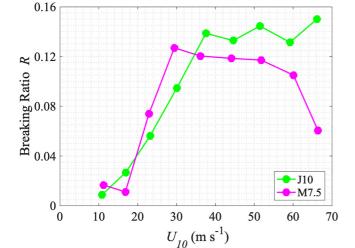


Figure 10. Breaking ratio *R* in J10 (green) and M7.5 for each wind forcing.

which is primarily manifested as the pressure difference between the windward and leeward faces of the wave. They concluded that breaking events increase wind stress τ .

To better understand the cause of the wind stress variability between different J10 and M7.5 experiments, we first isolate the water elevation associated with the mechanically generated waves by applying a band-pass filter (the filter ranges from 0.8 to 1.2 Hz). Then, we calculate the local steepness of the mechanically generated waves γ as described in Section 2.5. Since local steepness is an indicator of breaking events, its value yields information about the breaking of the long waves (Liu & Babanin, 2004). Then, we relate the wave breaking to the τ variability by defining the breaking ratio R as the ratio of long waves with $\gamma > 0.6$ to all long waves, following Liu and Babanin (2004). This is shown in Figure 10. J10 and M7.5 show a similar trend of breaking ratio suddenly increasing with wind speed from 16 m s⁻¹ wind speeds to approximately 30 m s⁻¹ wind speeds. In hurricane-force winds, the breaking ratio saturates at approximately 0.14 and 0.12 in experiments J10 and M7.5, respectively. Unlike that of the J10 experiment, the breaking ratio in the M7.5 experiment exhibits a decrease in extreme winds $(U_{10} > 50 \text{ m s}^{-1})$. This decrease may be caused by the intense wave dissipation due to direct impact from wind, which we can visually observe to

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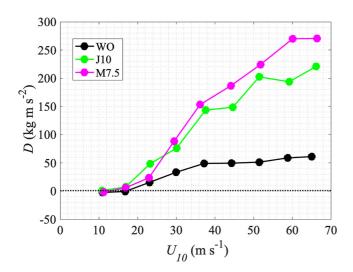


Figure 11. Sheltering coefficient denominator *D* from all experiments as function of 10-m wind speed.

happen in the laboratory. Finally, we correlate the wave breaking ratio and the wind stress variability in J10 and M7.5. We find the correlation coefficients of 0.91 and 0.94 in experiments J10 and M7.5, respectively. They are thus highly correlated, and this is supported by the prior results of Babanin et al. (2007).

4.2. Sheltering Coefficient Variability

To better understand the variability of the sheltering coefficient, we evaluate the denominator D from the expression for A in Equation 15. We plotted D as a function of wind speed from all three experiments (Figure 11). D is mostly monotonically increasing with wind speed. In the case of WO, there is a hint of saturation of D in $U_{10} > 36$ m s⁻¹). This saturation may be a consequence of intensified wave breaking in hurricane wind conditions (Curcic & Haus, 2020; Takagaki et al., 2012). Due to the increased wind stress and the gradual saturation of D shown in Figure 6, the sheltering coefficient A first decreases due to the sharp increase of D and then increases due to the gradual saturation of D and the continuous increase of T_f . Physically, the decrease of T_f from low-to-moderate winds results from wave growth: with increasing wind speeds, waves develop and more sheltering is induced on the shortwaves.

After U_{10} exceeds 20 m s⁻¹, strong breaking (large R, Figure 10) and wave energy saturation occur, as seen in the spectral peaks that did not further increase with wind speed (Figure 5). The breaking of high waves increases the sheltered area and reduces the sheltering coefficient.

It may provide further insight into the sheltering of shorter waves to integrate Equation 16 over the frequency band of 1–10 Hz:

$$A_{in} = \int_{1Hz}^{10Hz} A(f) \, df \tag{22}$$

We compare shortwave-banded A_{in} to the total integrated sheltering coefficient in A for all experiments and wind conditions (Figure 12). Unlike A which has an overall parabolic shape in all three experiments, A_{in} exhibits an overall decrease with wind speed. The shortwaves in the 1–10 Hz frequency band become increasingly more sheltered with increasing wind speed. A_{in} under U_{10} of 10.9 m s⁻¹ in WO is exceptionally large (2.7, not shown in Figure 12a) compared to other A_{in} values under stronger wind forcings in WO. This is because of the absence of paddle waves and lowest wind forcing, which rendered relatively weak sheltering effect on shorter waves and henceforth, a large A_{in} value. In the WO and J10 experiments, A_{in} is larger than their respective A in $U_{10} < 30$ m s⁻¹ and $U_{10} < 50$ m s⁻¹, respectively. However, under extreme wind forcing, A_{in} becomes smaller than A. Unlike in J10 and WO, A_{in} in M7.5 is smaller than A in all wind conditions. This is because the M7.5 experiment has the dominant wave that is steep and monochromatic, which effectively sheltered all shorter waves.

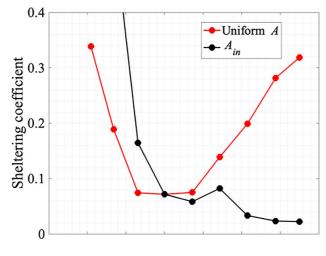
4.3. Side-Camera Imaging of Wave Growth and Breaking

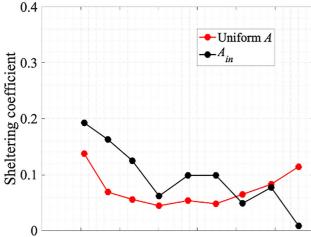
With the aid of a side-mounted digital camera with sampling frequency at 20 Hz, we visualized the air–sea interface on the windward and leeward faces of each passing wave with increasing wind speeds (Figure 13). We select photographs that were illustrative of the typical process of wind forcing and wave breaking during the M7.5 experiment. The images are of the windward and leeward faces of the same monochromatic wave.

Under U_{10} values of $10.9~{\rm m~s^{-1}}$, windward and leeward faces appear smooth and maintain a nearly sine-like shape. An increase in amplitude can be seen on windward face under U_{10} of $23.1~{\rm m~s^{-1}}$ due to wind input (Figure 13c). As wind forcing increased, shorter waves become more prominent on the windward face (Figures 13e and 13g). This is consistent with our local steepness results from Figure 9 where we found a local maximum of shortwave steepness on the windward face of the long wave. On the leeward face of the wave and beginning with U_{10} of $36.1~{\rm m~s^{-1}}$, we see evidence of intense, plunging wave breaking, with bubbles, spume, and spray generation (Figures 13f, 13h, and 13j). Finally, in the most extreme wind condition, the windward face of the wave shows evidence of the wave tearing and spume generation due to direct impact from wind on the wave crest (Figure 13i).

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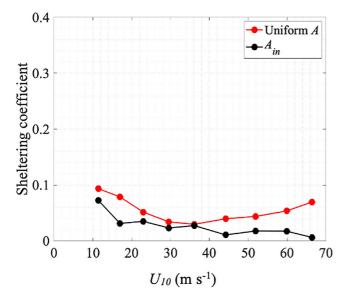


Figure 12. Shortwave-banded sheltering coefficient A_{in} and total integrated sheltering coefficient A from experiments (a) Wind Only (WO), (b) J10, and (c) M7.5 in different wind conditions.

The side-mounted camera images of growing and breaking waves thus provide visual support of some of our results and interpretations presented in the previous sections.

5. Conclusions

In this study, we quantified the aerodynamic sheltering of shortwaves by longer waves using the JS hypothesis and high-frequency laboratory measurements of waves and stress in a wide range of wave states and wind conditions. We conclude with several takeaways:

- We find that the sheltering coefficient is not constant, as was previously commonly assumed. Instead, the sheltering coefficient varies significantly depending on the wave state and the wind forcing.
- 2. The sheltering coefficient is an approximately parabolic function of wind speed: it first decreases with wind speed up to $U_{10} \approx 30~{\rm m~s^{-1}}$ (corresponding to the transition from tropical storm-force to hurricane-force winds) where it saturates with the value between 0.04 and 0.08; then, it increases with wind speed, reaching values between 0.08 and 0.32, depending on the background wave state.
- 3. The sheltering coefficient also varies greatly with the background wave state. Pure wind-sea yields higher sheltering coefficients (0.08–0.32), while a broad-banded JONSWAP spectra and monochromatic waves yield significantly lower sheltering coefficients with ranges of 0.05–0.14 and 0.04–0.09, respectively. Overall, steeper and more narrow-banded waves yield stronger sheltering (but lower sheltering coefficient) of the shortwaves.
- 4. Our estimates of the sheltering coefficient complement the existing, albeit scarce, data sets from previous studies (Grare et al., 2013), and extend the ranges of previously studied conditions both in terms of wind speed and wave steepness.
- Phase-dependent bin-averaging over many consecutive phases of the monochromatic long wave reveals an overall downshift of shortwave spectra and a gradual increase of the shortwave steepness on the windward face of the long wave with increasing wind speed.
- 6. Side-camera imaging provides visual evidence of the development of short, steep waves on the windward face of the long wave due to strong wind forcing. As the winds become extreme (major hurricane force), intense wave breaking and tearing of wave crests due to direct impact from wind is evident.
- 7. More detailed measurements, especially using PIV techniques on the air-side of the wavy interface, are needed to provide a more in-depth understanding of aerodynamic sheltering of shortwaves in extreme winds. This is important because the wind input functions in the current spectral wave models do not resolve this physical process to a sufficient detail.
- 8. Our results stress the need for a more accurate and comprehensive parameterization of aerodynamic sheltering that takes into account not only the wind speed but also the shape and amplitude of the wave spectrum. Our future work will attempt to fill this gap while building on top of results presented here.

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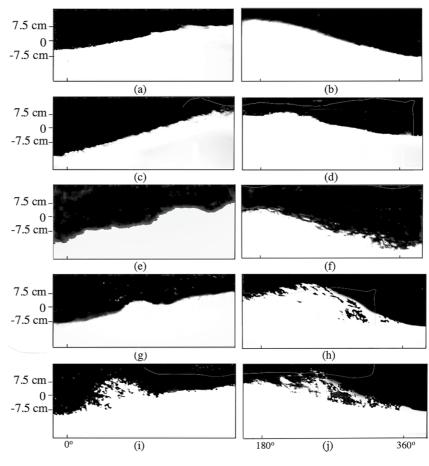


Figure 13. Photographs of waves during the M7.5 experiment of the windward (a, c, e, g, and i) and leeward (b, d, f, h, and j) faces and U_{10} values of 11.4 m s⁻¹ (a, b), 23.0 m s⁻¹ (c, d), 36.1 m s⁻¹ (e, f), 51.8 m s⁻¹ (g, h), and 66.4 m s⁻¹ (i, j). The contrast was enhanced and image cropped to isolate and center on the air-water interface. The waves are propagating from left to right.

Data Availability Statement

The quality-controlled data used in this paper can be found at: https://zenodo.org/record/7764266.

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Acknowledgments

Information S1.

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