

# 360.252 - Computational Science on Many-Core Architectures

WS 2020 - Exercise 6

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#### 1 Dot Product with warp shuffles - shared memory

I tested my code setting N=5 which gave me the result shown in figure 1. I decided to implement everything with integers since the atomicMin() and atomicMax() would need some additional code snippets to work for double which, of course, I could have copied from the cuda documentation. But I wanted to avoid more overhead since I wanted to only focus on the principals here.

# Compile output

[Compilation successful]

## Run output

```
Input
-2 | -1 | 0 | 1 | 2 |
Sum of all entries: 0
Sum of maximum values: 6
Sum of squares: 10
Max-norm: 2
minimum value: -2
maximum value: 2
number of zeros: 1
```

Figure 1: Output of shared memory version

Listing 1: Calculations done with shared memory

```
#include <iostream>
2
    __global__ void sharedMemoryKernel(const
3
                                                   int * x,
                                                            int * y, const int N) {
        \_shared\_ int sharedMemory [7][256];
4
5
         int sum = 0;
         int maxSum = 0;
6
7
         int   sqrSum = 0;
8
         int \max Mod = 0;
9
         int min = x[0];
10
         int max = 0;
11
         int zeros = 0;
12
13
        for (int tid = blockDim.x * blockIdx.x + threadIdx.x;
        tid < N; tid += gridDim.x * blockDim.x) {
14
            int val = x[tid];
15
16
17
            sum += val;
18
            \max Sum += std :: abs(val);
19
            sqrSum += val*val;
20
            \max Mod = std :: abs(val) > \max Mod ? val : \max Mod;
21
            \min = \text{val} < \min ? \text{val} : \min;
            \max = val > \max ? val : \max;
22
23
            zeros += val == 0 ? 1 : 0;
24
25
26
        int tid = threadIdx.x;
27
        if (tid < N) {
            sharedMemory[0][threadIdx.x] = sum;
28
```

```
29
             sharedMemory[1][threadIdx.x] = maxSum;
             sharedMemory[2][threadIdx.x] = sqrSum;
30
             sharedMemory[3][threadIdx.x] = maxMod;
31
             sharedMemory[4][threadIdx.x] = min;
32
33
             sharedMemory[5][threadIdx.x] = max;
34
             sharedMemory[6][threadIdx.x] = zeros;
35
             _syncthreads();
36
37
             // blockDim.x needs to be a power of 2 in order for this to work
             for (int i = blockDim.x/2; i != 0; i /= 2) {
38
39
                  _syncthreads();
                  if (tid < i) 
40
                      \operatorname{sharedMemory}[0][\operatorname{tid}] += \operatorname{sharedMemory}[0][\operatorname{tid} + i];
41
                      sharedMemory[1][tid] += sharedMemory[1][tid + i];
42
                      sharedMemory [2][tid] += sharedMemory [2][tid + i];
43
44
                      sharedMemory[3][tid] = sharedMemory[3][tid] > sharedMemory[3][tid + i]
                      ? sharedMemory[3][tid] : sharedMemory[3][tid + i];
45
                      sharedMemory [4][tid] = sharedMemory [4][tid] < sharedMemory [4][tid + i]
46
                      ? sharedMemory [4][tid]: sharedMemory [4][tid + i];
47
                      \operatorname{sharedMemory}[5][\operatorname{tid}] = \operatorname{sharedMemory}[5][\operatorname{tid}] > \operatorname{sharedMemory}[5][\operatorname{tid}+\operatorname{i}]
48
49
                      ? sharedMemory [5] [tid] : sharedMemory [5] [tid + i];
                      sharedMemory [6] [tid] += sharedMemory [6] [tid + i];
50
51
                  }
             }
52
        }
53
54
        if (tid = 0) {
55
56
             atomicAdd(y, sharedMemory[0][0]);
             atomicAdd(y+1, sharedMemory[1][0]);
57
             atomicAdd(y+2, sharedMemory[2][0]);
58
59
             atomicMax(y+3, sharedMemory[3][0]);
60
             atomicMin(y+4, sharedMemory[4][0]);
61
             atomicMax(y+5, sharedMemory[5][0]);
             atomicAdd(y+6, sharedMemory[6][0]);
62
        }
63
64
   }
65
    template <typename T>
66
     void printContainer (T container,
67
         for (int i = 0; i < N; i++) {
68
              std::cout << container[i] << " | ";
69
70
   }
71
72
73
74
   int main() {
75
76
        int N = 5;
77
         int *x = (int *) malloc(sizeof(int) * N);
78
         int *y = (int *) malloc(sizeof(int) * 7);
79
80
81
        for (int i = 0; i < N; i++) {
             x[i] = i - N/2;
82
83
84
85
         int *cuda_x;
```

```
int *cuda_y;
 86
 87
           cudaMalloc(&cuda_x, sizeof( int) * N);
           cudaMalloc(&cuda_y, sizeof( int) * 7);
 88
 89
           cudaMemcpy(cuda_x, x, sizeof( int) * N, cudaMemcpyHostToDevice);
 90
 91
 92
           sharedMemoryKernel << <256, 256>>>(cuda_x, cuda_y, N);
 93
           cudaMemcpy(y, cuda_y, sizeof( int) * 7, cudaMemcpyDeviceToHost);
 94
 95
 96
           std::cout << "Input" << std::endl;
 97
           printContainer(x, N);
           std::cout << std::endl;
 98
 99
           std::cout << "Sum of all entries: " << y[0] << std::endl;\\
100
           std::cout << "Sum of maximum values: " << y[1] << std::endl;
101
           std::cout << "Sum of squares: " << y[2] << std::endl;
102
103
           std::cout << "Max-norm: " << y[3] << std::endl;
           \begin{array}{l} {\rm std}:: {\rm cout} << \text{"minimum value}: \text{"} << y[4] << {\rm std}:: {\rm endl}; \\ {\rm std}:: {\rm cout} << \text{"maximum value}: \text{"} << y[5] << {\rm std}:: {\rm endl}; \\ {\rm std}:: {\rm cout} << \text{"number of zeros}: \text{"} << y[6] << {\rm std}:: {\rm endl}; \\ \end{array}
104
105
106
107
108
           free(x);
109
           free (y);
110
           cudaFree(cuda_x);
           cudaFree(cuda_y);
111
112
113
           return EXIT_SUCCESS;
114
```

#### 2 Dot Product with warp shuffles - warp shuffles

I tested my code by comparing to the version in point 1.

Listing 2: Calculations done with warp shuffles

```
#include <iostream>
   __global__ void shuffleKernel(const int * x, int * y, const int N) {
3
4
5
       int sum
                           = 0;
6
       int maxSum
                           = 0;
7
       int sqrSum
                           = 0;
8
       int maxMod
                           = 0;
                           = x[0];
9
       int min
10
       int max
                           = 0:
                           = 0:
11
       int zeros
12
13
       for (int tid = blockDim.x * blockIdx.x + threadIdx.x;
14
       tid < N; tid += gridDim.x * blockDim.x) 
15
           int val = x[tid];
16
17
           sum
                       += val;
                       += std::abs(val);
18
           maxSum
19
                       += val*val;
           sqrSum
                       = std :: abs(val) > maxMod ? val : maxMod;
20
           \max Mod
21
           min
                       = val < min ? val : min;
                       = val > max ? val :max;
22
           max
23
                       += val == 0 ? 1 : 0;
           zeros
24
       }
25
26
       int tid = threadIdx.x;
27
       for (int i = warpSize / 2; i != 0; i /= 2) {
                       += -shfl_down_sync(0 xffffffff, sum, i);
28
           sum
29
           \max Sum
                       += __shfl_down_sync(0xfffffffff, maxSum, i);
30
           sqrSum
                       += -shfl_down_sync(0 xfffffffff, sqrSum, i);
           31
                       = temporary > maxMod ? temporary : maxMod;
32
           \max Mod
33
                       = -shfl_down_sync(0xffffffff, min, i);
           temporary
34
                       = temporary < min ? temporary : min;
           min
35
                       = -shfl_down_sync(0xffffffff, max, i);
           temporary
36
           max
                       = temporary > max ? temporary : max;
37
                       zeros
38
39
       _syncthreads();
40
       if (tid % warpSize = 0) {
41
           atomicAdd(y,
                          sum);
42
           atomicAdd(y+1, maxSum);
           atomicAdd(y+2, sqrSum);
43
44
           atomicMax(y+3, maxMod);
45
           atomicMin(y+4, min);
           atomicMax(y+5, max);
46
           atomicAdd(y+6, zeros);
47
48
       }
49
50
   template <typename T>
```

```
void printContainer(T container, int N) {
52
53
         for (int i = 0; i < N; i++) {
             std::cout << container[i] << " | ";
54
55
56
   }
57
58
59
   int main() {
60
        int N = 100000;
61
62
63
        int *x = (int *) malloc(size of (int) * N);
64
        int *y = (int *) malloc(size of (int) * 7);
65
66
        for (int i = 0; i < N; i++) {
67
            x[i] = i - N/2;
68
69
70
        int *cuda_x;
        int *cuda_y;
71
        cudaMalloc(&cuda_x, sizeof(int) * N);
72
73
        cudaMalloc(&cuda_y, sizeof(int) * 7);
74
75
        cudaMemcpy(cuda_x, x, sizeof(int) * N, cudaMemcpyHostToDevice);
76
        shuffleKernel \ll N/256, 128 >>> (cuda_x, cuda_y, N);
77
78
        cudaMemcpy(y, cuda_y, sizeof(int) * 7, cudaMemcpyDeviceToHost);
79
80
81
        //std::cout << "Input" << std::endl;
82
        //printContainer(x, N);
83
        // std :: cout << std :: endl;
84
        std::cout \ll "Sum of all entries: " \le y[0] \le std::endl;
85
        86
87
        \operatorname{std}::\operatorname{cout}<<\operatorname{"Max-norm}: " <<\operatorname{y}[3]<<\operatorname{std}::\operatorname{endl};
88
89
        std::cout << "minimum value: " << y[4] << std::endl;
        std::cout << "maximum value: " << y[5] << std::endl;
90
91
        std::cout << "number of zeros: " << y[6] << std::endl;
92
        free(x);
93
        free(y);
94
95
        cudaFree(cuda_x);
96
        cudaFree(cuda_y);
97
98
        return EXIT_SUCCESS;
99
```

### 3 Dot Product with warp shuffles - performance comparison

In order to compare the performances, I launched every kernel with [N/256, 128]. I additionally implemented the dot product in shared and shuffled version. The results can be found in figure 2. It can be seen that the shuffled versions perform a little better than the shared memory versions unless for one data point at the last N. I cannot really explain this behaviour. I doublechecked my tests and didn't find any errors in there.

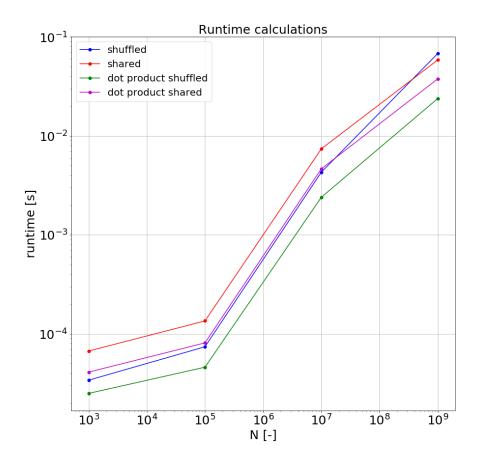


Figure 2: Runtimes for different versions

Listing 3: Dot product using shared memory

```
__global__ void dot_product(int* x, int* y, int* dot, int N) {
1
2
3
       int index = threadIdx.x + blockDim.x * blockIdx.x;
       int stride = blockDim.x * gridDim.x;
4
5
6
        _shared_ int cache[128];
7
8
       int temp = 0;
9
       while (index < N) {
10
            temp += x[index] * y[index];
            index += stride;
11
12
13
       cache[threadIdx.x] = temp;
14
15
        _syncthreads();
16
```

```
17
18
        for (int i = blockDim.x/2; i > 0; i/= 2) {
19
            __syncthreads();
            if (threadIdx.x < i)
20
                cache[threadIdx.x] += cache[threadIdx.x + i];
21
22
        }
23
        if (threadIdx.x == 0)
24
25
            atomicAdd(dot, cache[0]);
26
27
   }
```

#### Listing 4: Dot product using warp shuffles

```
__global__ void dot_product_shuffle(int* x, int* y, int* dot, int N) {
1
2
3
       int index = threadIdx.x + blockDim.x * blockIdx.x;
4
       int stride = blockDim.x * gridDim.x;
5
6
       int temp = 0;
        while (index < N) {
7
8
            temp += x[index] * y[index];
9
            index += stride;
10
       }
11
        for (int i = warpSize / 2; i != 0; i /= 2) {
12
13
                         += -shfl_down_sync(0xffffffff, temp, i);
14
15
16
       --syncthreads();
17
       int tid = threadIdx.x;
18
19
        if (tid % warpSize == 0) {
20
21
            atomicAdd(dot, temp);
22
23
24
```

#### 4 Sparse Matrix Times Dense Matrix - The kernel

I tested my implementation of the sparse matrix times dense matrix with the matrix from the lecture, see figure 3, and by comparing it to a sparse matrix times a vector. Details and results please take from figure 4 and the code listing.

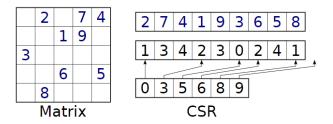


Figure 3: testmatrix from the lecture

## Run output

```
x:
1 | 2 | 3 | 4 | 5 |
Result:
52 | 39 | 3 | 43 | 16 |
X:
1 | 2 | 3 | 4 | 5 | 1 | 2 | 3 | 4 | 5 | 1 | 2 | 3 | 4 | 1 |
Result:
52 | 39 | 3 | 43 | 16 | 52 | 39 | 3 | 43 | 16 | 36 | 39 | 3 | 23 | 16 |
```

Figure 4: results of matrix vector and matrix matrix product

#### Listing 5: matrix\*vector and matrix\*matrix

```
#include <iostream>
1
2
3
   // y = A * x
4
   --global-- void sparseVector(int N, int *csr_rowoffsets,
5
                                              int *csr_colindices , double *csr_values ,
6
                                              double *x, double *y)
7
8
     for (int i = blockIdx.x * blockDim.x + threadIdx.x;
9
     i < N; i += blockDim.x * gridDim.x)  {
10
        double sum = 0;
11
        for (int k = csr_rowoffsets[i]; k < csr_rowoffsets[i + 1]; k++) {
12
         sum += csr_values[k] * x[csr_colindices[k]];
13
14
15
       y[i] = sum;
16
17
   }
18
19
20
21
   // Y = A * X
   __global__ void sparseDense(int N, int K, int *csr_rowoffsets,
```

```
23
      int *csr_colindices, double *csr_values,
24
      double *x, double *y)
25
      for (int i = blockIdx.x * blockDim.x + threadIdx.x;
26
27
      i < N; i \leftarrow blockDim.x * gridDim.x) {
28
29
        for (int k = 0; k < K; k++) {
30
          double sum = 0;
31
          for \ (int \ jj = csr\_rowoffsets [i]; \ jj < csr\_rowoffsets [i+1]; \ jj++) \ \{
32
33
            sum += csr_values[jj] * x[csr_colindices[jj] + N*k];
34
35
          y[i + N*k] = sum;
36
37
38
39
      }
   }
40
41
42
43
   template <typename T>
    void printContainer(T container, int N) {
44
         for (int i = 0; i < N; i++) {
45
             std::cout << container[i] << " | ";
46
47
48
        std::cout << std::endl;
   }
49
50
51
52
   int main() {
53
54
      int N = 5;
      int K = 3;
55
56
      double *values = ( double *) malloc(sizeof( double) * 9);
57
      int *colindices = (int*) malloc(sizeof(int) * 9);
58
59
      int *offsets = (int*) malloc(sizeof(int) * 6);
60
      double *x = ( double *) malloc(sizeof( double) * N);
61
62
      double *X = (double*) malloc(sizeof(double) * N*K);
63
      double *y = ( double *) malloc(sizeof( double) * N);
64
      double *Y = (double*) malloc(sizeof(double) * N*K);
65
66
67
      values [0] = 2;
      values [1] = 7;
68
69
      values [2] = 4;
70
      values [3] = 1;
71
      values [4] = 9;
      values [5] = 3;
72
      values [6] = 6;
73
      values [7] = 5;
74
75
      values [8] = 8;
76
      colindices[0] = 1;
77
      colindices[1] = 3;
78
      colindices[2] = 4;
79
```

```
80
      colindices[3] = 2;
81
      colindices[4] = 3:
82
      colindices[5] = 0;
      colindices[6] = 2;
83
84
      colindices[7] = 4;
85
      colindices[8] = 1;
86
87
      offsets[0] = 0;
88
      offsets[1] = 3;
      offsets[2] = 5;
89
      offsets[3] = 6;
90
      offsets [4]
                  = 8;
91
      offsets[5] = 9;
92
93
94
      x[0] = 1;
95
      x[1] = 2;
96
      x[2]
           = 3;
97
      x[3]
           = 4;
      x[4] = 5;
98
99
100
      X[0] = 1;
      X[1]
           = 2;
101
      X[2]
102
           = 3;
      X[3]
103
           = 4;
104
      X[4]
           = 5;
105
      X[5]
           = 1;
106
      X[6]
           = 2;
      X[7]
107
           = 3;
108
      X[8]
           = 4;
109
      X[9] = 5;
      X[10] = 1;
110
111
      X[11] = 2;
      X[12] = 3;
112
      X[13] = 4;
113
      X[14] = 1;
114
115
116
      double *cuda_values;
117
      int *cuda_colindices;
118
      int *cuda_offsets;
119
      double *cuda_x:
120
      double *cuda_X:
121
      double *cuda_y;
122
      double *cuda_Y;
123
      cudaMalloc(&cuda_values, sizeof( double) * 9);
124
125
      cudaMalloc(&cuda_colindices, sizeof( int) * 9);
126
      cudaMalloc(&cuda_offsets, sizeof(int) * 6);
127
      cudaMalloc(&cuda_x, sizeof( double) * N);
128
      cudaMalloc(&cuda_X, sizeof( double) * N*K);
      cudaMalloc(&cuda_y, sizeof( double) * N);
129
      cudaMalloc(&cuda_Y, sizeof( double) * N*K);
130
131
132
      cudaMemcpy(cuda_values, values, sizeof( double) * 9, cudaMemcpyHostToDevice);
      cudaMemcpy(cuda_colindices, colindices, sizeof( int) * 9, cudaMemcpyHostToDevice);
133
134
      cudaMemcpy(cuda_offsets, offsets, sizeof( int) * 6, cudaMemcpyHostToDevice);
135
      cudaMemcpy(cuda_x, x, sizeof( double) * N, cudaMemcpyHostToDevice);
      cudaMemcpy(cuda_X, X, sizeof( double) * N*K, cudaMemcpyHostToDevice);
136
```

```
137
138
        sparseVector << <256, 256>>>(N, cuda_offsets,
139
        cuda_colindices , cuda_values , cuda_x , cuda_y );
        cudaMemcpy(y, cuda_y, sizeof(double) * N, cudaMemcpyDeviceToHost);
140
141
142
        sparseDense <<<256, 256>>>(N, K, cuda_offsets,
143
        \verb"cuda-colindices", \verb"cuda-values", \verb"cuda-X", \verb"cuda-Y");
        cudaMemcpy(Y, cuda_Y, sizeof(double) * N*K, cudaMemcpyDeviceToHost);
144
145
146
        std::cout << "x : " << std::endl;
147
        \begin{array}{l} \operatorname{printContainer}\left(x\,,\;N\right);\\ \operatorname{std}::\operatorname{cout}\;<<\;\overset{\scriptscriptstyle *}{\operatorname{Result}}\;:\;\;^{\scriptscriptstyle *}\;<<\;\operatorname{std}::\operatorname{endl}; \end{array}
148
149
        printContainer(y, N);
150
151
152
        std::cout << std::endl;
        std::cout << "X : " << std::endl;
153
        printContainer(X, N*K);
154
        std::cout << "Result : " << std::endl;
155
        printContainer(Y, N*K);
156
157
158
        free(x);
159
        free(X);
        free(y);
160
        free (Y);
161
        free (values);
162
163
        free (colindices);
        free (offsets);
164
165
        cudaFree(cuda_values);
166
        cudaFree(cuda_colindices);
167
168
        cudaFree(cuda_offsets);
169
        cudaFree(cuda_x);
        cudaFree(cuda_X);
170
        cudaFree(cuda_y);
171
        cudaFree(cuda_Y);
172
173
174
        return EXIT_SUCCESS;
175
```