LECTURE 3: PROBABILISTIC LEARNING AND SAMPLING METHODS

COMPUTATIONAL INTELLIGENCE



PROBABILISTIC LEARNING



• $c \in \{0,1\}$ - a random variable (a result of tossing a coin)





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- 1 x = p(c = 0) probability of observing *tail*
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Quick check:

$$p(c = 0|x) = x^{0} (1 - x)^{1-0} = 1 - x$$

$$p(c = 1|x) = x^{1} (1 - x)^{1-1} = x$$





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EXAMPLE:

$$\mathcal{D} = \{0,0,1,1,0,1,1\}$$





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- $p(c|x) = x^c (1-x)^{1-c}$ Bernoulli distribution
- $\mathcal{D} = \{c_1, c_2, ..., c_N\}$ *iid* observations (data)
- The likelihood function:

$$p(\mathcal{D}|x) = \prod_{n=1}^{N} p(c_n|x)$$





The optimization problem:



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Find such $x \in [0,1]$ that minimizes the negative log-likelihood function:

$$\min_{x \in [0,1]} - \log p(\mathcal{D} | x)$$



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1) Why negative? Because: $\max f(x) = \min \{-f(x)\}.$



The optimization problem:

Find such $x \in [0,1]$ that minimizes the negative log-likelihood function:

$$\min_{x \in [0,1]} - \log p(\mathcal{D}|x)$$

Remarks:

- 1) Why negative? Because: $\max f(x) = \min \{-f(x)\}.$
- 2) Why logarithm? Because: $\log \Pi = \sum \log$ and optimum is the same.



$$\log p(\mathcal{D}|x) = \log \prod_{n=1}^{N} p(c_n|x)$$

the log-likelihood



$$\log p(\mathcal{D}|x) = \log \prod_{n=1}^{N} p(c_n|x)$$

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Bernoulli distribution



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the log-likelihood

$$\log \prod = \sum \log$$

Bernoulli distribution

$$\log a^b = b \log a$$
$$\log ab = \log a + \log b$$



$$\frac{\mathrm{d}}{\mathrm{d}x}f(x) = 0 \text{ gives optimum}$$



$$\frac{d}{dx} \sum_{n=1}^{N} (c_n \log x + (1 - c_n) \log(1 - x)) = 0$$

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$$\frac{\mathrm{d}}{\mathrm{d}x}\log x = \frac{1}{x}$$



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$$\sum_{n=1}^{N} c_n - x \sum_{n=1}^{N} c_n - Nx + x \sum_{n=1}^{N} c_n = 0 \implies x = \frac{1}{N} \sum_{n=1}^{N} c_n$$

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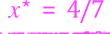
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e.g., Bernoulli, Gaussian...

e.g., iid or sequential

e.g., only values between [0, 1]

e.g., using gradient-descent or analytically or DFM

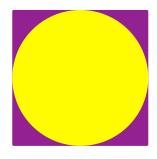


SAMPLING METHODS





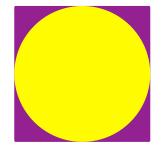
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- We know that the square area is $A_{\square} = (2r)^2$.





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- We know that the square area is $A_{\square} = (2r)^2$.
- The ratio:

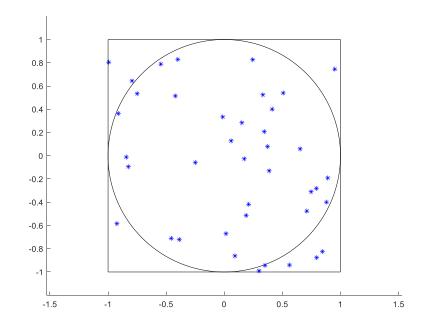
$$\frac{A_{\bigcirc}}{A_{\square}} = \frac{\pi}{4} \Rightarrow \pi = 4 \frac{A_{\bigcirc}}{A_{\square}}$$





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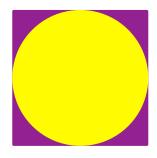


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$$\pi = 4\mathbb{E}_{(x,y)\sim \text{Unif}[-r,r]} \Big[I[x^2 + y^2 \le r^2] \Big]$$





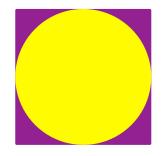
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We can express it as follows:

$$\pi = 4\mathbb{E}_{(x,y) \sim \text{Unif}[-r,r]} \left[I[x^2 + y^2 \le r^2] \right]$$

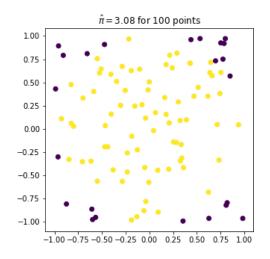
$$\approx 4\frac{1}{N} \sum_{n=1}^{N} I[x_n^2 + y_n^2 \le r^2]$$

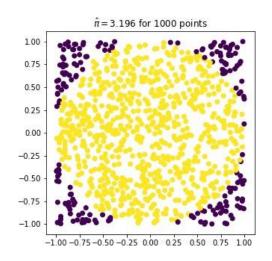


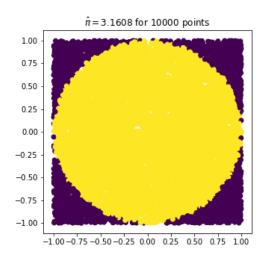
Approximate it by sampling!



HOW TO ESTIMATE π ?









• History: **Stanisław Ulam** played solitaire and asked himself what are the chances that a particular laid out with 52 cards is successful.

Stanisław Ulam (1909-1984) was a Polish mathematician, a participant of the Manhattan project, known for applications of mathematics to physics, biology and computer science, and first formulations of Monte Carlo methods and cellular automata (with John von Neumann).



- History: **Stanisław Ulam** played solitaire and asked himself what are the chances that a particular laid out with 52 cards is successful.
- The underlying idea: Approximate by sampling!

$$\frac{1}{N} \sum_{n} f(x_n) \xrightarrow{n \to \infty} \int f(x) p(x) dx$$



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- General applications:
 - **A.** Analytically infeasible quantities (e.g., normalization constants, statistical inference, expectations of some function of interest).
 - **B.** Optimization.



• Problem with sampling (*curse of dimensionality*):



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Now, we do the same but in 2D $\rightarrow 10^4$ points.



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A grid on a unit interval (dist. adjacent points = 0.01) \rightarrow 10² points.

Now, we do the same but in 2D $\rightarrow 10^4$ points.

And in 10D \rightarrow 10²⁰ points.

• Even for 10 dimensions the number of possible states is infeasible...



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A grid on a unit interval (dist. adjacent points = 0.01) $\rightarrow 10^2$ points.

Now, we do the same but in 2D $\rightarrow 10^4$ points.

And in 10D \rightarrow 10²⁰ points.

- Even for 10 dimensions the number of possible states is infeasible...
- A natural question is:

Can we do better than independent sampling?



• Idea: Make a new sample dependent on the past (Markov chain).



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- In other words, we introduce a proposal distribution $q(x_t|x_{t-1})$ to obtain a chain that corresponds to a sample from the original distribution p(x).
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- In other words, we introduce a proposal distribution $q(x_t|x_{t-1})$ to obtain a chain that corresponds to a sample from the original distribution p(x).
- Could any distribution be used as a proposal distribution? NO.
- Conditions on the proposal distribution:
 - A. (Irreducibility) There is a positive probability of visiting all states.
 - B. (Aperiodicity) The chain should not get trapped in cycles.



- 1. Initialize $x_t := x_0$.
- 2. For $t \in \{0,1,...,T-1\}$:
 - (i) (Generate) Sample $x' \sim q(x|x_t)$.
 - (ii) (Evaluate) Calculate acceptance probability:

$$A(x', x_t) = \min \left\{ 1, \frac{p(x') \ q(x_t | x')}{p(x_t) \ q(x' | x_t)} \right\}$$

If
$$A(x', x_t) > u$$
, then $x_{t+1} := x'$.

Else
$$x_{t+1} := x_t$$
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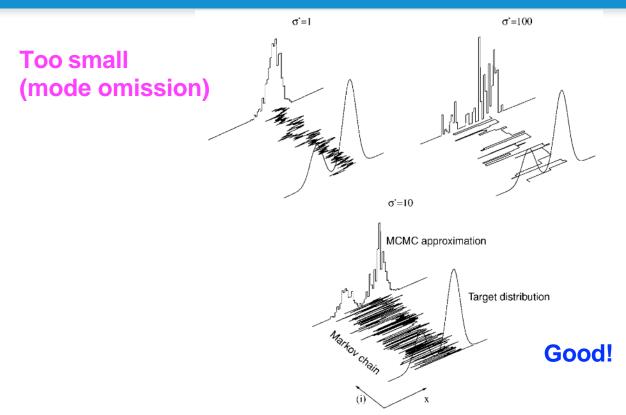
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Else
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.

$$p(x) \propto \exp(-f(x))$$





Too large (low acceptance)



INDEPENDENT SAMPLER

- 1. Initialize $x_t := x_0$.
- 2. For $t \in \{0,1,...,T-1\}$:
 - (i) (Generate) Sample $x' \sim q(x)$.
 - (ii) (Evaluate) Calculate acceptance probability:

$$A(x', x_t) = \min \left\{ 1, \frac{p(x') \ q(x_t)}{p(x_t) \ q(x')} \right\}$$

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METROPOLIS ALGORITHM

- 1. Initialize $x_t := x_0$.
- 2. For $t \in \{0,1,...,T-1\}$:
 - (i) (Generate) Sample $x' \sim q(x|x_t)$, where $q(x'|x_t) = q(x_t|x')$.
 - (ii) (Evaluate) Calculate acceptance probability:

$$A(x', x_t) = \min\left\{1, \frac{p(x')}{p(x_t)}\right\}$$

If
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SIMULATED ANNEALING

- 1. Initialize $x_t := x_0$ and $T_t := T_0$.
- 2. For $t \in \{0,1,...,T-1\}$:
 - (i) (Generate) Sample $x' \sim q(x|x_t)$.
 - (ii) (Evaluate) Calculate acceptance probability:

$$A(x', x_t) = \min \left\{ 1, \frac{p^{\frac{1}{T_t}}(x') \ q(x_t | x')}{p^{\frac{1}{T_t}}(x_t) \ q(x' | x_t)} \right\}$$

(iii) (Select) Sample $u \sim \text{Unif}[0,1]$.

If
$$A(x', x_t) > u$$
, then $x_{t+1} := x'$.

Else
$$x_{t+1} := x_t$$
.

(iv) Set T_{t+1} according to chosen cooling schedule.



SIMULATED ANNEALING

- 1. Initialize $x_t := x_0$ and $T_t := T_0$.
- 2. For $t \in \{0,1,...,T-1\}$:
 - (i) (Generate) Sample $x' \sim q(x|x_t)$.
 - (ii) (Evaluate) Calculate acceptance probability:

If
$$p(x) \propto \exp(-f(x))$$
,
then $p^{\frac{1}{T}}(x) \propto \exp(-\frac{1}{T}f(x))$.

(iii) (Select) Sample
$$u \sim \text{Unif}[0,1]$$
.

If $A(x', x_t) = \min \left\{ 1, \frac{p^{\frac{1}{T_t}}(x') \ q(x_t|x')}{p^{\frac{1}{T_t}}(x_t) \ q(x'|x_t)} \right\}$

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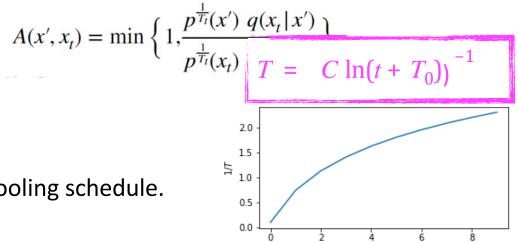


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If $A(x', x_t) > u$, then $x_{t+1} := x'$.
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OPTIMIZATION THROUGH SAMPLING

- We are interested in minimizing f(x).
- Alternatively, we can consider a distribution of the form

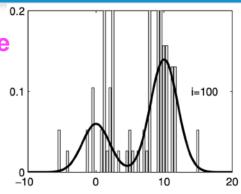
$$p(x) \propto \exp(-f(x)/T)$$

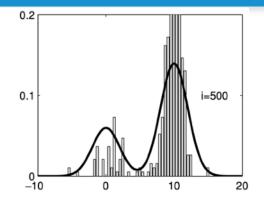
- By changing the temperature, we can consider almost uniform distribution (high temperature) or peaky distribution (low temperature).
- For uniform distribution we have **exploration**, while for more peaky distribution we have **exploitation**.

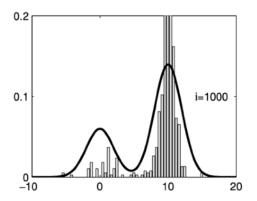


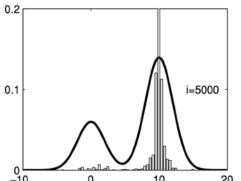
EXAMPLE (SIMULATED ANNEALING)

High temperature









Low temperature



METROPOLIS-HASTINGS ALG. VS LOCAL SEARCH

Stochastic search

- 1. Initialize $x_t := x_0$.
- 2. For $t \in \{0,1,...,T-1\}$:
 - (i) (Generate) Sample $x' \sim q(x|x_t)$.
 - (ii)(Evaluate) Calculate acceptance probability:

$$A(x', x_t) = \min \left\{ 1, \frac{p(x') \ q(x_t | x')}{p(x_t) \ q(x' | x_t)} \right\}$$

(iii) (Select) Sample $u \sim \text{Unif}[0,1]$. If $A(x', x_t) > u$, then $x_{t+1} := x'$. Else $x_{t+1} := x_t$.

Deterministic search

- 1. Initialize a solution.
- 2. For $t \in \{0,1,...,T-1\}$:
 - (i)(Generate) Generate solutions in the neighborhood of the current best solution.
 - (ii)(Evaluate) Evaluate the potential solutions.
 - (iii)(Select) Pick the solution with best objective as the best current solution.



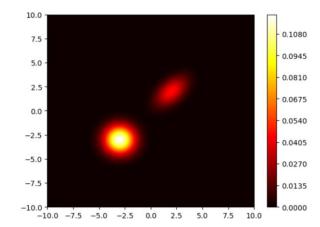
ASSIGNMENT 2: Sampling

The goal is to implement Metropolis-Hastings (MH) and Simulated Annealing (SA) algorithms and analyze their behavior.

Here, we are interested in sampling from a mixture of two Gaussians, namely:

$$\text{Target distribution:} \quad p(\mathbf{x}) = 0.25 \cdot \mathcal{N} \left(\mu = \begin{bmatrix} 2 \\ 2 \end{bmatrix}, \\ \Sigma = \begin{bmatrix} 1 & 0.5 \\ 0.5 & 1 \end{bmatrix} \right) + 0.75 \cdot \mathcal{N} \left(\mu = \begin{bmatrix} -3 \\ -3 \end{bmatrix}, \\ \Sigma = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \right)$$

Visualization:





Thank you!



EXTRA READING

Andrieu et al., "An Introduction to MCMC for Machine Learning", Machine Learning, Vol. 50, pp. 5-43, 2003

Ch. Bishop, "Pattern Recognition and Machine Learning", Springer

K. Murphy, "Machine Learning: A Probabilistic Perspective", The MIT Press

