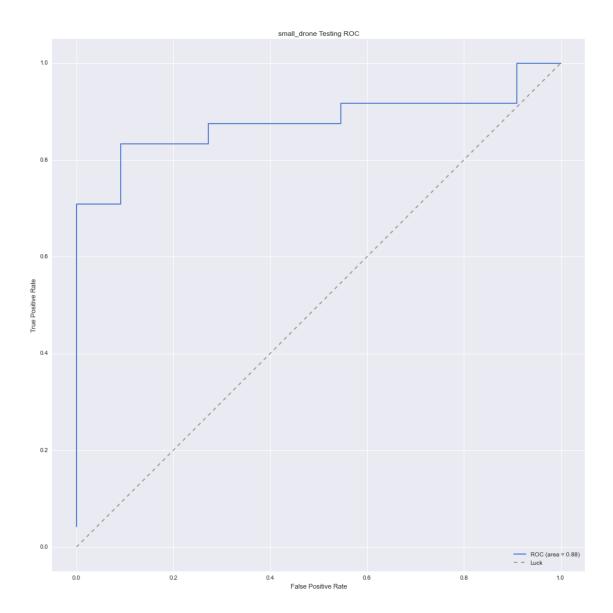
bnn_mvp_model_test_evaluation

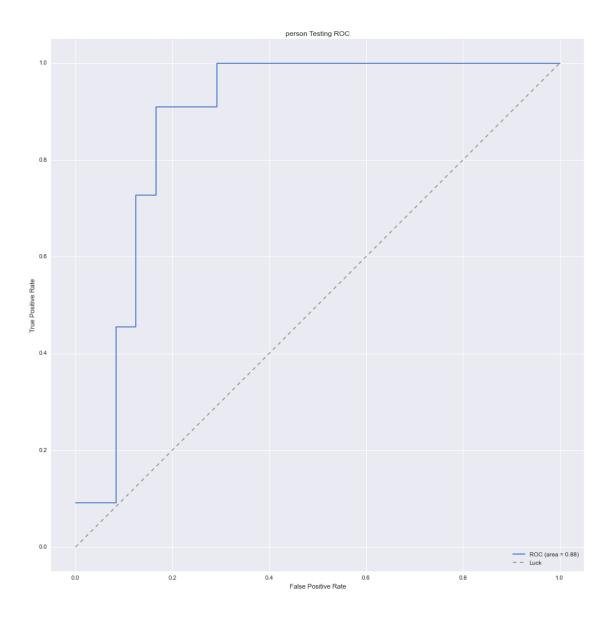
August 21, 2015

```
In [3]: """
        The intent of this notebook is model selection and
        evaluation for the MVP of our brainNN classifier.
        import sys
        import json
        import matplotlib
        import numpy as np
        import matplotlib.pyplot as plt
        import pandas as pd
        from tornado import gen
        from tornado.ioloop import IOLoop
        import aimetrics as aim
        import aimetrics.metrics as aim_metrics
        import seaborn as sns
        from sklearn.metrics import roc_curve, auc
        %matplotlib inline
In [4]: optimal_model_key = '1x4x0.7'
        optimal_layers = 1
        optimal_cols = 4
        optimal_rate = 0.7
        X_trn_val = pd.read_csv('output/bnn-mvp/X_trn_val.csv', index_col=0)
        y_trn_val = pd.read_csv('output/bnn-mvp/y_trn_val.csv', index_col=0)
        X_test = pd.read_csv('output/bnn-mvp/X_test.csv', index_col=0)
        y_test = pd.read_csv('output/bnn-mvp/y_test.csv', index_col=0)
        with open('output/bnn-mvp/test_metrics.json', 'r') as f:
            test_metrics = json.load(f)
        labels = ['small_drone', 'person']
        # create data storage variable
In [17]: from scipy import interp
         sns.set()
         sns.set_palette(sns.color_palette('muted'))
         def plot_roc(label, figsize=(16,16), metrics=test_metrics):
             # This is taken from a skl example:
             # http://scikit-learn.org/stable/auto_examples/model_selection/plot_roc_crossval.html
             mean\_tpr = 0.0
             mean_fpr = np.linspace(0, 1, 100)
             all_tpr = []
             f = plt.figure(figsize=figsize)
             if isinstance(metrics, list):
                 for i, fold in enumerate(metrics):
```

```
fold = fold['roc'][label]
                     fpr, tpr, thresholds = fold['fpr'], fold['tpr'], fold['threshold']
                     mean_tpr += interp(mean_fpr, fpr, tpr)
                     mean\_tpr[0] = 0.0
                     roc_auc = auc(fpr, tpr)
                     plt.plot(fpr, tpr, lw=1, label='ROC fold %d (area = %0.2f)' % (i, roc_auc))
                 mean_tpr /= len(model_metrics)
                 mean\_tpr[-1] = 1.0
                 mean_auc = auc(mean_fpr, mean_tpr)
                 plt.plot(mean_fpr, mean_tpr, 'k--',
                          label='Mean ROC (area = %0.2f)' % mean_auc, lw=2)
             else:
                 fold = metrics['roc'][label]
                 fpr, tpr, thresholds = fold['fpr'], fold['tpr'], fold['threshold']
                 roc_auc = auc(fpr, tpr)
                 plt.plot(fold['fpr'], fold['tpr'], label='ROC (area = %0.2f)' % roc_auc)
             plt.plot([0, 1], [0, 1], '--', color=(0.6, 0.6, 0.6), label='Luck')
            plt.xlim([-0.05, 1.05])
            plt.ylim([-0.05, 1.05])
             plt.xlabel('False Positive Rate')
             plt.ylabel('True Positive Rate')
             plt.title('%s Testing ROC' % label)
             plt.legend(loc="lower right")
            plt.show()
In [18]: plot_roc('small_drone', metrics=test_metrics)
```



In [19]: plot_roc('person', metrics=test_metrics)



In []: