

Approximate Minimum-Weight Partial Matching under Translation

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Wolfgang Mulzer³ Günter Rote³ Micha Sharir² Allen Xiao¹

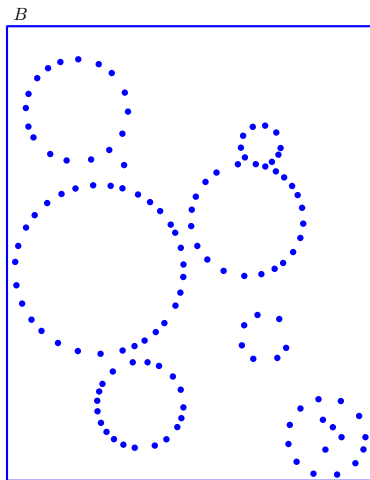
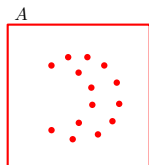
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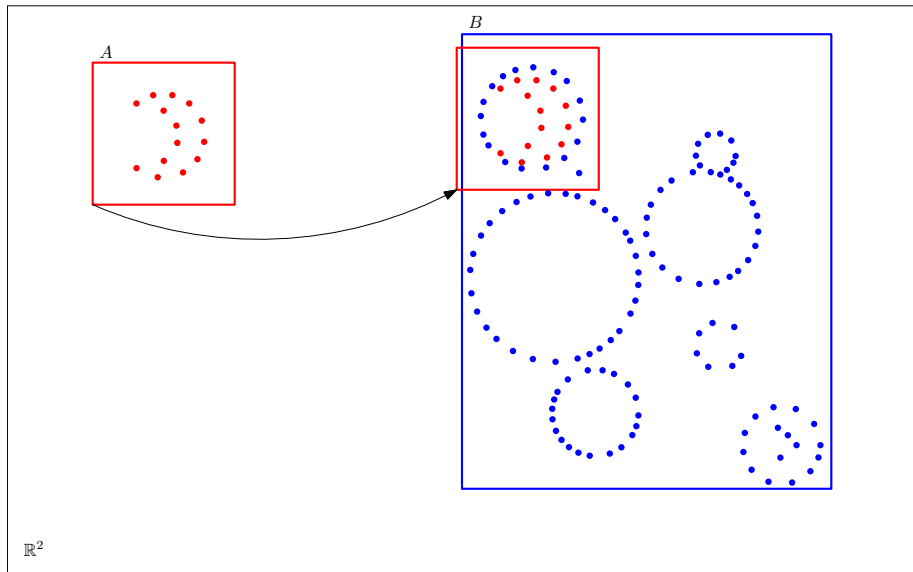
December 2018

Example

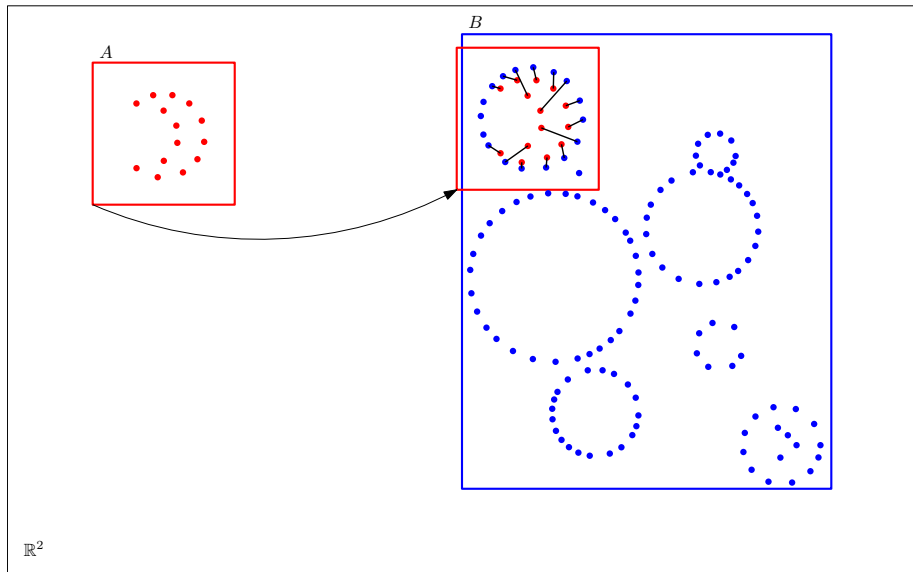


\mathbb{R}^2

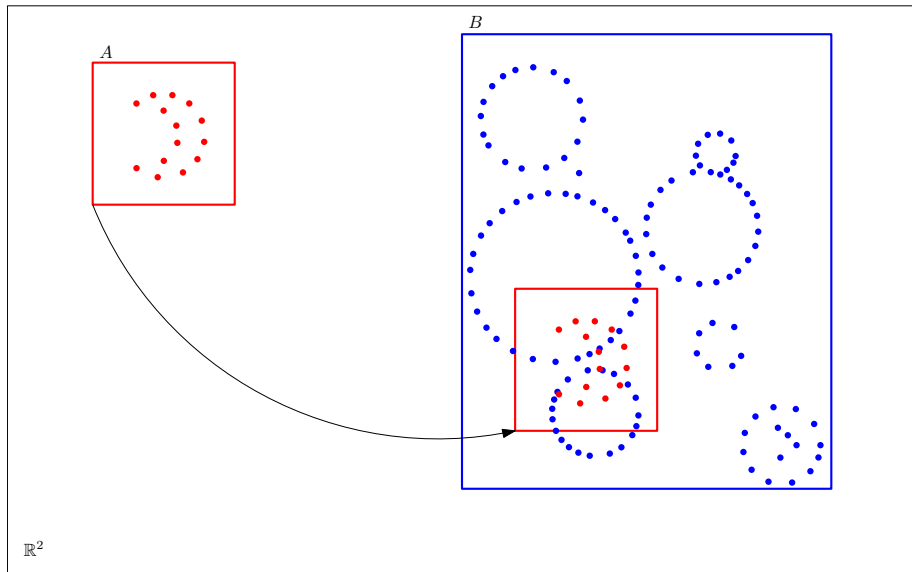
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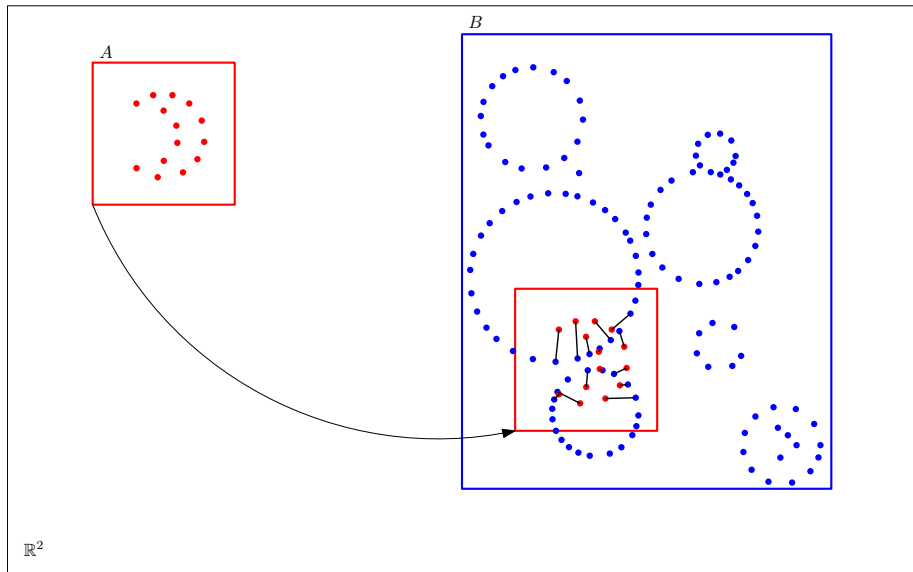
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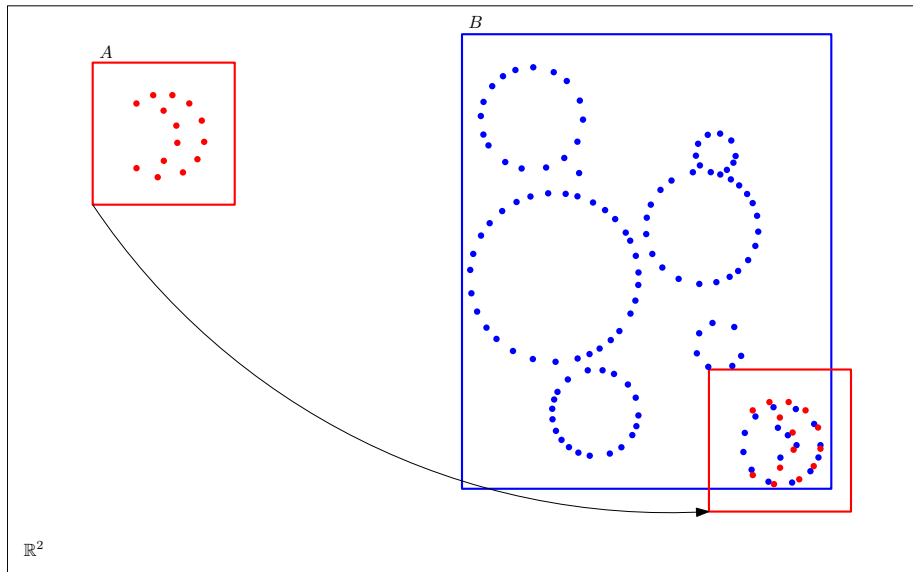
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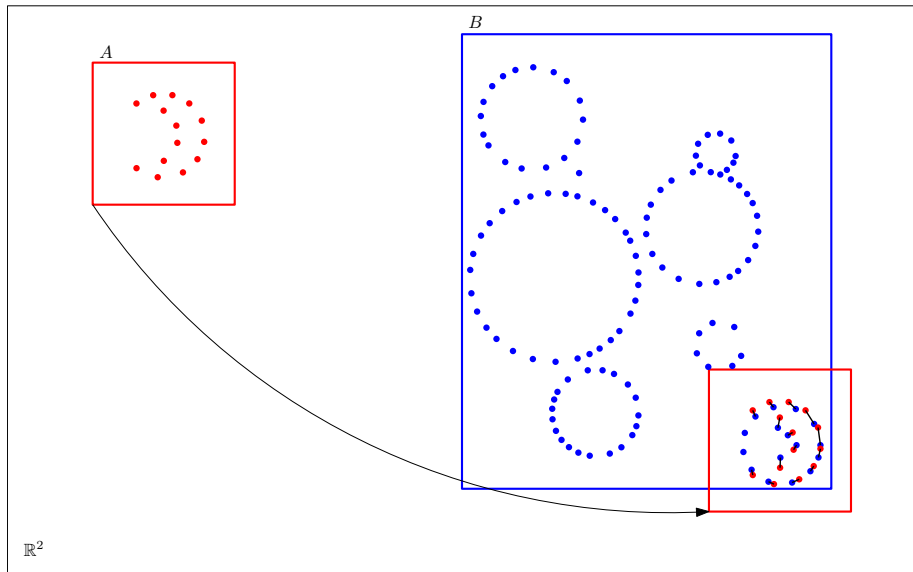
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Cost function

- ▶ For k -matching M and translation t , define the L_p -cost:

$$\text{cost}(M, t) := \left[\frac{1}{k} \sum_{(a,b) \in M} \|a + t - b\|^p \right]^{1/p}$$

- ▶ $p = 2$: root-mean-squared cost
- ▶ For fixed t , minimum M computable in $\text{poly}(k, m, n)$ time, e.g. by Hungarian algorithm.

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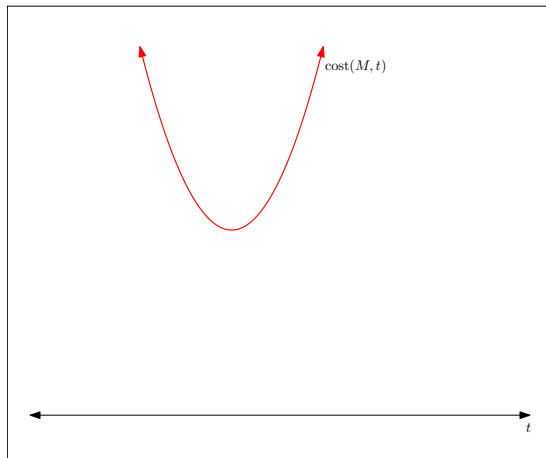
Minimization diagram \mathcal{M}

$$\text{cost}^*(t) := \min_{k\text{-matching } M} \text{cost}(M, t)$$



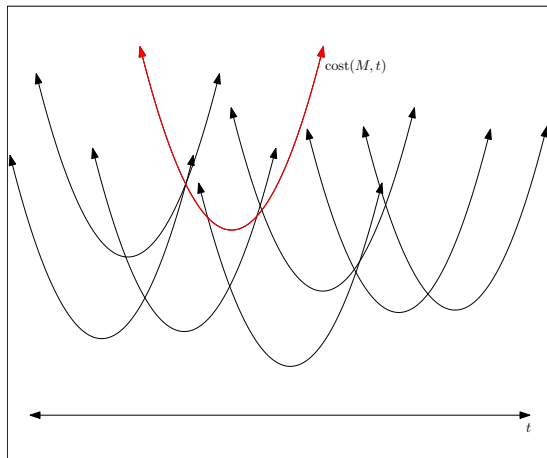
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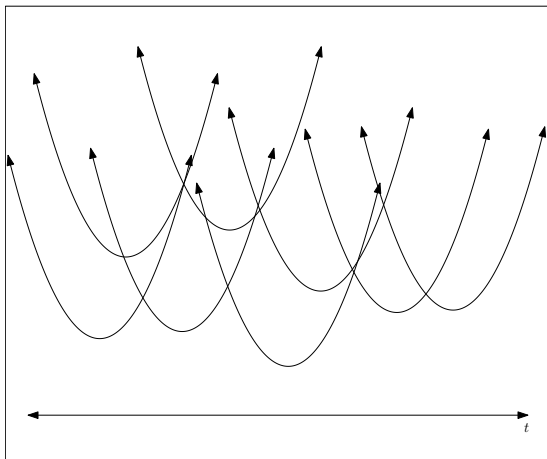
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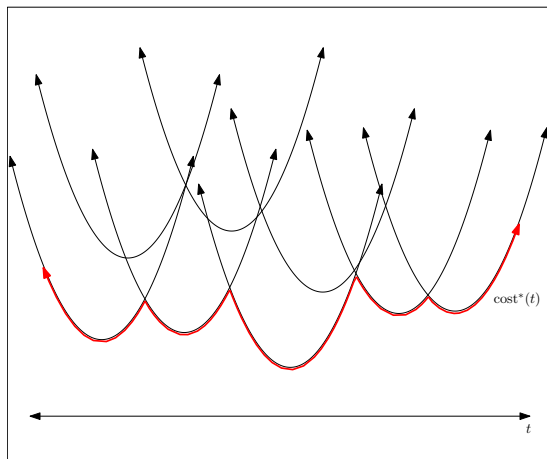
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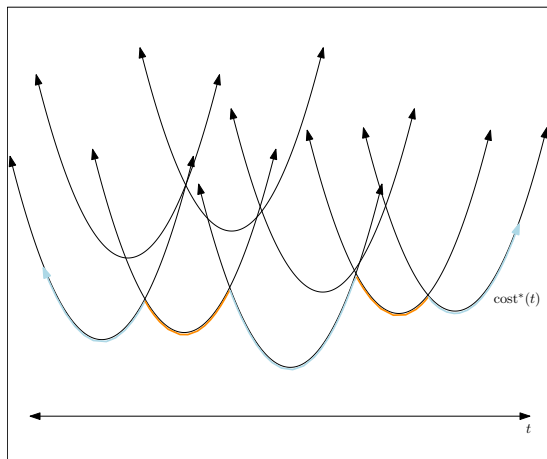
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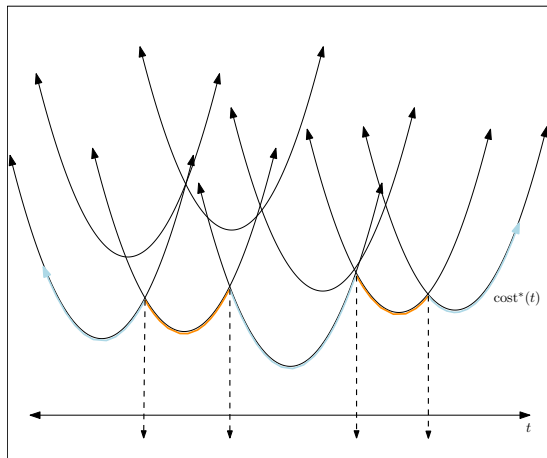
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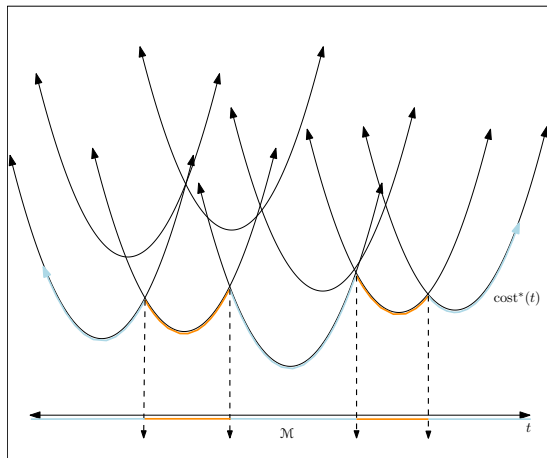
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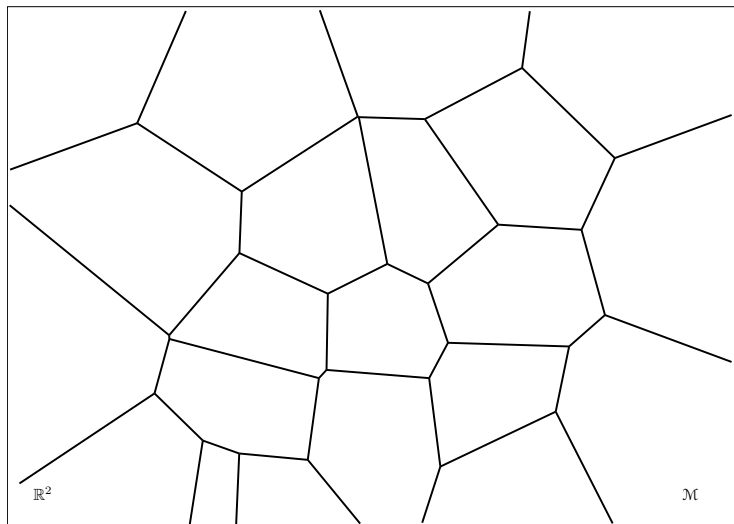
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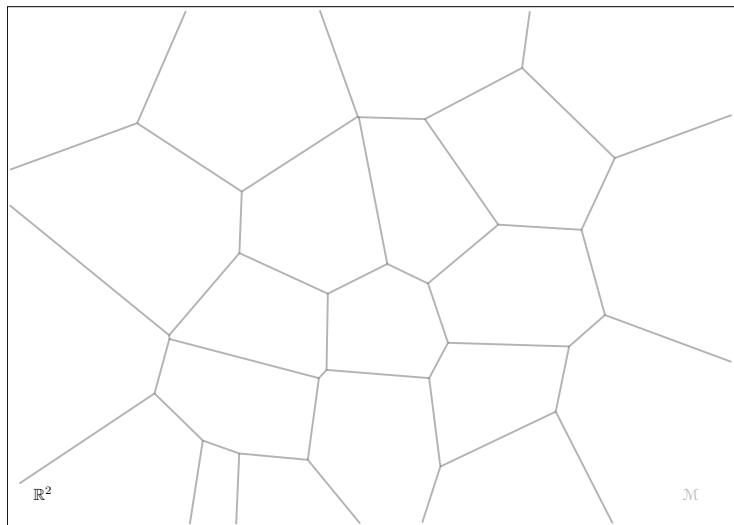


1. What is the *combinatorial complexity of \mathcal{M}* ? Is it polynomial?
 - ▶ [Rote 10]: for $p = 2$ and $k = m$,
a line crosses at most $m(n - m) + 1$ cells
 - ▶ [Ben-Avraham *et al.* 14]: for $p = 2$ and $k = m$,
 $O(n^2 m^{3.5} (e \ln m + e)^m)$
2. How quickly can we *compute t^** , a global minimum of $\text{cost}^*(t)$?
 - ▶ Explore \mathcal{M} , use static algorithm within cells.

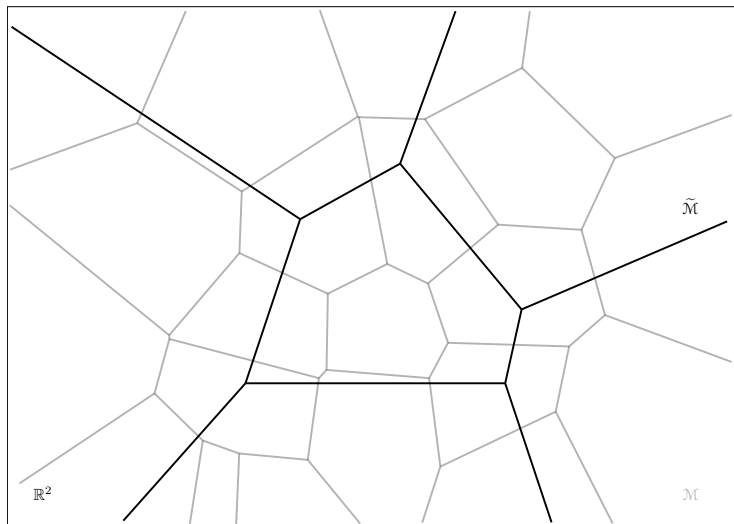
Approximating \mathcal{M}



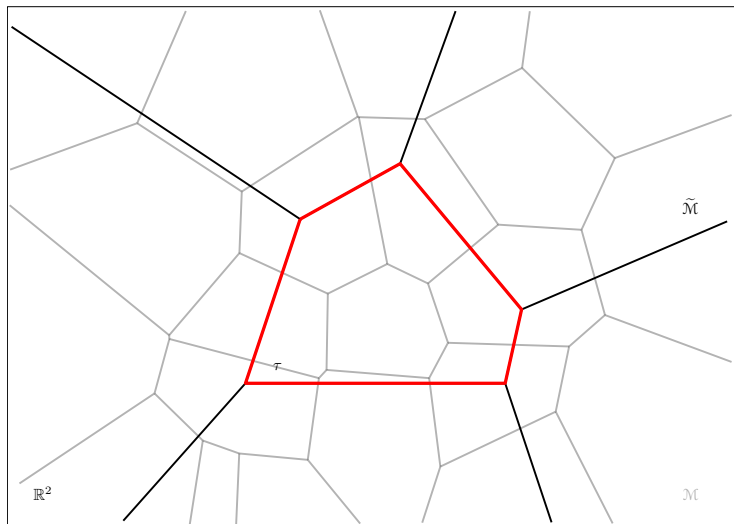
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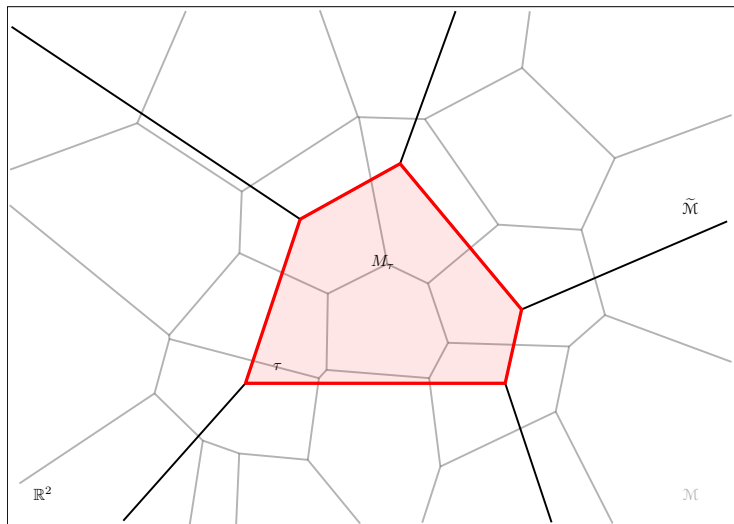
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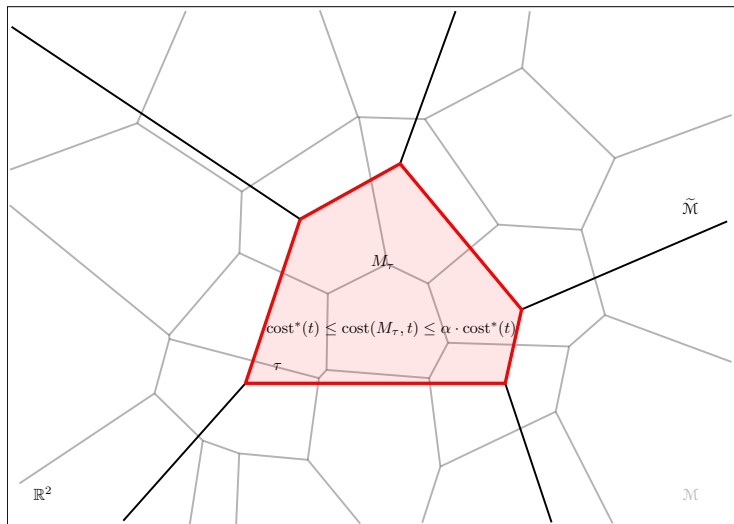
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Approximating \mathcal{M}



Our results (approximation helps)

1. What is the *combinatorial complexity of \mathcal{M}* ? Is it polynomial?

Theorem

*In $\text{poly}(k, m, n, \varepsilon^{-1})$ time, can construct a $(1 + \varepsilon)$ *approximate diagram* $\tilde{\mathcal{M}}$ of complexity $O((mn/k)\varepsilon^{-2} \log \varepsilon^{-1})$.*

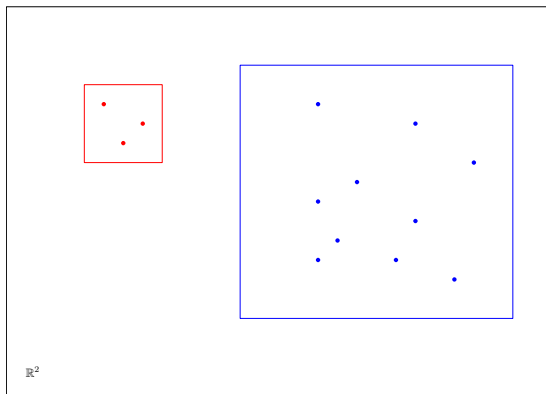
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Theorem

*In $\text{poly}(k, m, n, \varepsilon^{-1})$ time, can compute a $(1 + \varepsilon)$ *approximation to $\text{cost}^*(t^*)$* by exploring the cells of $\tilde{\mathcal{M}}$.*

Point-to-point translations [Cabello *et al.* 08]

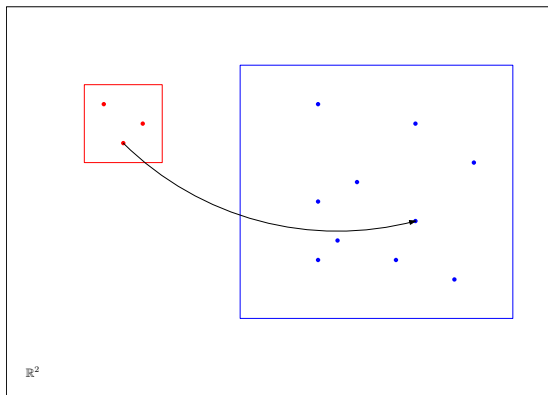
- *Point-to-point translations*: $T := \{t_{ba} = (b - a) \mid a \in A, b \in B\}$



- Claim: Let $\tilde{\mathcal{M}}$ be $\text{Vor}(T)$, with each $\text{VorRegion}(t_{ba})$ assigned the optimal k -matching at t_{ba} . Then, $\tilde{\mathcal{M}}$ is a $O(1)$ -approximate diagram.

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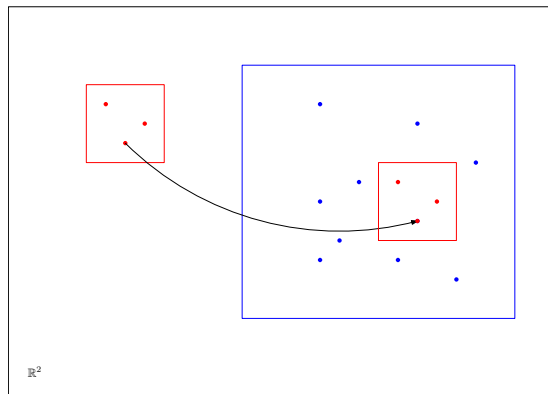
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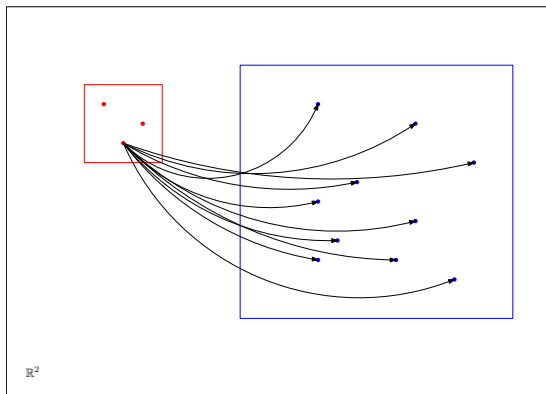
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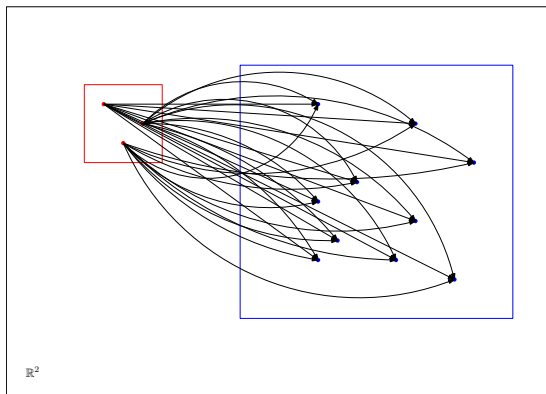
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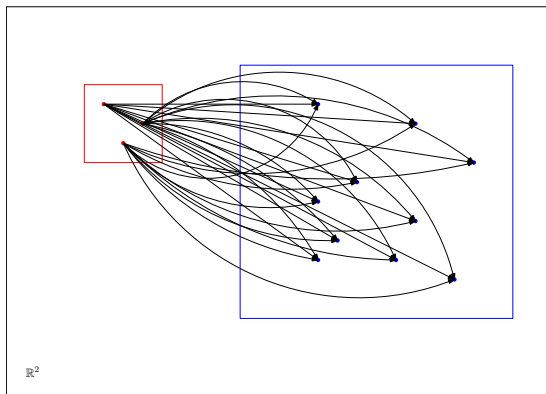
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Lipschitz continuity for L_p -cost

$$\text{cost}(M, t) := \left[\frac{1}{k} \sum_{(a,b) \in M} \|a + t - b\|^p \right]^{1/p}$$

Lemma (Lipschitz condition)

Given $t, \Delta \in \mathbb{R}^2$, let M_t be the optimal k -matching at t .
Then $\text{cost}(M_t, t + \Delta) \leq \text{cost}^*(t) + \|\Delta\|$.

Proof of approximation for T

- ▶ Claim: \tilde{M} is an $O(1)$ -approximate diagram.
- ▶ Given $t \in \mathbb{R}^2$, let t_0 be its nearest neighbor in T , and M_{t_0} the optimal matching at t_0 .

$$\begin{aligned}\text{cost}^*(t) &= \min_{k\text{-matching } M} \left[\frac{1}{k} \sum_{(a,b) \in M} \|a + t - b\|^p \right]^{1/p} \\ &= \min_{k\text{-matching } M} \left[\frac{1}{k} \sum_{(a,b) \in M} \|t - t_{ba}\|^p \right]^{1/p} \\ &\geq \min_{k\text{-matching } M} \left[\frac{1}{k} \sum_{(a,b) \in M} \|t - t_0\|^p \right]^{1/p} \\ &= \|t - t_0\|\end{aligned}$$

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- ▶ $\|t - t_0\| \leq \text{cost}^*(t)$

$$\begin{aligned}\text{cost}(M_{t_0}, t) &\leq \text{cost}^*(t_0) + \|t - t_0\| && \text{(Lipschitz cond.)} \\ &\leq \text{cost}^*(t) + 2\|t - t_0\| && \text{(Lipschitz cond.)} \\ &\leq \text{cost}^*(t) + 2 \text{cost}^*(t) \\ &= 3 \text{cost}^*(t)\end{aligned}$$

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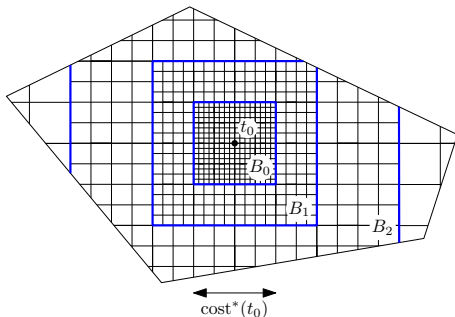
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$O(1) \rightarrow (1 + \varepsilon)$ approximation

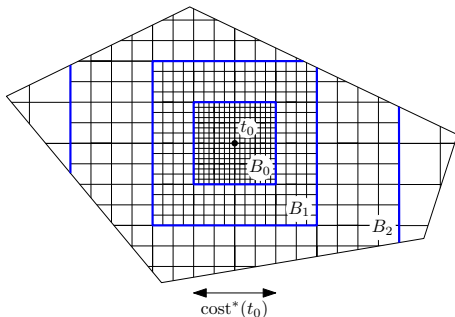


- $(1 + \varepsilon)$ approximate diagram of size $O(|T|\varepsilon^{-2} \log \varepsilon^{-1}) = O((mn)\varepsilon^{-2} \log \varepsilon^{-1})$

Theorem

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$O(1) \rightarrow (1 + \varepsilon)$ approximation



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Theorem

In $\text{poly}(k, m, n, \varepsilon^{-1})$ time, can construct a $(1 + \varepsilon)$ approximate diagram $\tilde{\mathcal{M}}$ of complexity $O((mn/k)\varepsilon^{-2} \log \varepsilon^{-1})$.

- ▶ Reduce size from $O(mn) \rightarrow O(mn/k)$.
- ▶ Any $O(1)$ approx. diagram is enough for the $(1 + \varepsilon)$ diagram.
- ▶ *Cluster the points of T* ... while keeping cluster radius small w.r.t. $\text{cost}^*(t)$.

Averaging argument

$$\text{cost}^*(t) := \min_{k\text{-matching } M} \left[\frac{1}{k} \sum_{(a,b) \in M} \|a + t - b\|^p \right]^{1/p}$$

- ▶ At most $k/2$ pairs $(a, b) \in M_t$ have $\|a + t - b\| \geq 2^{1/p} \text{cost}^*(t)$.
- ▶ At most $k/2$ pairs $(a, b) \in M_t$ have $\|t - t_{ab}\| \geq 2^{1/p} \text{cost}^*(t)$.
- ▶ **At least** $k/2$ pairs $(a, b) \in M_t$ have $\|t - t_{ab}\| \leq 2^{1/p} \text{cost}^*(t)$.

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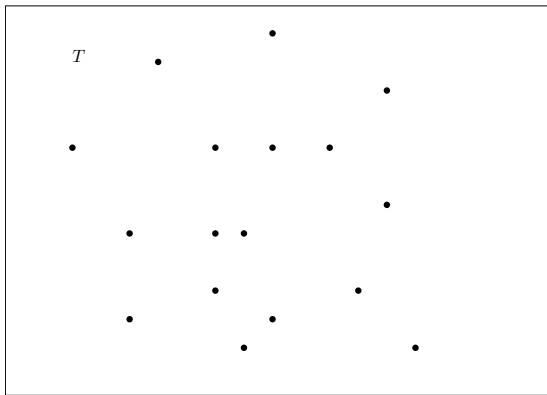
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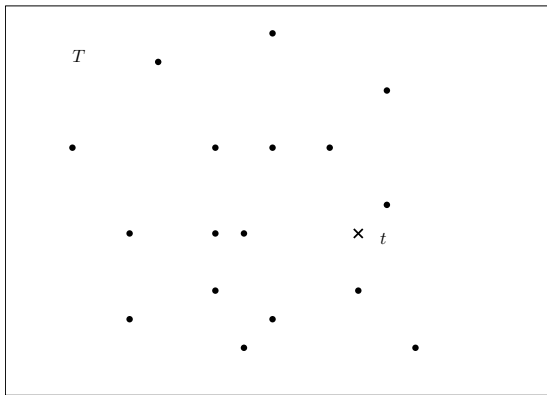
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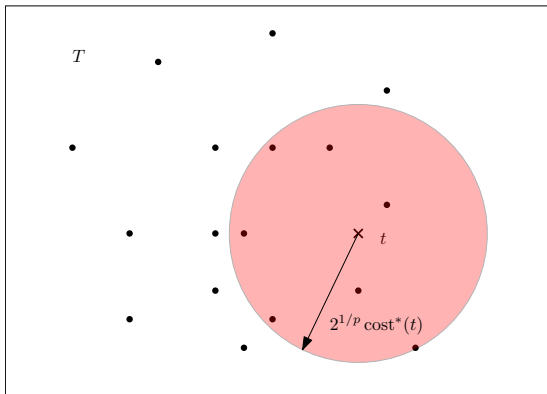
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Clustering T greedily

1. Let $D_i = B(x_i, r_i)$ be the smallest disk containing at least $k/2$ remaining points of T .
 2. Remove from T the points covered by D_i .
 3. Repeat.
- ▶ *Quorum clustering*
2-approx. algorithm in $O(|T| \text{polylog } n)$ time [Carmi et al. 05]
- ▶ $O(|T|/k) = O(mn/k)$ clusters.

Clustering T greedily

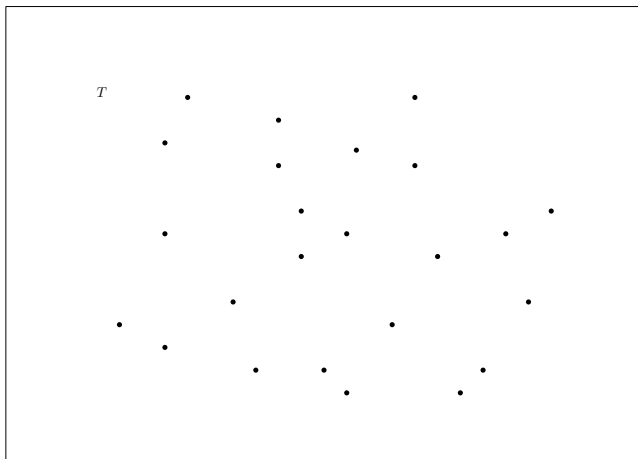
1. Let $D_i = B(x_i, r_i)$ be the smallest disk containing at least $k/2$ remaining points of T .
 2. Remove from T the points covered by D_i .
 3. Repeat.
- ▶ *Quorum clustering*
2-approx. algorithm in $O(|T| \text{polylog } n)$ time [Carmi et al. 05]
- ▶ $O(|T|/k) = O(mn/k)$ clusters.

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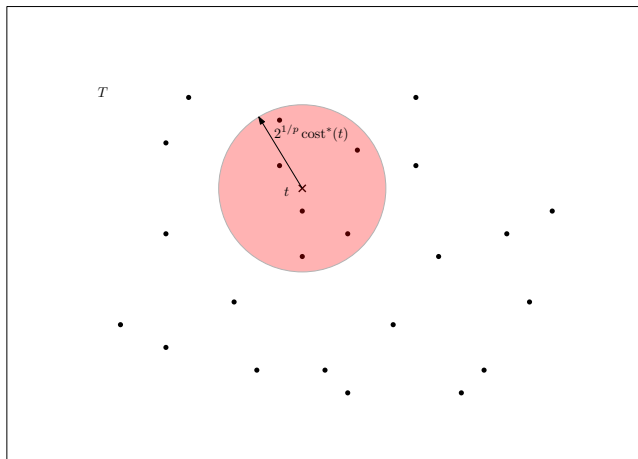
Greedy clustering proof of approximation

- ▶ Let X be the set of centers x_i from the greedy clustering, and $\tilde{\mathcal{M}} = \text{Vor}(X)$ with each $\text{VorRegion}(x_i)$ assigned M_{x_i} .



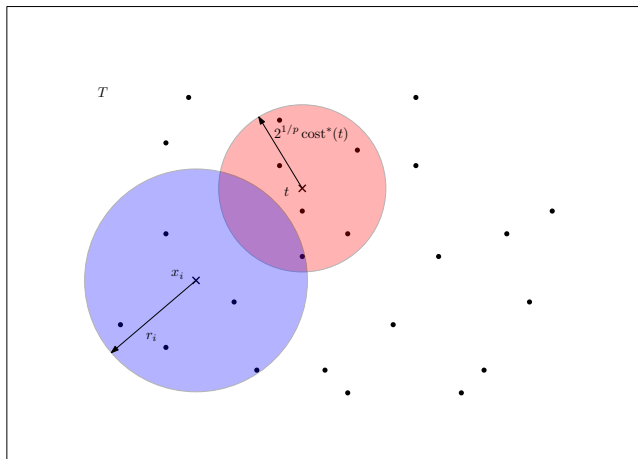
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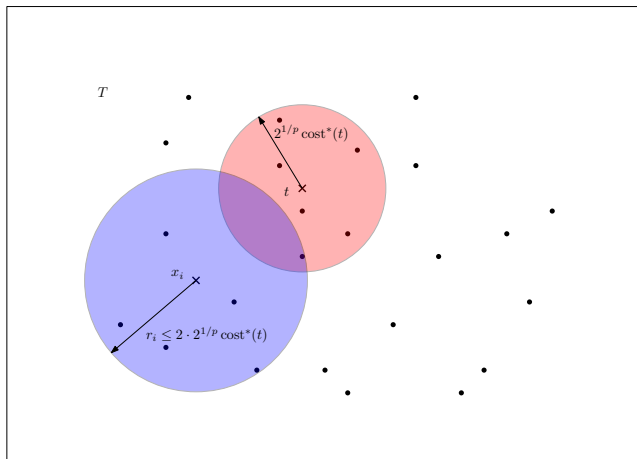
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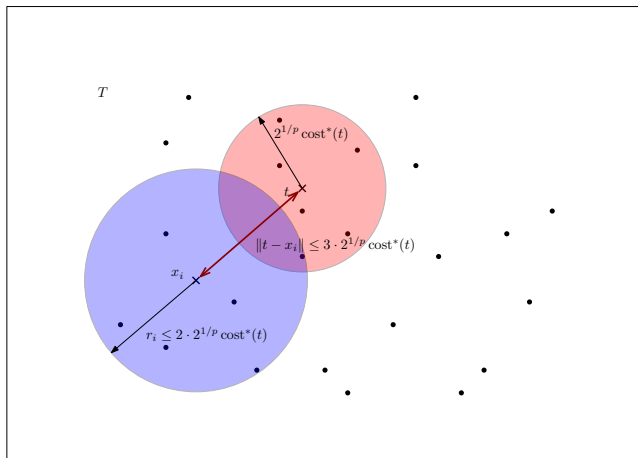
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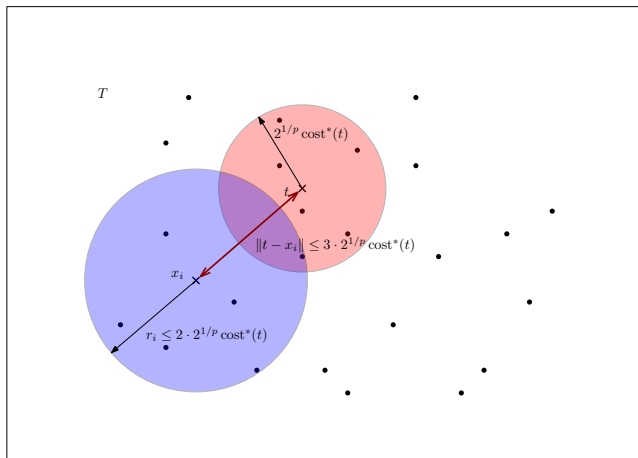


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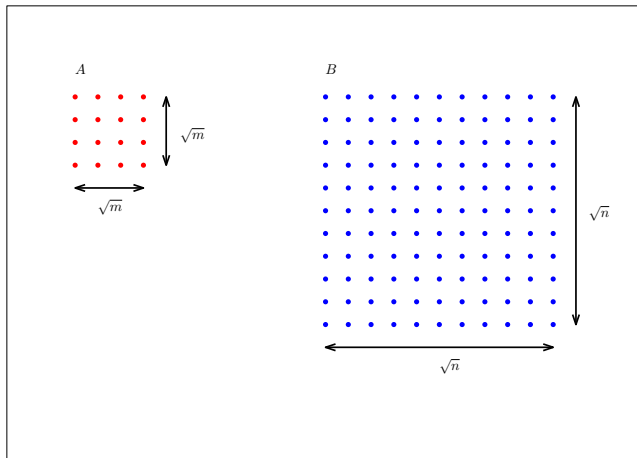
Greedy clustering proof of approximation



- ▶ $\text{cost}(M_{x_i}, t) \leq (1 + 6 \cdot 2^{1/p}) \text{cost}^*(t)$
- ▶ Using grids, $(1 + \varepsilon)$ approx. diagram of size $O((mn/k)\varepsilon^{-2} \log \varepsilon^{-1})$.

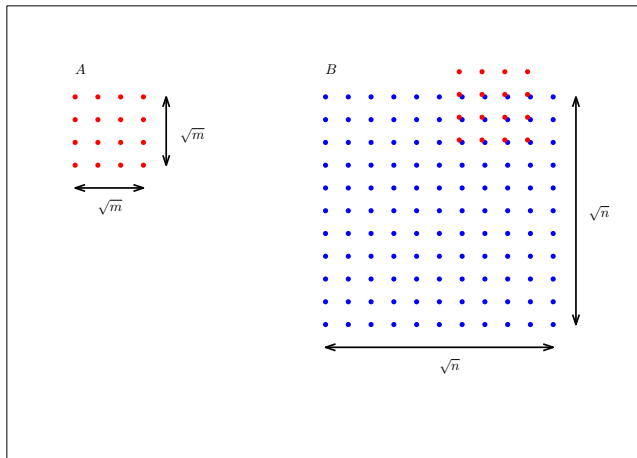
Lower bound: $O(mn/k)$ tight for large k

- For $k = c \cdot \min(m, n)$, constant c :



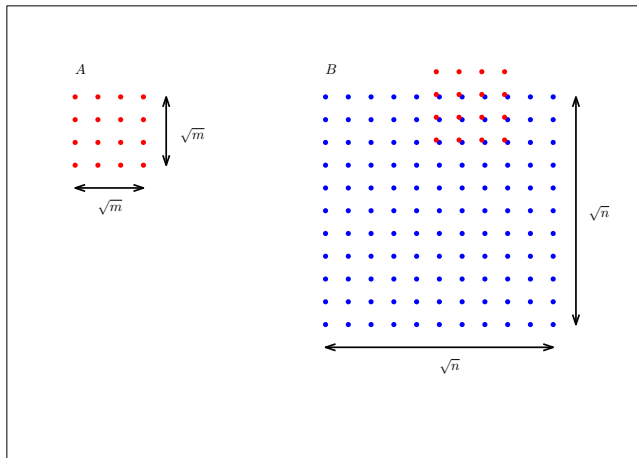
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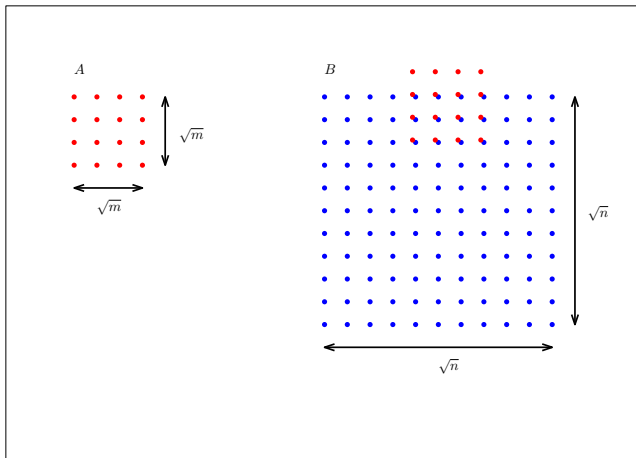
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Open questions

1. Is the complexity of \mathcal{M} polynomial, for any p ?
2. Approximate diagrams for rotations? Rigid transforms?

The End

Thank you.