# Approximate Minimum-Weight Partial Matching under Translation

Pankaj Agarwal  $^1$  Haim Kaplan  $^2$  Geva Kipper  $^2$  Wolfgang Mulzer  $^3$  Günter Rote  $^3$  Micha Sharir  $^2$  Allen Xiao  $^1$ 

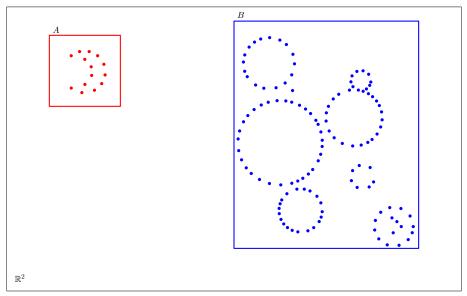
<sup>1</sup>Duke University

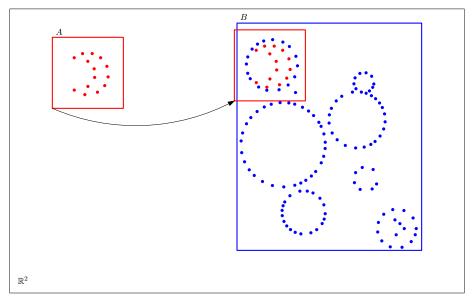
<sup>2</sup>Tel Aviv University

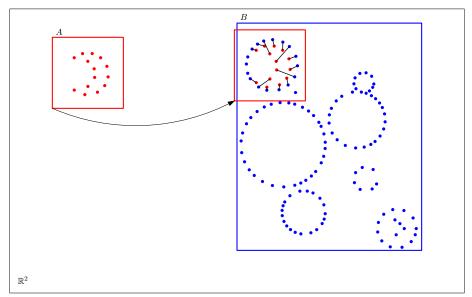
<sup>3</sup>Freie Universität Berlin

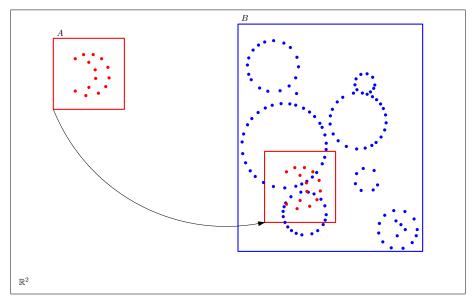
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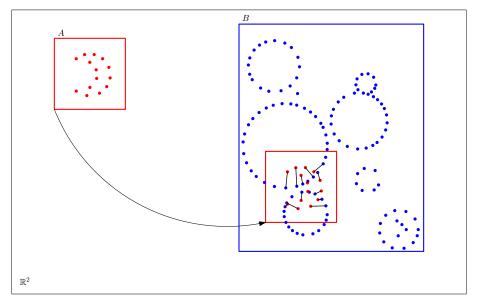


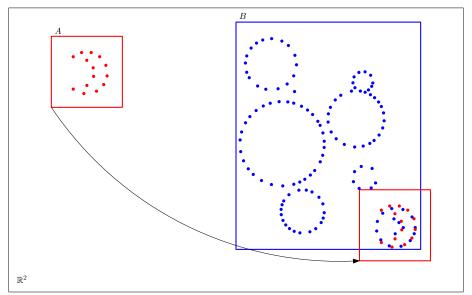


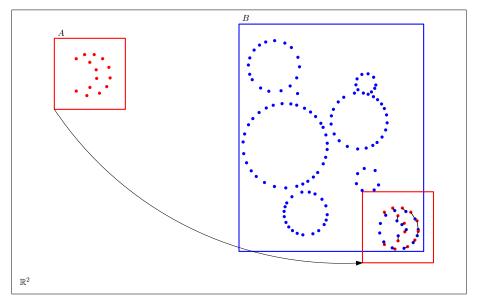












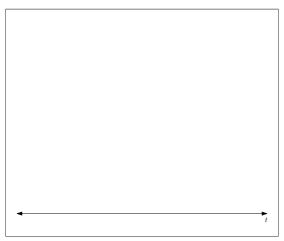
#### Cost function

▶ For k-matching M and translation t, define the  $L_p$ -cost:

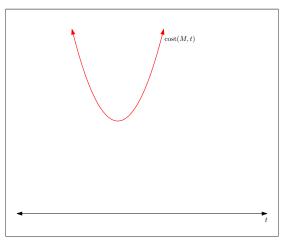
$$cost(M, t) := \left[ \frac{1}{k} \sum_{(a,b) \in M} ||a + t - b||^p \right]^{1/p}$$

- ightharpoonup p = 2: root-mean-squared cost
- For fixed t, minimum M computable in  $\operatorname{poly}(k,m,n)$  time, e.g. by Hungarian algorithm.

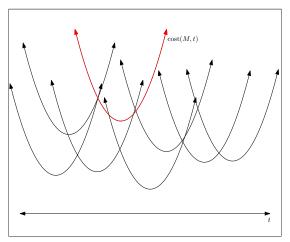
$$\operatorname{cost}^*(t) \coloneqq \min_{k\text{-matching }M} \operatorname{cost}(M,t)$$



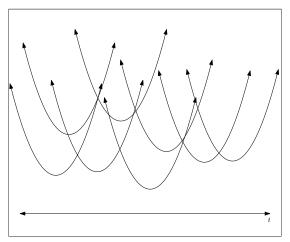
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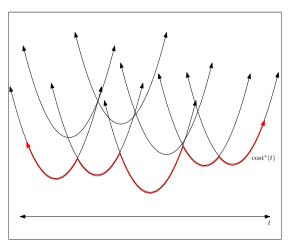
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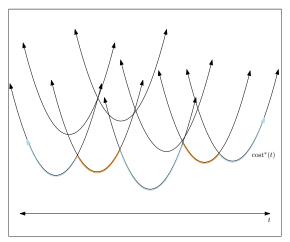
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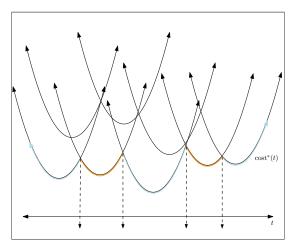
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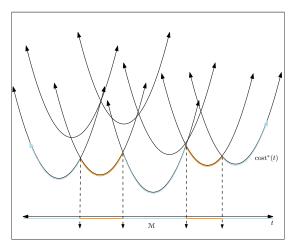
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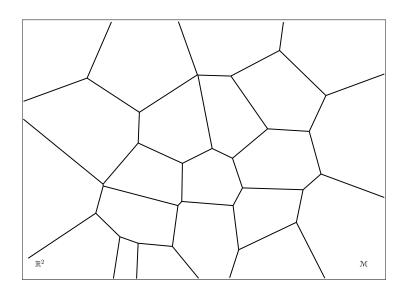
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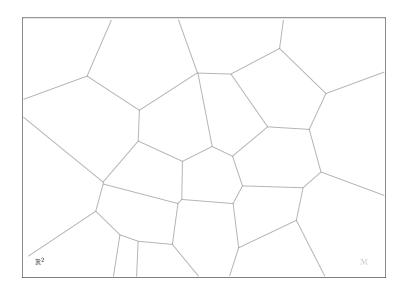


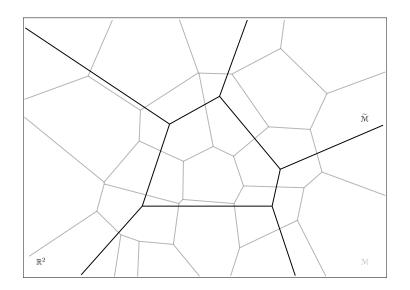
### Questions and prior results

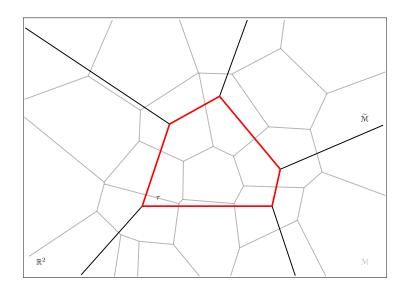
- 1. What is the *combinatorial complexity of*  $\mathfrak{M}$ ? Is it polynomial?
  - Rote 10]: for p=2 and k=m, a line crosses at most m(n-m)+1 cells
  - ▶ [Ben-Avraham et al. 14]: for p=2 and k=m,  $O(n^2m^{3.5}(e\ln m+e)^m)$
- 2. How quickly can we *compute*  $t^*$ , a global minimum of  $cost^*(t)$ ?
  - ightharpoonup Explore  $\mathfrak{M}$ , use static algorithm within cells.

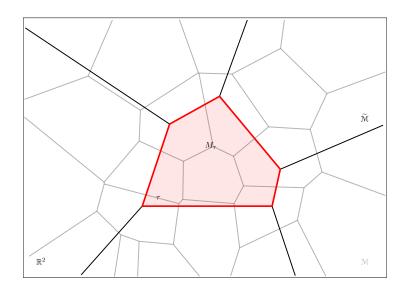
### Approximating $\mathcal M$



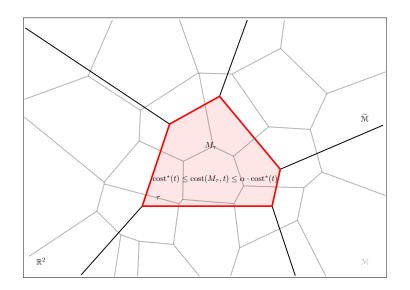








### Approximating $\mathcal{M}$



### Our results (approximation helps)

1. What is the *combinatorial complexity of*  $\mathfrak{M}$ ? Is it polynomial?

#### Theorem

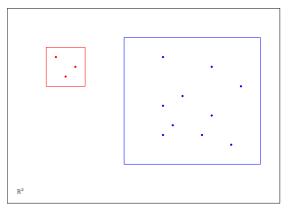
In  $\operatorname{poly}(k,m,n,\varepsilon^{-1})$  time, can construct a  $(1+\varepsilon)$  approximate diagram  $\widetilde{\mathbb{M}}$  of complexity  $O((mn/k)\varepsilon^{-2}\log\varepsilon^{-1})$ .

2. How quickly can we *compute*  $t^*$ , a global minimum of  $cost^*(t)$ ?

#### **Theorem**

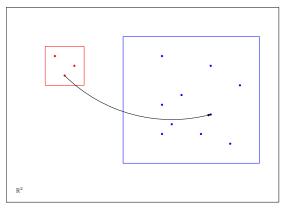
In  $\operatorname{poly}(k,m,n,\varepsilon^{-1})$  time, can compute a  $(1+\varepsilon)$  approximation to  $\operatorname{cost}^*(t^*)$  by exploring the cells of  $\widetilde{\mathbb{M}}$ .

▶ Point-to-point translations:  $T := \{t_{ba} = (b-a) \mid a \in A, b \in B\}$ 



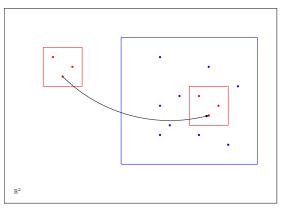
▶ Claim: Let  $\widetilde{\mathbb{M}}$  be Vor(T), with each  $VorRegion(t_{ba})$  assigned the optimal k-matching at  $t_{ba}$ . Then,  $\widetilde{\mathbb{M}}$  is a O(1)-approximate diagram.

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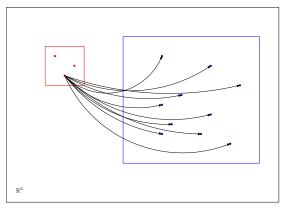
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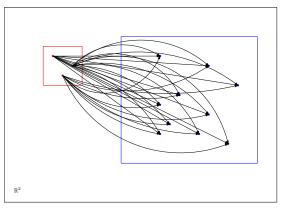
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 $\triangleright$  Claim: Let  $\mathcal{M}$  be Vor(T), with each  $VorRegion(t_{ba})$  assigned the optimal k-matching at  $t_{ba}$ . Then,  $\mathfrak{M}$  is a O(1)-approximate diagram.

### Lipschitz continuity for $cost^*(t)$

$$\operatorname{cost}^*(t) \coloneqq \min_{k \text{-matching } M} \left[ \frac{1}{k} \sum_{(a,b) \in M} \lVert a + t - b \rVert^p \right]^{1/p}$$

#### Lemma (Lipschitz condition)

Given  $t, \Delta \in \mathbb{R}^2$ , let  $M_t$  be the optimal k-matching at t.

Then  $cost(M_t, t + \Delta) \leq cost^*(t) + ||\Delta||$ .

### Proof of approximation for T

- ▶ Claim:  $\widetilde{\mathcal{M}}$  is an O(1)-approximate diagram.
- ▶ Given  $t \in \mathbb{R}^2$ , let  $t_0$  be its nearest neighbor in T, and  $M_{t_0}$  the optimal matching at  $t_0$ .

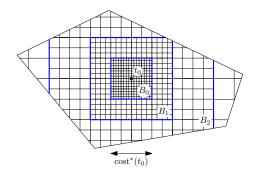
$$\begin{aligned} \cos t^*(t) &= \min_{k\text{-matching } M} \left[ \frac{1}{k} \sum_{(a,b) \in M} \lVert a + t - b \rVert^p \right]^{1/p} \\ &= \min_{k\text{-matching } M} \left[ \frac{1}{k} \sum_{(a,b) \in M} \lVert t - t_{ba} \rVert^p \right]^{1/p} \\ &\geq \min_{k\text{-matching } M} \left[ \frac{1}{k} \sum_{(a,b) \in M} \lVert t - t_0 \rVert^p \right]^{1/p} \\ &= \lVert t - t_0 \rVert \end{aligned}$$

### Proof of approximation for T (cont.)

- $\triangleright$  Claim:  $\mathcal{M}$  is an O(1)-approximate diagram.
- Given  $t \in \mathbb{R}^2$ , let  $t_0$  be its nearest neighbor in T, and  $M_{t_0}$  the optimal matching at  $t_0$ .
- $||t t_0|| \le \cos^*(t)$  $cost(M_{t_0}, t) \leq cost^*(t_0) + ||t - t_0||$  (Lipschitz cond.)  $< \cos t^*(t) + 2||t - t_0||$  (Lipschitz cond.)  $< \cos^*(t) + 2\cos^*(t)$  $= 3 \cos^*(t)$

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### $O(1) \rightarrow (1+\varepsilon)$ approximation



 $\begin{array}{c} \bullet & (1+\varepsilon) \text{ approximate diagram of size} \\ O(|T|\varepsilon^{-2}\log\varepsilon^{-1}) = O((mn)\varepsilon^{-2}\log\varepsilon^{-1}) \end{array}$ 

#### **Theorem**

In  $\operatorname{poly}(k,m,n,\varepsilon^{-1})$  time, can construct a  $(1+\varepsilon)$  approximate diagram  $\widetilde{\mathbb{M}}$  of complexity  $O((mn/k)\varepsilon^{-2}\log\varepsilon^{-1})$ .

# Compressing $\widetilde{\mathcal{M}}$

- ▶ Reduce size from  $O(mn) \rightarrow O(mn/k)$ .
- Any O(1) approx. diagram is enough for the  $(1+\varepsilon)$  diagram.
- ▶ Cluster the points of T... while keeping cluster radius small w.r.t.  $cost^*(t)$ .

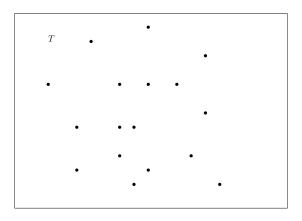
### Averaging argument

$$\operatorname{cost}^*(t) \coloneqq \min_{k \text{-matching } M} \left[ \frac{1}{k} \sum_{(a,b) \in M} \lVert a + t - b \rVert^p \right]^{1/p}$$

- At most k/2 pairs  $(a,b) \in M_t$  have  $||a+t-b|| \ge 2^{1/p} \operatorname{cost}^*(t)$ .
- At most k/2 pairs  $(a,b) \in M_t$  have  $||t t_{ab}|| \ge 2^{1/p} \cos^*(t)$ .

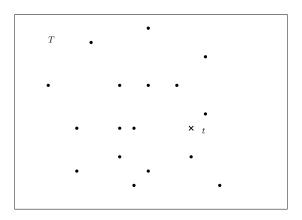
## Averaging argument (cont.)

At most k/2 pairs  $(a,b) \in M_t$  have  $||t-t_{ab}|| \ge 2^{1/p} \operatorname{cost}^*(t)$ .



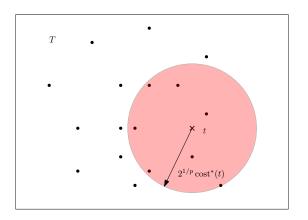
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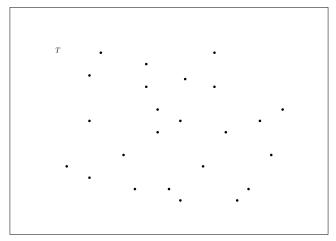
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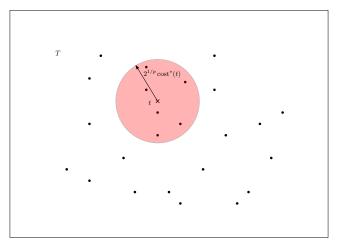
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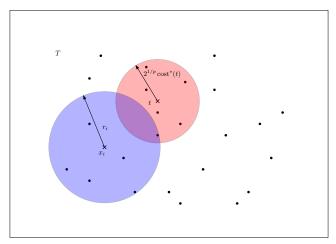


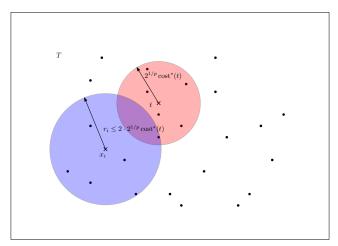
### Clustering T greedily

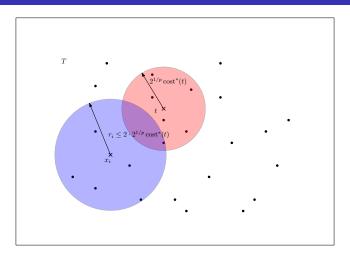
- 1. Let  $D_i = B(x_i, r_i)$  be the smallest disk containing at least k/2 remaining points of T.
- 2. Remove from T the points covered by  $D_i$ .
- 3. Repeat.
- ▶ Quorum clustering 2-approx. algorithm in  $O(|T| \operatorname{polylog} n)$  time [Carmi et al. 05]
- ightharpoonup O(|T|/k) = O(mn/k) clusters.



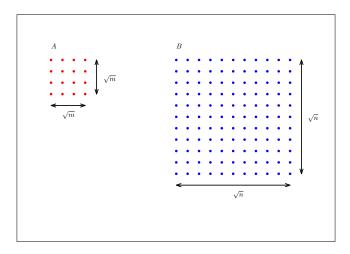


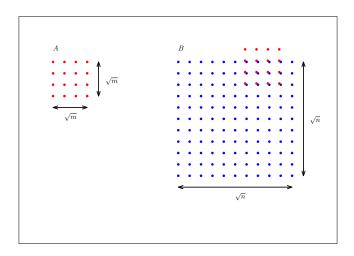


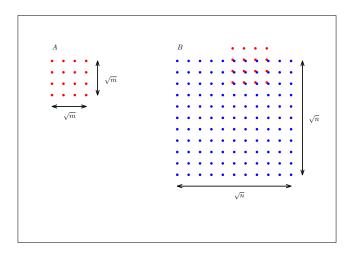


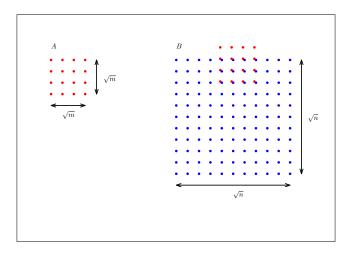


- $ightharpoonup \cos(M_{x_i}, t) \le (1 + 6 \cdot 2^{1/p}) \cos^*(t)$
- ▶ Using grids,  $(1+\varepsilon)$  approximate diagram of size  $O((mn/k)\varepsilon^{-2}\log\varepsilon^{-1})$ .









#### Open questions

- 1. Is the complexity of M polynomial, for any p?
- 2. Approximate diagrams for rotations? Rigid transforms?

#### The End

Thank you.