

Curriculum Vitae
Alexander Koenig

Education

- 10/2018 — ongoing **Technical University of Munich**
M.Sc. Robotics, Cognition, Intelligence
Exchange Semester at Tel Aviv University
- 10/2014 — 10/2018 **Technical University of Munich**
B.Sc. Engineering Science
Exchange Semester at Tor Vergata University of Rome
- 09/2012 — 05/2014 **King Edward's School Witley, GB**
International Baccalaureate (Grade: 40 points – top 5%)

Research Experience

- 11/2020 — ongoing **Master Thesis, Harvard Biorobotics Lab, Harvard University**
Title: Tactile Grasp Refinement using Analytic Grasp Stability Metrics and Entropy-Regularized Reinforcement Learning
Implementation of a C++ robotics simulator in ROS and Gazebo
- 04/2019 — 09/2019 **Research Intern, Mechatronics in Medicine Laboratory, Imperial College London**
Publication: A. Koenig, F. Rodriguez y Baena and R. Secoli “Gesture-Based Teleoperated Grasping for Educational Robotics”
In: IEEE International Symposium on Robot and Human Interactive Communication (RO-MAN), 2021.
- 04/2018 — 10/2018 **Bachelor Thesis, Chair for Computer Aided Medical Procedures and Augmented Reality, Technical University of Munich**
Title: Visualization of Complex Bone Fractures in Augmented Reality during Reduction Surgery
Development of a HoloLens application and independent implementation of a quantitative study with four trauma surgeons, Thesis Grade: 4.0/4.0

Industry Experience

- 11/2018 — 01/2019 **Working Student, Microstep, Munich**
Software development for usage in sales campaign: web crawler, automated generation of SQL scripts for user registration process
- 03/2017 — 08/2017 **Intern, Technical Integration, BMW Group, Munich**
Evaluation of a rendering software prototype, Extensive testing within the BMW IT-structure, Identification of error patterns and optimization potentials, Support of a scientific study

Skills

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|-------------|---|
| Software | Robot Operating System (ROS), Gazebo, Git, Docker, Unity3D, 3DSlicer, \LaTeX |
| Hardware | HoloLens, KUKA iiwa, AprilTags, Oculus Rift, Leap Motion, RGB-D cameras |
| Programming | C++, Python, C#, Swift, MATLAB, C, GraphQL |
| Frameworks | PyTorch, Tensorflow 2, Keras, Pyglet, SwiftUI |
| Languages | German: native, English: proficient, Italian: intermediate, French: beginner |