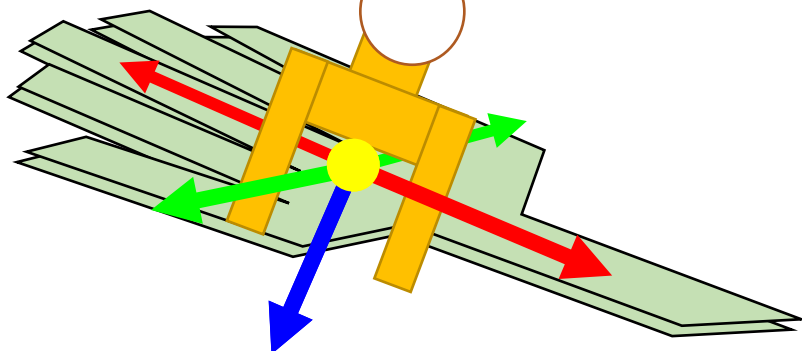
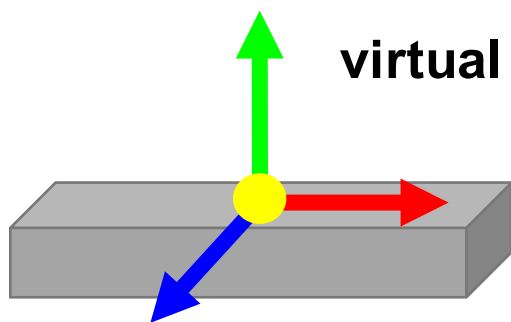


**adjusted hand**



**tool**

**virtual leap motion**



**base**

