For a non-negative integer n, the tactorial n! can be be obtained using the integral

$$N! = \int_0^\infty e^{-t} t^n dt$$

We can demonstrate this by repeated integration by parts (IBP)

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, then

$$\int_0^\infty e^{-t} t^n dt = -\int_0^\infty t^n d(e^{-t})$$

$$= -\left[t^n e^{-t}\right]_0^\infty - \int_0^\infty e^{-t} d(t^n)$$

$$= -\left[\lim_{t \to \infty} t^n e^{-t} - o \cdot e^{\circ}\right] + \int_0^\infty n t^{n-1} e^{-t} dt$$

$$= -O + n \int_0^\infty e^{-t} t^{n-1} dt$$

we let $n' = n - 1$

$$\int_0^\infty e^{-t} t^{n'} dt = n' \int_0^\infty e^{-t} t^{n'-1} dt$$

 $= (n-1) \int_{0}^{\infty} e^{-t} t^{n-2} dt$

£2. Show-explicitly that

$$1! = 1 \quad \text{and} \quad 0! = 1$$

Gamma Function

$$\Gamma(z) = \int_0^\infty e^{-t} t^{z-1} dt$$
, Re(z) > 0
where z is a complex number

*
$$N! = \Gamma(n+1)$$
By IBP

* $\Gamma(z+1) = z\Gamma(z)$

$$\Gamma\left(\frac{1}{2}\right) = \sqrt{11}$$

let
$$x=t^{1/2}$$
, $dx=\frac{1}{2}t^{-1/2}dt$

$$\Gamma\left(\frac{1}{2}\right) = 2 \int_{0}^{\infty} e^{-x^{2}} dx$$

$$= \int_{0}^{\infty} e^{-x^{2}} dx + \int_{0}^{\infty} e^{-x^{2}} dx$$

$$= \int_{0}^{\infty} e^{-(-x)^{2}} dx + \int_{0}^{\infty} e^{-x^{2}} dx$$

$$= \int_{0}^{\infty} e^{-(-x)^{2}} d(-x) = -\int_{0}^{-\infty} e^{-x^{2}} dx$$

$$= \int_{-\infty}^{\infty} e^{-x^{2}} dx$$

$$= \int_0^\infty e^{-\chi^2} d\chi + \int_0^\infty e^{-\chi^2} d\chi$$

$$= \int_{-\infty}^\infty e^{-\chi^2} d\chi \quad (Gaussian integral)$$

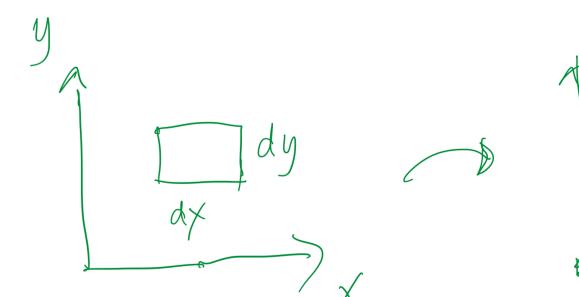
x is just a driving variable

$$\begin{aligned} & \left(\begin{array}{c} \Gamma(\frac{1}{2}) = \int_{\infty}^{\infty} e^{-x^2} dx & \text{or} \quad \left[\Gamma(\frac{1}{2}) = \int_{\infty}^{\infty} e^{-y^2} dy \right] \\ & \left(\begin{array}{c} \Gamma(\frac{1}{2}) \right)^2 = \int_{\infty}^{\infty} dx & \text{od} \quad e^{-(x^2+y^2)} \\ & \text{the integration from rectargular } (x,y) \\ & \text{to} \quad \text{polar } (r,\phi) \end{aligned} \\ & \begin{array}{c} x = r \cos \phi \\ y = r \sin \phi \\ & \begin{array}{c} y = r \sin \phi \\ & \begin{array}{c} x = r \cos \phi \\ & \begin{array}{c} y = r \sin \phi \\ & \begin{array}{c} x = r \cos \phi \\ & \begin{array}{c} y = r \sin \phi \\ & \begin{array}{c} x = r \cos \phi \\ & \begin{array}{c} y = r \sin \phi \\ & \begin{array}{c} x = r \cos \phi \\ & \end{array} \end{aligned} } \end{aligned} \\ & \begin{array}{c} = 2\pi x + \frac{1}{2} & \text{otherwise} \\ & \begin{array}{c} x = r \cos \phi \\ & \begin{array}{c} x = r \cos \phi \\ & \end{array} \end{aligned} \\ & \begin{array}{c} x = r \cos \phi \\ & \end{array} \end{aligned} \end{aligned} \\ & \begin{array}{c} x = r \cos \phi \\ & \begin{array}{c} x = r \cos \phi \\ & \begin{array}{c} x = r \cos \phi \\ & \end{array} \end{aligned} \end{aligned} \\ & \begin{array}{c} x = r \cos \phi \\ & \end{array} \end{aligned} \end{aligned} \\ & \begin{array}{c} x = r \cos \phi \\ & \begin{array}{c} x = r \cos \phi \\ & \begin{array}{c} x = r \cos \phi \\ & \end{array} \end{aligned} \end{aligned} \\ & \begin{array}{c} x = r \cos \phi \\ & \begin{array}{c} x = r \cos \phi \\ & \begin{array}{c} x = r \cos \phi \\ & \end{array} \end{aligned} \end{aligned} \\ & \begin{array}{c} x = r \cos \phi \\ & \begin{array}{c} x = r \cos \phi \\ & \begin{array}{c} x = r \cos \phi \\ & \end{array} \end{aligned} \end{aligned} \\ & \begin{array}{c} x = r \cos \phi \\ & \begin{array}{c} x = r \cos \phi \\ & \begin{array}{c} x = r \cos \phi \\ & \end{array} \end{aligned} \end{aligned} \\ & \begin{array}{c} x = r \cos \phi \\ & \begin{array}{c} x = r \cos \phi \\ & \begin{array}{c} x = r \cos \phi \\ & \end{array} \end{aligned} \end{aligned} \\ & \begin{array}{c} x = r \cos \phi \\ & \begin{array}{c} x = r \cos \phi \\ & \begin{array}{c} x = r \cos \phi \\ & \end{array} \end{aligned} \end{aligned} \end{aligned} \\ & \begin{array}{c} x = r \cos \phi \\ & \end{array} \end{aligned} \end{aligned} \end{aligned} \end{aligned} \\ & \begin{array}{c} x = r \cos \phi \\ & \begin{array}{c} x = r \cos \phi \\ & \begin{array}{c} x = r \cos \phi \\ & \end{array} \end{aligned} \end{aligned} \end{aligned} \\ & \begin{array}{c} x = r \cos \phi \\ & \begin{array}{c} x = r \cos \phi \\ & \begin{array}{c} x = r \cos \phi \\ & \end{array} \end{aligned} \end{aligned} \end{aligned} \\ & \begin{array}{c} x = r \cos \phi \\ & \begin{array}{c} x = r \cos \phi \\ & \begin{array}{c} x = r \cos \phi \\ & \end{array} \end{aligned} \end{aligned} \end{aligned} \end{aligned} \\ & \begin{array}{c} x = r \cos \phi \\ & \end{array} \end{aligned} \end{aligned} \end{aligned} \end{aligned} \\ & \begin{array}{c} x = r \cos \phi \\ & \end{array} \end{aligned} \end{aligned} \end{aligned} \end{aligned} \end{aligned} \end{aligned} \\ \begin{array}{c} x = r \cos \phi \\ & \begin{array}{c} x = r \cos \phi \\ & \begin{array}{c} x = r \cos \phi \\ & \end{array} \end{aligned} \end{aligned} \end{aligned} \end{aligned} \end{aligned} \\ \begin{array}{c} x = r \cos \phi \\ & \begin{array}{c} x = r \cos \phi$$

SUF NOTES:

Jacolonam
$$\int \frac{\partial x}{\partial y} dy = \int \frac{\partial x}{\partial y} \frac{\partial y}{\partial y} = \int \frac{\partial x}{\partial y} \frac{\partial y}{\partial y}$$

or you can use your intuition (based on your familiarity with auc length relation



Note: k!! = k(k-2)(k-4)...

Appy proof of induction to antidently assert the relation