

UART DRIVER MANUAL (ESP32)

DECEMBER 2022

Autors:

Axel Gay Díaz

Anahí González Holguin

Carlos Alberto González Vázquez

Carlos Eduardo López Lara



INDEX

1. Generalities
 - 1.1 Developer Recommendations
 - 1.2 Download and Driver Implementation
2. General operation
 - 2.1 Header Files(.h)
 - 2.1.1 Uart_Driver_2022.h
 - 2.2 Functions(.c)
 - 2.2.1 Uart_Driver_2022.c
3. DevKitCV1 Setup
4. Examples
 - 4.1 ApplicationUart.h
 - 4.2 ApplicationUart.c
 - 4.3 Links



1. Generalities

1.1 Developer Recommendations

If you have never used the ESP32 unit, the following link provides detailed information:

[ESP32 Wi-Fi & Bluetooth MCU | Espressif Systems](#)

On this page you will find things like:

- Technical information
- Modules information and Development Kits
- Videos with examples

Links will be provided for installing the recommended IDE:

Espressif-IDE Installation Guide (ES):

[1\) Espressif ESP32 - ESP-IDF - Instalación y Primer Ejemplo - YouTube](#)

Espressif-IDE Installation Guide (EN):

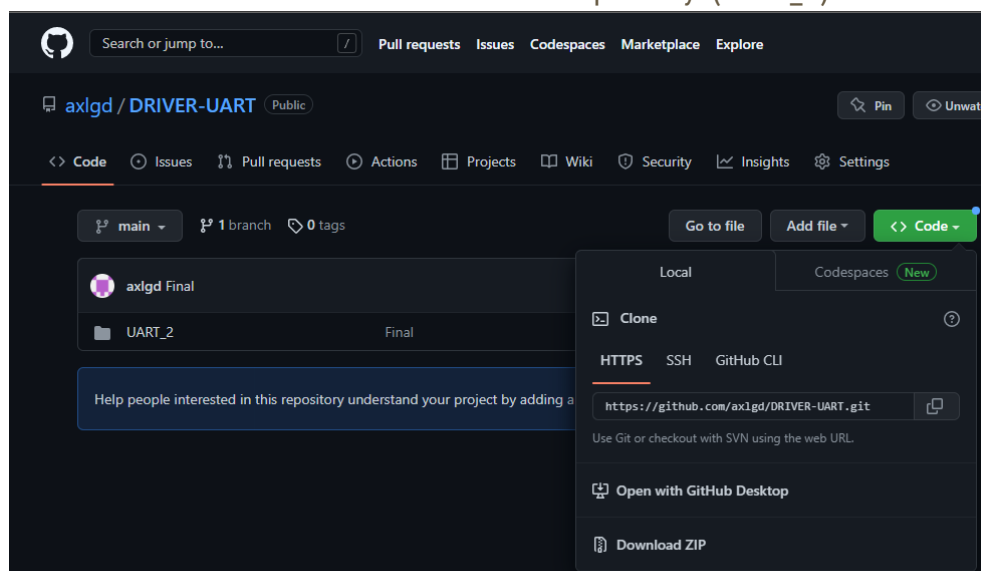
[Getting started with ESP-IDF programming using espressif IDE - YouTube](#)

1.2 Download and Driver Implementation

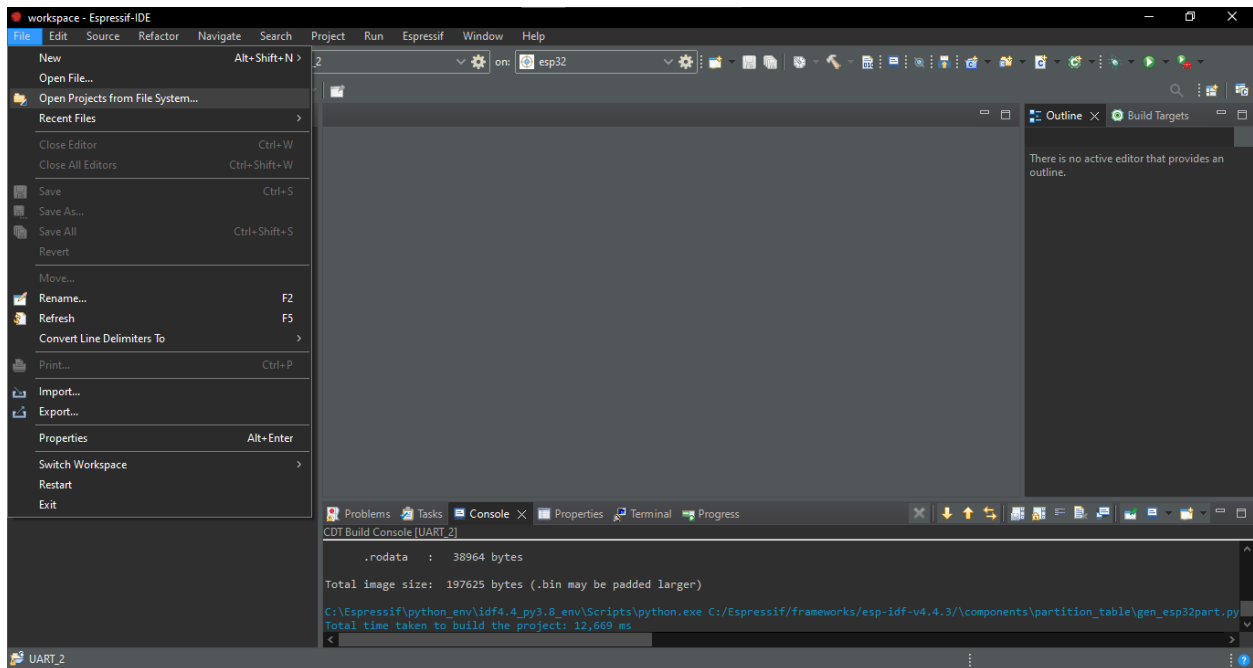
1. Access the following GitHub link:

<https://github.com/axlgd/DRIVER-UART.git>

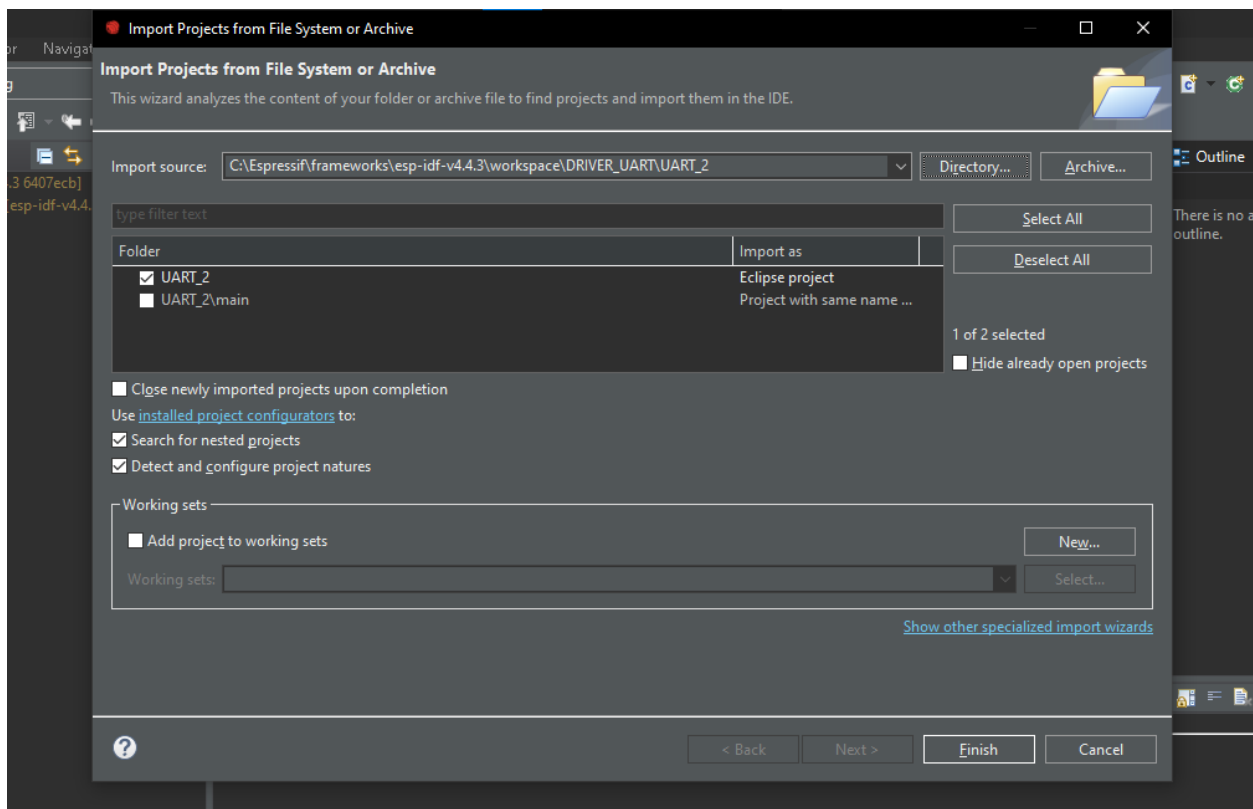
2. Click on Code and on Download ZIP inside the repository (UART_2):



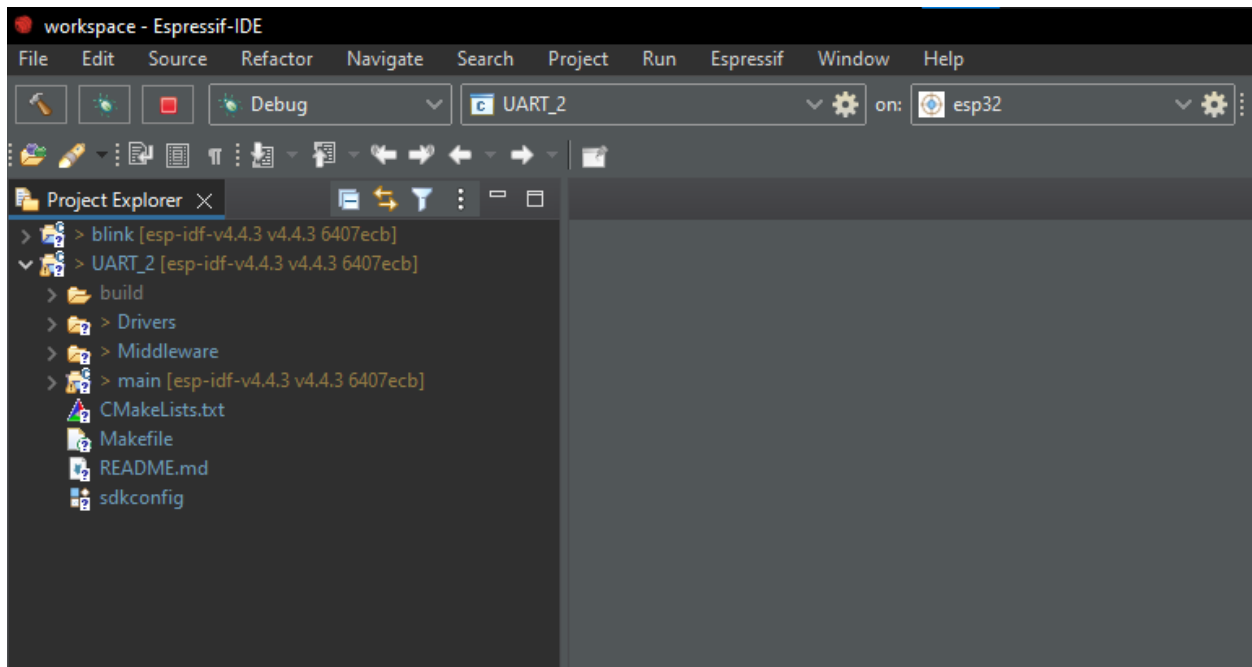
3. Select the option Open Projects from File System:



4. Select the path of the project and click on Finish:

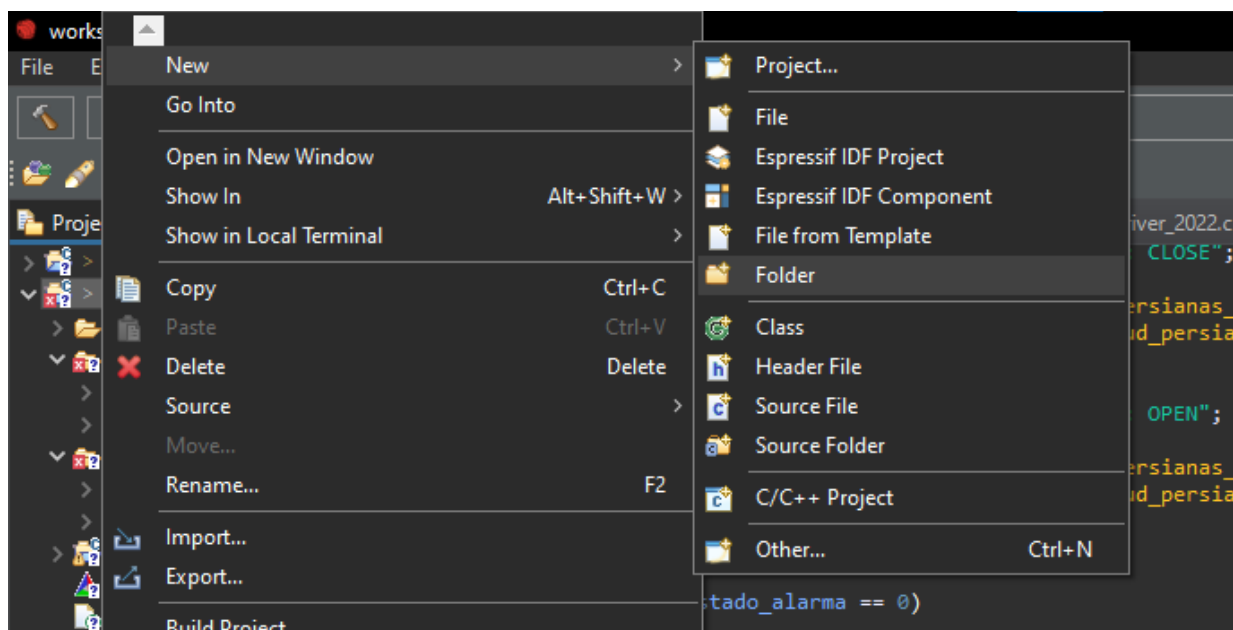


5. Then the project should appear on the left:

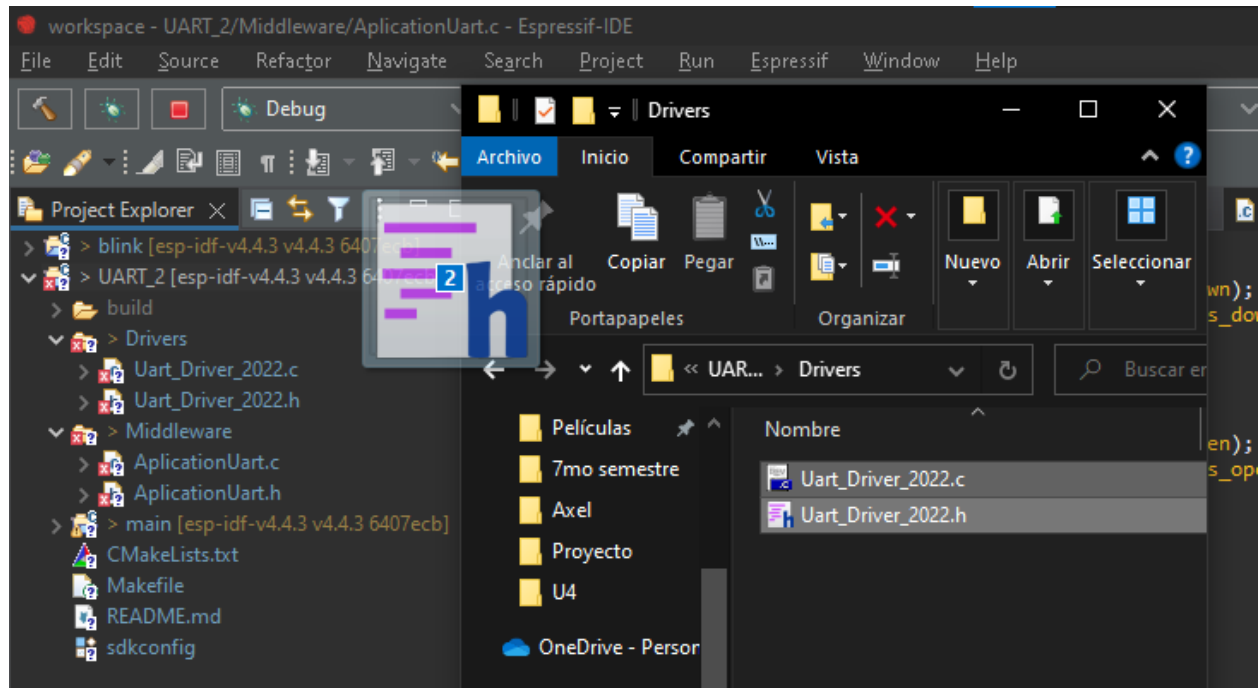


6. In case you need to add the drivers to another project than the example one, you just need to follow the steps below:

a) Create a new folder inside your project and name it.



- b) Drag the Uart_Driver_2022.c and Uart_Driver_2022.h files to the folder you just created.





2. General operation

2.1 Header Files(.h)

In these files are all the definitions and redefinitions of functions and constants necessary for the configuration of the UART, pins and an external button.

2.1.1 Uart_Driver_2022.h

```

14
15 #pragma once
16
17 //librerías necesarias
18 #include <stdio.h>
19 #include <stdlib.h>
20 #include "freertos/FreeRTOS.h"
21 #include "freertos/task.h"
22 #include "driver/uart.h"
23 #include "driver/gpio.h"
24 #include "sdkconfig.h"
25 #include "esp_log.h"
26
27
28 //CONFIGURACIÓN PARA SELECCIONAR PINES DE LA ESP Y CARACTERÍSTICAS DE LA UART
29 #define ECHO_TEST_TXD (GPIO_NUM_17) //PIN TXD
30 #define ECHO_TEST_RXD (GPIO_NUM_16) //PIN RXD
31 #define ECHO_TEST_RTS (UART_PIN_NO_CHANGE)
32 #define ECHO_TEST_CTS (UART_PIN_NO_CHANGE)
33
34 #define ECHO_UART_PORT_NUM (CONFIG_EXAMPLE_UART_PORT_NUM) //NUMERO DE PUERTO DE UART
35 #define ECHO_UART_BAUD_RATE (CONFIG_EXAMPLE_UART_BAUD_RATE) //BAUD RATE
36 #define ECHO_TASK_STACK_SIZE (CONFIG_EXAMPLE_TASK_STACK_SIZE)
37
38 //Redefiniciones del driver
39 #define TX_PIN (ECHO_TEST_TXD)
40 #define RX_PIN (ECHO_TEST_RXD)
41
42
43 #define UART_PORT (ECHO_UART_PORT_NUM)
44 #define BAUD_RATE (ECHO_UART_BAUD_RATE)
45 #define DATA_BITS (UART_DATA_8_BITS) // BITS DE DATOS
46 #define PARITY (UART_PARITY_DISABLE) // PARIDAD
47 #define STOP_BITS (UART_STOP_BITS_1) //BITS DE PARO
48
49
50 static const char *TAG = "UART TEST";
51
52 #define BUF_SIZE (1024)
53
54 /*****
55 * Function: uart_config
56 * Preconditions: Ninguna.
57 * Overview: Accede a los registros por medio de una estructura para configurar la UART.
58 * Input: Ninguna.
59 * Output: Ninguna.
60 *
61 *****/
62 extern void uart_config(void);
63
64 /*****
65 * Function: uart_read
66 * Preconditions: data, len.
67 * Overview: Permite recibir información vía UART desde otra terminal.
68 * Input: "data. Dirección de memoria de la variable "data", el arreglo dentro
69 * de memoria dinámica que guarda lo que se recibe de la UART.
70 * Output: int len. Entero que guarda el índice del arreglo data donde se guardó la
71 * información que recibió la UART.
72 *****/

```

```
73 extern int uart_read(uint8_t *data);
74
75 /*
76  * Function: uart_write
77  * Preconditions: data, len.
78  * Overview: Permite escribir en la terminal.
79  * Input:
80  * *data. Dirección de memoria de la variable "data", el arreglo dentro
81  * de memoria dinámica que guarda lo que se recibe de la UART.
82  * int len. Entero que guarda el índice del arreglo data donde se guardó la
83  * información que recibió la UART.
84  * Output: Ninguna.
85  */
86 extern void uart_write(uint8_t *data, int len);
87
```

2.2 Functions (.c)

In these files you will find the implementation of all the functions used in the Driver.

2.2.1 Uart_Driver_2022.c

uart_config()

This function is used to configure the UART accessing memory through a structure.

```

37 void uart_config(void)
38 {
39     uart_config_t uart_config = {
40         .baud_rate = BAUD_RATE, //Baud Rate 115 200
41         .data_bits = DATA_BITS, //8 bits de datos
42         .parity = PARITY, //Sin paridad
43         .stop_bits = STOP_BITS, //1 bit de parada
44         .flow_ctrl = UART_HW_FLOWCTRL_DISABLE,
45         .source_clk = UART_SCLK_APB,
46     };
47     intr_alloc_flags = 0;
48
49 #if CONFIG_UART_ISR_IN_IRAM
50     intr_alloc_flags = ESP_INTR_FLAG_IRAM;
51 #endif
52
53     //Instalación del driver para la UART
54     ESP_ERROR_CHECK(uart_driver_install(UART_PORT, BUF_SIZE * 2, 0, 0, NULL, intr_alloc_flags));
55     //Confirmación de la configuración de la UART con la estructura antes definida
56     ESP_ERROR_CHECK(uart_param_config(UART_PORT, &uart_config));
57     //SETTER de los pines RXD, TXD y el número de pines de la UART.
58     ESP_ERROR_CHECK(uart_set_pin(UART_PORT, ECHO_TEST_TXD, ECHO_TEST_RXD, ECHO_TEST_RTS, ECHO_TEST_CTS));
59 }

```

uart_read()

This function is the one that allows receiving information from another terminal through UART.

```

71 int uart_read(uint8_t *data)
72 {
73     int len = uart_read_bytes(ECHO_UART_PORT_NUM, data, (BUF_SIZE - 1), 20 / portTICK_RATE_MS);
74     return len;
75 }

```

uart_write()

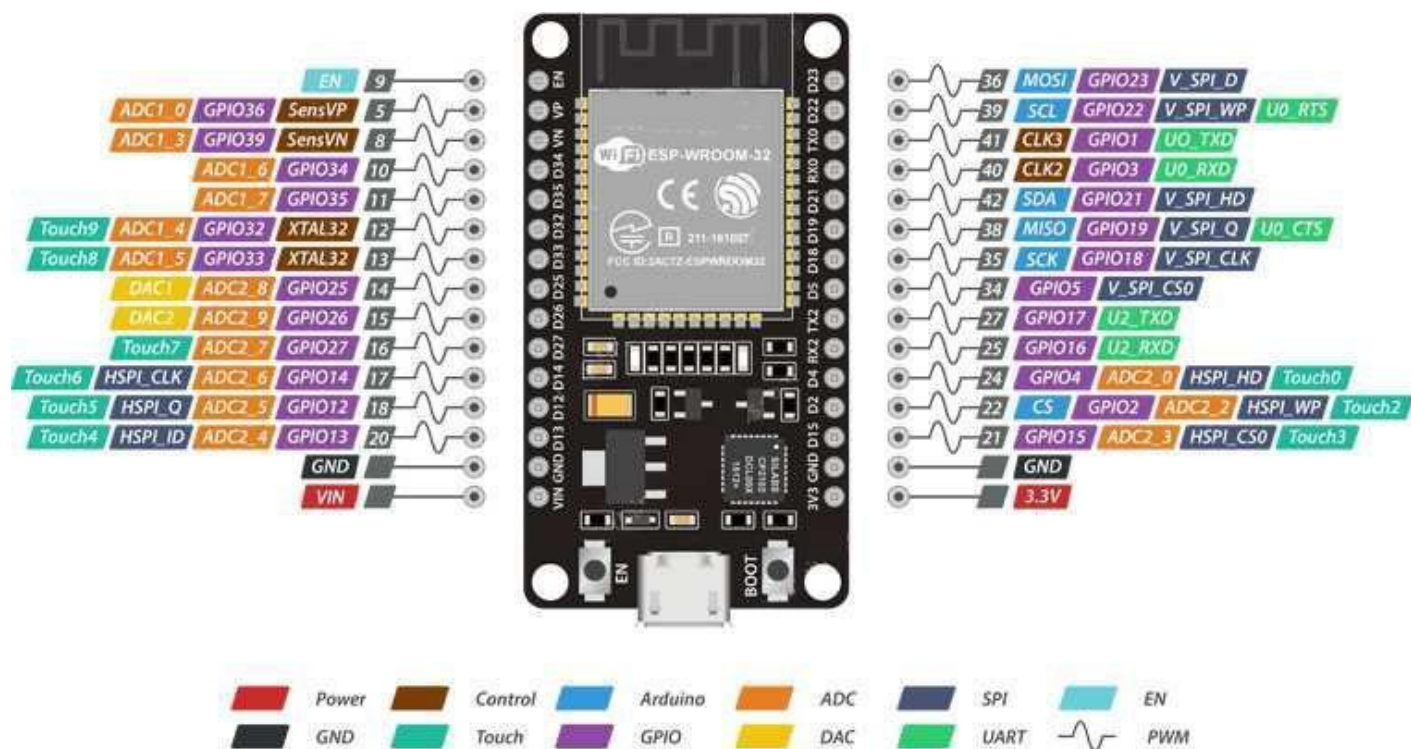
This function allows us to write to the terminal.

```
89 void uart_write(uint8_t *data, int len)
90 {
91     uart_write_bytes(ECHO_UART_PORT_NUM, (const char *) data, len);
92     if (len) {
93         data[len] = '\0';
94         ESP_LOGI(TAG, "Recv str: %s", (char *) data);
95     }
96 }
```



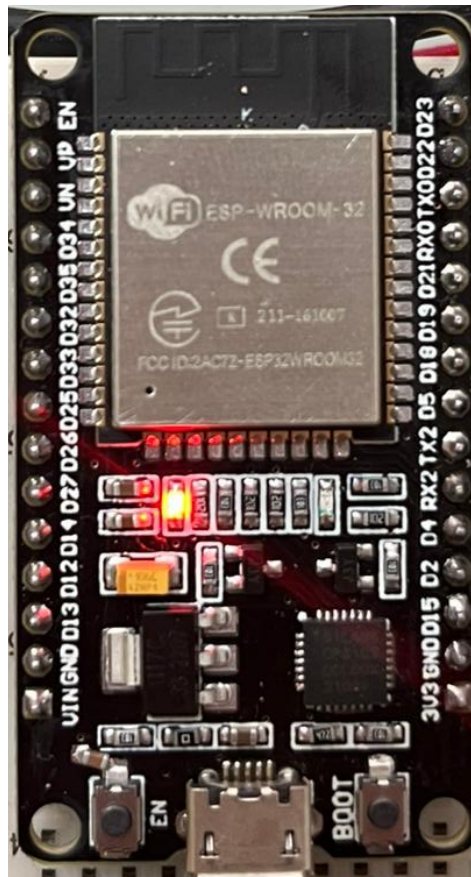
3. DevKitC V1 Setup

3.1 Pinout



ESP32 Dev. Board Pinout

3.2 Physical features



Some of its main physical characteristics are:

- SoC Tensilica Xtensa 32-bit LX6
- 2 buttons, one to activate Bootloader mode, and another to Reset
- 30 pins. We find pins for GPIO, UART, GND, 5V or 3.3V supply, ADC, etc.
- WiFi & Bluetooth modules
- Micro USB port
- LED indicator



4. Examples

4.1 ApplicationUart.h

In this header file we find the definitions of functions and constants to be used in the application example.

```

14 #pragma once
15
16 #include <stdio.h>
17 #include <stdlib.h>
18 #include "C:\Espressif\frameworks\esp-idf-v4.4.3\workspace\UART_2\Drivers\Uart_Driver_2022.h"
19 #include "C:\Espressif\frameworks\esp-idf-v4.4.3\workspace\UART_2\Drivers\Uart_Driver_2022.c"
20 #include <unistd.h>
21 #include <TIME.H>
22 #include "esp_log.h"
23 #include "freertos/FreeRTOS.h"
24 #include "freertos/task.h"
25 #include "driver/uart.h"
26 #include "driver/gpio.h"
27 #include "sdkconfig.h"
28 #include "esp_log.h"
29
30 //Definiciones para el código de aplicación
31 #define On 1
32 #define Off 0
33 #define Open 1
34 #define Close 0
35
36 /**
37  * Function: sistema_init
38  * Preconditions:
39  * Overview: Imprime que ha iniciado el programa.
40  * Input: Ninguna.
41  * Output: Ninguna.
42  */
43 extern void sistema_init(void);
44
45 /**
46  * Function: imprimir_menu
47  * Preconditions:
48  * Overview: Imprime el menú de la aplicación
49  * Input: Ninguna.
50  * Output: Ninguna.
51  */
52 extern void imprimir_menu(void);
53
54 /**
55  * Function: imprimir_estado
56  * Preconditions:
57  * Overview: Imprime el estado de cada componente del sistema.
58  * Input: uint8_t estado_luces, uint8_t estado_persianas, uint8_t estado_alarma
59  * Output: Ninguna.
60  */
61 extern void imprimir_estado(uint8_t estado_luces, uint8_t estado_persianas, uint8_t estado_alarma);
62

```

4.2 *AplicationUart.c*

This file contains the implementation of each of the functions to be used in the application example.

sistema_init()

This function tells us that the program has started, by printing in the terminal and telling us to press a key to start.

```
40 void sistema_init(void)
41 {
42     char cadena[] = "El programa ha iniciado\n\r Presione una tecla para iniciar";
43     uint8_t longitud;
44     longitud = sizeof(cadena);
45     uart_write(&cadena, longitud);
46 }
```

imprimir_menu()

This function prints the application menu, displaying all the available options, which are to control the lights, blinds, alarm or turn off the system.

```
56 void imprimir_menu(void)
57 {
58     char luces[] = "1.Prender/Apagar luces";
59     uint8_t longitud_luces;
60     longitud_luces = sizeof(luces);
61     uart_write(&luces, longitud_luces);
62     char persianas[] = "2.Subir/Bajar persianas";
63     uint8_t longitud_persianas;
64     longitud_persianas = sizeof(persianas);
65     uart_write(&persianas, longitud_persianas);
66     char alarma[] = "3.Prender/Apagar alarma";
67     uint8_t longitud_alarma;
68     longitud_alarma = sizeof(alarma);
69     uart_write(&alarma, longitud_alarma);
70     char apagar[] = "4.Apagar el sistema";
71     uint8_t longitud_apagar;
72     longitud_apagar = sizeof(apagar);
73     uart_write(&apagar, longitud_apagar);
74     char opcion[] = "Presione el boton de menu:";
75     uint8_t longitud_opcion;
76     longitud_opcion = sizeof(opcion);
77     uart_write(&opcion, longitud_opcion);
78 }
```

imprimir_estado()

This function prints the status of each system component.

```

88 void imprimir_estado(uint8_t estado_luces, uint8_t estado_persianas, uint8_t estado_alarma)
89 {
90     char Micasa[] = "Mi casa";
91     uint8_t longitud_micasa;
92     longitud_micasa = sizeof(Micasa);
93     uart_write(&Micasa, longitud_micasa);
94
95     if(estado_luces == 0)
96     {
97         char luces_off[] = "Luces: OFF";
98         uint8_t longitud_luces_off;
99         longitud_luces_off = sizeof(luces_off);
100        uart_write(&luces_off, longitud_luces_off);
101    }else
102    {
103        char luces_on[] = "Luces: ON";
104        uint8_t longitud_luces_on;
105        longitud_luces_on = sizeof(luces_on);
106        uart_write(&luces_on, longitud_luces_on);
107    }
108    if(estado_persianas == 0)
109    {
110        char persianas_down[] = "Persianas: CLOSE";
111        uint8_t longitud_persianas_down;
112        longitud_persianas_down = sizeof(persianas_down);
113        uart_write(&persianas_down, longitud_persianas_down);
114    }else
115    {
116        char persianas_open[] = "Persianas: OPEN";
117        uint8_t longitud_persianas_open;
118        longitud_persianas_open = sizeof(persianas_open);
119        uart_write(&persianas_open, longitud_persianas_open);
120    }
121
122
123    if(estado_alarma == 0)
124    {
125        char alarma_off[] = "Alarma: Off";
126        uint8_t longitud_alarma_off;
127        longitud_alarma_off = sizeof(alarma_off);
128        uart_write(&alarma_off, longitud_alarma_off);
129    }else
130    {
131        char alarma_on[] = "Alarma: On";
132        uint8_t longitud_alarma_on;
133        longitud_alarma_on = sizeof(alarma_on);
134        uart_write(&alarma_on, longitud_alarma_on);
135    }
136
137
138 }
139

```

4.3 Links

Links:

-Driver UART ZIP file:

<https://github.com/axlgd/DRIVER-UART.git>

-Video tutorials (Playlist):

<https://www.youtube.com/playlist?list=PLUqGq5mzysq71o7x00JAr6qn0i-qRyWpq>