Linear Programming

What is Linear Programming?

A method for solving certain types of minimization/maximization problems.

The problems must be expressible by a system of inequalities

The inequalities must have very specific constraints.

Our first example:

maximize $x_1 + x_2$ subject to

$$4x_{1} - x_{2} \leq 8$$

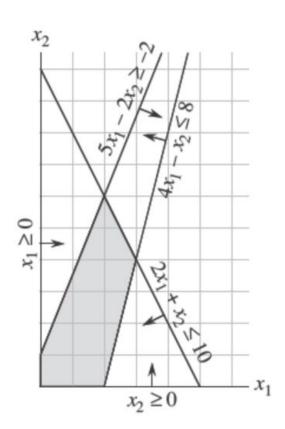
$$2x_{1} + x_{2} \leq 10$$

$$5x_{1} - 2x_{2} \geq -2$$

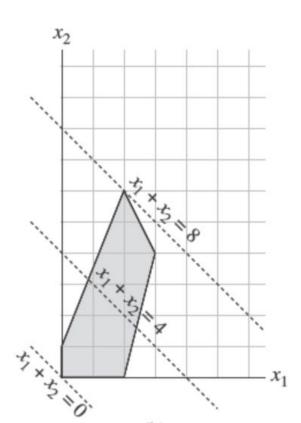
$$x_{1}, x_{2} \geq 0$$

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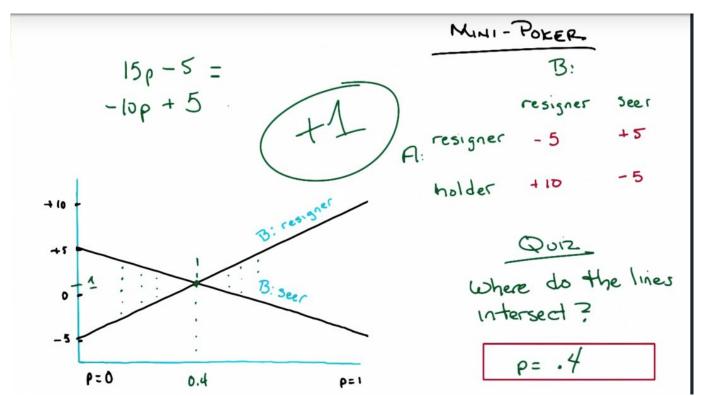
Let's graph it!



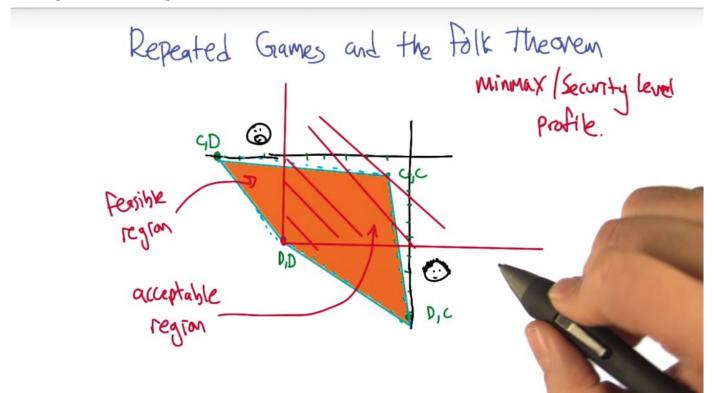
And, we are done...



This should look familiar

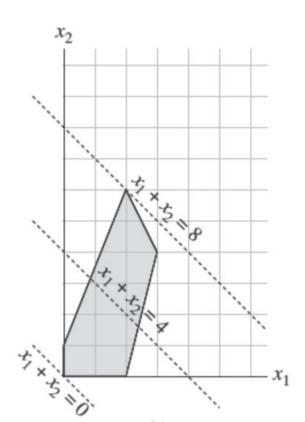


Seriously, really familiar...



Udacity Reinforcement Learning Lesson 13: 11B Game Theory Reloaded 13. Security Level Profile

So, how do we use a computer to solve this?



Linear Programming!

Get yourself a LP solver: glpk, CVXOPT, SCPSolver, etc...

Express your problem as a system of inequalities.

Run your solver on the resulting matrix.

Back to our example

maximize $x_1 + x_2$ subject to

$$4x_{1} - x_{2} \leq 8$$

$$2x_{1} + x_{2} \leq 10$$

$$5x_{1} - 2x_{2} \geq -2$$

$$x_{1}, x_{2} \geq 0$$

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Almost there

minimize $-x_1 - x_2$ subject to

$$4x_{1} - x_{2} \leq 8$$

$$2x_{1} + x_{2} \leq 10$$

$$5x_{1} - 2x_{2} \geq -2$$

$$x_{1}, x_{2} \geq 0$$

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"Standard Form"

minimize $-x_1 - x_2$ subject to

$$4x_{1} - x_{2} \leq 8$$

$$2x_{1} + x_{2} \leq 10$$

$$-5x_{1} + 2x_{2} \leq 2$$

$$x_{1}, x_{2} \geq 0$$

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CVXOPT LP Solver

http://cvxopt.org/userguide/coneprog.html#cvxopt.solvers.lp

cvxopt.solvers.lp(c, G, h[, A, b[, solver[, primalstart[, dualstart]]]])

Explicit Multipliers

minimize $-1x_1 - 1x_2$ subject to

$$4x_{1} - 1x_{2} \leq 8$$

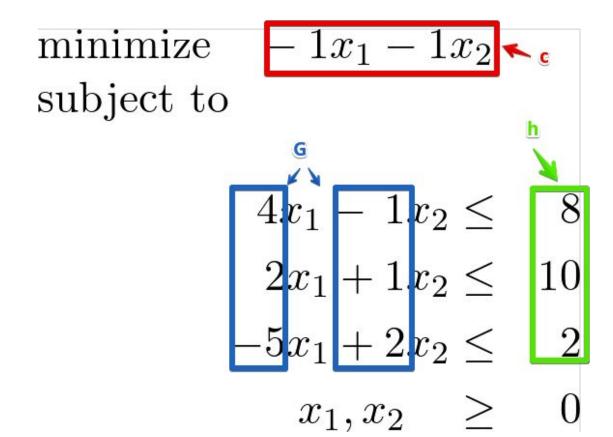
$$2x_{1} + 1x_{2} \leq 10$$

$$-5x_{1} + 2x_{2} \leq 2$$

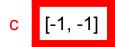
$$x_{1}, x_{2} \geq 0$$

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CVXOPT LP Parameters



CVXOPT LP Parameters



cvxopt.solvers.lp(c, G, h[, A, b[, solver[, primalstart[, dualstart]]]])

Code

```
from cvxopt import matrix, solvers

c = matrix([-1., -1.])
G = matrix([[4., 2., -5.], [-1., 1., 2.]])
h = matrix([8., 10., 2.])

solution = solvers.lp(c, G, h)
```

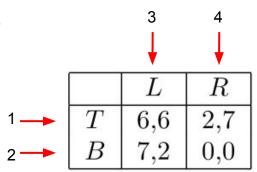
Just a small bit harder... The game of "chicken"

	L	R
T	6,6	2,7
B	7,2	0,0

The correlated equilibria in this game are described by the probability constraints $\pi_{TL} + \pi_{TR} + \pi_{BL} + \pi_{BR} = 1$ and $\pi_{TL}, \pi_{TR}, \pi_{BL}, \pi_{BR} \geq 0$ together with the following rationality constraints:

$$-1\pi_{TL} + 2\pi_{TR} \ge 0$$
 $-1\pi_{TL} + 2\pi_{BL} \ge 0$ $1\pi_{BL} - 2\pi_{BR} \ge 0$ $1\pi_{TR} - 2\pi_{BR} \ge 0$

Four Inequalities



The correlated equilibria in this game are described by the probability constraints $\pi_{TL} + \pi_{TR} + \pi_{BL} + \pi_{BR} = 1$ and $\pi_{TL}, \pi_{TR}, \pi_{BL}, \pi_{BR} \geq 0$ together with the following rationality constraints:

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 $-1\pi_{TL} + 2\pi_{BL} \ge 0$ $1\pi_{BL} - 2\pi_{BR} \ge 0$ $1\pi_{TR} - 2\pi_{BR} \ge 0$

Four Inequalities

Formula 1 Formula 3 $6\pi_{L|T} + 2\pi_{R|T} \ge 7\pi_{L|T} + 0\pi_{R|T}$ $-1\pi_{L|T} + 2\pi_{R|T} \ge 0$ $-1\pi_{TL} + 2\pi_{TR} \ge 0$ $-1\pi_{TL} + 2\pi_{R} \ge 0$ Formula 3 $6\pi_{T|L} + 2\pi_{B|L} \ge 7\pi_{T|L} + 0\pi_{B|L}$ $-1\pi_{T|L} + 2\pi_{B|L} \ge 0$ $-1\pi_{TL} + 2\pi_{BL} \ge 0$

note: $\pi_{xy} = \pi(x|y)\pi(y) = \pi(x \cap y) = \pi(y|x)\pi(x) = \pi_{yx}$

Four Inequalities, four variables: it is party time.

 $\pi_{TL} + \pi_{TR} + \pi_{BL} + \pi_{BR} = 1$ s.t.

$$-1\pi_{TL} + 2\pi_{TR} \ge 0$$

$$1\pi_{BL} - 2\pi_{BR} \ge 0$$

$$-1\pi_{TL} + 2\pi_{BL} \ge 0$$

$$1\pi_{TR} - 2\pi_{BR} \ge 0$$

 $x_1 = \pi_{TL}, \ x_2 = \pi_{TR}, \ x_3 = \pi_{BL}, \ x_4 = \pi_{BR}$

"Standard Form"?

$$1x_1 + 1x_2 + 1x_3 + 1x_4 = 1$$
 s.t.

$$-1x_1 + 2x_2 \ge 0$$
$$1x_3 - 2x_4 \ge 0$$

$$-1x_1 + 2x_3 \ge 0$$
$$1x_2 - 2x_4 \ge 0$$

"Standard Form"?

$$1x_1 + 1x_2 + 1x_3 + 1x_4 = 1$$
 s.t.

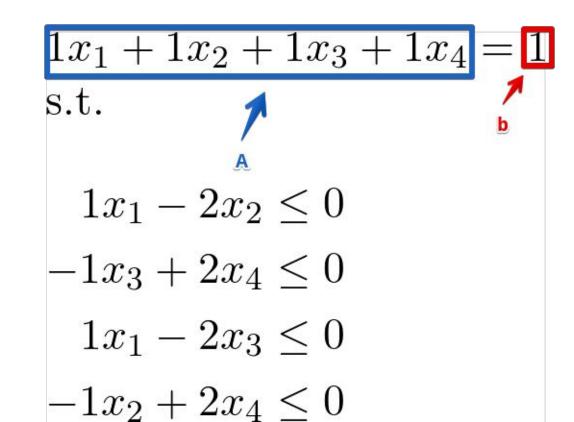
$$1x_1 - 2x_2 \le 0$$

$$-1x_3 + 2x_4 \le 0$$

$$1x_1 - 2x_3 \le 0$$

$$-1x_2 + 2x_4 \le 0$$

New parameters



Code

```
from cvxopt import matrix, solvers
c = matrix([1., 1., 1., 1.])
G = matrix([[1., 1., 0., 0.], [-2., 0., 0., -1.],
           [0., -2., -1., 0.], [0., 0., -2., -2.]])
h = matrix([0., 0., 0., 0.])
A = matrix([[1.], [1.], [1.], [1.])
b = matrix(1.)
solution = solvers.lp(c, G, h, A, b)
```

https://github.com/axonal/cvxopt-tutorial

Presentation and Code samples can be found at: