ALL CLASSES SEARCH: Search

SUMMARY: NESTED | FIELD | CONSTR | METHOD DETAIL: FIELD | CONSTR | METHOD

Package dev.robocode.tankroyale.botapi

# **Class BotState**

java.lang.Object dev.robocode.tankroyale.botapi.BotState

public final class BotState
extends java.lang.Object

Represents the current bot state.

# **Constructor Summary**

#### **Constructors**

Constructor	Description
BotState(boolean isDroid, double energy, double x, double y, double direction, double gunDirection, double radarDirection, double radarSweep, double speed, double turnRate, double gunTurnRate, double radarTurnRate, double gunHeat, int enemyCount, java.awt.Color bodyColor, java.awt.Color turretColor, java.awt.Color radarColor, java.awt.Color bulletColor, java.awt.Color scanColor, java.awt.Color tracksColor, java.awt.Color gunColor, boolean isDebuggingEnabled)	Initializes a new instance of the BotState class.

# **Method Summary**

# All Methods Instance Methods Concrete Methods

Modifier and Type	Method	Description
java.awt.Color	<pre>getBodyColor()</pre>	Returns the color the body.
java.awt.Color	<pre>getBulletColor()</pre>	Returns the color of the bullets when fired.
double	<pre>getDirection()</pre>	Returns the driving direction of the bot in degrees.

SUMMARY: NESTED | FIELD | CONSTR | METHOD DETAIL: FIELD | CONSTR | METHOD

java.awt.Color	getGunColor()	Returns the color of the gun.
double	<pre>getGunDirection()</pre>	Returns the gun direction of the bot in degrees.
double	getGunHeat()	Returns the gun heat.
double	<pre>getGunTurnRate()</pre>	Returns the turn rate of the gun in degrees per turn (can be positive and negative).
java.awt.Color	getRadarColor()	Returns the color of the radar.
double	<pre>getRadarDirection()</pre>	Returns the radar direction of the bot in degrees.
double	getRadarSweep()	Returns the radar sweep angle in degrees, i.e.
double	<pre>getRadarTurnRate()</pre>	Returns the turn rate of the radar in degrees per turn (can be positive and negative).
java.awt.Color	getScanColor()	Returns the color of the scan arc.
double	getSpeed()	Returns the speed measured in units per turn.
java.awt.Color	getTracksColor()	Returns the color of the tracks.
double	<pre>getTurnRate()</pre>	Returns the turn rate of the body in degrees per turn (can be positive and negative).
java.awt.Color	<pre>getTurretColor()</pre>	Returns the color of the gun turret.
double	getX()	Returns the X coordinate of the bot, which is in the center of the bot.
double	getY()	Returns the Y coordinate of the bot, which is in the center of the bot.
boolean	isDebuggingEnabled()	Checks if graphical debugging is enabled.
boolean	isDroid()	Checks if the bot is a droid or not.

# Methods inherited from class java.lang.Object

SUMMARY: NESTED | FIELD | CONSTR | METHOD DETAIL: FIELD | CONSTR | METHOD

# **Constructor Detail**

### **BotState**

```
public BotState(boolean isDroid,
                double energy,
                double x,
                double y,
                double direction,
                double gunDirection,
                double radarDirection,
                double radarSweep,
                double speed,
                double turnRate,
                double gunTurnRate,
                double radarTurnRate,
                double gunHeat,
                int enemyCount,
                java.awt.Color bodyColor,
                java.awt.Color turretColor,
                java.awt.Color radarColor,
                java.awt.Color bulletColor,
                java.awt.Color scanColor,
                java.awt.Color tracksColor,
                java.awt.Color gunColor,
                boolean isDebuggingEnabled)
```

Initializes a new instance of the BotState class.

# **Parameters:**

isDroid - is the flag specifying if the bot is a droid.
energy - is the energy level.
x - is the X coordinate.
y - is the Y coordinate.
direction - is the driving direction in degrees.
gunDirection - is the gun direction in degrees.
radarDirection - is the radar direction in degrees.
radarSweep - is the radar sweep angle in degrees.
speed - is the speed measured in units per turn.

SUMMARY: NESTED | FIELD | CONSTR | METHOD DETAIL: FIELD | CONSTR | METHOD gunneat - is the gun neat.

enemyCount - is the number of enemies left

bodyColor - is the body color.

turretColor - is the gun turret color.

radarColor - is the radar color.

bulletColor - is the bullet color.

scanColor - is the scan arc color.

tracksColor - is the tracks color.

gunColor - is the gun color.

isDebuggingEnabled - is a flag indicating if graphical debugging is enabled.

### Method Detail

#### isDroid

public boolean isDroid()

Checks if the bot is a droid or not.

#### Returns:

true if the bot is a droid; false otherwise.

#### getEnergy

public double getEnergy()

Returns the energy level of the bot. The energy level is typically starting at 100. The bot gains more energy when hitting other bots, and loses energy by getting hit and when spending energy on firing bullets. When the energy reaches 0, the bot becomes disabled and will not be able to take any new action. It might become active again, if one of its bullets hit another bot, meaning that the bot gains new energy.

# **Returns:**

The energy level.

SUMMARY: NESTED | FIELD | CONSTR | METHOD DETAIL: FIELD | CONSTR | METHOD

Returns the X coordinate of the bot, which is in the center of the bot.

#### **Returns:**

The X coordinate.

# getY

public double getY()

Returns the Y coordinate of the bot, which is in the center of the bot.

#### **Returns:**

The Y coordinate.

## getDirection

public double getDirection()

Returns the driving direction of the bot in degrees.

#### **Returns:**

The driving direction.

### getGunDirection

public double getGunDirection()

Returns the gun direction of the bot in degrees.

### **Returns:**

The gun direction.

# getRadarDirection

public double getRadarDirection()

Returns the radar direction of the bot in degrees.

SUMMARY: NESTED | FIELD | CONSTR | METHOD DETAIL: FIELD | CONSTR | METHOD

# getRadarSweep

public double getRadarSweep()

Returns the radar sweep angle in degrees, i.e. delta angle between previous and current radar direction.

#### **Returns:**

The radar sweep angle.

### getSpeed

public double getSpeed()

Returns the speed measured in units per turn.

#### **Returns:**

The speed.

# getTurnRate

public double getTurnRate()

Returns the turn rate of the body in degrees per turn (can be positive and negative).

#### **Returns:**

the turn rate.

# getGunTurnRate

public double getGunTurnRate()

Returns the turn rate of the gun in degrees per turn (can be positive and negative).

#### **Returns:**

the gun turn rate.

SUMMARY: NESTED | FIELD | CONSTR | METHOD DETAIL: FIELD | CONSTR | METHOD

### **Returns:**

the radar turn rate.

### getGunHeat

public double getGunHeat()

Returns the gun heat. When firing the gun, it will be heated up. The gun will need to cool down before it can fire another bullet. When the gun heat is zero, the gun will be able to fire again.

#### **Returns:**

The gun heat.

# getEnemyCount

public int getEnemyCount()

Returns the number of enemy bots left on the battlefield.

#### **Returns:**

the number of enemy bots left on the battlefield.

# getBodyColor

public java.awt.Color getBodyColor()

Returns the color the body.

#### **Returns:**

The color the body.

# getTurretColor

public java.awt.Color getTurretColor()

SUMMARY: NESTED | FIELD | CONSTR | METHOD DETAIL: FIELD | CONSTR | METHOD

# getRadarColor

public java.awt.Color getRadarColor()

Returns the color of the radar.

#### Returns:

The color of the radar.

# getBulletColor

public java.awt.Color getBulletColor()

Returns the color of the bullets when fired.

#### Returns:

The color of the bullets when fired.

# getScanColor

public java.awt.Color getScanColor()

Returns the color of the scan arc.

#### **Returns:**

The color of the scan arc.

# getTracksColor

public java.awt.Color getTracksColor()

Returns the color of the tracks.

### **Returns:**

The color of the tracks.

SUMMARY: NESTED | FIELD | CONSTR | METHOD DETAIL: FIELD | CONSTR | METHOD

### **Returns:**

The color of the gun.

# **isDebuggingEnabled**

public boolean isDebuggingEnabled()

Checks if graphical debugging is enabled.

#### Returns:

true if graphical debugging is enabled; false otherwise.

OVERVIEW PACKAGE CLASS TREE DEPRECATED INDEX HELP

### **ALL CLASSES**

SUMMARY: NESTED | FIELD | CONSTR | METHOD DETAIL: FIELD | CONSTR | METHOD