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#### Introduction and functional overview:

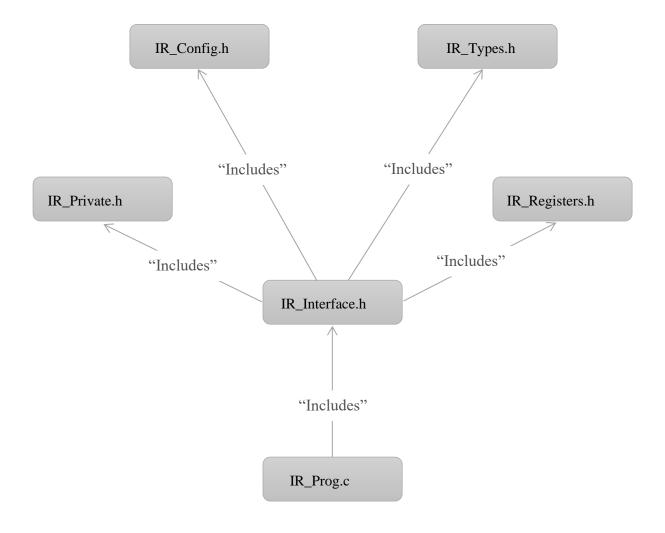
This document specifies detailed design of the module e IR Driver. The IR driver is targeting IR (Infra-Red) sensor Hardware.

The IR driver provides service for detecting objects.

The behaviour of those services is synchronous.

#### File structure:

The LM35 module shall comply with the following file structure:



# **Requirements traceability:**

Requirement	Description	Satisfied by
[SRS_IR_6101]	The IR Driver shall support symbolic names for	[DD_IR_6101]
	IR channels.	[DD_IR_6102]
		[DD_IR_6103]
		[DD_IR_6104]
		[DD_IR_6105]
		[DD_IR_6106]
[SRS_IR_6102]	The IR driver shall provide a service that initializes the IR.	[DD_IR_6107]
[SRS_IR_6103]	The IR driver shall provide a service that reads the IR signal.	[DD_IR_6108]

# **API specification:** Type definitions:

#### 1- [DD\_IR\_6101]

Name:	IR_SENSOR_PIN	
Туре	Macro	
Range:	07	
<b>Description:</b>	The pin connected to IR sensor	
<b>Covered requirements:</b>	[SRS_IR_6101]	

#### 2- [DD\_IR\_6102]

Name:	IR_PORT	
Туре	Macro	
Range:	DIO_PORTA DIO_PORTD	
<b>Description:</b>	The port register that contains the IR pin	
<b>Covered requirements:</b>	[SRS_IR_6101]	

#### 3- [DD\_IR\_6103]

Name:	IR_DDR	
Туре	Macro	
Range:	DIO_DDRADIO_DDRD	
<b>Description:</b>	The DDR register that contains the IR pin	
<b>Covered requirements:</b>	[SRS_IR_6101]	

#### 4- [DD\_IR\_6104]

Name:	IR_PIN	
Туре	Macro	
Range:	DIO_PINADIO_PIND	
<b>Description:</b>	The PIN register that contains the IR pin	
<b>Covered requirements:</b>	[SRS_IR_6101]	

#### 5- [DD\_IR\_6105]

Name:	DETECTED
Туре	Macro
Range:	1
<b>Description:</b>	Value for the IR signal that indicates that an object is detected
<b>Covered requirements:</b>	[SRS_IR_6101]

#### 6- [DD\_IR\_6106]

Name:	NOT_DETECTED
Туре	Macro
Range:	0
<b>Description:</b>	Value for the IR signal that indicates that nothing is detected
<b>Covered requirements:</b>	[SRS_IR_6101]

## **Function definitions:**

## 1- [DD\_IR\_6107]

Service name:	Initialize the IR sensor		
Syntax:	void HAL_IR_Init()		
Sync/Async:	ynchronous		
Re-entrancy:	Re-entrant		
Parameters (in):	none		
Parameters (out):	none		
Parameters (inout):	none		
Return type:	void		
<b>Description:</b>	Function that initializes the IR sensor		
<b>Covered requirements:</b>	[SRS_IR_6102]		

## 2- [DD\_IR\_6108]

Service name:	Read the IR sensor's state		
Syntax:	unsigned char HAL_IR_Read()		
Sync/Async:	Synchronous		
Re-entrancy:	Re-entrant		
Parameters (in):	none		
Parameters (out):	none		
Parameters (inout):	none		
Return type:	Unsigned char	DETECTED 1 NOT_DETECTED 0	
<b>Description:</b>	Function that reads the IR sensor's signal		
<b>Covered requirements:</b>	[SRS_IR_6103]		