

# **Detailed Design of RTC Driver**

**Team X**

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## Introduction and functional overview

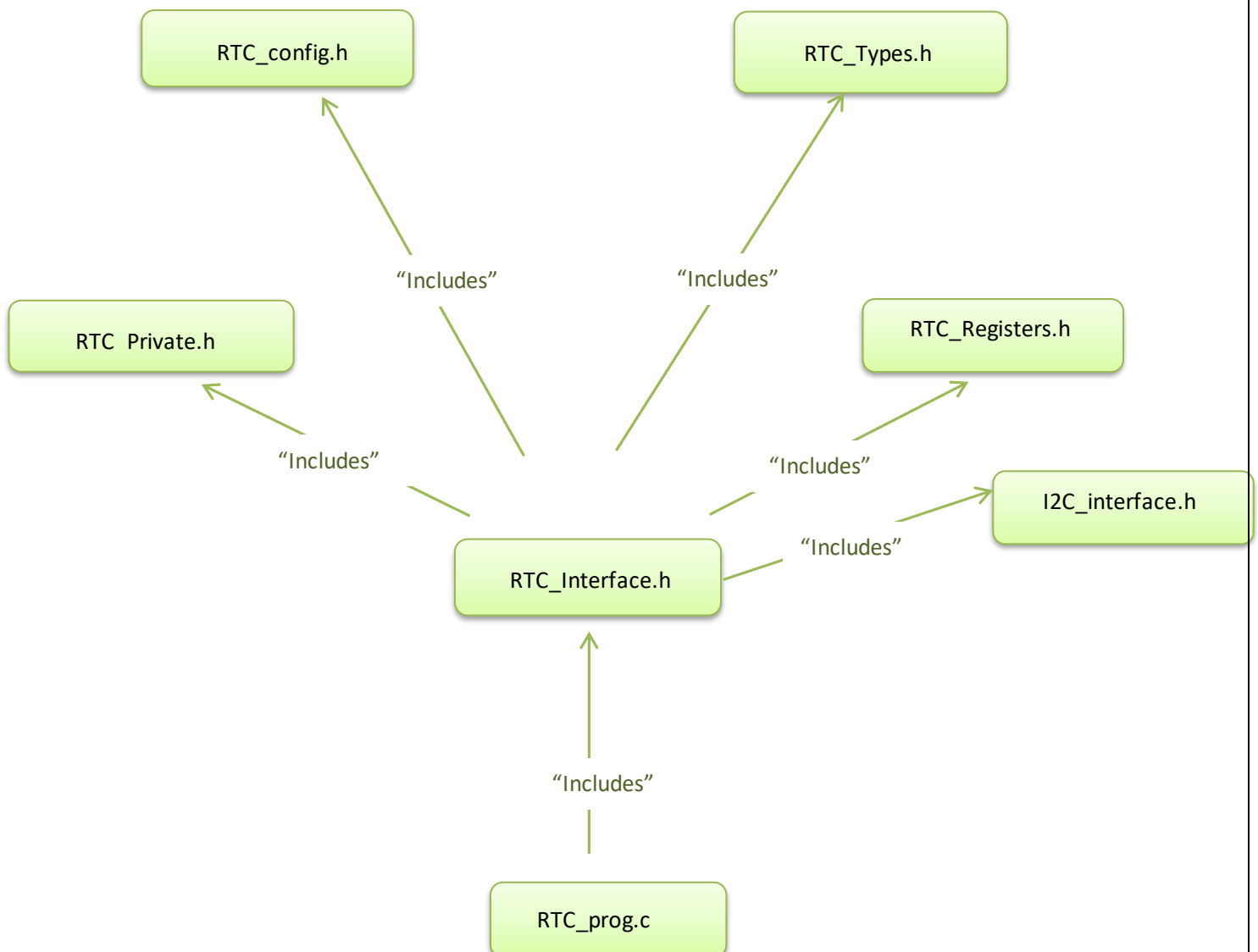
This document specifies the detailed design of RTC module.

The RTC driver controls clock & calendar.

## Dependencies to other modules

I2C driver as the RTC communicate with the microcontroller through I2C bus

## File Structure



**Requirement's traceability**

Requirement	Description	Satisfied by
[SRS_RTC_4500]	The RTC Driver shall support symbolic names of RTC Time	[DD_RTC_5600]
[SRS_RTC_4501]	The RTC Driver shall support symbolic names of RTC Date	[DD_RTC_5601]
[SRS_RTC_4502]	The RTC Driver shall provide a service to initialize the RTC Module	[DD_RTC_5602]
[SRS_RTC_4503]	The RTC Driver shall provide a service to read Time	[DD_RTC_5603]
[SRS_RTC_4504]	The RTC Driver shall provide a service to read calendar	[DD_RTC_5604]
[SRS_RTC_4505]	The RTC Driver shall provide a service to set Time	[DD_RTC_5605]
[SRS_RTC_4506]	The RTC Driver shall provide a service to set Calendar	[DD_RTC_5606]
[SRS_RTC_4507]	The RTC Driver shall provide a service to check if it's pm or am	[DD_RTC_5607]

## API specification

Type definitions:

1- [DD\_RTC\_5600]

<b>Name</b>	S_Time
<b>type</b>	Structure
<b>Range</b>	--
<b>Description</b>	It contains the RTC Time such as hours, mins, seconds
<b>Covered requirements</b>	--

2-[DD\_RTC\_5601]

<b>Name</b>	S_Date
<b>type</b>	Structure
<b>Range</b>	--
<b>Description</b>	It contains the RTC data such as day, month, year
<b>Covered requirements</b>	--

Function definitions:

1-[DD\_RTC\_5602]

<b>Service name:</b>	RTC Init
<b>Syntax:</b>	E_ErrorType HAL_RTC_Init(void)
<b>Sync/Async:</b>	Synchronous
<b>Re-entrancy:</b>	Re-entrant
<b>Parameters (in):</b>	--
<b>Parameters (out):</b>	--
<b>Parameters (inout):</b>	--
<b>Return type:</b>	E_ErrorType
<b>Description:</b>	It changes the status of RTC to be Initialized
<b>Covered requirements:</b>	Displays Date and time for user

## 2-[DD\_RTC\_5603]

<b>Service name:</b>	RTC_Read_Time
<b>Syntax:</b>	E_ErrorType HAL_RTC_ReadTime(char *Time)
<b>Sync/Async:</b>	Synchronous
<b>Re-entrancy:</b>	Re-entrant
<b>Parameters (in):</b>	Pointer to array of characters
<b>Parameters (out):</b>	Time
<b>Parameters (inout):</b>	--
<b>Return type:</b>	E_ErrorType
<b>Description:</b>	It read the real time and store it in the parameter in
<b>Covered requirements:</b>	Get the Time

## 3-[DD\_RTC\_5604]

<b>Service name:</b>	RTC_Read_Calender
<b>Syntax:</b>	E_ErrorType HAL_RTC_ReadDate(char *Date)
<b>Sync/Async:</b>	Synchronous
<b>Re-entrancy:</b>	Re-entrant
<b>Parameters (in):</b>	Pointer to array of characters
<b>Parameters (out):</b>	Date
<b>Parameters (inout):</b>	--
<b>Return type:</b>	E_ErrorType
<b>Description:</b>	It read the current and store it in the parameter in
<b>Covered requirements:</b>	Get the Date

## 4-[DD\_RTC\_5605]

<b>Service name:</b>	RTC_Set_Time
<b>Syntax:</b>	E_ErrorType HAL_RTC_SetTime(void)

<b>Sync/Async:</b>	Synchronous
<b>Re-entrancy:</b>	Re-entrant
<b>Parameters (in):</b>	--
<b>Parameters (out):</b>	--
<b>Parameters (inout):</b>	--
<b>Return type:</b>	E_ErrorType
<b>Description:</b>	It sets the Time based on the user requirements
<b>Covered requirements:</b>	Set the Date

## 5-[DD\_RTC\_5606]

<b>Service name:</b>	RTC_Set_Date
<b>Syntax:</b>	E_ErrorType HAL_RTC_SetDate(void)
<b>Sync/Async:</b>	Synchronous
<b>Re-entrancy:</b>	Re-entrant
<b>Parameters (in):</b>	--
<b>Parameters (out):</b>	--
<b>Parameters (inout):</b>	--
<b>Return type:</b>	E_ErrorType
<b>Description:</b>	It sets the Date based on the user requirements
<b>Covered requirements:</b>	Set the Date

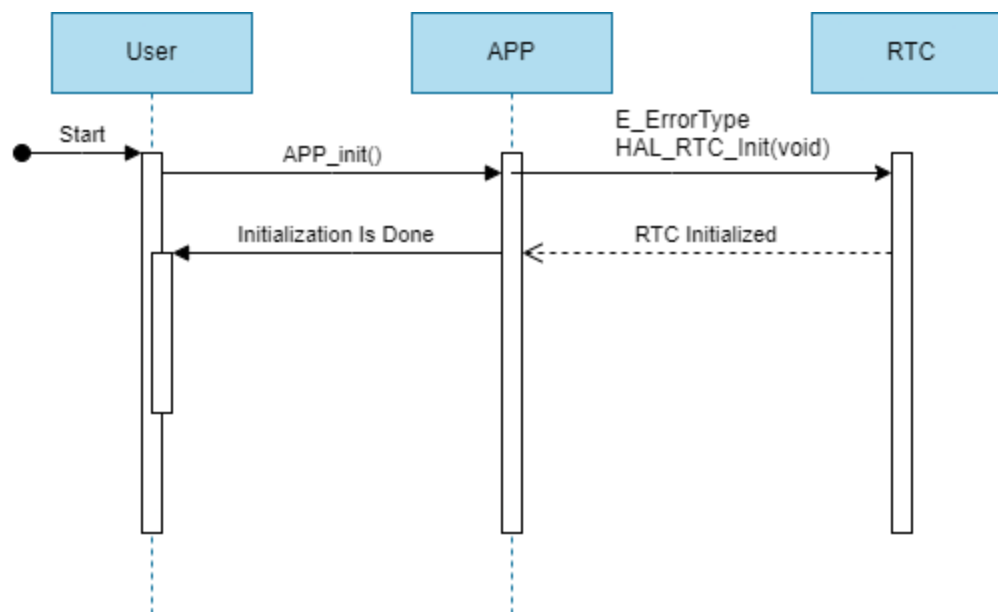
## 6-[DD\_RTC\_5607]

<b>Service name:</b>	RTC_Check
<b>Syntax:</b>	E_ErrorType HAL_RTC_Check(Boolean check)
<b>Sync/Async:</b>	Synchronous
<b>Re-entrancy:</b>	Re-entrant
<b>Parameters (in):</b>	Boolean flag
<b>Parameters (out):</b>	--
<b>Parameters (inout):</b>	--

<b>Return type:</b>	E_ErrorType
<b>Description:</b>	It checks if the current moment PM or AM
<b>Covered requirements:</b>	--

## Sequence Diagrams

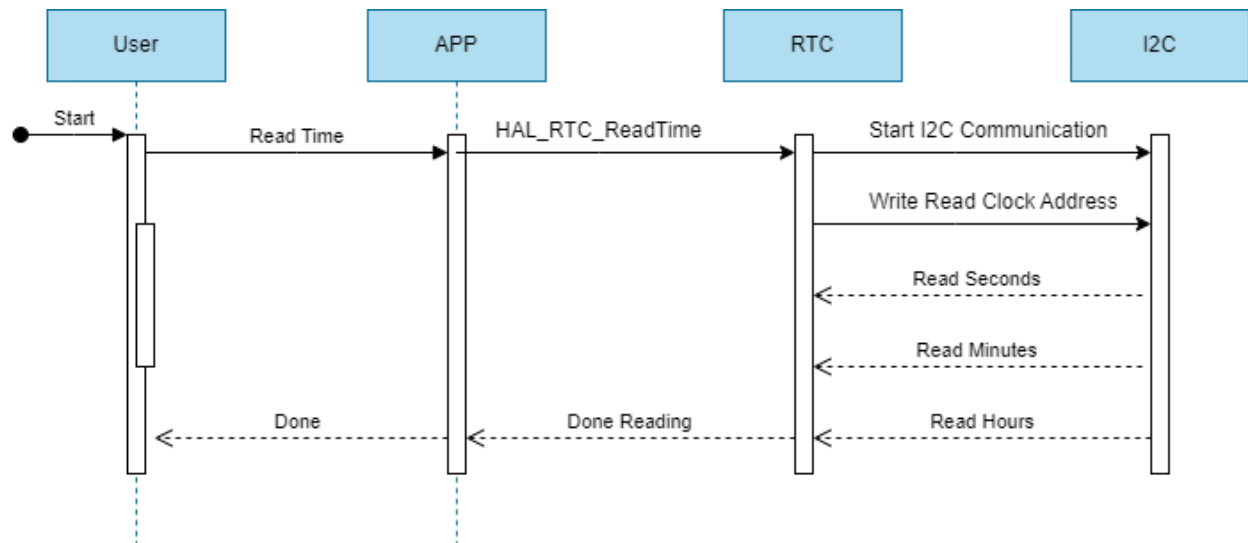
### RTC Initialization



When user initialize the application, it initializes the RTC module by change its status to initialized as indication to start the module.

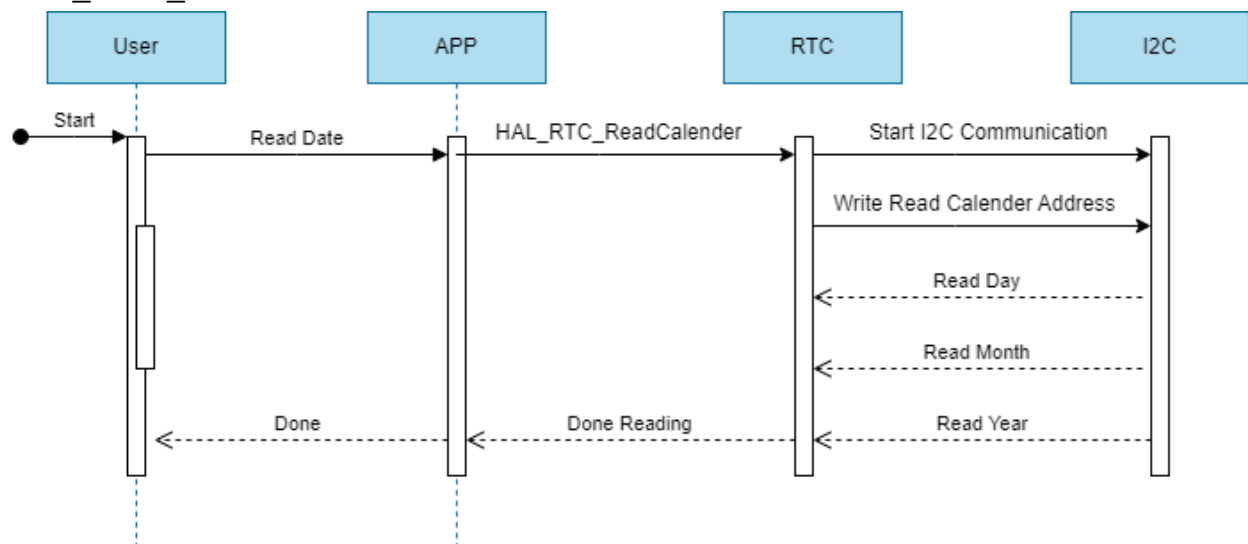


## RTC\_Read\_Time



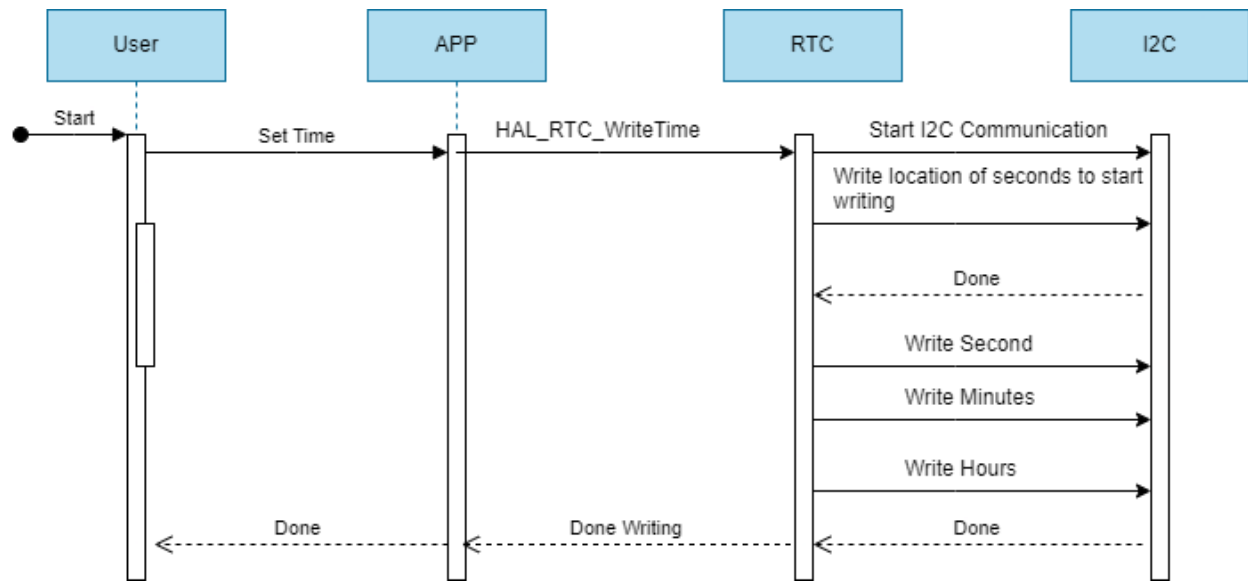
When user want to get the current time, the application calls the RTC module to get its time data then it communicates with the I2C with the read clock address then fetch seconds, minutes, hours simultaneously.

## RTC\_Read\_Date



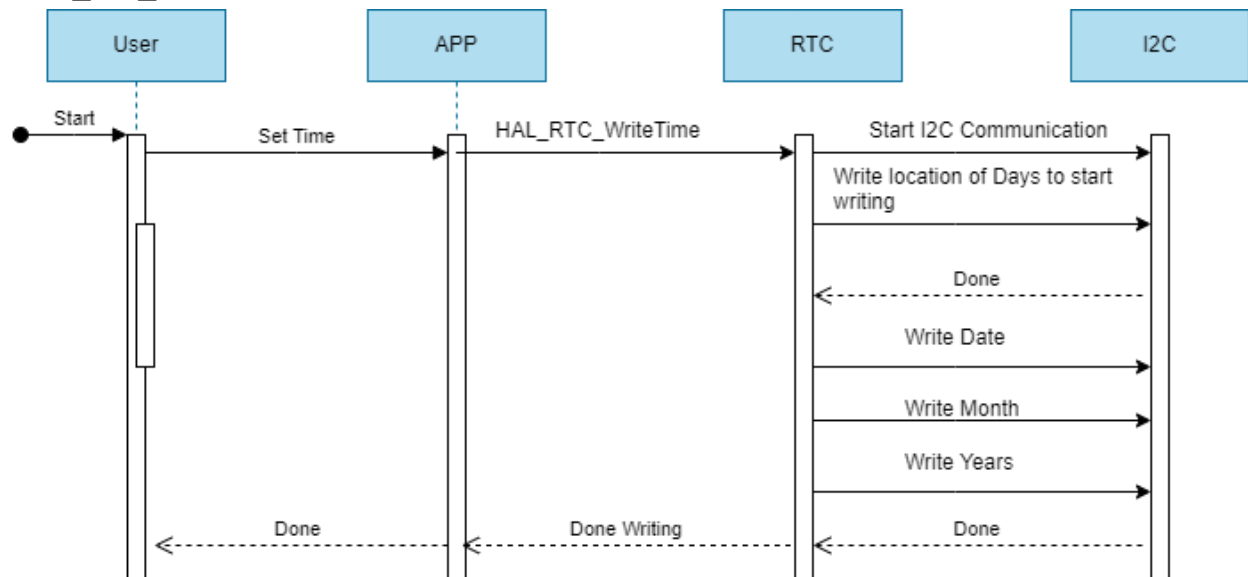
When user wants to get the current date, the application calls the RTC module to get its date by communicating the I2C bus with the specific address then fetch day, month, year simultaneously.

## RTC\_Set\_Time



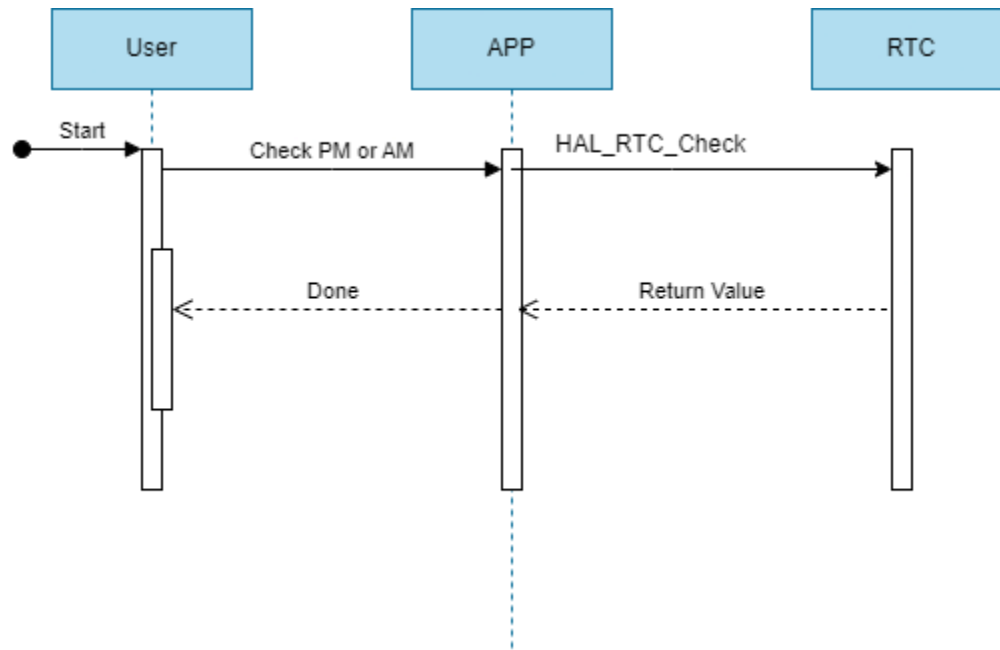
When user wants to sets the time, the application calls RTC module with the desired data, then it communicates using I2C bus to write these Data.

## RTC\_Set\_Date



When user wants to sets the date, the application calls RTC module with the desired data, then it communicates using I2C bus to write these Data.

## RTC\_Check



When user wants to check weather if it's PM or AM, the application calls the RTC module to give him the check