CS162
Operating Systems and Systems Programming
Lecture 5

Abstractions 3: Files and I/O (cont'd), Sockets and IPC

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  - Memory and storage systems
  - Distributed systems

Low-Level vs High-Level file API

- Low-level direct use of syscall interface: `open(), read(), write(), close()`
- Opening of file returns file descriptor:
  `int myfile = open(…);`
- File descriptor only meaningful to kernel
  – Index into process (PCB) which holds pointers to kernel-level structure ("file description") describing file.
- Every `read()` or `write()` causes syscall no matter how small (could read a single byte)
- Consider loop to get 4 bytes at a time using `read()`:
  – Each iteration enters kernel for 4 bytes.

- High-level buffered access: `fopen(), fread(), fwrite(), fclose()`
- Opening of file returns ptr to FILE:
  `FILE *myfile = fopen(…);`
- FILE structure is user space contains:
  – a chunk of memory for a buffer
  – the file descriptor for the file (`fopen()` will call `open()` automatically)
- Every `fread()` or `fwrite()` filters through buffer and may not call `read()` or `write()` on every call.
- Consider loop to get 4 bytes at a time using `fread()`:
  – First call to `fread()` calls `read()` for block of bytes (say 1024). Puts in buffer and returns first 4 to user.
  – Subsequent `fread()` grab bytes from buffer

Low-Level vs. High-Level File API

Low-Level Operation:

```
ssize_t read(…) {

    asm code … syscall # into %eax
    put args into registers %ebx, …
    special trap instruction
        Kernel:
          get args from regs
          dispatch to system func
          Do the work to read from the file
          Store return value in %eax
    get return values from regs

  Return data to caller

};
```

High-Level Operation:

```
ssize_t fread(…) {
  Check buffer for contents
  Return data to caller if available
    asm code … syscall # into %eax
    put args into registers %ebx, …
    special trap instruction
        Kernel:
          get args from regs
          dispatch to system func
          Do the work to read from the file
          Store return value in %eax
    get return values from regs
  Update buffer with excess data
  Return data to caller
};
```

High-Level vs. Low-Level File API

- Streams are buffered in user memory:

```
printf("Beginning of line ");
sleep(10); // sleep for 10 seconds
printf("and end of line\n");
```

  Prints out everything at once

- Operations on file descriptors are visible immediately

```
write(STDOUT_FILENO, "Beginning of line ", 18);
sleep(10);
write("and end of line \n", 16);
```

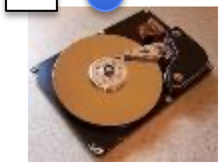
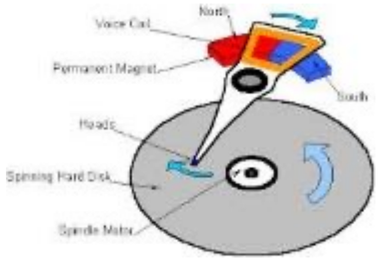
  Outputs "Beginning of line" 10 seconds earlier than "and end of line"

What's below the surface ??

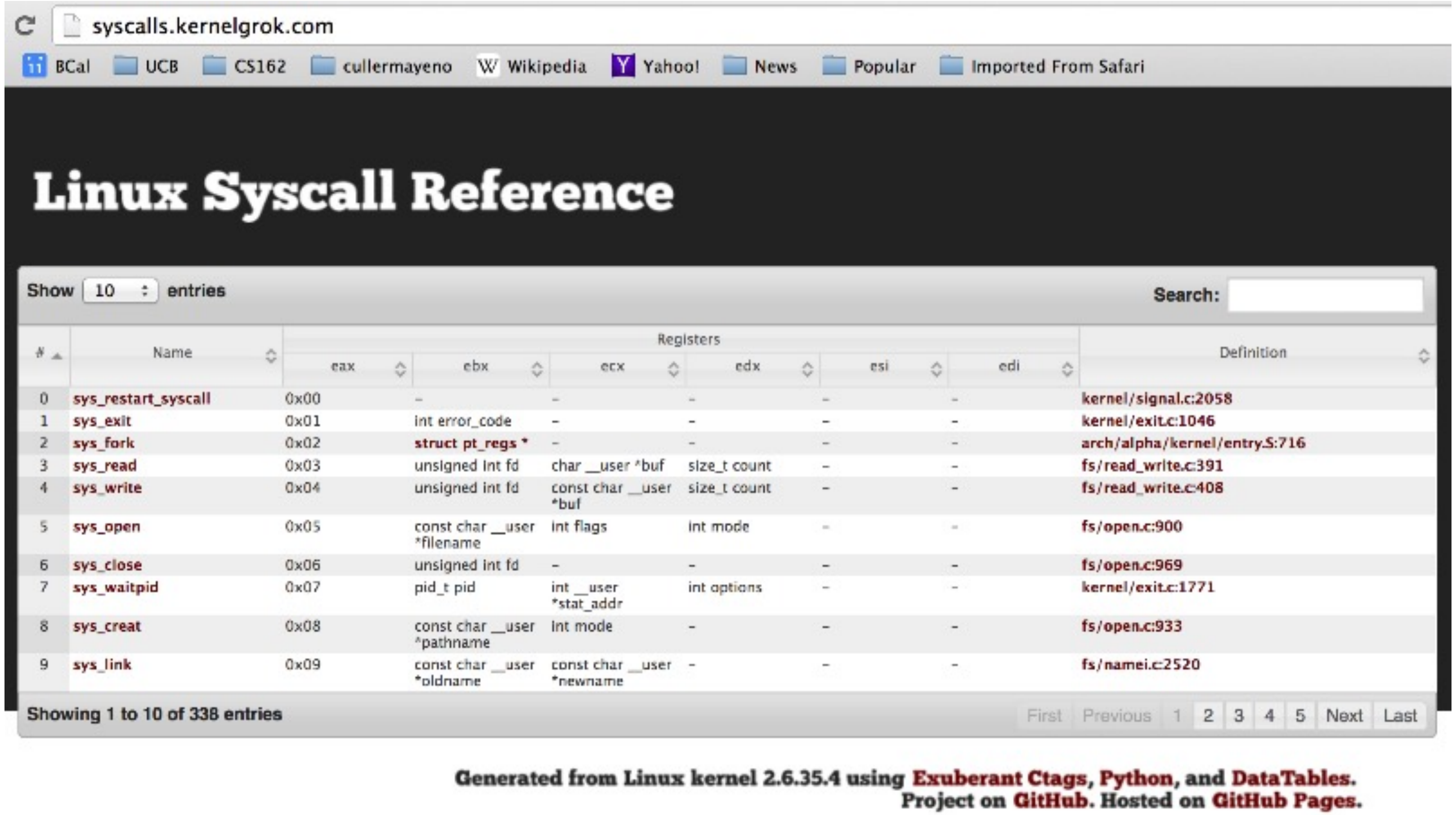
Application / Service

High Level I/O	streams
Low Level I/O	handles
Syscall	registers
File System	descriptions
I/O Driver	Commands and Data Transfers
	Disks, Flash, Controllers, DMA



Recall: SYSCALL


syscalls.kernelgrok.com

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Linux Syscall Reference

Show 10 entries Search:

#	Name	Registers						Definition
		eax	ebx	ecx	edx	esi	edi	
0	sys_restart_syscall	0x00	-	-	-	-	-	kernel/signal.c:2058
1	sys_exit	0x01	int error_code	-	-	-	-	kernel/exit.c:1046
2	sys_fork	0x02	struct pt_regs *	-	-	-	-	arch/alpha/kernel/entry.S:716
3	sys_read	0x03	unsigned int fd	char __user *buf	size_t count	-	-	fs/read_write.c:391
4	sys_write	0x04	unsigned int fd	const char __user *buf	size_t count	-	-	fs/read_write.c:408
5	sys_open	0x05	const char __user *filename	int flags	int mode	-	-	fs/open.c:900
6	sys_close	0x06	unsigned int fd	-	-	-	-	fs/open.c:969
7	sys_waitpid	0x07	pid_t pid	int __user *stat_addr	int options	-	-	kernel/exit.c:1771
8	sys_creat	0x08	const char __user *pathname	int mode	-	-	-	fs/open.c:933
9	sys_link	0x09	const char __user *oldname	const char __user *newname	-	-	-	fs/namei.c:2520

Showing 1 to 10 of 338 entries First Previous 1 2 3 4 5 Next Last

Generated from Linux kernel 2.6.35.4 using Exuberant Ctags, Python, and DataTables.
Project on GitHub. Hosted on GitHub Pages.

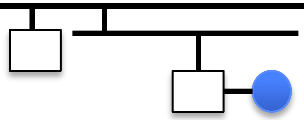
- Low level lib parameters are set up in registers and syscall instruction is issued
  - A type of synchronous exception that enters well-defined entry points into kernel

What's below the surface ??

File descriptor number
- an int

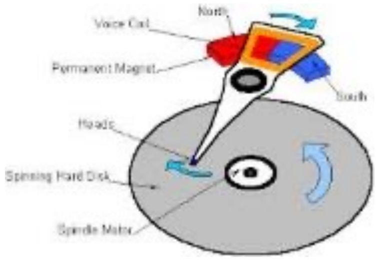
Application / Service

High Level I/O	streams
Low Level I/O	handles
Syscall	registers
File System	descriptions
I/O Driver	Commands and Data Transfers



Disks, Flash, Controllers, DMA

File description
- a struct with all the info about the files

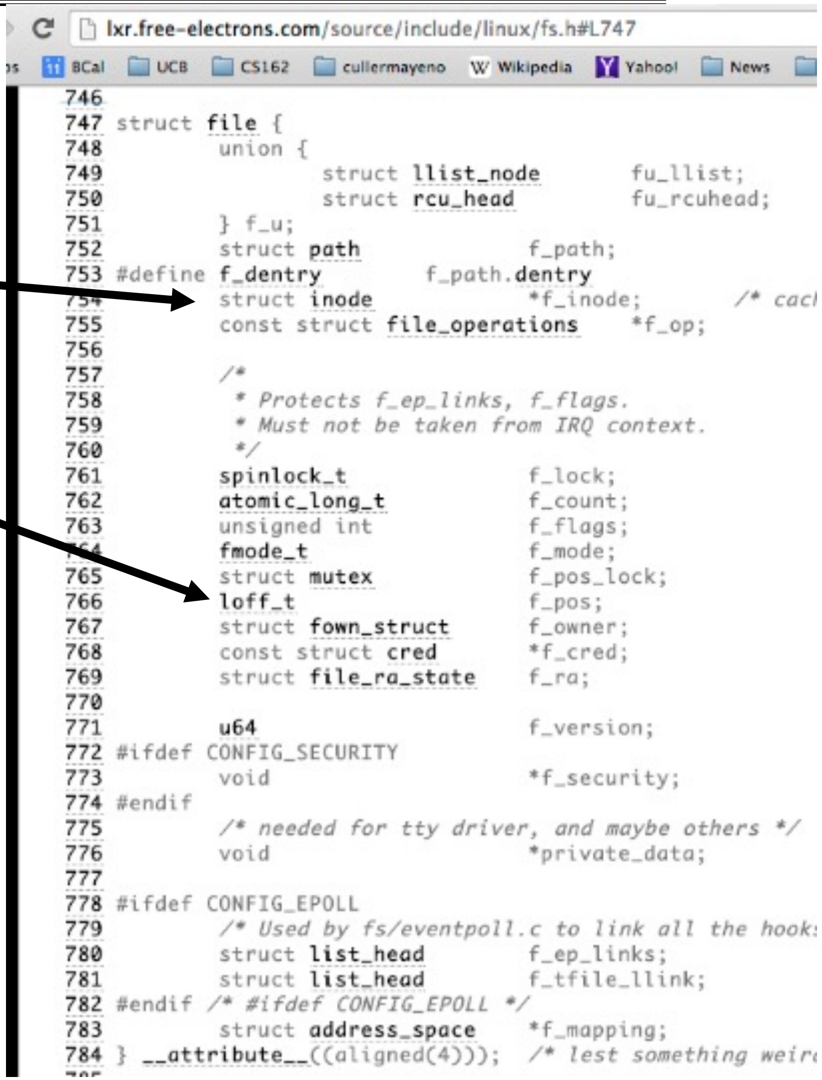


What's in an Open File Description?

Inside Kernel!

For our purposes, the two most important things are:

- Where to find the file data on disk
- The current position within the file




```
struct file {
        union {
                struct llist_node       fu_llist;
                struct rcu_head         fu_rcuhead;
        } f_u;
        struct path             f_path;
#define f_dentry        f_path.dentry
        struct inode            *f_inode;       /* cac
        const struct file_operations    *f_op;

        /*
         * Protects f_ep_links, f_flags.
         * Must not be taken from IRQ context.
         */
        spinlock_t              f_lock;
        atomic_long_t           f_count;
        unsigned int            f_flags;
        fmode_t                 f_mode;
        struct mutex            f_pos_lock;
        loff_t                  f_pos;
        struct fown_struct      f_owner;
        const struct cred       *f_cred;
        struct file_ra_state    f_ra;

        u64                     f_version;
#ifdef CONFIG_SECURITY
        void                    *f_security;
#endif
        /* needed for tty driver, and maybe others */
        void                    *private_data;

#ifdef CONFIG_EPOLL
        /* Used by fs/eventpoll.c to link all the hook
        struct list_head        f_ep_links;
        struct list_head        f_tfile_llink;
#endif /* #ifdef CONFIG_EPOLL */
        struct address_space    *f_mapping;
} __attribute__((aligned(4)));  /* lest something weir
```

File System: from syscall to driver

In `fs/read_write.c`

```
ssize_t vfs_read(struct file *file, char __user *buf, size_t count, loff_t *pos)
{
  ssize_t ret;
  if (!(file->f_mode & FMODE_READ)) return
  if (!file->f_op || (!file->f_op->read &&
    return -EINVAL;
  if (unlikely(!access_ok(VERIFY_WRITE, bu
  ret = rw_verify_area(READ, file, pos, count);
  if (ret >= 0) {
    count = ret;
    if (file->f_op->read)
      ret = file->f_op->read(file, buf, count, pos);
    else
      ret = do_sync_read(file, buf, count, pos);
    if (ret > 0) {
      fsnotify_access(file->f_path.dentry);
      add_rchar(current, ret);
    }
    inc_syscr(current);
  }
  return ret;
}
```

- Read up to “count” bytes from “file” starting from “pos” into “buf”.
- Return error or number of bytes read.

File System: from syscall to driver

In `fs/read_write.c`

```
ssize_t vfs_read(struct file *file, char __user *buf, size_t count, loff_t *pos)
{
  ssize_t ret;
  if (!(file->f_mode & FMODE_READ)) return -EBADF;
  if (!file->f_op || (!file->f_op->read && !file->f_op->aio_read))
    return -EINVAL;
  if (unlikely(!access_ok(VERIFY_WRITE, buf, count))) ret
  ret = rw_verify_area(READ, file, pos, count);
  if (ret >= 0) {
    count = ret;
    if (file->f_op->read)
      ret = file->f_op->read(file, buf, count, pos);
    else
      ret = do_sync_read(file, buf, count, pos);
    if (ret > 0) {
      fsnotify_access(file->f_path.dentry);
      add_rchar(current, ret);
    }
    inc_syscr(current);
  }
  return ret;
}
```

Make sure we are allowed to read this file

File System: from syscall to driver

In `fs/read_write.c`

```
ssize_t vfs_read(struct file *file, char __user *buf, size_t count, loff_t *pos)
{
  ssize_t ret;
  if (!(file->f_mode & FMODE_READ)) return -EBADF;
  if (!file->f_op || (!file->f_op->read && !file->f_op->aio_read))
    return -EINVAL;
  if (unlikely(!access_ok(VERIFY_WRITE, buf, count))) return -EFAULT;
  ret = rw_verify_area(READ, file, pos, count);
  if (ret >= 0) {
    count = ret;
    if (file->f_op->read)
      ret = file->f_op->read(file, buf, count, pos);
    else
      ret = do_sync_read(file, buf, count, pos);
    if (ret > 0) {
      fsnotify_access(file->f_path.dentry);
      add_rchar(current, ret);
    }
    inc_syscr(current);
  }
  return ret;
}
```

Check if file has read methods

File System: from syscall to driver

In fs/read_write.c

```
ssize_t vfs_read(struct file *file, char __user *buf, size_t count, loff_t *pos)
{
  ssize_t ret;
  if (!(file->f_mode & FMODE_READ)) return -EBADF;
  if (!file->f_op || (!file->f_op->read && !file->f_op->aio_read))
    return -EINVAL;
  if (unlikely(!access_ok(VERIFY_WRITE, buf, count))) return -EFAULT;
  ret = rw_verify_area(READ, file, pos, count);
  if (ret >= 0) {
    count = ret;
    if (file->f_op->read)
      ret = file->f_op->read(file, buf, c
    else
      ret = do_sync_read(file, buf, count
    if (ret > 0) {
      fsnotify_access(file->f_path.dentry);
      add_rchar(current, ret);
    }
    inc_syscr(current);
  }
  return ret;
}
```

- Check whether we can write to buf (e.g., buf is in the user space range)
- unlikely(): hint to branch prediction this condition is unlikely

File System: from syscall to driver

In `fs/read_write.c`

```
ssize_t vfs_read(struct file *file, char __user *buf, size_t count, loff_t *pos)
{
  ssize_t ret;
  if (!(file->f_mode & FMODE_READ)) return -EBADF;
  if (!file->f_op || (!file->f_op->read && !file->f_op->aio_read))
    return -EINVAL;
  if (unlikely(!access_ok(VERIFY_WRITE, buf, count))) return -EFAULT;
  ret = rw_verify_area(READ, file, pos, count);
  if (ret >= 0) {
    count = ret;
    if (file->f_op->read)
      ret = file->f_op->read(file, buf, count, po
    else
      ret = do_sync_read(file, buf, count, pos);
    if (ret > 0) {
      fsnotify_access(file->f_path.dentry);
      add_rchar(current, ret);
    }
    inc_syscr(current);
  }
  return ret;
}
```

Check whether we read from a valid range in the file.

File System: from syscall to driver

In `fs/read_write.c`

```
ssize_t vfs_read(struct file *file, char __user *buf, size_t count, loff_t *pos)
{
  ssize_t ret;
  if (!(file->f_mode & FMODE_READ)) return -EBADF;
  if (!file->f_op || (!file->f_op->read && !file->f_op->aio_read))
    return -EINVAL;
  if (unlikely(!access_ok(VERIFY_WRITE, buf, count))) return -EFAULT;
  ret = rw_verify_area(READ, file, pos, count);
  if (ret >= 0) {
    count = ret;
    if (file->f_op->read)
      ret = file->f_op->read(file, buf, count, pos);
    else
      ret = do_sync_read(file, buf, count, pos);
    if (ret > 0) {
      fsnotify_access(file->f_path.dentry);
      add_rchar(current, ret);
    }
    inc_syscr(current);
  }
  return ret;
}
```

If driver provide a read function (f_op->read) use it; otherwise use do_sync_read()

File System: from syscall to driver

In `fs/read_write.c`

```
ssize_t vfs_read(struct file *file, char __user *buf, size_t count, loff_t *pos)
{
  ssize_t ret;
  if (!(file->f_mode & FMODE_READ)) return -EBADF;
  if (!file->f_op || (!file->f_op->read && !file->f_op->aio_read))
    return -EINVAL;
  if (unlikely(!access_ok(VERIFY_WRITE, buf, count))) return -EFAULT;
  ret = rw_verify_area(READ, file, pos, count);
  if (ret >= 0) {
    count = ret;
    if (file->f_op->read)
      ret = file->f_op->re
    else
      ret = do_sync_read(file, buf, count, pos);
    if (ret > 0) {
      fsnotify_access(file->f_path.dentry);
      add_rchar(current, ret);
    }
    inc_syscr(current);
  }
  return ret;
}
```

Notify the parent of this file that the file was read (see http://www.fieldses.org/~bfields/kernel/vfs.txt)

File System: from syscall to driver

In `fs/read_write.c`

```
ssize_t vfs_read(struct file *file, char __user *buf, size_t count, loff_t *pos)
{
  ssize_t ret;
  if (!(file->f_mode & FMODE_READ)) return -EBADF;
  if (!file->f_op || (!file->f_op->read && !file->f_op->aio_read))
    return -EINVAL;
  if (unlikely(!access_ok(VERIFY_WRITE, buf, count))) return -EFAULT;
  ret = rw_verify_area(READ, file, pos, count);
  if (ret >= 0) {
    count = ret;
    if (file->f_op->read)
      ret = file->f_op->read(file, buf, count, pos);
    else
      ret = do_sync_read(file, buf, count, pos);
    if (ret > 0) {
      fsnotify_access(file->f_path.dentry);
      add_rchar(current, ret);
    }
    inc_syscr(current);
  }
  return ret;
}
```

Update the number of bytes read by "current" task (for scheduling purposes)

File System: from syscall to driver

In fs/read_write.c

```
ssize_t vfs_read(struct file *file, char __user *buf, size_t count, loff_t *pos)
{
  ssize_t ret;
  if (!(file->f_mode & FMODE_READ)) return -EBADF;
  if (!file->f_op || (!file->f_op->read && !file->f_op->aio_read))
    return -EINVAL;
  if (unlikely(!access_ok(VERIFY_WRITE, buf, count))) return -EFAULT;
  ret = rw_verify_area(READ, file, pos, count);
  if (ret >= 0) {
    count = ret;
    if (file->f_op->read)
      ret = file->f_op->read(file, buf, count, pos);
    else
      ret = do_sync_read(file, buf, count, pos);
    if (ret > 0) {
      fsnotify_access(file->f_path.dentry);
      add_rchar(current, ret);
    }
    inc_syscr(current);
  }
  return ret;
}
```

Update the number of read syscalls by "current" task (for scheduling purposes)

Device Drivers

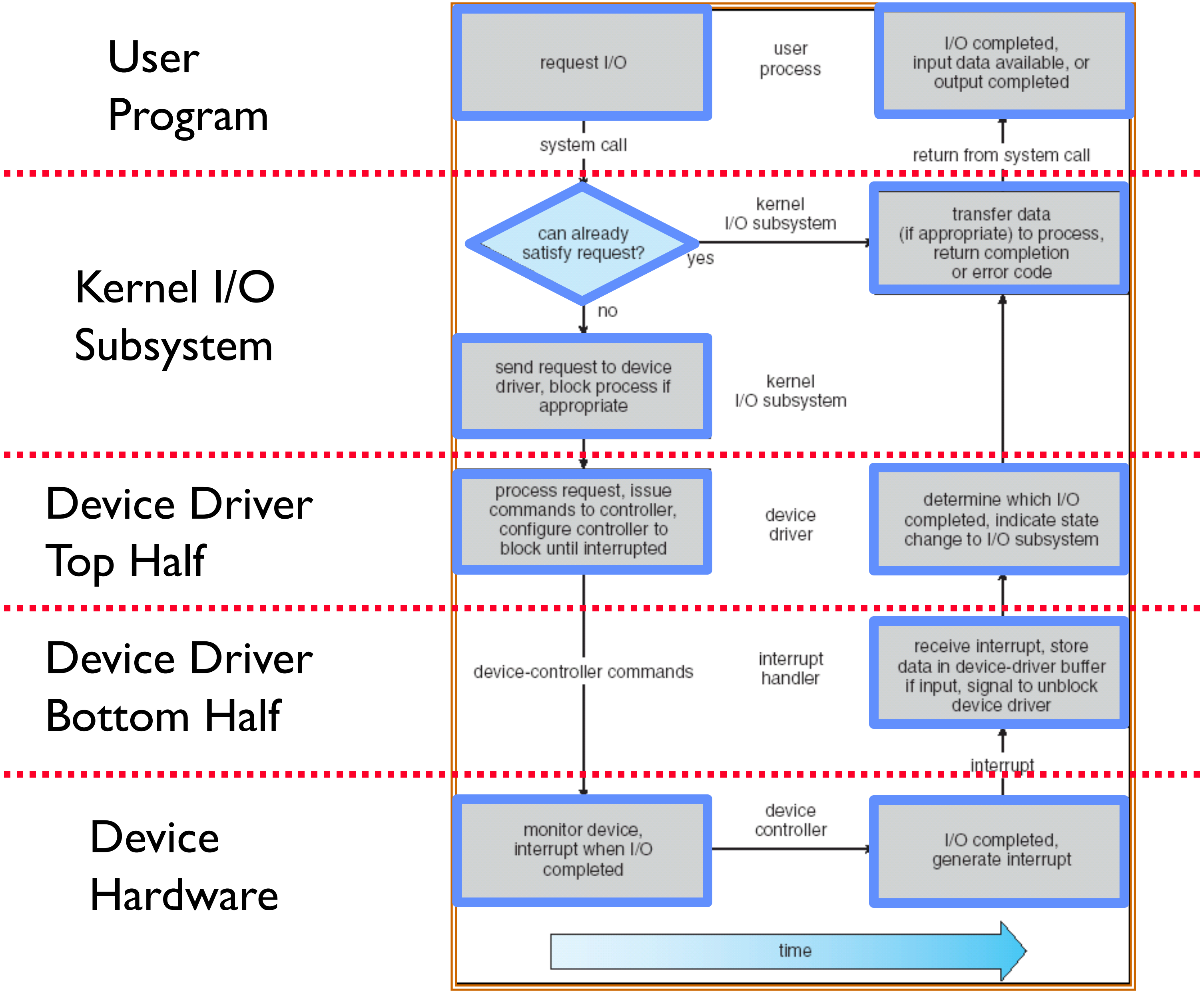
- Device Driver: Device-specific code in the kernel that interacts directly with the device hardware
  - Supports a standard, internal interface
  - Same kernel I/O system can interact easily with different device drivers
  - Special device-specific configuration supported with the `ioctl()` system call
- Device Drivers typically divided into two pieces:
  - Top half: accessed in call path from system calls
    - implements a set of standard, cross-device calls like `open()`, `close()`, `read()`, `write()`, `ioctl()`, `strategy()`
    - This is the kernel's interface to the device driver
    - Top half will *start* I/O to device, may put thread to sleep until finished
  - Bottom half: run as interrupt routine
    - Gets input or transfers next block of output
    - May wake sleeping threads if I/O now complete

Lower Level Driver

```
struct file_operations {
    struct module *owner;
    loff_t (*llseek) (struct file *, loff_t, int);
    ssize_t (*read) (struct file *, char __user *, size_t, loff_t *);
    ssize_t (*write) (struct file *, const char __user *, size_t, loff_t *);
    ssize_t (*aio_read) (struct kiocb *, const struct iovec *, unsigned long, loff_t);
    ssize_t (*aio_write) (struct kiocb *, const struct iovec *, unsigned long, loff_t);
    int (*readdir) (struct file *, void *, filldir_t);
    unsigned int (*poll) (struct file *, struct poll_table_struct *);
    int (*ioctl) (struct inode *, struct file *, unsigned int, unsigned long);
    int (*mmap) (struct file *, struct vm_area_struct *);
    int (*open) (struct inode *, struct file *);
    int (*flush) (struct file *, fl_owner_t id);
    int (*release) (struct inode *, struct file *);
    int (*fsync) (struct file *, struct dentry *, int datasync);
    int (*fasync) (int, struct file *, int);
    int (*flock) (struct file *, int, struct file_lock *);
    [...]
};
```

- Associated with particular hardware device
- Registers / Unregisters itself with the kernel
- Handler functions for each of the file operations

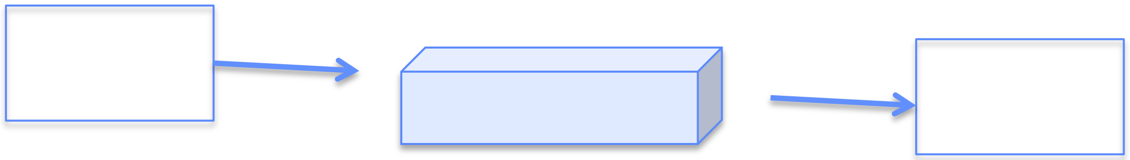
Life Cycle of An I/O Request



Communication between processes

- Can we view files as communication channels?

```
write(wfd, wbuf, wlen);
```

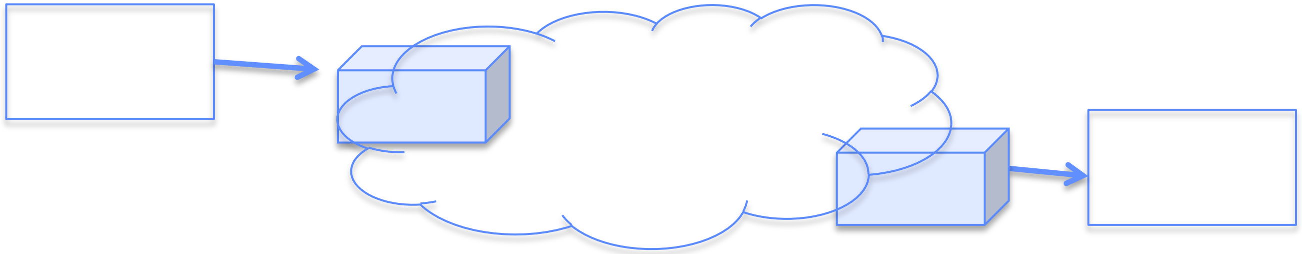


```
n = read(rfd,rbuf,rmax);
```

- Producer and Consumer of a file may be distinct processes
  – May be separated in time (or not)
- However, what if data written once and consumed once?
  – Don't we want something more like a queue?
  – Can still look like File I/O!

Communication Across the world looks like file IO!

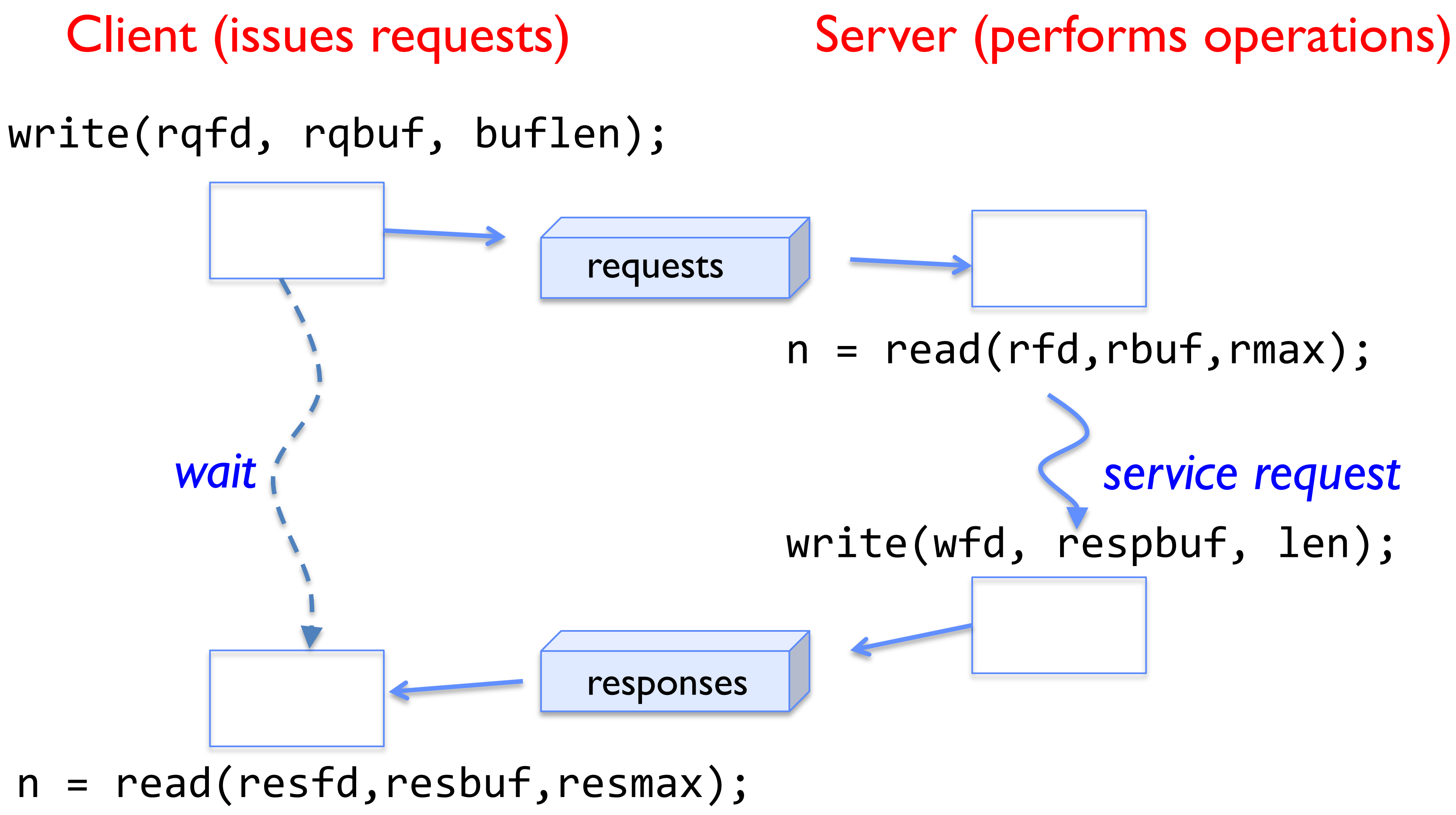
```
write(wfd, wbuf, wlen);
```



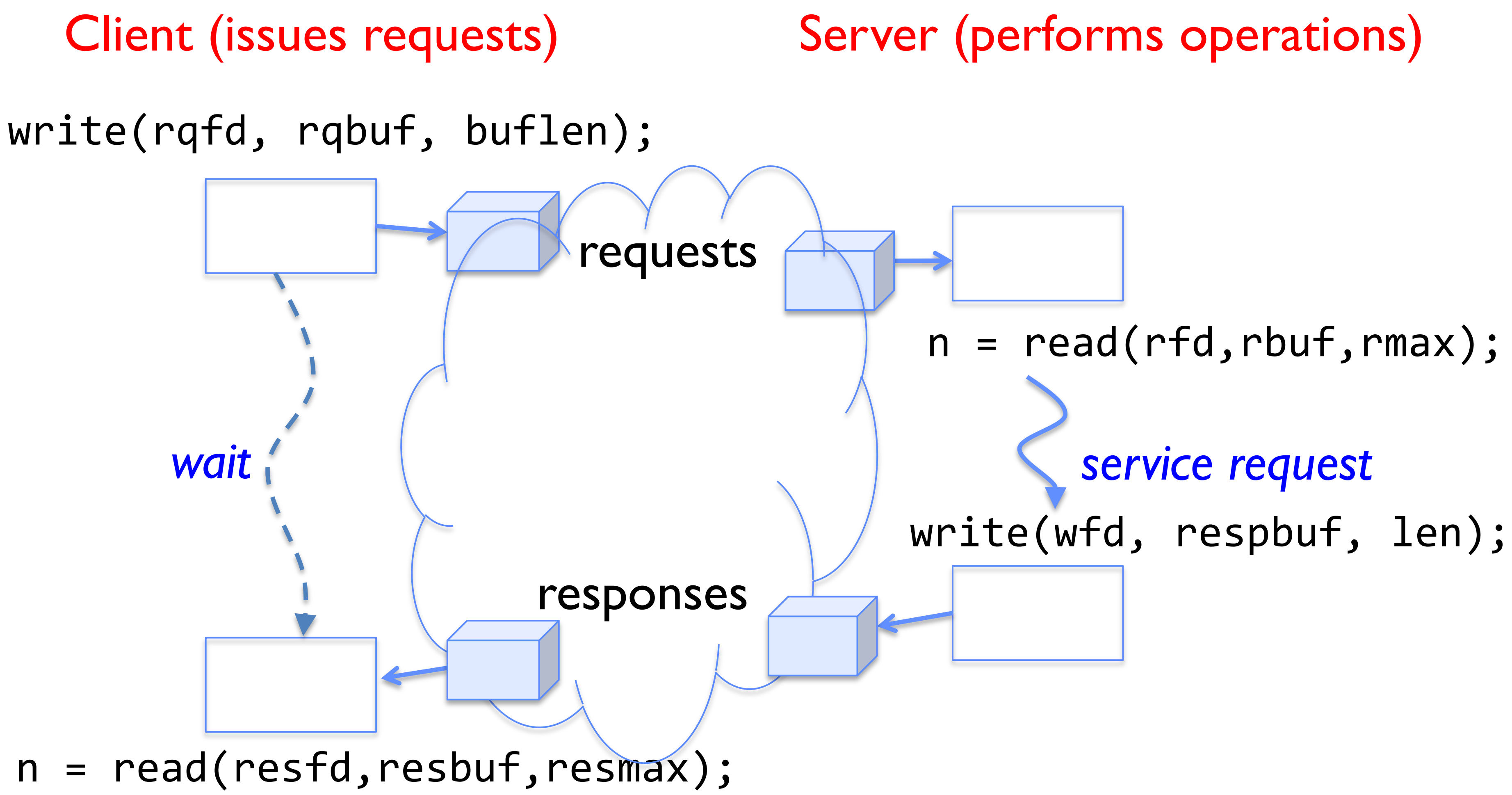
```
n = read(rfd,rbuf,rmax);
```

- Connected queues over the Internet
  - But what's the analog of open?
  - What is the namespace?
  - How are they connected in time?

Request Response Protocol



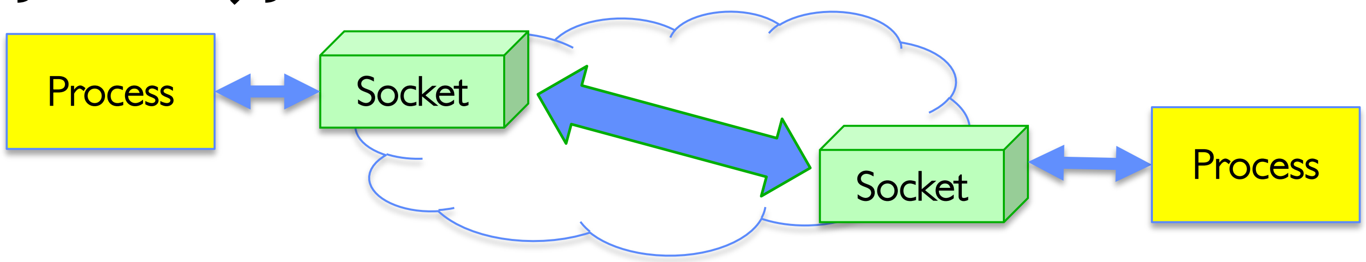
Request Response Protocol: Across Network



The Socket Abstraction: Endpoint for Communication

- **Key Idea:** Communication across the world looks like File I/O

```
write(wfd, wbuf, wlen);
```




```
n = read(rfd, rbuf, rmax);
```

- Sockets: Endpoint for Communication
  - Queues to temporarily hold results
- Connection: Two Sockets Connected Over the network ⇒ IPC over network!
  - How to **open()**?
  - What is the namespace?
  - How are they connected in time?

Sockets: More Details

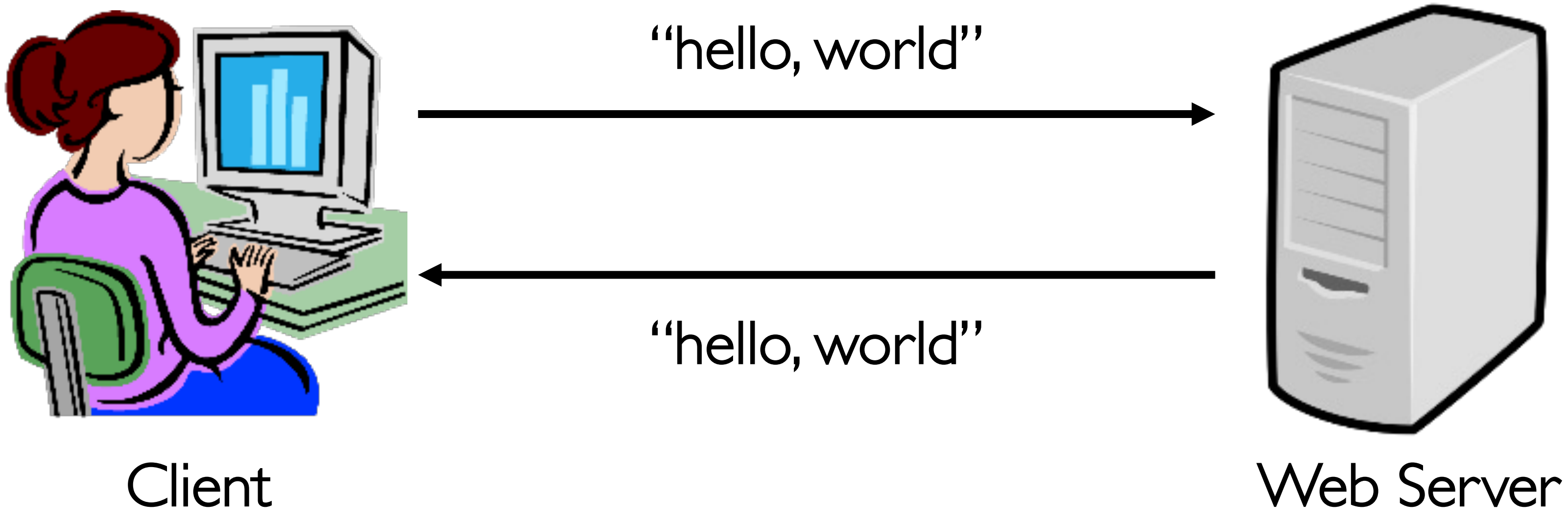
- **Socket:** An abstraction for one endpoint of a network connection
  - Another mechanism for **inter-process communication**
  - Most operating systems (Linux, Mac OS X, Windows) provide this, even if they don't copy rest of UNIX I/O
  - Standardized by POSIX
- First introduced in 4.2 BSD (Berkeley Standard Distribution) Unix
  - This release had some huge benefits (and excitement from potential users)
  - Runners waiting at release time to get release on tape and take to businesses
- Same abstraction for any kind of network
  - Local (within same machine)
  - The Internet (TCP/IP, UDP/IP)
  - Things "no one" uses anymore (OSI, Appletalk, IPX, …)

Sockets: More Details

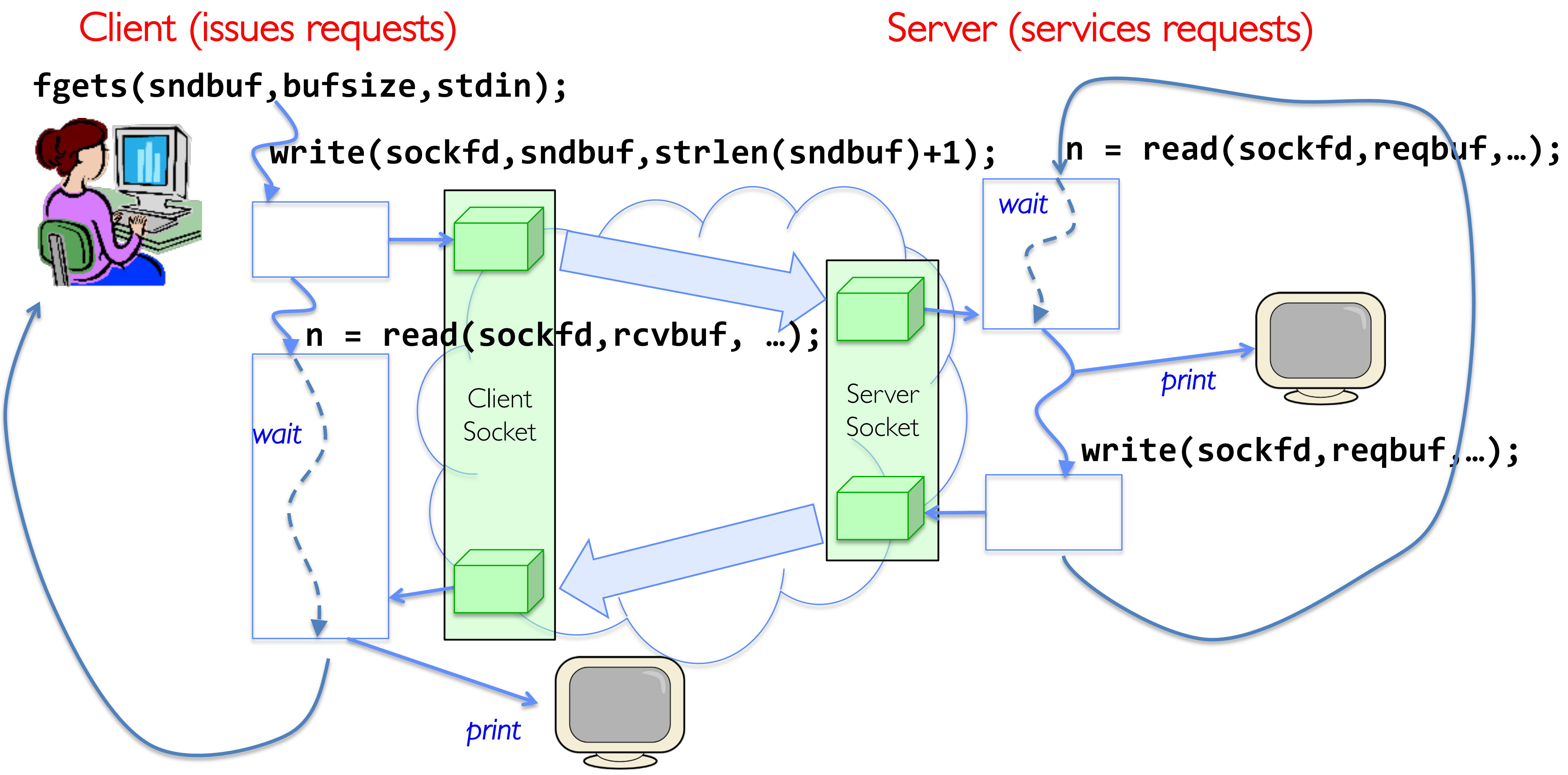
- Looks just like a file with a **file descriptor**
  - Corresponds to a network connection (*two* queues)
  - **`write`** adds to output queue (queue of data destined for other side)
  - **`read`** removes from it input queue (queue of data destined for this side)
  - Some operations do not work, e.g. **`lseek`**

- How can we use sockets to support real applications?
  - A bidirectional byte stream isn't useful on its own…
  - May need messaging facility to partition stream into chunks
  - May need RPC facility to translate one environment to another and provide the abstraction of a function call over the network

Simple Example: Echo Server



Simple Example: Echo Server



Echo client-server example

```
void client(int sockfd) {
  int n;
  char sndbuf[MAXIN]; char rcvbuf[MAXOUT];
  while (1) {
    fgets(sndbuf,MAXIN,stdin);                  /* prompt */
    write(sockfd, sndbuf, strlen(sndbuf)+1);  /* send (including null terminator) */
    memset(rcvbuf,0,MAXOUT);                  /* clear */
    n=read(sockfd, rcvbuf, MAXOUT);           /* receive */
    write(STDOUT_FILENO, rcvbuf, n);          /* echo */
}
```

```
void server(int consockfd) {
  char reqbuf[MAXREQ];
  int n;
  while (1) {
    memset(reqbuf,0, MAXREQ);
    n = read(consockfd,reqbuf,MAXREQ); /* Recv */
    if (n <= 0) return;
    write(STDOUT_FILENO, reqbuf, n);
    write(consockfd, reqbuf, n); /* echo*/
  }
}
```

What Assumptions are we Making?

- Reliable
  - Write to a file => Read it back. Nothing is lost.
  - Write to a (TCP) socket => Read from the other side, same.

- In order (sequential stream)
  - Write X then write Y => read gets X then read gets Y

- When ready?
  - File read gets whatever is there at the time
    - » Actually need to loop and read until we receive the terminator ('\0')
  - Assumes writing already took place
  - Blocks if nothing has arrived yet

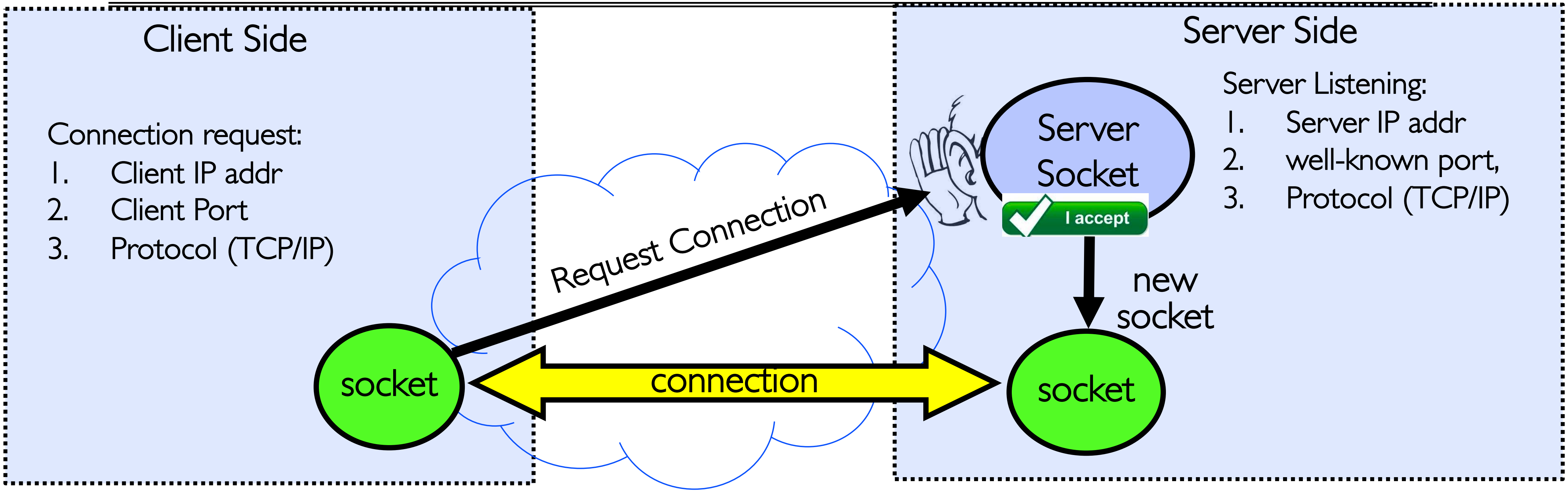
Socket Creation

- File systems provide a collection of permanent objects in a structured name space:
  - Processes open, read/write/close them
  - Files exist independently of processes
  - Easy to name what file to **`open()`**
- Pipes: one-way communication between processes on same (physical) machine
  - Single queue
  - Created transiently by a call to **`pipe()`**
  - Passed from parent to children (descriptors inherited from parent process)
- Sockets: two-way communication between processes on same or different machine
  - Two queues (one in each direction)
  - Processes can be on separate machines: no common ancestor
  - How do we *name* the objects we are **`open`**ing?
  - How do these completely independent programs know that the other wants to "talk" to them?

Namespaces for Communication over IP

- Hostname
  - www.eecs.berkeley.edu
- IP address
  - 128.32.244.172 (IPv4, 32-bit Integer)
  - 2607:f140:0:81::f (IPv6, 128-bit Integer)
- Port Number
  - 0-1023 are "well known" or "system" ports
    - » Superuser privileges to bind to one
  - 1024 – 49151 are "registered" ports (registry)
    - » Assigned by IANA for specific services
  - 49152–65535 ($2^{15}+2^{14}$ to $2^{16}-1$) are "dynamic" or "private"
    - » Automatically allocated as "ephemeral ports"

Connection Setup over TCP/IP



- Special kind of socket: **server socket**
  - Has file descriptor
  - Can't read or write
- Two operations:
  1. **listen()**: Start allowing clients to connect
  2. **accept()**: Create a *new socket* for a *particular* client

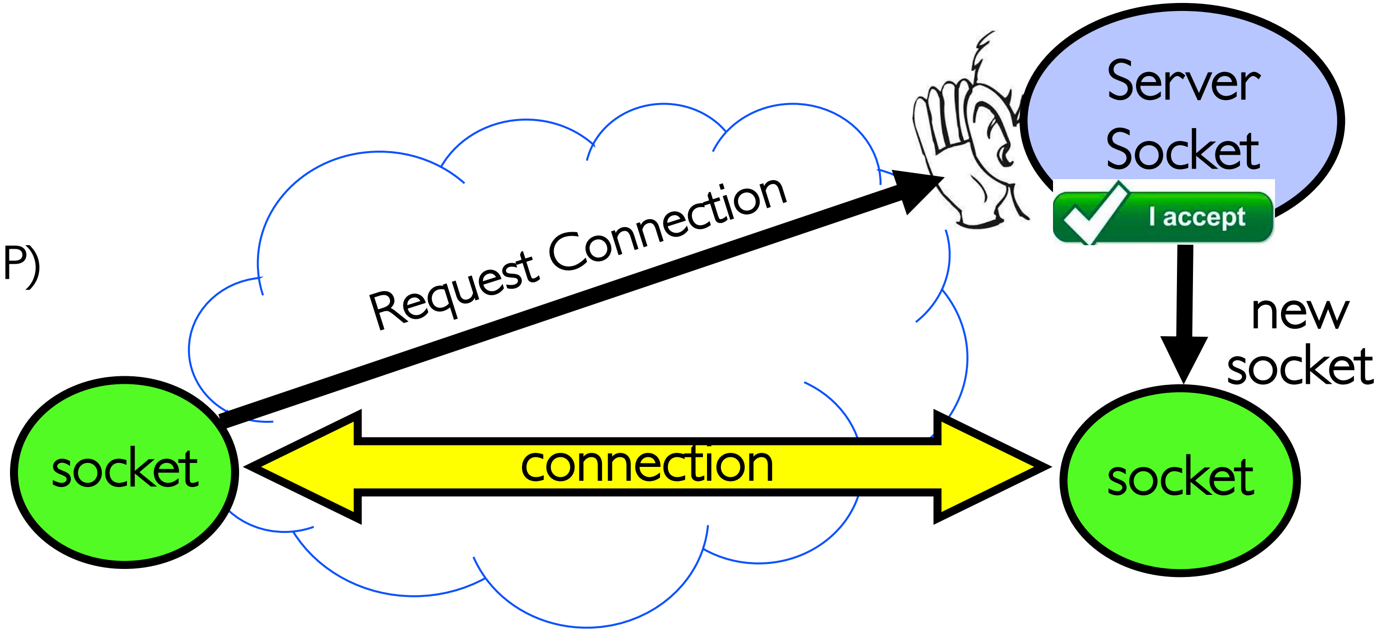
Connection Setup over TCP/IP

Client Side

Connection request:
1. Client IP addr
2. Client Port
3. Protocol (TCP/IP)

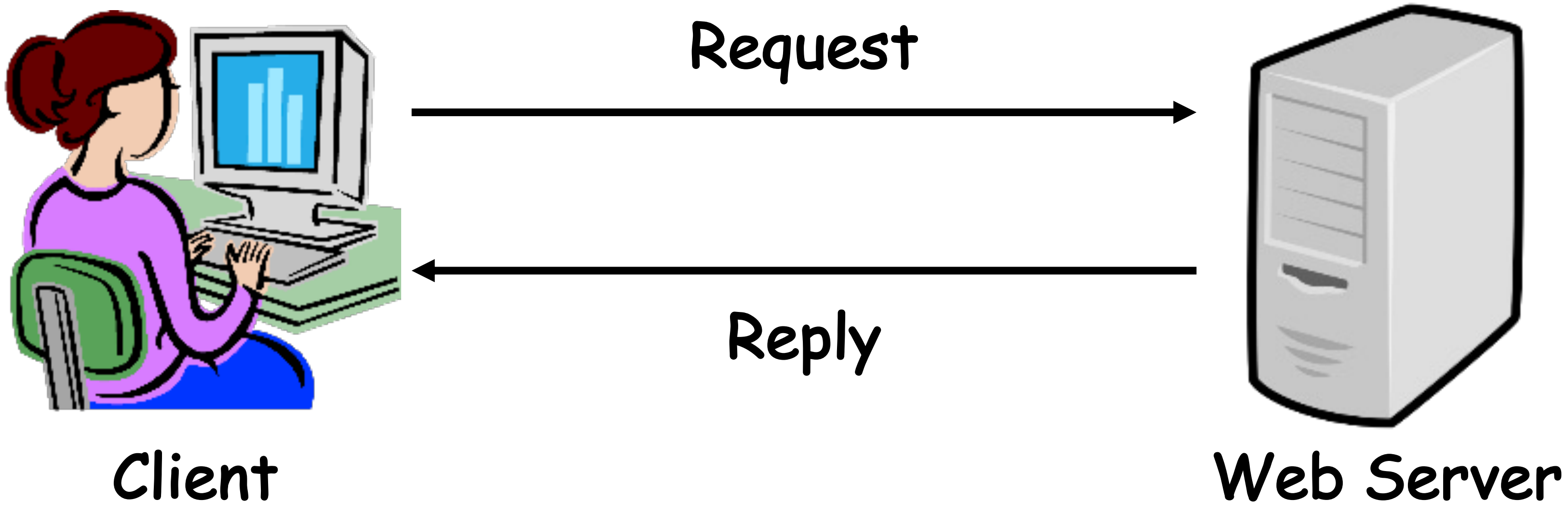
Server Side

Server Listening:
1. Server IP addr
2. well-known port,
3. Protocol (TCP/IP)

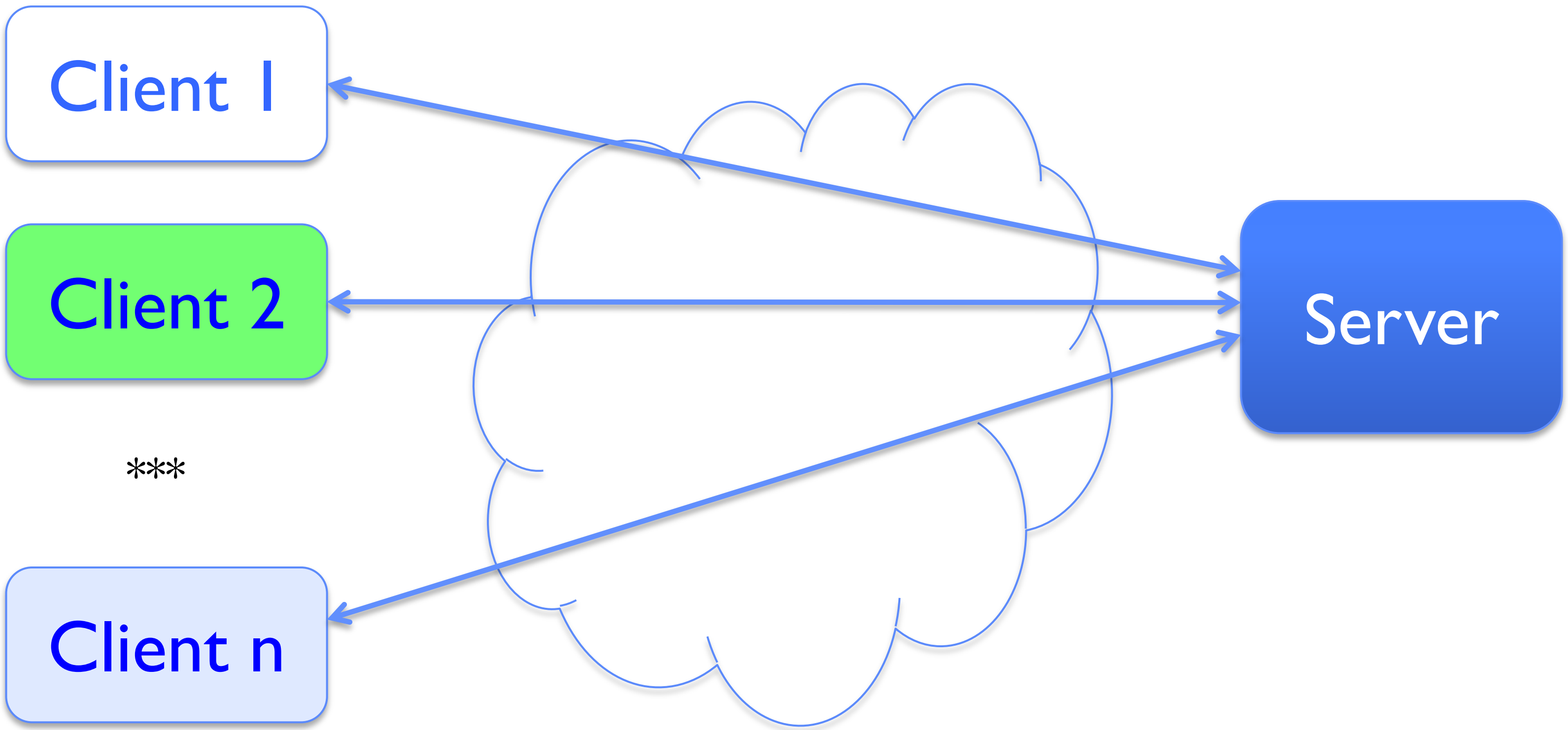


- 5-Tuple identifies each connection:
  1. Source IP Address
  2. Destination IP Address
  3. Source Port Number
  4. Destination Port Number
  5. Protocol (always TCP here)
- Often, Client Port "randomly" assigned
  – Done by OS during client socket setup
- Server Port often "well known"
  – 80 (web), 443 (secure web), 25 (sendmail), etc
  – Well-known ports from 0—1023

Web Server

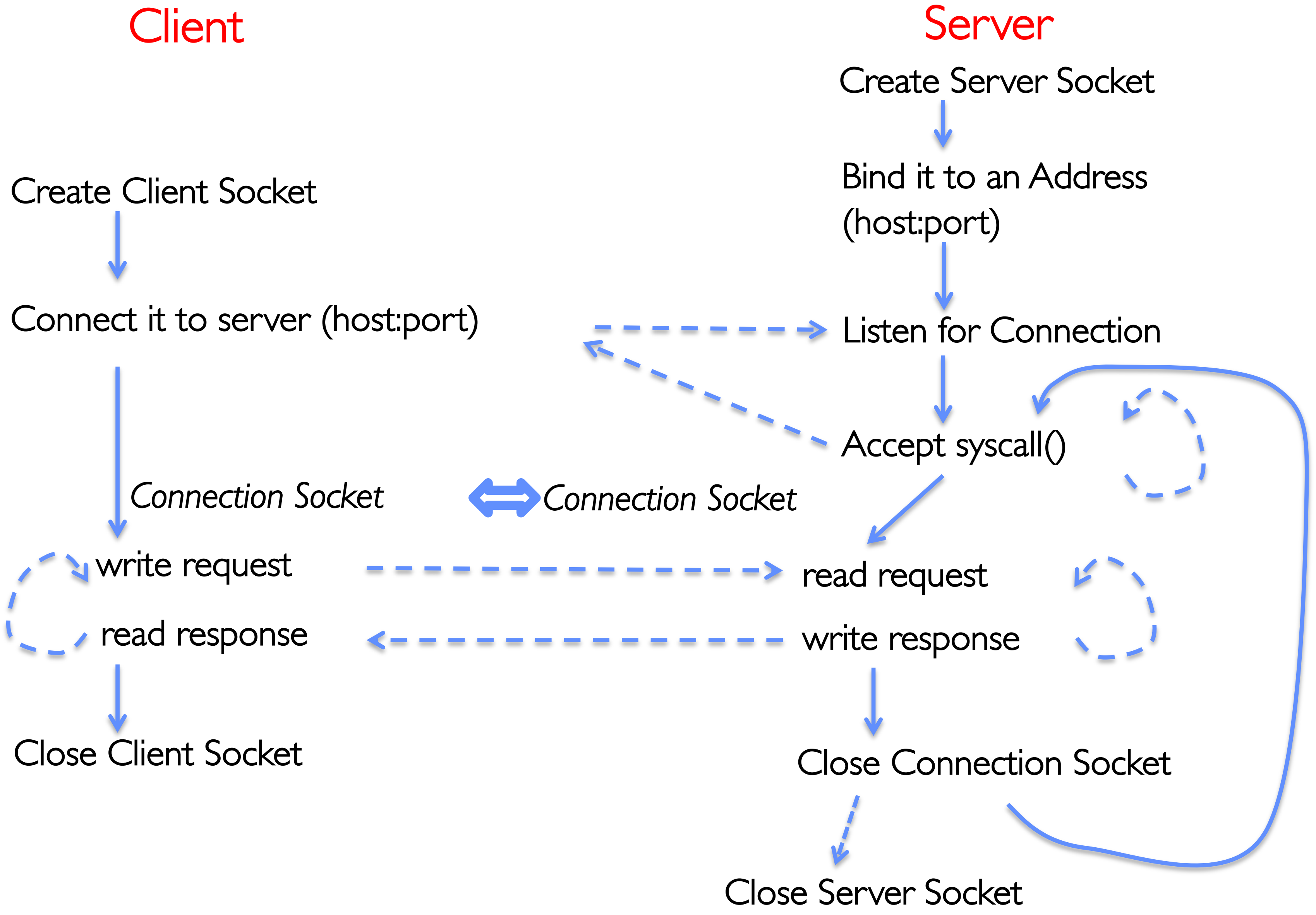


Client-Server Models



- File servers, web, FTP, Databases, …
- Many clients accessing a common server

Simple Web Server



Client Code

```
char *host_name, *port_name;

// Create a socket
struct addrinfo *server = lookup_host(host_name, port_name);
int sock_fd = socket(server->ai_family, server->ai_socktype,
                     server->ai_protocol);

// Connect to specified host and port
connect(sock_fd, server->ai_addr, server->ai_addrlen);

// Carry out Client-Server protocol
run_client(sock_fd);

/* Clean up on termination */
close(sock_fd);
```

Client-Side: Getting the Server Address

```
struct addrinfo *lookup_host(char *host_name, char *port) {
  struct addrinfo *server;
  struct addrinfo hints;
  memset(&hints, 0, sizeof(hints));
  hints.ai_family = AF_UNSPEC;         /* Includes AF_INET and AF_INET6 */
  hints.ai_socktype = SOCK_STREAM;     /* Essentially TCP/IP */

  int rv = getaddrinfo(host_name, port_name, &hints, &server);
  if (rv != 0) {
    printf("getaddrinfo failed: %s\n", gai_strerror(rv));
    return NULL;
  }
  return server;
}
```

Server Code (v1)

```
// Create socket to listen for client connections
char *port_name;
struct addrinfo *server = setup_address(port_name);
int server_socket = socket(server->ai_family,
                           server->ai_socktype, server->ai_protocol);
// Bind socket to specific port
bind(server_socket, server->ai_addr, server->ai_addrlen);
// Start listening for new client connections
listen(server_socket, MAX_QUEUE);

while (1) {
  // Accept a new client connection, obtaining a new socket
  int conn_socket = accept(server_socket, NULL, NULL);
  serve_client(conn_socket);
  close(conn_socket);
}
close(server_socket);
```

Server Address: Itself (wildcard IP), Passive

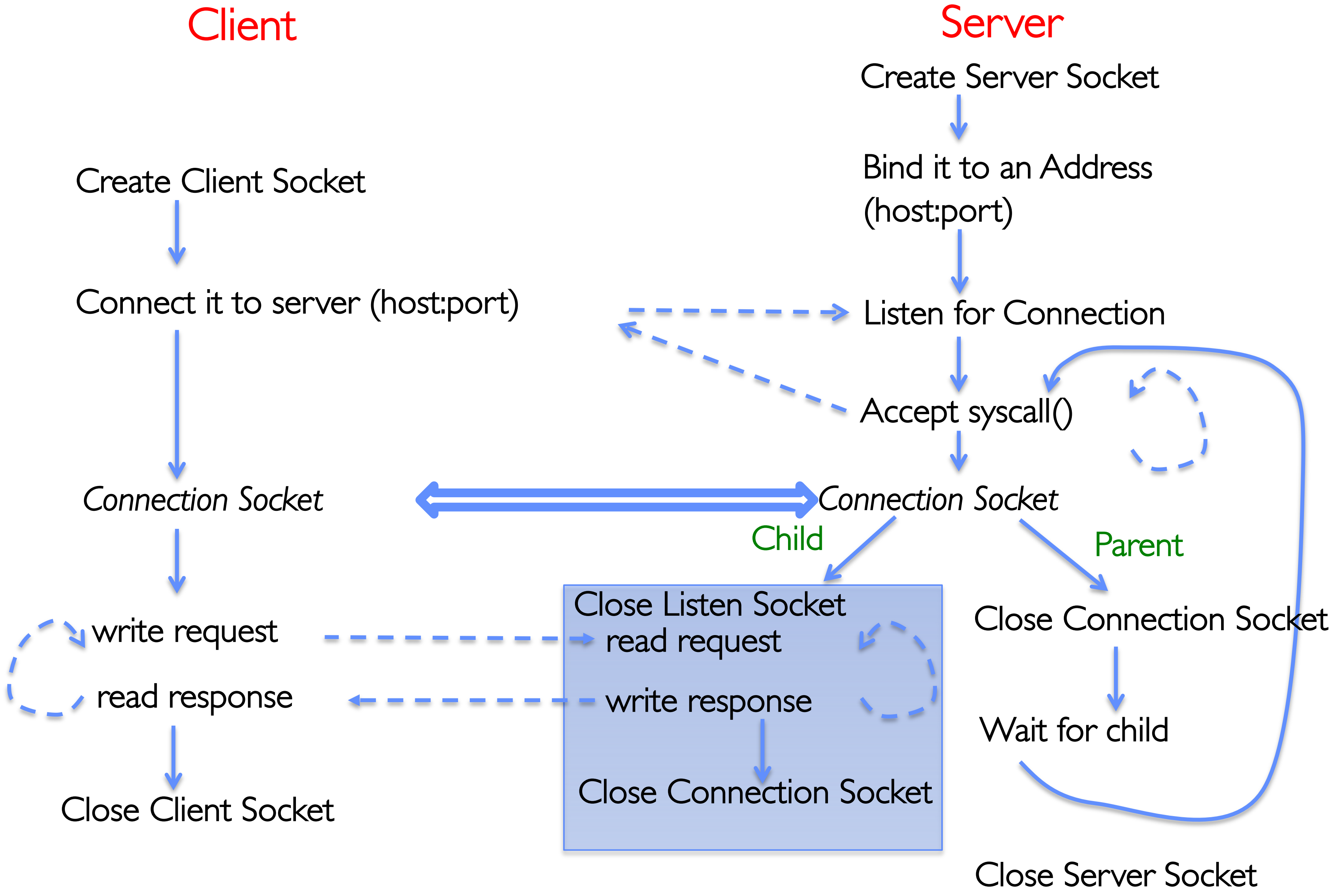
```
struct addrinfo *setup_address(char *port) {
  struct addrinfo *server;
  struct addrinfo hints;
  memset(&hints, 0, sizeof(hints));
  hints.ai_family = AF_UNSPEC;          /* Includes AF_INET and AF_INET6 */
  hints.ai_socktype = SOCK_STREAM;      /* Essentially TCP/IP */
  hints.ai_flags = AI_PASSIVE;          /* Set up for server socket */

  int rv = getaddrinfo(NULL, port, &hints, &server);  /* No address! (any local IP) */
  if (rv != 0) {
    printf("getaddrinfo failed: %s\n", gai_strerror(rv));
    return NULL;
  }
  return server;
}
```

- Accepts any connections on the specified port

How Could the Server Protect Itself?

- Handle each connection in a separate process
  - This will mean that the logic serving each request will be "sandboxed" away from the main server process
- In the following code, keep in mind:
  - `fork()` will duplicate *all* of the parent's file descriptors (i.e. pointers to sockets!)
  - We keep control over accepting new connections in the parent
  - New child connection for each remote client

Server With Protection (each connection has own process)



Server Code (v2)

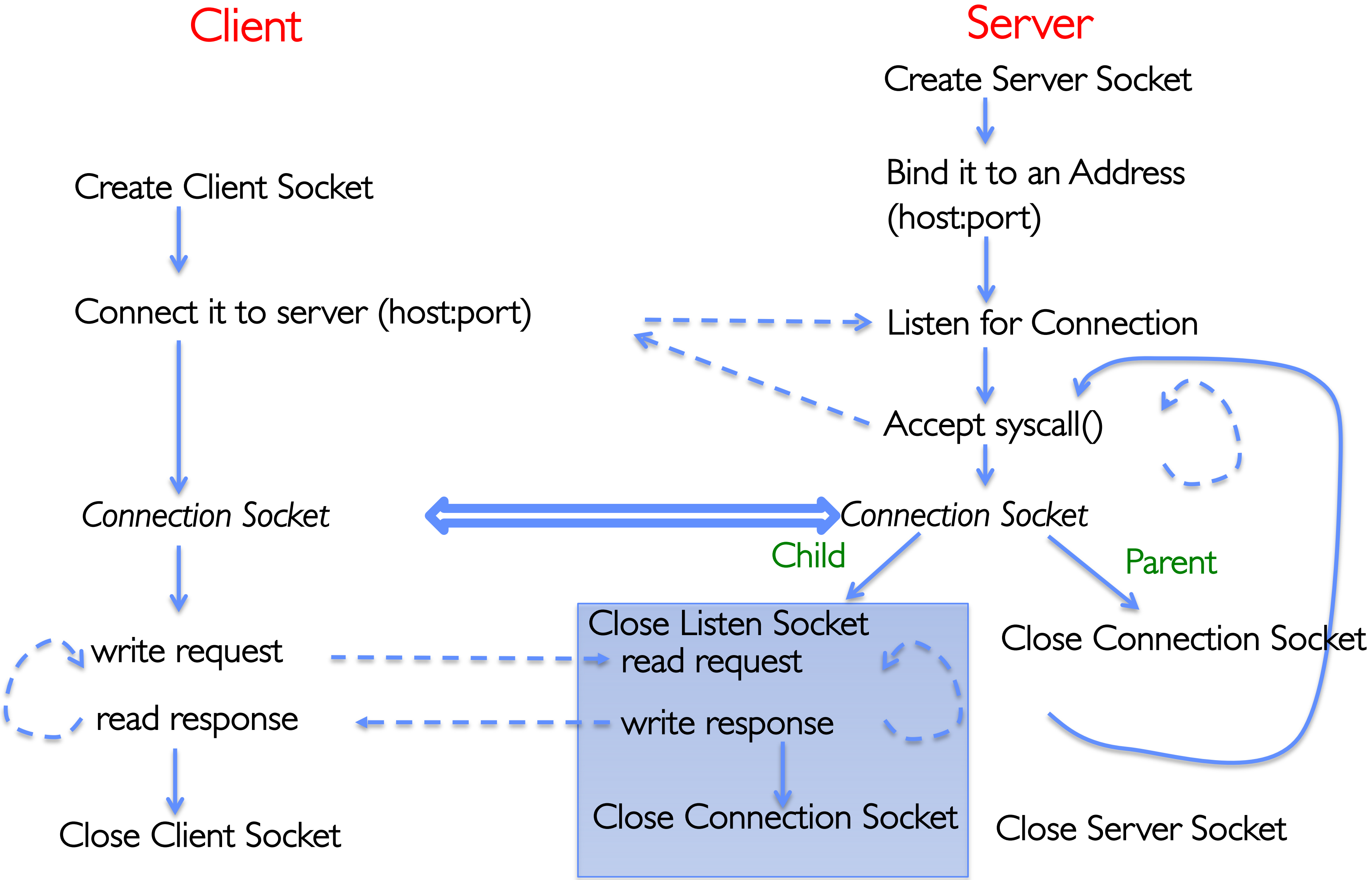
```
// Socket setup code elided…
listen(server_socket, MAX_QUEUE);
while (1) {
  // Accept a new client connection, obtaining a new socket
  int conn_socket = accept(server_socket, NULL, NULL);
  pid_t pid = fork();
  if (pid == 0) {
    close(server_socket);
    serve_client(conn_socket);
    close(conn_socket);
    exit(0);
  } else {
    close(conn_socket);
    wait(NULL);
  }
}
close(server_socket);
```

How to make a Concurrent Server

- So far, in the server:
  - Listen will queue requests
  - Buffering present elsewhere
  - But server *waits* for each connection to terminate before servicing the next
    - » This is the standard shell pattern

- A concurrent server can handle and service a new connection before the previous client disconnects
  - Simple – just don't wait in parent!
  - Perhaps not so simple – multiple child processes better not have data races with one another through file system/etc!

Server With Protection and Concurrency



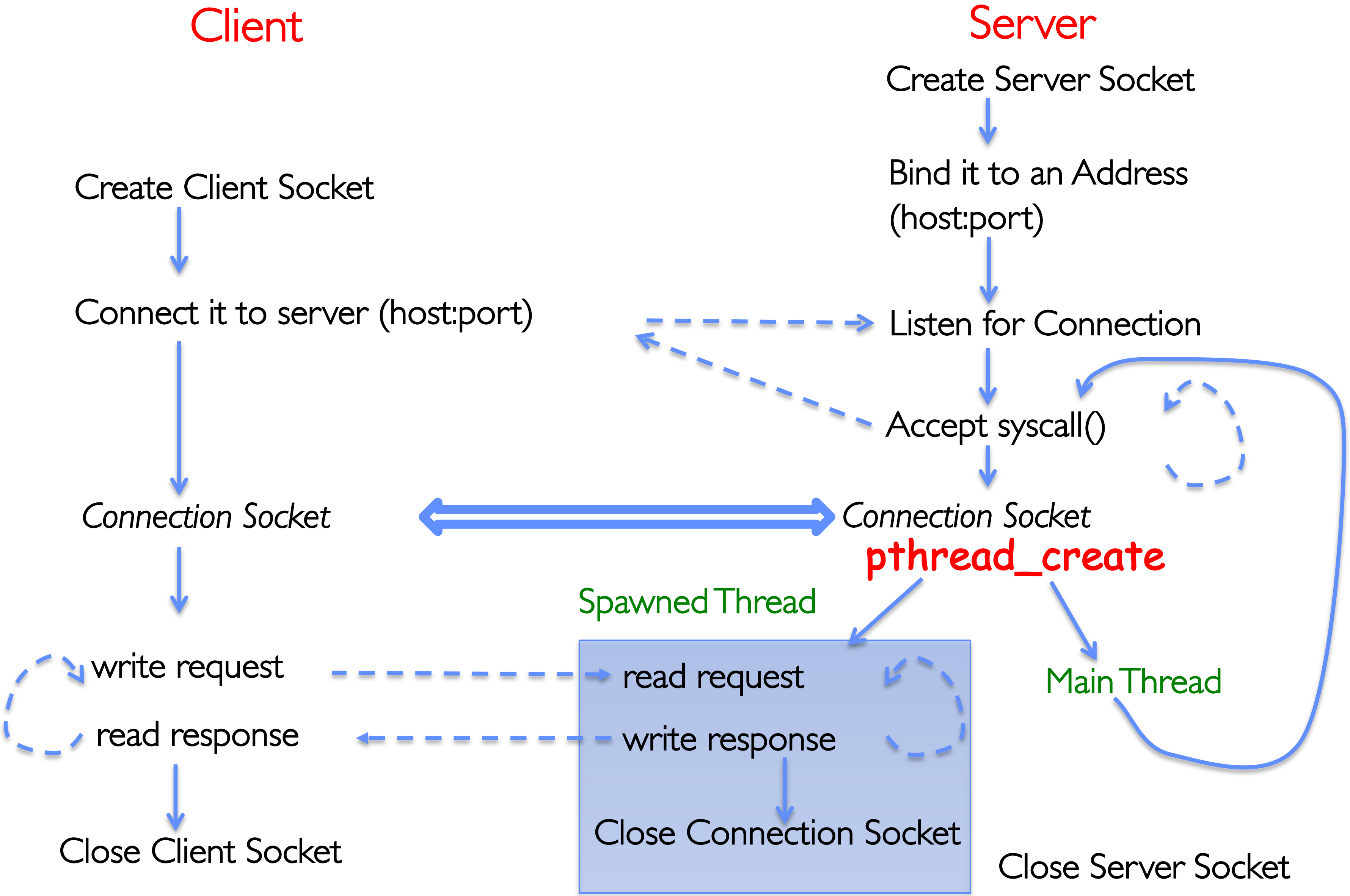
Server Code (v3)

```
// Socket setup code elided…
listen(server_socket, MAX_QUEUE);
while (1) {
  // Accept a new client connection, obtaining a new socket
  int conn_socket = accept(server_socket, NULL, NULL);
  pid_t pid = fork();
  if (pid == 0) {
    close(server_socket);
    serve_client(conn_socket);
    close(conn_socket);
    exit(0);
  } else {
    close(conn_socket);
    //wait(NULL);
  }
}
close(server_socket);
```

Faster Concurrent Server (without Protection)

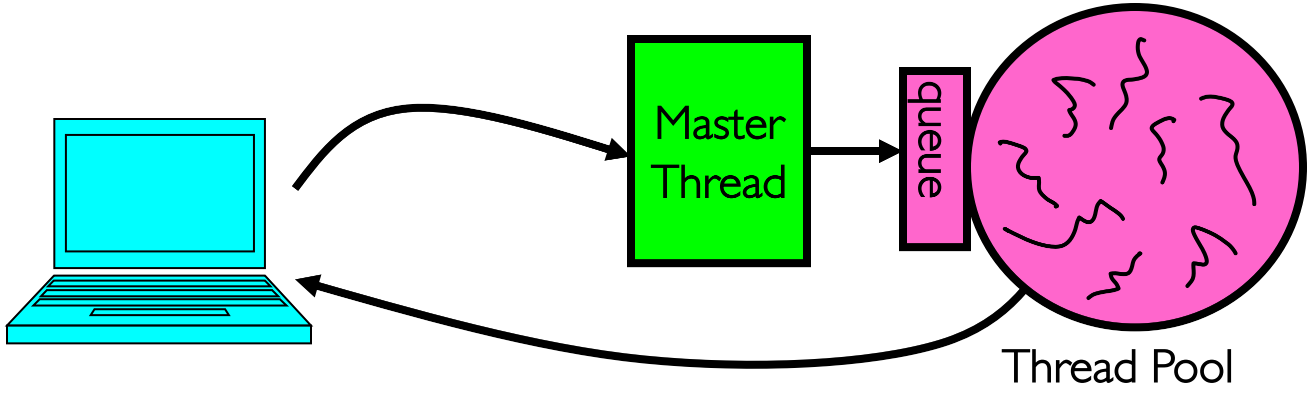
- Spawn a new *thread* to handle each connection
  - Lower overhead spawning process (less to do)
- Main *thread* initiates new client connections without waiting for previously spawned threads
- Why give up the protection of separate processes?
  - More efficient to create new threads
  - More efficient to switch between threads
- Even more potential for data races (need synchronization?)
  - Through shared memory structures
  - Through file system

Server with Concurrency, without Protection



Thread Pools: More Later!

- Problem with previous version: Unbounded Threads
  - When web-site becomes too popular – throughput sinks
- Instead, allocate a bounded "pool" of worker threads, representing the maximum level of multiprogramming




```
master() {
   allocThreads(worker,queue);
   while(TRUE) {
      con=AcceptCon();
      Enqueue(queue,con);
      wakeUp(queue);
   }
}
```

```
worker(queue) {
   while(TRUE) {
      con=Dequeue(queue);
      if (con==null)
         sleepOn(queue);
      else
         ServiceWebPage(con);
   }
}
```

Conclusion

- POSIX I/O
  - Everything is a file!
  - Based on the system calls **`open()`**, **`read()`**, **`write()`**, and **`close()`**
- Streaming IO: modeled as a stream of bytes
  - Most streaming I/O functions start with "f" (like "fread")
  - Data buffered automatically by C-library function
- Low-level I/O:
  - File descriptors are integers
  - Low-level I/O supported directly at system call level
- Device Driver: Device-specific code in the kernel that interacts directly with the device hardware
  - Supports a standard, internal interface
  - Same kernel I/O system can interact easily with different device drivers
- File abstraction works for inter-processes communication (local or Internet)
- Socket: an abstraction of a network I/O queue (IPC mechanism)