

Lecture 3

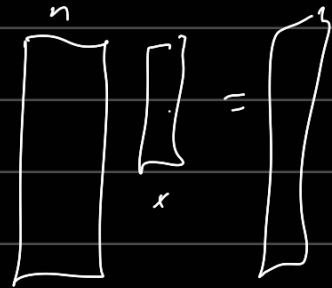
- Gram-Schmidt
- Fund. Thm of Lin Alg
 - ↳ min norm problem
- Symmetric Matrices

Fund Thm of Lin Alg. ECG 3.1

$$\mathbb{R}^n \quad N(A) \oplus R(A^T) = \mathbb{R}^n \quad A \in \mathbb{R}^{m \times n}$$

↑
direct sum \rightarrow implies uniqueness of decomposition

$$R(A) \oplus N(A^T) = \mathbb{R}^m$$



Orthogonal Decomposition Theorem (Thm 2.1 ECG)

\mathcal{X} : vector space

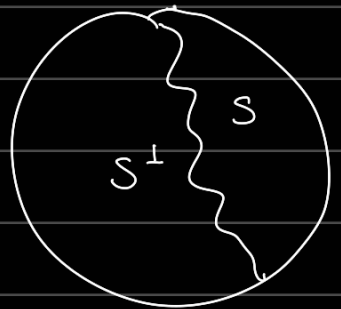
S : subspace. Then $\forall \vec{x} \in \mathcal{X}$

$$\vec{x} = \vec{s} + \vec{r}$$

$$\vec{s} \in S, \vec{r} \in S^\perp$$

$$S^\perp = \{ \vec{r} \mid \langle \vec{r}, \vec{s} \rangle = 0, \forall \vec{s} \in S \}$$

$$\mathcal{X} = S \oplus S^\perp$$



using the orthogonal decomposition thm to prove the FTLA:

$$\text{Want: } N(A)^\perp = R(A^T)$$

$$\text{WTS: } N(A) \overset{(1)}{\subseteq} R(A^T)^\perp \quad \text{?} \quad R(A^T)^\perp \overset{(2)}{\subseteq} N(A)$$

↳ subsets of each other

To show (1): Let $\vec{x} \in N(A)$, show $\vec{x} \in R(A^T)^\perp$

$$A\vec{x} = \vec{0}$$

$$\Rightarrow \vec{x}^T A^T = 0$$

$$\forall \vec{w} \text{ s.t. } \vec{w} = A^T \vec{y}$$

can be
re-written as
 $\vec{w} = A^T \vec{y}$

$$\langle \vec{x}, \vec{w} \rangle = \langle \vec{x}, A^T \vec{y} \rangle$$

$$\langle \vec{x}, \vec{w} \rangle = 0$$

$$= \vec{x}^T A^T \vec{y}$$

$$\vec{x} \in \mathbb{R}^n \quad = \vec{y}^T A \vec{x}$$

$$= 0$$

Aside

A scalar transposed is just
that same scalar



$$\vec{x}^T: \quad \text{[horizontal rectangle]}$$

To show (2): Let $\vec{x} \in R(A^T)^\perp$

$$\forall \vec{w} \text{ s.t. } \vec{w} = A^T \vec{y}$$

$$\langle \vec{x}, \vec{w} \rangle = 0$$

$$= \langle \vec{x}, A^T \vec{y} \rangle$$

$$= \vec{x}^T A^T \vec{y}$$

$$= \vec{y}^T A \vec{x} \quad \text{this is true for } \forall \vec{y} \text{ because } \vec{w} = A^T \vec{y} \text{ is valid for } \forall \vec{w}$$

$$= 0$$

Want: $\vec{x} \in N(A)$

$$A\vec{x} = 0$$

\Rightarrow since true $\forall \vec{y}$, $A\vec{x} = 0$.

$$a^T b = 0 \quad \forall a$$

$$\begin{bmatrix} 1 & 0 & \dots & 0 & 0 \end{bmatrix}$$

$\forall a$

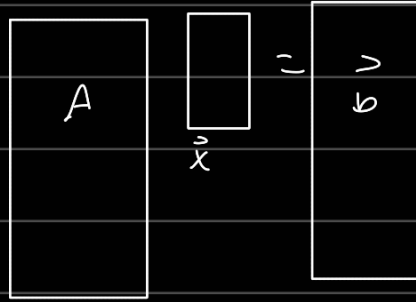
$$\begin{bmatrix} b_1 \\ b_2 \\ \vdots \\ b_n \end{bmatrix}$$

$$= \begin{bmatrix} b_1 \\ 0 \\ \vdots \\ 0 \end{bmatrix}$$

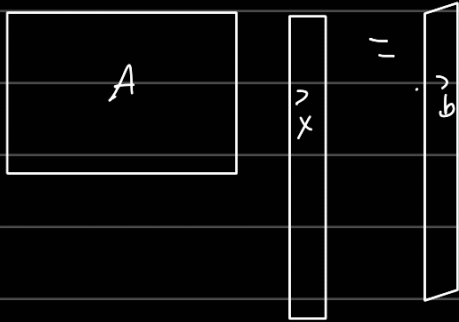
$\Rightarrow \vec{b}$ must be 0

Minimum Norm Problem

$$A\vec{x} = \vec{b}$$



overdetermined
↳ generally 0 solutions



underdetermined
↳ generally ∞ solutions

minimize the 2 norm of \vec{x} subject to $A\vec{x} = \vec{b}$

$$\min \|\vec{x}\|_2^2$$

s.t. $A\vec{x} = \vec{b}$

$$A\vec{x} = \vec{b}$$

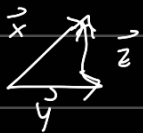
$$\text{FTLA} \Rightarrow \vec{x} = \vec{y} + \vec{z} \quad \vec{y} \in N(A), \quad \vec{z} \in R(A^T)$$

$$A\vec{x} = \vec{b}$$

$$A\vec{y} + A\vec{z} = \vec{b}$$

$$A\vec{z} = \vec{b}$$

$$\vec{y} \perp \vec{z} \quad \|\vec{x}\|_2^2 = \|\vec{y}\|_2^2 + \|\vec{z}\|_2^2$$



$$\vec{z} = A^T \vec{w}$$

$$A\vec{z} = \vec{b}$$

$$\Rightarrow A \cdot A^T \vec{w} = \vec{b}$$

square matrix
→ full rank, invertible

$$\vec{\omega} = (A A^T)^{-1} \vec{b}$$

$$\vec{z} = A^T (A A^T)^{-1} \vec{b}$$

care about full row rank

In the case of least squares, care about full column rank

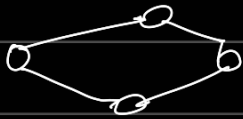
Symmetric Matrices

$A = A^T$ \Rightarrow all scalars are symmetric matrices
 $A \in \mathbb{R}^n$

$$A_{ij} = A_{ji} \quad \begin{bmatrix} a & b \\ b & c \end{bmatrix} \quad \text{is symmetric}$$

eg. covariance matrices are symmetric $A = B B^T$
 $A^T = (B B^T)^T = B B^T$

eg. graph laplacians



- have nice eigenvalues
- are always diagonalizable

eg $\begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix} \rightarrow$ not diagonalizable
 $A = U \underbrace{\Lambda}_{\text{not diagonal}} U^{-1}$

"algebraic multiplicity" = "geometric multiplicity"
 \hookrightarrow dimension of $N(\lambda I - A)$

$$\det(\lambda I - A)$$

\hookrightarrow # of times λ appears as a root

$$\begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix} \rightarrow \det(\lambda I - A) = (\lambda - 1)^2$$

$\hookrightarrow \lambda = 1$
 \hookrightarrow multiplicity of 2
 $\mu = 2$

$$\text{Null}(\lambda I - A) = \begin{bmatrix} 0 & -1 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} -y \\ 0 \end{bmatrix} \Rightarrow \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$

is the eigenvector
corresponding to $\lambda = 1$

Spectral Theorem : $A \in \mathbb{S}^n$

- ① $\lambda_i \in \mathbb{R}$
- ② eigenspaces corresponding to distinct eigenvalues $\lambda_i \neq \lambda_j$ are orthogonal

$$\Phi_i = \text{Null}(\lambda_i I - A)$$

- ③ $\dim(\Phi_i) = \mu_i$ (μ_i is algebraic multiplicity)

$$A \in \mathbb{S}^n$$

$$A = U \Lambda U^T$$

U : orthonormal

Λ : diagonal

Proof of ③

Lemma: (λ, \vec{v}) be an eigenpair for A .

Then \exists orthonormal U st. $U^T A U = \begin{bmatrix} \lambda & 0 & \dots & 0 \\ 0 & & & \\ \vdots & & & \\ 0 & & & B \end{bmatrix}$

and $B \in \mathbb{S}^{n-1}$

Proof by Construction:

Consider: $U = \begin{bmatrix} \vec{u} & U_1 \end{bmatrix}$

gramschmidt to fill out the rest of the matrix

$$U^T A U = \begin{bmatrix} -\vec{u} & - \\ U_1^T & \end{bmatrix} \begin{bmatrix} A \end{bmatrix} \begin{bmatrix} \vec{u} & U_1 \end{bmatrix}$$

$$= \begin{bmatrix} -\vec{u} & - \\ U_1^T & \end{bmatrix} \begin{bmatrix} A\vec{u} & AU_1 \end{bmatrix}$$

$$= \begin{bmatrix} -\vec{u} & - \\ U_1^T & \end{bmatrix} \begin{bmatrix} \lambda\vec{u} & AU_1 \end{bmatrix}$$

$$= \begin{bmatrix} \lambda & 0 \dots 0 \\ 0 & B \end{bmatrix}$$

$$B = U_1^T A U_1$$

$$B^T = B \quad (\text{bc } A = A^T)$$

$$B \in \mathcal{S}^{n-1}$$

Say $B \in \mathcal{S}^{n-1}$ *other normal*

$$B = \underbrace{V^T}_{A \text{ diagonal}} \underbrace{L}_{\text{normal}} V$$

$$\gamma \in \mathcal{R}^{(n-1) \times (n-1)}$$

$$U^T A U = \begin{bmatrix} \lambda & \dots & 0 \\ \vdots & B & \\ 0 & & \end{bmatrix}$$

$$V U^T A U V^T = \begin{bmatrix} \lambda & & \\ & V B V^T & \\ & & \end{bmatrix} = \begin{bmatrix} \lambda & 0 \\ 0 & I \end{bmatrix}$$

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-2