

EECS 127

- shadow prices recap
- duality certificate
- complementary slackness
- KKT conditions

Recall

200 kilos merlot

300 kilos shiraz

Blend 1: 4 kilos merlot + 1 kilo shiraz } \$20/bottle

Blend 2: 2 kilos merlot + 3 kilos shiraz } \$15/bottle

→ make q_1 of Blend 1

q_2 of Blend 2

$$p^* = \max_{q_1, q_2 \geq 0} 20q_1 + 15q_2$$

$$4q_1 + 2q_2 \leq 200$$

$$q_1 + 3q_2 \leq 300$$

$$\max_{q_1, q_2 \geq 0} 20q_1 + 15q_2 + \lambda_1(200 - 4q_1 - 2q_2) + \lambda_2(300 - q_1 - 3q_2)$$

$$q_1, q_2 \geq 0$$

$$= \max_{q_1, q_2} \underbrace{(20 - 4\lambda_1 - \lambda_2)q_1}_{\text{if } < 0 \rightarrow \text{don't make blend 1}} + \underbrace{(15 - 2\lambda_1 - 3\lambda_2)q_2}_{\text{if } < 0 \rightarrow \text{don't make blend 2}} + 200\lambda_1 + 300\lambda_2$$

$$q_1, q_2$$

what if these both equal 0?

↳ break-even point → don't care whether you sell off or make the juice

→ these are the shadow prices of the grapes

For LPs, as long as the problem is feasible, strong duality holds

→ minimum profit:

$$d^* = \min 200\lambda_1 + 300\lambda_2$$

$\lambda_1, \lambda_2 \geq 0$ correspond to shadow prices (ie, prices to make it worth your while)

$$20 - 4\lambda_1 - \lambda_2 = 0$$

$$15 - 2\lambda_1 - 3\lambda_2 = 0$$

Certificate (λ, ν) : dual feasible point

x_1 : primal feasible

$$p^* \geq g(\lambda, \nu) \Rightarrow f_0(x_1) - p^* \leq \underbrace{f_0(x_1) - g(\lambda, \nu)}_{\leq \varepsilon}$$

$$p^* \in [g(\lambda, \nu), f_0(x_1)] \quad \text{if strong duality } d^* \in [g(\lambda, \nu), f_0(x_1)]$$

Complementary Slackness

consider primal optimal \vec{x}^* & dual optimal $(\vec{\lambda}^*, \vec{\nu}^*)$

↳ Assume strong duality holds ($p^* = d^*$)

$$p^* = f_0(\vec{x}^*) = d^* = g(\vec{\lambda}^*, \vec{\nu}^*)$$

$$g(\vec{\lambda}^*, \vec{\nu}^*) = \min_{\vec{x}} \left(f_0(\vec{x}) + \sum_{i=1}^m \lambda_i^* f_i(\vec{x}) + \sum_{i=1}^p \nu_i^* h_i(\vec{x}) \right)$$

$$\textcircled{1} \quad \leq f_0(\vec{x}^*) + \underbrace{\sum_{i=1}^m \lambda_i^* f_i(\vec{x}^*)}_{\leq 0} + \underbrace{\sum_{i=1}^p \nu_i^* h_i(\vec{x}^*)}_{=0}$$

↑ Lagrangian

$$p^* = \min_{\vec{x}} f_0(\vec{x})$$

$$d^* = \max_{\vec{\lambda} \geq 0} g(\vec{\lambda}, \vec{\nu})$$

$$f_i(\vec{x}) \leq 0 \quad \forall i \quad 1 \leq i \leq m$$

$$h_i(\vec{x}) = 0 \quad \forall i \quad 1 \leq i \leq p$$

$$L(x, \lambda, \nu) = f_0(x) + \sum \lambda_i f_i(x) + \sum \nu_i h_i(x)$$

$\min_{\vec{x}} L(x, \lambda, \nu)$ ← this is an unconstrained minimization. \vec{x} doesn't have to be in feasible set.

$$\textcircled{2} \quad \leq f_0(\vec{x}^*) + 0 + 0 = f_0(\vec{x}^*) = g(\vec{\lambda}^*, \vec{\nu}^*)$$

Both inequalities $\textcircled{1} \neq \textcircled{2}$ must be equalities! (in special case of strong duality).

$$\textcircled{1} \Rightarrow \min_{\vec{x}} L(\vec{x}^*, \vec{\lambda}^*, \vec{\nu}^*) = L(\vec{x}^*, \vec{\lambda}^*, \vec{\nu}^*)$$

$$\textcircled{2} \Rightarrow \sum_{i=1}^m \lambda_i^* \underbrace{f_i(\vec{x}^*)}_{\leq 0} = 0 \quad \Rightarrow \lambda_i^* f_i(\vec{x}^*) = 0 \quad \forall i \quad 1 \leq i \leq m$$

non-positive term
not-neg term

$$\text{if } \lambda_i^* > 0 \Rightarrow f_i(\vec{x}^*) = 0$$

$$f_i(\vec{x}^*) < 0 \Rightarrow \lambda_i^* = 0$$

Complementary slackness
(applies to non-convex fcn's → note; we only assumed strong duality, not convexity?)

Karush Kuhn Tucker KKT Conditions

- ↳ these are necessary conditions (i.e. $F, \vec{x}^*, \vec{\lambda}^*, \vec{v}^*$ are optimal)
- Primal optimal \vec{x}^* & dual optimal $(\vec{\lambda}^*, \vec{v}^*)$
- strong duality holds
- differentiable f_i 's, h_i 's
- non-convex problems OK

$\vec{x}^*, \vec{\lambda}^*, \vec{v}^*$ optimality \Rightarrow

- ① $f_i(\vec{x}^*) \leq 0 \quad i=1, \dots, m$
- ② $h_i(\vec{x}^*) = 0 \quad i=1, \dots, p$
- ③ $\lambda_i^* \geq 0 \quad \forall i=1, \dots, m$
- ④ $\lambda_i^* f_i(\vec{x}^*) = 0 \quad \forall i=1, \dots, m$ (complementary slackness)
- ⑤ $\nabla f_0(\vec{x}^*) + \sum \lambda_i^* \nabla f_i(\vec{x}^*) + \sum v_i^* \nabla h_i(\vec{x}^*) = 0$
↳ \vec{x}^* minimizes $L(\vec{x}, \vec{\lambda}^*, \vec{v}^*)$

↳ proved earlier if strong duality

holds using complementary slackness.

implied by the main thm

KKT Conditions II - Sufficient Conds

- convex problems
- differentiable
- strong duality doesn't necessarily hold

Sufficient cond: $\tilde{x}, \tilde{\lambda}, \tilde{v}$ are points

$f_i \quad i=0, \dots, m$ convex

$$\{x \mid f_i(x) \leq 0\}$$

h_i : affine

- ① $f_i(\tilde{x}) \leq 0 \quad i=1, \dots, m$
- ② $h_i(\tilde{x}) = 0 \quad i=1, \dots, p$
- ③ $\tilde{\lambda} \geq 0 \quad i=1, \dots, m$
- ④ $\tilde{\lambda} \cdot f_i(\tilde{x}) = 0$
- ⑤ $\nabla f_0(\tilde{x}) + \sum \tilde{\lambda} \nabla f_i(\tilde{x}) + \sum \tilde{v} \nabla h_i(\tilde{x}) = 0$

↳ then $\tilde{x}, \tilde{\lambda}, \tilde{v}$ are primal & dual optimum

↳ if $\tilde{x}, \tilde{\lambda}, \tilde{\nu}$ satisfy KKT

+ convex

+ h_i affine

+ Slater condition

+ strong duality

$\Leftrightarrow \tilde{x}, \tilde{\lambda}, \tilde{\nu}$ are primal & dual optimal