

Assessing Environmental Inequality in Air Pollution Exposure

Preliminary Analysis for Final Research Paper

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Introduction

Background: Environmental Inequality

Lower socioeconomic status and racialized communities often face higher pollution exposure. In Canada, evidence exists but is fragmented and inconsistent across cities.

Research Gap in Canadian Context

- Canadian evidence on socioeconomic inequality in pollution exposure existed but was fragmented.
- Existing studies rarely control for key physical confounders (population density, industrial activity, road networks).
- No prior Canadian study has tested whether income and racial composition jointly shape pollution exposure.

Hypotheses

- **H1: Socioeconomic Inequality**

Income ↓, Education ↓, \implies PM_{2.5} ↑

- **H2: Robust SES Effects (after controls)**

SES \implies PM_{2.5} even after controlling for: $\begin{cases} \text{Industrial emissions} \\ \text{Major roads} \\ \text{Population density} \end{cases}$

- **H3: Compounded Vulnerability (Interaction)**

Income ↓ \times Minority Share ↑ \implies PM_{2.5} ↑↑

Data and Variables

Data sources

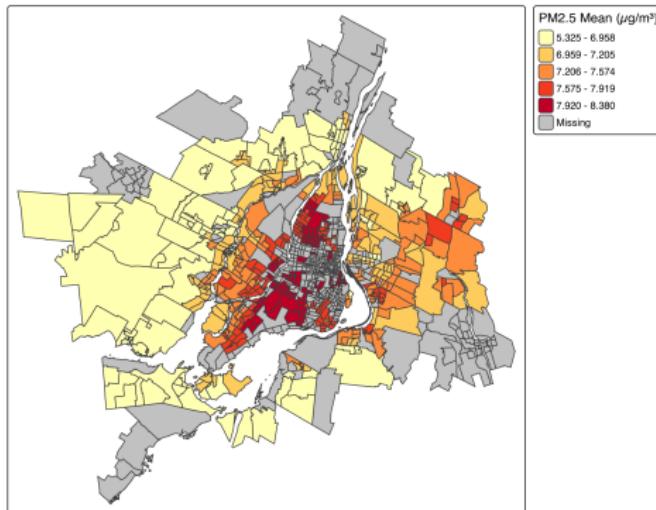
- Census 2016: median income, education rate (share with university degree), visible minority share, population density
- NASA PM_{2.5} (2016–2018): satellite-based annual average concentrations
- NPRI (2016–2018): industrial emissions (facility-level)
- Road Network File 2016: major road density

Study area: Montréal

- 970 Census Tracts in the original dataset
- After removing records with missing values: **478 complete CTs used for analysis**

Explanatory Analysis: Spatial Distribution of PM_{2.5}:

PM2.5 Spatial Distribution

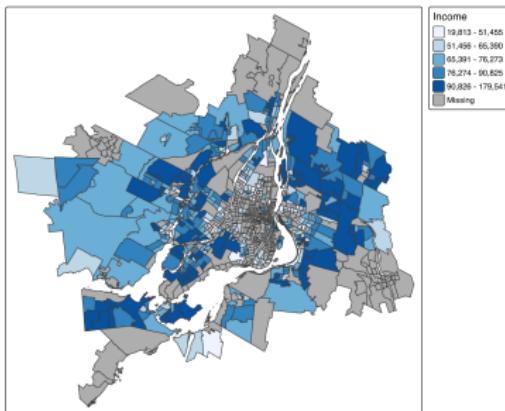


Key Observation

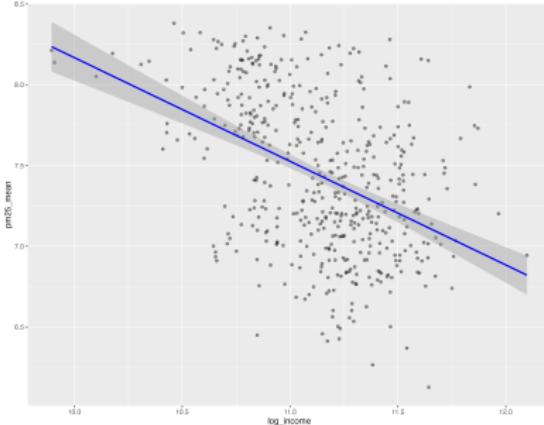
PM_{2.5} concentrations are highest in the central and eastern parts of Montréal, showing a clear spatial gradient across the city.

Explanatory Analysis: Income and PM_{2.5}

Income by Census Tract



Log Income vs PM_{2.5} (3-year average)



Median Income (Map)

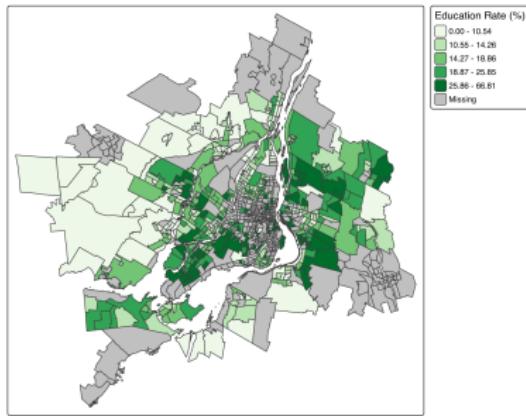
Income vs. PM_{2.5} (Scatter)

Key Observation

Lower-income Census Tracts tend to have higher PM_{2.5} concentrations.

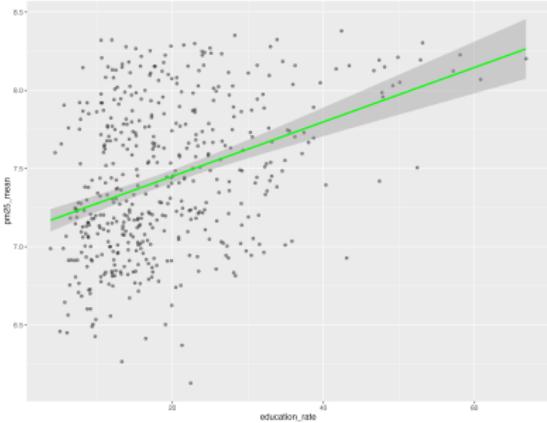
Explanatory Analysis: Education and PM_{2.5}

Education Rate by Census Tract



Education Rate (Map)

Education Rate vs PM_{2.5}



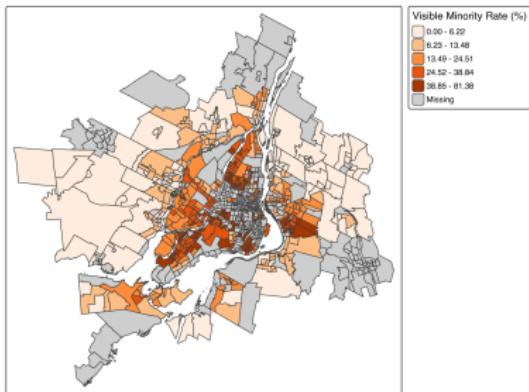
Education Rate vs. PM_{2.5} (Scatter)

Key Observation

Higher education areas show higher PM_{2.5}, but this reflects urban core concentration of highly educated residents rather than SES disadvantage..

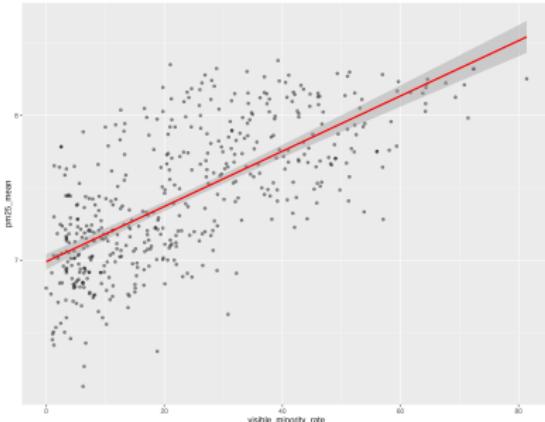
Explanatory Analysis: Visible Minority and PM_{2.5}

Visible Minority Share



Visible Minority Share (Map)

Visible Minority Ratio vs PM_{2.5}



Visible Minority vs. PM_{2.5} (Scatter)

Key Observation

Areas with a higher share of visible minority residents tend to have systematically higher PM_{2.5} exposure.

Explanatory Analysis: Spatial Distribution of Structural Variables

Spatial Distribution of Structural Variables (each scaled 0–1)

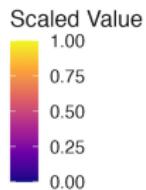
Population Density (scaled)



Industrial Emission (scaled)



Major Roads Length (scaled)



Interpretation

Population density, road density and industrial activity serve as essential physical confounders.

OLS Model Specification

Baseline model (H1):

$$PM_{2.5,i} = \beta_0 + \beta_1 Income_i + \beta_2 EducationRate_i + \beta_3 MinorityShare_i + \epsilon_i$$

(Income and education capture socioeconomic status; MinorityShare represents racial composition. Education rate may function as a proxy for urban core structure rather than SES.)

Extended model with controls (H2):

$$+ \beta_4 Industrial_i + \beta_5 RoadDensity_i + \beta_6 PopDensity_i$$

Interaction model (H3):

$$+ \beta_7 (Income_i \times MinorityShare_i)$$

A log-income version of this model is also estimated.

OLS Results

	SES only	Full OLS	Interaction	Log OLS
(Intercept)	7.153 *** (0.068)	7.200 *** (0.077)	7.234 *** (0.090)	10.480 *** (1.092)
income	-0.000 *** (0.000)	-0.000 *** (0.000)	-0.000 *** (0.000)	
education_rate	0.015 *** (0.002)	0.014 *** (0.002)	0.014 *** (0.002)	0.013 *** (0.002)
visible_minorit y_rate	0.014 *** (0.001)	0.013 *** (0.001)	0.011 *** (0.003)	-0.051 (0.027)
total_industria l_emission		0.000 (0.000)	0.000 (0.000)	
major_road_km		-0.003 *** (0.001)	-0.003 *** (0.001)	
pop_density		-0.000 (0.000)	0.000 (0.000)	
income:visible_ minority_rate			0.000 (0.000)	
log_income				-0.334 *** (0.094)
log_major_road_ km				-0.082 * (0.037)
log_pop_density				0.054 * (0.022)
log_total_indus trial_emission				-0.007 (0.006)
log_income:visi ble_minority_ra te				0.006 * (0.002)
N	478	478	478	478
R2	0.562	0.583	0.583	0.592
Adj_R2	0.560	0.577	0.577	0.586
AIC	266.480	249.819	251.285	241.256
logLik	-128.240	-116.909	-116.642	-111.628

*** p < 0.001; ** p < 0.01; * p < 0.05.

Model Diagnostics: Why OLS is Not Enough

VIF (Model 2)

- income = 2.15; education = 1.47; minority = 1.79
- industrial = 1.03; roads = 1.41; density = 2.26
- → No multicollinearity concerns (all < 3)

RESET Test (Model 2)

- RESET statistic = 17.267, df = (2, 468), p-value = 5.817e08
- → Functional form misspecification detected

Moran's I for PM_{2.5}

- Moran's I = 0.89 ($p < 0.001$)
- → Very strong spatial autocorrelation

Implication

OLS residuals violate key assumptions (functional form + spatial independence). → OLS estimates may be biased, motivating the use of a Spatial Error Model (SEM).

Spatial Error Model (SEM): Specification and Results

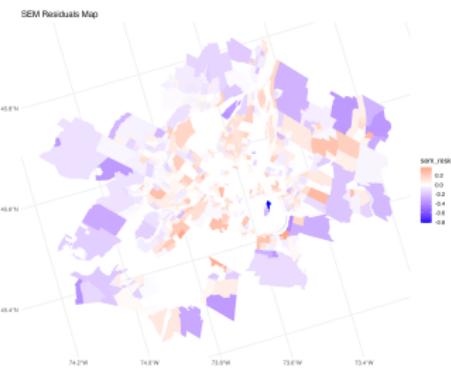
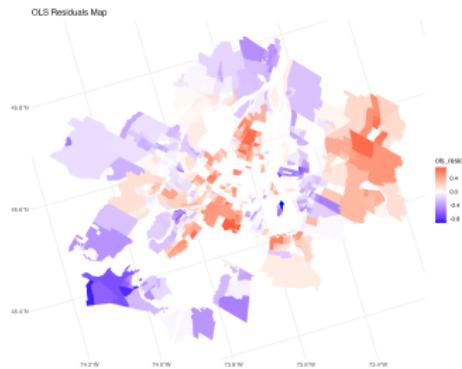
	SES
(Intercept)	7.715 *** (0.555)
log_income	-0.092 (0.048)
visible_minority_rate	-0.025 (0.014)
education_rate	0.005 *** (0.001)
log_major_road_km	0.019 (0.016)
log_pop_density	0.062 *** (0.009)
log_total_industrial_emission	0.006 (0.006)
log_income:visible_minority_rate	0.002 (0.001)
lambda	0.921 *** (0.011)
N	478
R2	0.932
AIC	-409.406
logLik	214.703

*** p < 0.001; ** p < 0.01; * p < 0.05.

Spatial Diagnostics: SEM Corrects Spatial Dependence

Spatial Autocorrelation (Residuals)

- OLS residual Moran's I = 0.89 ($p < 0.001$)
- SEM residual Moran's I = 0.076 ($p = 0.004$)



Interpretation

SEM greatly reduces spatial dependence in the residuals, indicating that the model successfully accounts for spatial error processes.

Conclusion

Conclusions

- **H1: Not supported.** Income is not significant in the SEM, and education's positive effect reflects urban-core density rather than SES inequality.
- **H2: Not supported.** After controlling for density, roads, and industry, SES variables lose significance. $\text{PM}_{2.5}$ variation is driven mainly by urban structure.
- **H3: Weak support.** The income \times minority interaction appears only in the log-OLS model and disappears in SEM.
- **Population density is the strongest predictor of $\text{PM}_{2.5}$ → urban structure is central to explaining pollution hotspots.**

Additional Insights

- SEM drastically reduces spatial autocorrelation → confirming that spatial models are essential for valid inference.

Limitations and Next Steps

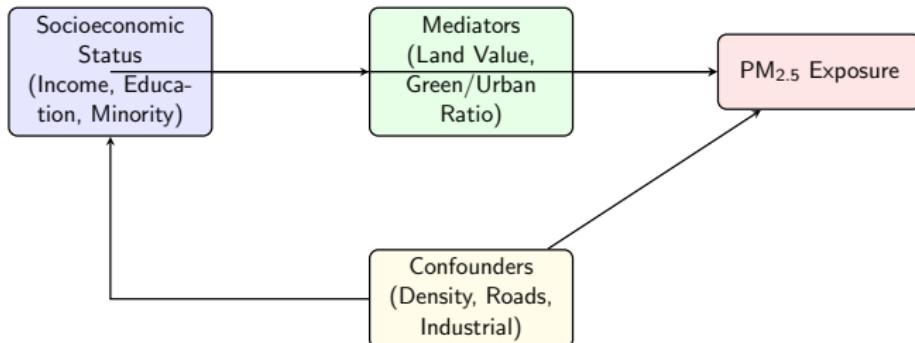
Limitations

- Findings are not yet generalizable across Canada.
- NO₂ and other pollutants are not included.
- Several Census Tracts were removed due to missing data, which may introduce spatial selection bias.
- Industrial emissions are aggregated at the tract level and may underrepresent point-source variation.

Next Steps

- Refine the SES specification in the final paper by reclassifying education as an indicator of urban spatial structure, rather than treating it as a core SES component.
- Explore whether mediators (e.g., greenness, land value, urban form) statistically amplify SES-based exposure disparities.
- Extend spatial analysis to other major cities in Canada.

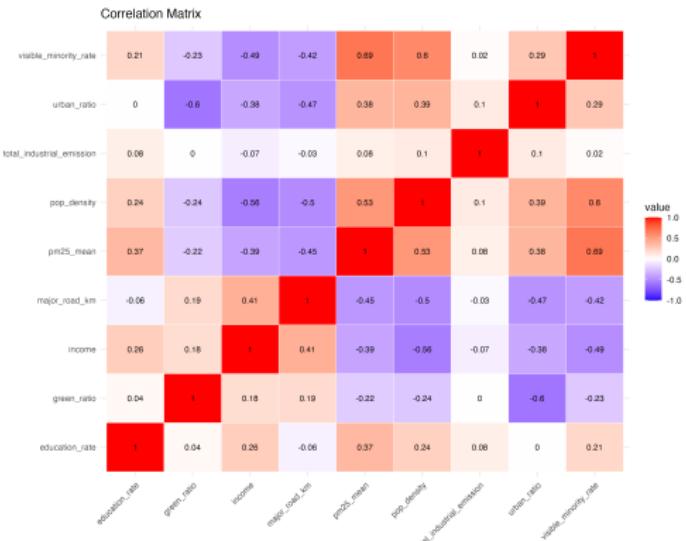
Appendix: SES, Confounders, and Mediators



Interpretation

- SES influences both neighborhood sorting and pollution exposure.
- Land value and green/urban ratio lie on the SES → PM pathway (mediators).
- Density, roads, and industrial activity affect both SES sorting and PM levels (confounders).

Appendix: Correlation Structure



- Socioeconomic variables correlate strongly with PM_{2.5}.
- Population density shows strong positive correlation (urban core effect).
- Green/urban ratios closely track SES → likely **mediators**.

Appendix: Spatial Error Model (SEM)

SEM structure

$$y = X\beta + u, \quad u = \lambda W u + \varepsilon$$

- y : Outcome ($PM_{2.5}$).
- X : Observed predictors (log-income, education, minority share, roads, population density, industry).
- β : Effect of each predictor (similar to OLS).
- W : Spatial weights matrix (4-nearest-neighbors).
- u : Spatially correlated error term capturing unobserved spatial processes.
- λ : Spatial error dependence ($\lambda = 0.921$).
- ε : i.i.d. random noise.

Intuition

SEM corrects for unobserved spatial factors that violate OLS assumptions. It removes spatial clustering in residuals and produces unbiased estimates.