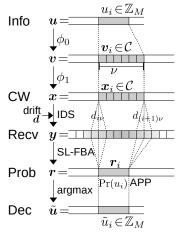
## **Constrained coding + Synchronization**

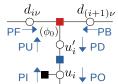


block length: N (symbol)  $N\nu$  (bit)

$$\begin{array}{l} \phi_0: \mathbb{Z}_M \to \mathcal{C} & \text{(encoding)} \\ \boldsymbol{v}_i = \phi_0(\boldsymbol{u}_i) \in \mathcal{C} & (\boldsymbol{u}_i \in \mathbb{Z}_M) \\ \phi_1: \mathcal{C}^{l_0} \times \mathcal{C} \to \mathcal{C} & \text{(constraint)} \\ \boldsymbol{x}_i = \phi_1(\boldsymbol{x}_{i-l_0}^{i-1}, \boldsymbol{v}_i) & \text{(priority)} \ \mathbf{H} \\ = \begin{cases} \boldsymbol{v}_i & (\mathbbm{1}_{\rho,\ell,\delta}[\boldsymbol{x}_{i-l_0}^{i-1}, \boldsymbol{v}_i] = 1) \\ \overline{\boldsymbol{v}}_i & (\mathbbm{1}_{\rho,\ell,\delta}[\boldsymbol{x}_{i-l_0}^{i-1}, \overline{\boldsymbol{v}}_i] = 1) \\ (\overline{\boldsymbol{v}}\boldsymbol{v})^{\frac{\nu}{2}} & (\mathbbm{1}_{\rho,\ell,\delta}[\boldsymbol{x}_{i-l_0}^{i-1}, (\overline{\boldsymbol{v}}\boldsymbol{v})^{\frac{\nu}{2}}] = 1) \\ (\boldsymbol{v}\overline{\boldsymbol{v}})^{\frac{\nu}{2}} & (\mathbbm{1}_{\rho,\ell,\delta}[\boldsymbol{x}_{i-l_0}^{i-1}, (\boldsymbol{v}\overline{\boldsymbol{v}})^{\frac{\nu}{2}}] = 1) \end{cases} \\ \boldsymbol{l}_0 = \begin{bmatrix} \ell-1 \\ \boldsymbol{l} \end{bmatrix} \quad \boldsymbol{v}: \text{ first bit of } \boldsymbol{v}_i \end{cases}$$

**SL-FBA** 

 $\begin{aligned} p(\boldsymbol{y}, \boldsymbol{x}, \boldsymbol{u}, \boldsymbol{d}) & \left(\phi_0(u_i') = \boldsymbol{x}_{i\nu}^{(i+1)\nu-1}\right) \\ &= p(\boldsymbol{y}|\boldsymbol{x}, \boldsymbol{u}, \boldsymbol{d}) p(\boldsymbol{x}, \boldsymbol{u}) p(\boldsymbol{d}) = p(\boldsymbol{y}|\boldsymbol{x}, \boldsymbol{d}) p(\boldsymbol{x}|\boldsymbol{u}) p(\boldsymbol{u}) p(\boldsymbol{d}) = p(\boldsymbol{y}|\phi_0(\boldsymbol{u}'), \boldsymbol{d}) p(\boldsymbol{u}'|\boldsymbol{u}) p(\boldsymbol{u}) p(\boldsymbol{d}) \\ &= p(d_0) \prod_{i=0}^{N-1} p\left(\boldsymbol{y}_{i\nu+d_{i\nu}}^{(i+1)\nu+d_{(i+1)\nu}-1} \middle| \boldsymbol{x}_{i\nu}^{(i+1)\nu-1}, d_{i\nu}, d_{(i+1)\nu}\right) p\left(\boldsymbol{x}_{i\nu}^{(i+1)\nu-1} \middle| \boldsymbol{u}_0^i\right) p(u_i) p(d_{(i+1)\nu}|d_{i\nu}) \\ &\simeq p(d_0) \prod_{i=0}^{N-1} p\left(\boldsymbol{y}_{i\nu+d_{i\nu}}^{(i+1)\nu+d_{(i+1)\nu}-1} \middle| \phi_0(u_i'), d_{i\nu}, d_{(i+1)\nu}\right) p\left(u_i'|u_i\right) p(u_i) p(d_{(i+1)\nu}|d_{i\nu}) \\ &= \text{GX[Nu2][y][x]} & \text{ECM[uin][uout]} & \text{GD[d0][d1]} \end{aligned}$ 



 $\begin{vmatrix} x_{i\nu} & , a_{i\nu}, a_{(i+1)\nu} \end{pmatrix} p \begin{pmatrix} x_{i\nu} & | u_0 \end{pmatrix} p(u_i) p(a_{(i+1)\nu} | a_i) \\ +d_{(i+1)\nu}^{-1} & \phi_0(u_i'), d_{i\nu}, d_{(i+1)\nu} \end{pmatrix} p \begin{pmatrix} u_i' | u_i \end{pmatrix} p(u_i) p(d_{(i+1)\nu} | d_{i\nu}) \\ \text{GX[Nu2][y][x]} & \text{ECM[uin][uout]} & \text{GD[d0][d1]} \\ \text{Nu2: } 0...\text{Nu*2} & \text{uin: } 0...\text{M-1} & \text{d0: Dmin...Dmax} \\ \text{y: } & 0...\text{2-Nu2-1} & \text{uout: } 0...\text{M-1} & \text{d1: Dmin...Dmax} \\ \text{x: } & 0...\text{Q-1} & \text{(approximation)} \\ \text{Nu2 range: } \text{Nu2min...max} \\ \text{d range: not bounded}$ 

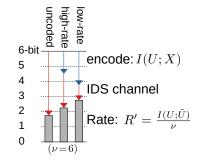
## Constraint

 $\begin{array}{ll} \text{run-length:} & \rho \\ \text{local-balance:} & (\ell,\delta) \\ & \ell: \text{even} \\ & \left| w(\boldsymbol{x}_i^{i+\ell-1}) - \frac{\ell}{2} \right| \leq \delta \end{array}$ 

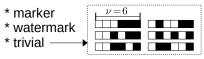
#### **IDS** channel

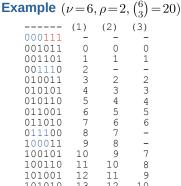
$$\begin{split} p_{\rm i}, p_{\rm d}, p_{\rm s} : & \text{ins/del/sub probability} \\ d_{\rm min} < 0 : & \text{drift min} \\ d_{\rm max} > 0 : & \text{drift max} \\ \mathcal{D} = & \{d \!\in\! \mathbb{Z} | d_{\rm min} \!\leq\! d \!\leq\! d_{\rm max} \} \end{split}$$

## Performance measure



#### **Baseline**



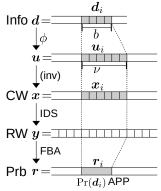


101001 12 11 9 101010 13 12 10 101100 14 13 11 110001 15 - - -110010 16 14 12 110100 17 15 13 111000 - - -

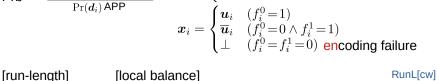
insertion  $p_{\rm i}$ :

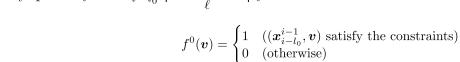
 $\begin{array}{ll} p_{\mathrm{d}}: & \text{deletion} \\ p_{\mathrm{d}}: & \text{deletion} \\ p_{\mathrm{s}}(y|x): & \text{asymmetric error} \\ d_{\mathrm{min}} < 0: & \text{drift min} \\ d_{\mathrm{max}} > 0: & \text{drift max} \\ \mathcal{D} \!=\! \big\{ d \!\in\! \mathbb{Z} \big| d_{\mathrm{min}} \!\leq\! d \!\leq\! d_{\mathrm{max}} \big\} \end{array}$ 

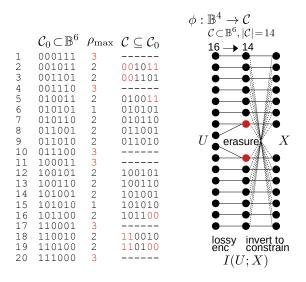
## **Constrained coding + Synchronization**



$$\mathcal{C} \subset \mathbb{B}^{\nu} \ (|\mathcal{C}| \leq 2^b) \longleftarrow \text{Inner code (not bijective)} \\ \phi: \mathbb{B}^b \to \mathcal{C} & \text{length: } \nu \ (\text{even}) \\ \boldsymbol{d}_i \in \mathbb{B}^b & \text{balanced: } w(\boldsymbol{u}) = \nu/2 \\ \boldsymbol{u}_i = \phi(\boldsymbol{d}_i) \in \mathcal{C} & \text{invertible: } \boldsymbol{u} \in \mathcal{C} \to \overline{\boldsymbol{u}} \in \mathcal{C} \\ l_0 = \left\lceil \frac{\ell-1}{\nu} \right\rceil & (\forall \boldsymbol{u} \in \mathcal{C}) \\ f_i^0 = \begin{cases} 1 & ((\boldsymbol{x}_{i-l_0}^{i-1}, \boldsymbol{u}_i) \text{ satisfy the constraints}) \\ 0 & (\text{otherwise}) \end{cases} \\ f_i^1 = \begin{cases} 1 & ((\boldsymbol{x}_{i-l_0}^{i-1}, \overline{\boldsymbol{u}}_i) \text{ satisfy the constraints}) \\ 0 & (\text{otherwise}) \end{cases}$$





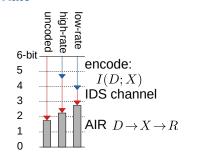


## **Constraint**

$$\begin{split} & \text{run-length:} \quad \rho \\ & \text{local-balance:} \ (\ell, \delta) \\ & \ell : \text{even} \\ & \left| w(\boldsymbol{x}_i^{i+\ell-1}) - \frac{\ell}{2} \right| \leq \delta \end{split}$$

## Rate

RunR[cw] WtL[cw][idx] WtR[cw][idx]

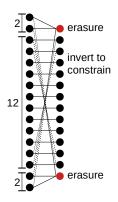


baseline: constraint only

IDS only

decoding: SL-FBA outer code: NB-LDPC (?) performance: code rate

AIR



## **Constrained non-binary IDS channel**

\* channel input/output alphabet:

$$\Sigma = \{0, 1, 2, 3\}$$

 $\star$  block length: n

\* input: 
$$x=(x_0,\ldots,x_{n-1})\in \Sigma^n$$
  
\* output:  $y=(y_0,\ldots,y_{n'-1})\in \Sigma^{n'}$ 

\* input constraint:

- run-length:  $f_{\rm R}(\boldsymbol{x}) \leq \rho$ 

- local-balance:  $(\ell,\epsilon)$ 

$$\max_{i} \left| \frac{1}{2} - f_{\mathrm{B}}(\phi_w(\boldsymbol{x}_i^{i+\ell-1})) \right| \le \varepsilon$$

\* error model

insertion  $p_{\rm i}$ : deletion  $p_{\rm d}$ :

 $p_{\mathrm{s}}(y|x)$  : asymmetric error

 $d_{\min} < 0$  : drift min  $d_{\rm max} \! > \! 0$  : drift max

$$\mathcal{D} = \{ d \in \mathbb{Z} | d_{\min} \leq d \leq d_{\max} \}$$

\* performance measure:

\* code rate

\* mutual info (AIR)

\* mappings

$\phi_x: \mathbb{B} \times \mathbb{B} \to \Sigma$	$\overline{w}$	d	$\phi_x(w,d)$
$\phi_w:\Sigma\to\mathbb{B}$	0	0	0
$\phi_d:\Sigma\to\mathbb{B}$	0	1	1
	1	0	2
$\phi_x(\phi_w(x),\phi_d(x)) = x$	1	1	3

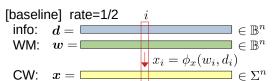
\* functions

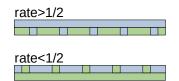
max run-length:  $f_{\mathrm{R}}({m v})$ 

local-balance (binary):

$$f_{\mathrm{B}}(\boldsymbol{u}_{i}^{i+\ell-1}) = w(\boldsymbol{u}_{i}^{i+\ell-1})/\ell$$
:

# **Constrained non-binary WM**





WM: synchronization:?

run-length:  $f_{\mathrm{R}}(m{w}) \leq 
ho$  local-balance:  $\max_i \left| \frac{1}{2} - f_{\mathrm{B}}(m{w}_i^{i+\ell-1}) \right| \leq arepsilon$ 

[decoding (detection)] SPA on factor graph

## WM design

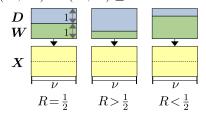


[generalize]

$$\phi_x: \mathcal{M} \times \Sigma^{\nu} \to \Sigma^{\nu} \ (1 \le |\mathcal{M}| < 2^{2\nu})$$

rate:  $R = \frac{\log_2 |\mathcal{M}|}{2\nu}$ 

$$I(\boldsymbol{X}; \boldsymbol{W}) + I(\boldsymbol{X}; \boldsymbol{D}) \le 2$$



maximize I(X; W)?

k + k + k

index ↔ W: mutual info