



# Fundamentals of ML & DL CASA course (12/10/2018)

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#### Plan for TS2

- Frameworks evolution
- Learning representations from data
- Branches of ML
- Overfitting & Underfitting
- Evaluating ML models
- Universal workflow of ML

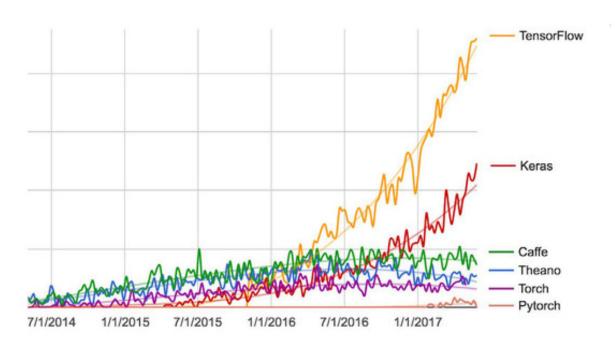








#### Frameworks evolution













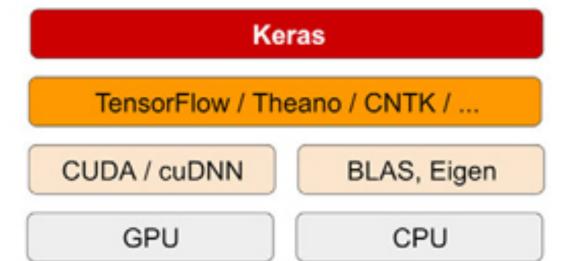








#### Frameworks evolution





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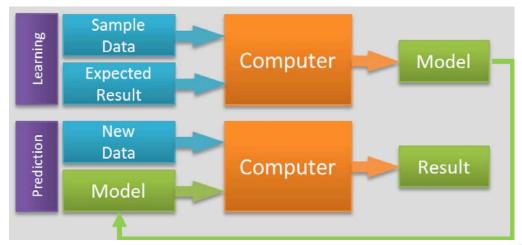


#### CV & ML

Traditional modeling - CV (feat.ext.)+ML(class.):



#### Deep learning:













To do ML we need:

- 1. Input data points.
  - If the task is image tagging, pictures are needed.
  - If the task is speech recog., people speaking samples are needed.
- 2. Examples of expected output.
  - In the image task, samples already tagged.
  - In the speech recog. Task, transcriptions of the sound files.









To do ML we need:

- 3. A measurement of how good is the algorithm working.
  - Distance between current output and expected output.
  - This measurement is a feedback signal to adjust the algorithm → This adjustment is known as **learning**.

Problem to solve in ML & DL:

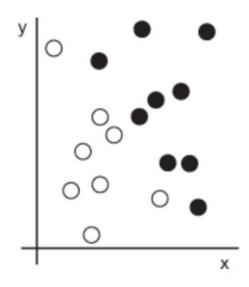
To learn useful representations of the input data











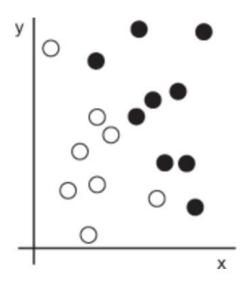
Lets say we want to develop an algorithm that take coordinates (x,y) of a point and output whether that point is likely to be black or white.











#### Inputs?

Expected outputs?

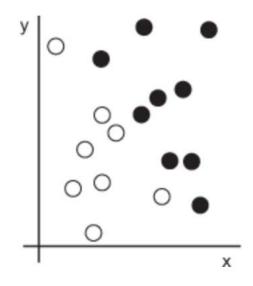
A measurement?











Inputs? Points coordinates.

Expected outputs?

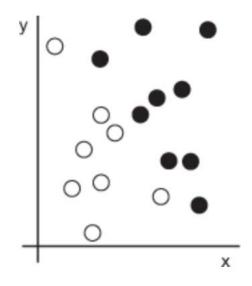
A measurement?











Inputs? Points coordinates.

Expected outputs? Color of our points.

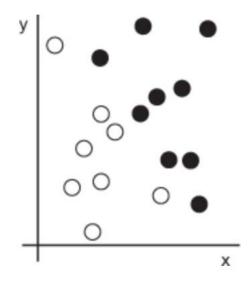
A measurement?











Inputs? Points coordinates

Expected outputs? Color of our points

A measurement? Percentage of points that are being corrected classified







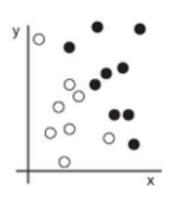


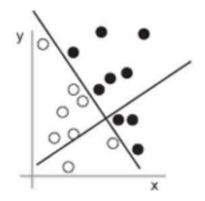


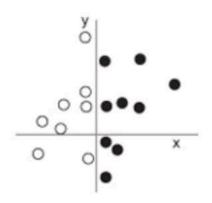
Raw data

Coordinate change

Better representation







A new coordinate systems provides a new representation of our data With this representation:

Black points are such that x>0

White points are such that x<0

The new representation solves the classification problem.



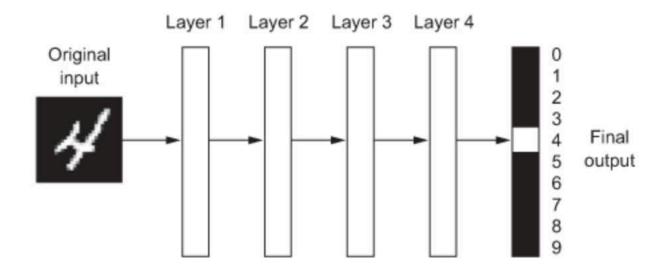








Neural network term is a reference to neurobiology. But DL models are not models in the brain. No evidence.

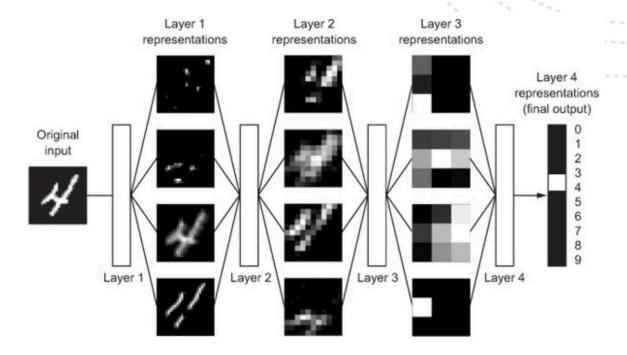












DL is a multistage way to learn data representations.



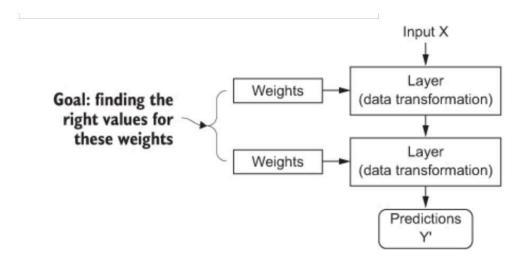








The specification of what a layer does to its input data is stored in the layer's weights.



The transformation implemented by a layer is parameterized by its weights.



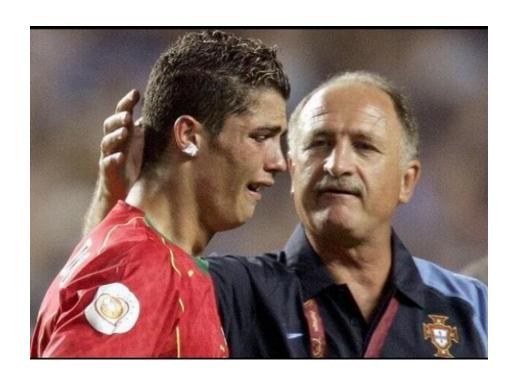








Problem: A deep neural network can contain tens of millions of parameters.









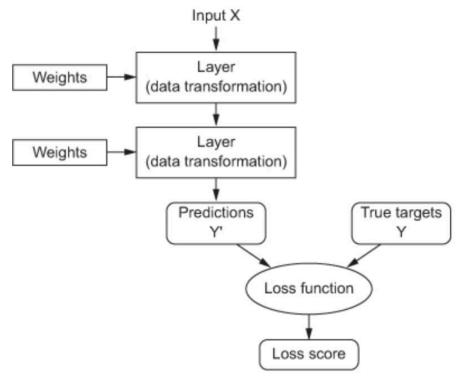




To control something...we need to observe it.

To control de output of a NN we need to measure how far is it from the target. Solution: **loss function** 

Takes NN predictions and true target and computes a distance score









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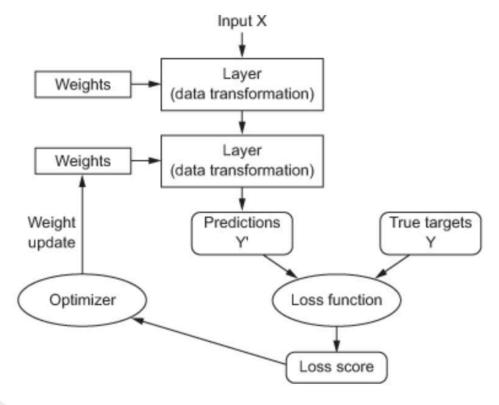






How can we use the loss function information as a feedback signal to adjust weights in a proper way (reduce the loss)?

Solution: optimizer which implements backpropagation









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#### Remember LS1



mymodel.compile(optimizer='rmsprop', loss='categorical\_crossentropy', metrics=['acc'])

Loss function  $\rightarrow$  How the network is able to measure its performance on the training data.

Optimizer > The mechanism through which the network will update Itself based on the data it sees and its loss function

Metrics → Measure to monitor during training and testing



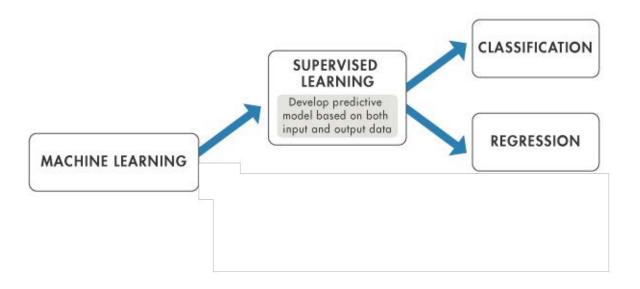








- Most common case (by far).
- Almost all applications of DL in the spotlight.
- Machine learns to map input data to known targets.













#### More variants:

•Sequence generation → Given a picture, predict a caption describing it.







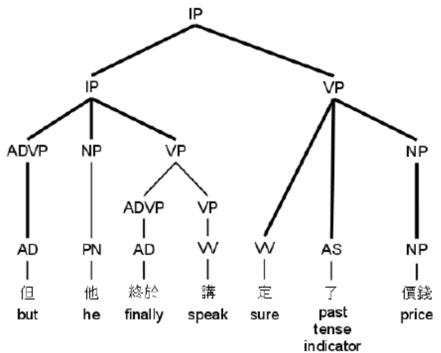






#### More variants:

•Syntax tree prediction  $\rightarrow$  Given a sentence, predict its decomposition into a syntax tree.





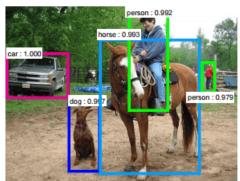


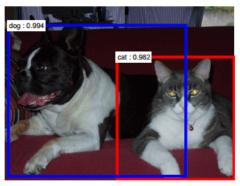


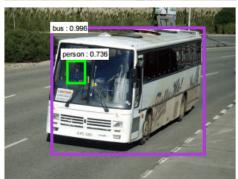




•Object detection → Given a picture, draw a bounding box around certain objects inside the picture.













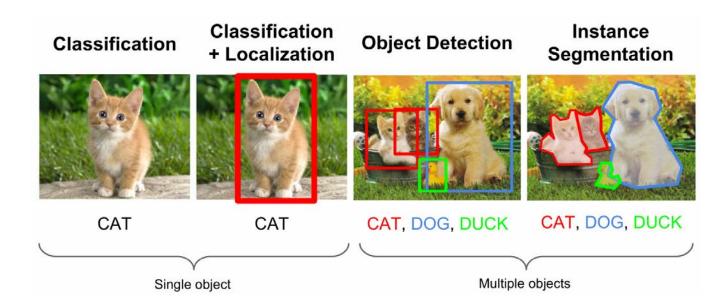






#### More variants:

•Image segmentation → Given a picture, draw a pixel level mask on a specific object.













- Find interesting transformations of the input data, without the help of any labels.
- Where? Data visualization, data compression, data denoising.
- Used in data analtytics → Necessary step in better understanding a dataset before doing supervised ML.
- Variants:
  - Dimensionality reduction
  - Clustering

























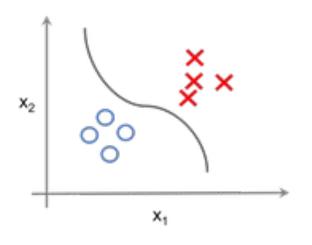


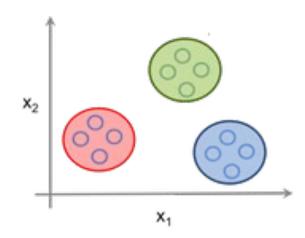




Supervised learning

Unsupervised learning















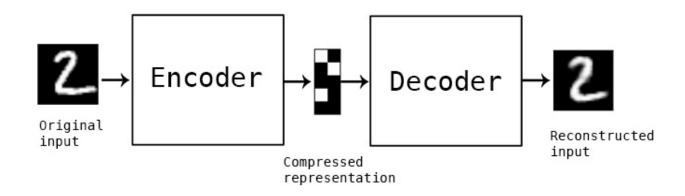








- Supervised learning without human-annotated labels.
- Autoencoders → Same input is the target.







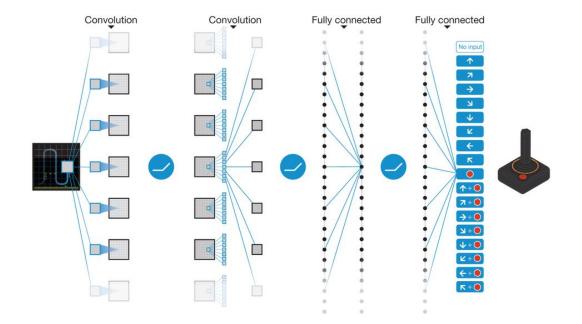




#### Branches of ML: Reinforcement learning



• An agent receives information about its environment and learns to choose actions that maximize some reward. https://www.youtube.com/watch?v=V1eYniJ0Rnk





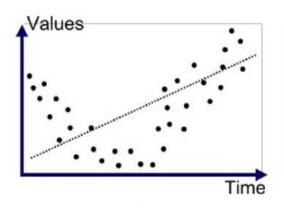


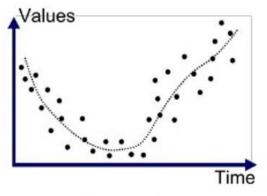


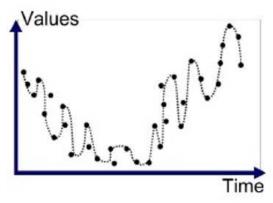


#### Overfitting & Underfitting

#### Generalization is the key







Underfitted

Good Fit/Robust

Overfitted



















#### Overfitting & Underfitting



















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#### Overfitting & Underfitting





Milan!



Tottenham!



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## Overfitting & Underfitting Overfitting



New test samples..



Fly Emirates

Madrid!

Madrid!

Sassuolo!

Generalization  $\rightarrow$  To perform well on never-before-seen data.









#### **Evaluating ML models**



So far, we have splitted datasets into training and test samples.

Why dont we evaluate the model on the train set?









#### **Evaluating ML models**

Why dont we evaluate the model on the train set?

Female!!!



Model overfits quickly. No generalization









Awesome...then we will have two sets, training and test sets.

Eeeem....not so fast.











If we train and test with the same dataset → Overfitting Weights are tunned based on the same data...no learning.

When we create a model...we tune hyperparameters.

- Number of layers
- Size of layers (units per layer)
- Etc.

If we do this tunning based on the test...we are still overfitting.

Information leaks → Every time we tune a hyperparameter based on the test data performance, some information about the test dataset leaks into the model....we are creating our model using test data!!









RULE 1: Data is aways raw...preprocessing is necessary.

RULE 2: Split your dataset into training, validation and test sets.









RULE 2: Split your dataset into training, validation and test sets.

Where is the validation set? Extract it from the training set...20% validation - 80% training. Be careful with data representativeness.

Training set is ordered: [ 0 1 2 3 4 5 6 7 8 9]

Test set....forget about it! Don't touch it until the end.





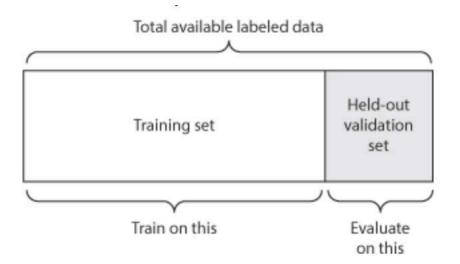




RULE 2: Split your dataset into training, validation and test sets.

Approaches:

Simple hold out:







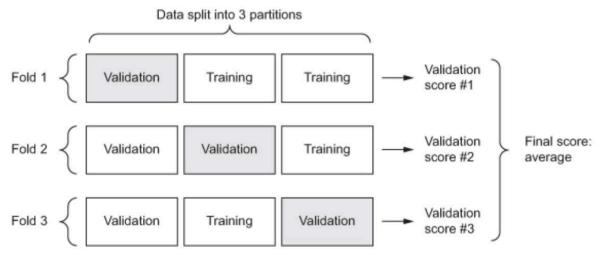




RULE 2: Split your dataset into training, validation and test sets.

### Approaches:

K-Fold Cross Validation











RULE 2: Split your dataset into training, validation and test sets.

### Approaches:

Iterated K-Fold validation with suffling →

- When we have very little available data.
- Apply K-Fold multiple times...shuffling data every time before splitting.
- PxK models are evaluated (expensive).











1. Defining the problem and assembling the datasets



Define the problem at hand:

- What will your input data be? What is your question?
  - Bear in mind: no data, no business.

#### Movie Reviews



http://www.rottentomatoes.com

http://www.cs.cornell.edu/people/pabo/movie-review-data/

#### Negative

most of the problems with the film don't derive from the screenplay, but rather the mediocre performances by most of the actors involved

#### **Postive**

the film provides some great insight into the neurotic mindset of all comics -- even those who have reached the absolute top of the game .









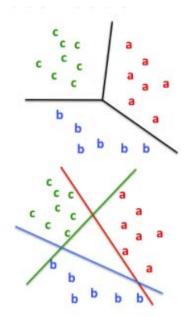




1. Defining the problem and assembling the datasets

Define the problem at hand:

- What will your input data be? What is your question?
  - Bear in mind: no data, no business.
- What type of problem are you facing?
  - Identifying the problem type will guide your choice of model architecture, loss function, etc.











1. Defining the problem and assembling the datasets



Define the problem at hand:

- What will your input data be? What is your question?
  - Bear in mind: no data, no business.
- What type of problem are you facing?
  - Identifying the problem type will guide your choice of model architecture, loss function, etc.

Do not move to the next stage until you know:

### What your inputs/outputs are

You are making two hypotheses:

- 1. You hypothesize that your outputs can be predicted (given your inputs).
- 2. You hypothesize that you have enough available data.









1. Defining the problem and assembling the datasets



Not all problems can be solved.

You may have inputs X and targets Y, but that doesn't mean X contains enough information to predict Y.

Tell me an example of an impossible problem (yet).









1. Defining the problem and assembling the datasets



#### The stock market









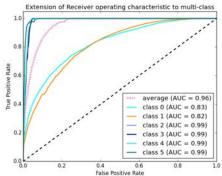


2. Choosing a measure of success

To control something, you need to observe it.

To achieve success, you need to define what you mean by success

Metric for success → Guides the choice of a loss function For balanced-classification problems → ROC AUC



#### Remember:

model.compile(optimizer='rmsprop', loss='categorical\_crossentropy', metrics=['acc'])





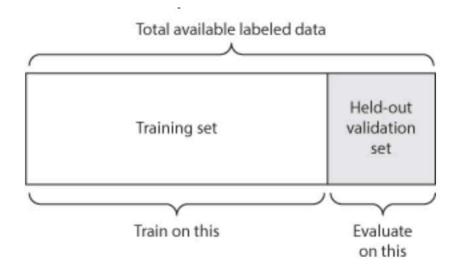




3. Deciding on an evaluation protocol

You must establish how you will measure you current progress:

• Hold-out validation set  $\rightarrow$  When you have plenty of data







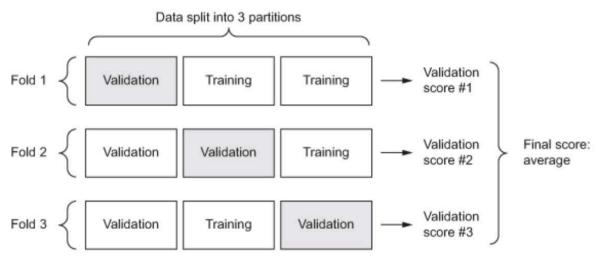




3. Deciding on an evaluation protocol

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- Hold-out validation set  $\rightarrow$  When you have plenty of data
- K-Fold cross-validation  $\rightarrow$  Too few samples for hold-out validation to be reliable.











3. Deciding on an evaluation protocol

You must establish how you will measure you current progress:

- Hold-out validation set  $\rightarrow$  When you have plenty of data
- K-Fold cross-validation  $\rightarrow$  Too few samples for hold-out validation to be reliable.
- Iterated K-Fold validation → For performing highly accurate model evaluation when little data is available.









### 4. Preparing your data

You must format your data in a way that can be fed into a DL/ML model.

#### 1- Data vectorization:

- All inputs in a NN must be tensors (floating point (float32) o integers)
- No matter your raw data is (images, sounds, text)....turn it into tensors.
- Wait!!! What are tensors?





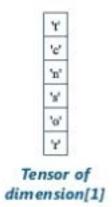




4. Preparing your data

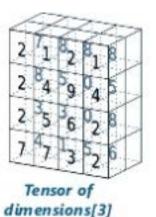
### 1- Data vectorization:

- All inputs in a NN must be tensors (floating points!)
- No matter your raw data is (images, sounds, text)....turn it into tensors.
- Wait!!! What are tensors?
  - Multidimensional arrays.



3	1	4	1
5	9	2	6
5	3	5	8
9	7	9	3
2	3	8	4
6	2	6	4







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4. Preparing your data

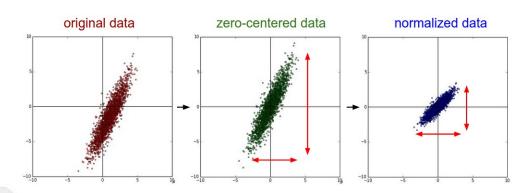


- 1- Data vectorization.
- 2- Value normalization:

Is not safe to feed into a NN data that takes large values o heterogeneous data.

Doing that can trigger large gradient updates → Prevents the NN form converging. To make learning easier for your network:

- 1. Take small values  $\rightarrow$  Usually in the 0 to 1 range (or -1 to 1 range).
- 2. Be homogeneous  $\rightarrow$  All features should take values in the same range.











#### 5. Baseline model



Goal  $\rightarrow$  Achieve statistical power = develop a model capable of beating a dumb classifier.

Let's consider a throwing a coin problem.

2 classes...what is the baseline case?

Let's consider the MNIST problem.

10 classes...what is the baseline case?









#### 5. Baseline model



Goal  $\rightarrow$  Achieve statistical power = develop a model capable of beating a dumb classifier.

Let's consider a throwing a coin problem.

2 classes...what is the baseline case?

Anything with an accuracy higher than 0.5 can be said to have statistical power

Let's consider the MNIST problem.

10 classes...what is the baseline case?

Anything with an accuracy higher than 0.1 can be said to have statistical power









#### 5. Baseline model



Goal  $\rightarrow$  Achieve statistical power = develop a model capable of beating a dumb classifier.

It is not always possible to achieve statistical power.

If you can't beat a random baseline after trying multiple architectures... Then may be that the answer to your question is not present in the input data...

Remember you made two hypotheses:

- You hypothesize that your outputs can be predicted (given your inputs).
- You hypothesize that you have enough available data.

They can be false!









#### 5. Baseline model



Goal  $\rightarrow$  Achieve statistical power = develop a model capable of beating a dumb classifier.

Let's assume things go well...three key choices to build our first model:

- Last-layer activation.
- Loss function.
- Optimization configuration.





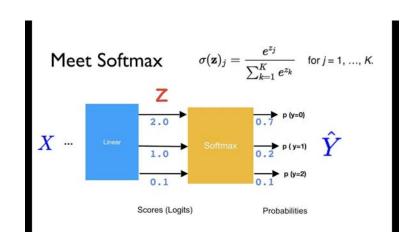


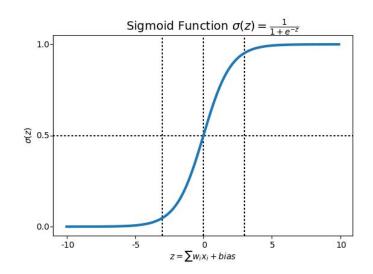


#### 5. Baseline model

Let's assume things go well...three key choices to build our first model:

- Last-layer activation:
  - Establishes a useful constraints on the NN output.













#### 5. Baseline model

Let's assume things go well...three key choices to build our first model:

- Last-layer activation:
  - Establishes a useful constraints on the NN output.
  - Do you want to know more about activation functions?:

https://www.youtube.com/watch?v=tf9p1xQbWNM

This list is brilliant (Hugo Larochelle):

https://www.youtube.com/playlist?list=PL6Xpj9I5qXYEcOhn7TqghAJ6NAPrNmUBH









#### 5. Baseline model



Let's assume things go well...three key choices to build our first model:

- Last-layer activation.
- Loss function:
  - Should match the type of problem you are solving.
  - Used to compare the networks predicted output with the real output.
  - It tells the model how the weights should be updated.
  - Common loss functions:
    - Mean squared error
    - Cross entropy (binary/categorical)
    - Etc.

#### Remember:

model.compile(optimizer='rmsprop', loss='categorical\_crossentropy', metrics=['acc'])









### 5. Baseline model



How to combine them with the type of problem?

- Last-layer activation.
- Loss function.

Table 4.1 Choosing the right last-layer activation and loss function for your model

Problem type	Last-layer activation	Loss function
Binary classification	sigmoid	binary_crossentropy
Multiclass, single-label classification	softmax	categorical_crossentropy
Multiclass, multilabel classification	sigmoid	binary_crossentropy
Regression to arbitrary values	None	mse
Regression to values between 0 and 1	sigmoid	mse or binary_crossentropy





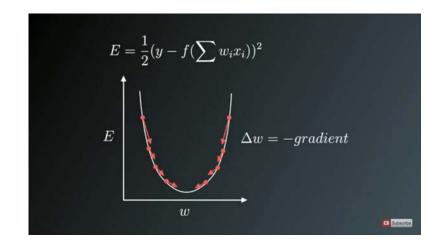




#### 5. Baseline model

Let's assume things go well...three key choices to build our first model:

- Last-layer activation
- Loss function
- Optimization configuration:
  - What optimizer you will use?
  - What learning rate?



#### Remember:

model.compile(optimizer='rmsprop', loss='categorical\_crossentropy', metrics=['acc'])









#### 5. Baseline model

Let's assume things go well...three key choices to build our first model:

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Read: <a href="https://towardsdatascience.com/types-of-optimization-algorithms-used-in-neural-networks-and-ways-to-optimize-gradient-95ae5d39529f">https://towardsdatascience.com/types-of-optimization-algorithms-used-in-neural-networks-and-ways-to-optimize-gradient-95ae5d39529f</a>

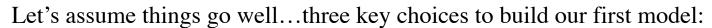








#### 5. Baseline model



- Last-layer activation
- Loss function
- Optimization configuration:

Stochastic Gradient Descent(SGD):

Updates weights every training sample...takes too long!

Loss function fluctuates to different intensities

Mini-batch Gradient Descent:

Updates weights every batch size of training samples

Leads us to stable convergence.

Range 64 to 256 works fine.

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#### **HOW CAN WE CODE THIS? ANY IDEA?**

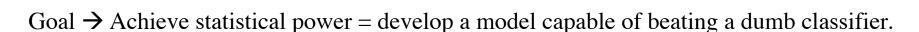








#### 5. Baseline model



Let's assume things go well...three key choices to build our first model:

- Last-layer activation
- Loss function
- Optimization configuration:

```
Stochastic Gradient Descent(SGD):
```

model.fit(x\_train, y\_train, epochs=5, **batch\_size=1**)

Mini-batch Gradient Descent:

model.fit(x\_train, y\_train, epochs=5, batch\_size=128)









5. Scaling up...create a model that overfits

Is your model enough poweful? Does it have enough layers? Is it the best model?

#### Remember:

- A NN with a single layer and 2 units have statistical power on MNIST.
- But it doesn't solve the problem well.

The true is: If your model doesn't overfit, probably is not enough.

To figure out how big a model you'll need, you must develop a model that overfits

How? Any ideas?

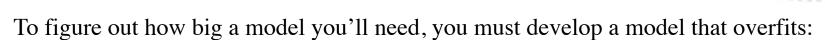






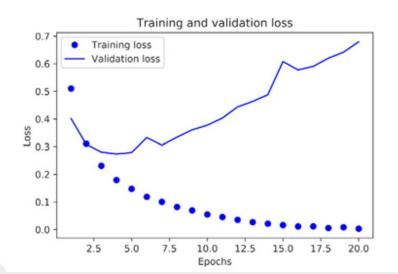


5. Scaling up...create a model that overfits



- 1. Add Layers.
- 2. Make the layer bigger.
- 3. Train for more epochs.

Always monitor training loss and validation loss.











6. Regularize your model

#### Next week!















