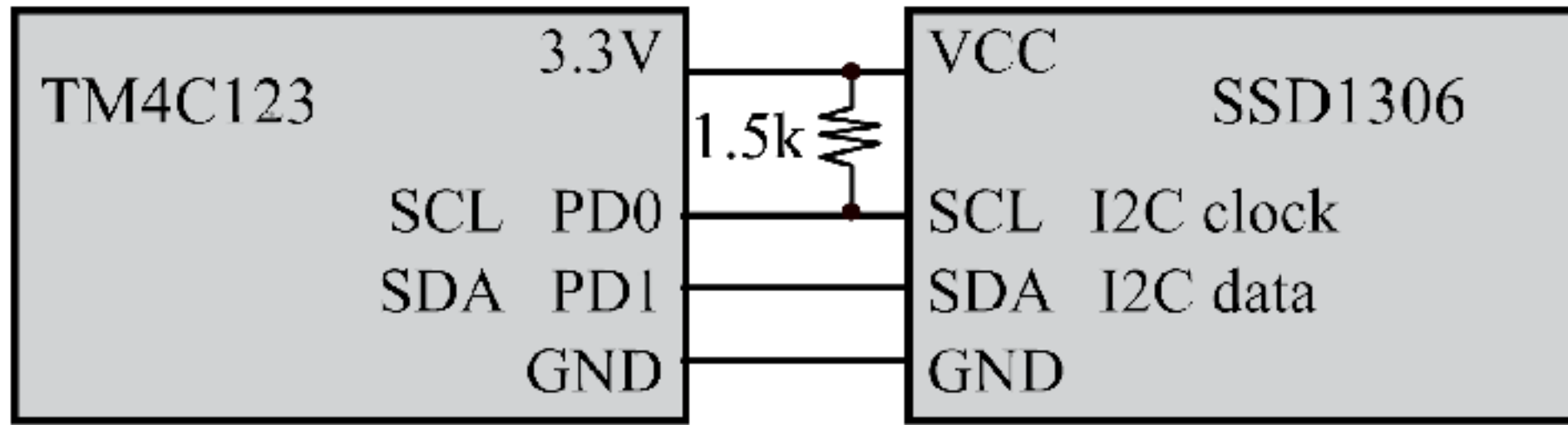


Part A : Build HW



Test HW by running the project.

You should test the hardware by running the SSD1306_4C123 starter project.

Part B : I2C Driver

; sends two bytes to specified slave
; Input: R0 7-bit slave address
; R1 first 8-bit data to be written.
; R2 second 8-bit data to be written.
; Output: 0 if successful, nonzero (error code) if error
; Assumes: I2C3 and port D have already been initialized and enabled

I2C_Send2

; --UUU--

- ; 1) wait while I2C is busy, wait for I2C3_MCS_R bit 0 to be 0
- ; 2) write slave address to I2C3_MSA_R,
; MSA bits 7-1 is slave address
; MSA bit 0 is 0 for send data
- ; 3) write first data to I2C3_MDR_R
- ; 4) write 0x03 to I2C3_MCS_R, send no stop, generate start, enable
; add 4 NOPs to wait for I2C to start transmitting
- ; 5) wait while I2C is busy, wait for I2C3_MCS_R bit 0 to be 0
- ; 6) check for errors, if any bits 3,2,1 I2C3_MCS_R is high
; a) if error set I2C3_MCS_R to 0x04 to send stop
; b) if error return R0 equal to error bits 3,2,1 of I2C3_MCS_R
- ; 7) write second data to I2C3_MDR_R
- ; 8) write 0x05 to I2C3_MCS_R, send stop, no start, enable
; add 4 NOPs to wait for I2C to start transmitting
- ; 9) wait while I2C is busy, wait for I2C3_MCS_R bit 0 to be 0
- ; 10) return R0 equal to bits 3,2,1 of I2C3_MCS_R, error bits
; will be 0 is no error

→ Start Here

→ i) Load I2C3_MCS_R
in reg

ii) Load data at location

iii) Extract bit 0

iv) compare to 0: if not 0
loop back
to start

```

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; 10) return R0 equal to bits 3,2,1 of I2C3_MCS_R, error bits
; will be 0 is no error

```

(2)

- i) Left shift R0
- ii) Make sure bit 0 of R0 is 0
- iii) Load MSA_R locⁿ in reg
- iv) Store R0 in MSA reg

(3)

- i) Load MDR_R locⁿ in reg
- ii) Store R1 in MDR reg

(4)

- i) mov 0x03 in reg
- ii) load MCS_R loc in reg
- iii) Store reg in MCS reg


```

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; 10) return R0 equal to bits 3,2,1 of I2C3_MCS_R, error bits
; will be 0 is no error

```

(Error) :

- (i) move error code to R0
- (ii) move 0x04 to reg

(4) iv) NOP (x4)

(5) Same as (1)

(6) (i) use MCS loaded in (5)

(ii) Right shift by 1

(iii) Extract bit 2,1,0 (0x07)

(iv) Compare with 0
(if not 0, Error)
else continue

(iii) load MCS_Rloc in reg
(iv) Store 0x04 to MCS reg
(v) return (BX LR)

```

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; 10) return R0 equal to bits 3,2,1 of I2C3_MCS_R, error bits
; will be 0 is no error

```

(7) → Same as (3)

(8) → Same as (4) but write (0x05)

(9) → Same as (5)

(10) → Same as (6)
if no error
mov B in R0
return

Part C: Out string fn.

```
void SSD1306_OutString(char *ptr){  
}
```

ptr to string

null terminated
array of char
null = '\0'

int i as index

loop(i=0 → ptr[i] == '\0'; i=i+1)



SSD1306_OutChar(ptr[i]);

Part D: IO Functions

```
#define PF2 (*((volatile unsigned long *)0x40025010)) // PF2
#define PF4 (*((volatile unsigned long *)0x40025040)) // PF4
```

```
void IO_Init(void) { volatile uint32_t delay;
// --UUU-- Code to initialize PF4 and PF2
SYSCTL_RCGCGPIO_R = // 1) activate clock for Port
delay = SYSCTL_RCGCGPIO_R; // allow time for clock to start
GPIO_PORTF_DIR_R = // 2) PF4 in, PF2 out
GPIO_PORTF_PUR_R = // 3) Set pullup register for PF4
GPIO_PORTF_DEN_R = // 4) enable digital I/O on PF4,2
}
```

```
uint8_t led = 0x04;
void IO_HeartBeat(void) {
// --UUU--
led ^= ;
PF2 = ;
Clock_Delay1ms(100);
}
```

→ Set bit 5

→ Set for Output (=1)
Reset for input (20)

→ Set bit 4

→ Set for bit 2,4

→ Initialize a variable

→ toggle value

→ Store value to port

→ Use this function for a delay

//-----IO_Touch-----

// wait for release and press of the switch

// Input: none

// Output: none

// 1) wait for release;

// 2) delay for 5ms;

// 3) wait for press; and then

// 4) delay for another 5ms

→ wait while PF4 is 0

→ Use delay func

→ wait while PF4 is 1

→ Use delay func

Part E: LCD Driver (Out Dec)

N EQU 4
CNT EQU 0
FP (RN 1)

(on top of code)

The number to get units place for
Count of numbers
Frame pointer Init

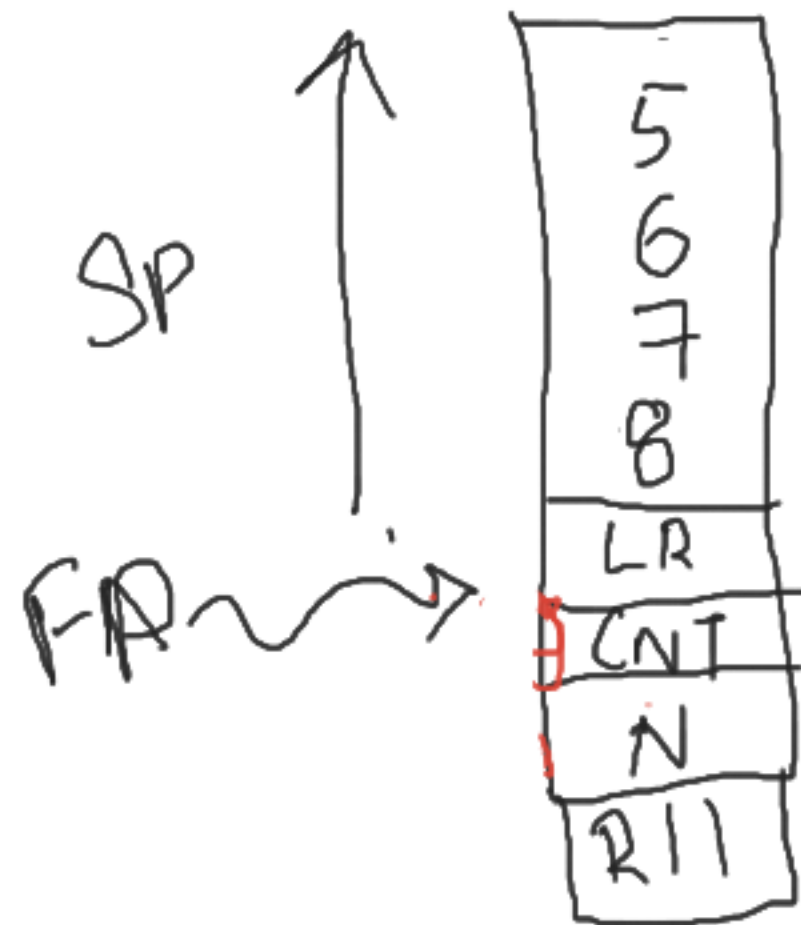
Check for
N == 0

Read bits :

N = 5678 → 567 → 56 → 5 → 0

CNT = 0
[SP] =

1 → 2 → 3 → 4
8 → 7 → 6 → 5



Init to 0
Initialize to R0

Write Char

[SP] = 5 → 6 → 7 → 8
CNT = 4 → 3 → 2 → 1 → 0
check CNT == 0
Exit

Out Dec Algorithm: (Using recursion)

LCD_OutDec

— Store R11 on stack

— Store number N on stack

— make space for Count (Subtract SP by 4) ← CNT = 0

— make SP your frame pointer

(INIT)
1

— Store LR on stack

INIT
2 — Store CNT as 0

— load a reg with #10 for division

How to access a var?
LDR R0, [FP, #CNT] ← CNT is defined as 0
STR R0, [FP, #CNT]
in last slide

Read loop

Load CNT, add 1, Store

- ①
- Load CNT to reg
 - add 1 to reg
 - Store reg as CNT
-

- ②
- Load current value of N to reg1
 - make a copy in reg2
 - Unsigned divide reg1 by 10 in reg1
 - Store this reg1 as new N
 - multiply this reg1 to 10 in reg1
 - Subtract reg1 from reg2 ($\text{reg2} - \text{reg1}$)
 - Store this difference to Stack

Load N
N1, N2.
N1/10 → new.
extracted
or digit
push on st

- ③ - Load new N
- Check if N is 0
- NO? Loop back to read loop
- YES? Continue
-

Write loop

- ④ - POP value from Stack
- Add to 0x30 and store in R0
- Branch to SSD1306_OutChar {BL?}
-

- ⑤ - Load CNT to reg1
- Decrement
- Store CNT from reg1
-

- ⑥ - Check if CNT (reg1) greater than 0
- Yes? Loop back to write loop
- NO? continue
-

- ⑦ - Store LR from stack
- ADD #8 to SP
- POP R11 from stack
- Return BX LR

LCD_OUTFIX

- INIT1 same as OUTDEC

- INIT2 same as OUTDEC

① - Check if N is less than 1000 (BLN)

- YES? Jump to INRANGE

NO? continue

② - move 0x2A to R0 (*)

= Branch SSD1306_OutChar

③ - move 0x2E to R0
= Branch SSD1306_OutChar

④ - DO ②

⑤ - DO ②

- Jump to Exit

INRANGE

⑥ - Same as ①
in OUTDEC

⑦ - Same as ②
in OUTDEC

- ⑧
- Load CNT to rlg
 - Compare CNT to 3
 - Less than? Loop to INRANGE
 - NO? Continue
-

- ⑨
- Same as ④ in OutDec
 - Same as ② in OutFix
 - Same as ④ in OutDec
 - Same as ④ in OutDec

⑩

EXIT.

- Store LR from stack
- ADD #8 to SP
- Store R11 from stack
- return (BX, LR)