

# CS/ECE/ME 532

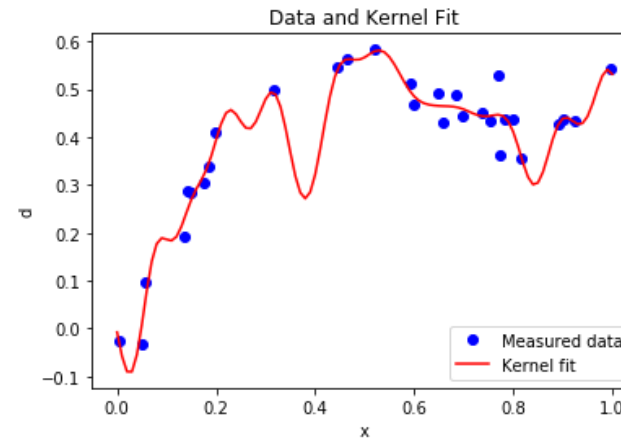
## Period 23

Today

- Kernel methods: video 6.3

Applications:

- *Regression*



- *Classification (Kernel SVMs)*

- *Nothing to do with kernel of a matrix:*

$\ker(\mathbf{A})$  is all vectors such that  $\mathbf{A}\mathbf{x} = 0$

Kernel may refer to:

Wikipedia:

Computing [\[ edit \]](#)

- [Kernel \(image processing\)](#), a matrix used for image conv
- [Kernel \(operating system\)](#), the central component of mos
- [Compute kernel](#), in GPGPU programming
- [Kernel method](#), in machine learning
- In [numerical analysis](#), a subroutine that performs a comm
  - In particular, a routine that is executed in a vectorized
- [Kernelization](#), a technique for designing efficient algorithr

Mathematics [\[ edit \]](#)

Objects [\[ edit \]](#)

- [Kernel \(algebra\)](#), a general concept that includes:
  - [Kernel \(linear algebra\)](#), the set of all vectors which m
  - [Kernel \(category theory\)](#), in category theory
  - [Kernel \(set theory\)](#), the set of all pairs of elements th
  - [Equalizer \(mathematics\)](#), the set of all elements wher
- Kernel of a [directed graph](#), a subset of the vertex set of a

Functions [\[ edit \]](#)

- [Kernel \(geometry\)](#), the set of points within a polygon from
- [Kernel \(statistics\)](#), a weighting function used in kernel de
- [Integral kernel](#), a function of two variables that defines ar
- [Heat kernel](#), the fundamental solution to the heat equatio
- [Convolution kernel](#)
- [Stochastic kernel](#), the transition function of a stochastic p
- [Transition kernel](#), a generalization of a stochastic kernel
- [Pricing kernel](#), the stochastic discount factor used in mat
- [Positive-definite kernel](#), a generalization of a positive-def
- [Kernel trick](#), in statistics
- [Reproducing kernel Hilbert space](#)

# Kernels (in Machine Learning)

Binary classification:  $\hat{y} = \text{sign}(\mathbf{x}^T \mathbf{w})$

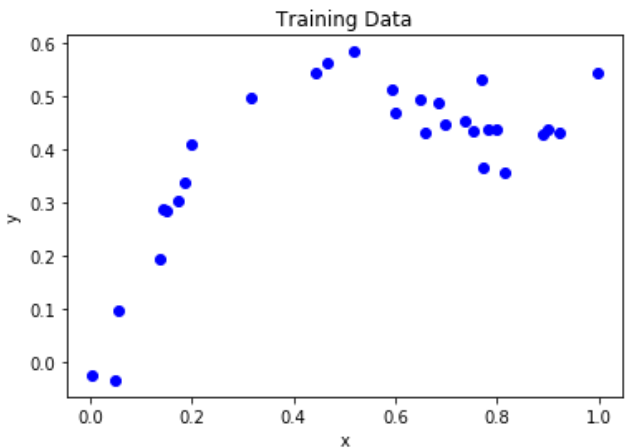
Linear regression:  $\hat{y} = \mathbf{x}^T \mathbf{w}$

Linear regression, after feature map:

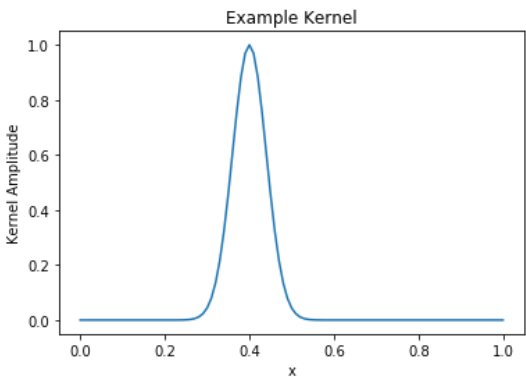
$\hat{y} = \phi(\mathbf{x})^T \mathbf{w}$  ←  $\mathbf{w}$  depends on  $\mathbf{x}_1, y_1, \mathbf{x}_2, y_2 \dots$

Kernel methods – re-write above as:

$\hat{y} = \sum_i \alpha_i K(\mathbf{x}, \mathbf{x}_i)$  ← weighted sum of similarities between feature vector and each training point



$K(\mathbf{x}, \mathbf{x}_i) = e^{-||\mathbf{x} - \mathbf{x}_i||^2}$



$\mathbf{x} = [0.4]$     How do we predict  $\hat{y}$ ?     $\hat{y} = \sum_i \alpha_i e^{-|0.4 - x_i|^2}$

How do we find good  $\alpha_i$ ?

start by finding  $\mathbf{w}$  using ridge regression

$\mathbf{w}^* = \arg \min_{\mathbf{w}} ||\Phi \mathbf{w} - \mathbf{y}|| + \lambda ||\mathbf{w}||^2$

$\mathbf{w}^* = (\Phi^T \Phi + \lambda \mathbf{I})^{-1} \Phi^T \mathbf{y}$

$\hat{y} = \phi(\mathbf{x})^T \mathbf{w}^* \quad \hat{y} = \sum_i \alpha_i K(\mathbf{x}, \mathbf{x}_i)$   
↓ Manipulations/comparisons

$\alpha = (\Phi \Phi^T + \lambda \mathbf{I})^{-1} \mathbf{y}$   
where  $\Phi \Phi^T$  has  $i, j$  entry  $K(\mathbf{x}_i, \mathbf{x}_j)$

No need to compute  $\phi(\cdot)$  to compute  $K(\cdot, \cdot)$  or  $\hat{y}$  !

