Bias-Variance Tradeoff in Low-Rank Approximations

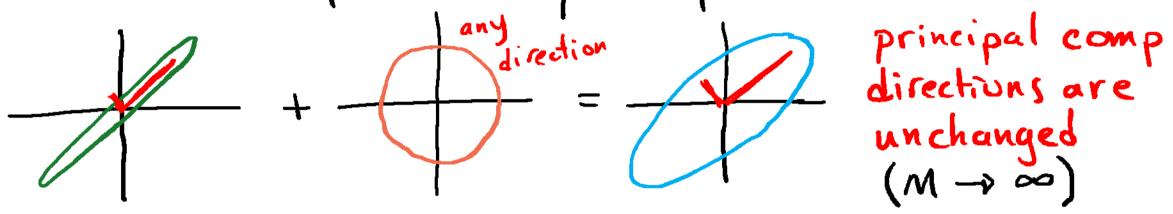
- Introduce concept of noisy data
- Consider impact of noise on SVD
- Define bias and variance

- Use low-rank models to trade bias for variance

5 + 6 electronics in sensing systems clean noise environmental static NXM A = limited precision in computers isotropic or white" noise - no preferred direction very structured diffuse structure Sum of squared errors: 11511F

 $\|S\|_{F}^{2} = \sum_{i=1}^{N} M\left(\frac{1}{M}\sum_{j=1}^{N}g^{2}j\right) = M\sum_{i=1}^{N} Var_{i} \approx MN \sigma_{g}^{2}$

Singular vectors are invariant (approx) to isotropic noise - Proof uses probability concepts



variance along each component (singuals) changes

 $\sigma_{A_i} \approx \sigma_{S_i} + M^{V_2} \sigma_{Q}$

$$\sum_{A} = \begin{bmatrix} 6_{A_{1}} & 0 \\ 0 & 6_{A_{2}} \end{bmatrix}, \sum_{S} = \begin{bmatrix} 6_{S_{1}} & 0 \\ 0 & 6_{S_{2}} \end{bmatrix}, \sum_{G} = \begin{bmatrix} M^{1/2} G_{3} \\ 0 & 6_{S_{1}} \end{bmatrix}$$
 (isotropic)

Low-rank models trade bias for variance 4 Original: A = S + G Error: A-5, 11911=≈NM6g²

Low rank: $\hat{A}_r = \sum_{i=1}^r \sigma_{A_i} U_i V_i^T \approx \hat{S}_r + \hat{G}_r$ $\hat{S}_r = \sum_{i=1}^r \sigma_{S_i} u_i v_i^T$ $\hat{G}_r \approx \sum_{i=1}^r M^{1/2} G_i u_i v_i^T$

Bias²: $b^{2}(r) = || 5 - \frac{5}{5}r||_{F}^{2}$ Variance: $V(r) = || \frac{6}{5}r||_{F}^{2}$ $b^{2}(r) = || \frac{5}{5}r_{+}^{2}\sigma_{S_{1}}u_{1}v_{1}^{2}||_{F}^{2}$ $V(r) = || \frac{5}{5}n^{2}\sigma_{S_{1}}u_{1}v_{1}^{2}||_{F}^{2}$

 $=\sum_{i=r+1}^{N} \sigma_{s_{i}}^{z_{i}}$ (notes)

sum of squared "tail" singular values = rM 6g²

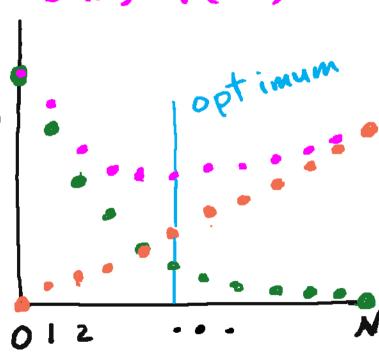
dimensions x variance
dimension

Trading bias for variance

V(r) = rM 5g2

increases as r increases

b²(r)+v(r) ≤ highly structured 6,>>0



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