

Matrix Completion

Objective s

- define the matrix completion problem
- approach missing data using low-rank models
- introduce iterative singular value thresholding

Use "patterns" to fill in missing entries 2

Ratings
matrix

$$\underline{X} \in \mathbb{R}^{N \times M}$$

5	4	9	1	x
9	6	x	x	7
x	10	x	2	4
3	7	3	x	x
8	x	x	6	2

N movies



M users →

Can we predict the missing entries?

Model: assume \underline{X} is well approximated with a small number of patterns

$$\underline{X} \approx \sum_{i=1}^r \underline{t}_i \underline{s}_i^T = \underline{T} \underline{S}$$

genres, actors, director...

hobbies, age, address...

Matrix completion: use known data to find ³ patterns and predict missing entries

$\Omega = \{i, j: \underline{X}_{ij} \text{ given}\}$ indices of known values

1) Rank minimization $\underline{X} = \underset{\underline{M}}{\operatorname{argmin}} \operatorname{rank}(\underline{M})$ s.t. $\underline{M}_{ij} = \underline{X}_{ij} \quad \forall i, j \in \Omega$
minimum number of patterns matching given values

Intractable!

$$\operatorname{rank} \underline{M} = \#\{\ell: \sigma_\ell > 0\}$$

2) Nuclear norm minimization

$$\underline{X} = \underset{\underline{M}}{\operatorname{argmin}} \|\underline{M}\|_* \quad \text{s.t.} \quad \underline{M}_{ij} = \underline{X}_{ij} \quad \forall i, j \in \Omega$$

Nuclear/trace norm

$$\|\underline{M}\|_* = \sum_{\ell} \sigma_{\ell}$$

Computationally tractable

Iterative Singular Value Thresholding 4

is one possible algorithm

Initialize

$$\underline{M}^{(0)} = \underline{0}$$

Set threshold or r

Iterate

for $k = 1, 2, 3, \dots$

$$\underline{M}^{(k)} = \underline{M}^{(k-1)}$$

$$\underline{M}_{\Omega}^{(k)} = \underline{X}_{\Omega} \quad (\text{fill in known values})$$

$$[\underline{U}, \underline{\Sigma}, \underline{V}] = \text{svd}(\underline{M}^{(k)})$$

$$\hat{\Sigma}_{ii} = \Sigma_{ii} \cdot \begin{cases} 1 & \Sigma_{ii} > \text{threshold} \\ 0 & \Sigma_{ii} \leq \text{threshold} \end{cases}$$

— or —

$$\hat{\Sigma}_{ii} = \begin{cases} \Sigma_{ii}, & i \leq r \\ 0, & i \geq r+1 \end{cases}$$

$$\underline{M}^{(k)} = \underline{U} \hat{\underline{\Sigma}} \underline{V}^T$$

$$\text{if } \|\underline{M}^{(k)} - \underline{M}^{(k-1)}\|_F < \varepsilon$$

stop

else

next k

Matrix completion is an open problem 5

- choosing r or threshold in ISVT
- multiple algorithms:
 - convergence
 - complexity
 - noise
- results depend on distribution of missing entries
- applications include missing pixels in images, position from partial distance info, ...

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