

```
In [13]: import numpy as np
import pandas as pd
import matplotlib
import matplotlib.pyplot as plt
import statsmodels.api as sm
from sklearn.linear_model import LinearRegression
from sklearn.linear_model import LogisticRegression
from sklearn import svm
from sklearn.svm import SVC
from sklearn.metrics import confusion_matrix
from sklearn.model_selection import train_test_split
from sklearn.preprocessing import PolynomialFeatures
from sklearn.model_selection import KFold
```

```
In [14]: df = pd.read_csv('Auto.csv')
df_copy = df.copy()
```

```
In [15]: # Eliminates the rows (instances) with '?' as a predictor value
df_copy['horsepower'] = pd.to_numeric(df_copy['horsepower'], errors='coerce')
df_copy = df_copy.dropna()
# df_copy['name'] = df_copy['name'].str.split(' ').str[0]

df_copy = df_copy.drop('name', 1)
df_copy.head()
```

Out[15]:

	mpg	cylinders	displacement	horsepower	weight	acceleration	year	origin
0	18.0	8	307.0	130.0	3504	12.0	70	1
1	15.0	8	350.0	165.0	3693	11.5	70	1
2	18.0	8	318.0	150.0	3436	11.0	70	1
3	16.0	8	304.0	150.0	3433	12.0	70	1
4	17.0	8	302.0	140.0	3449	10.5	70	1

## Problem a

```
In [16]: mpg_median = df_copy['mpg'].median()

# Create 'mpg01' column, 1 => mpg > mpg_median, 0 => mpg < mpg_median
df_copy.loc[df_copy['mpg'] >= mpg_median, 'mpg01'] = 1
df_copy.loc[df_copy['mpg'] < mpg_median, 'mpg01'] = 0
df_copy = df_copy.drop('mpg', 1)
```

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In [ ]:
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## Problem b

```
In [17]: # Extract predictor x and response y as arrays
y = np.asarray(df_copy['mpg01'])
X = np.asarray(df_copy[['displacement', 'acceleration']])

K=10
# K-Fold splitter
kfold = KFold(n_splits=K, shuffle=True)
sum_test_errors = 0 # Initialize the total test error
for train_index, test_index in kfold.split(X): # For each group
    # Obtain training and testing data
    X_train, X_test = X[train_index], X[test_index]
    y_train, y_test = y[train_index], y[test_index]

    # Create Linear Regression model and fit to the training data
    SV_classifier = SVC(kernel='linear')
    SV_classifier.fit(X_train, y_train);

    # Make predictions
    y_pred = SV_classifier.predict(X_test)
    y_pred = 1*(y_pred >= 0.5)

    tn, fp, fn, tp = confusion_matrix(y_test, y_pred).ravel()
    test_error = (fp+fn)/(tn+fp+fn+tp)
    sum_test_errors = sum_test_errors + test_error

# cross-validated test error
cv_error = sum_test_errors/K

print("The Cross-Validation Error is " + repr(cv_error))
```

The Cross-Validation Error is 0.10237179487179486

```
In [18]: y = df_copy['mpg01']
X = df_copy[['displacement', 'acceleration']]

SV_classifier = SVC(kernel='linear')
SV_classifier.fit(X, y);

# Make predictions
y_pred = SV_classifier.predict(X)
y_pred = 1*(y_pred >= 0.5)

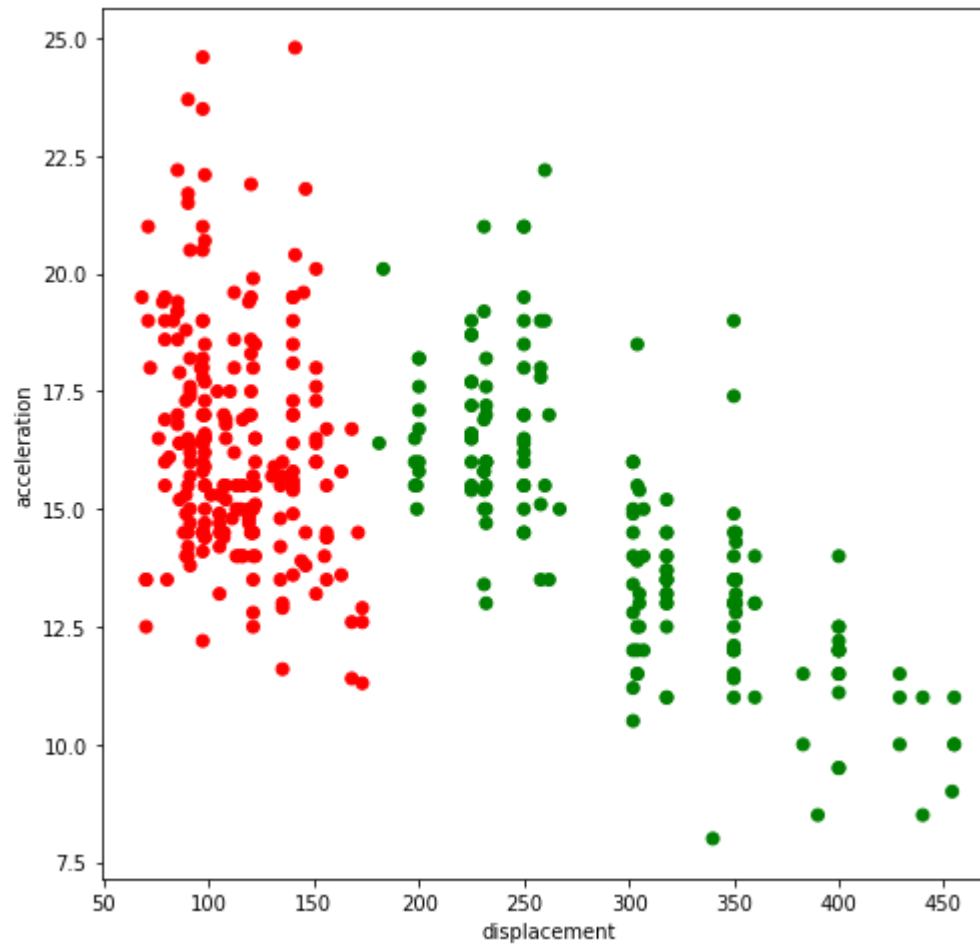
tn, fp, fn, tp = confusion_matrix(y, y_pred).ravel()
accuracy = (tp+tn)/(tn+fp+fn+tp)
print('The accuracy rate for a SVC with a Linear Kernel is ' + repr(accuracy))

# Define colors for the class labels: RED for 1, GREEN for 0
colors = ['green', 'red']

fig = plt.figure(figsize=(8,8))
plt.scatter(X['displacement'], X['acceleration'], c=y_pred, cmap=matplotlib.colors.ListedColormap(colors))
plt.xlabel('displacement')
plt.ylabel('acceleration')
```

The accuracy rate for a SVC with a Linear Kernel is 0.8979591836734694

Out[18]: Text(0,0.5,'acceleration')



## Problem c

## Polynomial Kernel

```
In [19]: gamma_values_list = [0.005, 0.01, 0.05]
degrees_list = [1, 2, 3]

# Create four polar axes and access them through the returned array
fig, axes = plt.subplots(len(gamma_values_list), len(degrees_list), figsize=(15,15))
row = 0
for gamma in (gamma_values_list):
    column = 0
    for degree in (degrees_list):
        # Obtain dataset and response
        y = df_copy['mpg01']
        X = df_copy[['displacement', 'acceleration']]

        # Create SVC model with polynomial kernel and fit to data
        SV_classifier = SVC(kernel='poly', gamma=gamma, degree=degree)
        SV_classifier.fit(X, y);

        print('Successfully fit the data')

        # Make predictions
        y_pred = SV_classifier.predict(X)
        y_pred = 1*(y_pred >= 0.5)

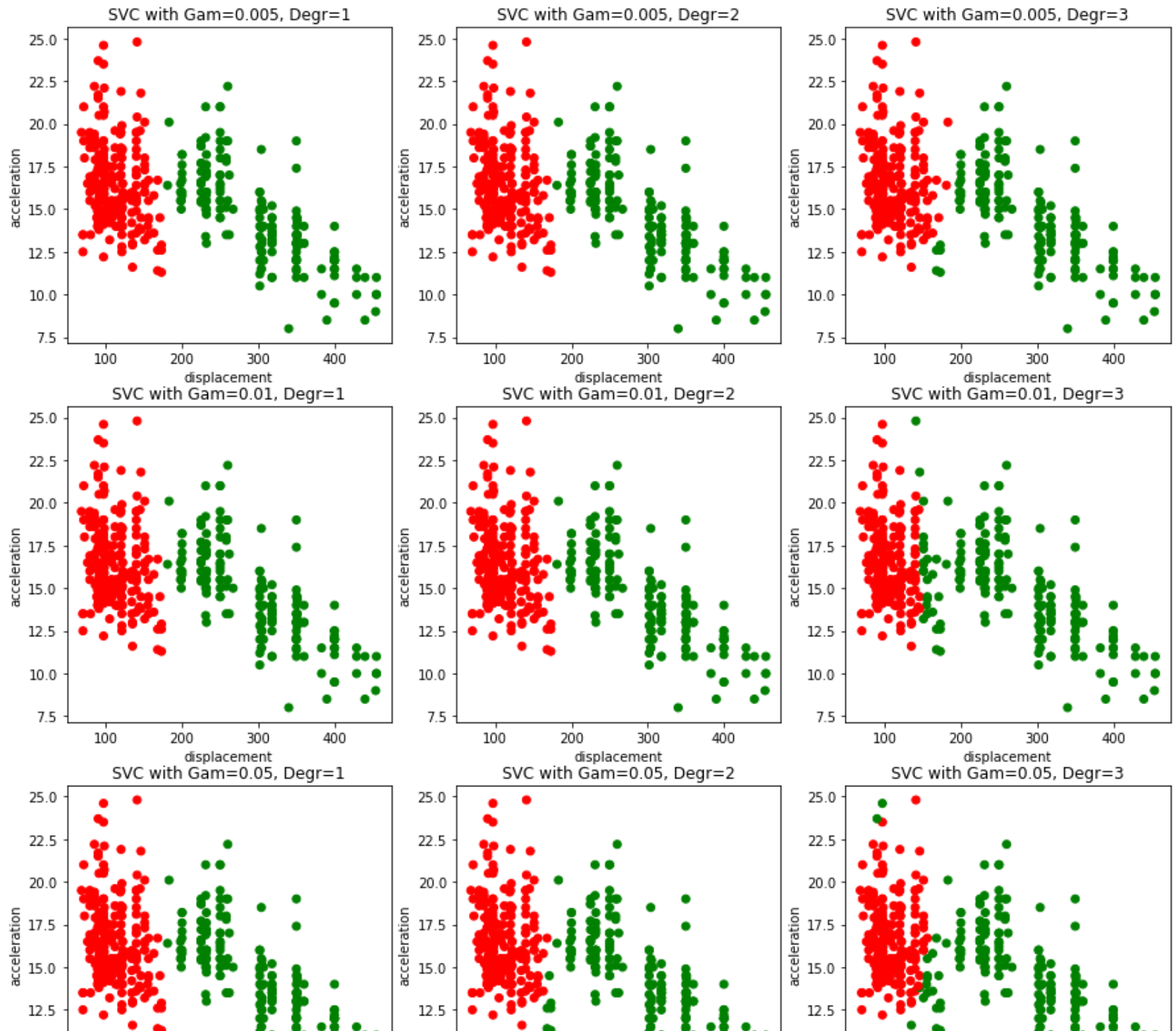
        # Define colors for the class labels: RED for 1, GREEN for 0
        colors = ['green', 'red']

        axes[row, column].scatter(X['displacement'],
                                   X['acceleration'],
                                   c=y_pred,
                                   cmap=matplotlib.colors.ListedColormap(colors))

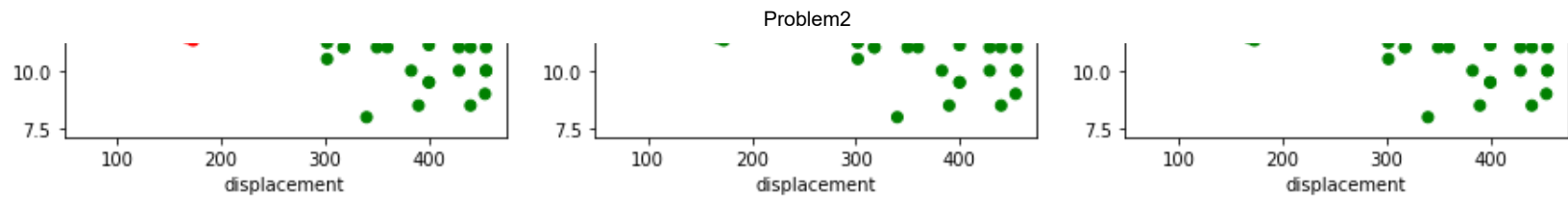
        axes[row, column].set_xlabel('displacement')
        axes[row, column].set_ylabel('acceleration')
        axes[row, column].set_title('SVC with Gam='+repr(gamma)+' , Degr='+repr(degree))

    column = column + 1
    row = row + 1
```

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## Radial Basis Kernel

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In [21]: gamma_values_list = [0.005, 0.01, 0.05]

# Create four polar axes and access them through the returned array
fig, axes = plt.subplots(len(gamma_values_list), 1, figsize=(12,12))
i = 0
for gamma in gamma_values_list:
    # Obtain dataset and response
    y = df_copy['mpg01']
    X = df_copy[['displacement', 'acceleration']]

    # Create SVC model with radial basis kernel and fit to data
    SV_classifier = SVC(kernel='rbf', gamma=gamma)
    SV_classifier.fit(X, y);

    print('Successfully fit the data')

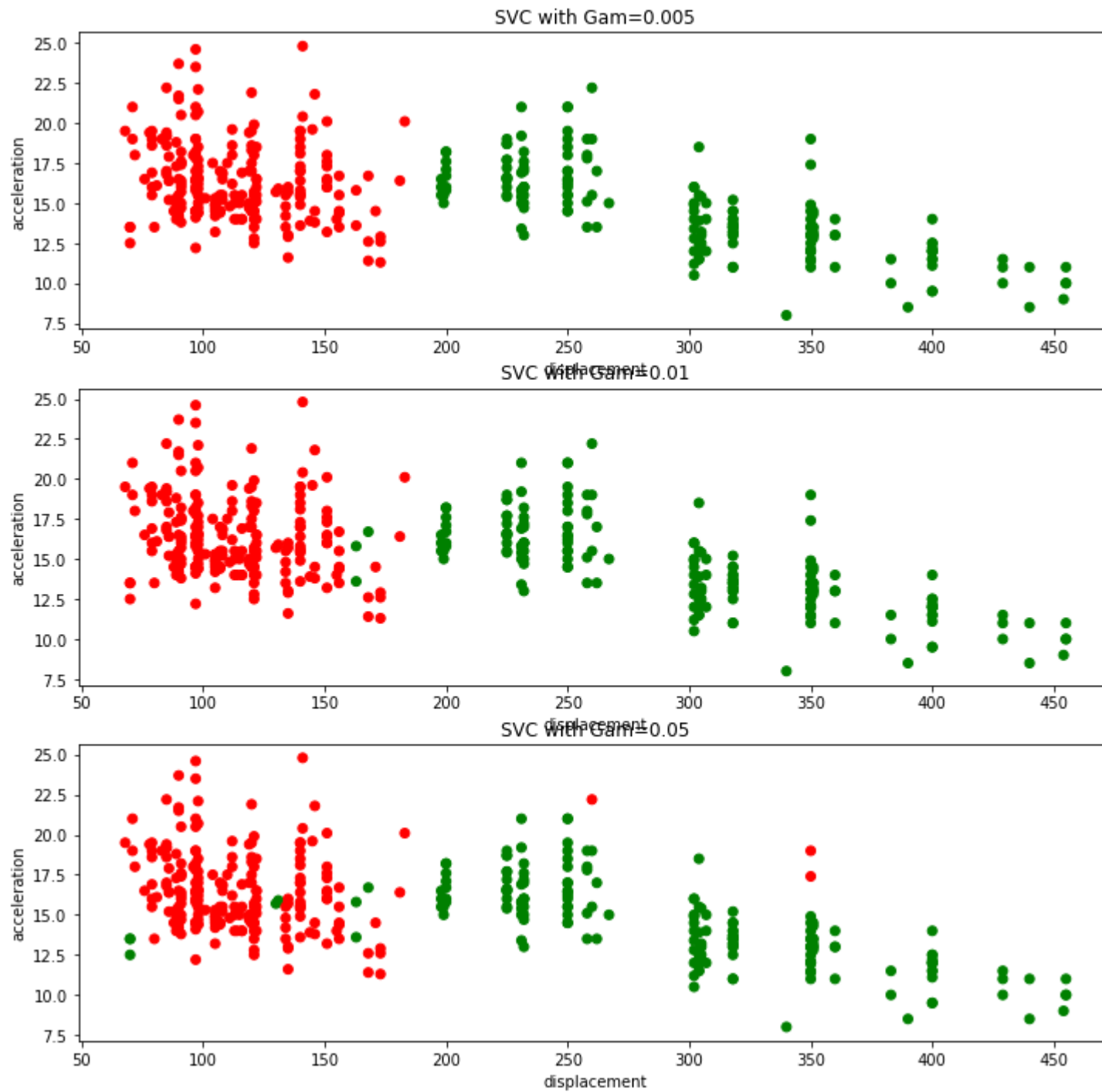
    # Make predictions
    y_pred = SV_classifier.predict(X)
    y_pred = 1*(y_pred >= 0.5)

    # Define colors for the class labels: RED for 1, GREEN for 0
    colors = ['green', 'red']

    axes[i].scatter(X['displacement'],
                    X['acceleration'],
                    c=y_pred,
                    cmap=matplotlib.colors.ListedColormap(colors))
    axes[i].set_xlabel('displacement')
    axes[i].set_ylabel('acceleration')
    axes[i].set_title('SVC with Gam='+repr(gamma))

    i = i + 1
```

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