```
LINEAR ALGEBRA
                                                                                                                                      (ATA) investible when A is full crank
Least Squares
  min ||Ax-y||2 : x = (ATA)-ATY
                                                                                                                                        Orthonormal Set { v, v2 ··· vn }
                                                                                                                                         4 v; has norm !
                                                                                                                                          4 v; I to all v;
cond: A has full col rank
                y & RM
                                                                                                                                         P-1 P = I
Norms
                                                                                                                                        det (I) =1
  f: X → R a norm if
                                                                                                                                        | [ [ ] ] | 2 : | | v | 2 + | | | | | | 2
  1. f(x) =0
 2. f(an): |a| f[n)
                                                                                                                                       A full rank => trivial mullspace
 3. f(x+ y) = f(x)+f(y)
                                                                                                                                       A not full rank 3 non-trivial nullapare
ابر المرابع = ( يَ المرز) م
                                                                                                                                        proj = = < 2, x > x
                                                                                                                                         ( × () × )
      ||え||<sub>00</sub> = max |x;|
                                                                                                                                         Orthonormal Motrix Q
(anchy - Schwarz Inequality)
|$\frac{1}{3} \frac{1}{3} | $\frac{1}{3} | $\frac{1
                                                                                                                                         4 9 9 = I
                                                                                                                                          4 9 5 9T
                                                                                                                                         4 9 = 0 - 1 is a in Aquare
Grahm - Schmidt Algorithm
 1. Span { a, 3 = span { q; 3
  2. {q; 3 orthonormal set
  Steps
  1, = 4,
  4 p2 = (a2q1) q1
        52 = a2 - P2
       92 = 3,
11311
        sk = ak - (ak q) q, - (ak q2) q2 - ... (at q x-,) qk-,
gr Decomposition
        A. OR
         Orthonormal Upper Triangular
  cond: A has full cal rank
 FTLA
· N(A) @ R(AT) = R"
· N (AT) + R (A) = Rm
· S @ S = Rn
 9f U Đ V = R", 元 = 元 + 元 
€ R" € U € V
 Min - Norm Solution
       min ||วี||: วี": AT(AAT)"่ๆ
      ncRn
s.t. Ax = y
     cond: A how four ROW rank (wide)
                      pick 1 from 00 soln
```



# LOW RANK APPROX

Frobenius Norm

$$||A||_{F} = \sqrt{22} A_{3}^{2}$$

$$||A||_{F}^{2} = \text{tr}(A^{T}A)$$

$$||UAV||_{F} = ||A_{F}||, U,V \text{ suthonor mal}$$

$$||A||_{F}^{2} = \sqrt{2}$$

Eckart Young Theorem
$$||A - A_{K}||_{2} \leq ||A - B||_{2} = C_{K+1}$$

$$||A - A_{K}||_{p} \leq ||A - B||_{p}^{2} = C_{K+1}$$

# VECTOR CALC

Gradient
$$\nabla f(\vec{x}) = \begin{bmatrix} \frac{\partial f}{\partial x_i} (\vec{x}) \\ \frac{\partial f}{\partial x_i} (\vec{x}) \end{bmatrix}$$

$$\nabla f(\vec{x})$$
 1. In purplane tangent to  $\vec{x}$ 

Javobian

Of 
$$(\vec{n}) = \begin{bmatrix} \nabla f_1(\vec{n})^T \\ \nabla f_2(\vec{n})^T \end{bmatrix} = \begin{bmatrix} \frac{\partial f_1}{\partial n} & (\vec{n}) & \cdots & \frac{\partial f_1}{\partial n} & (n) \\ \vdots & \vdots & \ddots & \vdots \\ \frac{\partial f_m}{\partial n} & (\vec{n}) & \cdots & \frac{\partial f_m}{\partial n} & \cdots \end{bmatrix}$$

## (transpose of the gradient)

Husian
$$\nabla^{2}f(\vec{n}) = \begin{pmatrix} \frac{\partial^{2}f}{\partial n^{2}} (\vec{n}) & \cdots & \frac{\partial^{2}f}{\partial n^{n}} (\vec{n}) \\ \frac{\partial^{2}f}{\partial n^{n}} (\vec{n}) & \cdots & \frac{\partial^{2}f}{\partial n^{n}} (\vec{n}) \end{pmatrix}$$

$$\frac{\partial^{2}f}{\partial n^{n}} (\vec{n}) & \cdots & \cdots & \cdots & \cdots & \cdots \\
\frac{\partial^{2}f}{\partial n^{n}} (\vec{n}) & \cdots & \cdots & \cdots & \cdots \\
\frac{\partial^{2}f}{\partial n^{n}} (\vec{n}) & \cdots & \cdots & \cdots & \cdots \\
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\frac{\partial^{2}f}{\partial n^{n}} (\vec{n}) & \cdots & \cdots & \cdots \\
\frac{\partial^{2}f}{\partial n^{n}} (\vec{n}) & \cdots & \cdots \\
\frac{\partial^{2}f}{\partial n^{n}} (\vec{n$$

$$\frac{\partial^2 f}{\partial n_i n_j}(\vec{x}) = \frac{\partial^2 f}{\partial n_j n_i}(x)$$

Taylais Theorem
$$f(x; x_0) = f(x_0) + \frac{\partial f}{\partial x}(x_0)(x_0) + \frac{1}{2} \frac{\partial^2 f}{\partial x^2}(x_0)(x_0)^2 + \frac{1}{K!} \frac{\partial f}{\partial x^K}(x_0)(x_0)^K$$

Toylori Approximation for Multivariate
$$f_{1}(2;\pi_{0}) = f(\vec{\pi}_{0}) + \left[\nabla f(\vec{\pi}_{0})\right]^{T}(\vec{\pi}_{0} - \vec{\pi}_{0})$$

$$f_{2}(\pi;\pi_{0}) = f(\vec{\pi}_{0}) + \left[\nabla f(\vec{\pi}_{0})\right]^{T}(\vec{\pi}_{0} - \vec{\pi}_{0}) + \frac{1}{2}(\vec{\pi}_{0} - \vec{\pi}_{0})^{T}\left[\nabla^{2} f(\vec{\pi}_{0})\right](\vec{\pi}_{0} - \vec{\pi}_{0})$$

Main Theorem

min  $f(\vec{x}) : \nabla f(\vec{x}^*) = 0$ ,  $f: \mathbb{R}^n \to \mathbb{R}$  is differentiable  $\vec{x} \in \Omega$ 

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Directional Derivative
f: R? → R , ||t||2=1
   Da f(x)= u [ V+(x)]
```

### REGRESSION

$$\kappa(A) = \frac{\kappa \{A\}}{\kappa \{A\}}$$

Ridge Regression

min 
$$\left\{ \| A\vec{x} - \vec{y} \|_{2}^{2} + \lambda \| \vec{x} \|_{2}^{2} \right\}$$

$$\vec{x}^* = (A^{T}A \cdot \lambda I)^{-1} A^{T} \vec{y}$$
 $A^{T}A \rightarrow PSD, \lambda > 0, (A^{T}A \leftarrow \lambda I) PSD = 0$ 
 $\vec{x}^* = \vec{y} \qquad \vec{y} \qquad$ 

Tikhorov Regrusion

min 
$$\{ \| W, (A\vec{x} - \vec{y}) \|_2^2 + \| W_2(\vec{x} - \vec{x}_0) \|_2^2 \}$$

TLE as 
$$\tau_i$$
 Khanov argmin  $\| Z_{\vec{w}}^{-1/2} (A_{\vec{v}} - \vec{y}) \|_2^2 \longrightarrow \text{what } \vec{v} \text{ makes data most likely}$ 

#### MAP as Tikhanov

angmax 
$$p(\vec{x}|\vec{y})$$
 = angmin  $\left\{ \| \underline{S}^{-1/2} (A\vec{x} - \vec{y}) \|_{2}^{2} + \| \underline{S}^{-1/2} (\vec{x} - z_{0}) \|_{2}^{2} \rightarrow \text{what } \vec{x} \text{ is most likely} \right\}$ 

#### CONVEXITY

$$\vec{c}$$
 is convex by  $\vec{\pi}_1$ ,  $\vec{\pi}_2 \in C$ ,  $\theta \in [0,1]$   
 $\theta \vec{\pi}_1 + (1-\theta) \vec{\pi}_2 \in C$ 

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