

Istanbul Technical University Faculty of Electrical and Electronics Department of Control and Automation Engineering

Feedback Control Systems (KON313E)

Homework Assignment 3

Prepared By

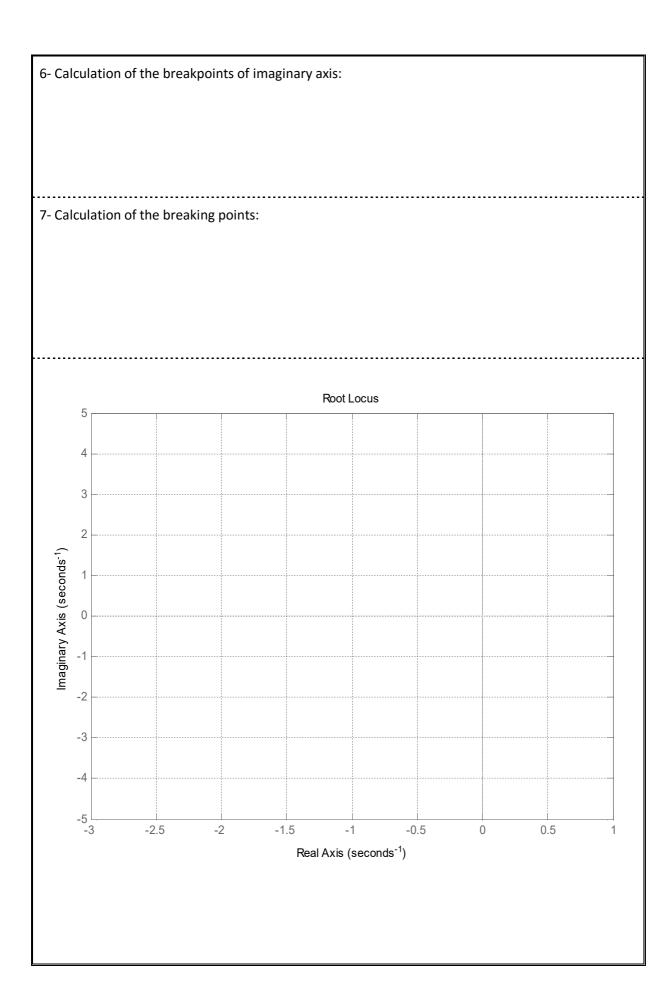
- 1.
- 2.
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2015 - 2016 Fall Term Deadline: 31.12.2015

FEEDBACK CONTROL SYSTEMS (KON 313E) HOMEWORK ASSIGNMENT - 3 SOLUTIONS

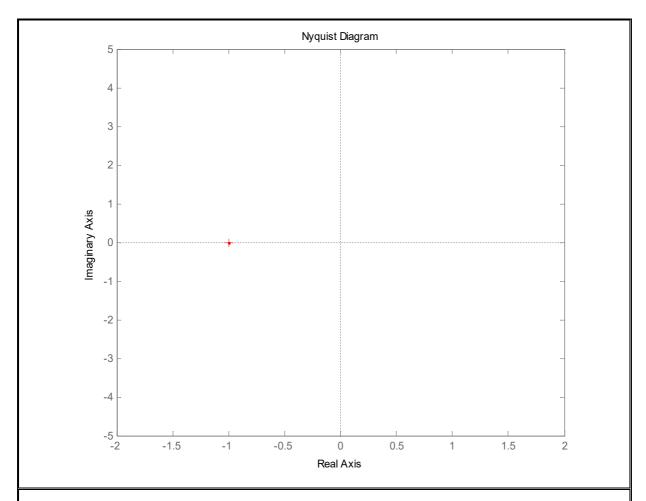
Question 1.a:
Closed-loop transfer function:
Question 1.b:
• Calculation of the parameters:

Question 1.c:	
• Y(s) / D(s) transfer function:	
• Steady- state error:	
Question 1.d:	
Rearrangement of the transfer function:	
1- Poles and zeros:	2- Number of branches:
	3- Symmetry:
4.1- Number of asymptotes:	·
4.2- Intersection point of asymptotes:	
4.3- Angle with the real axis:	
5- Root-locus on the real axis: (To be shown on the drawing)	



Question 2.a:
Open-loop transfer function (parametrically):
Question 2.b:
Amplitude and frequency of the input signal (sinus):
Amplitude and phase shift of the system output:
Obtaining the open-loop transfer function with the help of frequency response:
Calculation of the values of parameters R and C:
Calculation of the values of parameters K and C.

Question 2.c:			
• Open-loop transf	er function with F(s):		
• Magnitude and p	hase expressions of F(jω)G(jω):	
• Table for various	ω values:		
ω	$ F(j\omega)G(j\omega) $	$\angle F(j\omega)G(j\omega)$	
0			
10			
40.82			
60			
∞			
• Nyquist diagram a	and stabilizing k interv	val:	



Question 3.a:

• Stabilizing value range of k:



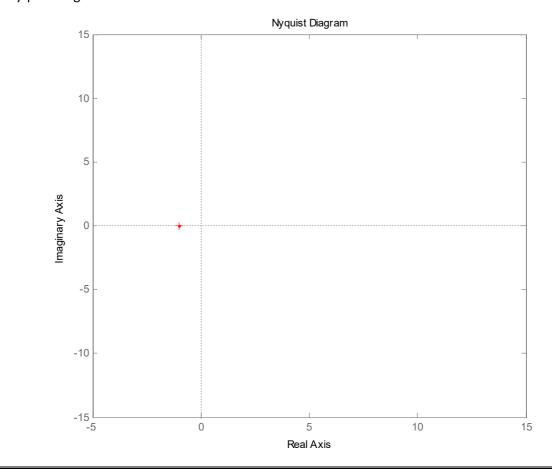
Question 3.b:

• Magnitude and phase expressions of $G(j\omega)$:

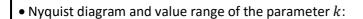
• Table for various ω values:

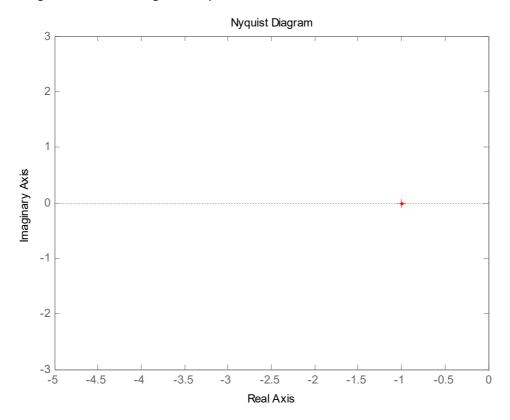
ω	$ G(j\omega) $	∠G(<i>jω</i>)
0		
0.2		
0.7071		
10		
∞		

• Nyquist diagram:



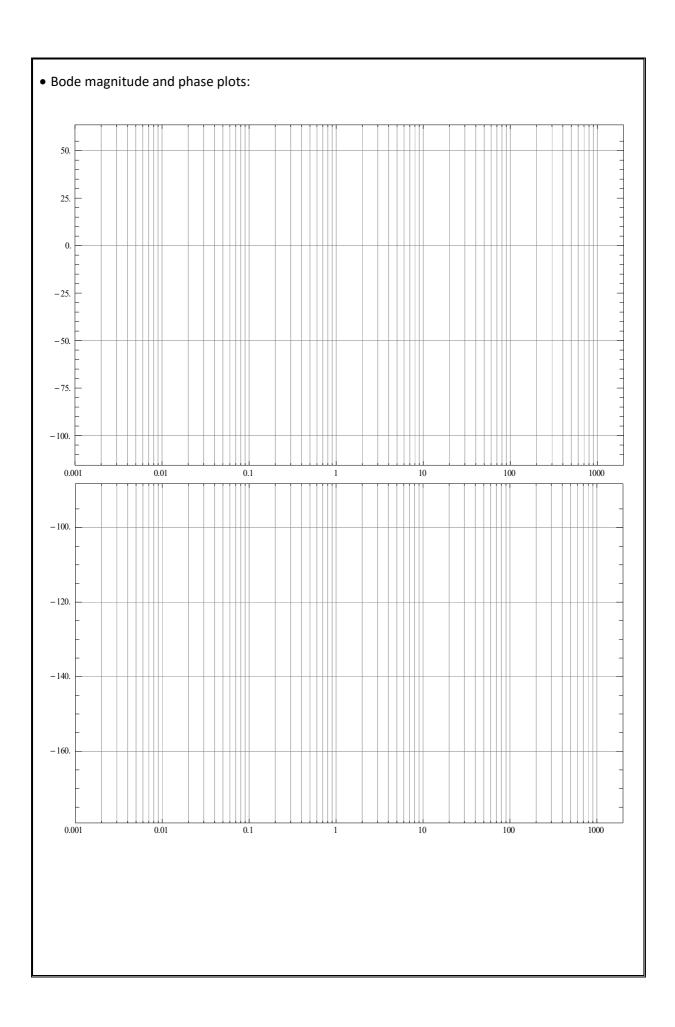
• Stabilizing leinta	m.ol.		
 Stabilizing k inte 	rvai:		
Question 3.c:			
Rough drawing o	f the new Nyquist path	ı:	
 Modified magnit 	ude and phase express	ions:	
• Table for various	ω values:		
ω	$ G(j\omega) $	$\angle G(j\omega)$	
0			
0.5			
1.3638			
5			
∞			
			•





Question 3.d:

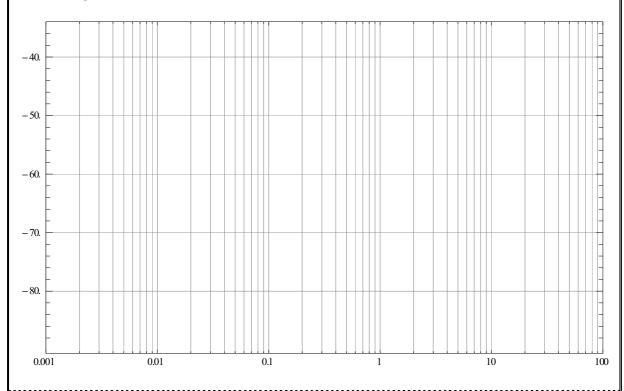
• Rearrangement of the open-loop transfer function:



Phase and gain margins:
Stability of the system:
Question 3.e:
• Expression of the system output:
Question 4.a:
Open-loop transfer function:

Question 4.b:

• Phase diagram:



• Calculation of the phase and gain margins:

Question 4.c:	
• Calculation of the critical L value:	