
OFFICE OF STRATEGIC NATIONAL ALIEN PLANNING



RASTERIZER

(RAST)

Project Team:
Garett Roberts

May 1, 2017

Executive Summary

A current rasterizer at goo.gl/fh8Zr1 that I previously created needs some more efficiency. There are a lot of moving parts within the code that I could parallelize. This will not be an easy task because of all of the possible data dependency issues.

Project Description

The project will be split into different sections. I will make the matrix multiplication, rasterizing, camera.. etc (all modules) running in parallel. This will not be so easy because there will be a lot of data dependencies and areas that could be optimized.

Highlevel Architecture

The architecture of the existing project is already built, it is split into its own modules.

Main - Calls everything Screen - Uses matrix, camera, triangles, lighting, and functions Triangle - uses matrix and functions Matrix - Standalone Lighting - Standalone IO - Standalone Camera - Matrix and functions

Optimization Plan

My optimization plan is as follows (and will be summarized on the following page).

I first plan to optimize my functions and matrix class initially, as these are the utilities that are utilized the most.

After that I plan to work on parallelizing the camera and triangle classes. This will take some time because there are a lot of optimizations that could be made in triangle.

Lastly I will take on the two harder ones, which would be main and screen. They both have the most and hardest for loops to make parallel.

Project Schedule

| Week | Milestone |
|------|-----------|
| 5 | Matrix |
| 6 | Functions |
| 7 | Camera |
| 8 | Triangle |
| 9 | Main |
| 10 | Screen |