

11.1

$$a) \omega_{syn} = 2\pi(f) = 2\pi(60 \text{ Hz}) = 377 \text{ rad/s}$$

$$\omega_{msyn} = \frac{2}{p} \omega_{syn} = \frac{2}{4} (377 \text{ rad/s}) = 188.5 \text{ rad/s}$$

$$b) KE? \rightarrow KE = H S_{rated} = (5 \text{ p.u.s}) (500 \text{ MVA}) = 2.5 \times 10^9 \text{ J}$$

$$c) P_e(t) = 0 \text{ MW}$$

$$P_{a.p.u.}(t) = \frac{P_m(t) - P_e(t)}{S_{rated}} = \frac{500 \text{ MW} - 0}{500 \text{ MVA}} = 1$$

$$\frac{2H}{\omega_{syn}} \omega_{p.u.}(t) \alpha(t) = P_{a.p.u.}(t)$$

$$\alpha(t) = \frac{P_{a.p.u.}(t)}{\frac{2H}{\omega_{syn}} (\omega_{p.u.}(t))} = \frac{1}{\frac{2(50 \text{ p.u.s})}{377 \text{ rad/s}} (1 \text{ rad/s})} = \frac{1}{0.265 \text{ p.u.s}} = 37.7 \text{ rad/s}$$

11.2

$$\frac{2H S_{rated}}{\omega_{msyn}^2} = J$$

$$\frac{2(5 \text{ p.u.s}) (500 \times 10^6 \text{ VA})}{(188.5 \text{ rad/s})^2} = \frac{J}{s^2} = 1.407 \times 10^5 \text{ kg} \cdot \text{m}^2$$

11.4

$$P_{mp.u.} = .7 \text{ p.u.}$$

Per Unit Swing equation:

$$\omega = \omega_{syn} = 2\pi f \text{ rad/s} = 377 \text{ rad/s}$$

$$\delta = 12^\circ \left( \frac{\pi}{180} \right) = .2094 \text{ rad}$$

$$\omega_{p.u.}(t) = 1$$

$$P_{ep.u.} = (.7)(.4) = .28$$

$$H = 5 \text{ p.u.s}$$

$$\frac{2H}{\omega_{syn}} \omega_{p.u.}(t) \frac{d^2 \delta(t)}{dt^2} = P_{mp.u.}(t) - P_{ep.u.}(t)$$

$$\frac{2(5 \text{ p.u.s})(1)}{377 \text{ rad/s}} \frac{d^2 \delta(t)}{dt^2} = .7 - .28$$

$$.02652 \text{ s}^2 \frac{d^2 \delta(t)}{dt^2} = .420$$

$$\delta(0) = 12^\circ$$

$$\frac{d\delta(0)}{dt} = 0$$

$$\frac{d^2 \delta(t)}{dt^2} = \frac{.420}{.02652 \text{ s}^2} = 15.834$$

$$\frac{d\delta(t)}{dt} = 15.834 t + 0$$

$$\delta(t) = 7.917 t^2 + .2094 \text{ rad} \rightarrow \delta(.05 \text{ sec [3 cycles]}) = 7.917 (.05)^2 + .2094 = .22919 \text{ rad}$$

$$t = \frac{n}{f} \text{ sec} = \frac{3 \text{ cycles}}{60 \text{ Hz}} = .05 \text{ sec}$$

$$.22919 \text{ rad} \left( \frac{180}{\pi} \right) = 13.13^\circ$$



11.6. Number of poles is 16.  $H$  is 1.5 p.u.

$$P_e = .5 \text{ p.u.} \quad P_m = .5 \text{ p.u.}$$

$$a) \quad \omega_{\text{syn}} = 2\pi (60 \text{ Hz}) = 377 \text{ rad/s}$$

$$\omega_{m\text{syn}} = \frac{2}{P} \omega_{\text{syn}} = \left( \frac{2}{16} \right) (377 \text{ rad/s}) = 47.12 \frac{\text{rad}}{\text{s}}$$

$$b) \quad \frac{2H}{\omega_{\text{syn}}} \omega_{p.u.}(t) \frac{d^2\delta(t)}{dt^2} = P_{m,p.u.}(t) - P_{e,p.u.}(t)$$

$$\frac{2(1.5 \text{ p.u.})}{377 \text{ rad/s}} \omega_{p.u.}(t) \frac{d^2\delta(t)}{dt^2} = P_{m,p.u.}(t) - P_{e,p.u.}(t)$$

$$c) \quad \omega = \omega_{\text{syn}} \quad \delta(0) = 10^\circ \left( \frac{\pi}{180^\circ} \right) = .1745 \text{ radians}$$

$$\frac{d\delta(0)}{dt} = 0 \quad \text{For } t \geq 0 \rightarrow \left[ \frac{2(1.5 \text{ p.u.})}{377 \frac{\text{rad}}{\text{s}}} \right] \frac{d^2\delta(t)}{dt^2} = .5$$

$$t = 3 \text{ cycles} = \frac{3 \text{ cycles}}{60 \text{ cycles/sec}} = .05 \text{ s} \quad \frac{d^2\delta(t)}{dt^2} = (.5) \left[ \frac{1}{\left[ \frac{2(1.5 \text{ p.u.})}{377 \frac{\text{rad}}{\text{s}}} \right]} \right]$$

$$\frac{d^2\delta(t)}{dt^2} = 62.833 \text{ rad}$$

$$\frac{d\delta(t)}{dt} = 62.833t + 0 \text{ rad}$$

$$\delta(t) = 31.41t^2 + .1745 \text{ rad}$$

$$\delta(.05) = 31.41(.05)^2 + .1745$$

$$\delta(.05) = .079525 + .1745 = .254025 \text{ rad}$$

$$.254025 \text{ rad} \left( \frac{180^\circ}{\pi \text{ rad}} \right) = 14.4972^\circ \approx 14.5^\circ$$



11.7  $W_{\text{kinetic}} = \frac{1}{2} M v^2$   
 $M_{\text{mass}} = 80,000 \text{ kg}$   
 $\text{Supply frequency} = 60 \text{ Hz}$   
 $\text{Poles} = 2$   
 $S_{\text{rated}} = 100 \text{ MVA}$   
 $\text{Inertia} = 3.0 \text{ p.u.} \cdot \text{s}$

$K_{\text{Egen}} = H S_{\text{rated}}$   
 $K_{\text{Egen}} = (3.0 \text{ p.u.} \cdot \text{s})(100 \times 10^6 \text{ VA})$   
 $K_{\text{Egen}} = 300 \text{ MJ}$

$K_{\text{Egen}} = \frac{1}{2} M v^2$   
 $\frac{2 K_{\text{Egen}}}{M} = v^2$   
 $v = \sqrt{\frac{2(300 \text{ MJ})}{80,000 \text{ kg}}} = 86.6 \text{ m/s}$   
 $\sqrt{\frac{2 K_{\text{Egen}}}{M}} = v$

11.8 a)  $X_{13} + X_{23} = .10 + .20 = .30$   
 $Y_{13+23} = \frac{1}{.30} = 3.33$   
 $Y_{12} = \frac{1}{.20} = 5$   
 $Y_{12} + Y_{13+23} = 5 + 3.33 = 8.33$   
 $X_{12+13+23} = \frac{1}{8.33} = .12$   
 $X_{\text{TR}} + X_{12+13+23} = .10 + .12 = .22 \text{ p.u.}$

$P_e = \frac{V_T V_{\text{bus}}}{X_{\text{TR}} + X_{12+13+23}} \sin \delta$   
 $.8 \text{ pu} = \frac{(1.05 \text{ pu})(1.0 \text{ pu})}{.22 \text{ p.u.}} \sin \delta$   
 $\sin \delta = .168$   
 $\delta = \sin^{-1}(.168) = 9.649^\circ$

$I = \frac{1.05 \angle 9.649^\circ - 1.0 \angle 0^\circ}{j .22} = \frac{.035 + j .176}{j .22} = 1.8 - j .16 = .8158 \angle -11.31^\circ \text{ p.u.}$

$S = V_T I^* = (1.05 \angle 9.64^\circ)(.8158 \angle 11.31^\circ \text{ p.u.}) = .8565 \angle 20.95^\circ = .7998 + j .3062 \text{ p.u.}$   
 $Q = .3062 \text{ p.u.}$

turn ratio :  $n_{2/1} = V_{2/1}$

Referring Impedance

b) Generator Internal voltage

$$E' \angle \delta = V_{\text{bus}} + j(X_d' + X)I$$

$$E' \angle \delta = 1.0 \angle 0^\circ + j(.30 + .22)(.816 \angle -11.29^\circ)$$

$$E' \angle \delta = 1.0 \angle 0^\circ + j(.52)(.816 \angle -11.29^\circ)$$

$$E' \angle \delta = 1.0 \angle 0^\circ + (.52 \angle 90^\circ)(.816 \angle -11.29^\circ)$$

$$E' \angle \delta = 1.0 \angle 0^\circ + (.424 \angle 78.71^\circ)$$

$$E' \angle \delta = 1.0 + .083 + j.4158$$

$$E' \angle \delta = 1.083 + j.4158 = 1.16 \angle 21.00^\circ \text{ p.u.}$$

$$c) P = \frac{E' V_{\text{bus}} \sin \delta}{X_d' + X_{RT} + X_{12+23+13}} = \frac{(1.16)(1.0) \sin(21.0^\circ)}{.30 + .22}$$

$$P = \frac{1.16 \sin \delta}{.52} = \frac{2.23(.358)}{.52} = .799 \text{ p.u.}$$