

ESTRUCTURAS DE DATOS

TIPOS ABSTRACTOS DE DATOS LINEALES

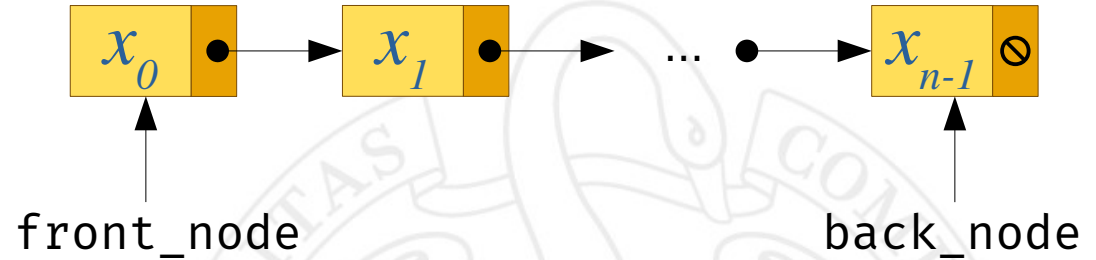
Implementando el TAD Cola

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Implementación mediante listas enlazadas



Implementación mediante listas enlazadas



Clase QueueLinkedList

```
template<typename T>
class QueueLinkedList {
```

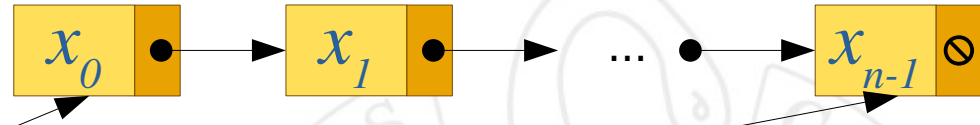
```
    ...
```

```
private:
```

```
    struct Node {
        T value;
        Node *next;
    };
```

```
    Node *front_node;
```

```
    Node *back_node;
};
```



- Si la cola está vacía:
 $\text{front_node} = \text{back_node} = \text{nullptr}$

Interfaz pública de QueueLinkedList

```
template<typename T>
class QueueLinkedList {

    QueueLinkedList();
    QueueLinkedList(const QueueLinkedList &other);
    ~QueueLinkedList();

    QueueLinkedList & operator=(const QueueLinkedList &other);

    void push(const T &elem);
    void pop();
    T & front();
    const T & front() const;
    bool empty() const;

    ...
};
```



Interfaz pública de QueueLinkedList

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template<typename T>
class QueueLinkedList {

    QueueLinkedList();
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    void push(const T &elem);
    void pop();
    T & front();
    const T & front() const;
    bool empty() const;

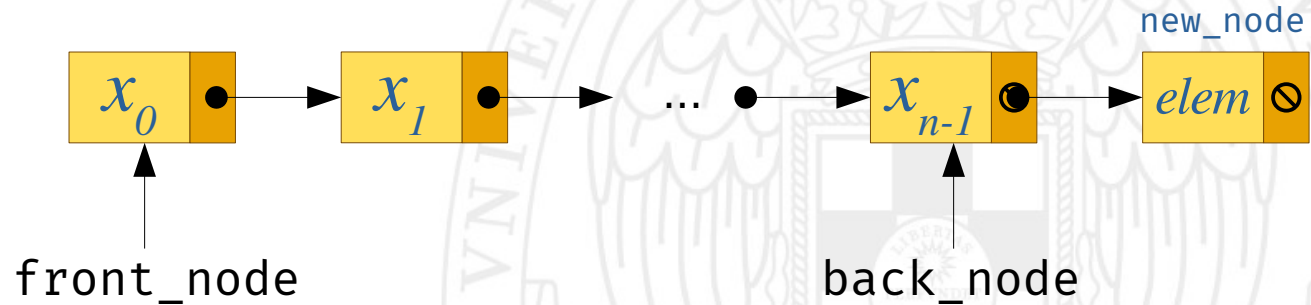
    ...

};
```



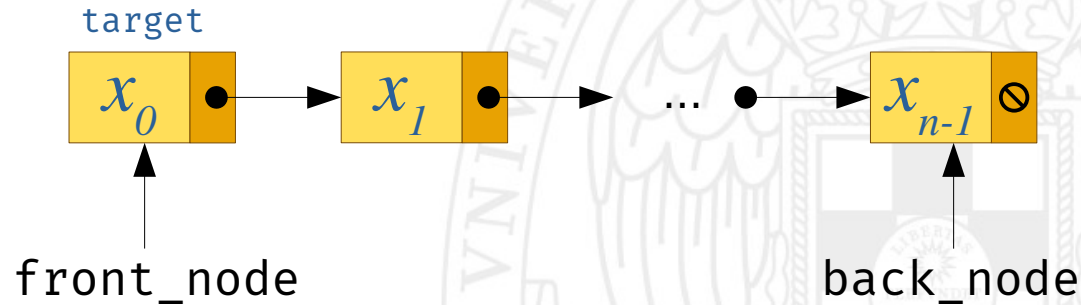
Método push()

```
void push(const T &elem) {  
    Node *new_node = new Node { elem, nullptr };  
    if (back_node == nullptr) {  
        back_node = new_node;  
        front_node = new_node;  
    } else {  
        back_node->next = new_node;  
        back_node = new_node;  
    }  
}
```



Método pop()

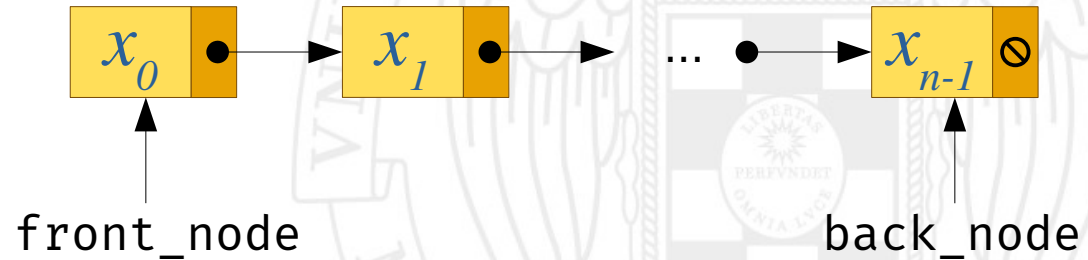
```
void pop() {  
    assert (front_node != nullptr);  
    Node *target = front_node;  
    front_node = front_node->next;  
    if (back_node == target) {  
        back_node = nullptr;  
    }  
    delete target;  
}
```



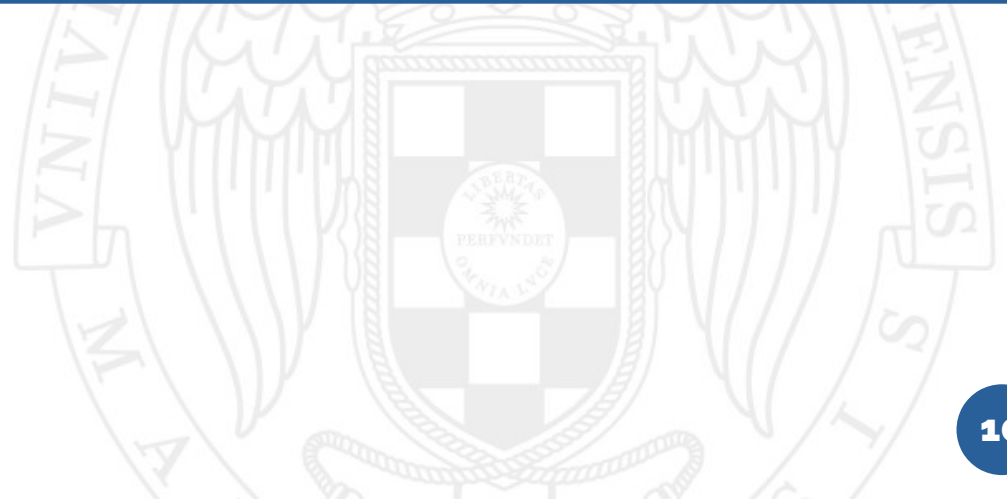
Métodos `front()` y `empty()`

```
const T & front() const {  
    assert (front_node != nullptr);  
    return front_node->value;  
}
```

```
bool empty() const {  
    return (front_node == nullptr);  
}
```



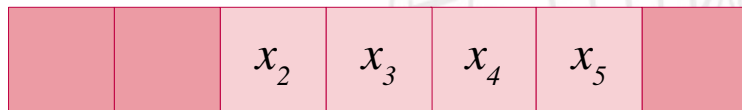
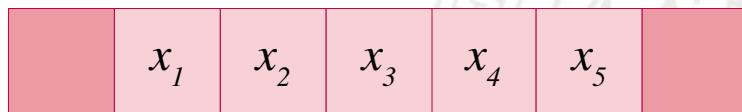
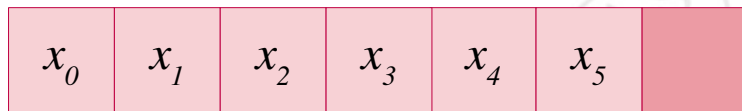
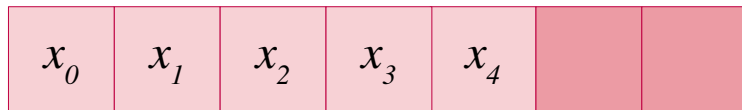
Implementación mediante vectores circulares



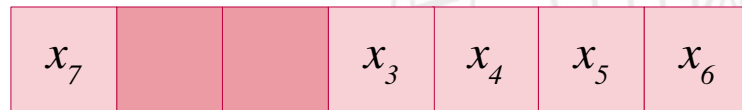
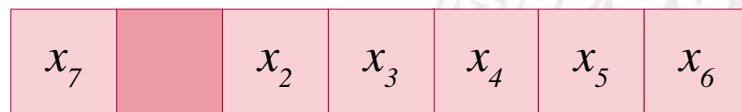
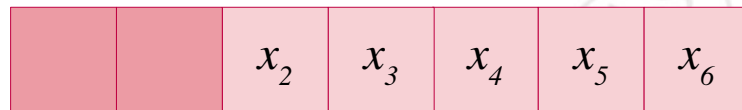
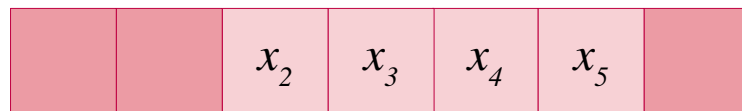
Implementación mediante vectores circulares



Idea: vectores circulares

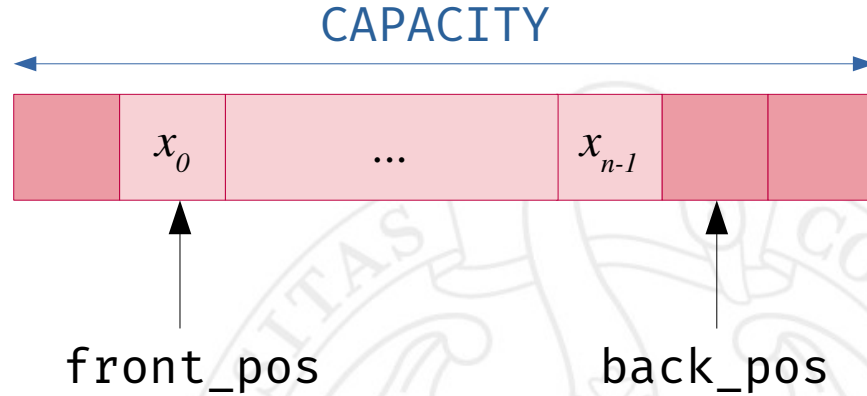


Idea: vectores circulares



Clase QueueArray

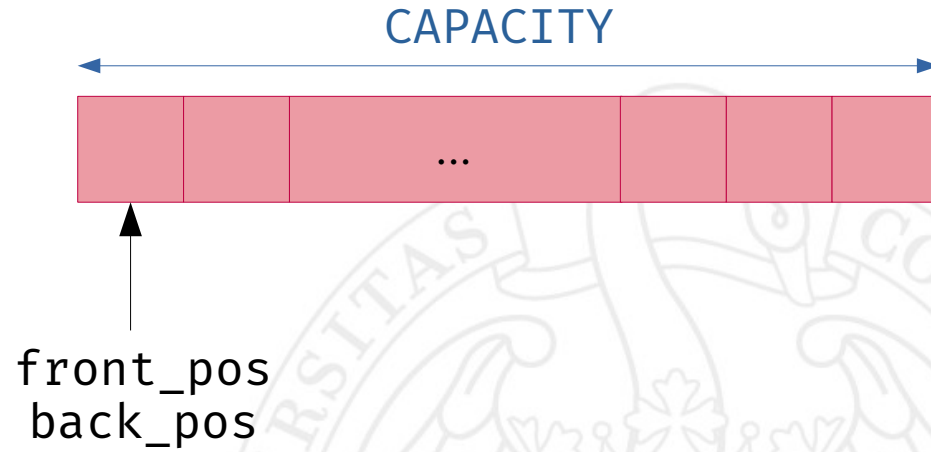
```
class QueueArray {  
public:  
  
    ...  
  
private:  
    T *elems;  
    int front_pos, back_pos;  
};
```



- Si la cola está vacía:
 $\text{front_pos} == \text{back_pos}$

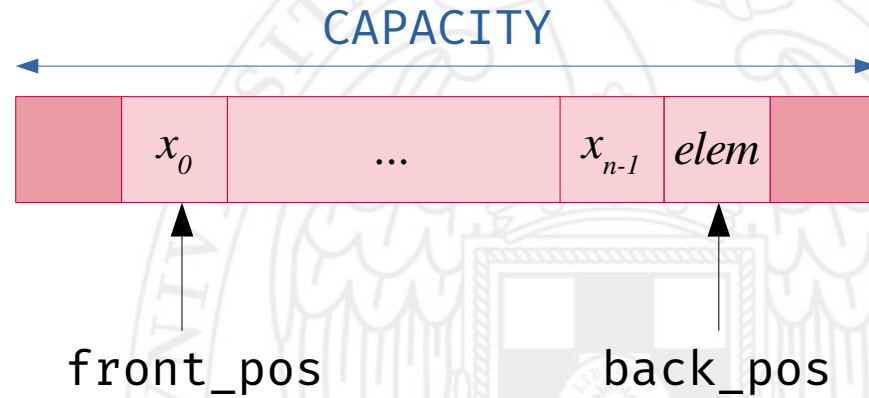
Constructor

```
QueueArray() {  
    elems = new T[CAPACITY];  
    front_pos = 0;  
    back_pos = 0;  
}
```



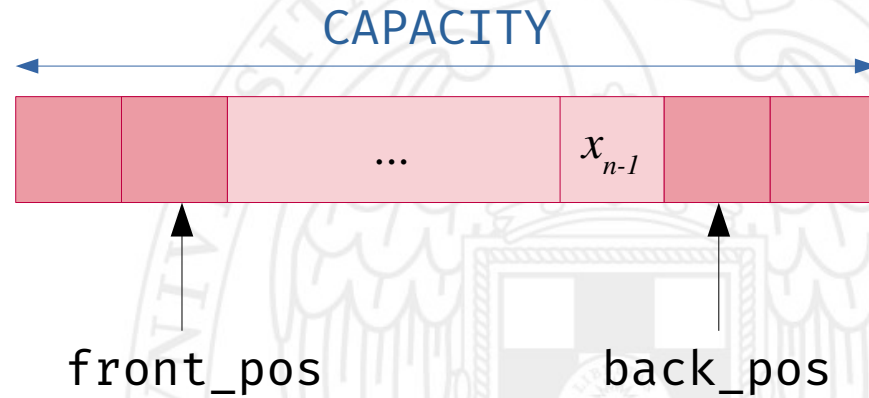
Método push()

```
void push(const T &elem) {  
    // Cabe el elemento en la cola?  
    assert ((back_pos + 1) % CAPACITY != front_pos);  
    elems[back_pos] = elem;  
    back_pos = (back_pos + 1) % CAPACITY;  
}
```



Método pop()

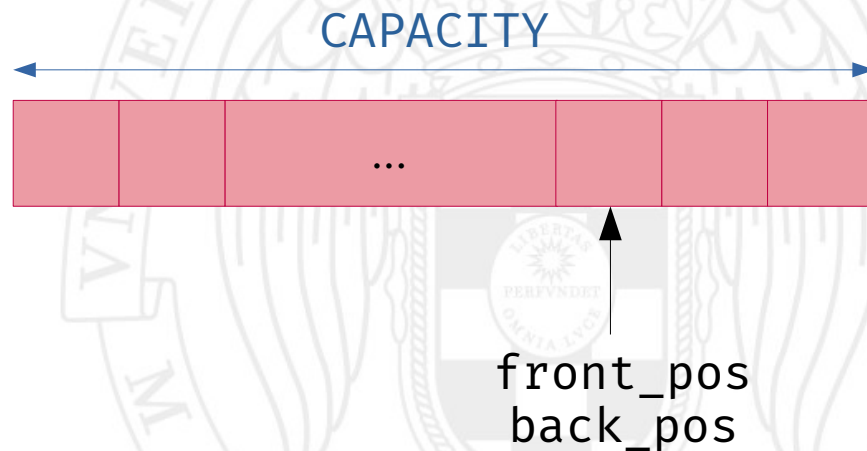
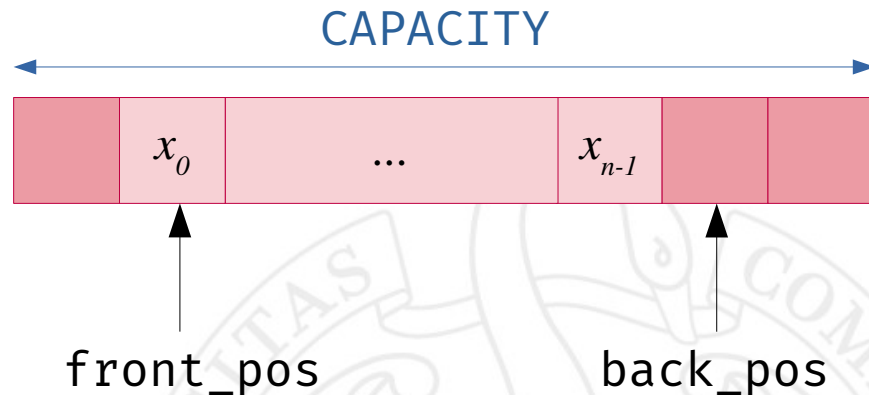
```
void pop() {  
    assert (front_pos  $\neq$  back_pos);  
    front_pos = (front_pos + 1) % CAPACITY;  
}
```



Métodos front() y empty()

```
const T & front() const {  
    assert (front_pos ≠ back_pos);  
    return elems[front_pos];  
}
```

```
bool empty() const {  
    return front_pos == back_pos;  
}
```



Coste de las operaciones

Operación	Listas enlazadas	Vectores circulares
push	$O(1)$	$O(1)$
pop	$O(1)$	$O(1)$
front	$O(1)$	$O(1)$
empty	$O(1)$	$O(1)$

n = número de elementos en la cola