

COMP201

Computer Systems & Programming

Lecture #21 - Cache Memories

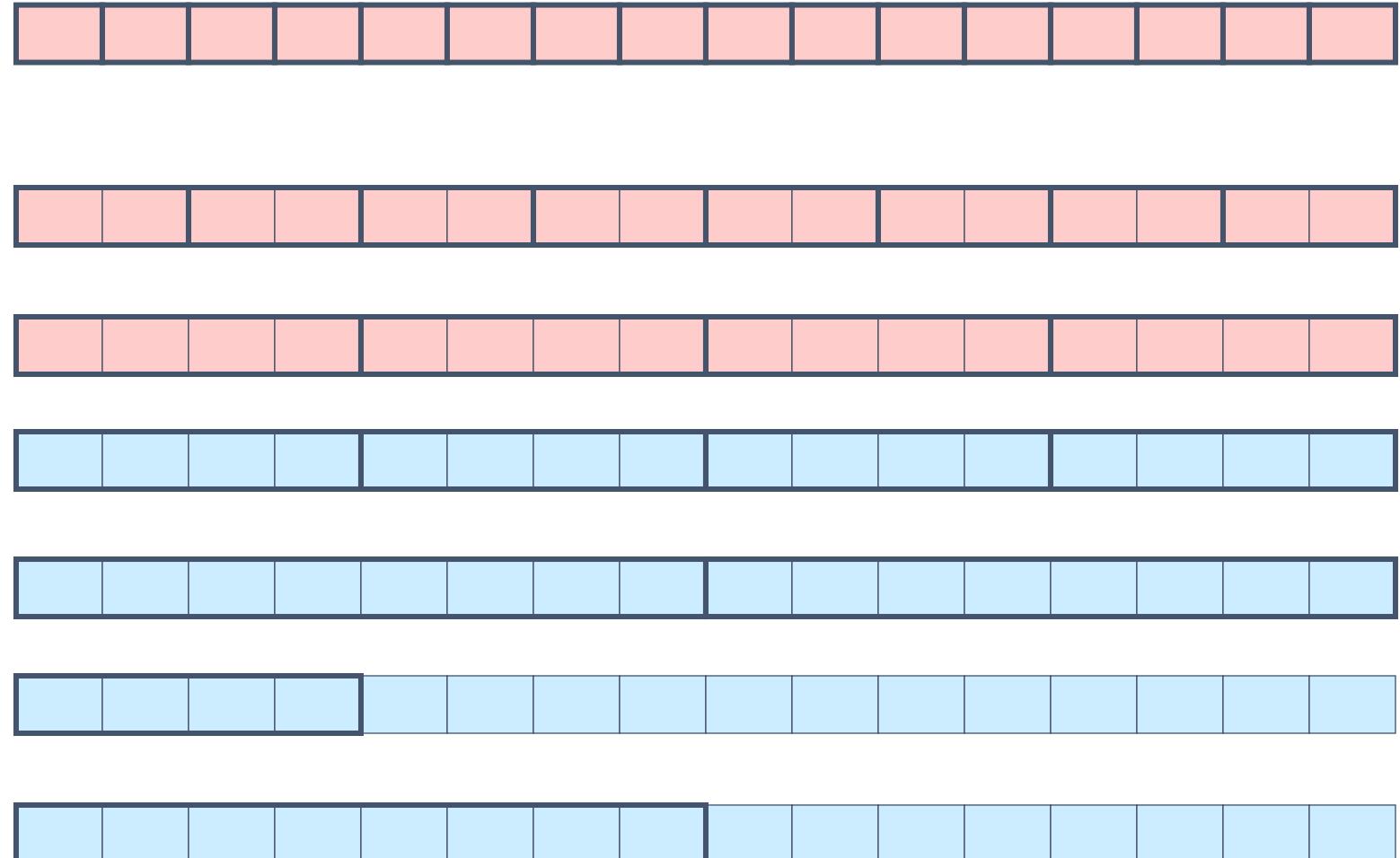
Recap

- Floating Point
- Memory Layout
- Buffer Overflow

Recap: Programming with SSE3

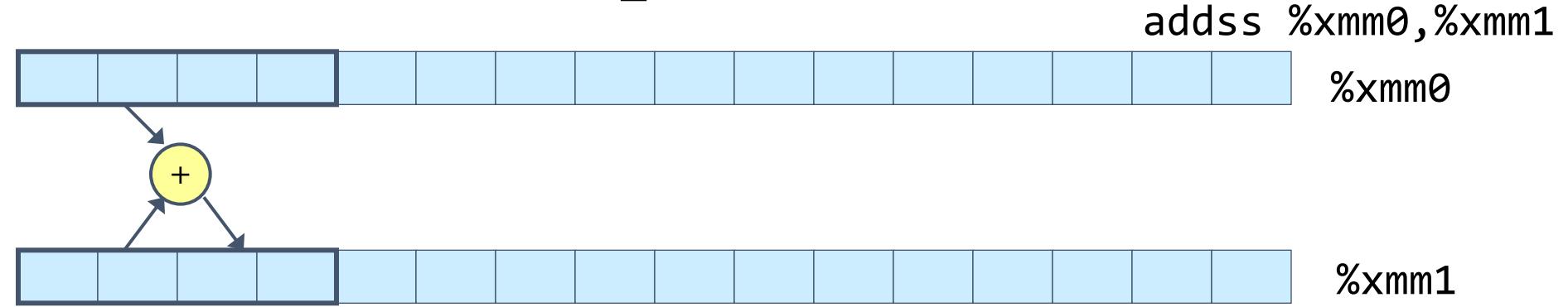
XMM Registers

- 16 total, each 16 bytes
- 16 single-byte integers
- 8 16-bit integers
- 4 32-bit integers
- 4 single-precision floats
- 2 double-precision floats
- 1 single-precision float
- 1 double-precision float

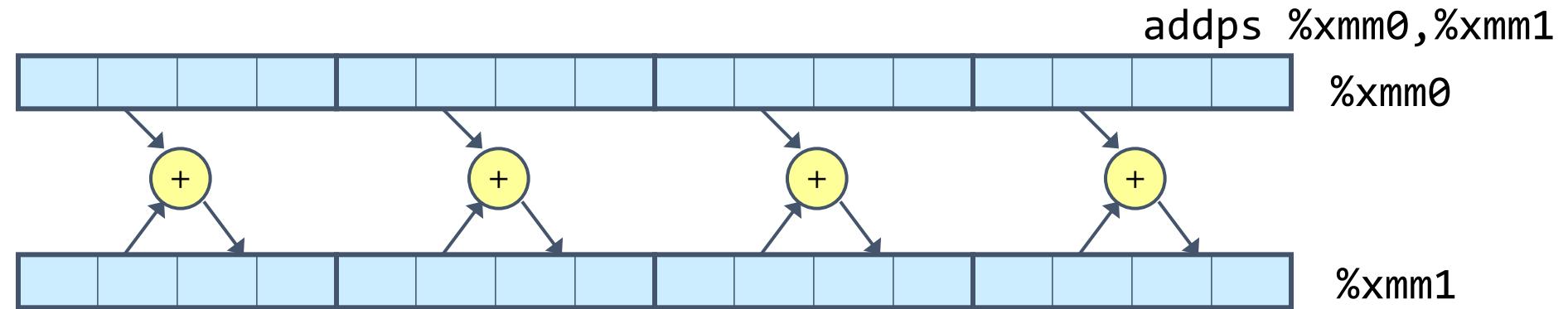


Recap: Scalar & SIMD Operations

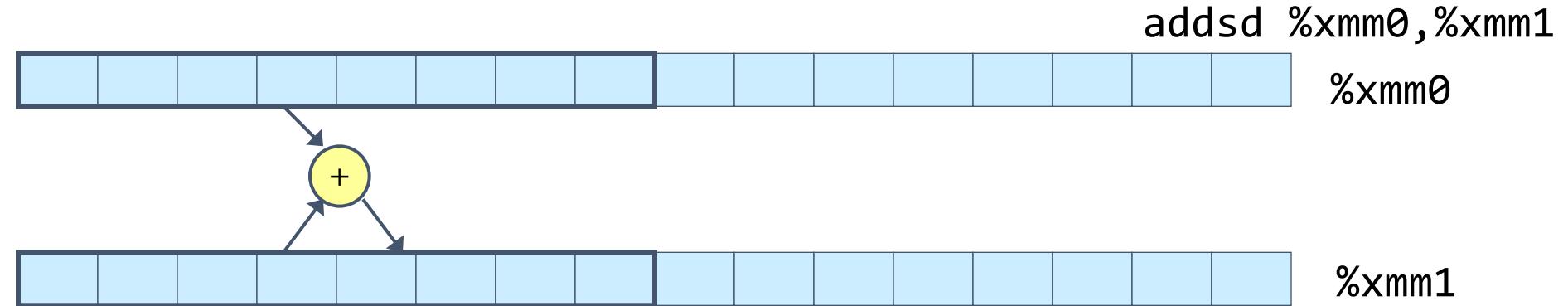
- Scalar Operations:
Single Precision



- SIMD Operations:
Single Precision



- Scalar Operations:
Double Precision



Recap: FP Memory Referencing

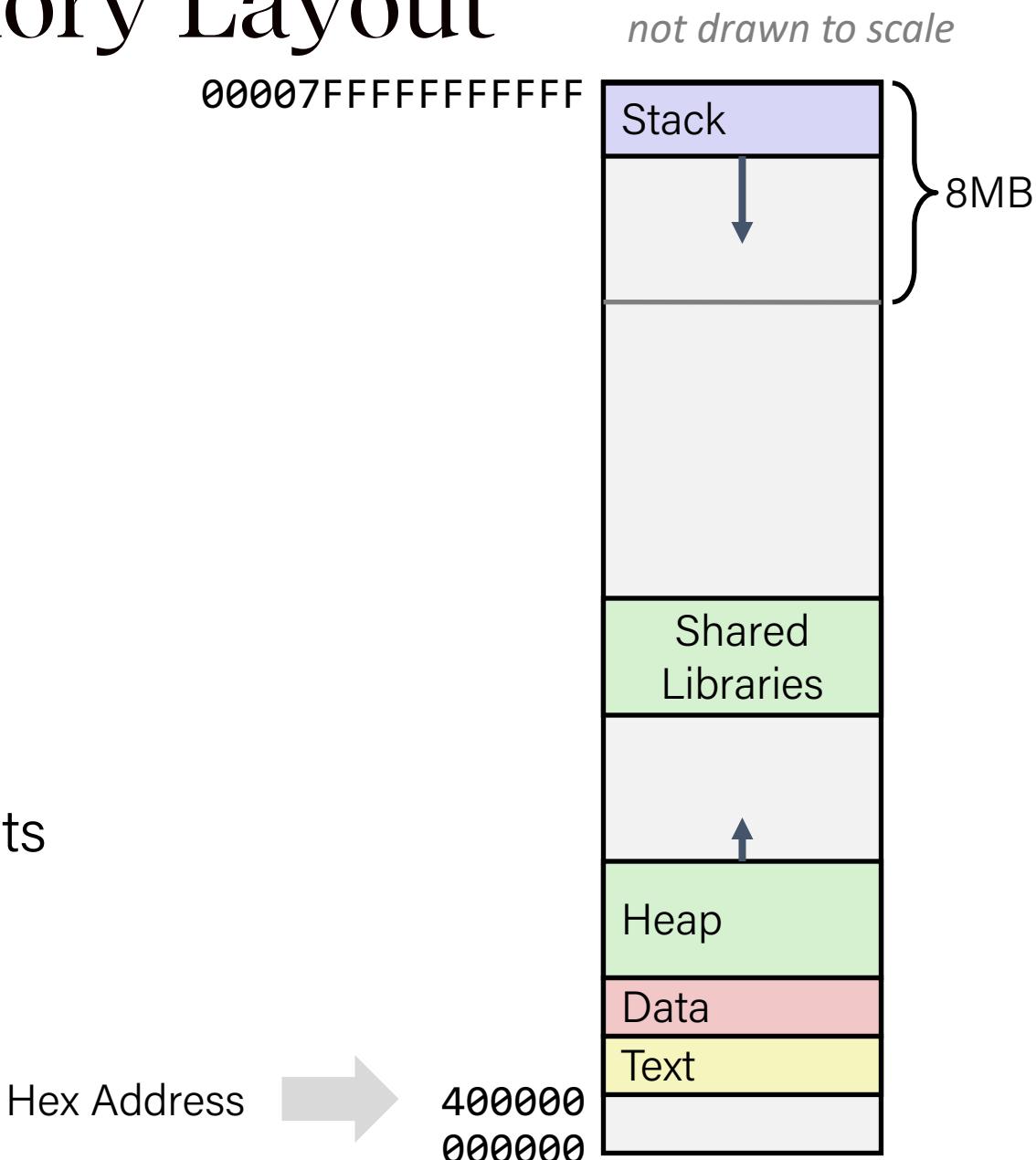
- Integer (and pointer) arguments passed in regular registers
- FP values passed in XMM registers
- Different `mov` instructions to move between XMM registers, and between memory and XMM registers

```
double dincr(double *p, double v)
{
    double x = *p;
    *p = x + v;
    return x;
}
```

```
# p in %rdi, v in %xmm0
movapd  %xmm0, %xmm1    # Copy v
movsd   (%rdi), %xmm0   # x = *p
addsd   %xmm0, %xmm1    # t = x + v
movsd   %xmm1, (%rdi)   # *p = t
ret
```

Recap: x86-64 Linux Memory Layout

- Stack
 - Runtime stack (8MB limit)
 - E. g., local variables
- Heap
 - Dynamically allocated as needed
 - When call `malloc()`, `calloc()`, `new()`
- Data
 - Statically allocated data
 - E.g., global vars, static vars, string constants
- Text / Shared Libraries
 - Executable machine instructions
 - Read-only

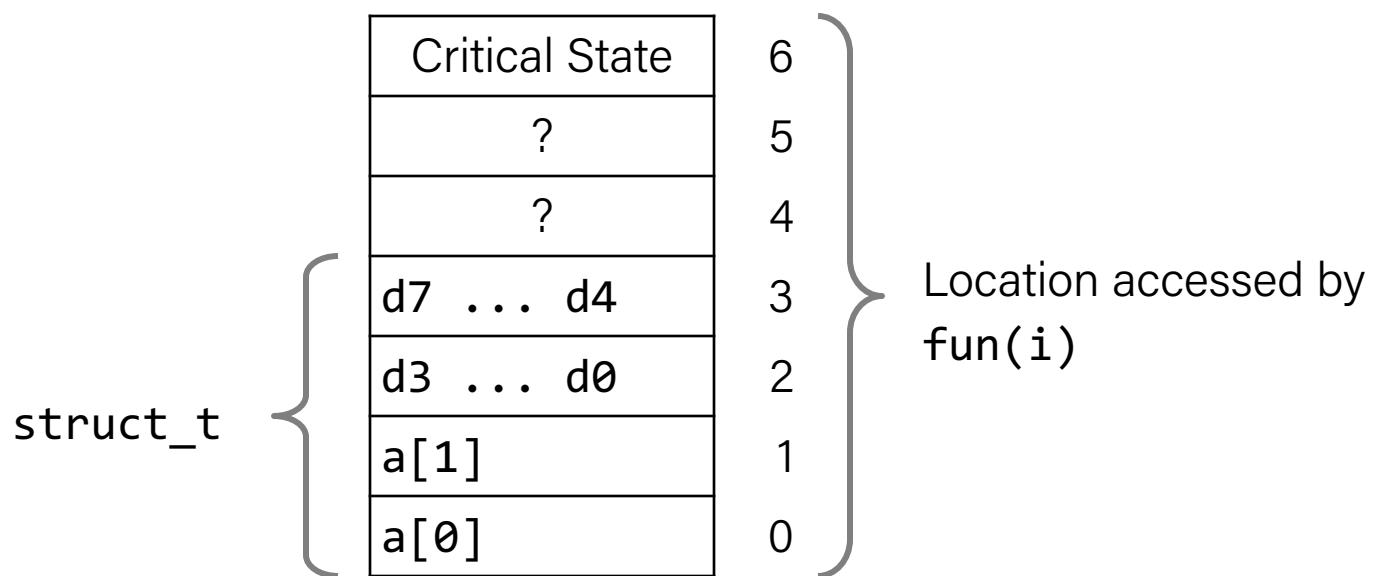


Recap: Memory Referencing Bug Example

```
typedef struct {  
    int a[2];  
    double d;  
} struct_t;
```

fun(0) → 3.14
fun(1) → 3.14
fun(2) → 3.1399998664856
fun(3) → 2.00000061035156
fun(4) → 3.14
fun(6) → Segmentation fault

Explanation:



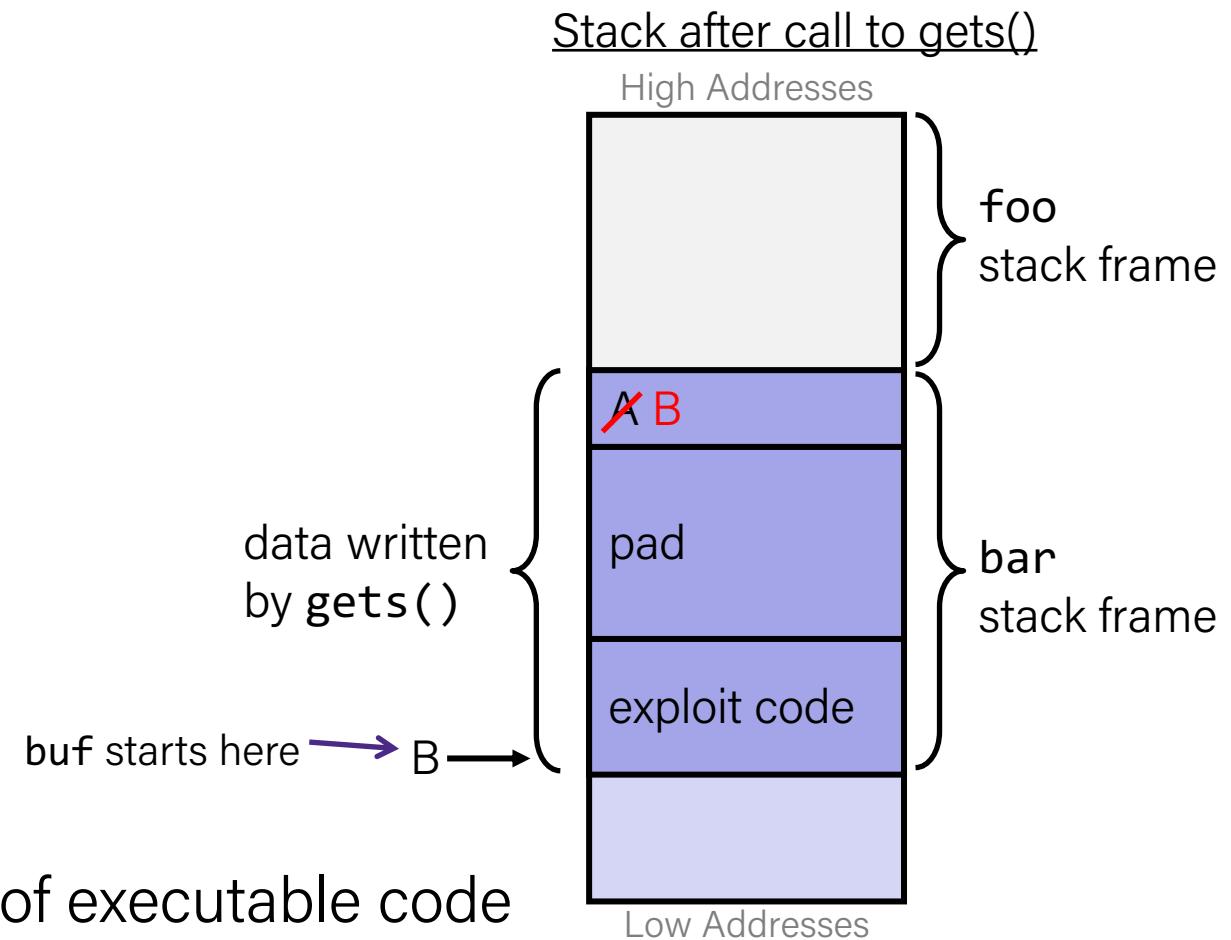
Recap: Buffer Overflows

- **Buffer overflow bugs can allow remote machines to execute arbitrary code on victim machines**
- Distressingly common in real programs
 - Programmers keep making the same mistakes 😞
 - Recent measures make these attacks much more difficult
- Examples across the decades
 - Original “Internet worm” (1988)
 - “IM wars” (1999)
 - Twilight hack on Wii (2000s)
 - ... and many, many more
- You will learn some of the tricks in Assignment 4
 - Hopefully to convince you to never leave such holes in your programs!!

Recap: Malicious Use of Buffer Overflow

```
void foo(){  
    bar();  
    A:...  
}
```

```
int bar() {  
    char buf[64];  
    gets(buf);  
    ...  
    return ...;  
}
```



- Input string contains byte representation of executable code
- Overwrite return address A with address of buffer B
- When bar() executes ret, will jump to exploit code

COMP201 Topic 7: How does the memory system is organized as a hierarchy of different storage devices with unique capacities?

Plan for Today

- The memory abstraction
- Storage technologies and trends
- Locality of reference
- The memory hierarchy
- Cache basics
- Cache organization

Disclaimer: Slides for this lecture were borrowed from
—Randal E. Bryant and David R. O'Hallaroni's CMU 15-213 class
—Porter Jones' UW CSE 351 class

Lecture Plan

- The memory abstraction
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Writing & Reading Memory

- Write

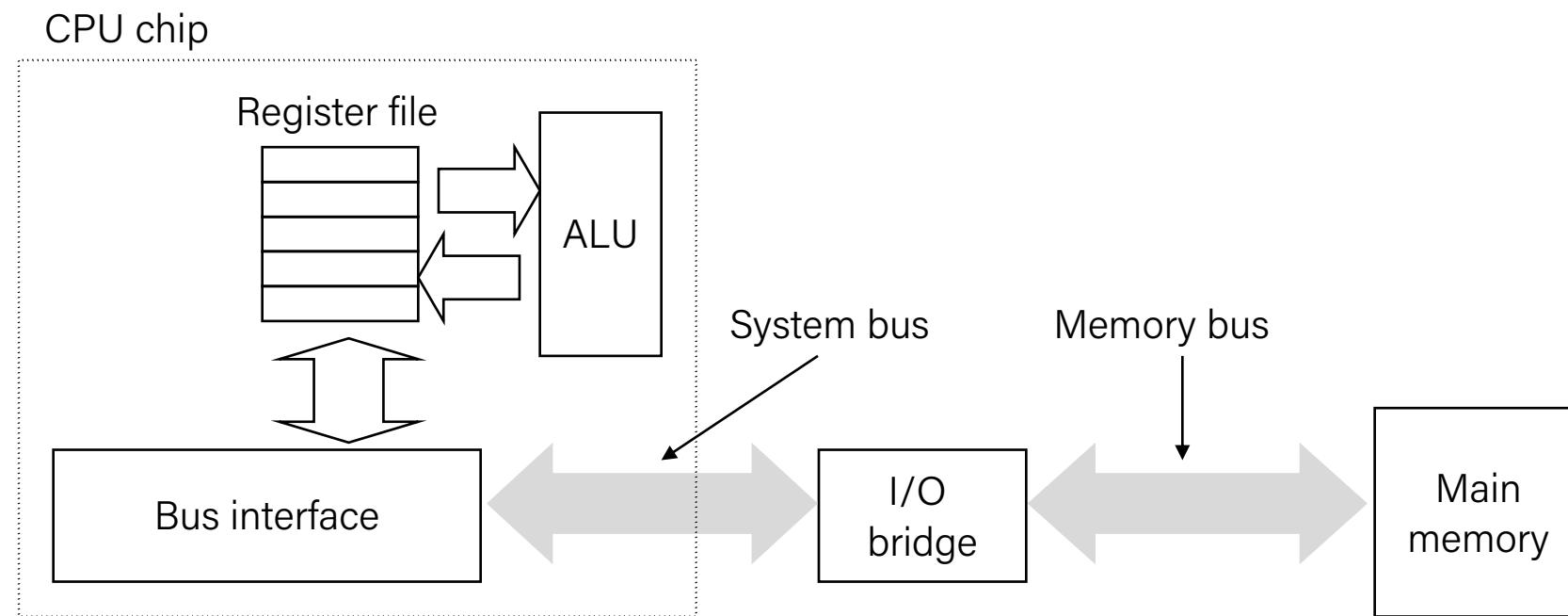
- Transfer data from CPU to memory
`movq %rax, 8(%rsp)`
 - “Store” operation

- Read

- Transfer data from memory to CPU
`movq 8(%rsp), %rax`
 - “Load” operation

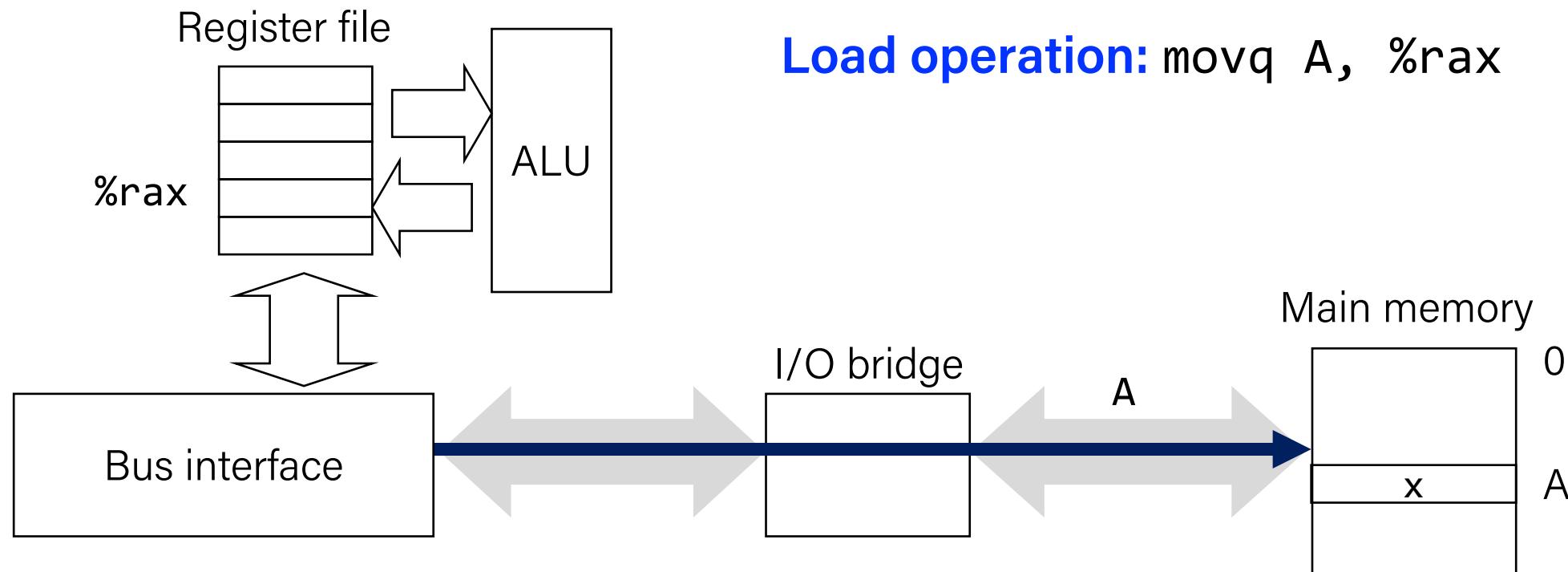
Traditional Bus Structure Connecting CPU and Memory

- A **bus** is a collection of parallel wires that carry address, data, and control signals.
- Buses are typically shared by multiple devices.



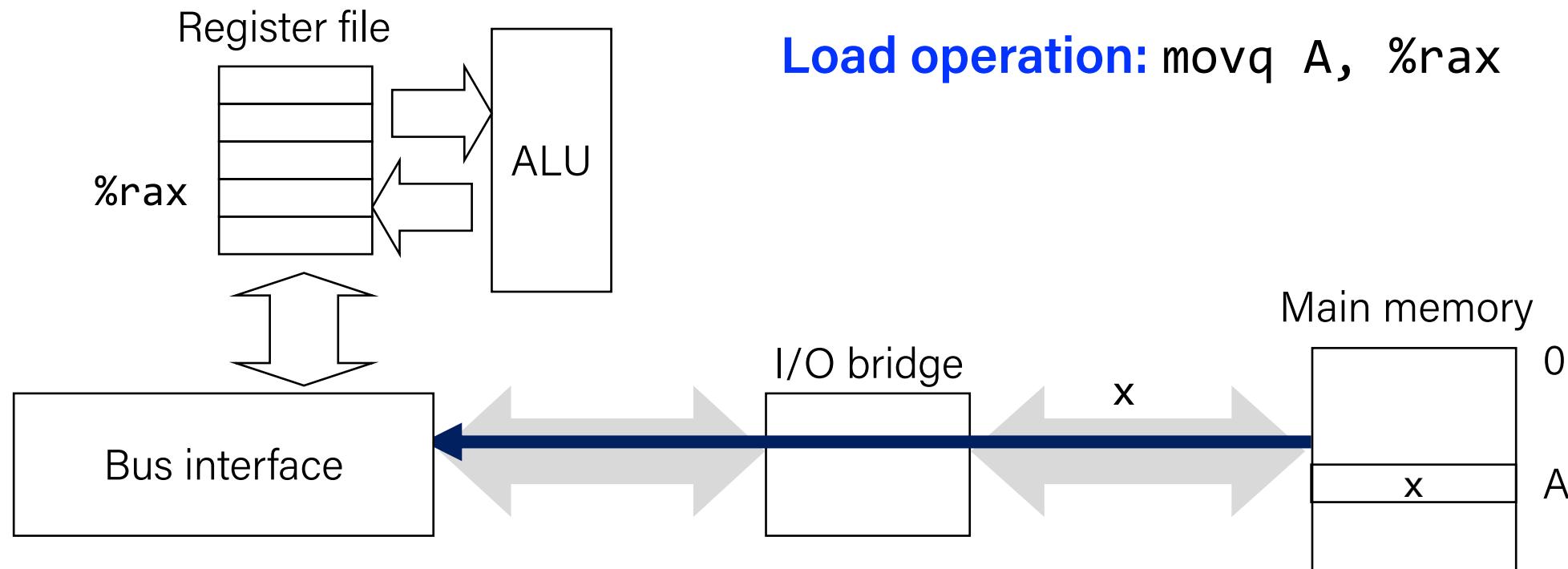
Memory Read Transaction (1)

- CPU places address A on the memory bus.



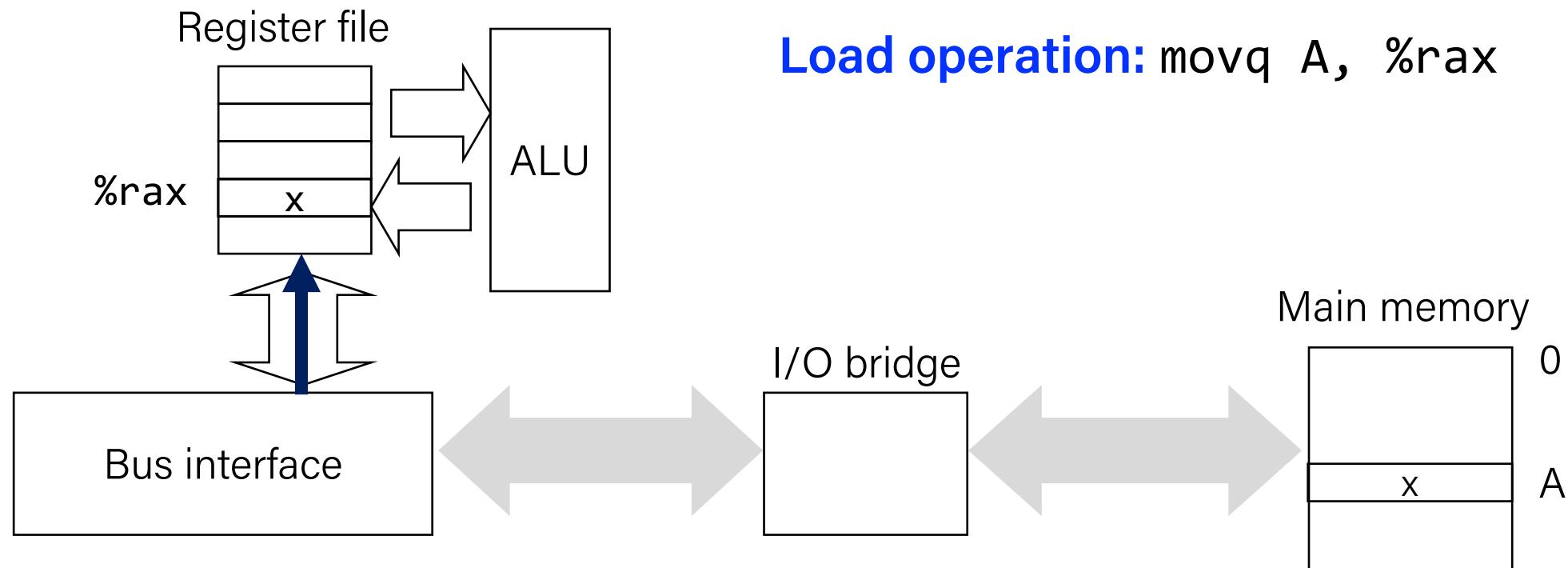
Memory Read Transaction (2)

- Main memory reads A from the memory bus, retrieves word x, and places it on the bus.



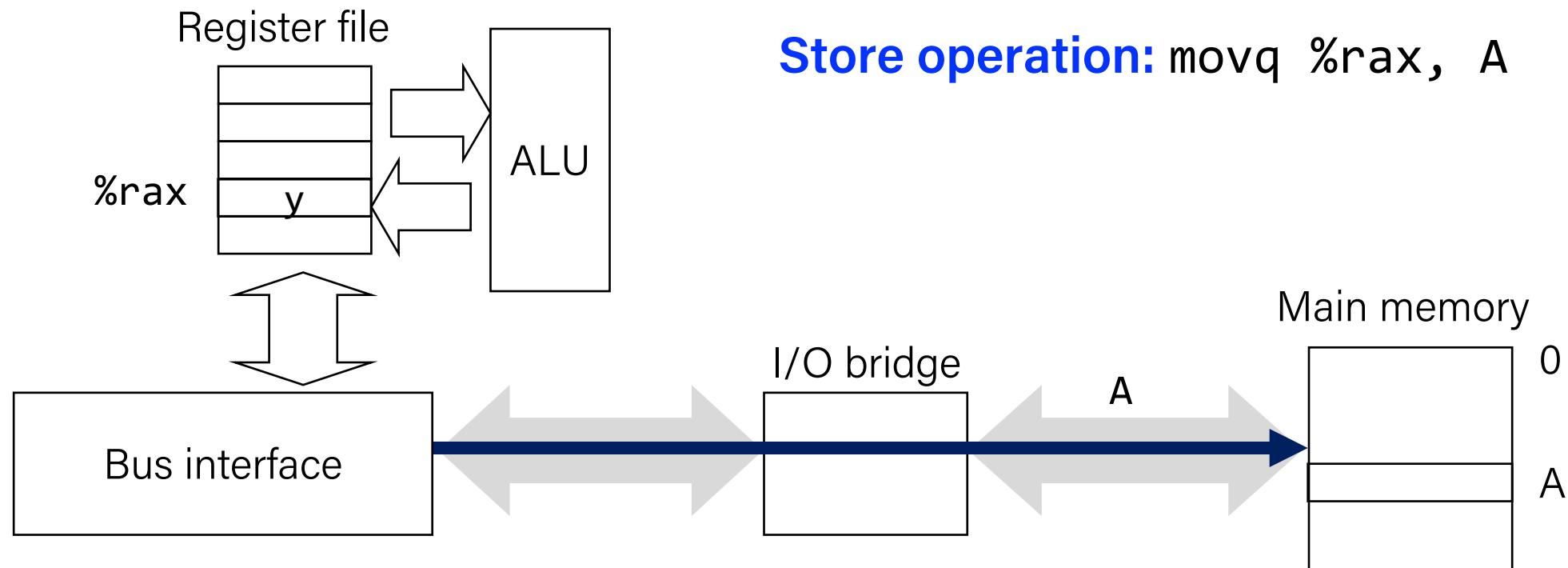
Memory Read Transaction (3)

- CPU read word x from the bus and copies it into register $\%rax$.



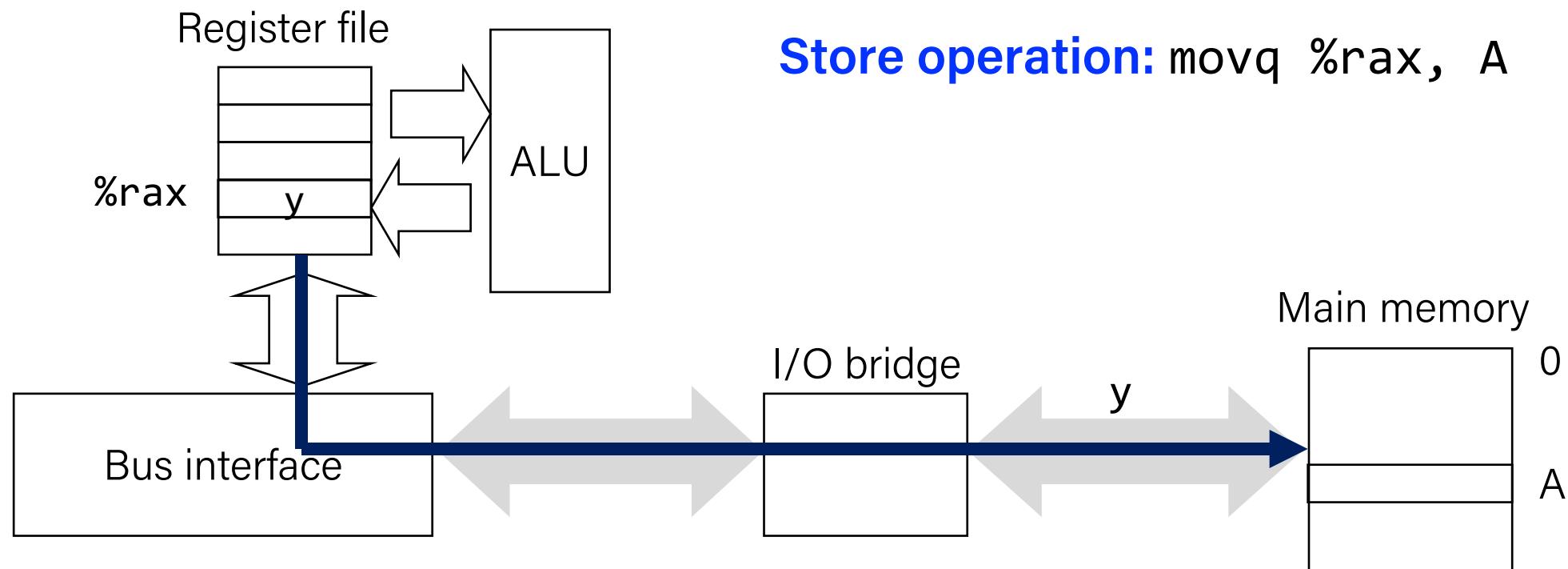
Memory Write Transaction (1)

- CPU places address A on bus. Main memory reads it and waits for the corresponding data word to arrive.



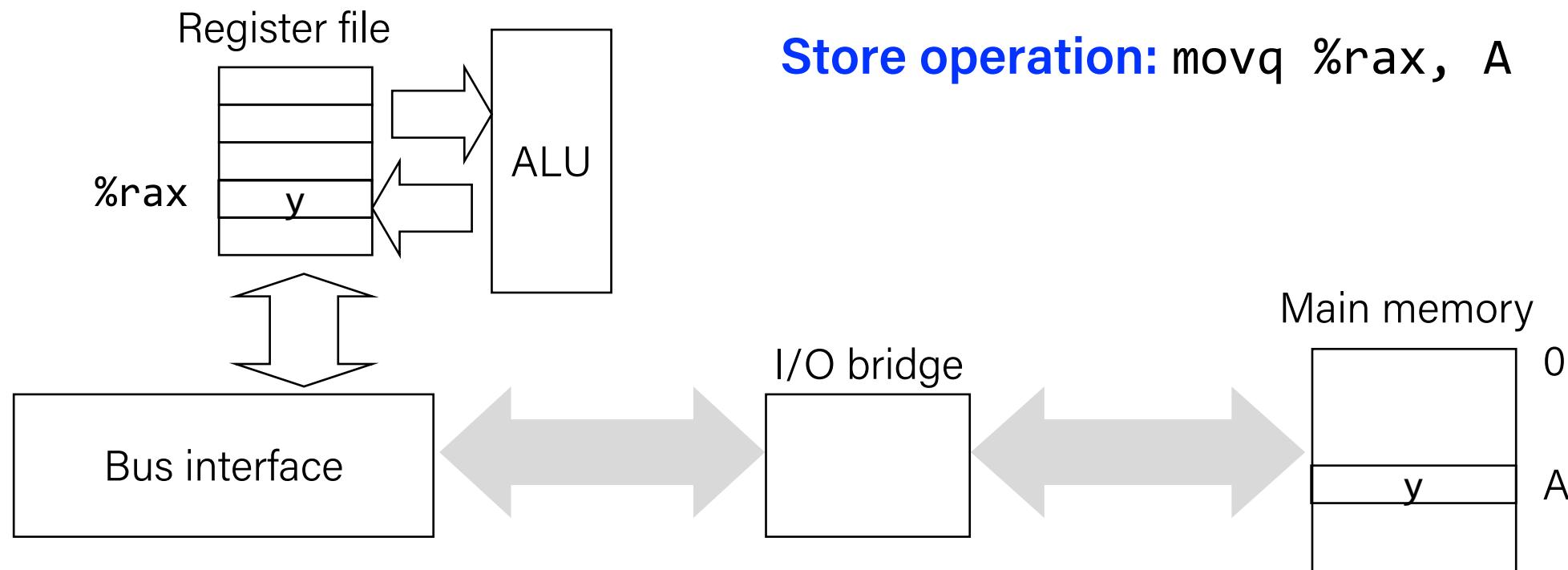
Memory Write Transaction (2)

- CPU places data word y on the bus.



Memory Write Transaction (3)

- Main memory reads data word y from the bus and stores it at address A .



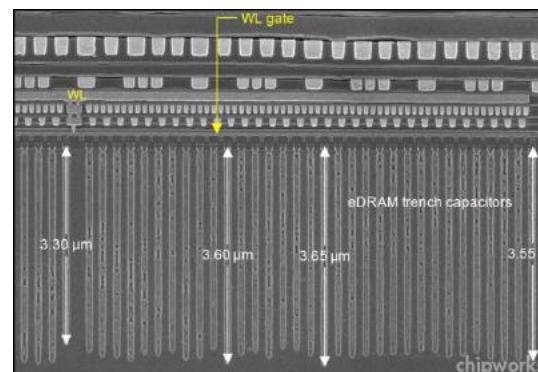
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- Locality of reference
- The memory hierarchy
- Cache basics
- Cache organization

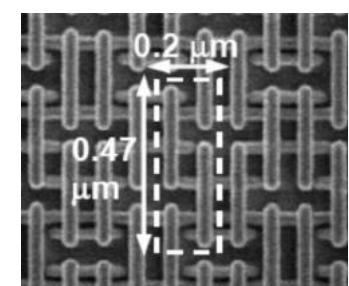
Random-Access Memory (RAM)

- Key features
 - RAM is traditionally packaged as a chip.
 - Basic storage unit is normally a **cell** (one bit per cell).
 - Multiple RAM chips form a memory.

- RAM comes in two varieties:
 - SRAM (Static RAM)
 - DRAM (Dynamic RAM)



DRAM



SRAM

SRAM vs DRAM

	Trans. per bit	Access time	Needs refresh?	Need EDC?	Cost	Applications
SRAM	4 or 6	1X	No	Maybe	100X	Cache memories
DRAM	1	10X	Yes	Yes	1X	Main memories, frame buffers

EDC: Error detection and correction

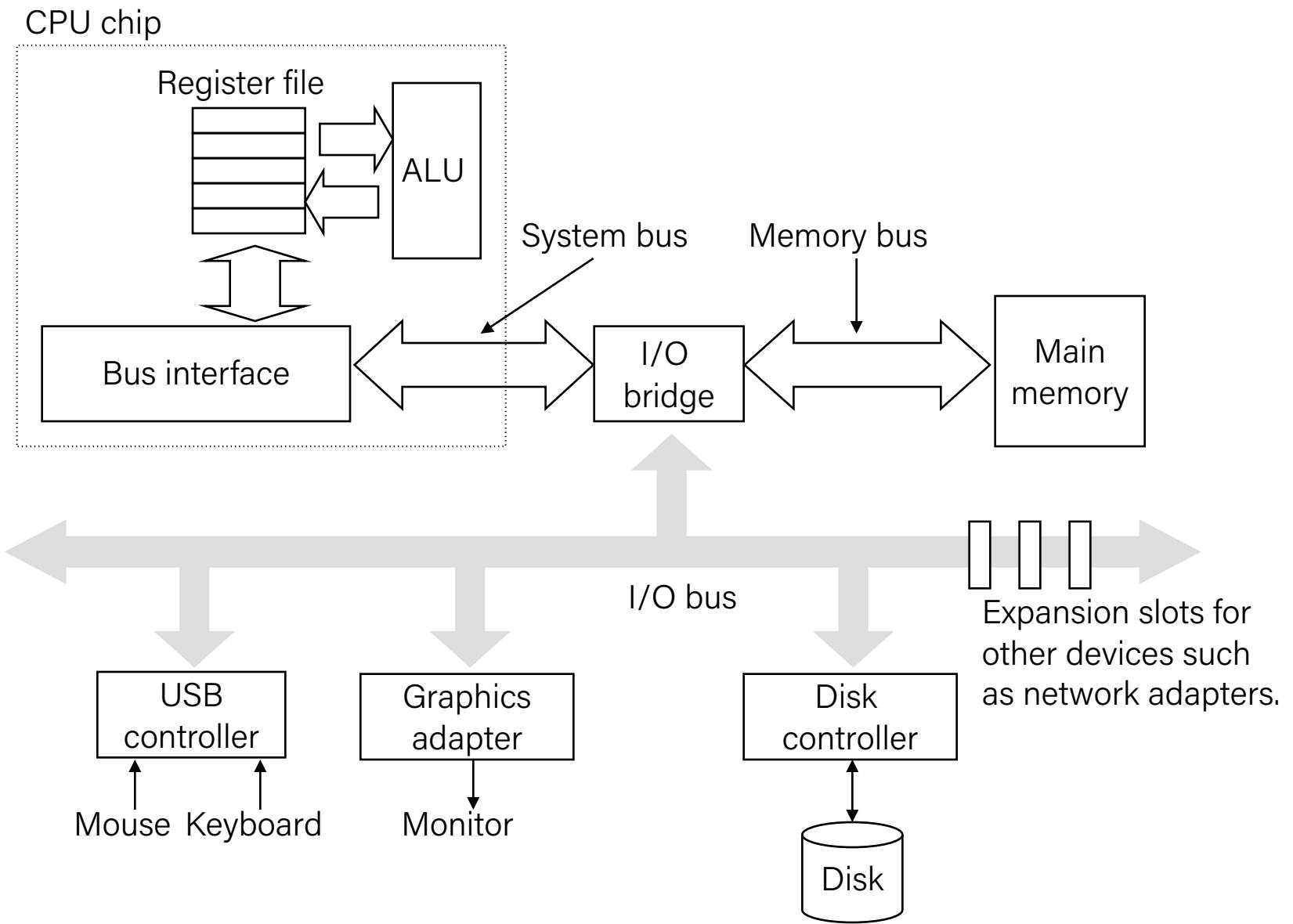
Trends

- SRAM scales with semiconductor technology
 - Reaching its limits
- DRAM scaling limited by need for minimum capacitance
 - Aspect ratio limits how deep can make capacitor
 - Also reaching its limits

Enhanced DRAMs

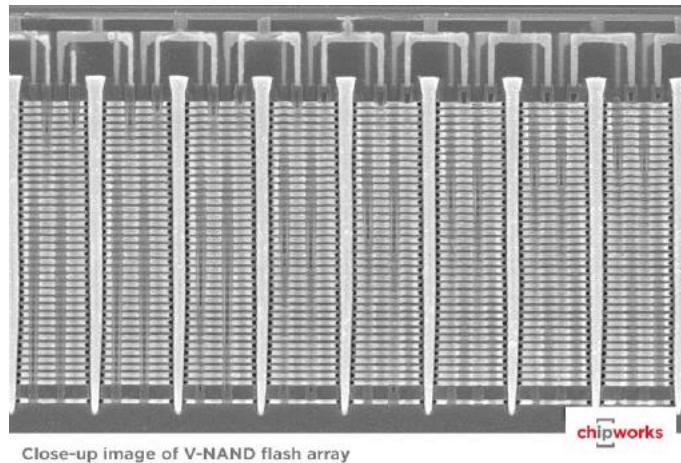
- Operation of DRAM cell has not changed since its invention
 - Commercialized by Intel in 1970.
- DRAM cores with better interface logic and faster I/O:
 - Synchronous DRAM (**SDRAM**)
 - Uses a conventional clock signal instead of asynchronous control
 - Double data-rate synchronous DRAM (**DDR SDRAM**)
 - Double edge clocking sends two bits per cycle per pin
 - Different types distinguished by size of small prefetch buffer:
 - **DDR** (2 bits), **DDR2** (4 bits), **DDR3** (8 bits), **DDR4** (16 bits)
 - By 2010, standard for most server and desktop systems
 - Intel Core i7 supports DDR3 and DDR4 SDRAM

I/O Bus



Storage Technologies

- Nonvolatile (Flash) Memory



- Store as persistent charge
- Implemented with 3-D structure
 - 100+ levels of cells
 - 3 bits data per cell

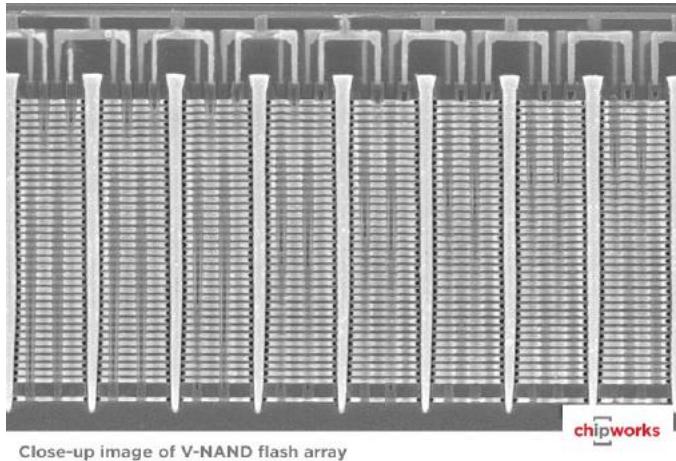
- Magnetic Disks



- Store on magnetic medium
- Electromechanical access

Storage Technologies

- Nonvolatile (Flash) Memory



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Nonvolatile Memories

- **DRAM and SRAM are volatile memories**
 - Lose information if powered off.
- **Nonvolatile memories retain value even if powered off**
 - Read-only memory (ROM): programmed during production
 - Electrically erasable PROM (EEPROM): electronic erase capability
 - Flash memory: EEPROMs with partial (block-level) erase capability
 - Wears out after about 100,000 erasings
 - 3D XPoint (Intel Optane) & emerging NVMs
 - New materials

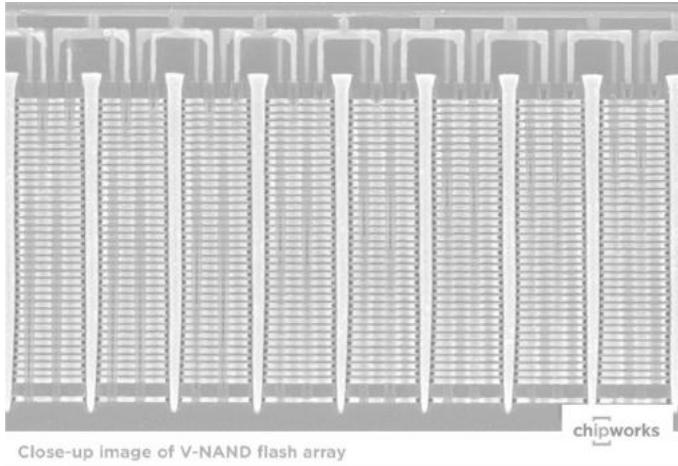


• Uses for Nonvolatile Memories

- Firmware programs stored in a ROM (BIOS, controllers for disks, network cards, graphics accelerators, security subsystems,...)
- Solid state disks (replace rotating disks in thumb drives, smart phones, mp3 players, tablets, laptops,...)
- Disk caches

Storage Technologies

- Nonvolatile (Flash) Memory



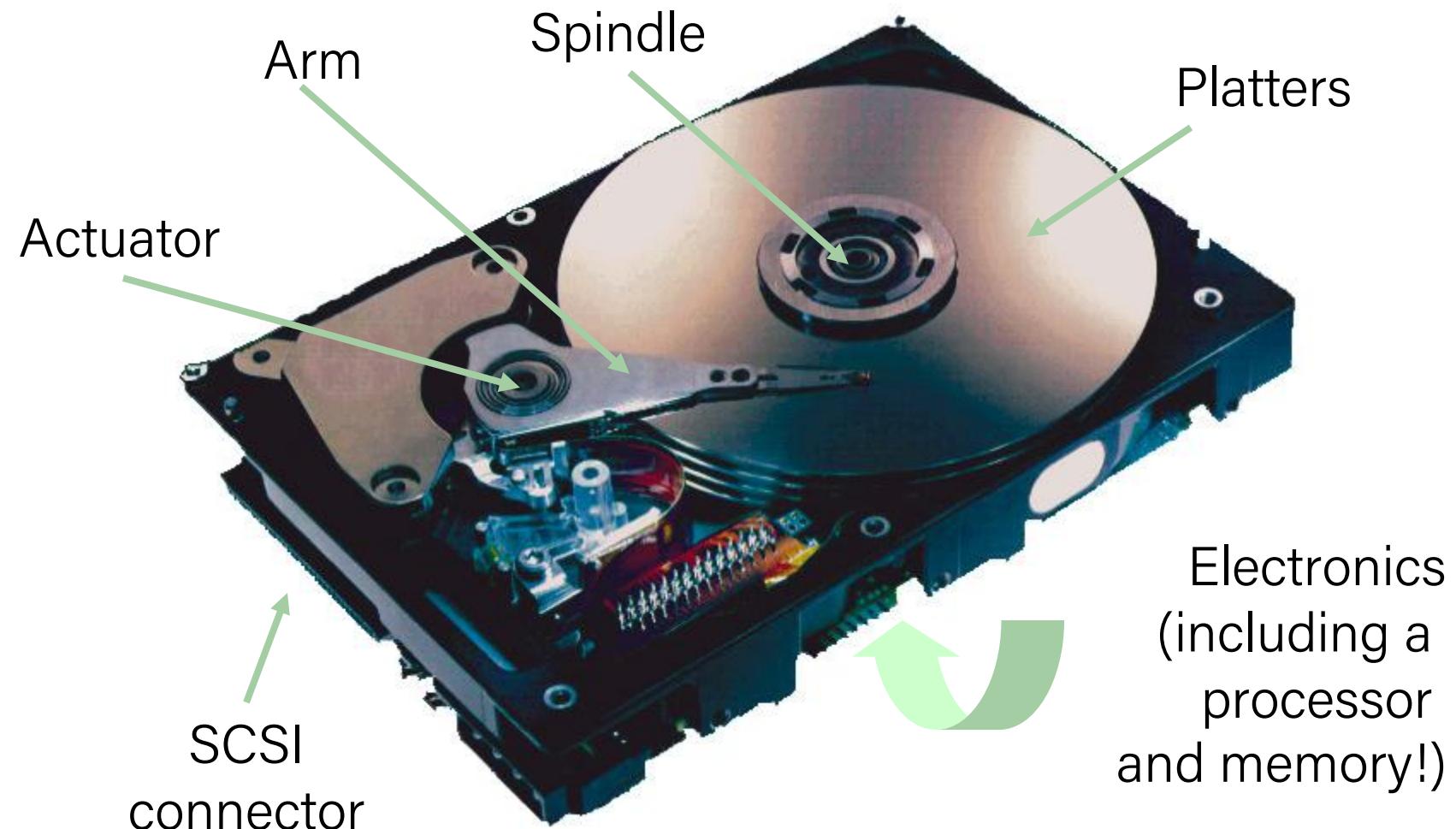
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- Magnetic Disks



- Store on magnetic medium
- Electromechanical access

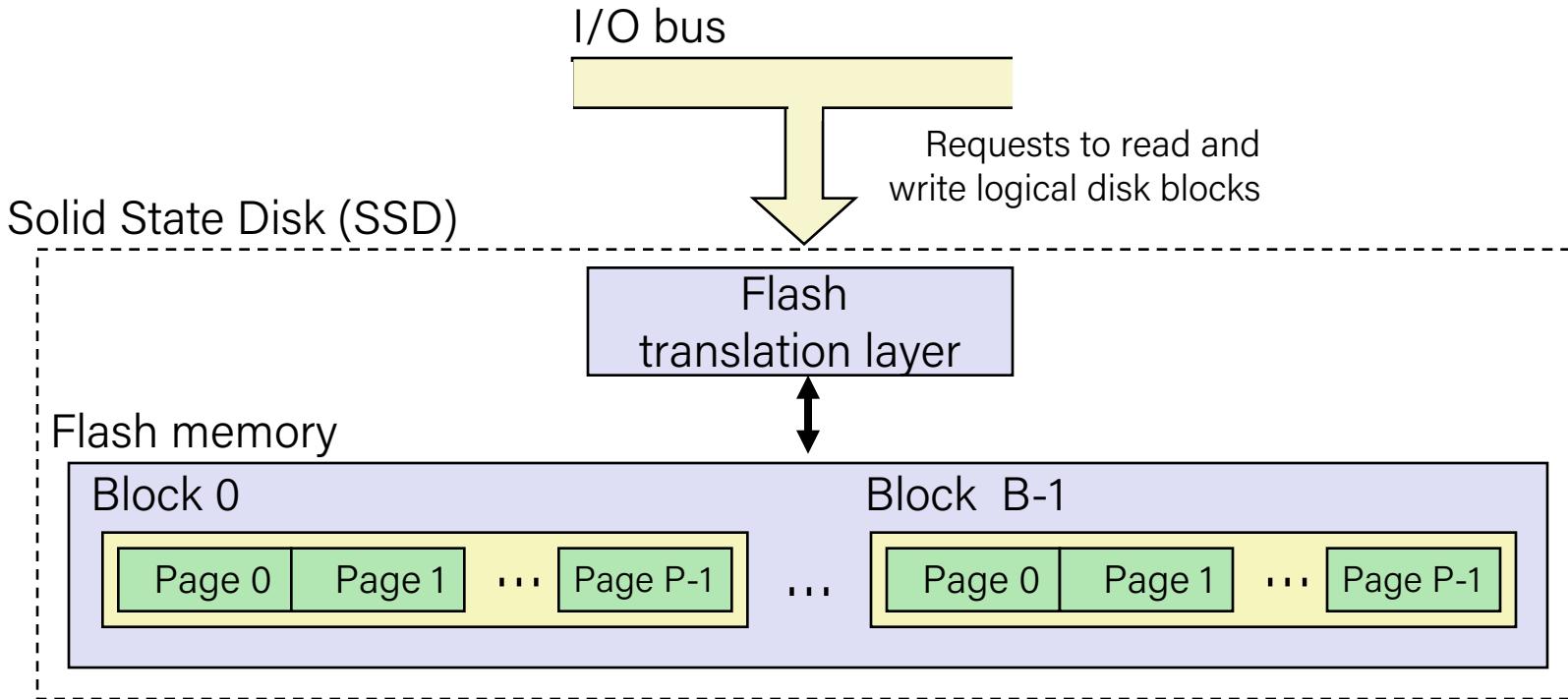
What's Inside A Magnetic Disk Drive?



Disk Access Time

- Given:
 - Rotational rate = 7,200 RPM
 - Average seek time = 9 ms.
 - Avg # sectors/track = 400.
- Derived:
 - $T_{avg\ rotation} = 1/2 \times (60\ secs/7200\ RPM) \times 1000\ ms/sec = 4\ ms.$
 - $T_{avg\ transfer} = 60/7200\ RPM \times 1/400\ secs/track \times 1000\ ms/sec = 0.02\ ms$
 - $T_{access} = 9\ ms + 4\ ms + 0.02\ ms$
- Important points:
 - Access time dominated by seek time and rotational latency.
 - First bit in a sector is the most expensive, the rest are free.
 - **SRAM access time is about 4 ns/doubleword, DRAM about 60 ns**
 - Disk is about 40,000 times slower than SRAM,
 - 2,500 times slower than DRAM.

Solid State Disks (SSDs)



- Pages: 512KB to 4KB, Blocks: 32 to 128 pages
- Data read/written in units of pages.
- Page can be written only after its block has been erased
- A block wears out after about 100,000 repeated writes.

SSD Tradeoffs vs Rotating Disks

- **Advantages**

- No moving parts → faster, less power, more rugged

- **Disadvantages**

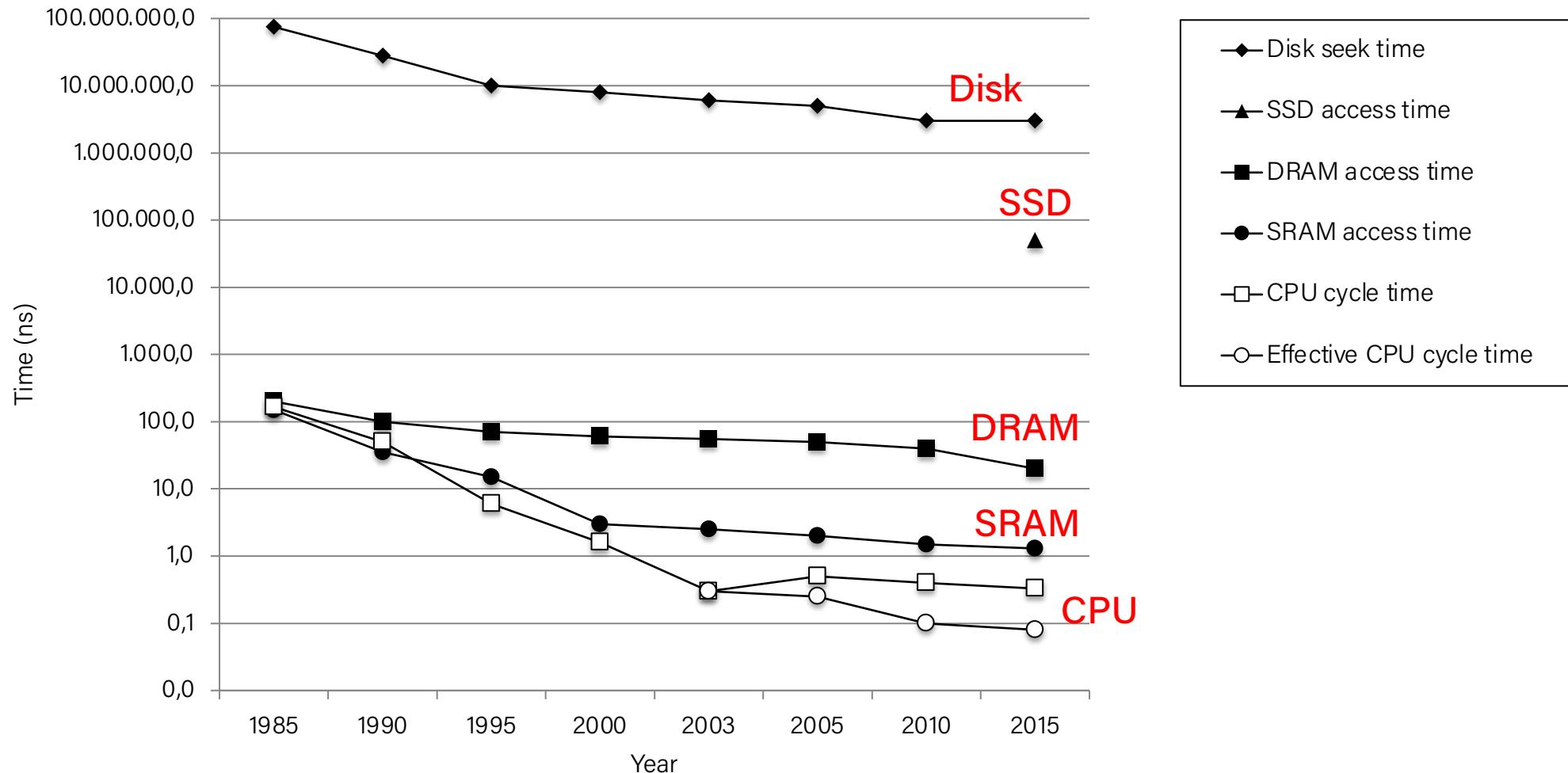
- Have the potential to wear out
 - Mitigated by “wear leveling logic” in flash translation layer
 - E.g. Samsung 940 EVO Plus guarantees 600 writes/byte of writes before they wear out
 - Controller migrates data to minimize wear level
 - In 2019, about 4 times more expensive per byte
 - And, relative cost will keep dropping

- **Applications**

- MP3 players, smart phones, laptops
 - Beginning to appear in desktops and servers

The CPU-Memory Gap

- The gap widens between DRAM, disk, and CPU speeds.



Locality to the Rescue!

- The key to bridging this CPU-Memory gap is a fundamental property of computer programs known as locality

Lecture Plan

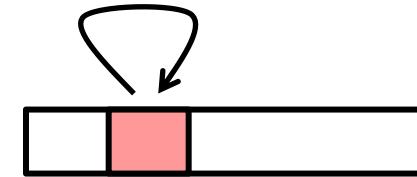
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Locality

- **Principle of Locality:** Programs tend to use data and instructions with addresses near or equal to those they have used recently

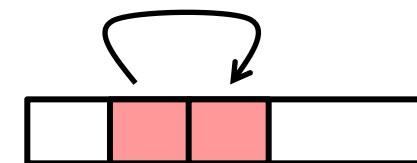
- **Temporal locality:**

- Recently referenced items are likely to be referenced again in the near future



- **Spatial locality:**

- Items with nearby addresses tend to be referenced close together in time



Locality Example

```
sum = 0;  
for (i = 0; i < n; i++)  
    sum += a[i];  
return sum;
```

- Data references
 - Reference array elements in succession (stride-1 reference pattern). **Spatial locality**
 - Reference variable sum each iteration. **Temporal locality**
- Instruction references
 - Reference instructions in sequence. **Spatial locality**
 - Cycle through loop repeatedly. **Temporal locality**

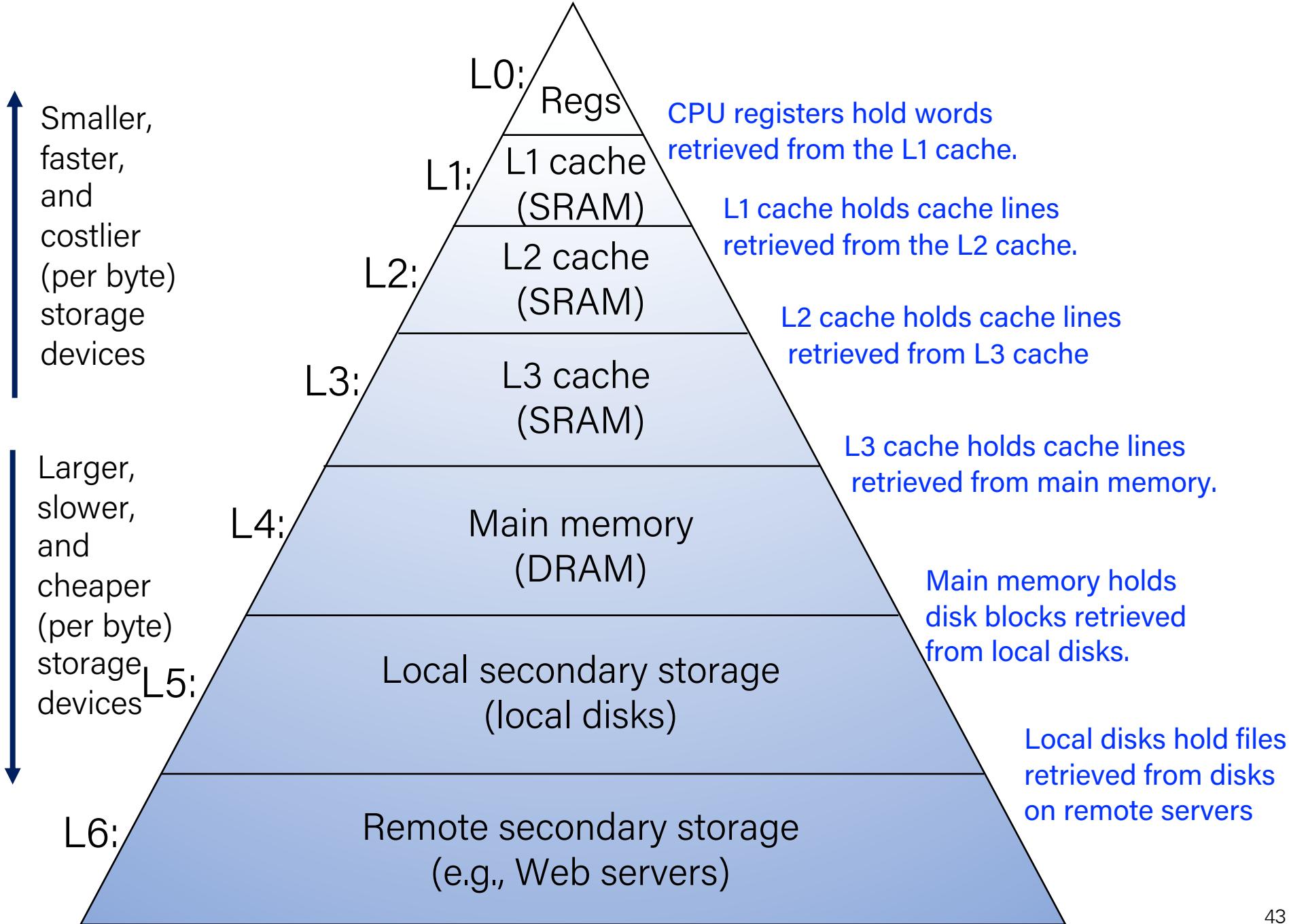
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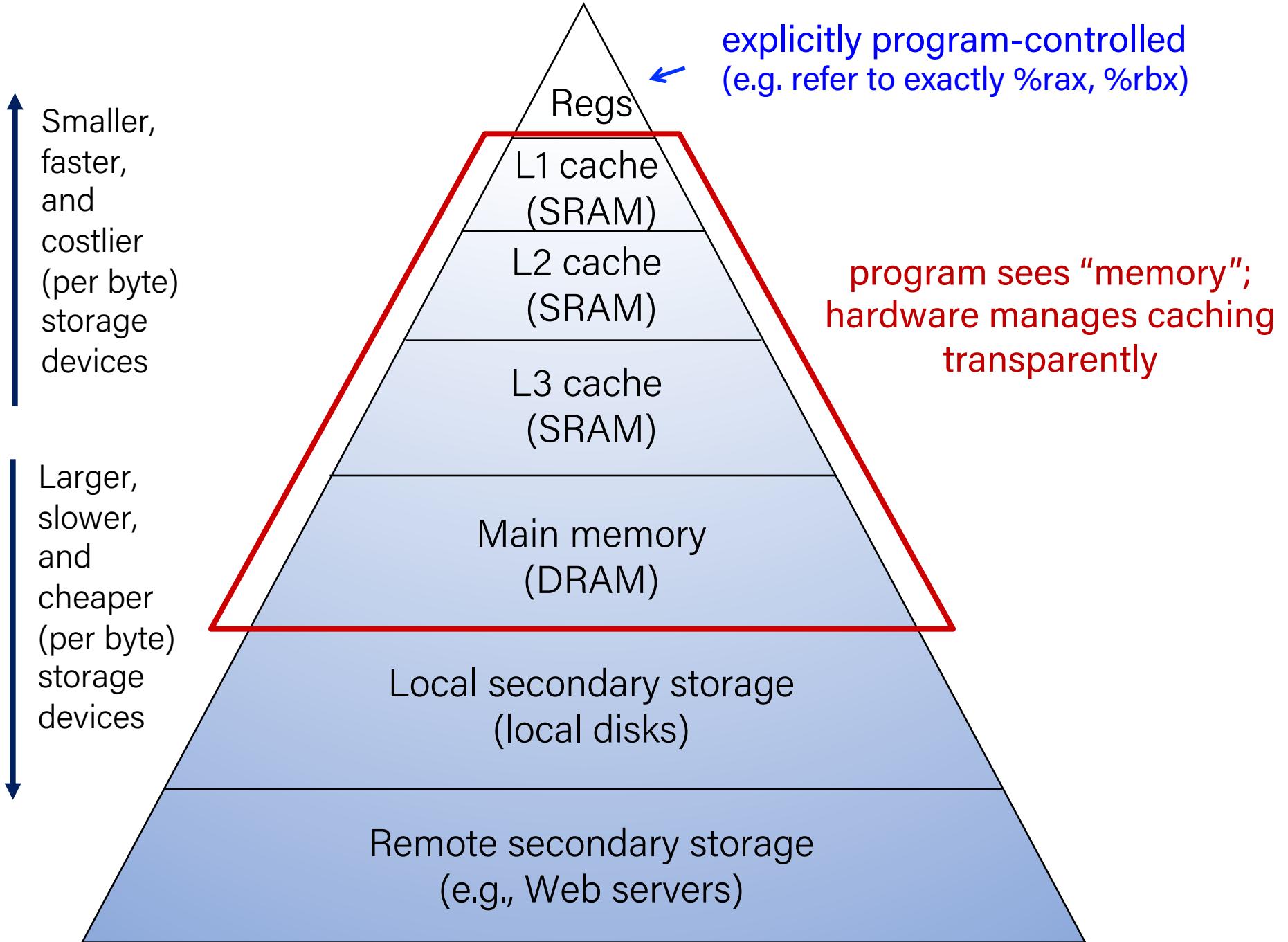
Memory Hierarchies

- Some fundamental and enduring properties of hardware and software:
 - Fast storage technologies cost more per byte, have less capacity, and require more power (heat!).
 - The gap between CPU and main memory speed is widening.
 - True for: registers \leftrightarrow cache, cache \leftrightarrow DRAM, DRAM \leftrightarrow disk, etc.
 - Well-written programs tend to exhibit good locality.
- These fundamental properties complement each other beautifully.
- They suggest an approach for organizing memory and storage systems known as a **memory hierarchy**.
 - For each level k , the faster, smaller device at level k serves as a cache for the larger, slower device at level $k+1$

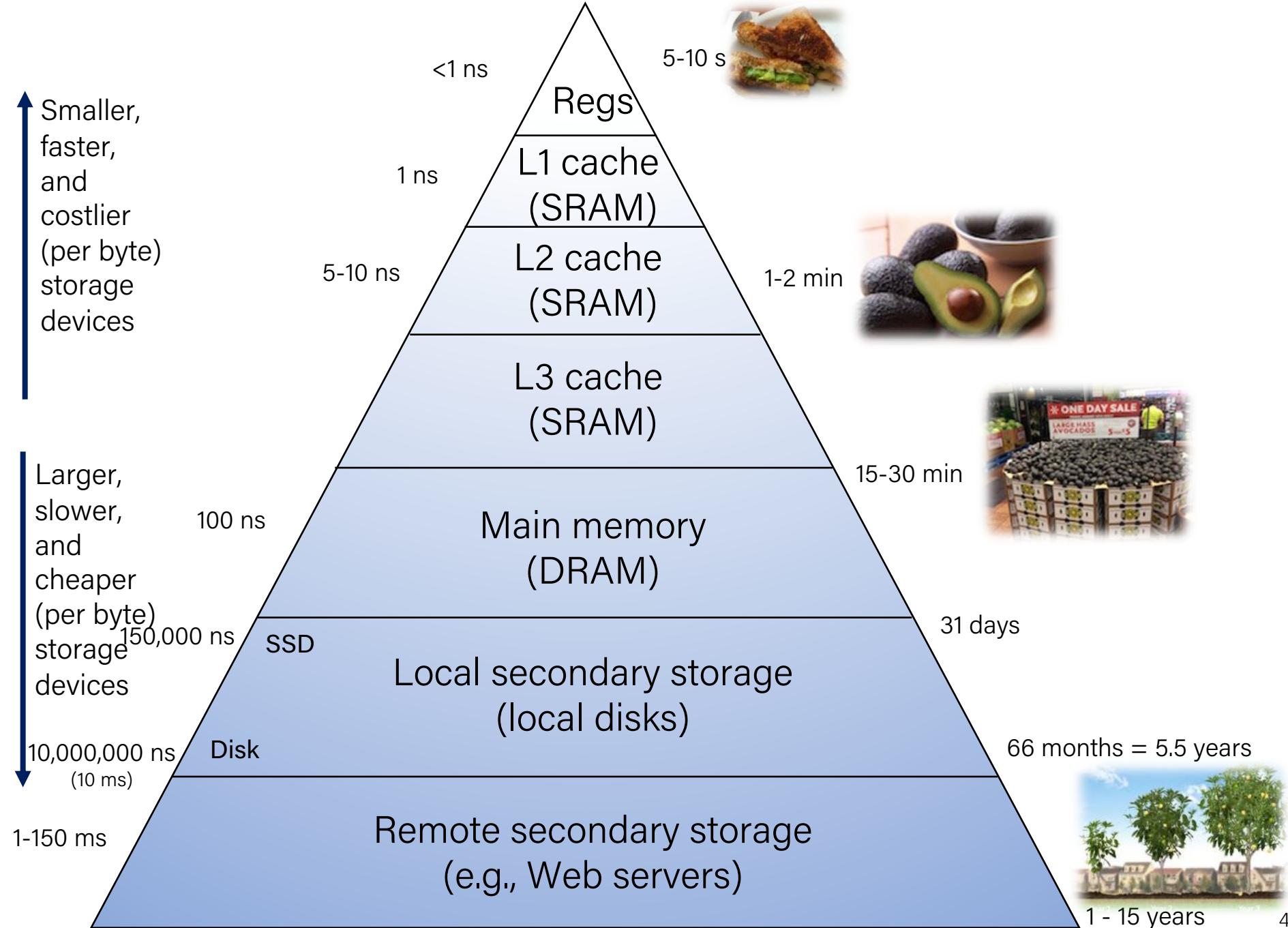
Example Memory Hierarchy



Example Memory Hierarchy



Example Memory Hierarchy



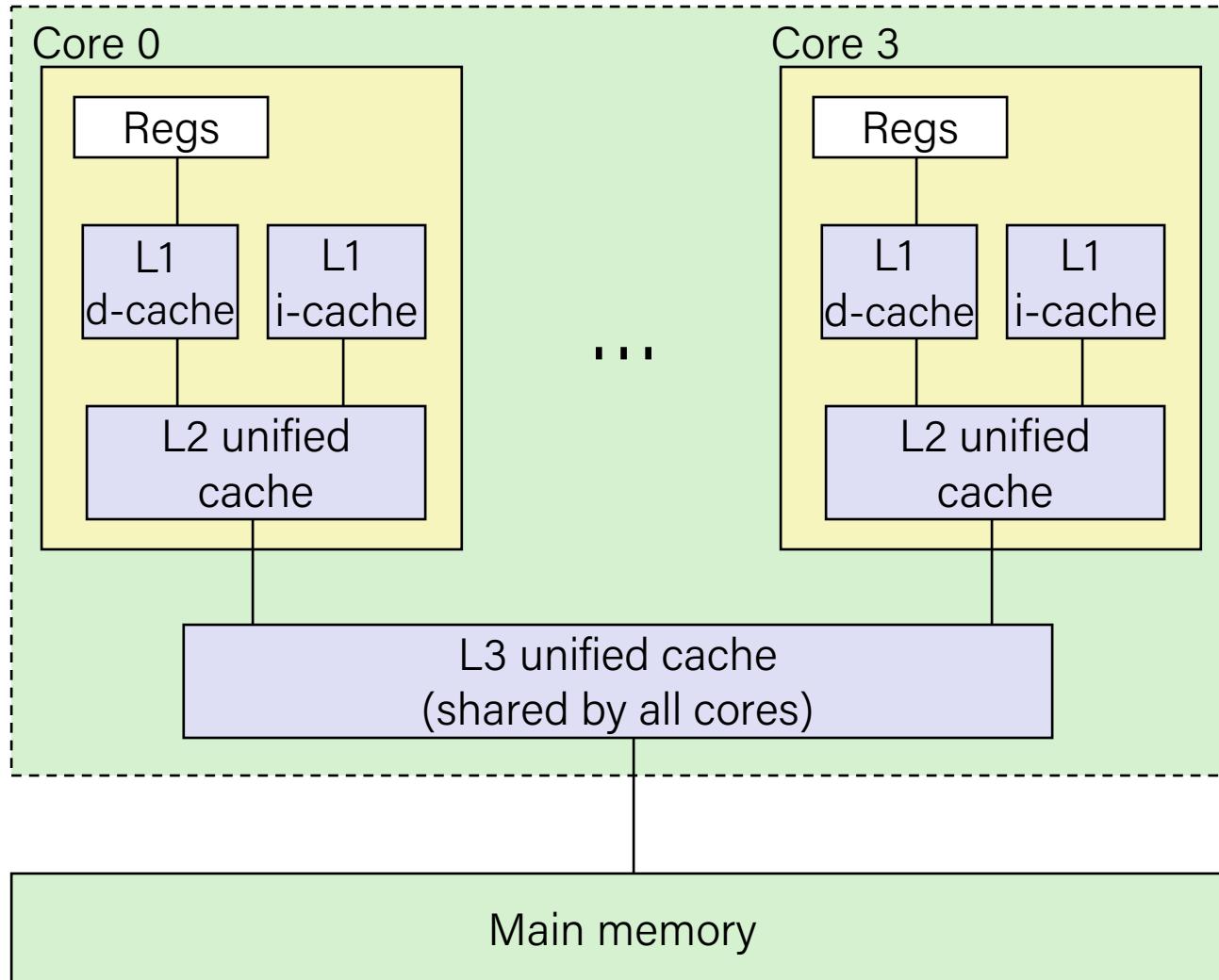
Caches

- **Cache:** A smaller, faster storage device that acts as a staging area for a subset of the data in a larger, slower device.
- Fundamental idea of a memory hierarchy:
 - For each k , the faster, smaller device at level k serves as a cache for the larger, slower device at level $k+1$.
- Why do memory hierarchies work?
 - Because of locality, programs tend to access the data at level k more often than they access the data at level $k+1$.
 - Thus, the storage at level $k+1$ can be slower, and thus larger and cheaper per bit.

Big Idea: The memory hierarchy creates a large pool of storage that costs as much as the cheap storage near the bottom, but that serves data to programs at the rate of the fast storage near the top.

Intel Core i7 Cache Hierarchy

Processor package



L1 i-cache and d-cache:

32 KB, 8-way,
Access: 4 cycles

L2 unified cache:

256 KB, 8-way,
Access: 10 cycles

L3 unified cache:

8 MB, 16-way,
Access: 40-75 cycles

Block size: 64 bytes for all caches.

Examples of Caching in the Mem. Hierarchy

Cache Type	What is Cached?	Where is it Cached?	Latency (cycles)	Managed By
Registers	4-8 bytes words	CPU core	0	Compiler
TLB	Address translations	On-Chip TLB	0	Hardware MMU
L1 cache	64-byte blocks	On-Chip L1	4	Hardware
L2 cache	64-byte blocks	On-Chip L2	10	Hardware
Virtual Memory	4-KB pages	Main memory	100	Hardware + OS
Buffer cache	Parts of files	Main memory	100	OS
Disk cache	Disk sectors	Disk controller	100,000	Disk firmware
Network buffer cache	Parts of files	Local disk	10,000,000	NFS client
Browser cache	Web pages	Local disk	10,000,000	Web browser
Web cache	Web pages	Remote server disks	1,000,000,000	Web proxy server

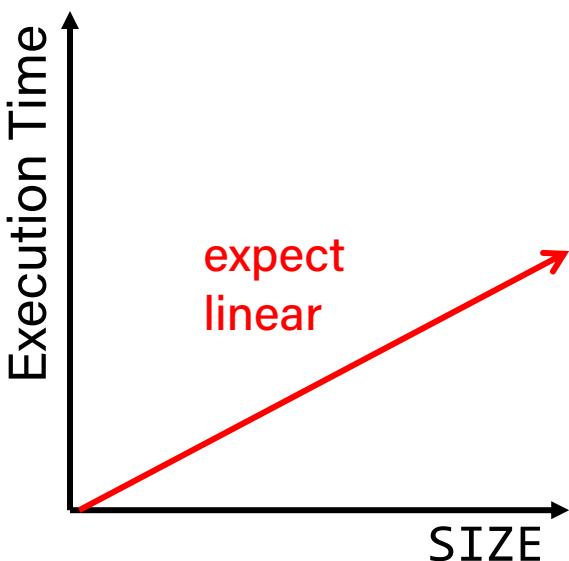
How does execution time grow with SIZE?

```
int array[SIZE];
int sum = 0;

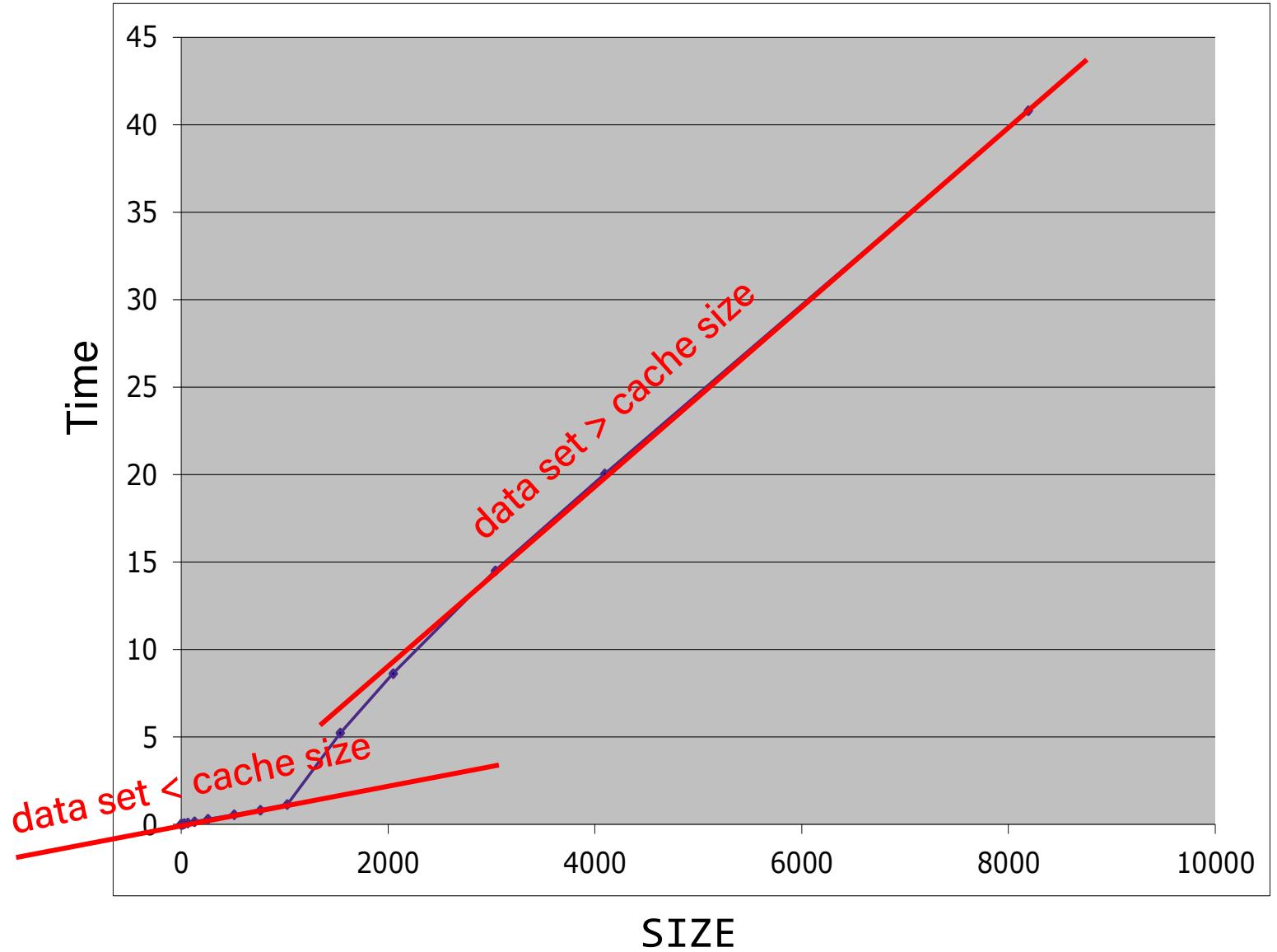
for (int i = 0; i < 200000; i++) {
    for (int j = 0; j < SIZE; j++) {
        sum += array[j]; ← execute SIZE×200,000 times
    }
}
```

repeat
200,000
times

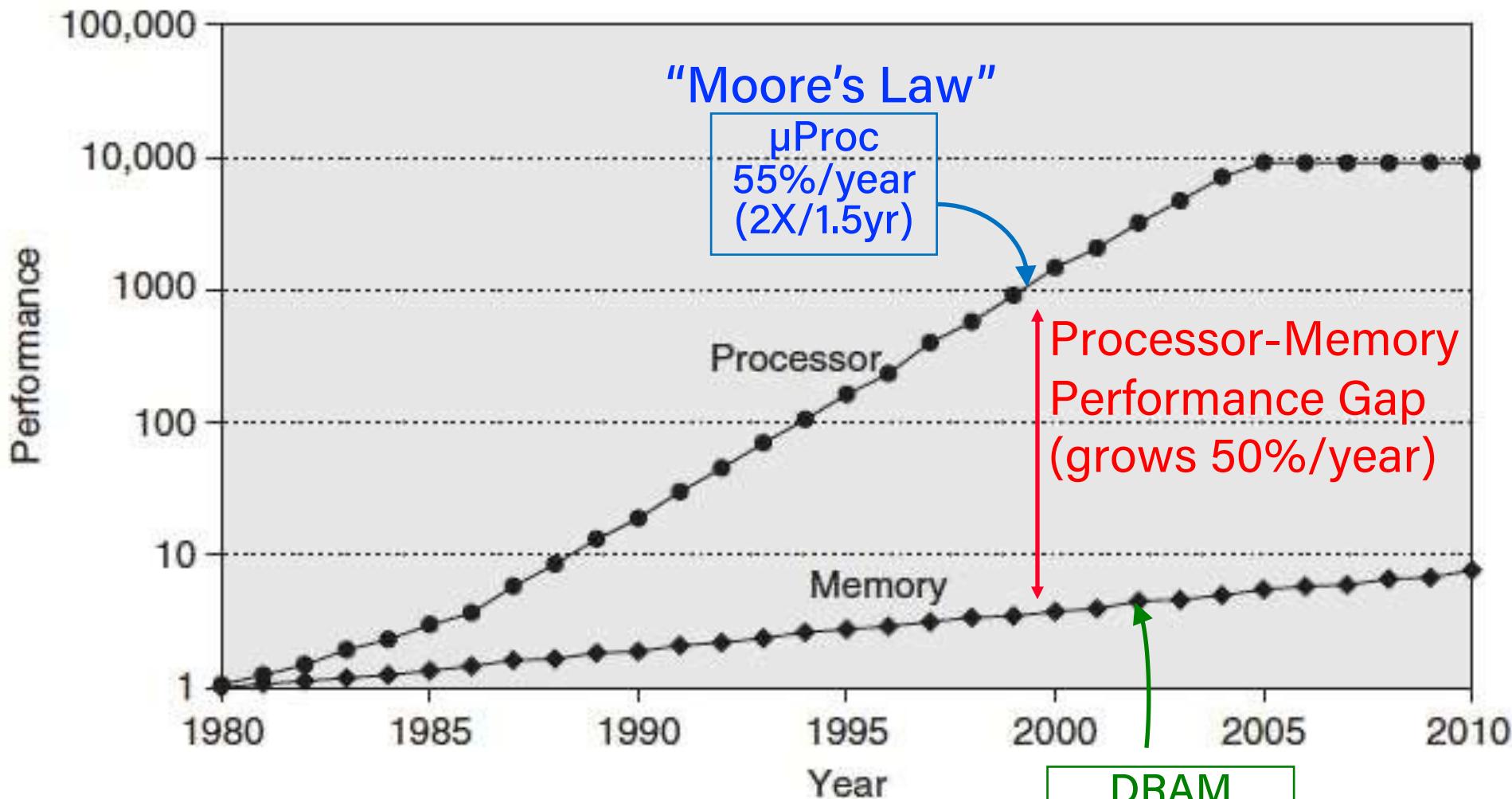
Plot:



Actual Data



Processor-Memory Gap

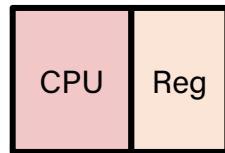


1989 first Intel CPU with cache on chip

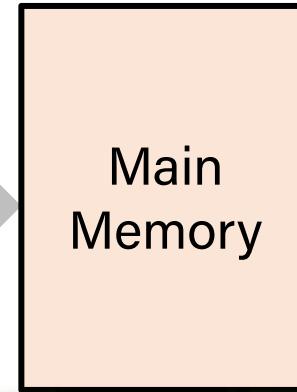
1998 Pentium III has two cache levels on chip

Problem: Processor-Memory Bottleneck

Processor performance doubled about every 18 months



Bus latency / bandwidth evolved much slower



Core 2 Duo:

Can process at least
256 Bytes/cycle



cycle: single machine step (fixed-time)

Core 2 Duo:

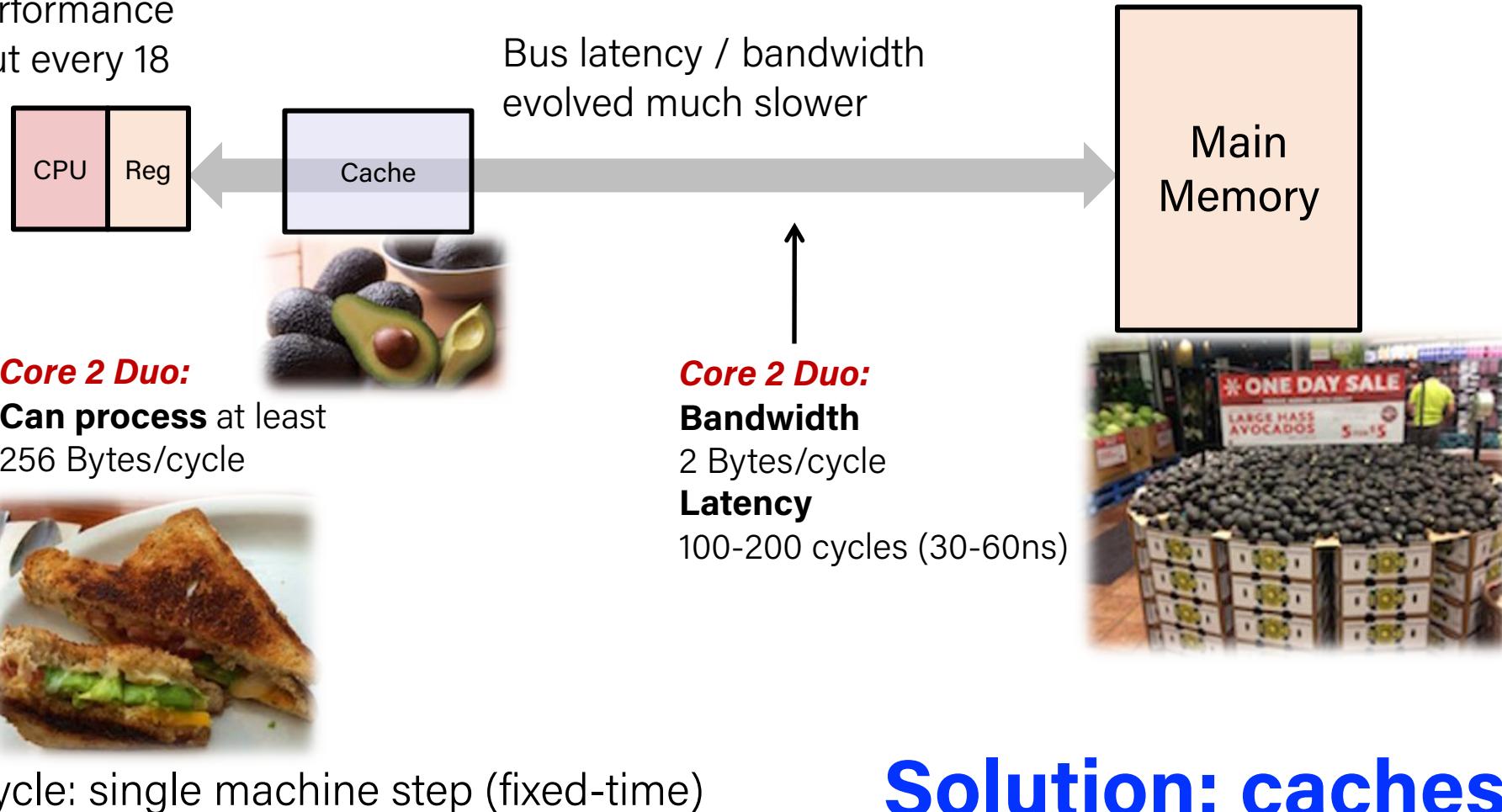
Bandwidth
2 Bytes/cycle
Latency
100-200 cycles (30-60ns)



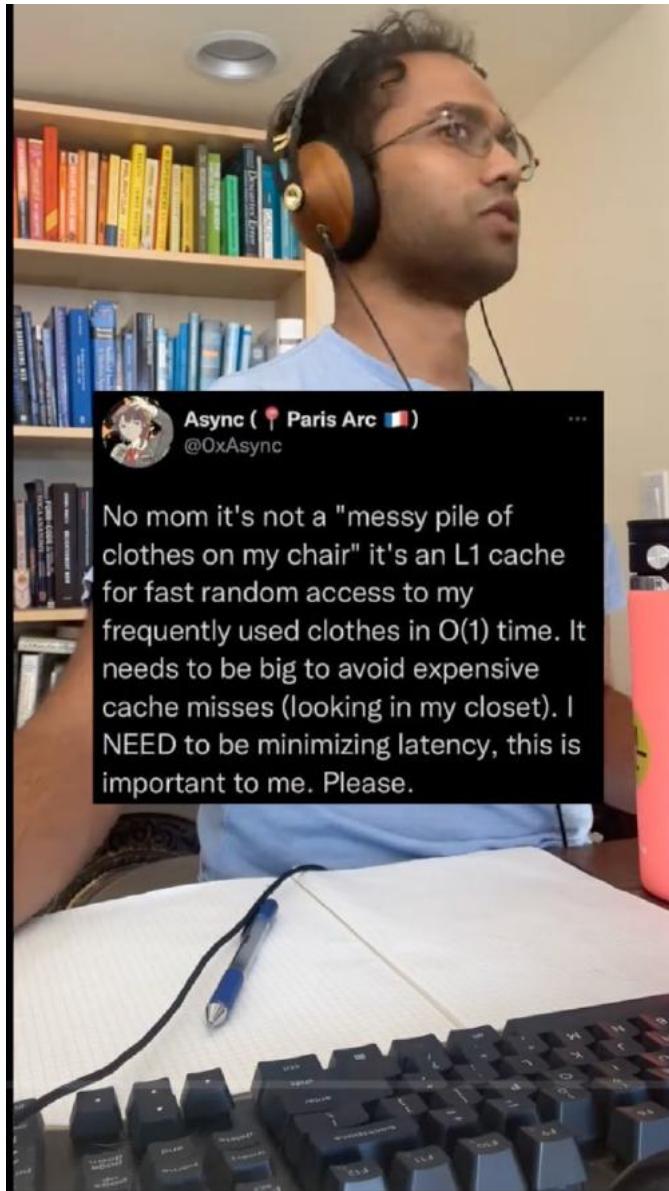
Problem: lots of waiting on memory

Problem: Processor-Memory Bottleneck

Processor performance doubled about every 18 months



Suggested by Sinemis Toktaş



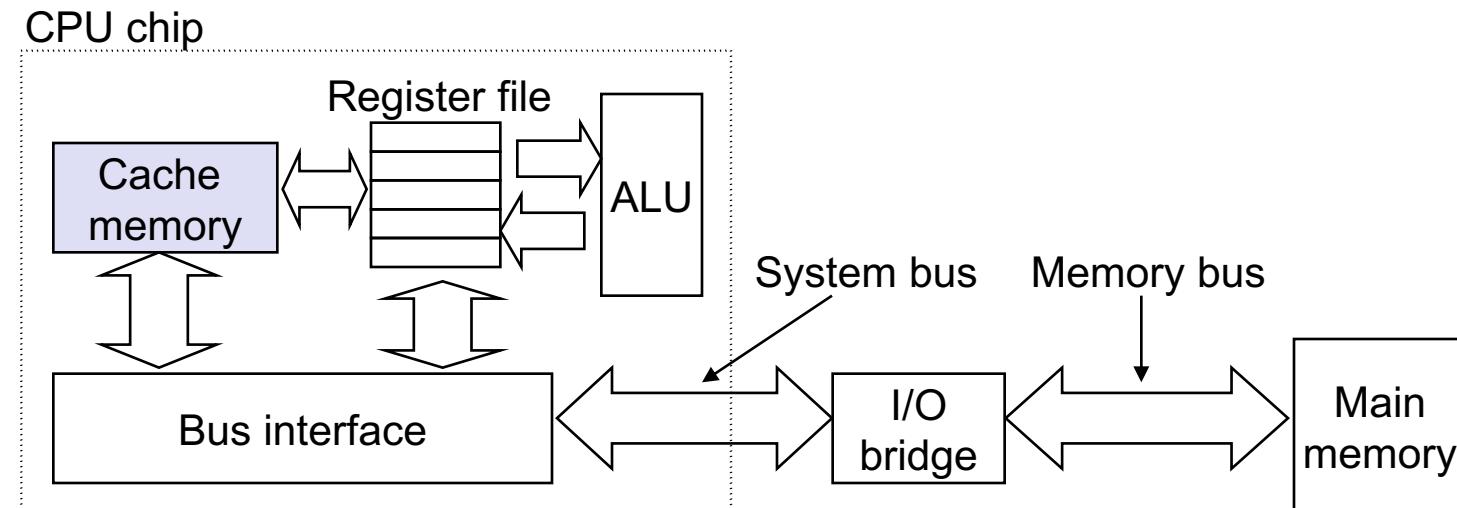
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Lecture Plan

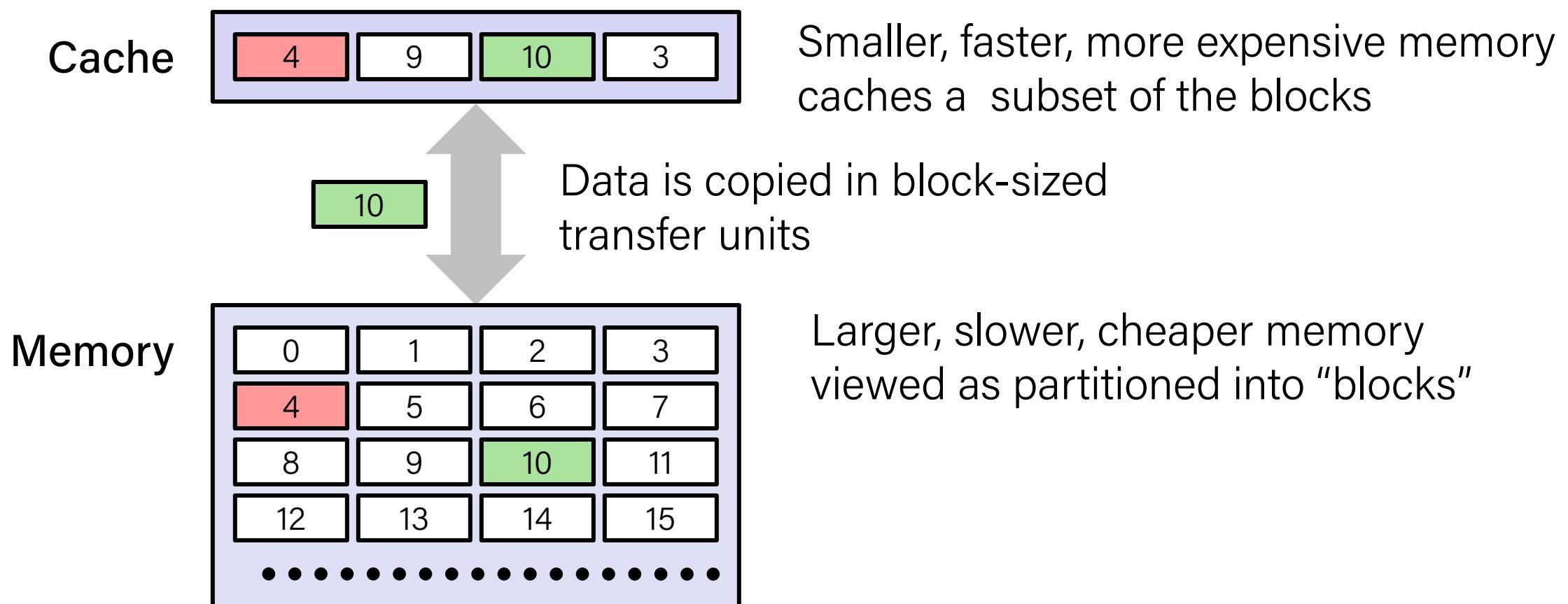
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Cache Memories

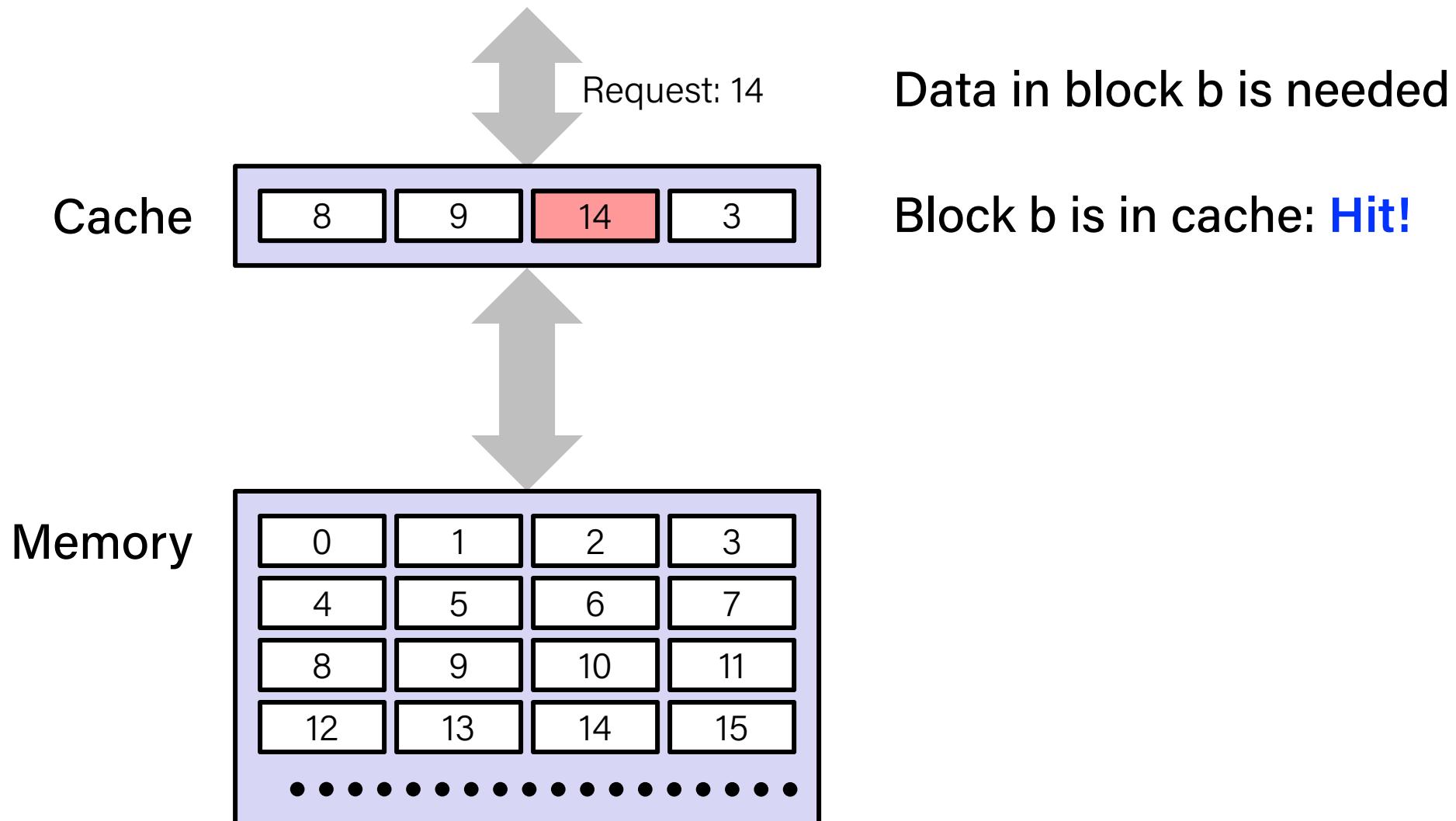
- Cache memories are small, fast SRAM-based memories managed automatically in hardware
 - Hold frequently accessed blocks of main memory
- CPU looks first for data in cache
- Typical system structure:



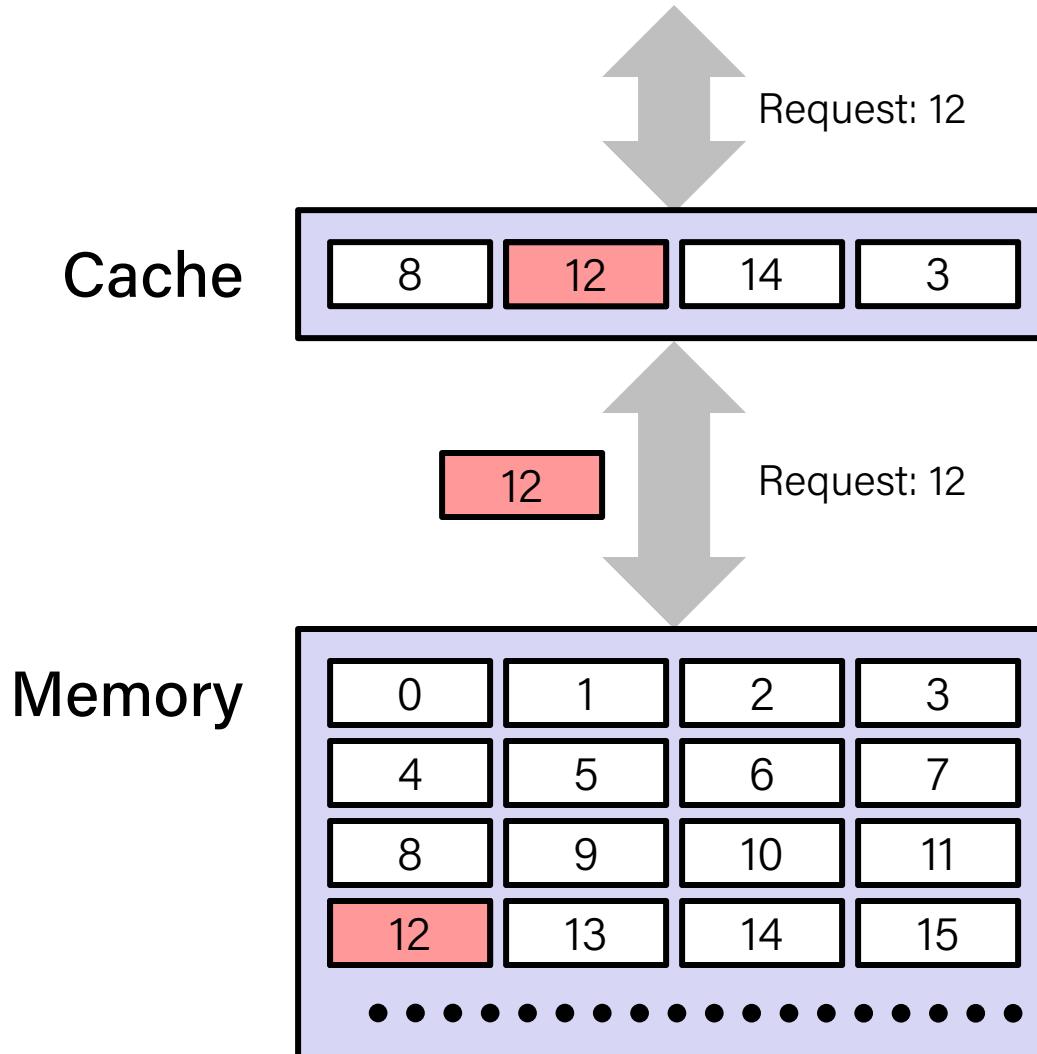
General Cache Concepts



General Cache Concepts: Hit



General Cache Concepts: Miss



Data in block b is needed

Block b is not in cache: **Miss!**

Block b is fetched from memory

Block b is stored in cache

- **Placement policy:** determines where b goes
- **Replacement policy:** determines which block gets evicted (victim)

Types of Cache Misses

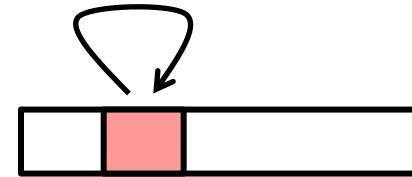
- **Cold (compulsory) miss**
 - Cold misses occur because the cache is empty.
- **Conflict miss**
 - Most caches limit blocks at level $k+1$ to a small subset (sometimes a singleton) of the block positions at level k .
 - E.g. Block i at level $k+1$ must be placed in block $(i \bmod 4)$ at level k .
 - Conflict misses occur when the level k cache is large enough, but multiple data objects all map to the same level k block.
 - E.g. Referencing blocks 0, 8, 0, 8, 0, 8, ... would miss every time.
- **Capacity miss**
 - Occurs when the set of active cache blocks (working set) is larger than the cache.

Why Caches Work

- **Principle of Locality:** Programs tend to use data and instructions with addresses near or equal to those they have used recently

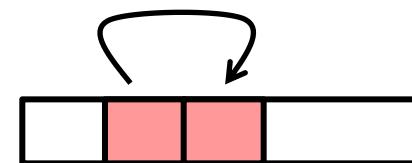
- **Temporal locality:**

- Recently referenced items are likely to be referenced again in the near future



- **Spatial locality:**

- Items with nearby addresses tend to be referenced close together in time



Qualitative Estimates of Locality

- **Claim:** Being able to look at code and get a qualitative sense of its locality is a key skill for a professional programmer.
- **Question:** Does this function have good locality with respect to array a?

```
int sum_array_rows(int a[M][N])
{
    int i, j, sum = 0;

    for (i = 0; i < M; i++)
        for (j = 0; j < N; j++)
            sum += a[i][j];
    return sum;
}
```

Locality Example 1

- Does this function have good locality with respect to array a?

```
int sum_array_rows(int a[M][N])
{
    int i, j, sum = 0;

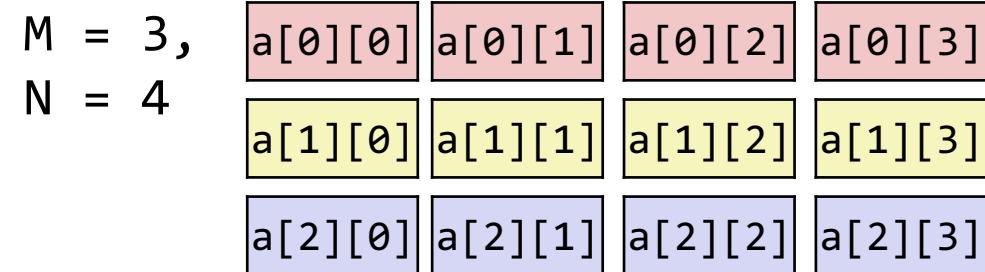
    for (i = 0; i < M; i++)
        for (j = 0; j < N; j++)
            sum += a[i][j];
    return sum;
}
```

Locality Example 1

- Does this function have good locality with respect to array a?

```
int sum_array_rows(int a[M][N])
{
    int i, j, sum = 0;

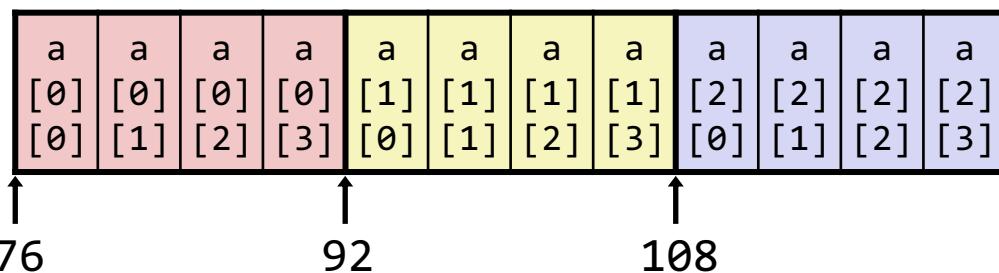
    for (i = 0; i < M; i++)
        for (j = 0; j < N; j++)
            sum += a[i][j];
    return sum;
}
```



Access Pattern:
stride = 1

1)	a[0][0]
2)	a[0][1]
3)	a[0][2]
4)	a[0][3]
5)	a[1][0]
6)	a[1][1]
7)	a[1][2]
8)	a[1][3]
9)	a[2][0]
10)	a[2][1]
11)	a[2][2]
12)	a[2][3]

Layout in Memory



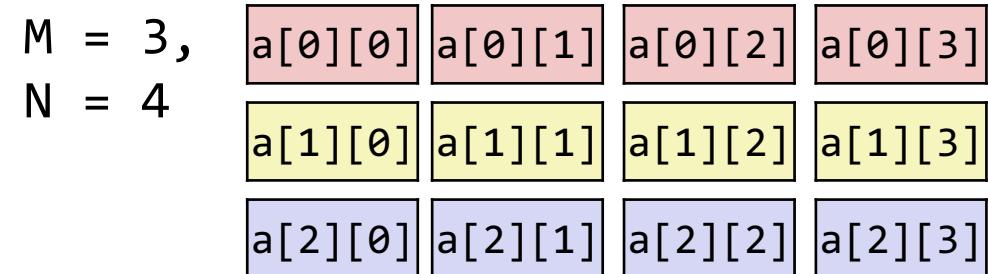
Note: 76 is just one possible starting address of array a

Locality Example 2

- Does this function have good locality with respect to array a?

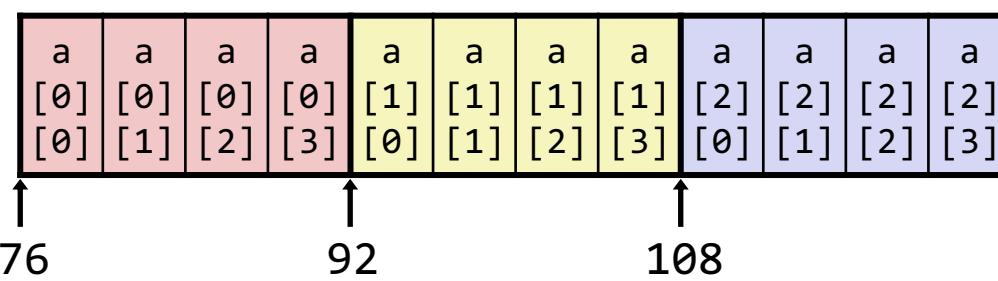
```
int sum_array_cols(int a[M][N])
{
    int i, j, sum = 0;

    for (j = 0; j < N; j++)
        for (i = 0; i < M; i++)
            sum += a[i][j];
    return sum;
}
```



Layout in Memory

Note: 76 is just one
possible starting
address of array a

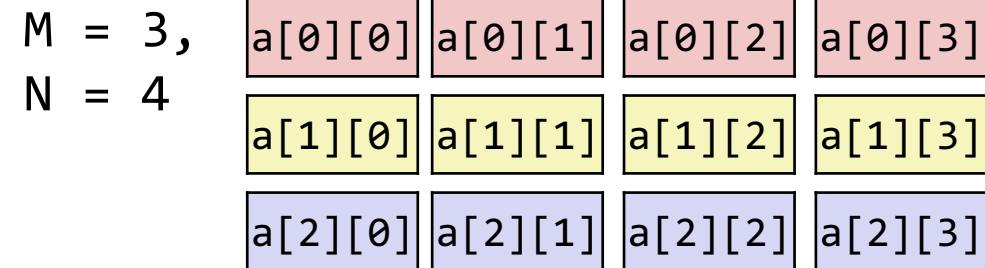


Locality Example 2

- Does this function have good locality with respect to array a?

```
int sum_array_cols(int a[M][N])
{
    int i, j, sum = 0;

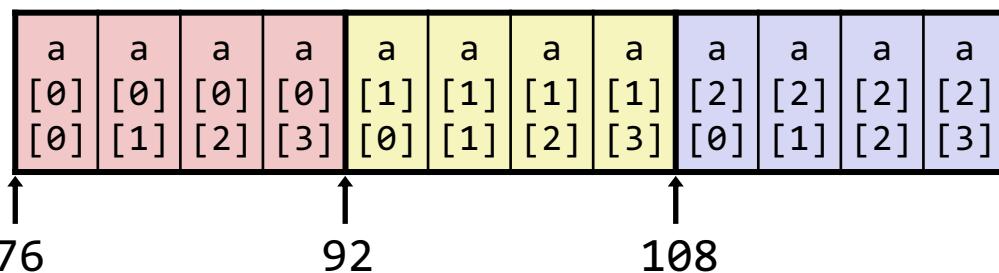
    for (j = 0; j < N; j++)
        for (i = 0; i < M; i++)
            sum += a[i][j];
    return sum;
}
```



Access Pattern:
stride = 4

- 1) a[0][0]
- 2) a[1][0]
- 3) a[2][0]
- 4) a[0][1]
- 5) a[1][1]
- 6) a[2][1]
- 7) a[0][2]
- 8) a[1][2]
- 9) a[2][2]
- 10) a[0][3]
- 11) a[1][3]
- 12) a[2][3]

Layout in Memory

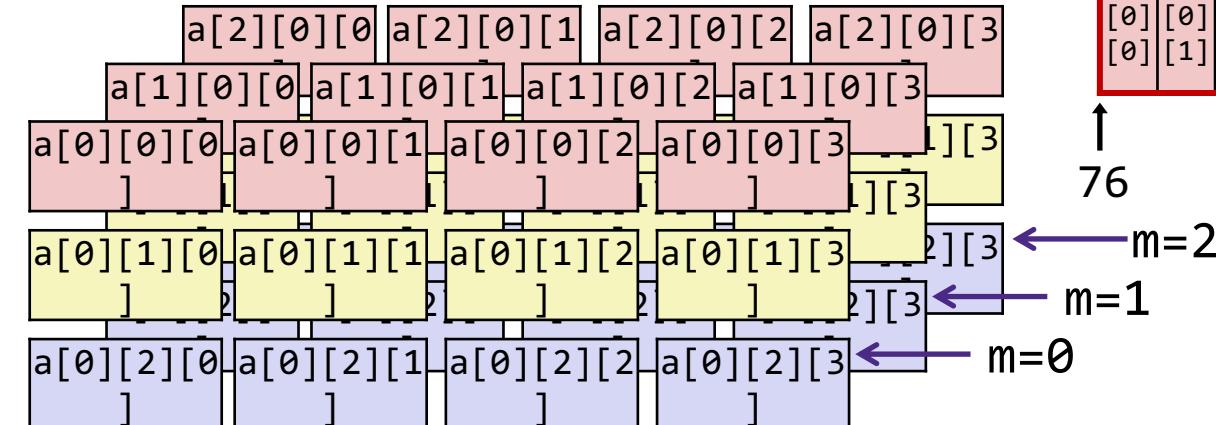


Locality Example 3

```
int sum_array_3d(int a[M][N][L])
{
    int i, j, k, sum = 0;

    for (i = 0; i < N; i++)
        for (j = 0; j < L; j++)
            for (k = 0; k < M; k++)
                sum += a[k][i][j];

    return sum;
}
```



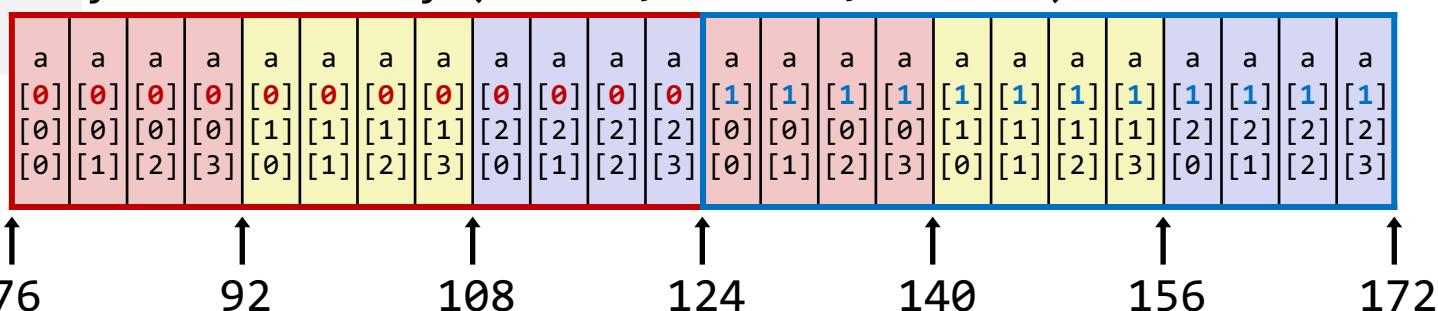
- What is wrong with this code?

Access Pattern: stride- $N \times L$

- How can it be fixed?

Inner loop: $i \rightarrow$ stride-1
 $j \rightarrow$ stride-1
 $k \rightarrow$ stride- $N \times L$

Layout in Memory ($M = 2, N = 3, L = 4$)



Cache Performance Metrics

- Huge difference between a cache hit and a cache miss
 - Could be 100x speed difference between accessing cache and main memory (measured in *clock cycles*)
- **Miss Rate (MR)**
 - Fraction of memory references not found in cache (misses / accesses)
= 1 - Hit Rate
- **Hit Time (HT)**
 - Time to deliver a block in the cache to the processor
 - Includes time to determine whether the block is in the cache
- **Miss Penalty (MP)**
 - Additional time required because of a miss

Can we have more than one cache?

- Why would we want to do that?
 - Avoid going to memory!
- Typical performance numbers:
 - Miss Rate
 - L1 MR = 3-10%
 - L2 MR = Quite small (*e.g.* < 1%), depending on parameters, etc.
 - Hit Time
 - L1 HT = 4 clock cycles
 - L2 HT = 10 clock cycles
 - Miss Penalty
 - P = 50-200 cycles for missing in L2 & going to main memory
 - Trend: increasing!

**(1) Optimize L1 for high HT
(2) Optimize L2 for low MR**

Lecture Plan

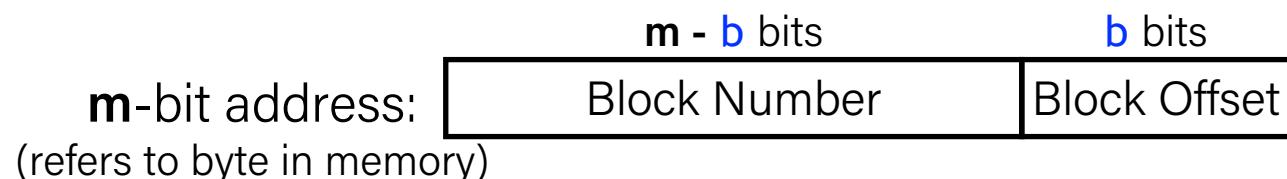
- The memory abstraction
- Storage technologies and trends
- Locality of reference
- The memory hierarchy
- Cache basics
- Cache organization

Cache Organization

- **Block Size (B):** unit of transfer between cache and main memory
 - Given in bytes and always a power of 2 (*e.g.* 64 bytes)
 - Blocks consist of adjacent bytes (differ in address by 1)
 - Spatial locality!

Cache Organization

- **Block Size (B):** unit of transfer between cache and main memory
 - Given in bytes and always a power of 2 (*e.g.* 64 bytes)
 - Blocks consist of adjacent bytes (differ in address by 1)
 - Spatial locality!
- Offset field
 - Low-order $\log_2(B) = b$ bits of address tell you which byte within a block
 - $(\text{address}) \bmod 2^n = n$ lowest bits of address
 - $(\text{address}) \bmod (\# \text{ of bytes in a block})$



Question

- If we have 6-bit addresses and block size $B = 4$ bytes, which block and byte does $0x15$ refer to?

Block Num	Block Offset
-----------	--------------

- | | | |
|----|---------------|---|
| A. | 1 | 1 |
| B. | 1 | 5 |
| C. | 5 | 1 |
| D. | 5 | 5 |
| E. | We're lost... | |

Please download and install the Slido app on all computers you use



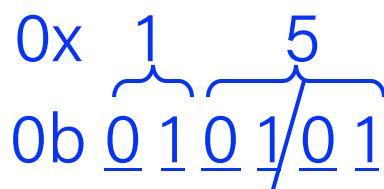
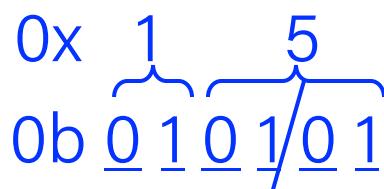
If we have 6-bit addresses and block size $B = 4$ bytes, which block and byte does $0x15$ refer to?

- ① Start presenting to display the poll results on this slide.

Question

- If we have 6-bit addresses and block size $B = 4$ bytes, which block and byte does $0x15$ refer to?

	Block Num	Block Offset
A.	1	1
B.	1	5
C.	5	1
D.	5	5
E.	We're lost...	

Address: 0b  0 1 0 1 / 0 1
0x 

Offset width = $\log_2(B) = \log_2(4) = 2$ bits

Cache Organization

- **Cache Size (C):** amount of *data* the cache can store
 - Cache can only hold so much data (subset of next level)
 - Given in bytes (C) or number of blocks (C/B)
 - Example: C = 32 KiB = 512 blocks if using 64-byte blocks
- Where should data go in the cache?
 - We need a mapping from memory addresses to specific locations in the cache to make checking the cache for an address **fast**
- What is a data structure that provides fast lookup?
 - Hash table!

Review: Hash Tables for Fast Lookup

Insert:

5

27

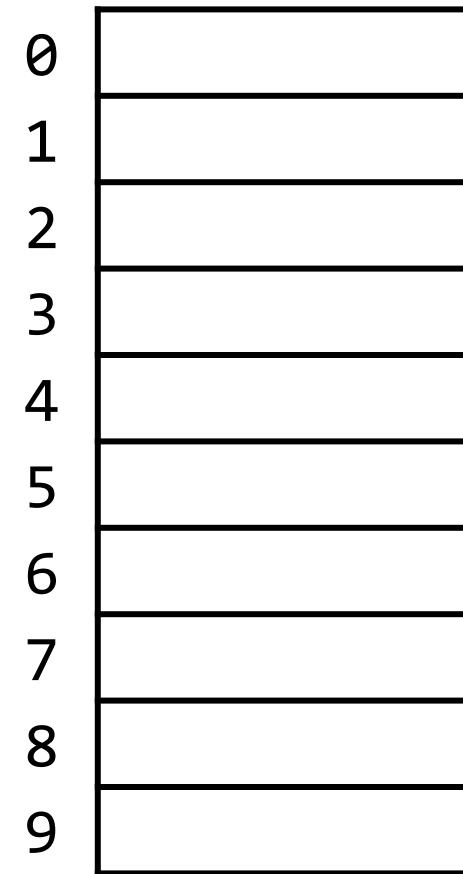
34

102

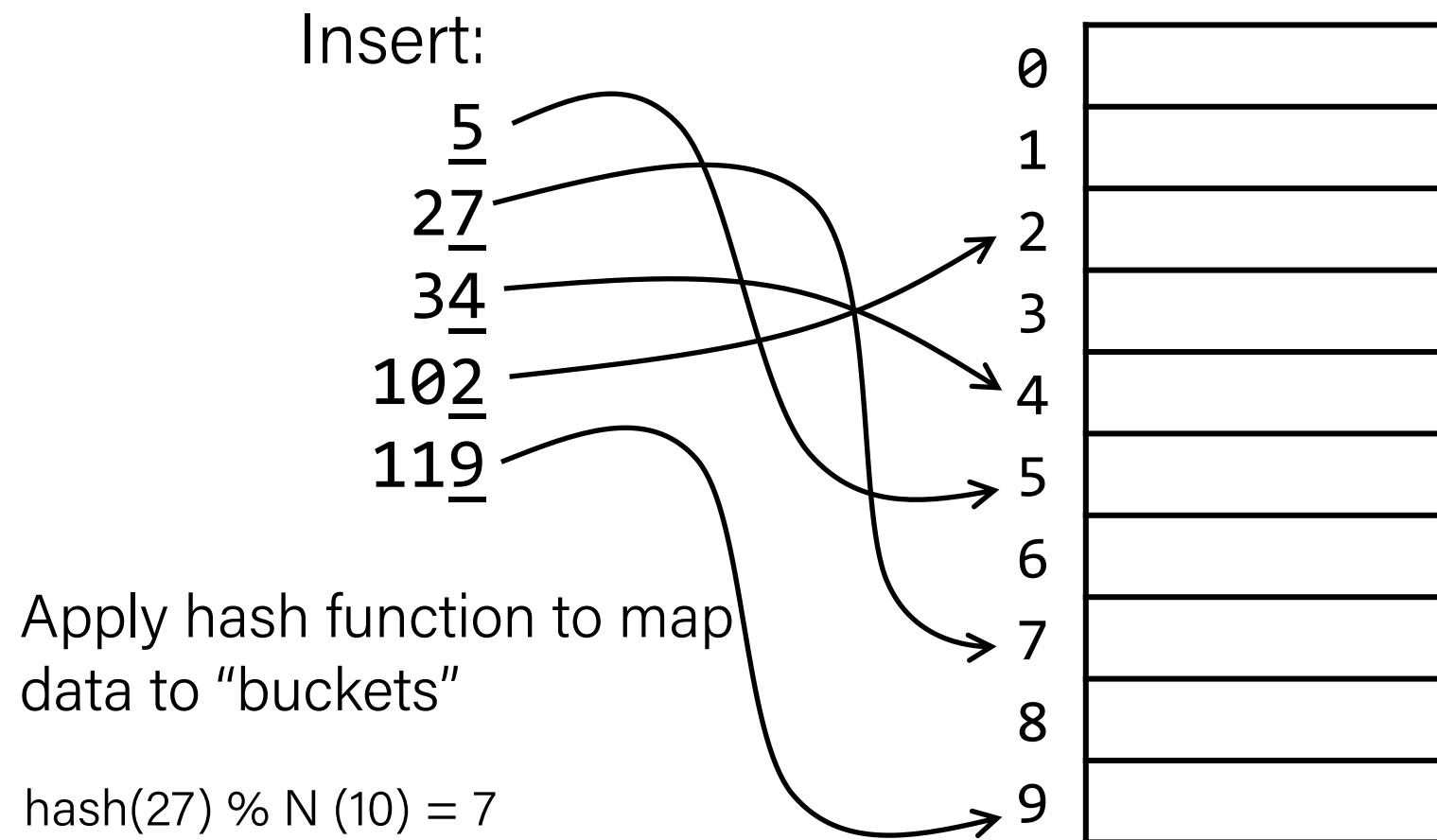
119

Apply hash function to map
data to “buckets”

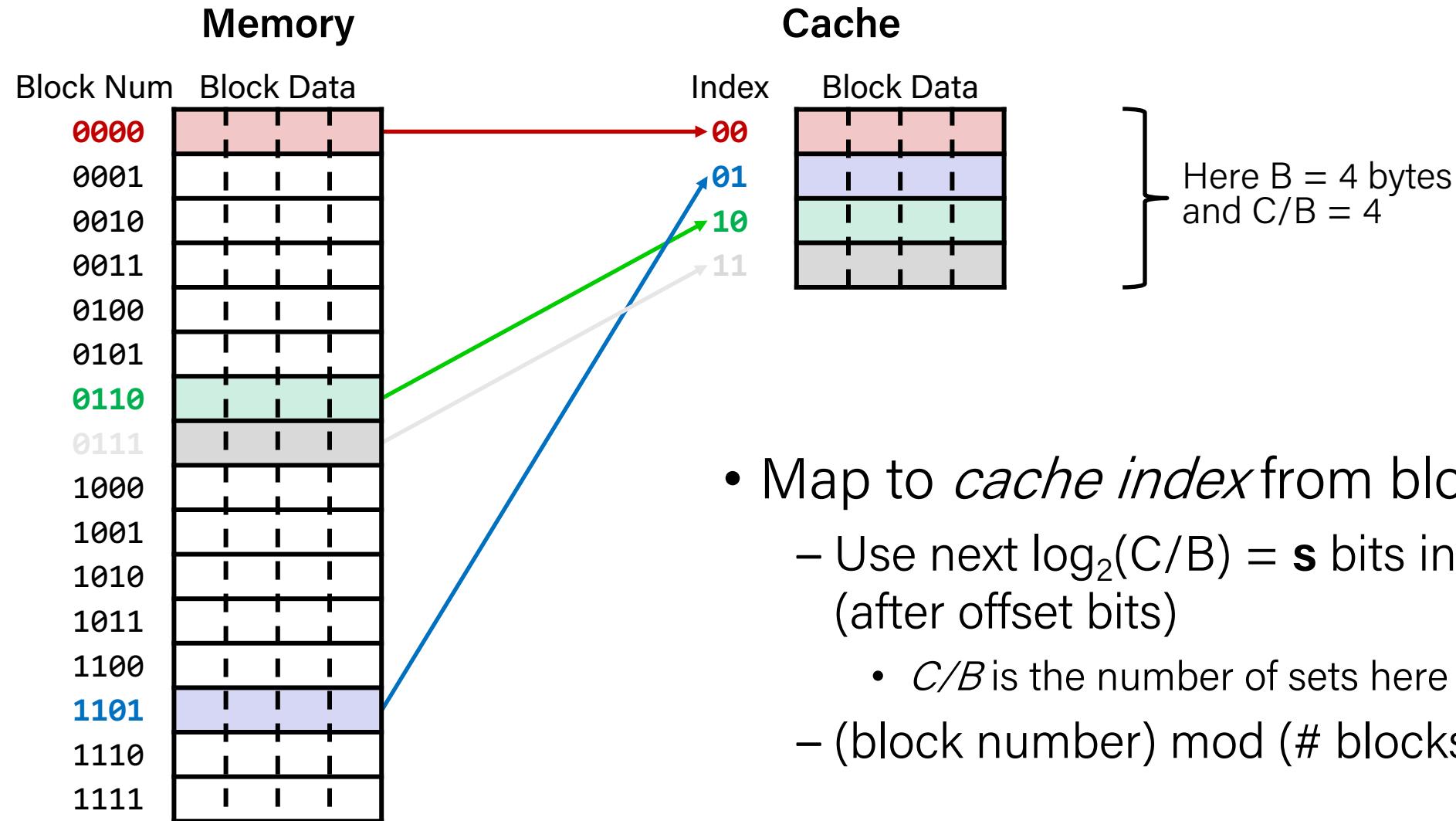
$\text{hash}(27) \% N (10) = 7$



Review: Hash Tables for Fast Lookup

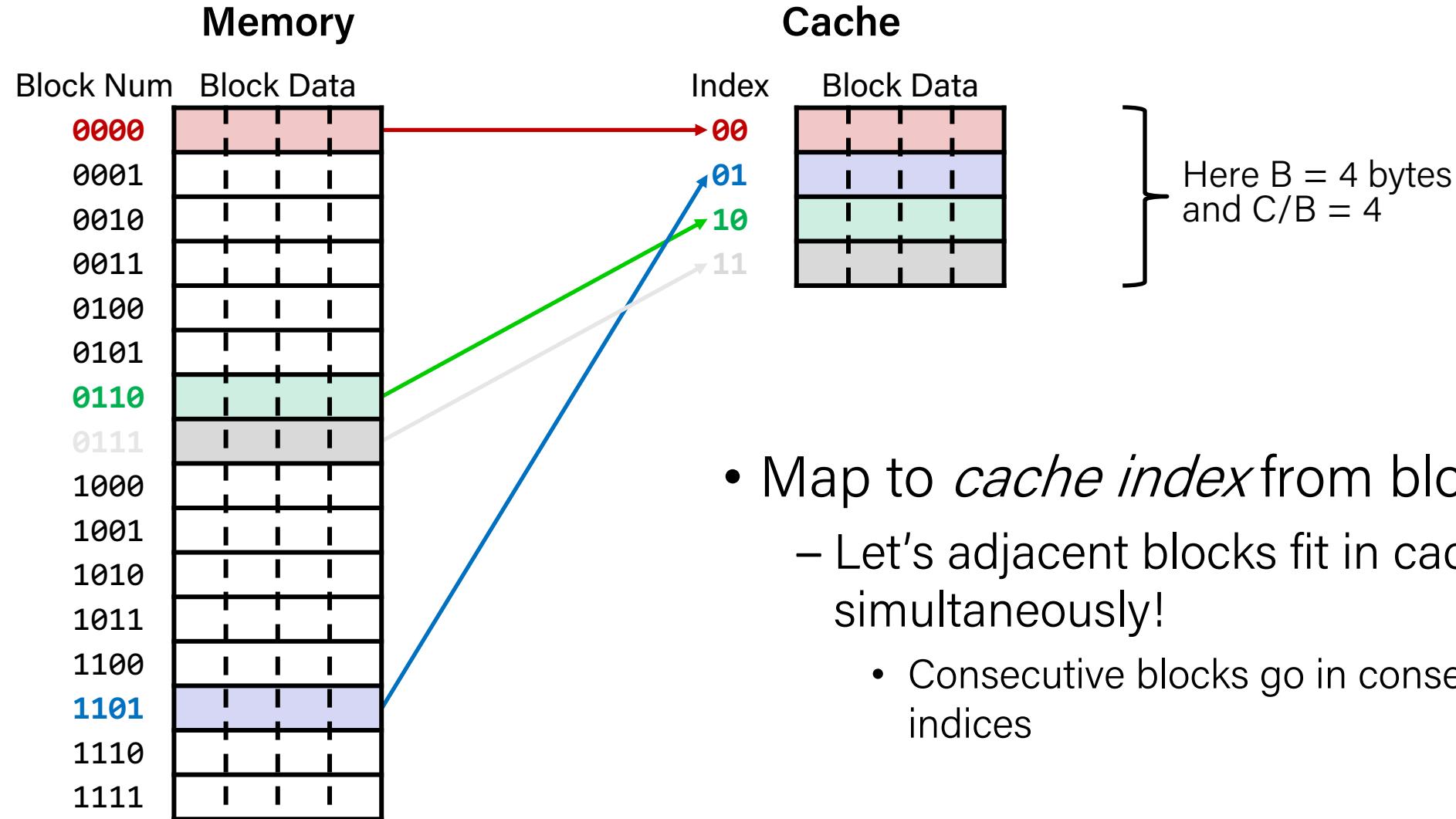


Place Data in Cache by Hashing Address



- Map to *cache index* from block number
 - Use next $\log_2(C/B) = s$ bits in the address (after offset bits)
 - C/B is the number of sets here
 - $(\text{block number}) \bmod (\# \text{ blocks in cache})$

Place Data in Cache by Hashing Address



- Map to *cache index* from block number
 - Let's adjacent blocks fit in cache simultaneously!
 - Consecutive blocks go in consecutive cache indices

Practice Question

- 6-bit addresses, block size $B = 4$ bytes, and our cache holds $S = 4$ blocks.
- A request for address **0x2A** results in a cache miss. Which set index does this block get loaded into and which 3 other addresses are loaded along with it?

Practice Question

- 6-bit addresses, block size $B = 4$ bytes, and our cache holds $S = 4$ blocks.

$$C = S \times B = 16 \text{ bytes}$$

$$b = \log_2(4) = 2 \text{ bits}$$

$$s = \log_2(4) = 2 \text{ bits}$$

- A request for address **0x2A** results in a cache miss. Which set index does this block get loaded into and which 3 other addresses are loaded along with it?

Address: 0b 10 | 10 | 10 | 10
 index offset
 block number

addresses w/block number 1010

$$0b\underline{10}1000 = 0x28$$

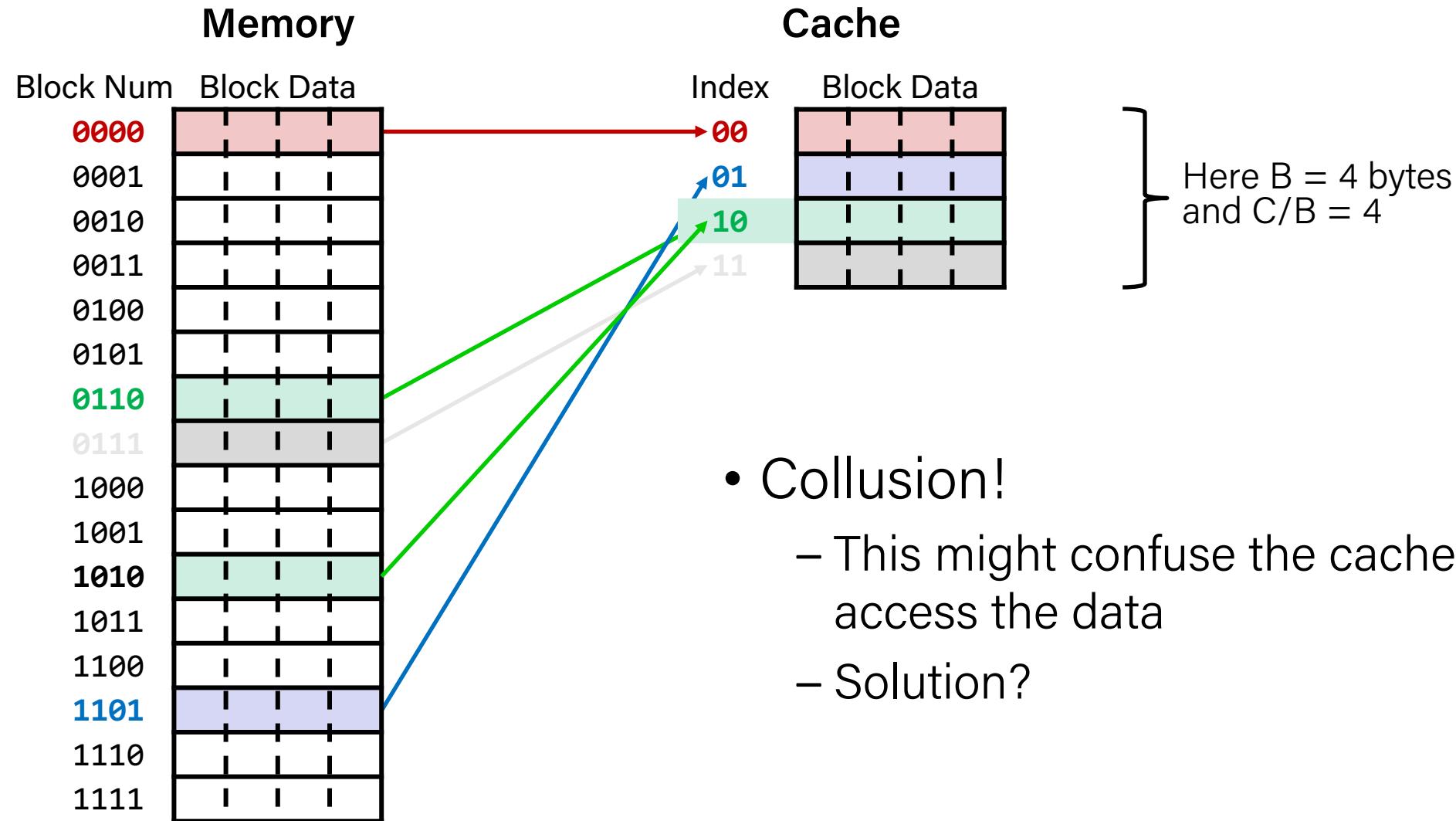
$$0b\underline{10}1001 = 0x29$$

$$0b\underline{10}1010 = 0x2A$$

$$0b\underline{10}1011 = 0x2B$$

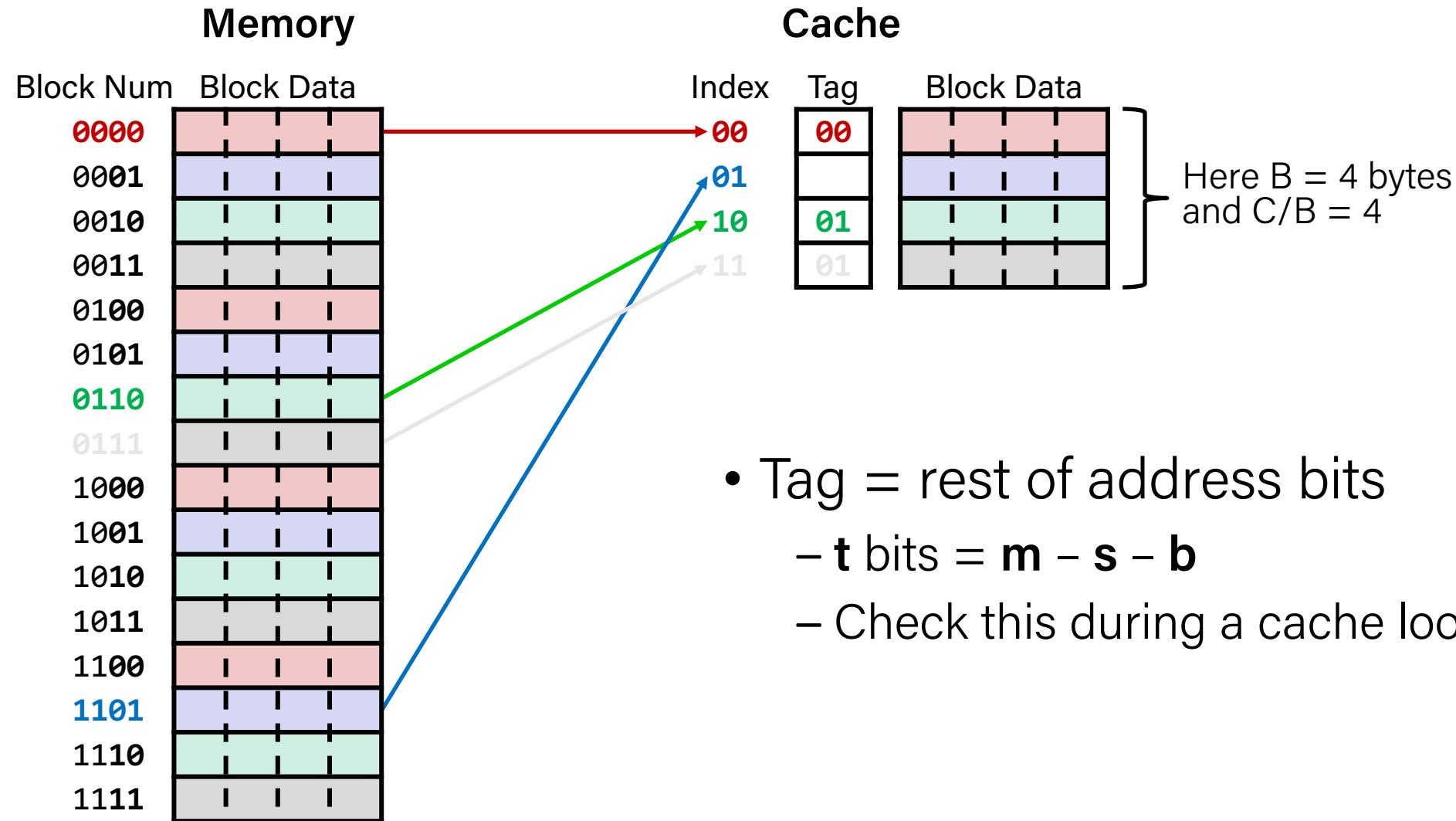
These are loaded into cache!

Place Data in Cache by Hashing Address



- Collusion!
 - This might confuse the cache later when we access the data
 - Solution?

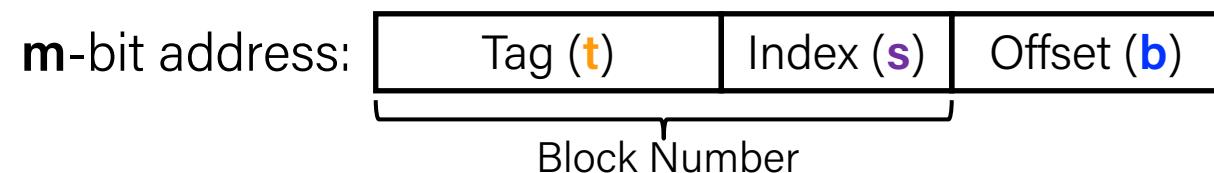
Tags Differentiate Blocks in Same Index



Checking for a Requested Address

- CPU sends address request for chunk of data
 - Address and requested data are not the same thing!
 - Analogy: your friend \neq their phone number

- TIO address breakdown:

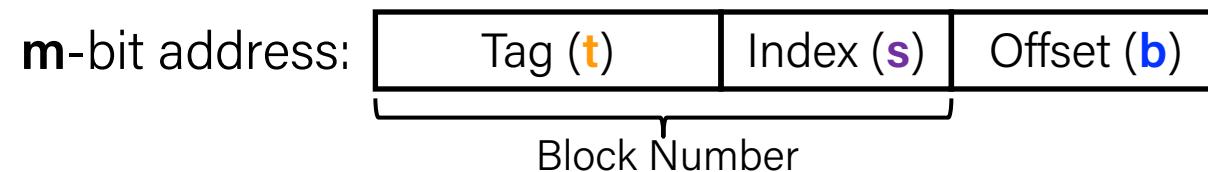


- **Index** field tells you where to look in cache
- **Tag** field lets you check that data is the block you want
- **Offset** field selects specified start byte within block

- Note: **t** and **s** sizes will change based on hash function

Checking for a Requested Address Example

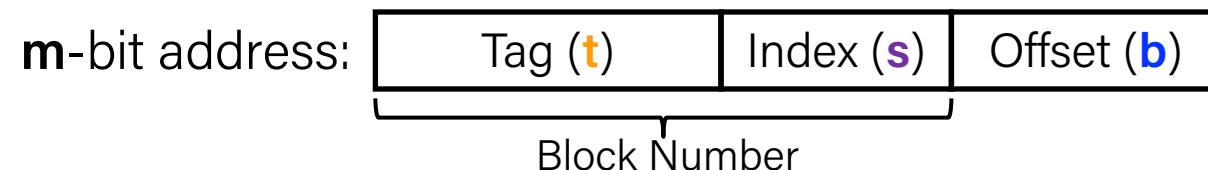
- Using 8-bit addresses.
- Cache Params: block size (B) = 4 bytes, cache size (C) = 32 bytes (which means number of sets is $C/B = 8$ sets).
 - Offset bits (b) = $\log_2(B) = 2$ bits
 - Index bits (s) = $\log_2(\text{number of sets}) = 3$ bits
 - Tag bits (t) = Rest of the bits in the address = $8 - 2 - 3 = 3$ bits



- What are the fields for address 0xBA?
 - Tag bits (unique id for block):
 - Index bits (cache set block maps to):
 - Offset bits (byte offset within block):

Checking for a Requested Address Example

- Using 8-bit addresses.
- Cache Params: block size (B) = 4 bytes, cache size (C) = 32 bytes (which means number of sets is $C/B = 8$ sets).
 - Offset bits (b) = $\log_2(B) = 2$ bits
 - Index bits (s) = $\log_2(\text{number of sets}) = 3$ bits
 - Tag bits (t) = Rest of the bits in the address = $8 - 2 - 3 = 3$ bits



- What are the fields for address 0xBA?
 - Tag bits (unique id for block): 0x5 101 110 10
 - Index bits (cache set block maps to): 0x6 5 6 2
 - Offset bits (byte offset within block): 0x2

Recap

- The memory abstraction
- Storage technologies and trends
- Locality of reference
- The memory hierarchy
- Cache basics
- Cache organization

Next: *More on cache memories*