COMP201

Computer

Systems &

Programming

Lecture #23 - Linking



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Recap

- Debugging
 - Defects and Failures
 - Scientific Debugging
 - Tools
- Design
 - Managing complexity
 - Communication
 - Naming
 - Comments
- Optimization
 - What is optimization?
 - GCC Optimization
 - Limitations of GCC Optimization
 - Caching revisited

Plan for Today

- Linking
- Case study: Library interpositioning

Disclaimer: Slides for this lecture were borrowed from

—Randal E. Bryant and David R. O'Hallaroni's CMU 15-213 class

Lecture Plan

- Linking
- Case study: Library interpositioning

Example C Program

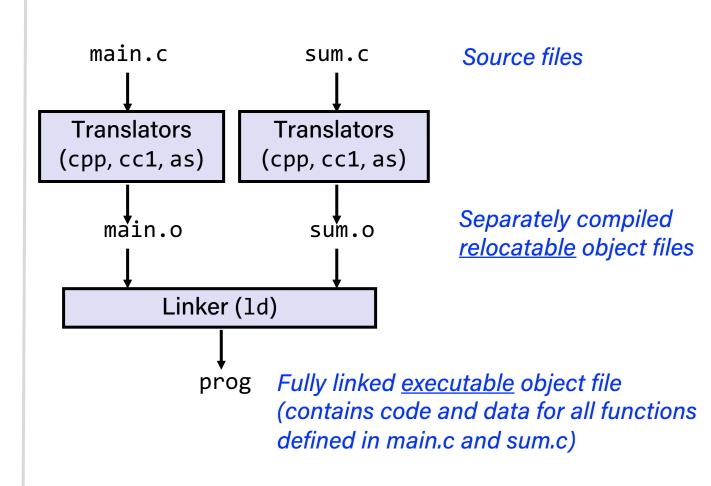
```
int sum(int *a, int n);
int array[2] = \{1, 2\};
int main()
    int val = sum(array, 2);
    return val;
                         main.c
```

```
int sum(int *a, int n)
    int i, s = 0;
    for (i = 0; i < n; i++) {
        s += a[i];
    return s;
                           sum.c
```

Static Linking

Programs are translated and linked using a *compiler driver*:

linux> gcc -Og -o prog main.c sum.c
linux> ./prog



Why Linkers?

Reason 1: Modularity

 Program can be written as a collection of smaller source files, rather than one monolithic mass.

- Can build libraries of common functions (more on this later)
 - e.g., Math library, standard C library

Why Linkers? (cont)

Reason 2: Efficiency

- Time: Separate compilation
 - Change one source file, compile, and then relink.
 - No need to recompile other source files.
- Space: Libraries
 - Common functions can be aggregated into a single file...
 - Yet executable files and running memory images contain only code for the functions they actually use.

What Do Linkers Do?

Step 1: Symbol resolution

• Programs define and reference symbols (global variables and functions):

```
-void swap() {...} /* define symbol swap */
-swap(); /* reference symbol swap */
-int *xp = &x; /* define symbol xp, reference x */
```

- Symbol definitions are stored in object file (by assembler) in symbol table.
 - Symbol table is an array of structs
 - Each entry includes name, size, and location of symbol.
- During symbol resolution step, the linker associates each symbol reference with exactly one symbol definition.

What Do Linkers Do? (cont)

Step 2: Relocation

Merges separate code and data sections into single sections

• Relocates symbols from their relative locations in the .o files to their final absolute memory locations in the executable.

Updates all references to these symbols to reflect their new positions.

Let's look at these two steps in more detail....

Three Kinds of Object Files (Modules)

Relocatable object file (.o file)

- Contains code and data in a form that can be combined with other relocatable object files to form executable object file.
 - Each .o file is produced from exactly one source (.c) file

Executable object file (a.out file)

 Contains code and data in a form that can be copied directly into memory and then executed.

Shared object file (.so file)

- Special type of relocatable object file that can be loaded into memory and linked dynamically, at either load time or run-time.
- Called *Dynamic Link Libraries* (DLLs) by Windows

Executable and Linkable Format (ELF)

Standard binary format for object files

- One unified format for
 - Relocatable object files (.o),
 - Executable object files (a.out)
 - Shared object files (.so)
- Generic name: ELF binaries

ELF Object File Format

Elf header

Word size, byte ordering, file type (.o, exec, .so), machine type, etc.

Segment header table

Page size, virtual addresses memory segments (sections), segment sizes.

.text section

- Code

rodata section

- Read only data: jump tables, ...

.data section

Initialized global variables

.bss section

- Uninitialized global variables
- "Block Started by Symbol"
- Better Save Space"
- Has section header but occupies no space

El E boodox	(
ELF header	
Segment header table (required for executables)	
.text section	
.rodata section	
.data section	
.bss section	
.symtab section	
.rel.txt section	
.rel.data section	
.debug section	
Section header table	

ELF Object File Format (cont.)

.symtab section

- Symbol table
- Procedure and static variable names
- Section names and locations

.rel.text section

- Relocation info for .text section
- Addresses of instructions that will need to be modified in the executable
- Instructions for modifying.

• .rel.data section

- Relocation info for .data section
- Addresses of pointer data that will need to be modified in the merged executable

.debug section

Info for symbolic debugging (gcc -g)

Section header table

Offsets and sizes of each section

ELF header
Segment header table (required for executables)
.text section
. rodata section
.data section
.bss section
.symtab section
.rel.txt section
.rel.data section
.debug section
Section header table

Linker Symbols

Global symbols

- Symbols defined by module *m* that can be referenced by other modules.
- E.g.: non-static C functions and non-static global variables.

External symbols

 Global symbols that are referenced by module m but defined by some other module.

Local symbols

- Symbols that are defined and referenced exclusively by module m.
- E.g.: C functions and global variables defined with the **static** attribute.
- Local linker symbols are not local program variables

Step 1: Symbol Resolution

```
Referencing
 ...that's defined here
                         a global...
 int sum(int *a, int n);
 int array[2] = \{1, 2\};
 int main()
      int val = sum(array, 2);
      return val;
                             main.c
                   Referencing
Defining
                   a global...
a global
        nothing of val
```

```
int sum(int *a, int n)
         int i, s = 0;
         for (i = 0; i < n; i++) {
         return s;
               Linker knows
                                  sum.c
               nothing of i or s
...that's defined here
```

Local Symbols

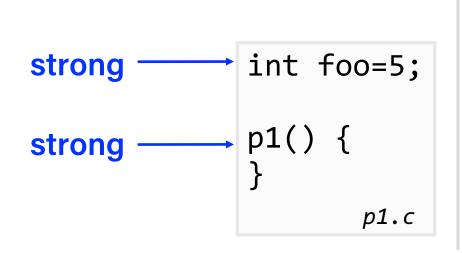
- Local non-static C variables vs. local static C variables
 - -local non-static C variables: stored on the stack
 - -local static C variables: stored in either .bss, or .data

```
int f()
    static int x = 0;
    return x;
int g()
    static int x = 1;
    return x;
```

- Compiler allocates space in .data for each definition of x
- Creates local symbols in the symbol table with unique names, e.g., x.1 and x.2.

How Linker Resolves Duplicate Symbol Definitions

- Program symbols are either strong or weak
 - Strong: procedures and initialized globals
 - Weak: uninitialized globals



Linker's Symbol Rules

- Rule 1: Multiple strong symbols are not allowed
 - Each item can be defined only once
 - Otherwise: Linker error

- Rule 2: Given a strong symbol and multiple weak symbols, choose the strong symbol
 - References to the weak symbol resolve to the strong symbol

- Rule 3: If there are multiple weak symbols, pick an arbitrary one
 - Can override this with gcc -fno-common

Linker Puzzles 1

p2() {}

p1() {}

```
int x;
                             Link time error: two strong symbols (p1)
           p1() {}
p1() {}
                             References to x will refer to the same uninitialized int.
int x;
         int x;
p1() {} p2() {}
                             Is this what you really want?
           double x;
int x;
                             Writes to x in p2 might overwrite y!
           p2() {}
int y;
                             Evil!
p1() {}
           double x;
int x=7;
                             Writes to x in p2 will overwrite y!
int y=5;
           p2() {}
                             Nasty!
p1() {}
int x=7;
           int x;
                             References to x will refer to the same initialized variable.
```

Nightmare scenario: two identical weak structs, compiled by different compilers with different alignment rules.

Linker Puzzles 2



• Which definitions do the references main or x refer to?

```
int main()
{}
```

```
int main;
int p2() {}
```

```
void main()
{}
```

```
int main = 1;
p2() {}
```

Error! Each module defines a strong symbol main

```
int x;
void main()
{}
```

```
double x=1.0;
int p2()
{}
```

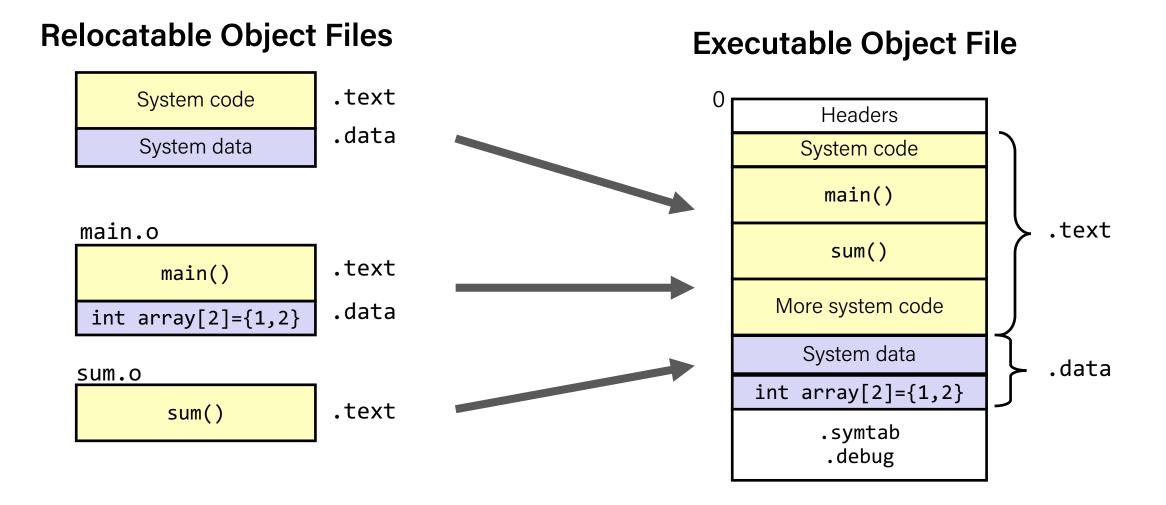
REF(x.1)
$$\rightarrow$$
 DEF(x.2)
REF(x.2) \rightarrow DEF(x.2)

Global Variables

Avoid if you can

- Otherwise
 - Use static if you can
 - Initialize if you define a global variable
 - Use extern if you reference an external global variable

Step 2: Relocation



Relocation Entries

```
int array[2] = {1, 2};
int main()
{
    int val = sum(array, 2);
    return val;
}
```

objdump -r -d main.o

```
0000000000000000 <main>:
                             sub $0x8,%rsp
       48 83 ec 08
  0:
  4: be 02 00 00 00
                             mov $0x2,%esi
                             mov $0x0,%edi
                                                   # %edi = &array
  9: bf 00 00 00 00
                                                    # Relocation entry
                      a: R_X86_64_32 array
  e:
      e8 00 00 00 00
                             callq 13 <main+0x13> # sum()
                      f: R_X86_64_PC32 sum-0x4 # Relocation entry
                             add $0x8,%rsp
 13: 48 83 c4 08
                                                               main.o
 17:
       c3
                             retq
```

Relocated .text section

objdump -dx prog

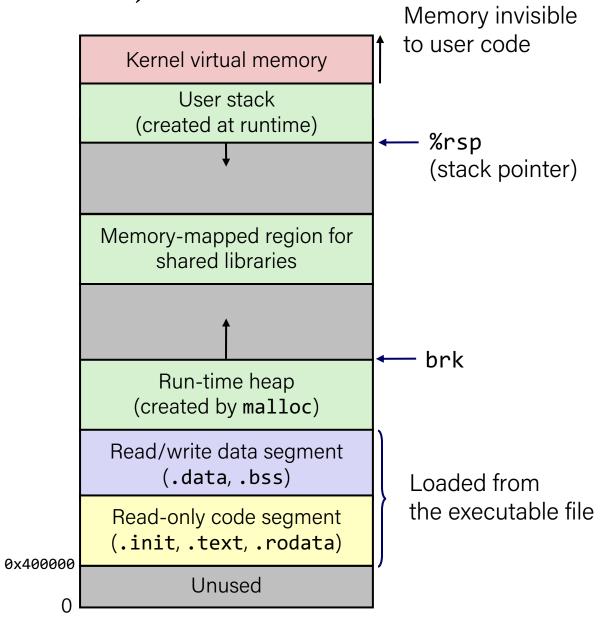
```
00000000004004d0 <main>:
  4004d0:
                48 83 ec 08
                                           $0x8,%rsp
                                   sub
  4004d4:
                be 02 00 00 00
                                           $0x2,%esi
                                   mov
                hf 18 10 60 00
  4004d9:
                                           $0x601018,%edi # %edi = &array
                                   mov
  4004de:
                e8 05 00 00 00
                                   callq
                                          4004e8 <sum>
                                                           # sum()
  4004e3:
                48 83 c4 08
                                   add
                                           $0x8,%rsp
  4004e7:
                c3
                                   retq
00000000004004e8 <sum>:
                                                 $0x0,%eax
  4004e8:
                b8 00 00 00 00
                                          mov
  4004ed:
                ba 00 00 00 00
                                                 $0x0,%edx
                                          mov
  4004f2:
                eb 09
                                          jmp
                                                 4004fd <sum+0x15>
  4004f4:
                48 63 ca
                                          movslq %edx,%rcx
  4004f7:
                03 04 8f
                                          add
                                                 (%rdi,%rcx,4),%eax
  4004fa:
                83 c2 01
                                          add
                                                 $0x1,%edx
  4004fd:
                39 f2
                                                 %esi,%edx
                                          \mathsf{cmp}
                                                 4004f4 <sum+0xc>
  4004ff:
                7c f3
                                          jl
                f3 c3
  400501:
                                          repz reta
```

Using PC-relative addressing for sum(): 0x4004e8 = 0x4004e3 + 0x5

Loading Executable Object Files

Executable Object File

ELF header
Program header table (required for executables)
.init section
.text section
.rodata section
.data section
.bss section
.symtab
.debug
.line
.strtab
Section header table (required for relocatables)



Packaging Commonly Used Functions

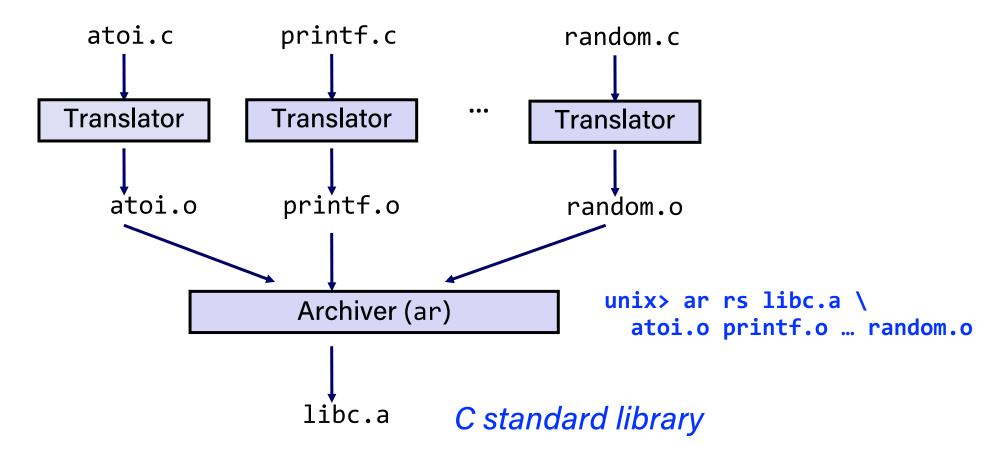
- How to package functions commonly used by programmers?
 - Math, I/O, memory management, string manipulation, etc.

- Awkward, given the linker framework so far:
 - Option 1: Put all functions into a single source file
 - Programmers link big object file into their programs
 - Space and time inefficient
 - Option 2: Put each function in a separate source file
 - Programmers explicitly link appropriate binaries into their programs
 - More efficient, but burdensome on the programmer

Old-fashioned Solution: Static Libraries

- Static libraries (.a archive files)
 - Concatenate related relocatable object files into a single file with an index (called an archive).
 - Enhance linker so that it tries to resolve unresolved external references by looking for the symbols in one or more archives.
 - If an archive member file resolves reference, link it into the executable.

Creating Static Libraries



- Archiver allows incremental updates
- Recompile function that changes and replace .o file in archive.

Commonly Used Libraries

libc.a (the C standard library)

- 4.6 MB archive of 1496 object files.
- I/O, memory allocation, signal handling, string handling, data and time, random numbers, integer math

libm.a (the C math library)

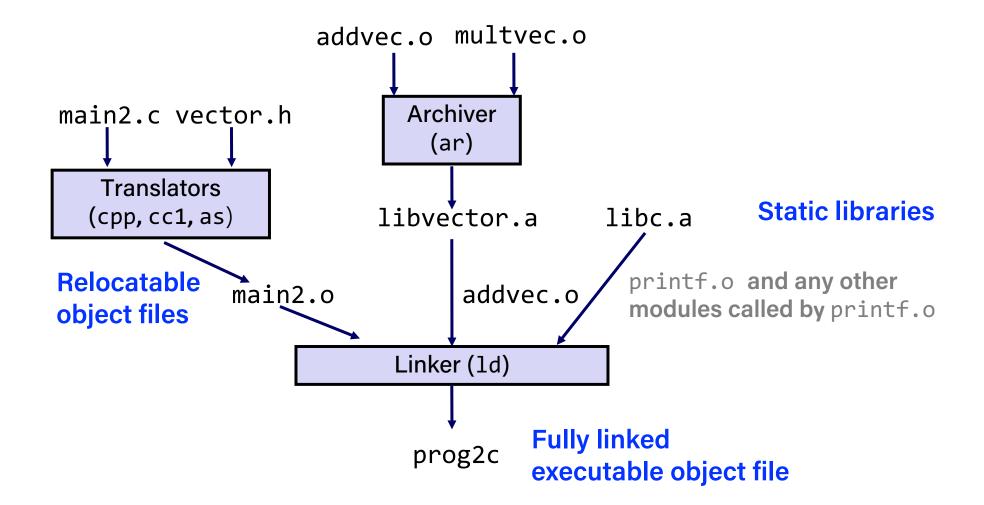
- 2 MB archive of 444 object files.
- floating point math (sin, cos, tan, log, exp, sqrt, ...)

```
% ar -t libc.a
                 sort
fork.o
fprintf.o
fpu control.o
fputc.o
freopen.o
fscanf.o
fseek.o
fstab.o
% ar -t libm.a
                 sort
e acos.o
e acosf.o
e acosh.o
e acoshf.o
e acoshl.o
e acosl.o
e asin.o
e asinf.o
e asinl.o
```

Linking with Static Libraries

```
#include <stdio.h>
#include "vector.h"
int x[2] = \{1, 2\};
int y[2] = \{3, 4\};
int z[2];
int main()
    addvec(x, y, z, 2);
    printf("z = [%d %d]\n", z[0], z[1]);
    return 0;
                                      main2.c
```

Linking with Static Libraries



Using Static Libraries

Linker's algorithm for resolving external references:

- Scan .o files and .a files in the command line order.
- During the scan, keep a list of the current unresolved references.
- As each new .o or .a file, obj, is encountered, try to resolve each unresolved reference in the list against the symbols defined in obj.
- If any entries in the unresolved list at end of scan, then error.

• Problem:

- Command line order matters!
- Moral: put libraries at the end of the command line.

```
unix> gcc -L. libtest.o -lmine
unix> gcc -L. -lmine libtest.o
libtest.o: In function `main':
libtest.o(.text+0x4): undefined reference to `libfun'
```

Modern Solution: Shared Libraries

Static libraries have the following disadvantages:

- Duplication in the stored executables (every function needs libc)
- Duplication in the running executables
- Minor bug fixes of system libraries require each application to explicitly relink

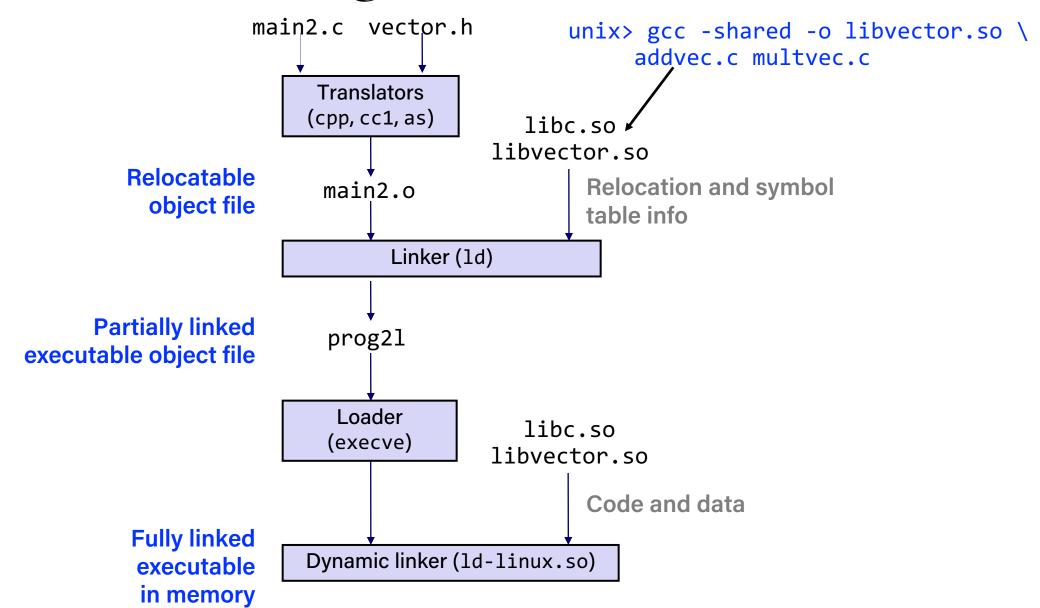
Modern solution: Shared Libraries

- Object files that contain code and data that are loaded and linked into an application dynamically, at either load-time or run-time
- Also called: dynamic link libraries, DLLs, .so files

Shared Libraries (cont.)

- Dynamic linking can occur when executable is first loaded and run (load-time linking).
 - Common case for Linux, handled automatically by the dynamic linker (ld-linux.so).
 - Standard C library (libc.so) usually dynamically linked.
- Dynamic linking can also occur after program has begun (run-time linking).
 - In Linux, this is done by calls to the dlopen() interface.
 - Distributing software.
 - High-performance web servers.
 - Runtime library interpositioning.
- Shared library routines can be shared by multiple processes.
 - More on this when you learn about virtual memory

Dynamic Linking at Load-time



Dynamic Linking at Run-time

```
#include <stdio.h>
#include <stdlib.h>
#include <dlfcn.h>
int x[2] = \{1, 2\};
int y[2] = \{3, 4\};
int z[2];
int main()
    void *handle;
    void (*addvec)(int *, int *, int *, int);
    char *error;
    /* Dynamically load the shared library that contains addvec() */
    handle = dlopen("./libvector.so", RTLD_LAZY);
    if (!handle) {
        fprintf(stderr, "%s\n", dlerror());
        exit(1);
                                                                                 dll.c
```

Dynamic Linking at Run-time

```
/* Get a pointer to the addvec() function we just loaded */
addvec = dlsym(handle, "addvec");
if ((error = dlerror()) != NULL) {
    fprintf(stderr, "%s\n", error);
    exit(1);
/* Now we can call addvec() just like any other function */
addvec(x, y, z, 2);
printf("z = [%d %d]\n", z[0], z[1]);
/* Unload the shared library */
if (dlclose(handle) < 0) {</pre>
    fprintf(stderr, "%s\n", dlerror());
    exit(1);
return 0;
                                                                             dll.c
```

Linking Summary

 Linking is a technique that allows programs to be constructed from multiple object files.

- Linking can happen at different times in a program's lifetime:
 - Compile time (when a program is compiled)
 - Load time (when a program is loaded into memory)
 - Run time (while a program is executing)
- Understanding linking can help you avoid nasty errors and make you a better programmer.

Lecture Plan

- Linking
- Case study: Library interpositioning

Case Study: Library Interpositioning

- Library interpositioning: powerful linking technique that allows programmers to intercept calls to arbitrary functions
- Interpositioning can occur at:
 - Compile time: When the source code is compiled
 - Link time: When the relocatable object files are statically linked to form an executable object file
 - Load/run time: When an executable object file is loaded into memory, dynamically linked, and then executed.

Some Interpositioning Applications

Security

- Confinement (sandboxing)
- Behind the scenes encryption

Debugging

- In 2014, two Facebook engineers debugged a treacherous 1-year old bug in their iPhone app using interpositioning
- Code in the SPDY networking stack was writing to the wrong location
- Solved by intercepting calls to Posix write functions (write, writev, pwrite)

Source: Facebook engineering blog post at https://code.facebook.com/posts/313033472212144/debugging-file-corruption-on-ios/

Some Interpositioning Applications

Monitoring and Profiling

- Count number of calls to functions
- Characterize call sites and arguments to functions
- Malloc tracing
 - Detecting memory leaks
 - Generating address traces

Example program

```
#include <stdio.h>
#include <malloc.h>

int main()
{
    int *p = malloc(32);
    free(p);
    return(0);
}
```

- Goal: trace the addresses and sizes of the allocated and freed blocks, without breaking the program, and without modifying the source code.
- Three solutions: interpose on the lib malloc and free functions at compile time, link time, and load/run time.

#ifdef COMPILETIME #include <stdio.h> #include <malloc.h> /* malloc wrapper function */ void *mymalloc(size t size) void *ptr = malloc(size); printf("malloc(%d)=%p\n", (int)size, ptr); return ptr; /* free wrapper function */ void myfree(void *ptr) free(ptr); printf("free(%p)\n", ptr); #endif

Compile-time Interpositioning

mymalloc.c

Compile-time Interpositioning

```
#define malloc(size) mymalloc(size)
#define free(ptr) myfree(ptr)

void *mymalloc(size_t size);
void myfree(void *ptr);

malloc.h
```

```
linux> make intc
gcc -Wall -DCOMPILETIME -c mymalloc.c
gcc -Wall -I. -o intc int.c mymalloc.o
linux> make runc
./intc
malloc(32)=0x1edc010
free(0x1edc010)
linux>
```

Link-time Interpositioning

```
#ifdef LINKTIME
#include <stdio.h>
void * real malloc(size t size);
void __real_free(void *ptr);
/* malloc wrapper function */
void * wrap malloc(size t size)
   void *ptr = __real_malloc(size); /* Call libc malloc */
   printf("malloc(%d) = %p\n", (int)size, ptr);
    return ptr;
/* free wrapper function */
void wrap free(void *ptr)
    real free(ptr); /* Call libc free */
   printf("free(%p)\n", ptr);
#endif
```

Link-time Interpositioning

```
linux> make intl
gcc -Wall -DLINKTIME -c mymalloc.c
gcc -Wall -c int.c
gcc -Wall -Wl,--wrap,malloc -Wl,--wrap,free -o intl int.o mymalloc.o
linux> make runl
./intl
malloc(32) = 0x1aa0010
free(0x1aa0010)
linux>
```

- The "-W1" flag passes argument to linker, replacing each comma with a space.
- The "--wrap, malloc" arg instructs linker to resolve references in a special way
 - Refs to malloc should be resolved as __wrap_malloc
 - Refs to __real_malloc should be resolved as malloc

#ifdef RUNTIME #define _GNU_SOURCE #include <stdio.h> #include <stdlib.h> #include <dlfcn.h> /* malloc wrapper function */ void *malloc(size_t size) void *(*mallocp)(size t size); char *error; mallocp = dlsym(RTLD NEXT, "malloc"); /* Get addr of libc malloc */ if ((error = dlerror()) != NULL) { fputs(error, stderr); exit(1); char *ptr = mallocp(size); /* Call libc malloc */ printf("malloc(%d) = %p\n", (int)size, ptr); return ptr;

Load/Run-time Interpositioning

mymalloc.c

Load/Run-time Interpositioning

```
/* free wrapper function */
void free(void *ptr)
   void (*freep)(void *) = NULL;
    char *error;
    if (!ptr)
        return;
    freep = dlsym(RTLD_NEXT, "free"); /* Get address of libc free */
    if ((error = dlerror()) != NULL) {
        fputs(error, stderr);
        exit(1);
    freep(ptr); /* Call libc free */
    printf("free(%p)\n", ptr);
                                                                            mymalloc.c
#endif
```

Load/Run-time Interpositioning

```
linux> make intr
gcc -Wall -DRUNTIME -shared -fpic -o mymalloc.so mymalloc.c -ldl
gcc -Wall -o intr int.c
linux> make runr
(LD_PRELOAD="./mymalloc.so" ./intr)
malloc(32) = 0xe60010
free(0xe60010)
linux>
```

• The LD_PRELOAD environment variable tells the dynamic linker to resolve unresolved refs (e.g., to malloc) by looking in mymalloc.so first.

Interpositioning Recap

Compile Time

 Apparent calls to malloc/free get macro-expanded into calls to mymalloc/myfree

Link Time

- Use linker trick to have special name resolutions
 - malloc → __wrap_malloc
 - __real_malloc → malloc

Load/Run Time

 Implement custom version of malloc/free that use dynamic linking to load library malloc/free under different names

Recap

- Linking
- Case study: Library interpositioning

• Next time: Managing the heap