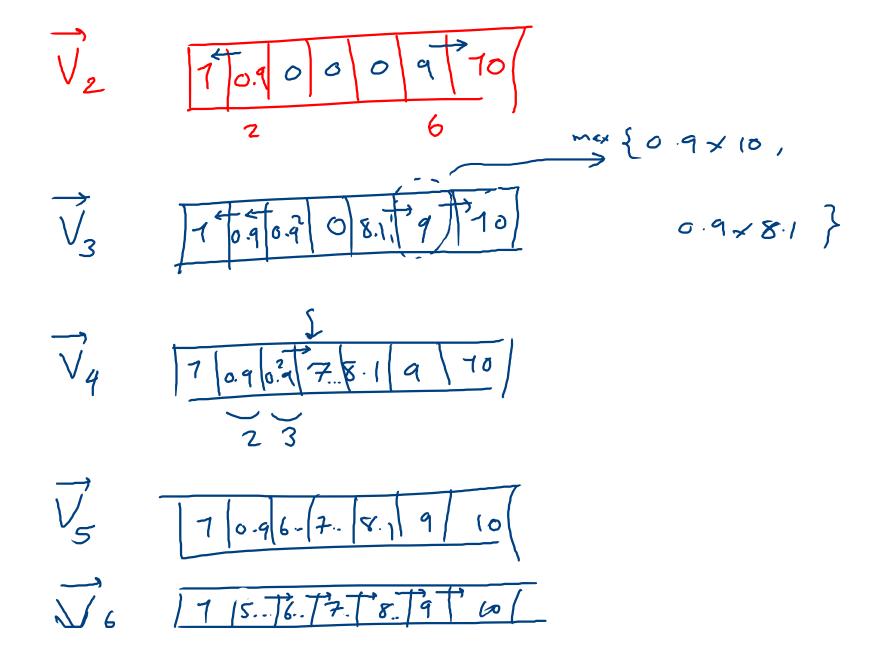
$$V_{k}^{*}(s) = \max_{a} \sum_{s} P(s'|s,a)[R(s) + V_{k-1}^{*}(s')]$$

$$V_{k-1}^{*}(s')$$

$$V$$



Contraction map  $||T\overrightarrow{V}_1 - T\overrightarrow{V}_2||_{\infty} \leq ||T\overrightarrow{V}_1 - ||T|_{\infty} ||T\overrightarrow{V}_1 - ||T|_{\infty} ||T|$ 

s - arbitrary

$$TV_{1}(s) = \max_{\alpha} \sum_{s'} P(s'|s,\alpha) \left[R(s) + YV(s')\right]$$

 $\overline{V}_{2}(s) = \max_{\alpha} \sum_{s'} P(s'|s,\alpha) \left[R(s) + V_{2}(s)\right]$ 

 $TV_{(s)} = TV_{2(s)} \leq \sum_{s \in P(s'|s,a_1)} [RK_{1} + V_{1}(s)]$ 

$$= \bigvee_{S'} P(S'|S,a) \left[ \bigvee_{(S')} - \bigvee_{z(S')} \right]$$

$$\leq \bigvee_{S'} \max_{S'} \left\{ \bigvee_{(S')} - \bigvee_{z(S')} \right\} \sum_{S} P(S|S,a)$$

$$\Rightarrow \bigvee_{S'} \bigvee_{V_{i}} - \bigvee_{V_{i}} ||D| = ||T \nabla_{k+i} - T \nabla^{k}||_{D}$$

$$= \bigvee_{Z} ||D| = ||T \nabla_{k+i} - T \nabla^{k}||_{D}$$

$$\langle Y | \overline{V}_{k-1} - \overline{V}^* | | \infty$$

$$\langle Y^2 | \overline{V}_{k-2} - \overline{V}^* | | \infty$$

$$\vdots$$

Policy Improvement  $\forall s: \pi(s) = \operatorname{argmax} \sum_{s'} P(s'|s,a) [R(s)]$ Optimal Does it implement TIK+1