#### **COMP 432 Machine Learning**

#### **Linear Models**

Computer Science & Software Engineering Concordia University, Fall 2024



## Summary of the last episode....

- Capacity, Underfitting, Overfitting, Regularization
- Gradient Descent (and variants)
- Linear Least Square
- Hyperparameters and Validation set
- Gradient Descent Variants

#### What we are going to learn today:

- Linear models for regression
- Linear models for classification

# Linear Models for Regression

A linear model can be written as:

$$\hat{y}(\mathbf{x}, \mathbf{w}) = \mathbf{w}^T \mathbf{x} = w_0 + \sum_{j=1}^D w_j x_j$$

$$\mathbf{x} = [1, x_1, x_2, ..., x_D]^T \qquad \longrightarrow \qquad \text{Input Features}$$

Concatenating a 1 is needed to implement the bias term.

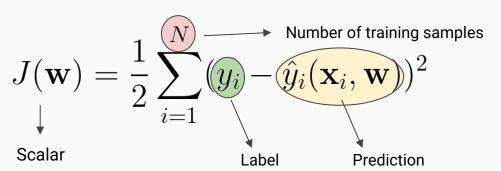
$$\mathbf{w} = [w_0, w_1, ..., w_D]^T \quad \Longrightarrow \quad \text{Parameters}$$

The output is a weighted sum of the inputs.

$$\hat{y}(\mathbf{x}, \mathbf{w}) = \mathbf{w}^T \mathbf{x} = w_0 + \sum_{j=1}^D w_j x_j$$

- To train the model, we need:
  - To define an objective function.
  - 2. Compute the **gradient** of the objective wrt the parameters.

• The natural objective function for a regression problem is the **Mean Squared Error** (MSE):



Let's assume our model provides the following prediction of the i-th input:

$$\hat{y} = w_0 + w_1 x_1 + w_2 x_2$$

In this case, we can write the objective as:

$$J(\mathbf{w}) = \frac{1}{2} \sum_{i=1}^{N} (y_i - w_0 - w_1 x_1 - w_2 x_2)^2$$

$$J(\mathbf{w}) = \frac{1}{2} \sum_{i=1}^{N} (y_i - w_0 - w_1 x_1 - w_2 x_2)^2$$

We now compute the gradient:

$$\nabla J(\mathbf{w}) = \begin{bmatrix} \frac{\partial J}{w0}, \frac{\partial J}{w1}, \frac{\partial J}{w2} \end{bmatrix}^T$$

$$\frac{\partial J}{\partial w_0} = 2 \cdot \frac{1}{2} \sum_{i=1}^{N} (y_i - \hat{y}_i) \cdot (-1)$$

$$= \sum_{i=1}^{N} (\hat{y}_i - y_i)$$

$$\frac{\partial J}{w1} = 2 \cdot \frac{1}{2} \sum_{i=1}^{N} (y_i - \hat{y}_i) \cdot (-x_1)$$

$$= \sum_{i=1}^{N} (\hat{y}_i - y_i) \cdot (-x_1)$$

$$\frac{\partial J}{\partial w^2} = \sum_{i=1}^{N} (\hat{y}_i - y_i) \cdot (-x_2)$$

• In the multidimensional case, we can generalize the gradient as:

$$\nabla J(\mathbf{w}) = \begin{bmatrix} \frac{\partial J(\mathbf{w})}{\partial w_0} \\ \frac{\partial J(\mathbf{w})}{\partial w_1} \\ \dots \\ \frac{\partial J(\mathbf{w})}{\partial w_D} \end{bmatrix} = \begin{bmatrix} \sum_{i=1}^{N} (\mathbf{w}^T \mathbf{x}_i - y_i) \\ \sum_{i=1}^{N} (\mathbf{w}^T \mathbf{x}_i - y_i) x_{i1} \\ \dots \\ \sum_{i=1}^{N} (\mathbf{w}^T \mathbf{x}_i - y_i) x_{iD} \end{bmatrix} = \begin{bmatrix} \sum_{i=1}^{N} (\mathbf{w}^T \mathbf{x}_i - y_i) \mathbf{x}_i \\ \dots \\ \sum_{i=1}^{N} (\mathbf{w}^T \mathbf{x}_i - y_i) \mathbf{x}_i \end{bmatrix}$$

$$\mathbf{x}_i = \begin{bmatrix} 1, x_0, \dots, x_D \end{bmatrix}^T \quad \mathbf{w} = \begin{bmatrix} w_0, w_1, \dots, w_D \end{bmatrix}^T$$
Error

• If we set:

$$\mathbf{x} = [1, x_1, x_2]^T$$
  $\mathbf{w} = [w0, w_1, w_2]^T$  We obtain the equations seen for the 2d case

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• We can also write the gradient equations in **matrix form**:

$$\nabla J(\mathbf{w}) = \sum_{i=1}^{N} (\mathbf{w}^T \mathbf{x}_i - y_i) \mathbf{x}_i = \mathbf{X}^T (\mathbf{X} \mathbf{w} - \mathbf{y})$$

$$\mathbf{X} = \begin{bmatrix} 1 & x_{1,1} & \dots & x_{1,D} \\ 1 & x_{2,1} & \dots & x_{2,D} \\ 1 & \dots & \dots & \dots \\ 1 & x_{N,1} & \dots & x_{N,D} \end{bmatrix} \quad \mathbf{w} = [w_0, w_1, \dots, w_D]^T$$

$$\mathbf{y} = [y_1, y_2, \dots, y_N]^T$$

$$\mathbf{y} = [y_1, y_2, \dots, y_N]^T$$
Label Vector (all samples)

• Let's do a **sanity check** on the dimensionalities to convince us better that the two expressions are equivalent.

$$\nabla J(\mathbf{w}) = \sum_{i=1}^{N} (\mathbf{w}^T \mathbf{x}_i - y_i) \mathbf{x}_i = \mathbf{X}^T (\mathbf{X} \mathbf{w} - \mathbf{y})$$

- Let's assume we have 3 parameters w<sub>0</sub>, w<sub>1</sub>, and w<sub>2</sub>
- What is the expected dimensionality for the gradient? (3,1)
- What is the dimensionality of  $\mathbf{w}$ ? (3,1)
- Let's assume we have 4 examples. What will be the dimensionality of the feature matrix **X?**

What is the dimensionality of y?

(4,1)

 Let's do a sanity check on the dimensionalities to convince us better that the two expressions are equivalent.

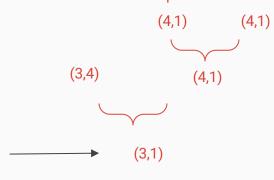
$$\nabla J(\mathbf{w}) = \sum_{i=1}^{N} (\mathbf{w}^T \mathbf{x}_i - y_i) \mathbf{x}_i = \mathbf{X}^T (\mathbf{X} \mathbf{w} - \mathbf{y})$$

Why do we want expressions that contain matrices?

- For the sake of compactness.
- We can take advantage of fast matrix multiplication libraries.



This is the expected dimensionality for the gradient.



We now have a compact expression of the gradient:

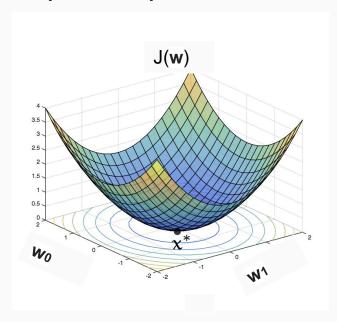
$$\nabla J(\mathbf{w}) = \sum_{i=1}^{N} (\mathbf{w}^{T} \mathbf{x}_{i} - y_{i}) \mathbf{x}_{i} = \mathbf{X}^{T} (\mathbf{X} \mathbf{w} - \mathbf{y})$$

We can use it for optimizing the parameters with gradient descent:

$$\mathbf{w}_{new} = \mathbf{w} - \eta \nabla J(\mathbf{w})$$

This model is very simple though. We can see if a direct (analytical solution exists).

- Let's take a look at the parameter space that we are optimizing.
- If we consider this simple linear model coupled with the mean squared error, the parameter space is convex!



 The function has only one minimum which is the global one.

 Instead of using gradient descent, we can see if an analytical solution exists!

• This is the expression for the gradient.

$$\nabla J(\mathbf{w}) = \sum_{i=1}^{N} (\mathbf{w}^{T} \mathbf{x}_{i} - y_{i}) \mathbf{x}_{i} = \mathbf{X}^{T} (\mathbf{X} \mathbf{w} - \mathbf{y})$$

We can look for an analytical solution by solving:

$$\nabla J(\mathbf{w}) = 0$$

$$\mathbf{X}^{T}(\mathbf{X}\mathbf{w} - \mathbf{y}) = 0$$

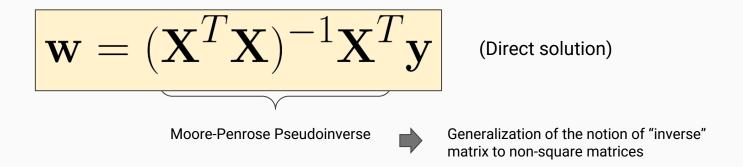
$$(\mathbf{X}^{T}\mathbf{X})\mathbf{w} - \mathbf{X}^{T}\mathbf{y} = 0 \text{ (Expansion)}$$

$$(\mathbf{X}^T\mathbf{X})\mathbf{w} = \mathbf{X}^T\mathbf{y}$$
 (Manipulation)

$$(\mathbf{X}^T\mathbf{X})^{-1}(\mathbf{X}^T\mathbf{X})\mathbf{w} = (\mathbf{X}^T\mathbf{X})^{-1}\mathbf{X}^T\mathbf{y}$$
 (Manipulation)

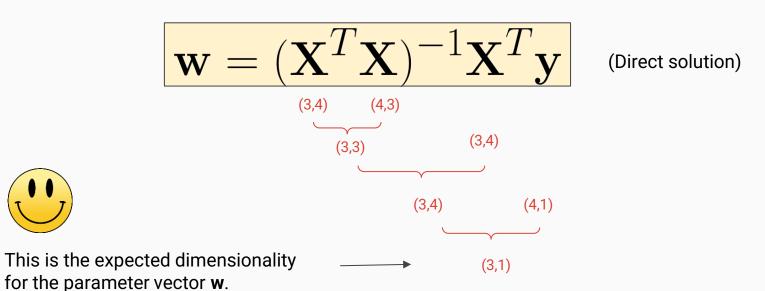
$$\mathbf{w} = (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T \mathbf{y}$$
 (Direct solution)

This problem is simple enough and can be solved in a **closed form** with an **analytical expression**:



- We can solve this simple problem in one shot just by solving a system of linear equations.
- Even though gradient descent works well in this case too, we do not necessarily need to use it as an analytical solution exists.

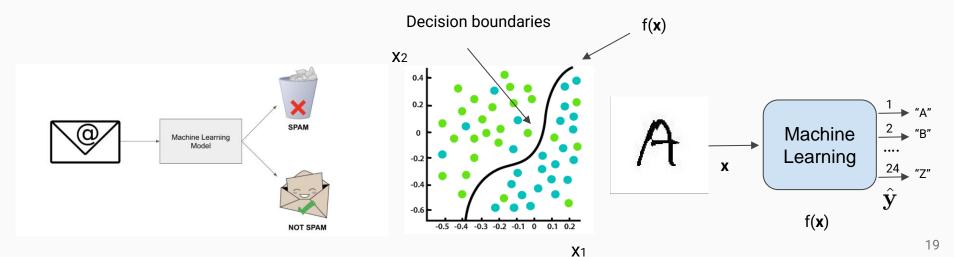
• Let's do a dimensionality check:



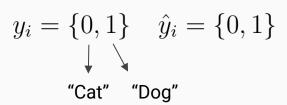
• So far, we have seen linear models for **regression**. But, what about **classification**?

**Classification:** the model has to specify which of the *k* categories some input belongs to.

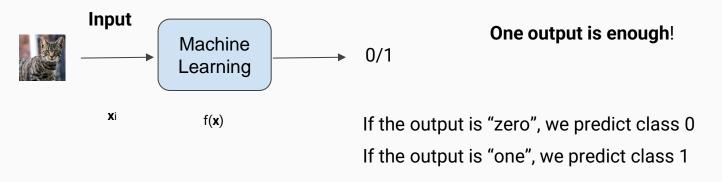
$$\hat{y} = f(\mathbf{x}) \quad \mathbf{x} = [x_1, x_2, ..., x_D]^T \quad \mathbf{x} \in \mathbb{R}^D \quad \hat{y} = \{1, ..., K\}$$



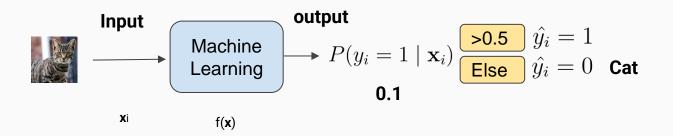
If we only have two classes (e.g., cat/dog) we have a binary classification problem.



How many outputs are needed for a binary classification?



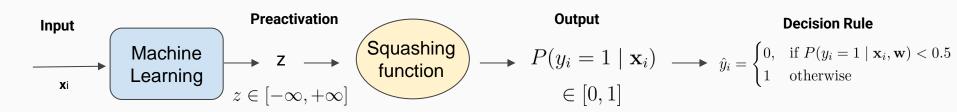
Often, we want the model to output a probability (soft prediction) rather than a discrete one (hard prediction),



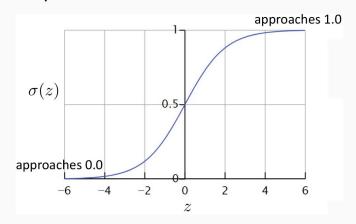
You can compute the probability of class 0 from the probability of class 1:

$$P(y_i = 0 \mid \mathbf{x}_i) = 1 - P(y_i = 1 \mid \mathbf{x}_i)$$
 The probability of class 1 determines the probability of class 0

How can we "force" the machine learning model to output a probability?



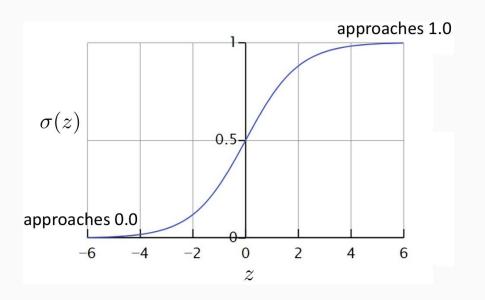
 To interpret our output as a probability, we need a "squashing" function that makes sure that the output is bounded between 0 and 1.



Sigmoid (logistic function):

$$\sigma(z) = \frac{1}{1 + e^{-z}}$$

The sigmoid has some nice properties:



**Sigmoid** (logistic function):

$$\sigma(z) = \frac{1}{1 + e^{-z}}$$

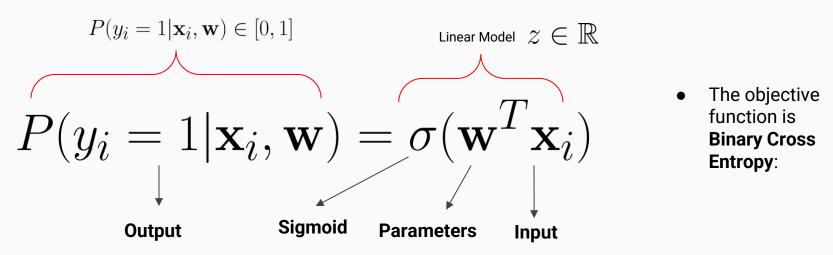
#### **Derivative:**

$$\frac{d\sigma(z)}{dz} = \sigma(z)(1 - \sigma(z))$$

Sigmoid (logistic function):

$$\sigma(z) = \frac{1}{1+e^{-z}} = (1+e^{-z})^{-1} \quad \text{(Algebraic manipulation)}$$
 
$$\frac{d\sigma(z)}{dz} = -(1+e^{-z})^{-2} \cdot -e^{-z} \quad \text{(Derivative computation)}$$
 
$$= \frac{e^{-z}}{(1+e^{-z})^2} \quad \text{(Algebraic manipulation)}$$
 
$$= \frac{1}{(1+e^{-z})} \cdot \frac{e^{-z}}{(1+e^{-z})} \quad \text{(Algebraic manipulation)}$$
 
$$= \frac{1}{(1+e^{-z})} \cdot \frac{e^{-z}+1-1}{(1+e^{-z})} = \sigma(z)(1-\sigma(z))$$

- Logistic Regression is a linear model used for binary classification.
- It is based on a linear model whose output is squashed by a sigmoid.



 This is a somewhat unfortunate name for a model that we use for classification and not for regression.

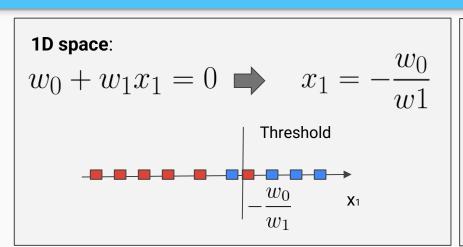
• Logistic Regression can only draw **linear boundaries** between the two classes:

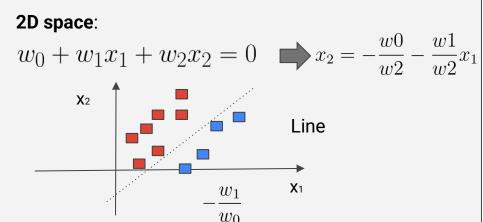
$$P(y_i = 1 | \mathbf{x}_i, \mathbf{w}) = \sigma(\mathbf{w}^T \mathbf{x}_i) \longrightarrow \hat{y}_i = \begin{cases} 0, & \text{if } P(y_i = 1 \mid \mathbf{x}_i, \mathbf{w}) < 0.5 \\ 1 & \text{otherwise} \end{cases}$$

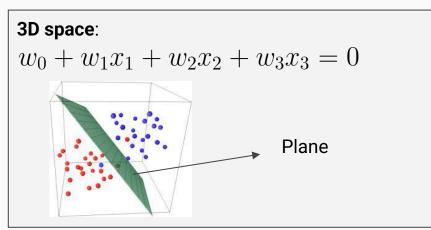
The decision boundaries are all those points where there is **maximum uncertainty**:

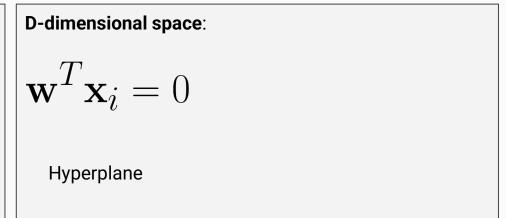
$$P(y_i = 1 | \mathbf{x}_i, \mathbf{w}) = \sigma(\mathbf{w}^T \mathbf{x}_i) = 0.5$$

$$\mathbf{w}^T \mathbf{x}_i = 0$$









$$P(y_i = 1 | \mathbf{x}_i, \mathbf{w}) = \sigma(\mathbf{w}^T \mathbf{x}_i)$$

- We can train logistic regression with gradient descent.
- To make this possible, we need:
  - 1. To define an **objective function**
  - Compute the gradient of the objective wrt the parameters.

- To train a binary classifier, we need an **objective function**.
- For classification, we can use the **categorical cross-entropy**:

$$CCE = -\frac{1}{N} \sum_{i=1}^{N} \sum_{k=1}^{K} y_{ik} ln(p_{ik})$$
 K=2 
$$\begin{cases} y_{i1} = 1, & y_{i2} = 1 - y_{i1} \\ p_{i1} = P(y_i = 1 | \mathbf{w}, \mathbf{x}_i) \\ p_{i2} = 1 - P(y_i = 1 | \mathbf{w}, \mathbf{x}_i) \end{cases}$$

$$\mathbf{K=2} \begin{cases} y_{i1} = 1, & y_{i2} = 1 - y_{i1} \\ p_{i1} = P(y_i = 1 | \mathbf{w}, \mathbf{x}_i) \\ p_{i2} = 1 - P(y_i = 1 | \mathbf{w}, \mathbf{x}_i) \end{cases}$$

$$BCE = -\frac{1}{N} \sum_{i=1}^{N} y_{i1} ln(p_{i1}) + (1 - y_{i1}) ln(1 - p_{i1})$$

Lower bound: 0

Upper bound: +inf

The binary cross-entropy is a special case of the categorical cross-entropy

We can now compute the gradient

$$BCE = -\frac{1}{N} \sum_{i=1}^{N} y_{i1} ln(p_{i1}) + (1 - y_{i1}) ln(1 - p_{i1})$$

Log-Likelihood (LL)

We focus first on the term highlighted called **Log-Likelihood** (LL) and compute the derivative wrt to a generic parameter wi

$$\frac{\partial LL_i(\mathbf{w})}{\partial w_j} = \frac{\partial}{\partial w_j} y_i \ln \sigma(\mathbf{w}^T \mathbf{x}_i) + (1 - y_i) \ln \left[ 1 - \sigma(\mathbf{w}^T \mathbf{x}_i) \right] 
= \frac{\partial}{\partial w_j} y_i \ln \sigma(\mathbf{w}^T \mathbf{x}_i) + \frac{\partial}{\partial w_j} (1 - y_i) \ln \left[ 1 - \sigma(\mathbf{w}^T \mathbf{x}_i) \right] 
_{30}$$

$$\begin{split} \frac{\partial LL_i(\mathbf{w})}{\partial w_j} &= \frac{\partial}{\partial w_j} y_i \ln \sigma(\mathbf{w}^T \mathbf{x}_i) + \frac{\partial}{\partial w_j} (1 - y_i) \ln \left[ 1 - \sigma(\mathbf{w}^T \mathbf{x}_i) \right] \\ &= y_i \frac{1}{\sigma(\mathbf{w}^T \mathbf{x}_i)} \frac{\partial}{\partial w_j} \sigma(\mathbf{w}^T \mathbf{x}_i) + (1 - y_i) \frac{1}{1 - \sigma(\mathbf{w}^T \mathbf{x}_i)} \cdot (-1) \frac{\partial}{\partial w_j} \sigma(\mathbf{w}^T \mathbf{x}_i) & \text{(derivation)} \\ &= \left[ \frac{y_i}{\sigma(\mathbf{w}^T \mathbf{x}_i)} - \frac{1 - y_i}{1 - \sigma(\mathbf{w}^T \mathbf{x}_i)} \right] \frac{\partial}{\partial w_j} \sigma(\mathbf{w}^T \mathbf{x}_i) & \text{(manipulation)} \\ &= \left[ \frac{y_i}{\sigma(\mathbf{w}^T \mathbf{x}_i)} - \frac{1 - y_i}{1 - \sigma(\mathbf{w}^T \mathbf{x}_i)} \right] \sigma(\mathbf{w}^T \mathbf{x}_i) \left( 1 - \sigma(\mathbf{w}^T \mathbf{x}_i) \right) x_j & \text{(derivative of the sigmoid)} \\ & W_{ij} \text{ why do we have the scalar x}_i \\ & \frac{\partial \mathbf{W}^T \mathbf{x}_i}{\partial w_i} = x_j \end{split}$$

$$= \left[ \frac{y_i}{\sigma(\mathbf{w}^T \mathbf{x}_i)} - \frac{1 - y_i}{1 - \sigma(\mathbf{w}^T \mathbf{x}_i)} \right] \sigma(\mathbf{w}^T \mathbf{x}_i) \left( 1 - \sigma(\mathbf{w}^T \mathbf{x}_i) \right) x_j$$

$$= \left[ \frac{y_i (1 - \sigma(\mathbf{w}^T \mathbf{x}_i)) - (1 - y_i) \sigma(\mathbf{w}^T \mathbf{x}_i)}{\sigma(\mathbf{w}^T \mathbf{x}_i) (1 - \sigma(\mathbf{w}^T \mathbf{x}_i))} \right] \sigma(\mathbf{w}^T \mathbf{x}_i) (1 - \sigma(\mathbf{w}^T \mathbf{x}_i) x_j \quad \text{(Manipulation)}$$

$$\frac{\partial LL_i(\mathbf{w})}{\partial w_j} = \left[y_i - \sigma(\mathbf{w}^T \mathbf{x}_i)\right] x_j \quad \text{(Simplification)}$$

**Gradient** (over all parameters w):

$$\nabla LL_i(\mathbf{w}) = \left[\frac{\partial LL_i}{\partial w_0}, \frac{\partial LL_i}{\partial w_1}, ..., \frac{\partial LL_i}{\partial w_j}, ..., \frac{\partial LL_i}{\partial w_D}\right]^T$$

$$\frac{\partial LL_i(\mathbf{w})}{\partial w_i} = \left[ y_i - \sigma(\mathbf{w}^T \mathbf{x}_i) \right] x_j$$

Weights:

$$\mathbf{w} = [w_0, w_1, ..., w_j, ..., w_D]^T$$

**Gradient** (over all parameters w):

$$\nabla LL_{i}(\mathbf{w}) = \left[\frac{\partial LL_{i}}{\partial w_{0}}, \frac{\partial LL_{i}}{\partial w_{1}}, ..., \frac{\partial LL_{i}}{\partial w_{j}}, ..., \frac{\partial LL_{i}}{\partial w_{D}}\right]^{T} \quad \mathbf{x}_{i} = [1, x_{1}, ..., x_{j}, ..., x_{D}]^{T}$$

$$\mathbf{x}_i = [1, x_1, ..., x_j, ..., x_D]^T$$

$$\frac{\partial LL_i(\mathbf{w})}{\partial w_0} = \begin{bmatrix} y_i - \sigma(\mathbf{w}^T \mathbf{x}_i) \end{bmatrix} \quad \frac{\partial LL_i(\mathbf{w})}{\partial w_1} = \begin{bmatrix} y_i - \sigma(\mathbf{w}^T \mathbf{x}_i) \end{bmatrix} x_1 \quad \frac{\partial LL_i(\mathbf{w})}{\partial w_j} = \begin{bmatrix} y_i - \sigma(\mathbf{w}^T \mathbf{x}_i) \end{bmatrix} x_j$$

The vectorized expression is thus:

$$\nabla LL_i(\mathbf{w}) = \left[ y_i - \sigma(\mathbf{w}^T \mathbf{x}_i) \right] \mathbf{x}_i$$

#### **Gradient of LL** (over all parameters w):

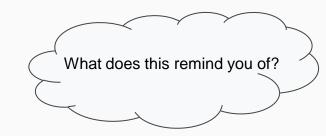
$$\nabla LL_i(\mathbf{w}) = [y_i - \sigma(\mathbf{w}^T \mathbf{x}_i)] \mathbf{x}_i$$

$$\nabla BCE(\mathbf{w}) = -\frac{1}{N} \sum_{i=1}^{N} \nabla LL_i(\mathbf{w})$$

#### **Vectorized form:**

$$\nabla BCE(\mathbf{w}) = \mathbf{X}^{T}(\sigma(\mathbf{X}\mathbf{w}) - \mathbf{y})$$

$$\nabla BCE(\mathbf{w}) = \frac{1}{N} \sum_{i=1}^{N} \left[ \sigma(\mathbf{w}^T \mathbf{x}_i) - y_i \right] \mathbf{x}_i$$



#### **Gradient** (Logistic Regression):

$$\nabla BCE(\mathbf{w}) = \frac{1}{N} \sum_{i=1}^{N} \left[ \sigma(\mathbf{w}^T \mathbf{x}_i) - y_i \right] \mathbf{x}_i$$

**Prediction - Label** 

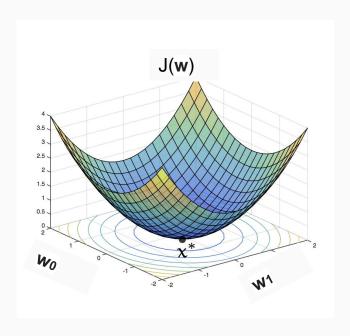
**Gradient** (Linear Regression):

$$abla J(\mathbf{w}) = \sum_{i=1}^{N} (\mathbf{w}^T \mathbf{x}_i - y_i) \mathbf{x}_i$$

• The gradient is the same as the one computed for linear regression:

 In both cases, the gradient depends on the difference between the predicted output and the target label (error).

How does the optimization space look like in this case?



- If we use logistic regression (linear model + BCE) the optimization space is still convex.
- This is good news for **optimization**.

Do we have a direct solution?

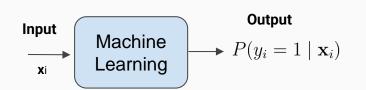


A direct closed-form solution does not exist.

We have to use gradient descent!

#### Logistic Regression

Let's now use logistic regression to solve a binary classification task:



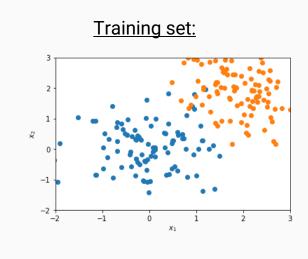
#### Model:

$$p(y_i = 1 \mid \mathbf{x}_i, \mathbf{w}) = \sigma(\mathbf{w}^T \mathbf{x}_i) = \sigma(w_0 + w_1 x_1 + w_2 x_2)$$

$$p(\mathbf{y} = 1 \mid \mathbf{X}, \mathbf{w}) = \sigma(\mathbf{X} \mathbf{w}) \text{ (Vectorized form)}$$

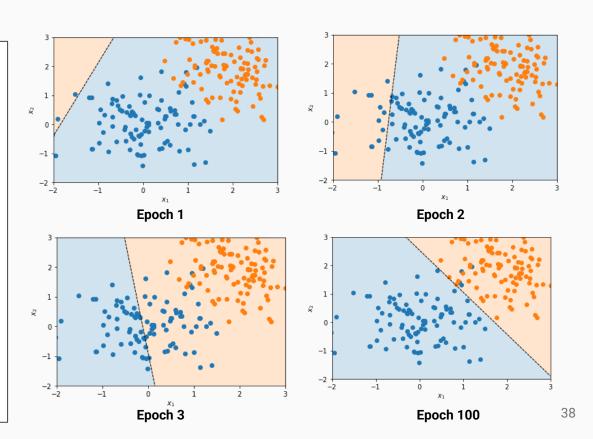
$$\mathbf{w} = [w_0, w_1, w_2]^T \text{ (Parameters)}$$

$$J(\mathbf{w}) = -\sum_{i=1}^{N} y_i \ln P(y_i = 1 \mid \mathbf{x}_i, \mathbf{w}) + (1 - y_i) \ln(1 - P(y_i = 1 \mid \mathbf{x}_i, \mathbf{w}))$$



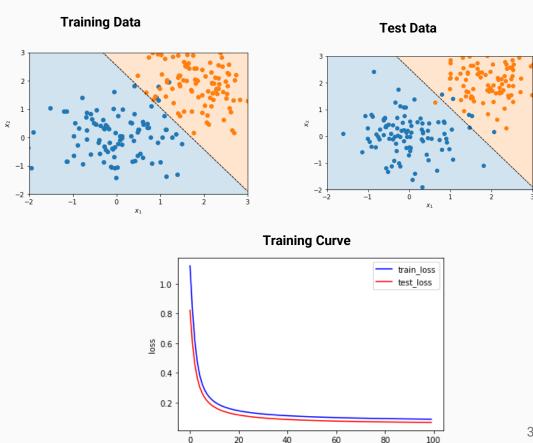
#### Logistic Regression

```
# Parameters Initialization
w = np.array([2.0, 0.5, -0.5])
# Hyperparameters
N = pochs = 100
lr = 0.01
for epoch in range (N epochs):
 # compute the predictions
 y hat = logistic regression(X train, w)
 # compute the gradient
 grad = np.dot(X train.T, (y hat - y train))
 # parameter updates with gradient descend
 w = w - lr * grad
```



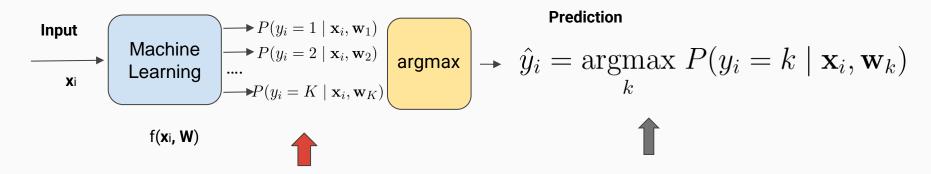
#### Logistic Regression

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 # compute the predictions
 y hat = logistic regression(X train, w)
 # compute the gradient
 grad = np.dot(X_train.T,(y_hat - y train))
 # parameter updates with gradient descend
 w = w - lr * grad
```



epochs

In multiclass classification, we want a machine learning model that outputs K probabilities.

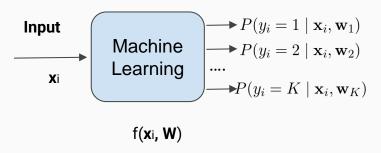


We want these probabilities to sum up to 1 A single cl

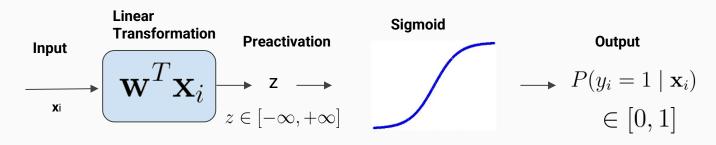
A single class is predicted for each input

We can then select the class with the highest probability with an argmax operation.

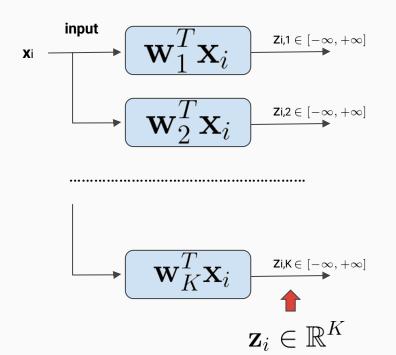
How can we "force" the machine learning model to output probabilities?



• For **binary classification** with logistic regression (where we have a single output), we can use a **sigmoid**:

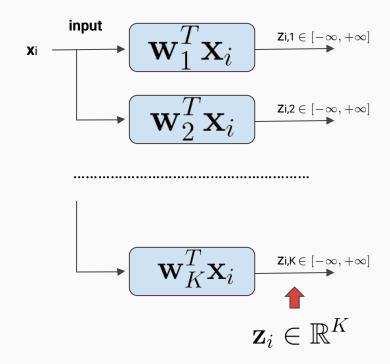


- For multiclass classification, we can map the input xi into a K dimensional space zi
- This mapping can be done by applying **K linear transformations** in **parallel**:



We can vectorize this operation in this way:

$$\mathbf{z}_i = \mathbf{W}^T \mathbf{x}_i$$



We can **vectorize** the K linear transformation in this way:

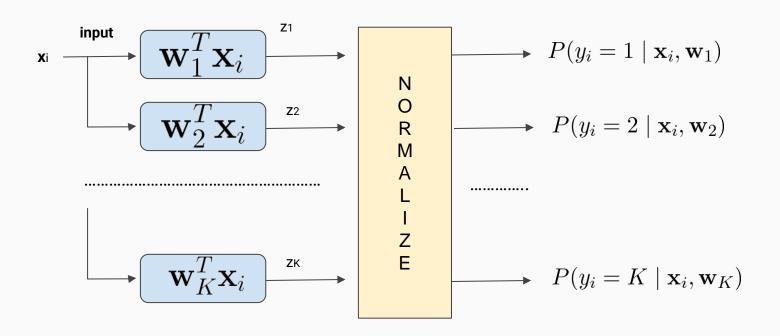
$$\mathbf{z}_i = \mathbf{W}^T \mathbf{x}_i$$
(K, 1) (K, P) (P, 1)

Due to intercept term

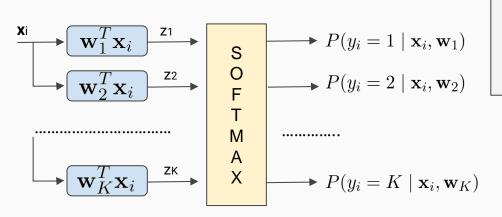
$$\mathbf{x}_i = [1, x_{i1}, x_{i2}, ..., x_{iD}]^T$$
 P=D+1

$$\mathbf{W} = [\mathbf{w}_1, \mathbf{w}_2, ..., \mathbf{w}_K] = \begin{bmatrix} w_{0,1} & w_{0,2} & ... & w_{0,K} \\ w_{1,1} & w_{1,2} & ... & w_{1,K} \\ ... & ... & ... & ... \\ w_{D,1} & w_{D,2} & ... & w_{D,K} \end{bmatrix}$$

Now we can apply a squashing function to output the probabilities over the K classes.



• A popular choice is the **softmax function**:



$$softmax(\mathbf{z})_k = \frac{\exp(z_k)}{\sum_{j=1}^K \exp(z_j)}$$

$$P(y = k \mid \mathbf{x}_i, \mathbf{W}) = \frac{\exp(\mathbf{w}_k^T \mathbf{x}_i)}{\sum_{j=1}^K \exp(\mathbf{w}_k^T \mathbf{x}_i)}$$

The softmax ensures that:

- 1. Each probability ranges between 0 and 1.
- 2. The sum of all the K probabilities is 1.

The softmax introduces **competition** within the output units: the **increase** of one probability leads to a **decrease** in the others.

**Linear Transformation + Softmax = Multiclass logistic regression** or **Softmax classification**.

• A popular choice is the **softmax function**:

$$softmax(\mathbf{z})_k = \frac{\exp(z_k)}{\sum_{j=1}^K \exp(z_j)}$$

$$\mathbf{z} = [z_1, ..., z_k, ..., z_K]^T$$

•

They sum to one

The sigmoid is a special case of the softmax function:

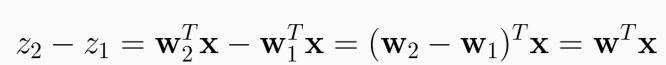
$$softmax(\mathbf{z})_k = \frac{\exp(z_k)}{\sum_{j=1}^K \exp(z_j)}$$

$$K = 2$$



$$softmax(z_1, z_2)_1 = \frac{exp(z_1)}{exp(z_1) + exp(z_2)} = \frac{1}{1 + exp(z_2 - z_1)}$$

Only one output is needed in a binary classification





$$softmax(z) = \frac{1}{1 + e^{-z}} = \sigma(z)$$

The softmax has some nice properties. For instance:

$$softmax(\mathbf{z}) = softmax(\mathbf{z} + c)$$

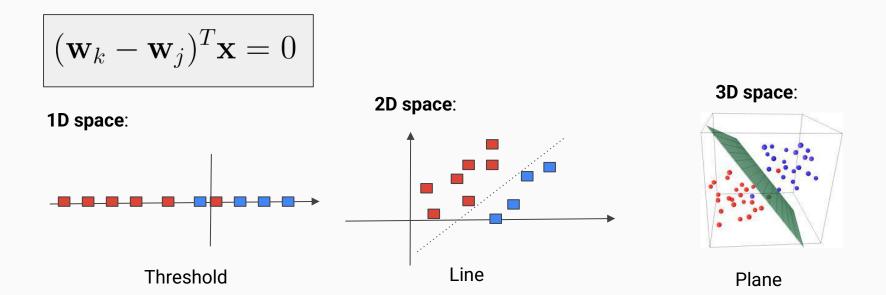
• This is helpful because we can improve the **numerical stability** of the softmax:

$$softmax(\mathbf{z}) = softmax(\mathbf{z} - \max_{j} z_{j})$$

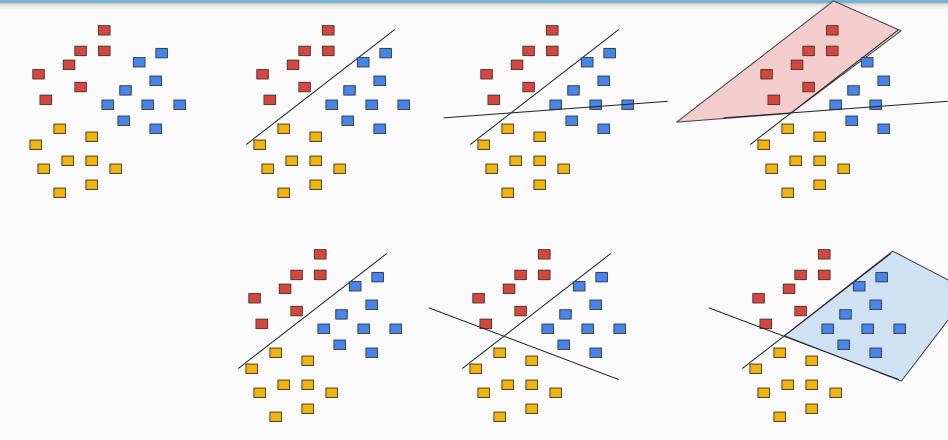
We will see other nice properties in the training part.

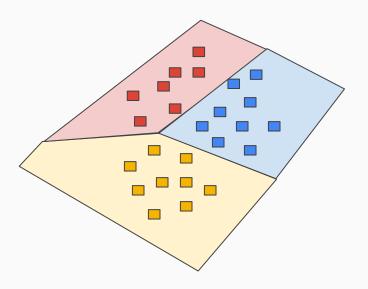
- Let's now analyze the **decision boundaries** of multiclass **logistic regression**.
- The **boundary condition** for two classes k and j selected within the pool of K classes is given by:

$$P(y = k \mid \mathbf{x}, \mathbf{w}) = P(y = j \mid \mathbf{x}, \mathbf{w}) \qquad \text{(equal probability)}$$
 
$$softmax(\mathbf{z})_k = softmax(\mathbf{z})_j \qquad \text{(replace with softmax)}$$
 
$$softmax(\mathbf{W}^T\mathbf{x})_k = softmax(\mathbf{W}^T\mathbf{x})_j \qquad \text{(replace z)}$$
 
$$\frac{\exp(\mathbf{w}_k^T\mathbf{x})}{\sum_{i=1}^K \exp(\mathbf{w}_i^T\mathbf{x})} = \frac{\exp(\mathbf{w}_j^T\mathbf{x})}{\sum_{i=1}^K \exp(\mathbf{w}_i^T\mathbf{x})} \qquad \text{(expand softmax)}$$
 
$$\mathbf{w}_k^T\mathbf{x} = \mathbf{w}_j^T\mathbf{x} \qquad \text{(algebraic manipulation)}$$
 
$$(\mathbf{w}_k - \mathbf{w}_j)^T\mathbf{x} = 0 \qquad \text{(boundary condition)}$$



This is the same as **binary classification**. In our multiclass context, we have to jointly consider all the boundaries across classes



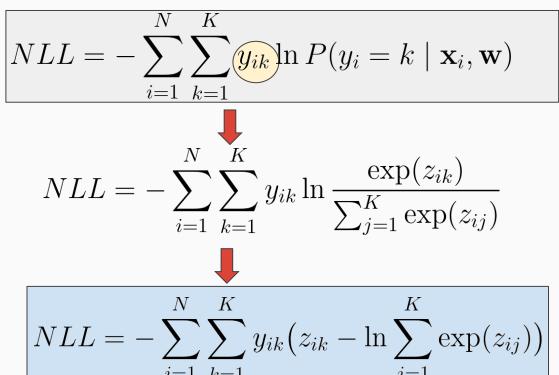


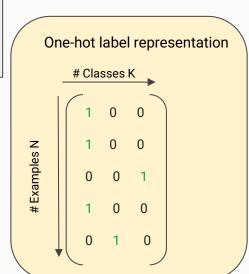
For multiclass logistic regression, the boundaries are defined by:

- 1D case Multiple thresholds
- 2D case Line intersections
- 3D case Plane intersections
- D > 3 case Hyperplane intersections

- As usual, we can train our multiclass classifier with **gradient descent**.
- To make this possible, we need:
  - 1. To define an **objective function** Categorical Cross Entropy (Negative Log-Likelihood)
  - 2. Compute the **gradient** of the objective wrt the parameters.

Let's now plug the softmax in the expression of NLL:



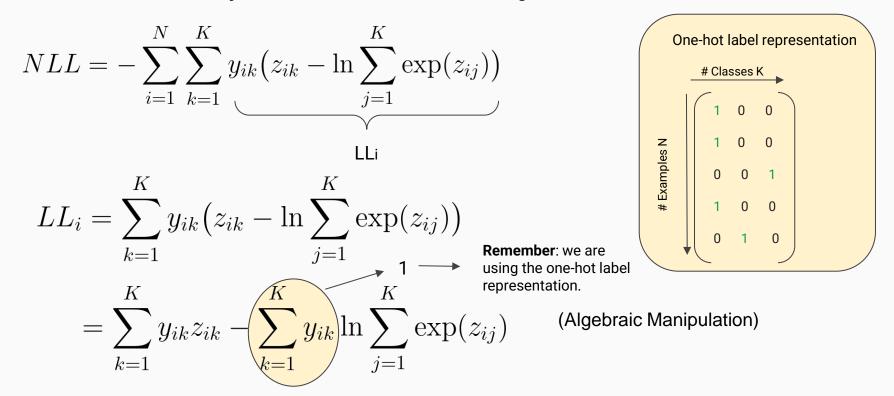


$$NLL = -\sum_{i=1}^{N} \sum_{k=1}^{K} y_{ik} \left( z_{ik} - \ln \sum_{j=1}^{K} \exp(z_{ij}) \right)$$

To minimize NLL, we have to **maximize** this term (the bigger the better)

- Intuitively, when training the model to minimize the NLL:
- We push up the output corresponding to the right label zik.
- 2. At the same time we **push down** the contribution of all the **other outputs** (second term of the equation)

Now, we have an objective function. We also need the gradient to train the model.



$$LL_i = \sum_{k=1}^{K} y_{ik} z_{ik} - \ln \sum_{j=1}^{K} \exp(z_{ij})$$

• We can now compute the **derivative** wrt the generic activation **z**<sub>il</sub> for the sample i and class I:

$$\begin{split} \frac{\partial LL_i}{\partial z_{il}} &= \frac{\partial}{\partial z_{il}} \sum_{k=1}^K y_{ik} z_{ik} - \frac{\partial}{\partial z_{il}} \ln \sum_{j=1}^K \exp(z_{ij}) \\ &= y_{il} - \underbrace{\frac{\exp(z_{il})}{\sum_{j=1}^K \exp(z_{il})}}_{\text{This is the softmax!}} \end{split}$$

$$\frac{\partial LL_i}{\partial z_{il}} = y_{il} - softmax(\mathbf{z}_i)_l$$

• We want to compute the derivative over the generic weight wml connecting the input feature m to class I:

$$\mathbf{W} = [\mathbf{w}_1, ..., \mathbf{w}_l, ..., \mathbf{w}_K] = \begin{bmatrix} w_{0,1} & ... & w_{0,l} & ... & w_{0,K} \\ ... & ... & ... & ... & ... \\ w_{m,1} & ... & w_{m,l} & ... & w_{m,K} \\ ... & ... & ... & ... & ... \\ w_{D,1} & ... & w_{D,l} & ... & w_{D,K} \end{bmatrix}$$

$$z_{il} = \mathbf{w}_{l}^{T} \mathbf{x}_{i} = w_{0l} + w_{1l} x_{i1} + \dots + w_{ml} x_{im} + \dots + w_{Dl} x_{iD}$$

$$\frac{\partial LL_i}{\partial z_{il}} = y_{il} - softmax(\mathbf{z}_i)_l$$

$$\frac{\partial LL_i}{\partial w_{ml}} = \frac{\partial LL_i}{\partial z_{il}} \cdot \frac{\partial z_{il}}{\partial w_{ml}}$$

$$z_{il} = \mathbf{w}_{l}^{T} \mathbf{x}_{i} = w_{0l} + w_{1l} x_{i1} + \dots + w_{ml} x_{im} + \dots + w_{Dl} x_{iD}$$

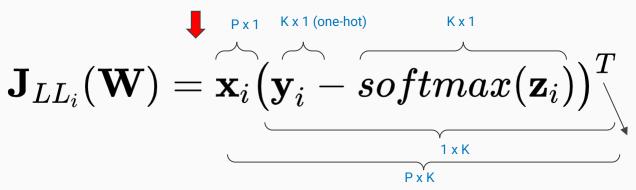
$$\frac{\partial LL_i}{\partial w_{ml}} = (y_{il} - softmax(\mathbf{z}_i)_l)x_{im}$$

• We can now collect all the partial derivatives for all the features M:

$$\frac{\partial LL_i}{\partial w_{ml}} = (y_{il} - softmax(\mathbf{z}_i)_l)x_{im}$$



$$abla LL_i(\mathbf{w}_m) = (y_{il} - softmax(\mathbf{z}_i)_l)\mathbf{x}_i$$
 Gradient for all the **features**.



Gradient (Jacobian) for all the **features** and **outputs**.

Transpose is needed here to match the dimensionality

$$\mathbf{J}_{LL_i}(\mathbf{W}) = \mathbf{x}_i ig(\mathbf{y}_i - softmax(\mathbf{z}_i)ig)^T$$
 Gradient (Jacobian for all the features and outputs)

• We can now compute the gradient of the **NLL** for all the inputs:

$$\mathbf{J}_{NLL}(\mathbf{W}) = -\sum_{i=1}^{N} \mathbf{J}_{LL_i}(\mathbf{W}) = \sum_{i=1}^{N} \mathbf{x}_i \left( softmax(\mathbf{W}^T \mathbf{x}_i) - \mathbf{y}_i \right)^T$$

$$\mathbf{J}_{NLL}(\mathbf{W}) = \mathbf{X}^T \left( softmax(\mathbf{X}\mathbf{W}) - \mathbf{Y} \right) \quad \text{Vectorized form}$$

K x 1

#### Gradient

$$\mathbf{Y} = \begin{bmatrix} 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 \\ 1 & 0 & 0 & 0 \end{bmatrix} \quad \mathbf{X} = \begin{bmatrix} 1 & x_{1,1} & \dots & x_{1,D} \\ 1 & x_{2,1} & \dots & x_{2,D} \\ 1 & \dots & \dots & \dots \\ 1 & x_{N,1} & \dots & x_{N,D} \end{bmatrix} \quad \mathbf{W} = [\mathbf{w}_1, \mathbf{w}_2, \dots, \mathbf{w}_K] = \begin{bmatrix} w_{0,1} & w_{0,2} & \dots & w_{0,K} \\ w_{1,1} & w_{1,2} & \dots & w_{1,K} \\ \dots & \dots & \dots & \dots \\ w_{D,1} & w_{D,2} & \dots & w_{D,K} \end{bmatrix}$$

PxK

$$\mathbf{J}_{NLL}(\mathbf{W}) = \mathbf{X}^{T} \left( softmax(\mathbf{X}\mathbf{W}) - \mathbf{Y} \right)$$

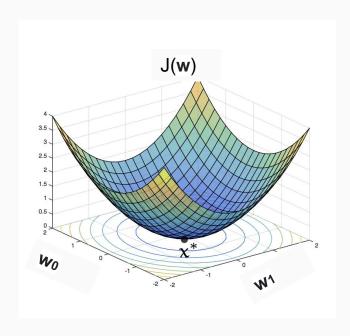


Do not confuse the Jacobian **J**f(**W**) with the objective function **J**(**W**)

$$\mathbf{J}_{f}(\mathbf{W}) = \begin{bmatrix} \frac{\partial f(\mathbf{W})}{\partial w_{0,1}} & \frac{\partial f(\mathbf{W})}{\partial w_{0,2}} & \dots & \frac{\partial f(\mathbf{W})}{\partial w_{0,K}} \\ \frac{\partial f(\mathbf{W})}{\partial w_{1,1}} & \frac{\partial f(\mathbf{W})}{\partial w_{1,2}} & \dots & \frac{\partial f(\mathbf{W})}{\partial w_{1,K}} \\ \dots & \dots & \dots & \dots \\ \frac{\partial f(\mathbf{W})}{\partial w_{D,1}} & \frac{\partial f(\mathbf{W})}{\partial w_{D,2}} & \dots & \frac{\partial f(\mathbf{W})}{\partial w_{D,K}} \end{bmatrix}$$

- In multiclass logistic regression, the weights are gathered in an M x K **matrix** and not anymore in an M-dimensional vector (due to the multiple classes K).
- As a result, also the gradient will be an M x K matrix.
- This matrix containing all the partial derivatives is called **Jacobian**.
- It extends the concept of gradients to functions with multiple inputs and multiple outputs.

How the optimization space looks like in this case?



- If we use multiclass logistic regression (linear model + CCE) the optimization space is still convex.
- This is a good news for **optimization**.

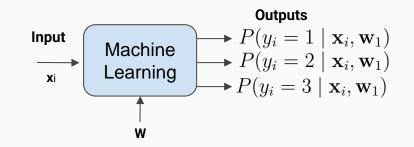
Do we have a direct solution?



A direct closed-form solution does not exist.

We have to use gradient descent!

Let's now use multiclass logistic regression to solve a multiclass classification task:



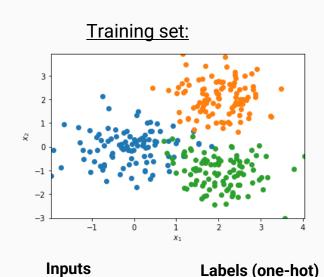
#### Model:

$$p(y_i = k \mid \mathbf{x}_i, \mathbf{W}) = softmax(\mathbf{W}^T \mathbf{x}_i)_k$$

$$\mathbf{W} = \begin{bmatrix} \mathbf{w}_1, \mathbf{w}_2, ..., \mathbf{w}_3 \end{bmatrix} = \begin{bmatrix} w_{0,1} & w_{0,2} & w_{0,3} \\ w_{1,1} & w_{1,2} & w_{1,3} \\ w_{2,1} & w_{2,2} & w_{2,3} \end{bmatrix}$$

#### Objective:

$$NLL(\mathbf{W}) = -\ln P(\mathbf{Y} \mid \mathbf{X}, \mathbf{w}) = -\sum_{i=1}^{N} \sum_{k=1}^{K} y_{ik} \ln softmax(\mathbf{W}^{T} \mathbf{x}_{i})_{k}$$

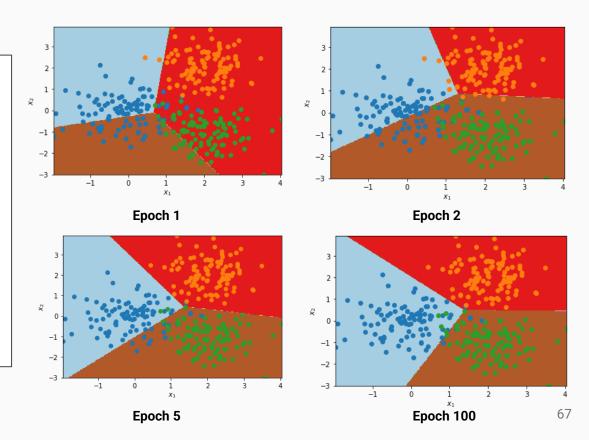


$$\mathbf{X} = \begin{bmatrix} 1 & x_{1,1} & x_{1,2} \\ 1 & x_{2,1} & x_{2,2} \\ 1 & \dots & \dots \\ 1 & x_{N,1} & x_{N,2} \end{bmatrix} \quad \mathbf{Y} = \begin{bmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \\ \dots & \dots & \dots \\ 0 & 0 & 1 \\ 1 & 0 & 0 \end{bmatrix}_{66}$$

$$\mathbf{Y} = \begin{bmatrix} 0 & 1 & 0 \\ \dots & \dots & \dots \\ 0 & 0 & 1 \\ 1 & 0 & 0 \end{bmatrix}$$

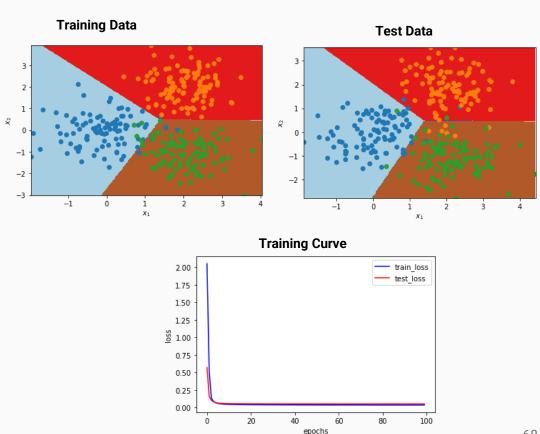
#### Example

```
# Initial Values
W = \text{np.random.randint}(-1, 1, (3, 3))
N_{epochs} = 100
lr = 0.01
for epoch in range(N_epochs):
 # compute the predictions
 Y_hat = multiclass_lr(X_train, W)
 # compute the gradient
 grad = np.dot(X_train.T,(Y_hat - Y_train))
 # parameter updates with gradient descend
 W = W - lr * grad
```



## Example

```
# Initial Values
W = np.random.randint(-1, 1, (3, 3))
N_{epochs} = 100
lr = 0.01
for epoch in range (N epochs):
 # compute the predictions
Y_hat = multiclass_lr(X_train, W)
 # compute the gradient
grad = np.dot(X_train.T,(Y_hat - Y_train))
 # parameter updates with gradient descend
W = W - lr * grad
```



#### Final Remarks on Linear Models

- The **capacity** of the model depends on the **input dimensionality D**. Remember, the **VC dimension** is **D + 1** for logistic regression without any transformation.
- This means that for low-dimensional data, there is an increased risk of underfitting.
- Instead, for **high-dimensional data** it is possible to **overfit**.
- Linear models are easy to optimize
- Fast training and predictions
- Interpretability

Suitable for linearly separable classes

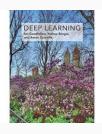
Linear models are very basic machine learning models but are still used a lot in machine learning.

In the next lectures, we will see improvements and extensions of linear models:

**neural networks** and **support vector machines**.



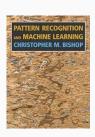
#### **Additional Material**



Chapter 2: Linear Algebra

Chapter 3: Probability and information theory

Chapter 5: Machine Learning Basics



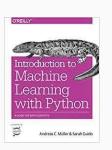
1.1.0 Example: Polynomial Curve Fitting

1.2.0 Probability Theory

3.1.0 Linear Basis Function Models

3.1.1 Maximum likelihood and least squares

4.3.2 Logistic regression



Introduction (page 1-27) Linear Models (page 47-70)

#### Lab Session

During the weekly lab session, we will do:

Tutorial on Linear Regression

Tutorial on Logistic Regression

Tutorial on Multiclass Logistic Regression



Major Assignment No.1 Deadline: Monday 11:59PM, September 1st, 2024 (Submission from Moodle)

# Appendix

### Scale of the Objective Function

- In the previous slides and lectures, we have seen the objective functions written with different **normalization factors**.
- For instance:

$$MSE = \frac{1}{N} \sum_{i=1}^{N} (y_i - \hat{y}_i)^2 \qquad MSE = \frac{1}{2} \sum_{i=1}^{N} (y_i - \hat{y}_i)^2 \qquad MSE = \sum_{i=1}^{N} (y_i - \hat{y}_i)^2$$

$$CCE = -\frac{1}{N} \sum_{i=1}^{N} \sum_{k=1}^{K} y_{ik} ln(p_{ik})$$
  $CCE = -\sum_{i=1}^{N} \sum_{k=1}^{K} y_{ik} ln(p_{ik})$ 

 The normalization factor does not play an important role and we can choose the one that is more convenient for us.

### Scale of the Objective Function

• The normalization factor of the objective only affects the **scale** of the gradient, but **not where the gradient** is pointing.

$$ilde{J}(\mathbf{w}) = kJ(\mathbf{w})$$
 (k is assumed a positive scaling factor)  $abla ilde{J}(\mathbf{w}) = k \nabla J(\mathbf{w})$ 

• When we use gradient descend, this term gets multiplied by the **learning rate**:

$$\mathbf{w}_{new} = \mathbf{w} - nk \nabla J(\mathbf{w}) \longrightarrow \text{You can choose the scale you want and tune the learning rate for your problem}$$

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## Scale of the Objective Function

A common choice is to scale the objective function with the number of training samples N:

$$MSE = \frac{1}{N} \sum_{i=1}^{N} (y_i - \hat{y}_i)^2$$
  $CCE = -\frac{1}{N} \sum_{i=1}^{N} \sum_{k=1}^{K} y_{ik} ln(p_{ik})$ 

- This way, the scale of the loss function (and those of the corresponding gradient) does not depend on the number of samples in the training set.
- When using gradient descend, we can set up a similar learning rate even if we change the number of training samples.