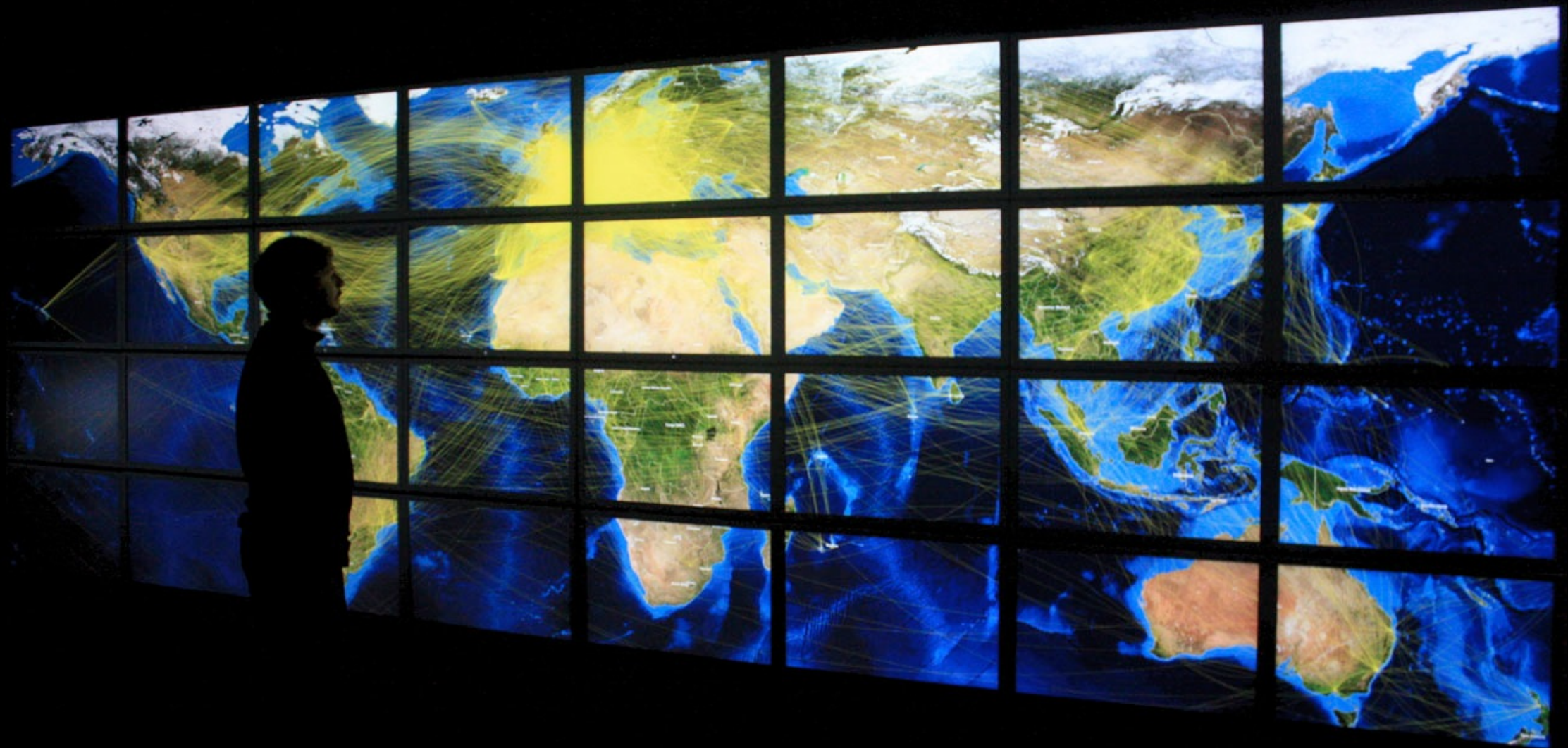


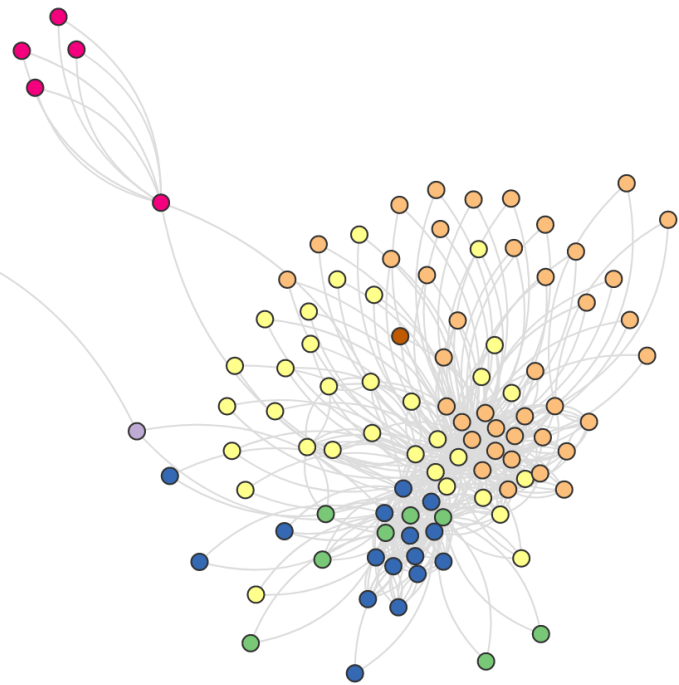
Data Visualization

INF552 - 2023 - Session 03 - exercices
Visualizing networks with D3

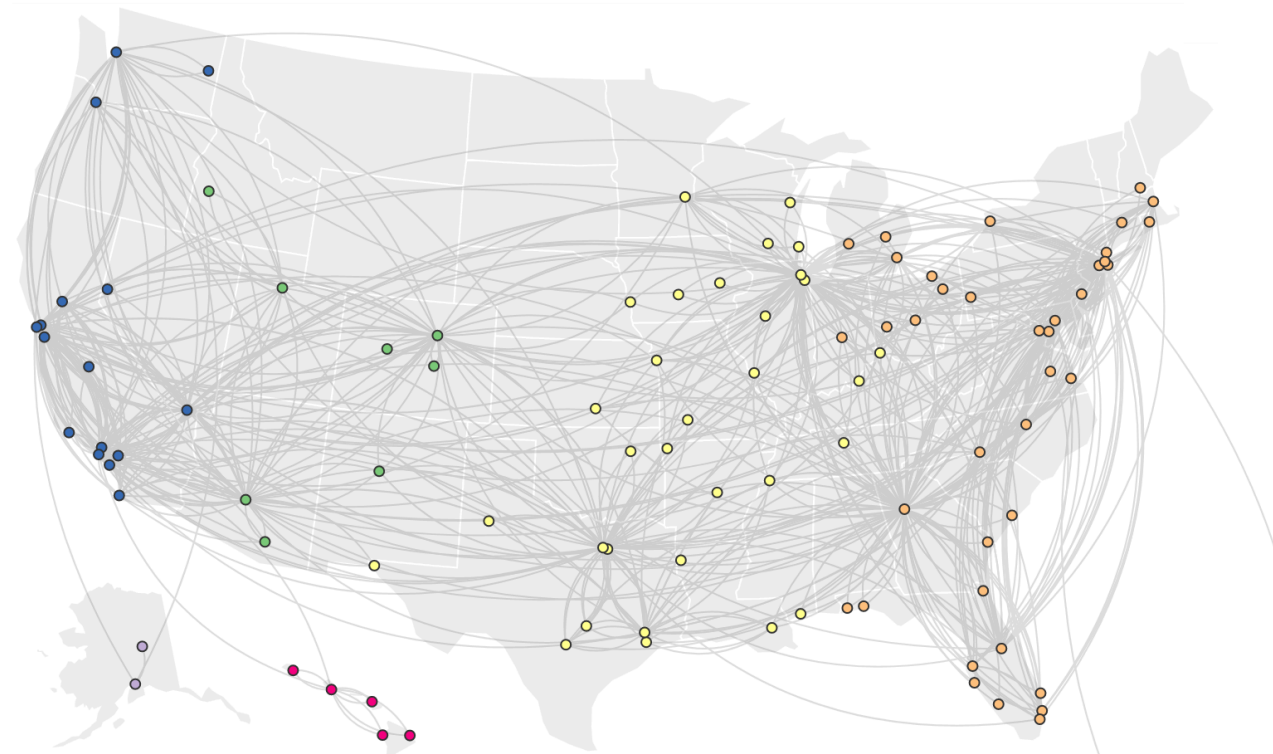


PC s07

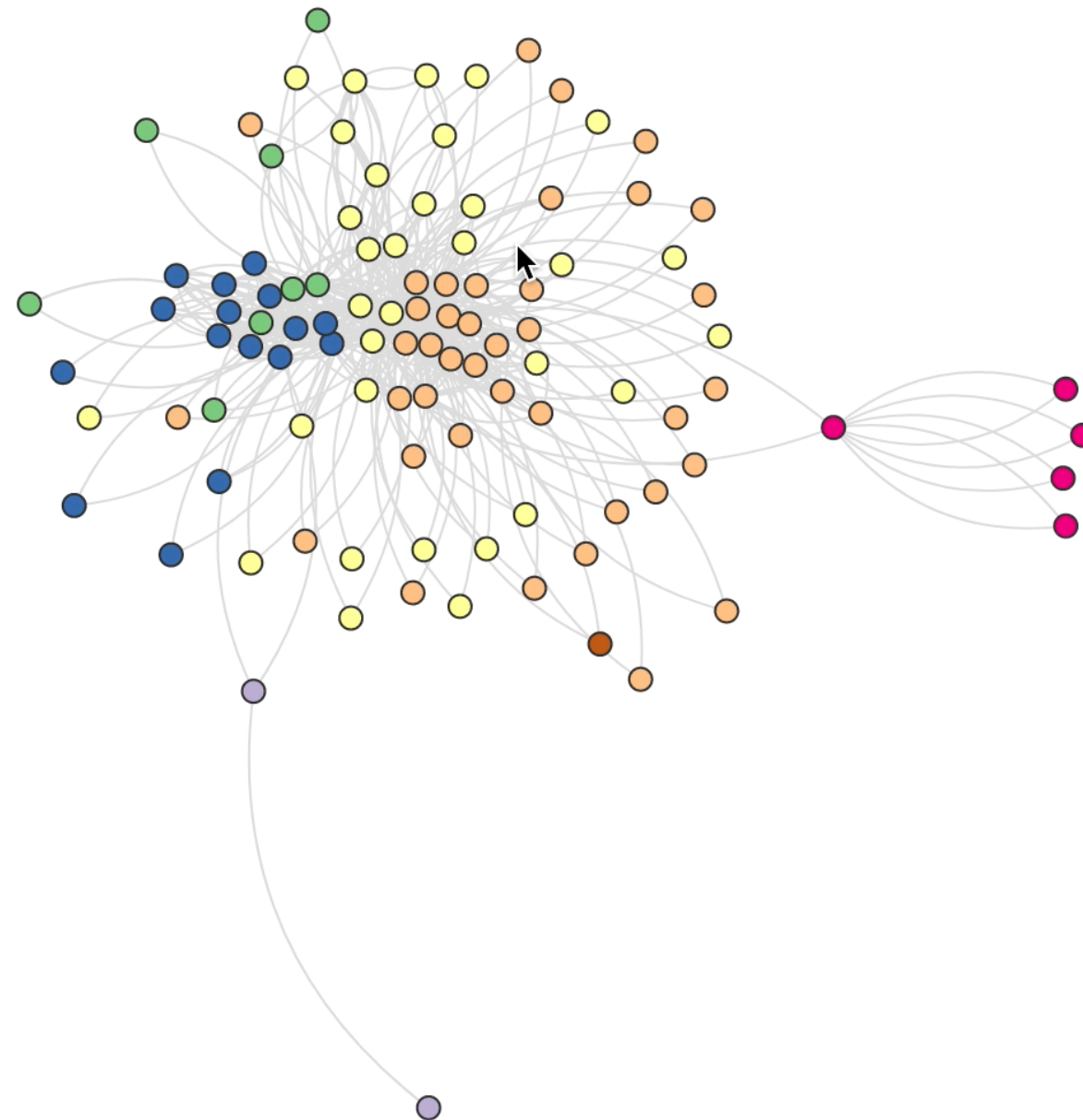
Visualization of an air traffic network.



Airports: 103, Flights: 582



Airports: 103, Flights: 582



d3-force

<https://github.com/d3/d3-force/blob/master/README.md>

Simulates physical forces on particles. Can be used for graph layout, collision detection, simple physical simulations.

Usage:

- create a simulation and set the nodes it applies to:

```
var simulation = d3.forceSimulation(myNodeArray);
```

- set forces

(in our case attraction forces of the graph's edges + node repulsion force + weak attraction force at the center)

```
simulation.force("link", ...); simulation.force("charge", ...); simulation.force("center", ...);
```

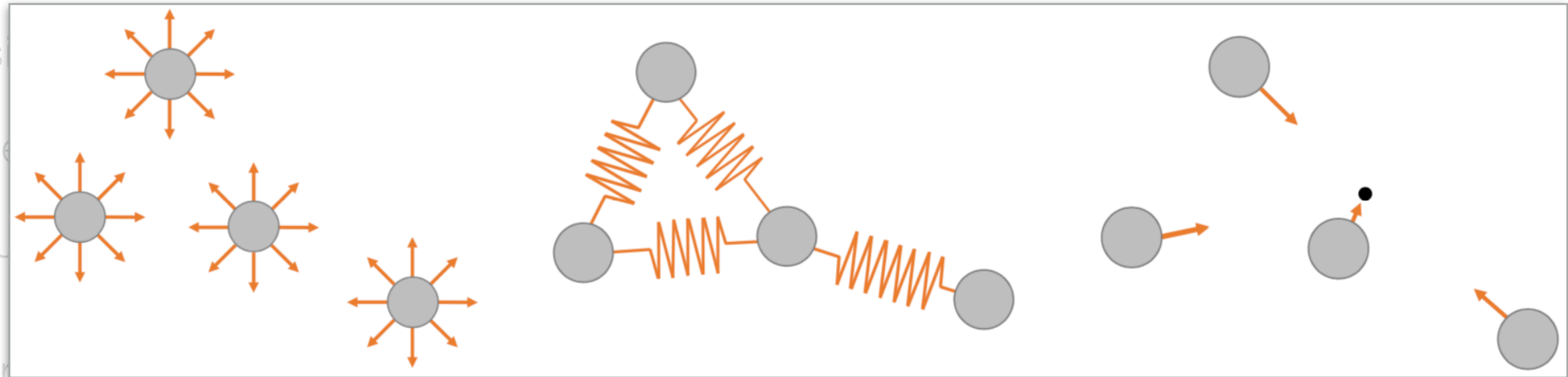
- listen to tick events (callback triggered at each new simulation step), move nodes and link endpoints accordingly

```
simulation.on("tick", mySimCallback);

function mySimCallback(){
  d3.selectAll("line")
    .attr("x1", (d) => (d.source.x))
    .attr("y1", (d) => (d.source.y))
    .attr("x2", (d) => (d.target.x))
    .attr("y2", (d) => (d.target.y));
  d3.selectAll("#nodes circle").attr("cx", (d) => (d.x))
    .attr("cy", (d) => (d.y));
}
```


Node-Link Diagrams / Force-directed Layout

- Metaphor of physical forces: attraction (springs, gravity) + repulsion (charged particles)



```
var simulation = d3.forceSimulation()  
  .force("charge", d3.forceManyBody())  
  .force("link", d3.forceLink().id(function(d) { return d.id; }).distance(5).strength(0.08))  
  .force("center", d3.forceCenter(ctx.w / 2, ctx.h / 2));
```

- GEM
- ForceAtlas
- LinLog
- Complexity
 - basic approaches are $O(V^2)$
 - Barnes & Hut's hierarchical force-calculation algorithm is $O(E + V \times \log(V))$

A note on SVG path

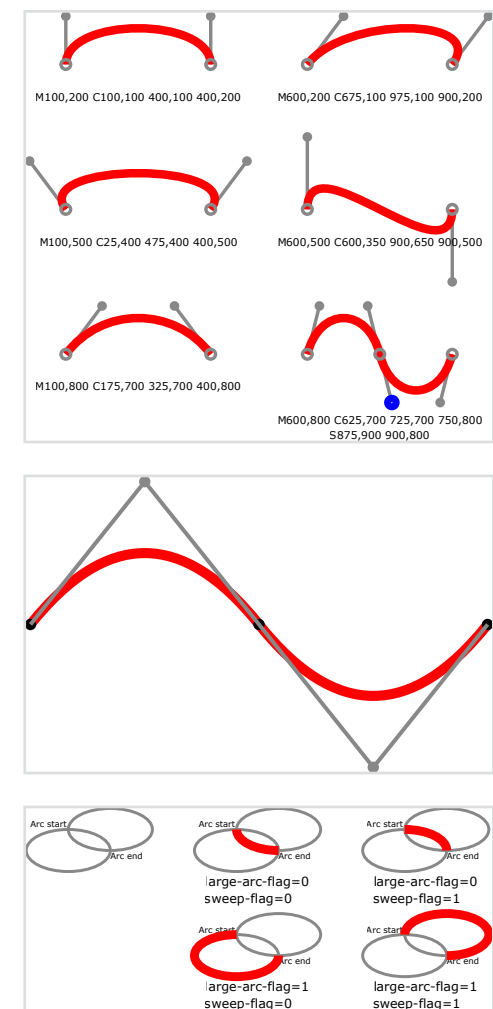
- d holds values like:

```
<path d="M10,315L110,215A36,60 0 0,1 150.71,170.29L172.55,152.45A30,50 -45 0,1 215.1,109.9L315,10"/>
```

- It has its own mini-syntax, with the following commands:

(cp = control point)

Command	Action	Syntax
L	line	Lx,y
H	horizontal line	Hx
V	vertical line	Vy
M	move (jump, without drawing)	Mx,y
Z	close path (straight line)	Z
C	cubic bezier curve (2 control points)	Ccp1x,cp1y cp2x,cp2y x,y
Q	quadratic bezier curve (1 control point)	Qcpx,cpy x,y
S	same as C where first cp is a reflection (central symmetry) of the last cp from the previous C or S cmd	Scp2x,cp2y x,y
T	same as Q where first cp is a reflection (central symmetry) of the cp from the previous Q or T cmd	Tx y
A	arc (ellipse with dimensions rX,rY,rotation)	A rX,rY rotation large-arc-flag,sweep-flag x,y



- Same commands using lowercase letters will interpret the coordinate pairs as relative coordinates rather than absolute ones.

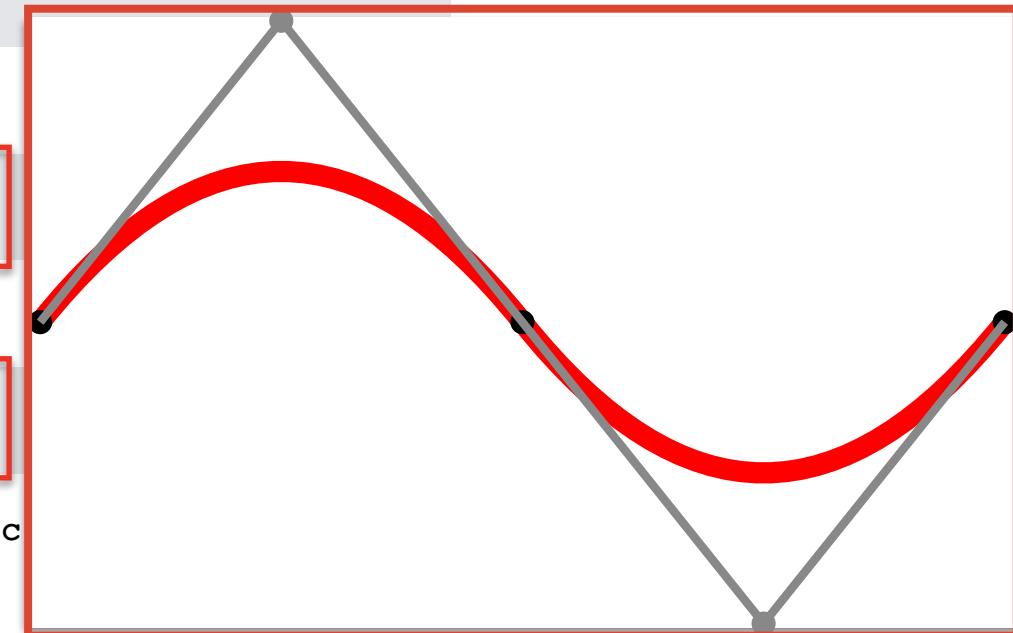
A note on SVG path

- d holds values like:

```
<path d="M10,315L110,215A36,60 0 0,1 150.71,170.29L172.55,152.45A30,50 -45 0,1 215.1,109.9L315,10"/>
```

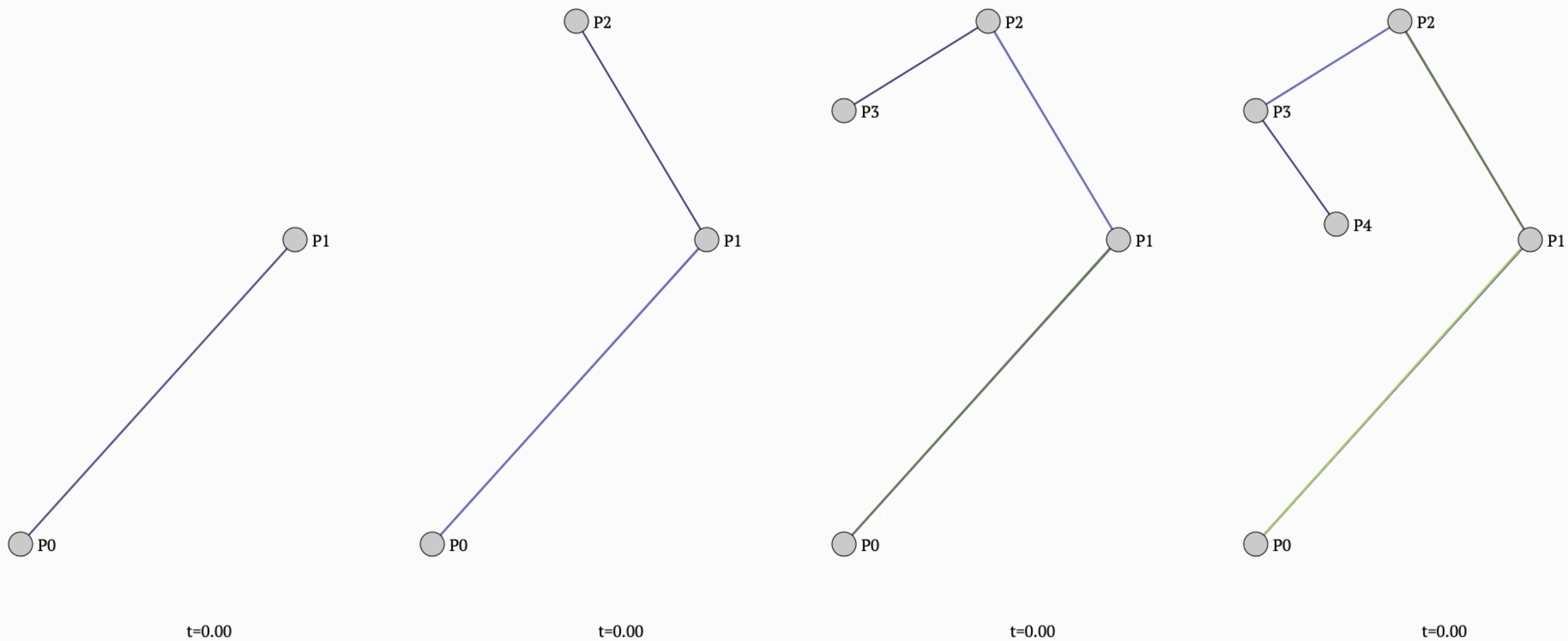
- It has its own mini-syntax, with the following commands: (cp = control point)

Command	Action	Syntax
L	line	Lx,y
H	horizontal line	Hx
V	vertical line	Vy
M	move (jump, without drawing)	Mx,y
Z	close path (straight line)	z
C	cubic bezier curve (2 control points)	Ccp1x,cp1y cp2x,cp2y x,y
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S	same as C where first cp is a reflection (central symmetry) of the last cp from the previous C or S cmd	Scp2x,cp2y x,y
T	same as Q where first cp is a reflection (central symmetry) of the cp from the previous Q or T cmd	Tx y
A	arc (ellipse with dimensions rX,rY,rotation)	A rX,rY rotation large-arc



- Same commands using lowercase letters will interpret the coordinate pairs as relative coordinates rather than absolute ones.

A note on SVG path



A note on SVG path

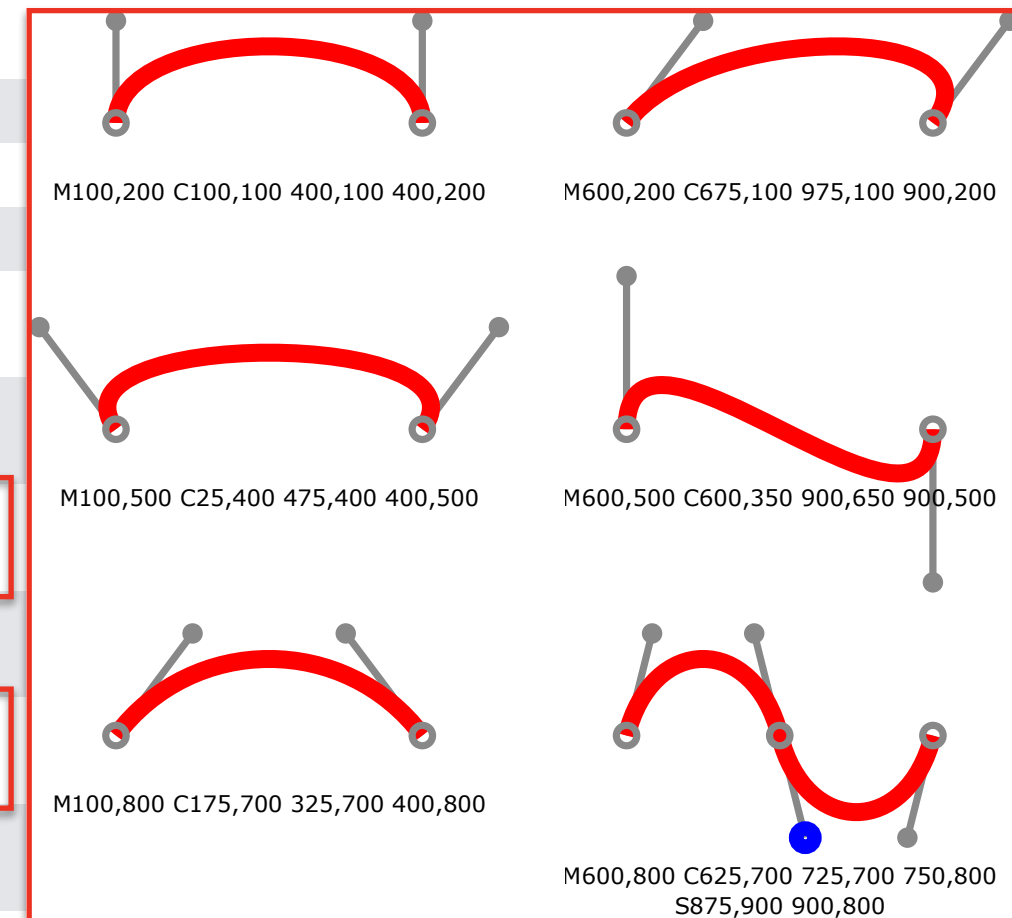
- d holds values like:

```
<path d="M10,315L110,215A36,60 0 0,1 150.71,170.29L172.55,152.45A30,50 -45 0,1 215.1,109.9L315,10"/>
```

- It has its own mini-syntax, with the following commands:

Command	Action	Syntax
L	line	Lx,y
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T	same as Q where first cp is a reflection (central symmetry) of the cp from the previous Q or T cmd	Tx y
A	arc (ellipse with dimensions rX,rY,rotation)	A rX,rY rotation large-arc-flag,sweep-flag x,y

(cp = control point)



- Same commands using lowercase letters will interpret the coordinate pairs as relative coordinates rather than absolute ones.

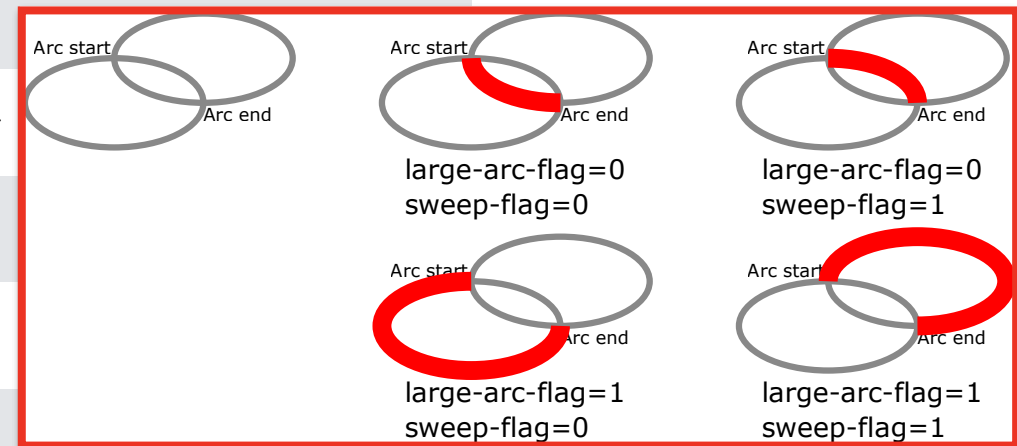
A note on SVG path

- d holds values like:

```
<path d="M10,315L110,215A36,60 0 0,1 150.71,170.29L172.55,152.45A30,50 -45 0,1 215.1,109.9L315,10"/>
```

- It has its own mini-syntax, with the following commands: (cp = control point)

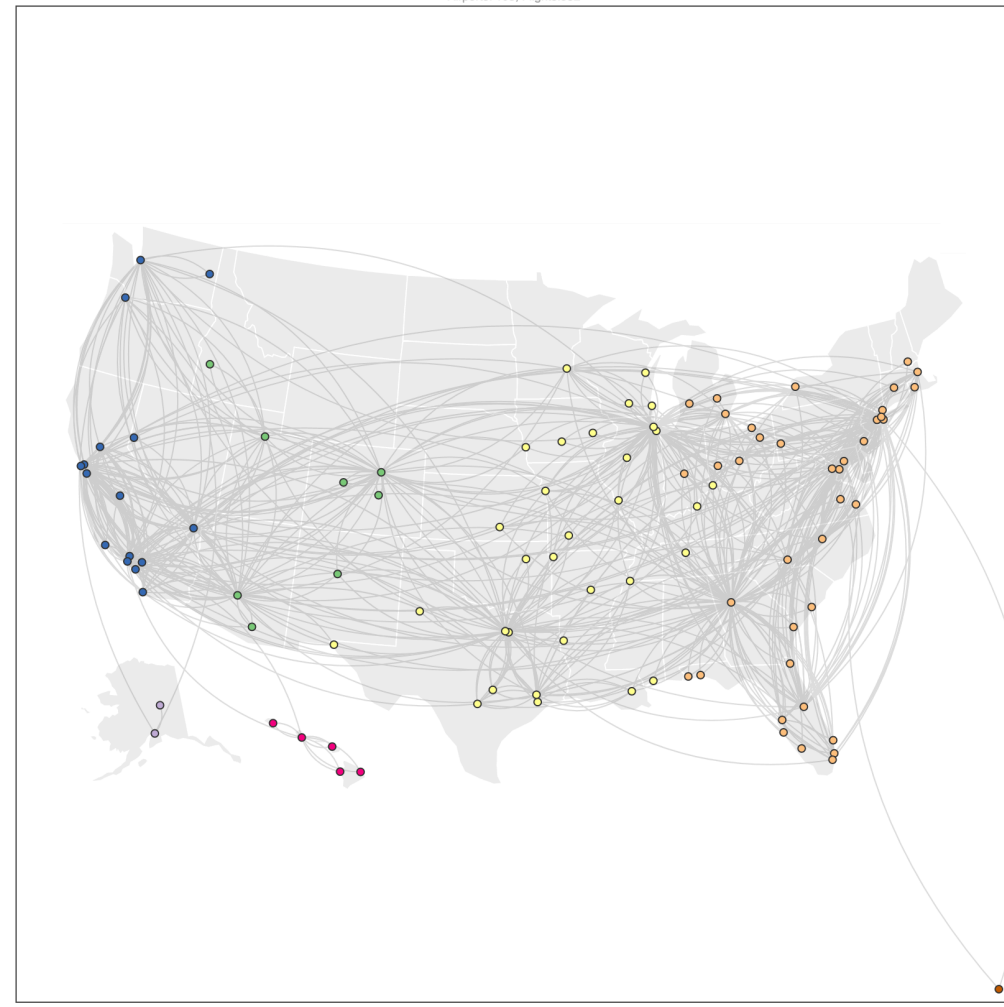
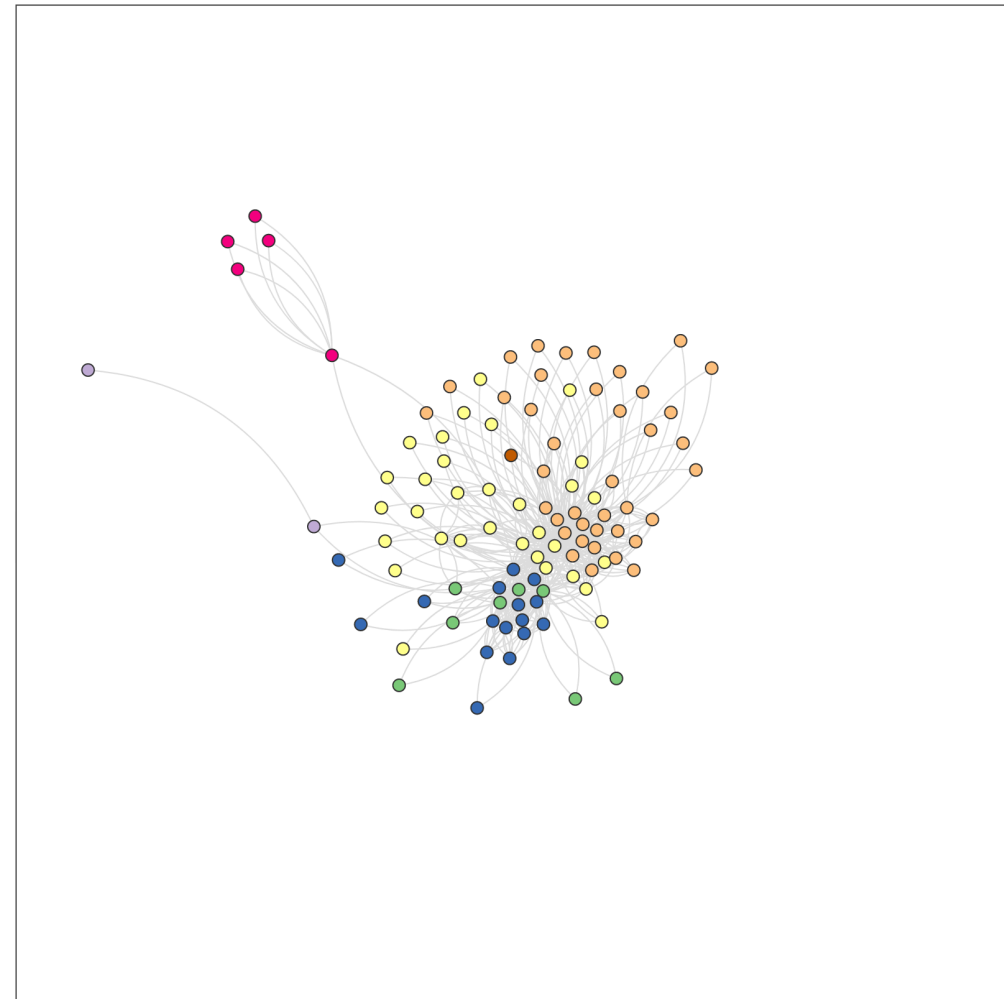
Command	Action	Syntax
L	line	Lx,y
H	horizontal line	Hx
V	vertical line	Vy
M	move (jump, without drawing)	Mx,y
Z	close path (straight line)	Z
C	cubic bezier curve (2 control points)	Ccp1x,cp1y cp2x,cp2y x,y
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A	arc (ellipse with dimensions rX,rY,rotation)	A rX,rY rotation large-arc-flag,sweep-flag x,y



- Same commands using lowercase letters will interpret the coordinate pairs as relative coordinates rather than absolute ones.

PC s07

- Visualization of an air traffic network.
- The network consists of airports (nodes) in the USA connected by flights (edges):
 - the network is hierarchical: each airport belongs to a state (**AL**, **MA**, **CA**, *etc.*);
 - edges are weighted using a numerical attribute (representing the passenger traffic on each edge).



PC s07

- The input data is split in four files:
 - `airports.json` contains data about the airports only;
 - `flights.json` contains data about the flights between those airports;
 - `states_tz.csv` contains data about which time zone all 50 states are in;
 - `us-states.geojson` contains data to draw the US states map.
- Load all files, using Javascript function `Promise.all()` to handle the async' calls.

```
d3.json(...) // like d3.csv(), returns a Promise.  
              // We called then(...) directly on that promise in ex02.  
  
// Here we want to load multiple resources before proceeding to the creation  
// of the visualization. To wait for multiple promises to be completed, use:  
Promise.all(...).then(function(data){/* Callback code */})  
  
// This runs all promises given as input (array) to all(),  
// and executes the code in then() only once  
// all promises have been completed  
// (in our case, fetching and parsing all CSV and JSON files)
```

<https://github.com/d3/d3-fetch>

https://developer.mozilla.org/docs/Web/JavaScript/Reference/Global_Objects/Promise/all

PC s07

- We will first visualize this network using a classic force-directed graph layout.
- Transform the input data to match the data structure expected by this D3 component.
- The graph is quite large and noisy. Filter the data given as input to the graph layout algorithm:
 - ignore airports with an IATA code starting with a number, such as, *e.g.*, 06C;
 - ignore flights whose `count` < 3000;
 - ignore airports that are not connected (possibly as a result of the above flight filtering).
- Add a group attribute to nodes (airports), whose value is the parent state's time zone.
- Use the traffic volume (`count`) as the edges' weight (attribute `value`).
- Add the state and city to node properties, as we will also display this information on demand.

```
{nodes:[{id: "ATL", group:"EST", state: "GA", city: "Atlanta", latitude:..., longitude:...},
        {id: "ABE", group:"EST", state: "PA", city: "Allentown", latitude:..., longitude:...},
        ...],
  links:[{source:"PHX", target:"ABQ", value: 5265.0},
        ...]
}
```



```
[{"city": "Bay Springs", "country": "USA", "iata": "00M",
"latitude": 31.95376472, "longitude": -89.23450472, "name":
"Thigpen", "state": "MS"},
{"city": "Livingston", "country": "USA", "iata": "00R",
"latitude": 30.68586111, "longitude": -95.01792778, "name":
"Livingston Municipal", "state": "TX"},
{"city": "Colorado Springs", "country": "USA", "iata":
"00V", "latitude": 38.94574889, "longitude": -104.5698933,
"name": "Meadow Lake", "state": "CO"},
{"city": "Perry", "country": "USA", "iata": "01G",
"latitude": 42.74134667, "longitude": -78.05208056, "name":
"Perry-Warsaw", "state": "NY"},
{"city": "Hilliard", "country": "USA", "iata": "01J",
"latitude": 30.6880125, "longitude": -81.90594389, "name":
"Hilliard Airpark", "state": "FL"}]
```

```
[{"count": 853.0, "destination": "ATL", "origin": "ABE"},
{"count": 1.0, "destination": "BHM", "origin": "ABE"},
{"count": 805.0, "destination": "CLE", "origin": "ABE"},
{"count": 465.0, "destination": "CLT", "origin": "ABE"},
{"count": 247.0, "destination": "CVG", "origin": "ABE"},
{"count": 997.0, "destination": "DTW", "origin": "ABE"},
{"count": 3.0, "destination": "JFK", "origin": "ABE"},
{"count": 9.0, "destination": "LGA", "origin": "ABE"},
{"count": 1425.0, "destination": "ORD", "origin": "ABE"},
{"count": 2.0, "destination": "PHL", "origin": "ABE"},
{"count": 2660.0, "destination": "DFW", "origin": "ABI"},
{"count": 368.0, "destination": "AMA", "origin": "ABQ"},
{"count": 1067.0, "destination": "ATL", "origin": "ABQ"},
{"count": 433.0, "destination": "AUS", "origin": "ABQ"}]
```

```
State,TimeZone
AL,CST
AK,AKST
AZ,MST
AR,CST
CA,PST
CO,MST
CT,EST
DE,EST
FL,EST
GA,EST
HI,HST
ID,MST
IL,CST
IN,EST
IA,CST
```

Classic force-directed graph layout.

Structure expected by this D3 component.

Data given as input to the graph layout algorithm:

with a number, such as, e.g., 06C;

```
{nodes:[{id: "ATL", group:"EST", state: "GA",
city: "Atlanta", latitude:..., longitude:...},
{id: "ABE", group:"EST", state: "PA",
city: "Allentown", latitude:..., longitude:...},
...],
links:[{source:"PHX", target:"ABQ",
value: 5265.0},
...]}]
```

whose value is the parent state's time zone.

height (attribute value).

We will also display this information on demand.

```
city: "Atlanta", latitude:..., longitude:...},
city: "Allentown", latitude:..., longitude:...},
5.0},
```

PC s07

- We will first visualize this network using a classic force-directed graph layout.
- Transform the input data to match the data structure expected by this D3 component.
- The graph is quite large and noisy. Filter the data given as input to the graph layout algorithm:
 - ignore airports with an IATA code starting with a number, such as, *e.g.*, 06C;
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- Add the state and city to node properties, as we will also display this information on demand.

```
{nodes:[{id: "ATL", group:"EST", state: "GA", city: "Atlanta", latitude:..., longitude:...},
        {id: "ABE", group:"EST", state: "PA", city: "Allentown", latitude:..., longitude:...},
        ...],
  links:[{source:"PHX", target:"ABQ", value: 5265.0},
        ...]
}
```

PC s07

- Once the input data has been transformed to match the structure expected by D3's forceSimulation, populate the SVG canvas:
 - append `<g class="links">` and `<g class="nodes">` to the `<svg>` element;
 - and bind elements from the `nodes` and `links` arrays to graphical marks:
 - using `d3.selectAll(...).data(...).enter()...`, populate the first group with `<line>` elements mapped to items in the `links` array in the input data structure, and set the opacity of all lines to `0.2`;
 - similarly, populate the second group with `<circle>` elements mapped to items in the `nodes` array in the input data structure, and set the radius of all circles to `5`.

PC s07

- We use d3-force to visualize the network as a node-link diagram:

<https://github.com/d3/d3-force/blob/master/README.md>

- The code initialising the layout algorithm is already provided in `ex07.js`

```
var simulation = d3.forceSimulation()  
    .force("link", d3.forceLink().id(function(d) { return d.id; }).distance(5).strength(0.08))  
    .force("charge", d3.forceManyBody())  
    .force("center", d3.forceCenter(ctx.w / 2, ctx.h / 2));
```

- Associate the previously-created nodes and links to this simulation:

```
{nodes:[{id: "iata4foo", group:"PST", state: "ST", city: "foo"},...],  
  links:[{source:"iata4foo", target:"iata4bar", value: 853.0},...]  
}
```

```
// input data structure created earlier is in ctx.nodes + ctx.links:
```

```
simulation.nodes(ctx.nodes)  
    .on("tick", simStep);
```

```
simulation.force("link")  
    .links(ctx.links);
```

```
function simStep(){  
    // code run at each iteration of the simulation  
    // updating the position of nodes and links  
    d3.selectAll("#links line").attr("x1", (d) => (d.source.x))  
        .attr("y1", (d) => (d.source.y))  
        .attr("x2", (d) => (d.target.x))  
        .attr("y2", (d) => (d.target.y));  
    d3.selectAll("#nodes circle").attr("cx", (d) => (d.x))  
        .attr("cy", (d) => (d.y));  
}
```

PC s07

- We use d3-force to visualize the network as a node-link diagram:

<https://github.com/d3/d3-force/blob/master/README.md>

reconciling nodes and links

- The code initialising the layout algorithm is already provided in `ex07.js`

```
var simulation = d3.forceSimulation()  
    .force("link", d3.forceLink().id(function(d) { return d.id; }).distance(5).strength(0.08))  
    .force("charge", d3.forceManyBody())  
    .force("center", d3.forceCenter(ctx.w / 2, ctx.h / 2));
```

- Associate the nodes and links to this simulation:

*3 different forces
relevant to graph layout*

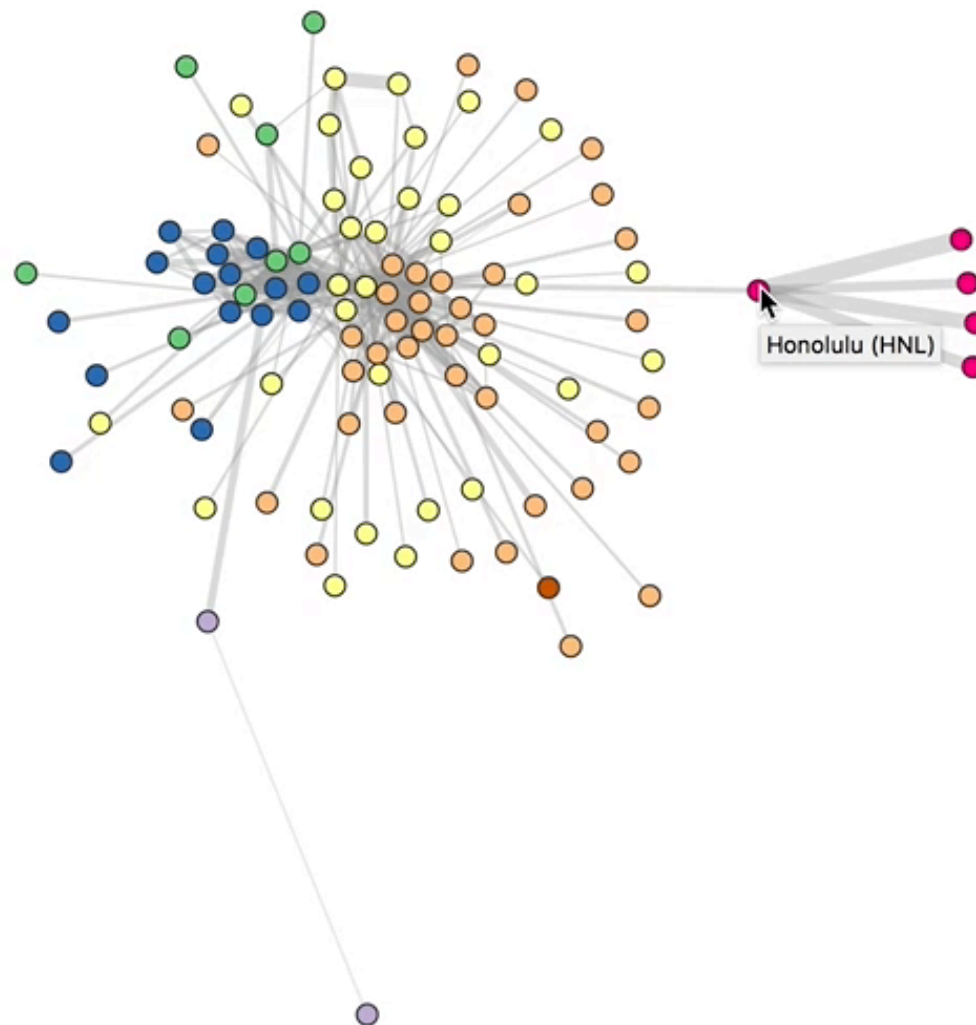
```
{nodes:[{id: "iata4", type: "foo"},...],  
 links:[{source:"iata4", target:"iata5", value: 853.0},...]  
}
```

// input data structure created earlier is in `ctx.nodes + ctx.links`:

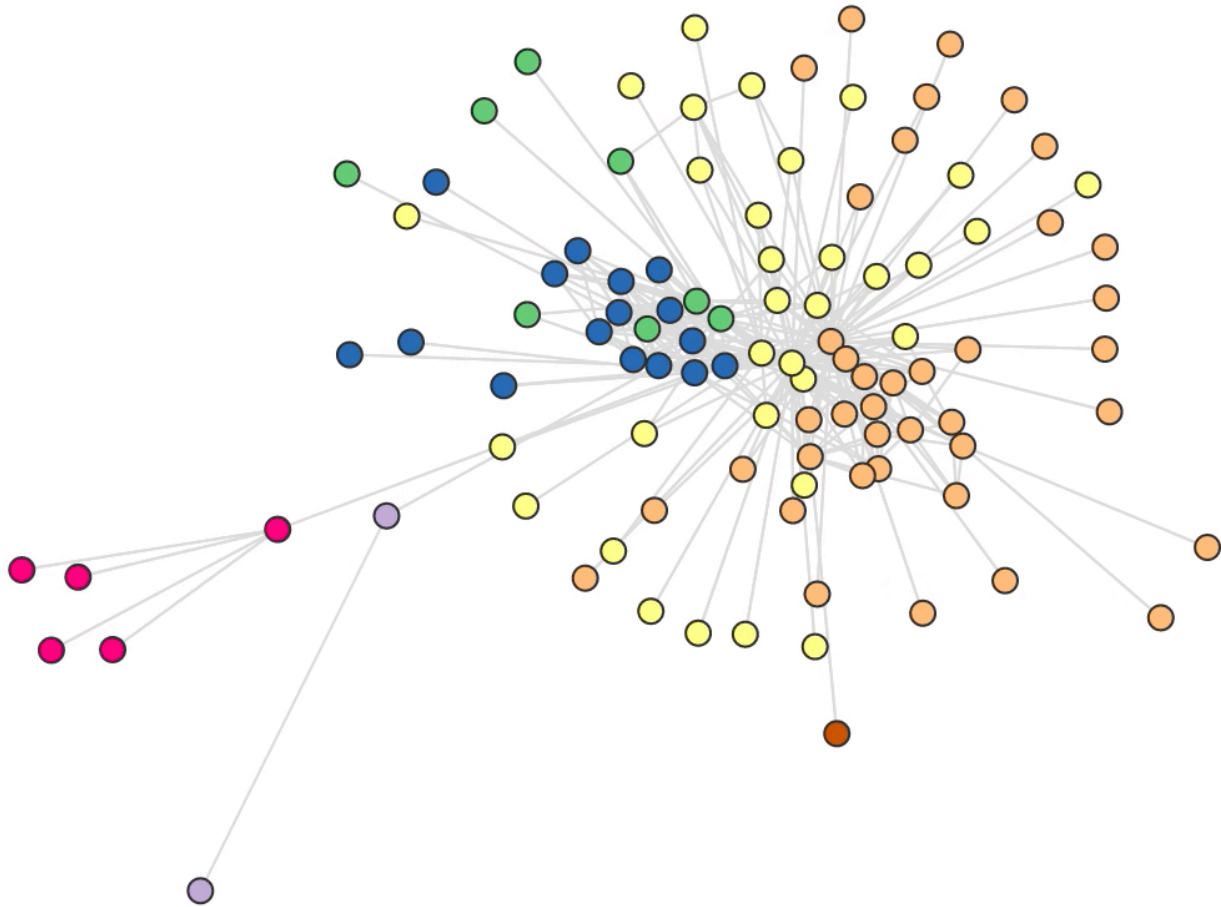
```
simulation.nodes(ctx.nodes)  
    .on("tick", simStep);  
  
simulation.force("link")  
    .links(ctx.links);  
  
function simStep(){  
    // code run at each iteration of the simulation  
    // updating the position of nodes and links  
    d3.selectAll("#links line").attr("x1", (d) => (d.source.x))  
        .attr("y1", (d) => (d.source.y))  
        .attr("x2", (d) => (d.target.x))  
        .attr("y2", (d) => (d.target.y));  
    d3.selectAll("#nodes circle").attr("cx", (d) => (d.x))  
        .attr("cy", (d) => (d.y));  
}
```


PC s07

Append a `title` to each node's `circle`. That title should be a string made of the city and airport IATA code. It will be displayed when hovering the node with the mouse cursor.



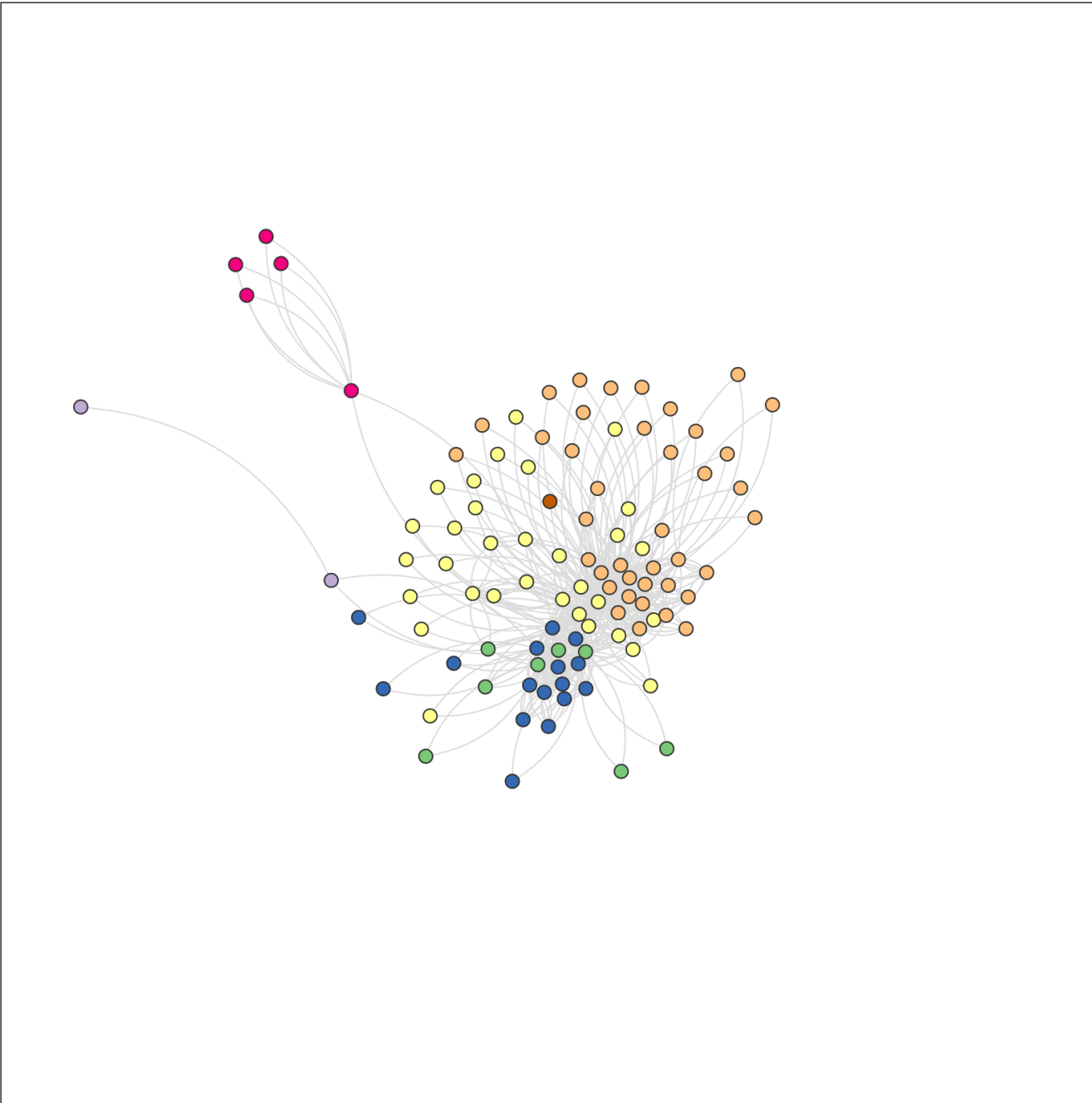
- Now we want to enable a smooth transition to a representation of this network on a map when pressing the `switch` button.
- All airport nodes have lat/lon coordinates. Draw a map of the US states with the Albers projection, project those airport coordinates on that map using the same projection, smoothly animate the transition from the node-link diagram to the map, and conversely.



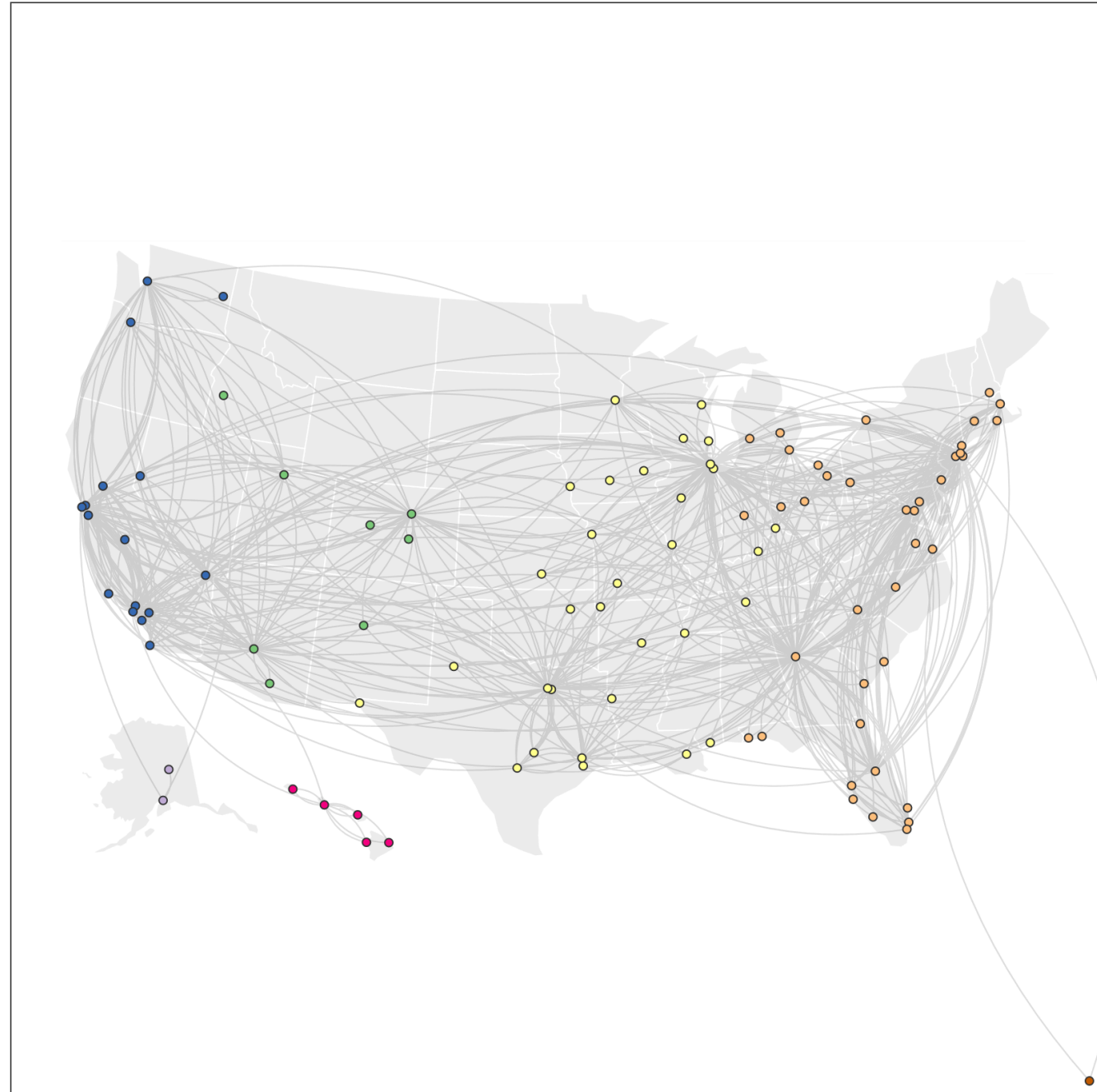
PC s07

where we see that we are actually dealing with a multi-graph

Replace `<line>` elements by `<path>` elements consisting of a single quadratic bézier curve:



Airports: 103, Flights:582



Airports: 103, Flights:582

A solution for the quad curve control point:

$$\begin{cases} x_{cp} = x_1 + \rho \cdot \cos(\alpha + \frac{\pi}{6}) \\ y_{cp} = y_1 + \rho \cdot \sin(\alpha + \frac{\pi}{6}) \end{cases}$$

21

where

$$\rho = \frac{\sqrt{(x_2 - x_1)^2 + (y_2 - y_1)^2}}{2}$$

$$\alpha = \arctan2(\frac{y_2 - y_1}{x_2 - x_1})$$